Serim Ryou

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EDUCATION

California Institute of Technology

Ph.D. Candidate in Electrical Engineering

Adviser: Pietro Perona

California Institute of Technology

MS in Electrical Engineering

Korea University

BS in Electrical Engineering

Top graduating student in College of Engineering

Pasadena, CA

Pasadena, CA

Sep. 2014 - Present

2016

Seoul, South Korea

Mar. 2009 - Feb. 2014

KEYWORDS

Computer vision, Machine learning, Keypoint estimation, Graph neural network, Unsupervised learning

EXPERIENCE

Research Assistant

Sep. 2014 - Present

Computational Vision Lab, Caltech

Pasadena, CA

- Developed a multi-person pose estimation algorithm for 2D images with people having interaction using convolutional recurrent neural networks
- Proposed a loss function which modulates the loss scale based on the sample difficulty
- Developed a keypoint discovery method using weak supervision
- Proposed an unsupervised keypoint discovery method that is directly applicable to animal behavior classification

Research Assistant

Jan. 2019 - Jan. 2020

The Reisman Group, Caltech

Pasadena, CA

- Curated the dataset of four ubiquitous reactions from the organic chemistry literature
- Explored methods to predict the optimal reaction conditions for organic chemistry experiments
- Proposed an attention-based graph neural network by incorporating the information from multiple graphs

Undergraduate Research Assistant

Mar. 2011 – Mar. 2013

Korea University

Seoul, Korea

- Proposed an image retargeting algorithm using semantic segmentation and saliency analysis
- Implemented seam carving and patch-based image retargeting algorithms for performance evaluation
- Developed a probability density function for hand tracking using depth and motion information
- Implemented wave motion detection and camshift algorithm

Publications

- 1. Serim Ryou and Pietro Perona, Weakly Supervised Keypoint Discovery (under review) 2021
- 2. Michael R. Maser*, Alexander Y. Cui*, Serim Ryou*, Travis J. DeLano, Yisong Yue, Sarah E. Reisman, Multi-label Classification Models for the Prediction of Cross-Coupling Reaction Conditions, in Journal of Chemical Information and Modeling (JCIM) 2021
- 3. Serim Ryou*, Michael R. Maser*, Alexander Y. Cui*, Travis J. DeLano, Yisong Yue, Sarah E. Reisman, Graph Neural Networks for the Prediction of Substrate-Specific Organic Reaction Conditions, in ICML Workshop on Graph Representation Learning and Beyond 2020
- 4. Serim Ryou, Seong-Gyun Jeong, Pietro Perona, Anchor Loss: Modulating Loss Scale Based on Prediction Difficulty, in ICCV 2019 (Oral)
- 5. Serim Ryou and Pietro Perona, Parsing Pose of People with Interaction, in BMVC 2018 ^k denotes equal contribution

TECHNICAL SKILLS

National Scholarship for Science and Engineering, KOSAF

Guwon Scholarship, The Guwon Scholarship Foundation

Best Honors Scholarship, Korea University

Honors Scholarship, Korea University

Languages: Python, C/C++, MATLAB, OpenCV Frameworks: PyTorch, Chainer, Keras Developer Tools: Git, AWS TEACHING EE148 Selected Topics in Computational Vision 2021 Spring • Guest Lecturer (Lecture: Pose Estimation) EE148 Selected Topics in Computational Vision 2020 Spring • Teaching Assistant • Guest Lecture: (Lecture: Pose Estimation) Honors and Awards Ph.D. Fellowship, Korea Foundation for Advanced Studies (KFAS) 2014 - 2016 Valedictorian of College of Engineering, Korea University 2014

2012 - 2013

2012 - 2013

2009, 2010

2010