

Mock Quiz

1. $V \in \mathbb{R}^{n \times n}$ is a unitary (or orthonormal) matrix if and only if $V^T V = U$ where U is the identity Matrix. Show that $\|Vx\|_2 = \|x\|_2$.

Hint. $\|x\|_2^2 = x^T x, \quad x \in \mathbb{R}^n$

$V \in \mathbb{R}^{n \times n}$ (V is a $n \times n$ real valued matrix)

$x \in \mathbb{R}^n$ (x " " $n \times 1$ " " vector)

$$\Rightarrow Vx \in \mathbb{R}^n$$

Square of 2-norm of Vx can be written as

$$\begin{aligned}\|Vx\|_2^2 &= (Vx)^T (Vx) \\ &= x^T V^T V x\end{aligned}$$

Since V is orthonormal matrix, $V^T V = U_{n \times n}$ (identity)

$$\begin{aligned}\Rightarrow \|Vx\|_2^2 &= x^T U x \\ &= x^T x\end{aligned}$$

$$\Rightarrow \|Vx\|_2^2 = \|x\|_2^2$$

Thus $\|Vx\|_2 = \|x\|_2$.

2. Using singular value decomposition, a matrix $A \in \mathbb{R}^{n \times n}$ can be decomposed into matrix $A = USV^T$ where U and V are unitary and S is a diagonal matrix with the positive singular values on the diagonal. In class we showed that $\|A\|_2 = \sigma_{\max}$, where σ_{\max} is the largest singular value of matrix $A \in \mathbb{R}^{n \times n}$. Based on this result show that $\|A^{-1}\|_2 = \frac{1}{\sigma_{\min}}$, where σ_{\min} is the smallest singular value of matrix $A \in \mathbb{R}^{n \times n}$. Find an expression for the condition of matrix $A \in \mathbb{R}^{n \times n}$.

$$A = U S V^T \leftarrow$$

$$\|A\|_2 = \sigma_{\max} \quad . \quad \boxed{\|A^{-1}\|_2 = \frac{1}{\sigma_{\min}}}$$

Definition of matrix norm,

$$\|A\|_2 = \max_{\|x\|_2 \neq 0} \frac{\|Ax\|_2}{\|x\|_2}$$

Thus assuming A is invertible, we can write 2-norm of A^{-1} as,

$$\|A^{-1}\|_2 = \max_{\|x\|_2 \neq 0} \frac{\|A^{-1}x\|_2}{\|x\|_2}$$

Suppose, $y = A^{-1}x \Rightarrow Ay = x.$

$$\Rightarrow \|A^{-1}\|_2 = \max_{\|y\|_2 \neq 0} \frac{\|y\|_2}{\|Ay\|_2}$$

The above can be written as,

$$\|A^{-1}\|_2 = \max_{\|y\|_2 \neq 0} \left(\frac{1}{\|Ay\|_2 / \|y\|_2} \right)$$

$$\|A^{-1}\|_2 = \frac{1}{\min_{\|y\|_2 \neq 0} \left(\frac{\|Ay\|_2}{\|y\|_2} \right)} = \frac{1}{\min_{\|y\|_2=1} \|Ay\|_2}$$

The matrix A can be decomposed using SVD.
as, $A = U S V^T$

$$\Rightarrow \|A^{-1}\|_2 = \frac{1}{\min_{\|y\|_2=1} \|U S V^T y\|_2}$$

Since U is orthonormal matrix therefore $\|Uw\|_2 = \|w\|_2$ for any vector w .

$$\|A^{-1}\|_2 = \frac{1}{\min_{\|y\|_2=1} \underbrace{\|U S V^T y\|_2}_w} = \frac{1}{\min_{\|y\|_2=1} \|S V^T y\|_2}$$

Similarly V is also a orthonormal matrix

$$\Rightarrow \|A^{-1}\|_2 = \frac{1}{\min_{\|y\|_2=1} \underbrace{\|S V^T y\|_2}_w} = \frac{1}{\min_{\|y\|_2=1} \|S y\|_2}$$

$$S = \begin{bmatrix} \sigma_1 & & \\ & \sigma_2 & \\ & & \ddots \\ & & & \sigma_n \end{bmatrix}, \quad \sigma_1 > \sigma_2 > \dots > \sigma_n$$

the minimum of $\|S y\|_2$ happens when $y = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}_{n \times 1}$

$$\Rightarrow \min_{\|y\|_2=1} \|S y\|_2 = \sigma_n \quad \leftarrow \text{minimum singular value.}$$

$$\Rightarrow \|A^{-1}\|_2 = \frac{1}{\sigma_{\min.}}$$

!!! $K(A) = \|A\|_2 \|A^{-1}\|_2 = \frac{\sigma_{\max}}{\sigma_{\min.}} \leftarrow \text{ratio of maximum \& minimum singular values.}$

What can be said about singular values of $A^T A$?

Hint:

$$A^T A = (U S V^T)^T (U S V)$$

$$= \dots$$

3. Given a square **lower triangular** matrix $L, L \in \mathbb{R}^{n \times n}$. We need to solve for the solve for the following system of equations.

$$L y = b$$

$$\begin{bmatrix} l_{11} & & & & \\ l_{21} & l_{22} & & & \\ l_{31} & l_{32} & l_{33} & & \\ \vdots & \vdots & \vdots & \ddots & \\ l_{n1} & l_{n2} & l_{n3} & \dots & l_{nn} \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_n \end{bmatrix}$$

Do we need to invert the matrix L ? How can we solve for y ?

Row 1: $l_{11} y_1 = b_1 \Rightarrow y_1 = b_1 / l_{11}$

Row 2: $l_{21} y_1 + l_{22} y_2 = b_2 \Rightarrow y_2 = \frac{1}{l_{22}} (b_2 - y_1 l_{21})$

Row 3: $l_{31} y_1 + l_{32} y_2 + l_{33} y_3 = b_3$

$$y_3 = \frac{1}{l_{33}} (b_3 - l_{31} y_1 - l_{32} y_2)$$

$$y_n = \frac{1}{l_{nn}} \left(b_n - \underbrace{l_{n1} y_1 - l_{n2} y_2 - \dots - l_{n,n-1} y_{n-1}} \right)$$

$$y_n = \frac{1}{l_{nn}} \left(b_n - \sum_{j=1}^{n-1} l_{nj} y_j \right) \leftarrow$$

$y = [0; 0; \dots 0]_{n \times 1}$ (initiate a zero valued $n \times 1$ column vector).

$$y_1 = \frac{b_1}{l_{11}}.$$

for $I = 2$ to n

$$y_I = \frac{1}{l_{II}} \left(b_I - \sum_{j=1}^{I-1} l_{Ij} y_j \right)$$

end

Since y is initiated as a column matrix of zeros and L is a lower triangular matrix.

The summation, $\sum_{j=1}^{I-1} l_{Ij} y_j$ can be

written as. $l_{I,:} y$ \rightarrow column(vector) y .

\uparrow
 I^{th} row of L matrix

4. Given a square **upper triangular** matrix U , $U \in \mathbb{R}^{n \times n}$. We need to solve for the solve for the following system of equations.

$$Ux = y$$

$$\rightarrow \begin{bmatrix} u_{11} & u_{12} & u_{13} & \dots & u_{1n} \\ & u_{22} & u_{23} & \dots & u_{2n} \\ & & u_{33} & \dots & u_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ & & & \dots & u_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_n \end{bmatrix}$$

Do we need to invert the matrix U ? How can we solve for x ?

$$u_{nn} x_n = y_n \quad \Leftrightarrow \quad x_n = y_n / u_{nn}$$

$$u_{33} x_3 + u_{34} x_4 + \dots + u_{3n} x_n = y_3$$

$$u_{33} x_3 = y_3 - (u_{34} x_4 + \dots + u_{3n} x_n)$$

$$x_3 = \frac{1}{u_{33}} \left(y_3 - (u_{34} x_4 + \dots + u_{3n} x_n) \right)$$

$$x_3 = \frac{1}{u_{33}} \left(y_3 - \underbrace{U(3, 4:n) * X(4:n)}_{\text{3rd Row columns 4 to n}} \right)$$

Generalise,

$$X(I) = \frac{1}{u(I, I)} \left(y(I) - \underbrace{U(I, I+1:n)}_{\substack{\text{Ith Row} \\ \text{of } U}} * X(I+1:n) \right)$$

$$X = [0; 0; \dots; 0]_{n \times 1}$$

% initiate x as a column vector of zeros.

$$x_n = y_n / u_{nn}$$

for I = n-1 to 1

% n > 1

$$x_I = \frac{1}{u_{II}} \left(y_I - \sum_{j=I+1}^n u_{Ij} x_j \right)$$

end .

↓

$$u_{I,i} * x$$

5. Given a system of equations $Ax = b$ ($A \in \mathbb{R}^{n \times n}$, $x \in \mathbb{R}^n$, and $b \in \mathbb{R}^n$), where matrix A is nonsingular. How will you solve for x using LU decomposition? Show your steps.

$$Ax = b.$$

$$L \underbrace{Ux}_y = b.$$

$$\textcircled{1} \quad Ly = b$$

Solve this by Forward Sub.

$$Ux = y$$

Solve this by backward
Sub.

6. Given an over determined system of equations $Ax = b$ (i.e., $A \in \mathbb{R}^{m \times n}$, $x \in \mathbb{R}^n$, and $b \in \mathbb{R}^m$, with $m > n$). How will you best x using method of least squares? Show your steps. What are possible algorithms for you could use?

$$A_{m \times n} x_{n \times 1} = b_{m \times 1}$$

$$\text{Residual, } r = Ax - b.$$

$$\|r\|_2 = \|Ax - b\|_2$$

We minimize the norm of residual, in lecture we saw that this happens when residual, r is orthogonal (i.e. perpendicular) to column space of A .

$$\Rightarrow A^T r = 0$$

$$A^T (Ax - b) = 0$$

$$A^T A x = A^T b$$

The above set of equations are called normal equations.

$$(A_{m \times n})^T A_{m \times n} = \underbrace{A_{n \times m}^T A_{m \times n}}_{n \times n \text{ (square)}}.$$

* $A^T A x = A^T b$ can be solved using Cholesky then use forward and backward substitutions.

$$\underbrace{A^T A}_{} x = A^T b.$$

LL^T , L is a lower triangular matrix.

$$\Rightarrow L \underbrace{L^T x}_y = A^T b$$

$Ly = A^T b \rightarrow$ solve using Forward substitution.

$L^T x = y \rightarrow$ solve using Backward substitution.