### Todd Roberts

(301) 769-8760 | todd roberts@berkeley.edu | toddroberts.website

Local Address: 1808 San Pablo Ave, Unit C. Berkeley, CA 94702 Permanent Address: 15620 Pt. Lookout Rd. Saint Inigoes, MD 20684

# **Education**

University of California, Berkeley, Berkeley, CA - M.E. in Mechanical Engineering

May 2020

- **Focus:** Biomechanics
- Relevant Courses: Advanced Designing for the Human Body, Advanced Design and Automation

# Northeastern University, Boston, MA - B.S. in Mechanical Engineering

May 2019

- Minor: Biomechanical Engineering
- **GPA:** 3.911/4.000
- Activities: Enabling Engineering, "Addditive", Engineers Without Borders: Uganda (2014-2015), American Society of Mechanical Engineers (ASME), NU Television (NUTV), Intramurals
- Senior Capstone Design Project:
  - Advisor: Professor Carol Livermore
  - Industry Sponsor: Lyndra Therapeutics
  - Designed an anatomically representative environment capable of simulating the digestive forces in a human stomach
  - Co-inventor on provisional patent filed by sponsor for work done on this project
  - Recipient of the Senior Capstone Design Award for Extra Mile

### Westtown School, Westchester, PA

May 2014

Academic Distinction (2010 – 2014)

#### **Honors and Awards**

•	Dean's List, Northeastern University	2014 – 2019
•	Merit Scholarship Recipient, Northeastern University	2014 – 2019
•	Tau Beta Pi, Engineering Honors Society	2018 – 2019
•	Pi Tau Sigma, Mechanical Engineering Honors Society	2018 – 2019
•	Extra Mile Award, Mechanical Engineering Capstone	2018
•	National Co-op Student of the Year Finalist, CEED	2019
•	COE Outstanding Co-op award, Northeastern University	2019
•	Society of Flight Test Engineers Scholarship	2016, 2018

# **Professional Experience**

**Lyndra Therapeutics,** *Watertown, MA* – Mechanical Engineering Consultant **February – August 2019** 

- Continued support of simulated stomach environment development including fatigue life and general mechanical design improvements
- Designed mechanical test fixtures for fatigue analysis of ultra-long-lasting oral dosage forms
- Standardized current mechanical characterization fixtures to increase repeatability of testing
- Developed environmental chamber to allow testing at accurate gastro temperature and humidity

## **Liberating Technologies Inc,** *Holliston, MA* – Research Engineer Co-op

January - July 2018

- Developed unilateral control mechanism for novel multi-function prosthetic fingertip gripper. Coinventor on US Provisional Pat. Ser. No. 62/570, 184
- Prototyped mechanical components with SolidWorks, 3D printing, and machine tools
- Designed substrate and overmold for casting urethane grip onto prosthetic finger

### **Todd Roberts**

(301) 769-8760 | todd roberts@berkeley.edu | toddroberts.website

Local Address: 1808 San Pablo Ave, Unit C. Berkeley, CA 94702 Permanent Address: 15620 Pt. Lookout Rd. Saint Inigoes, MD 20684

- Used ergonomic data to design electro-mechanical prosthetic simulator
- Conducted human subject testing to evaluate functional outcomes of new prosthesis
- Wrote C++ code to control prosthetic simulator with myoelectric inputs
- Presented weekly design progress to internal stakeholders

## **Tesla Inc**, Fremont, CA – Dimensional Engineering Co-op

January - July 2017

Supported the Model 3 launch by co-leading dimensional studies on the "Quality Assurance Fixture" which drove quality improvements in early production parts and assembly processes

- Devised and conducted studies based on requests from design and manufacturing engineers to root cause part and assembly level dimensional issues
- Created and analyzed dimensional reports and led subsequent reviews with management
- Developed datum strategies for test and assembly fixtures based on experimental results
- Designed and fabricated test equipment using CATIA, 3D printing, and local machine shops
- Managed daily responsibilities of 3 5 metrology technicians and measurement resources
- Provided real time solutions to assembly line issues based on current dimensional data
- Collected data using traditional and portable Coordinate Measuring Machines (CMM's)
- Evaluated Geometric Dimensioning and Tolerancing accuracy of third party supplier parts

# **DOTS Corp**, *Natick*, *MA* – Mechanical Engineering Co-op

January - July 2016

- Worked in high paced, research and development phase, consumer product start-up
- Designed and constructed multiple iterations of assembly and test fixtures using SolidWorks, shop tools, 3D Printers and Thor Labs prototyping hardware
- Collaborated with machinists, plating shops, and other vendors to fabricate custom parts
- Designed and conducted experiments and performed statistical data analysis
- Captured high resolution images for detailed optical analysis and observations

# NAVAIR, Webster Field, MD – Engineering Student Trainee

June - August 2015

- Wrote and submitted shock and vibration test procedures to MIL-STDS 901D and 167-1A
- Created technical trouble shooting documents for Microsoft Windows Server 2008 R2
- Field tested and documented standard operating procedure of Blue Sky Antenna Mast
- Assembled products and shipped them to test facilities and troops overseas

# **Research Experience**

Expeditionary Robotics Lab, Boston, MA – Independent Undergraduate Research January – May 2019

- Developed kinematically accurate hand for testing mechanical properties of hand orthosis
- Designed artificial ligaments and identified insertion sites for representative joint range of motion
- Designed artificial tendons for manual and automated actuation of hand

ReGame-VR Laboratory, Boston, MA – Undergraduate Research Assistant September 2016 – May 2019

- Designed and constructed custom mechanical components for physical and cognitive therapy equipment
- Developed multiple iterations of a portable rehabilitation game system
- Collaborated with electrical engineers to successfully integrate electromechanical systems
- Paper submission in preparation for the International Conference of Virtual Rehabilitation, July 2019

### **Todd Roberts**

(301) 769-8760 | todd roberts@berkeley.edu | toddroberts.website

Local Address: 1808 San Pablo Ave, Unit C. Berkeley, CA 94702 Permanent Address: 15620 Pt. Lookout Rd. Saint Inigoes, MD 20684

# **Leadership & Volunteer Experience**

Enabling Engineering, Boston, MA - Project Leader

January 2016 - May 2019

- Created customized head-operated Xbox controller for a student with cerebral palsy
- Organized group meetings and communicate with other student groups
- Filmed and edited interviews of all enabling group project teams for fundraising and promotions

#### Addditive, Boston, MA – Curriculum Development Co-lead

July 2018 – August 2019

- Mentoring local high school students about opportunities in STEM and higher education
- Developed new relationship with Dearborn STEM Academy Highschool
- Created curriculum for 25 student weekly class about engineering design and 3D printing

# **Software & Machining Skills**

- Applications: SolidWorks: CSWA Certified, CATIA V5, LabVIEW, MATLAB, C++, Adobe CC, Python, OpenSim
- Machining: Significant experience with 3-axis mill, lathe, rotary tools, and soldering equipment.
  Extensive wood working and aluminum experience: built cabinets, chairs, custom skateboards, and dock restoration.
- Additional Fabrication: Silicone and urethane casting and mold design. Additive manufacturing: SLA, SLS, and FDM. Basic knowledge of welding.

#### **Patents**

- *Co-inventor*: "Pointdexter: Dexterous Prosthetic Fingertips", Inventor: Martinez Luna et al US Provisional Pat. Ser.No. 62/570,184, filed 2017-10-10
- *Co-inventor:* "Stomach Simulating Device", Inventor: Kanasty et al US Provisional Pat. Ser.No. 62/774,802, filed 2018-12-03

# **Background and Interests**

- My greatest passion is empowering individuals with disabilities or alternative needs by bringing new levels of independence to their lives through development of assistive technology
- Designed and built personal film equipment including a stabilizer, dolly, and camera crane
- Videography, Screen Printing, Skateboarding, Snowboarding, Sailing, and Soccer