### 深度視覺

# **HW9: Facial Keypoint Detection**

#### notebook 執行過程:

Load Data:下載資料集

#### Visualize Data:查看資料狀況

### Design a Convolution Neural Network Model

```
KeypointModel(pl.LightningModule):
 def __init__(self, hparams):
        Warning: Don't change the method declaration (i.e. by adding more
        super(KeypointModel, self).__init__()
        self.hp = hparams
        self.maxpool = nn.MaxPool2d(2, 2)
        self.dropout = nn.Dropout(p=0.2)
        self.conv1 = nn.Conv2d(1, 32, 5)
        self.conv2 = nn.Conv2d(32, 64, 3)
self.conv3 = nn.Conv2d(64, 128, 3)
        self. fc1 = nn. Linear (128*10*10, 30)
def forward(self, x):
       if x.dim() == 3:
            x = torch.unsqueeze(x, 0)
       x = self.maxpool(F.relu(self.conv1(x)))
       x = self.maxpool(F.relu(self.conv2(x)))
       x = self.maxpool(F.relu(self.conv3(x)))
       x = x.view(x.size(0), -1)
       x = self.dropout(x)
```

\_\_init\_\_的部分包括三個種不同 filter size 的 convolution、一個 size 為 2 的 maxpooling、一個 dropout 負責隨機捨去 node、一個 fully connected layer。 forward 的部分則是依據初始化所宣告的 object 來實現 CNN 的步驟,依序 為 covl、ReLU、maxpooling,重複三回合後將資料攤平(view)後進入 fcl。

# Define Functions for pl.Trainer: 計算 loss、創建 dataloader、最佳化

```
def training_step(self, batch, batch_idx):

x, y = batch
y_hat = self.forward(batch[x])
loss = self.hp["loss"](y_hat, batch[y].view(-1, 30))
return loss

def train_dataloader(self):
return DataLoader(self.hp["train_dataset"], batch_size=self.hp["batch_size"], shuffle=True)

def configure_optimizers(self):
return torch.optim.Adam(self.parameters(), lr=self.hp["lr"])

return torch.optim.Adam(self.parameters(), lr=self.hp["lr"])
```

### Define Hyperparameters to the Model in a Dictionary:設定超參數

```
| The state of the
```

#### Test Whether the Model Follows the Basic Rules: 測試 model 是否符合規定

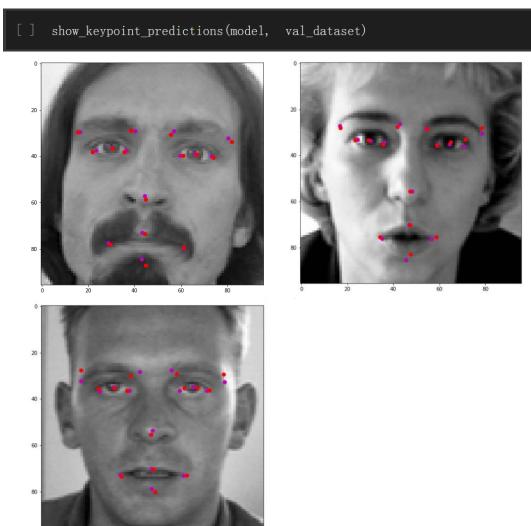
```
[16] model = KeypointModel(hparams)
test_keypoint_nn(model)

KeypointShapeTest passed.
ParamCountTest passed. Your model has 0.477 mio. params.
FileSizeTest passed. Your model is 1.9 MB large
All tests passed for your model. Tests passed: 3/3
```

### Model Training Using PyTorch Lightning: 重複訓練,設定 50 個 epochs

```
import pytorch_lightning as pl
    model = KeypointModel(hparams)
    trainer = pl.Trainer(max_epochs=50, gpus=0, fast_dev_run=False)
    trainer.fit(model)
GPU available: False, used: False
    TPU available: False, using: 0 TPU cores
    IPU available: False, using: 0 IPUs
    HPU available: False, using: 0 HPUs
      | Name | Type
                            Params
    0 | maxpool | MaxPool2d | 0
    1 | dropout | Dropout | 0
                             832
    4 | conv3
5 | fc1
              Trainable params
              Non-trainable params
              Total params
              Total estimated model params size (MB)
    Epoch 49: 100%
                                                                           78/78 [22:35<00:00, 17.38s/it, loss=0.00187, v_num=2]
```

### Visualize Predictions of the Model:以圖片檢視預測結果



# Compute Validation Score: 計算分數

```
[] print("Score:", evaluate_model(model, val_dataset))

Score: 505.79374660804467
```

#### Save the Model:存檔

```
imodels/facial_keypoints.p'

'models/facial_keypoints.p'

[] # Now zip the folder for upload
    from exercise code.util.submit import submit_exercise
    submit_exercise('exercise09')

relevant folders: ['exercise_code', 'models']
    notebooks files: ['l_facial_keypoints.ipynb', 'Optional-spatial_batchnorm.ipynb']
    Adding folder models
    Adding notebook l_facial_keypoints.ipynb
    Adding notebook Optional-spatial_batchnorm.ipynb
    Zipping successful! Zip is stored under: /content/drive/My Drive/HW9/9/exercise_09_cleaned/exercise09.zip
```