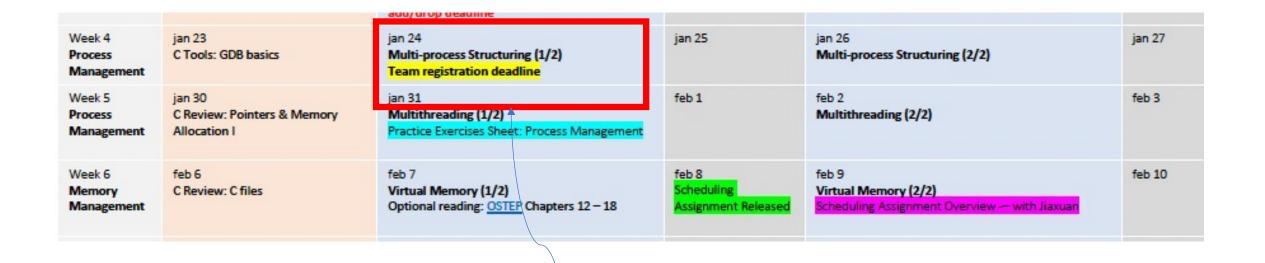
Week 4

Multiprocess Communication

Oana Balmau January 24, 2023

Schedule Highlights



Please sign up teams of 1 as well!

Recap Week 3 Concurrency – Option 1

- Build apps from many communicating processes
- Communicate through message passing
 - No shared memory
- Pros
 - If one process crashes, other processes unaffected
- Cons
 - High communication overheads
 - Expensive context switching



Recap Week 3 Two Processes

code globals heap stack registers PC

code globals heap stack registers PC

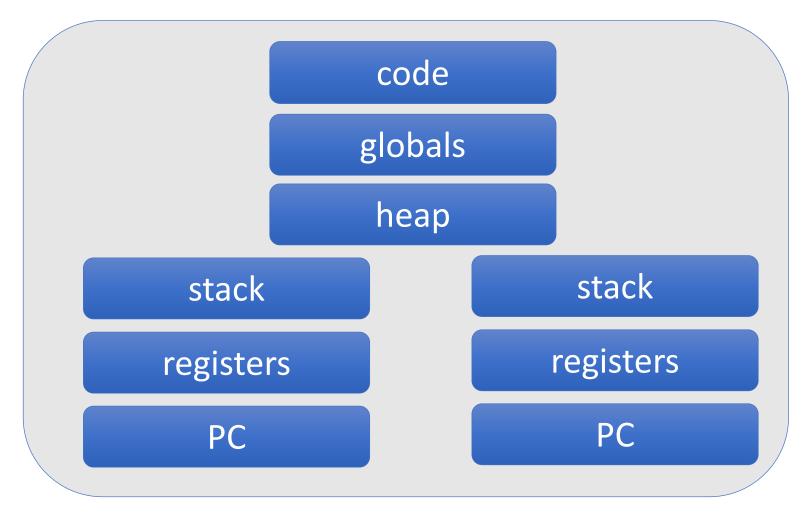
Recap Week 3 Concurrency – Option 2

- New abstraction: thread
- Multiple threads in a process

Will see practical examples in Week 5

- Threads are like processes except
 - Multiple threads in the same process share an address space
 - Communicate through shared address space
 - If one thread crashes,
 - the entire process, including other threads, crashes

Recap Week 3 Two Threads in a Process



Key Concepts for Today

- Interprocess communication
- Message passing
- Remote procedure call (RPC)

So far

- One program
 - = one process
- Examples:
 - Shell
 - Compiler
 - ...



This is not always the case

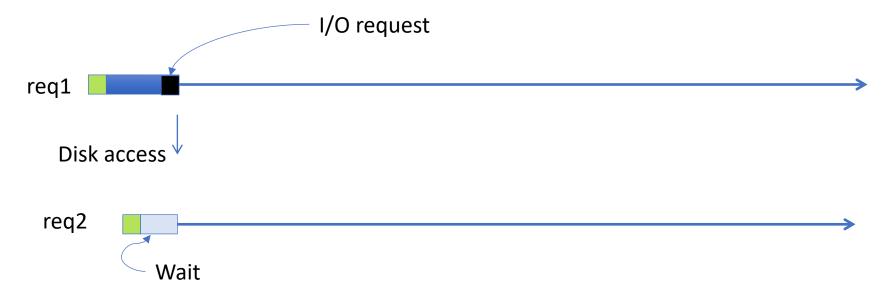
- One program
 - = multiple processes
- Example:
 - Web server

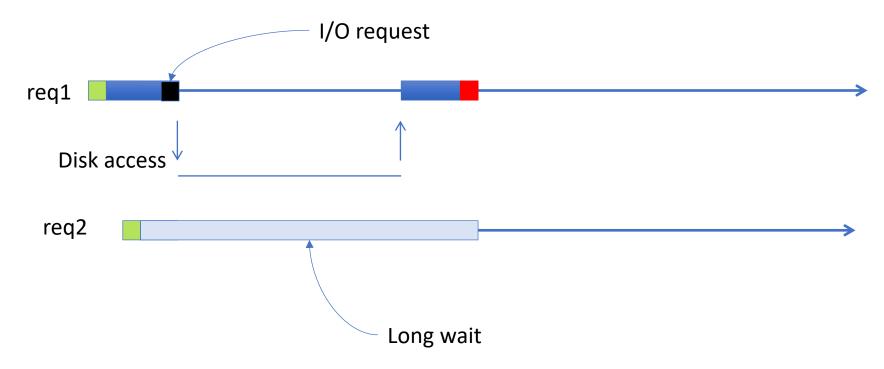


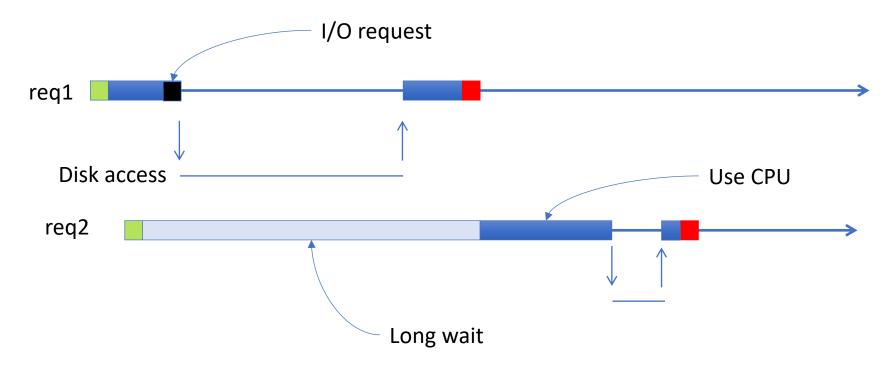
(Very Simple) Web Server

```
WebServerProcess {
    forever {
        wait for an incoming request
        read file from disk
        send file back in response
    }
}
```



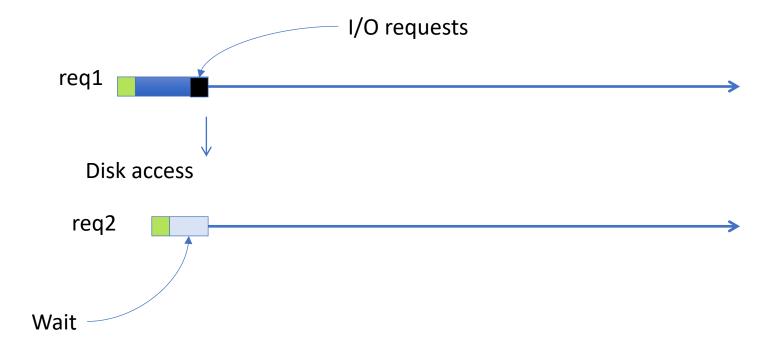


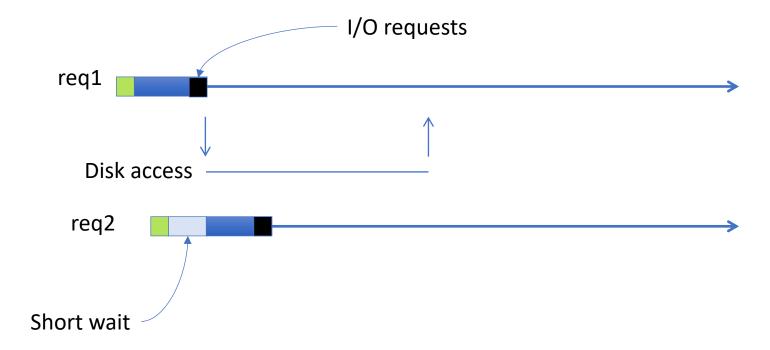


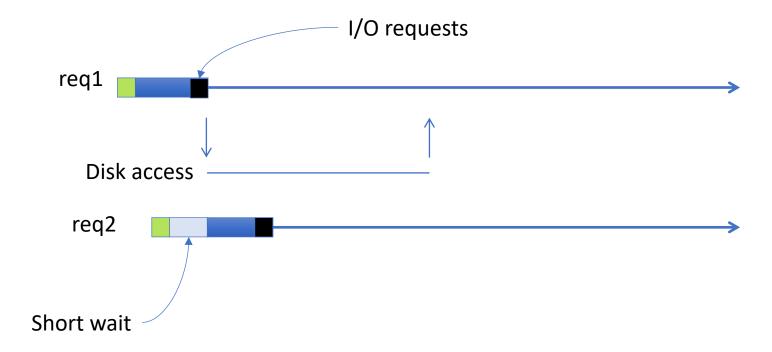


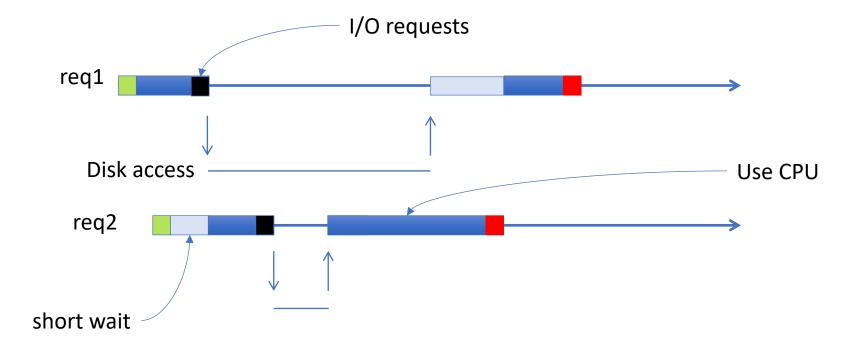
Multiprocess Web Server

```
ListenerProcess {
   forever {
     wait for incoming request
     CreateProcess( worker, request )
   }
}
WorkerProcess(request) {
   read file from disk
   send response
   exit
}
```

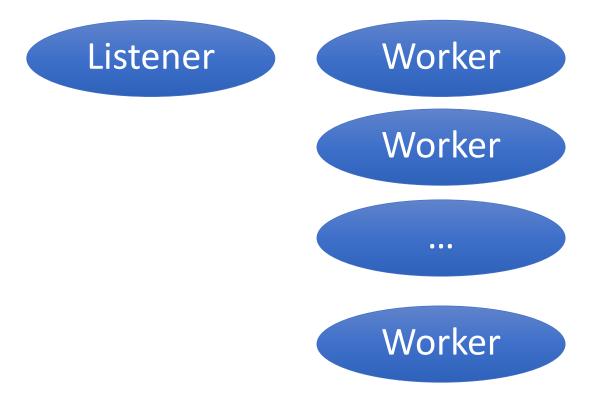




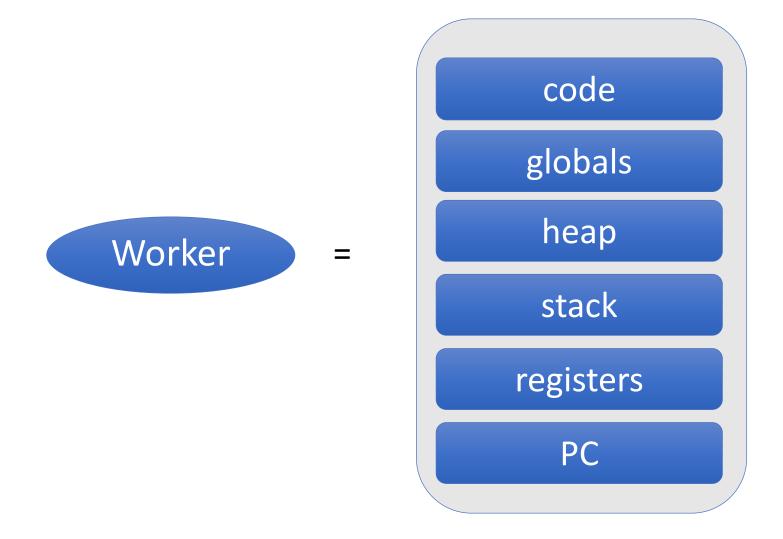




Multiprocess Web Server



Each Worker is a Process



Amount of work on server per request

- Receive network packet
- Run listener process
- Create worker process
- Read file from disk
- Send network packet

Amount of work on server per request

- Receive network packet
- Run listener process
- Create worker process is expensive
- Read file from disk
- Send network packet

Multiprocess Web Server

```
ListenerProcess {
  forever {
    wait for incoming request
    CreateProcess( worker, request )
  }
}

WorkerProcess(request) {
  read file from disk
  send response
  exit
}
```

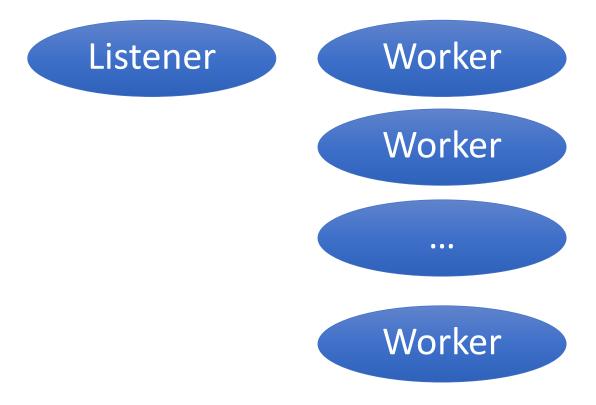
Process Pool

- Create worker processes during initialization
- Hand incoming request to them

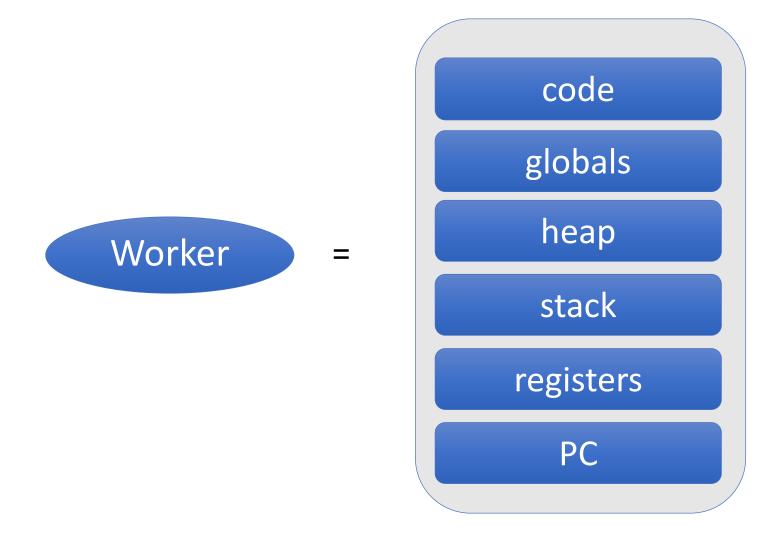
Multiprocess Web Server with Process Pool

```
ListenerProcess {
  for(i=0; i<MAX_PROCESSES; i++) process[i] = CreateProcess(worker)</pre>
    forever {
       wait for incoming request
       send(request, process[?])
WorkerProcess[?] {
  forever {
    wait for message(&request)
    read file from disk
    send response
```

Pictures remain the same



Pictures remain the same



What changed: Amount of work on server per request

- Receive network packet
- Run listener process
- Send message to worker process (cheaper)
- Read file from disk
- Send network packet

Interprocess Communication (IPC)

Interprocess Communication (IPC)

- OS support to allow the processes to manage shared data
 - Through message passing
 - Through remote procedure calls (RPC)

Where do you need IPC?

Multiprocess Web Server with Process Pool

```
ListenerProcess {
  for( i=0; i<MAX PROCESSES; i++ ) process[i] = CreateProcess(worker)</pre>
    forever {
       receive incoming request
      send( request, process[?] )
                                             Need IPC here
                                             For client-server communication
WorkerProcess[?] {
  forever {
    wait for message( &request/
    read file from disk
    send response -
```

Multiprocess Web Server with Process Pool

```
ListenerProcess {
  for( i=0; i<MAX PROCESSES; i++ ) process[i] = CreateProcess(worker)</pre>
    forever {
       receive incoming request
       send( request, process[?] )
                                             Need IPC here
                                             For communication between
WorkerProcess[?] {
  forever {
                                             cooperating processes
    wait for message( &request )
                                             (e.g., between listener and workers)
    read file from disk
    send response
```

Where do you need IPC?

- Between client and server
- Between cooperating processes

How to do IPC?

- Message passing
- Remote procedure calls (RPC)

Message Passing Primitives

- Send message
- Receive message

```
msg = alloc()
msg->field0 = 1
Send(msg, ...)
```

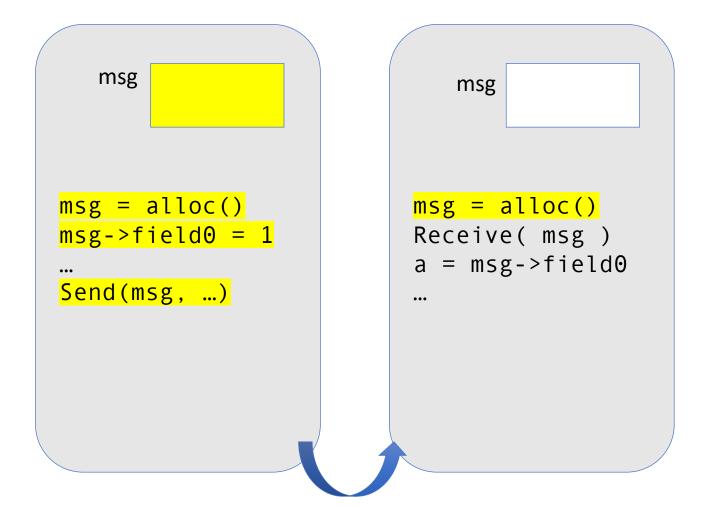
```
msg = alloc()
Receive( msg )
a = msg->field0
```

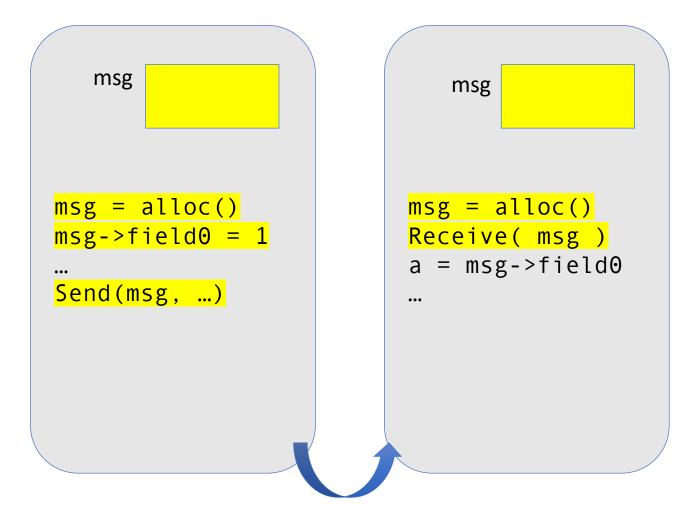
```
msg
msg = alloc()
                          msg = alloc()
msg->field0 = 1
                          Receive( msg )
                          a = msg->field0
Send(msg, ...)
```

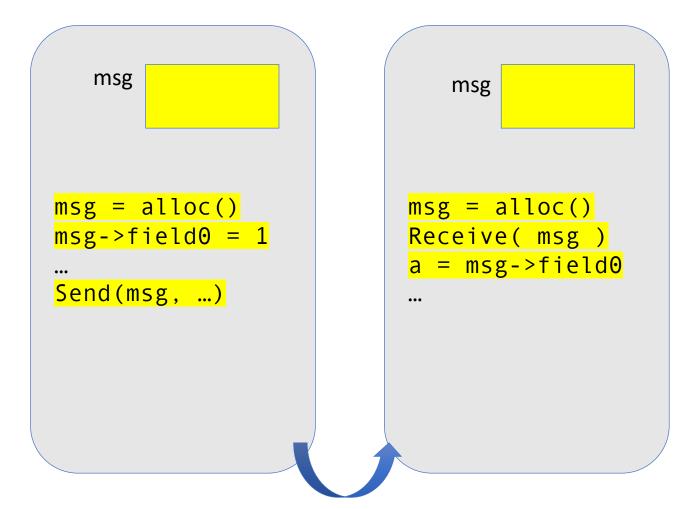
```
msg
msg = alloc()
msg->field0 = 1
Send(msg, ...)
```

```
msg = alloc()
Receive( msg )
a = msg->field0
```

```
msg
msg = alloc()
                          msg = alloc()
msg->field0 = 1
                          Receive( msg )
                          a = msg->field0
Send(msg, ...)
```



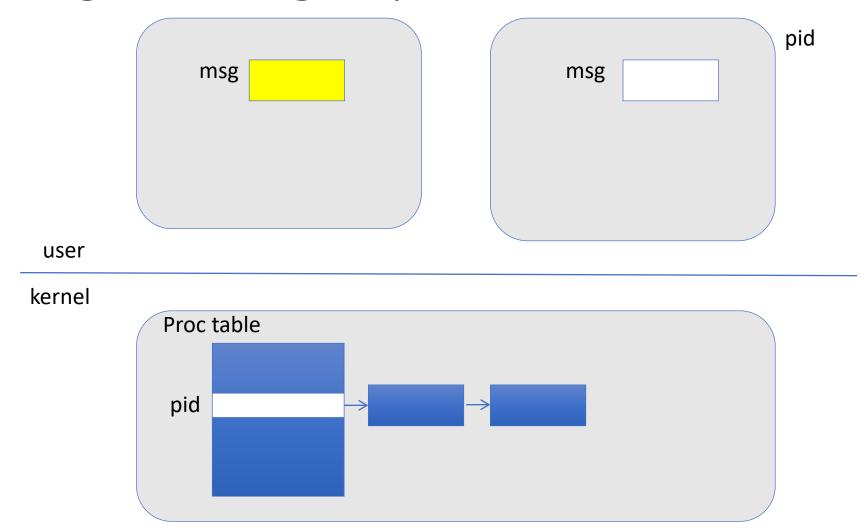




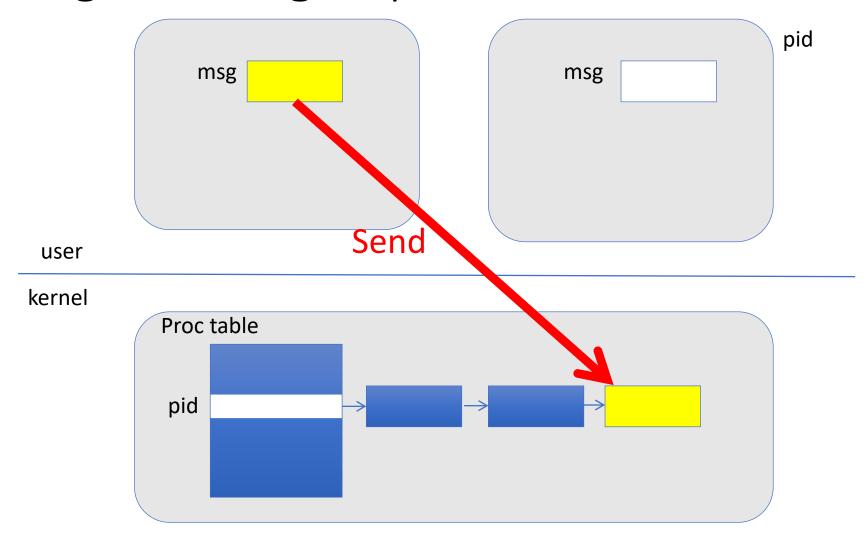
Message Passing

- By value communication
- Never by reference
- Receiver cannot affect message in sender

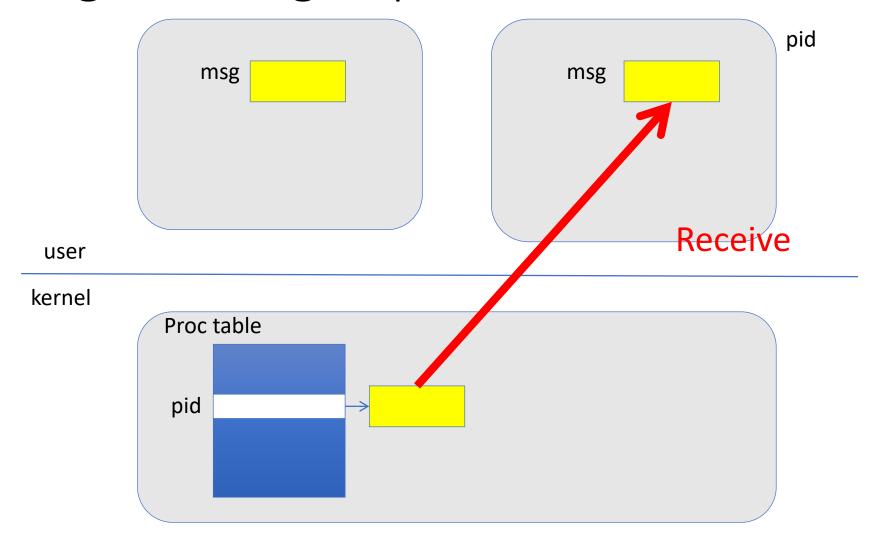
Message Passing Implementation



Message Passing Implementation



Message Passing Implementation



Message Passing Alternatives

- Symmetric / asymmetric addressing
- Blocking / nonblocking

Symmetric Addressing

- Send(msg, to_pid)
- Receive (msg, from_pid)
- Message is (typically) a struct
- to_pid, from_pid are process identifiers
- Symmetric addressing seldom used

Asymmetric Addressing

- Send(msg, pid)
 - Send msg to process pid
- pid = Receive(msg)
 - Receive msg from *any* process
 - Return the pid of sending process
- More common and useful form of addressing

Blocking or Nonblocking Send

- Nonblocking:
 - Send returns immediately after message is sent
- Blocking
 - Sender blocks until message is delivered
- Nonblocking is the more common form

Blocking or Nonblocking Receive

- Nonblocking
 - Receive returns immediately
 - Regardless of message present or not
- Blocking
 - Receive blocks until message is present
- Blocking is the more common form

(Slightly Rewritten) Example: Multiprocess Web Server with Process Pool

```
ListenerProcess {
  for(i=0; i<MAX PROCESSES; i++) process[i] = CreateProcess(worker)</pre>
    forever {
       client pid = receive(msg)
       msg' = slightly modify msg to include client pid
       send(msg', worker process[i])
WorkerProcess[i] {
  forever {
    receive(msg)
    read file from disk
    send(resp, client pid)
```

Asymmetric Addressing: Send

```
ListenerProcess {
  for(i=0; i<MAX PROCESSES; i++) process[i] = CreateProcess(worker)</pre>
    forever {
       client_pid = receive(msg)
       msg' = slightly modify msg to include client pid
       send(msg', worker process[i])
WorkerProcess[i] {
  forever {
    receive(msg)
    read file from disk
    send(resp, client_pid)
```

Asymmetric Addressing: Receive

```
ListenerProcess {
  for(i=0; i<MAX PROCESSES; i++) process[i] = CreateProcess(worker)</pre>
    forever {
       client_pid = receive(msg) /* receive msg from any client */
       msg' = slightly modify msg to include client_pid
       send(msg', worker process[i])
WorkerProcess[i] {
  forever {
    receive (msg) /* receive msg' from listener; could be symmetric */
    read file from disk
    send(resp, client_pid)
```

Blocking Receive

```
ListenerProcess {
  for(i=0; i<MAX PROCESSES; i++) process[i] = CreateProcess(worker)</pre>
    forever {
       client_pid = receive(msg) /* nothing else to do*/
       msg' = slightly modify msg to include client pid
       send(msg', worker process[i])
WorkerProcess[i] {
  forever {
    receive(msg) /* nothing else to do*/
    read file from disk
    send(resp, client_pid)
```

Nonblocking Send

```
ListenerProcess {
  for(i=0; i<MAX_PROCESSES; i++) process[i] = CreateProcess(worker)</pre>
    forever {
       client_pid = receive(msg)
       msg' = slightly modify msg to include client_pid
       send(msg', worker_process[i]) /* must not block */
WorkerProcess[i] {
  forever {
    receive(msg)
    read file from disk
    send(resp, client_pid) /* must not block */
```

Client-Server Communication

(Server Side) Client-Server Communication

```
ListenerProcess {
  for(i=0; i<MAX PROCESSES; i++) process[i] = CreateProcess(worker)</pre>
    forever {
       receive incoming request
       send( request, process[?] )
WorkerProcess[?] {
  forever {
    wait for message( &request )
    read file from disk
    send response
```

(Client-Side) Client-Server Communication

```
send(msg to server)
receive(reply msg from server)
```

A Very Common Pattern

• Client:

```
Send /* send request to server */
Blocking receive /* wait for reply */
Server
Blocking receive /* wait for request */
Send /* send reply */
```

This looks like ...

- Client:
 - Send
 - Blocking receive
- Server
 - Blocking receive
 - Send

calling site call procedure

return

callee site

invoke procedure

return

Remote Procedure Call (RPC)

- Client:
 - Send
 - Blocking receive
- Server
 - Blocking receive
 - Send

calling site
call procedure
return

callee site
invoke procedure
return

RPC: when client wants to call a function that belongs to server code

RPC Interface

- Interface
 - List of remotely callable procedures
 - With their arguments and return values

- Example: file system interface
 - Open(string filename)
 - returns int fd
 - fd = file descriptor; will see later in course
 - •

RPC Client Code

• Import file system interface

```
• fd = open("/a/b/c")
```

• nbytes = read(fd, buffer, size)

RPC Server Code

Export file system interface

```
int open(stringname) { ... }int read(fd, buffer, nbytes) { ... }...
```

Problem

- Want a procedure call interface
- Have only message passing between processes
- How to bridge the gap?

Solution: Stub Library

- Client stub and server stub
- Client stub linked with client process
- Server stub linked with server process

Two Message Types

- Call message
 - From client to server
 - Contains arguments
- Return message
 - From server to client
 - Contains return values

Client Stub

- Sends arguments in call message
- Receives return values in return message

Server Stub

- Receives arguments in call message
- Invokes procedure
- Sends return values in return message

RPC Implementation

client process

client code server process

server code

Client and Server Stubs

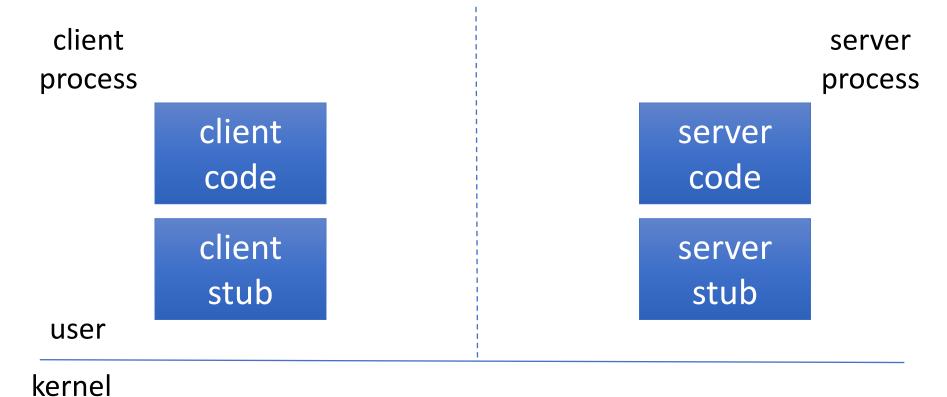
client process

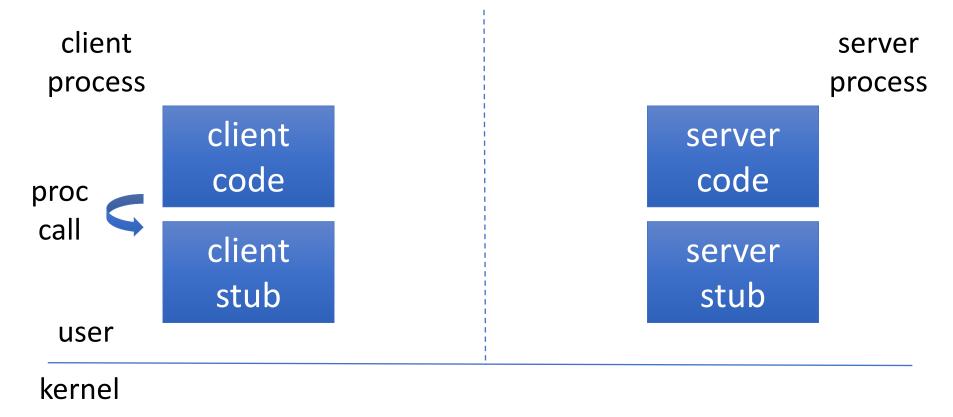
client code

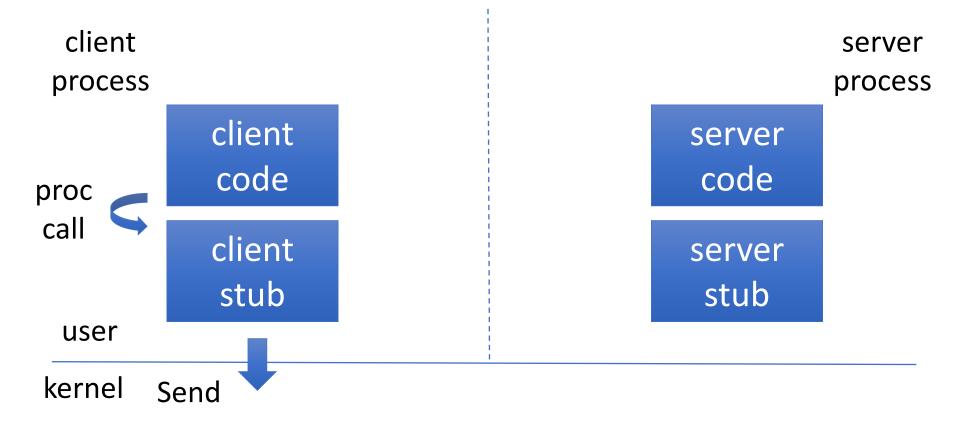
client stub server process

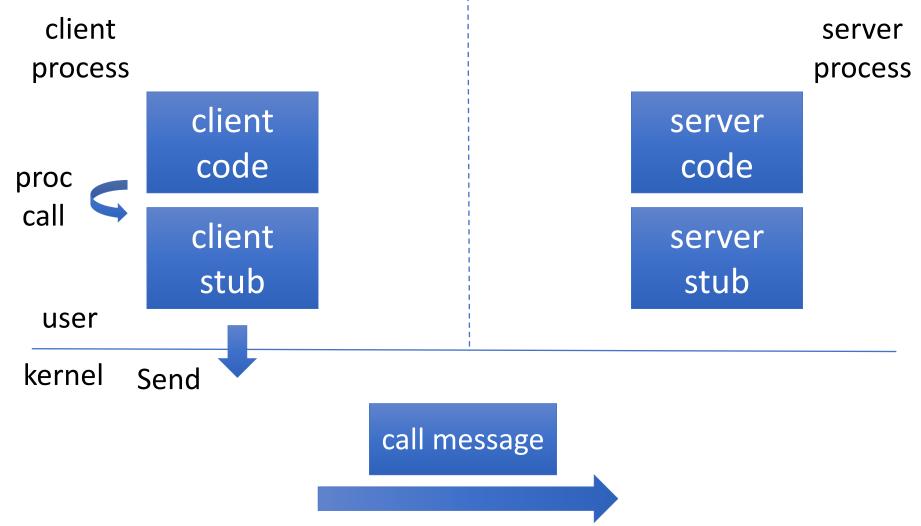
server code

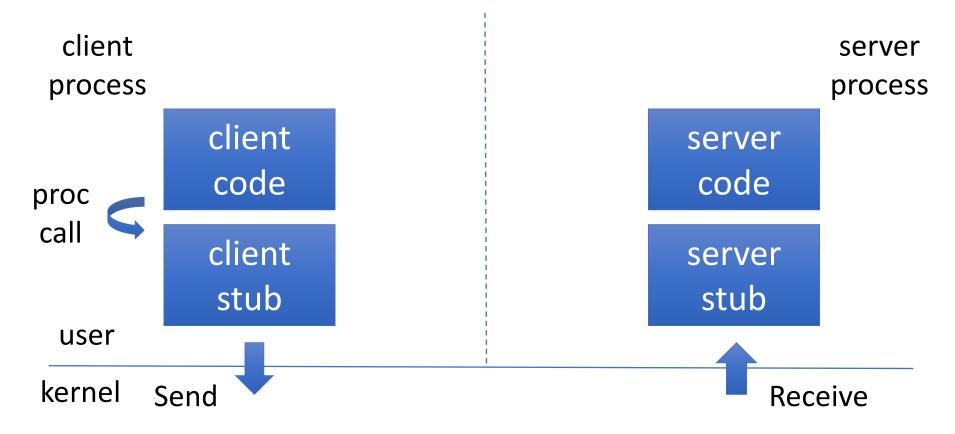
server stub

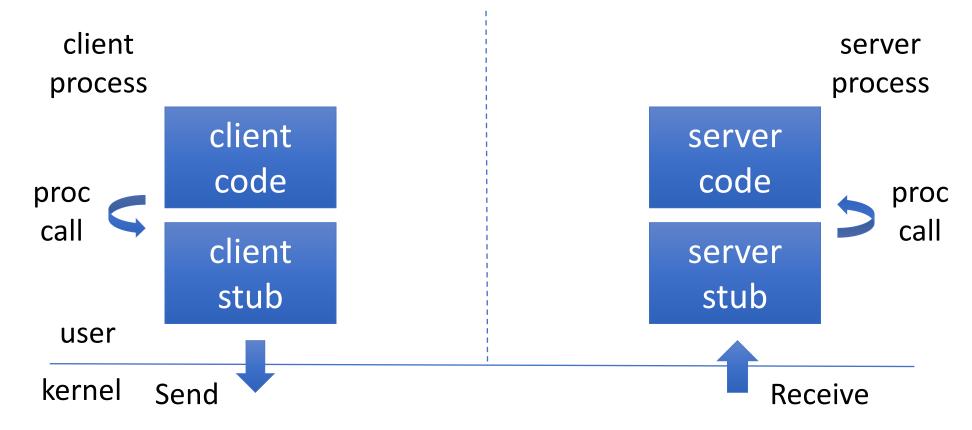


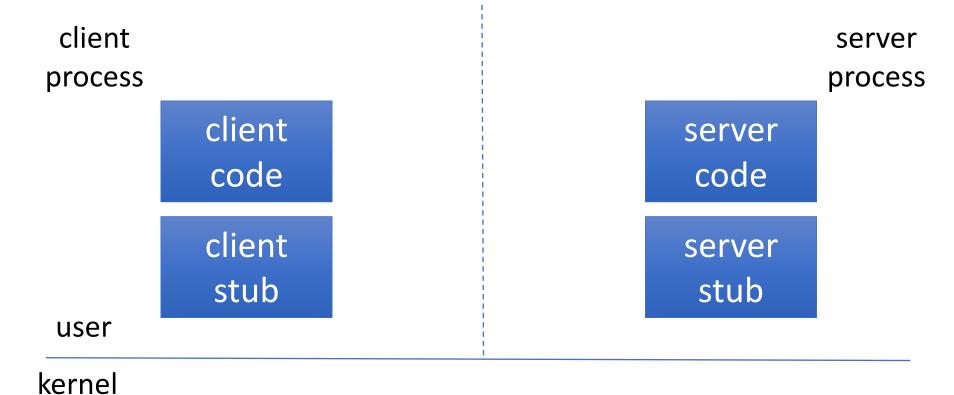


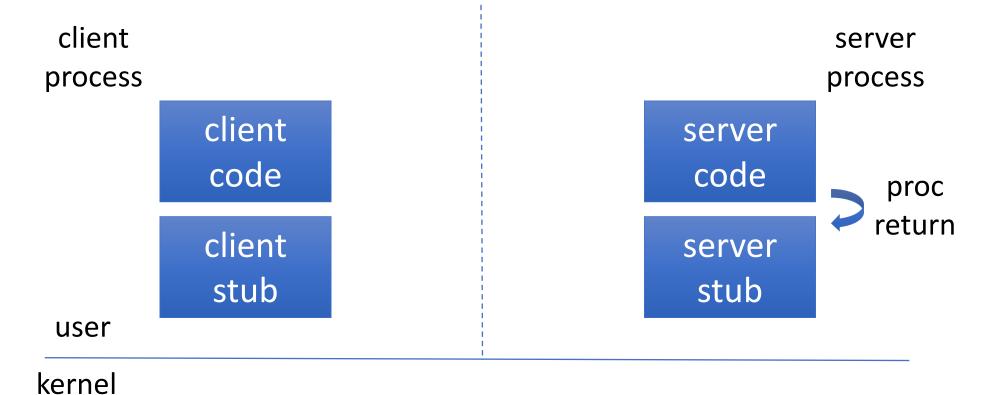


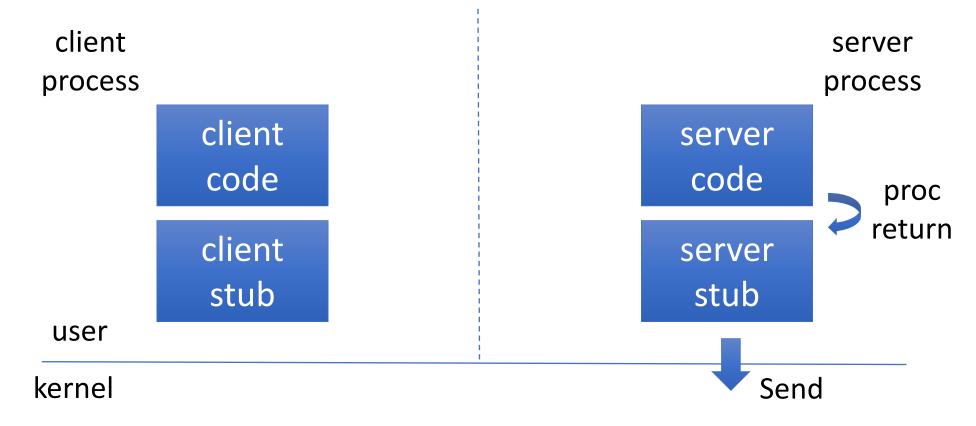


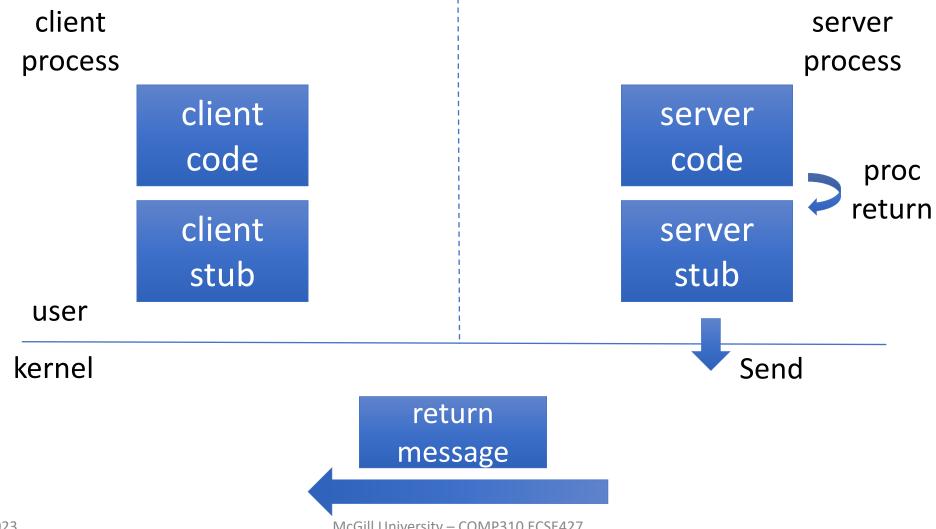


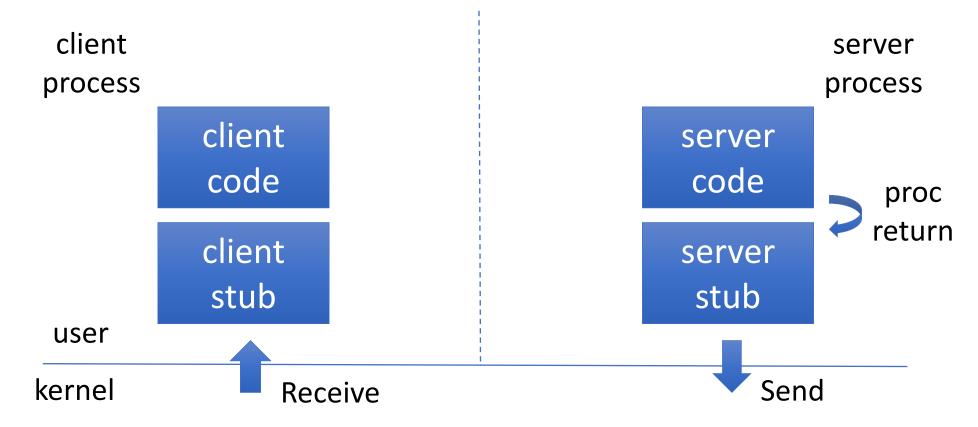


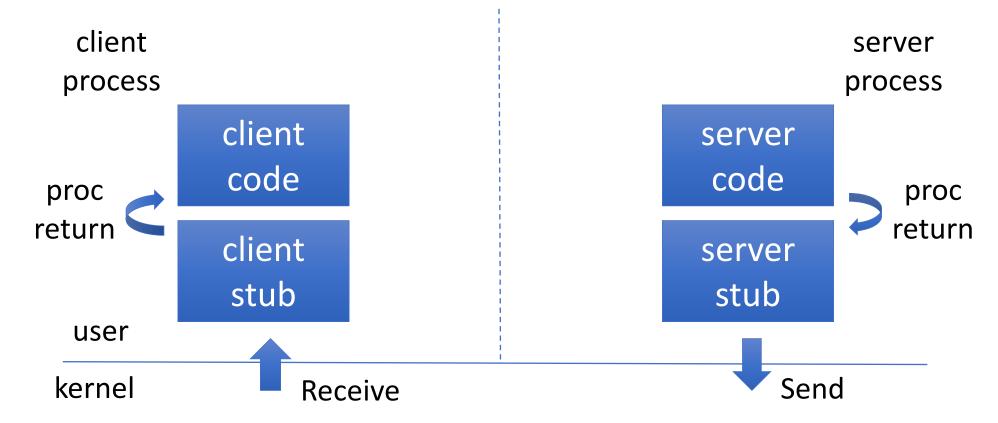












Further Optional Reading

Operating Systems: Three Easy Pieces by R. & A. Arpaci-Dusseau

Chapters 25 – 32 (inclusive) https://pages.cs.wisc.edu/~remzi/OSTEP/

Credits:

Some slides adapted from the OS courses of Profs. Remzi and Andrea Arpaci-Dusseau (University of Wisconsin-Madison), Prof. Willy Zwaenepoel (University of Sydney), and Prof. Maurice Herlihy (Brown University)