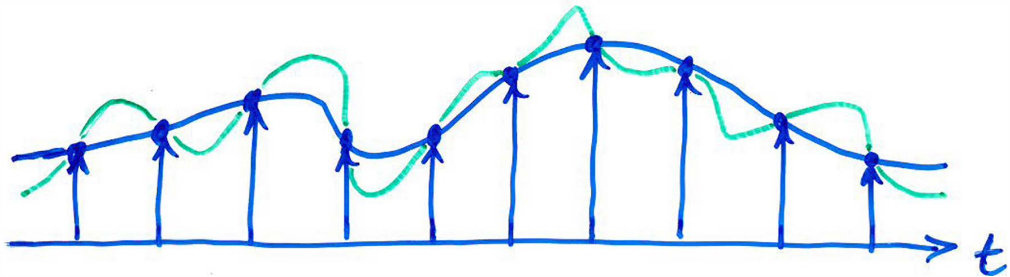


# SAMPLING (p 514)

## CT SIGNAL AND ITS SAMPLES

Q. WHEN CAN YOU SAMPLE A C.T. SIGNAL AND THEN EXACTLY RECONSTRUCT IT FROM THE SAMPLES?



## IMPULSE TRAIN SAMPLING

IMPULSE TRAIN  $p(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$

SAMPLING OF  $x(t)$

GIVES  $x_p(t) = x(t) p(t)$   
 $= \sum_{n=-\infty}^{\infty} x(nT) \delta(t - nT)$

Now,

$$X_p(j\omega) = \frac{1}{2\pi} X(j\omega) * P(j\omega)$$

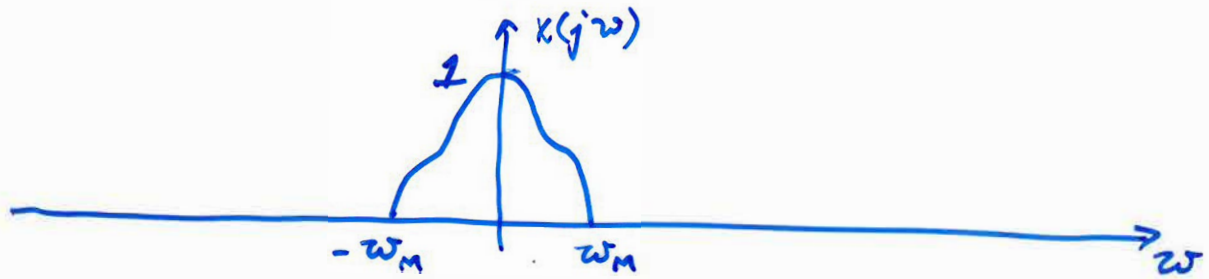
$$\& P(j\omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\omega - k\omega_s)$$

$$\omega_s = \frac{2\pi}{T}$$

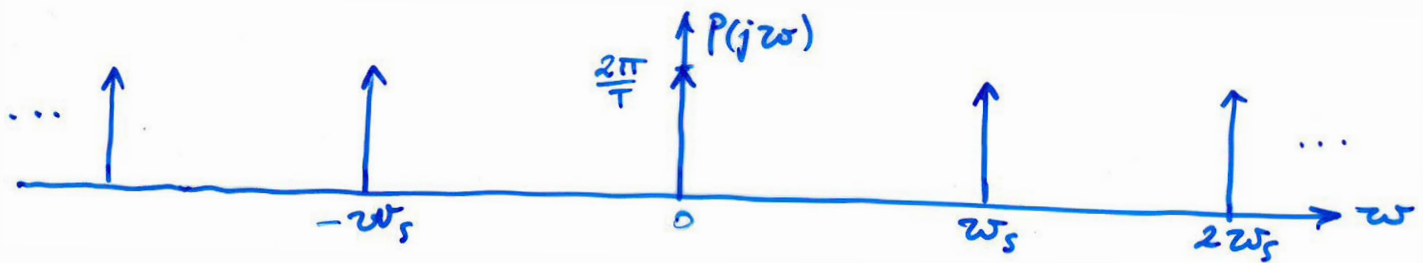
from  $p(t) \Rightarrow a_k = \frac{1}{T}$   $\left( a_k = \frac{1}{T} \int_{-T/2}^{T/2} p(t) e^{-jk\omega_s t} dt \right)$   
 $P(j\omega) = \sum_{k=-\infty}^{\infty} 2\pi a_k \delta(\omega - k\omega_s)$

$$\Rightarrow X_p(j\omega) = \frac{1}{T} X(j\omega) * \sum_{k=-\infty}^{\infty} \delta(\omega - k\omega_s)$$

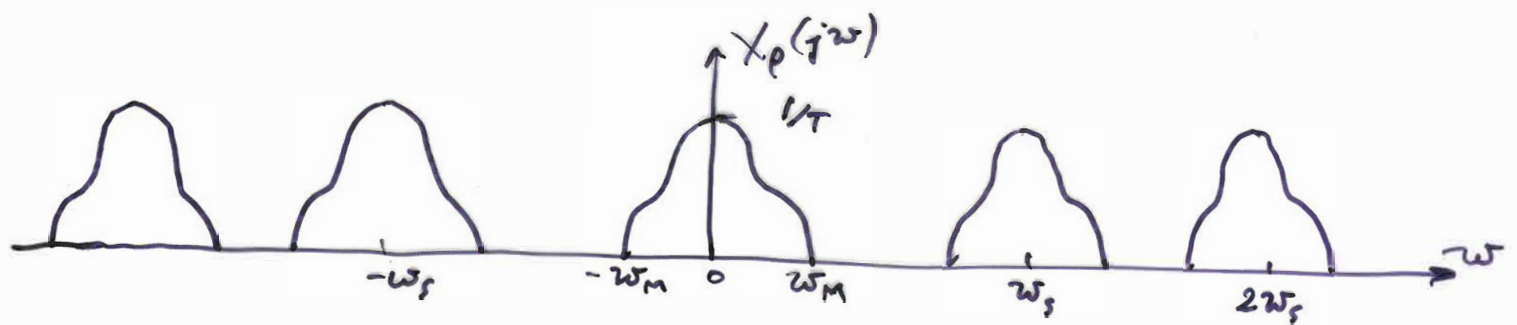
$$= \frac{1}{T} \sum_{k=-\infty}^{\infty} X(j(\omega - k\omega_s))$$



\*

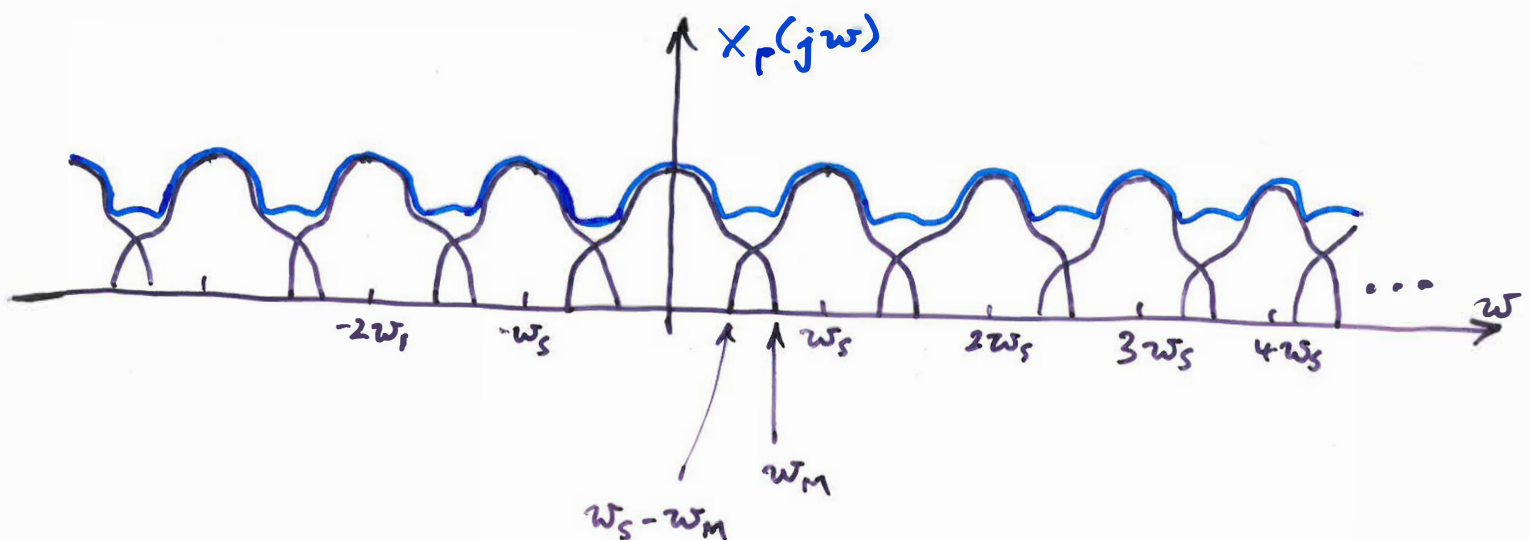


||

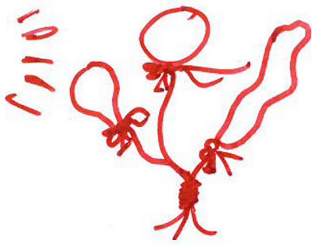


$$\omega_s = \frac{2\pi}{T}$$

OR, IF SAMPLING RATE IS SLOW ie  $\omega_s$  IS SMALLER



# SAMPLING THEOREM



FOR  $x(t)$  BANDLIMITED  $X(j\omega) = 0$  FOR  $|\omega| > \omega_M$

IF SAMPLING IS DONE AT PERIOD  $T$

THEN  $x(t)$  IS UNIQUELY DETERMINED BY SAMPLES  $x(nT)$

IF

$$\omega_s = \frac{2\pi}{T} > 2\omega_M$$

$2\omega_M$  IS CALLED NYQUIST RATE

$\omega_M$  IS CALLED NYQUIST FREQUENCY

RECOVER  $x(t)$  FROM  $x_p(t)$  USING IDEAL L.P.F.



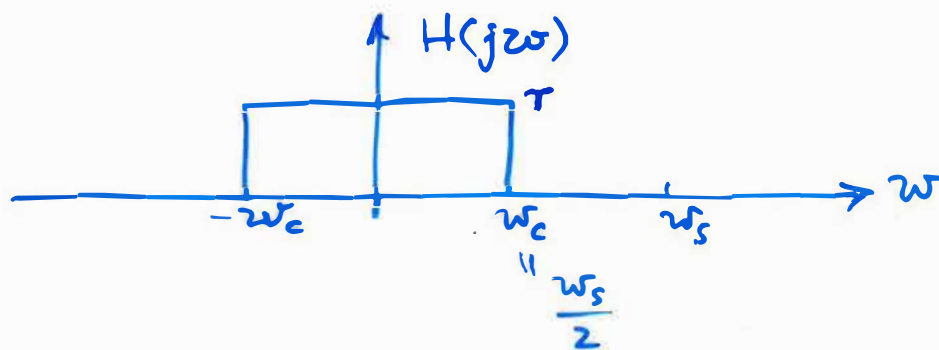
$x_r(t) = x(t)$  IF  $\omega_s > 2\omega_M$

&  $h(t)$  IDEAL L.P.F

# RECONSTRUCTION FROM SAMPLES

## INTERPOLATION (p 522)

### IDEAL LOW PASS FILTER (WITH GAIN T)

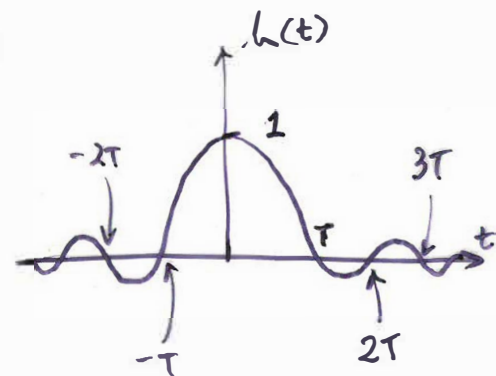


$$\omega_s = \frac{2\pi}{T}$$

$$\Rightarrow h(t) = T \frac{\sin(\omega_c t)}{\pi t}$$

$$h(t) = 0 \text{ when } \omega_c t = k\pi$$

$$\text{ie. } t = \frac{2k\pi}{\omega_s} = kT$$



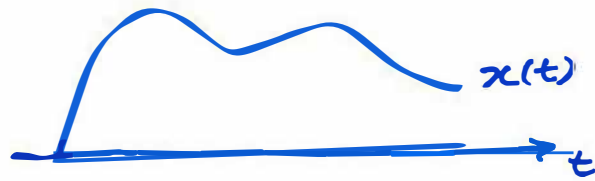
Recall,

$$x_p(t) = \sum_{n=-\infty}^{\infty} x(nT) \delta(t - nT)$$

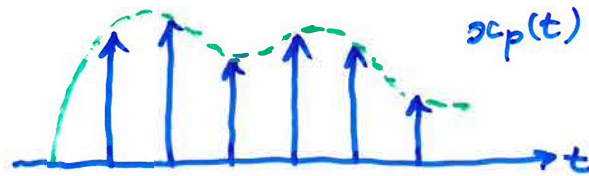
$$\Rightarrow x_r(t) = \sum_{n=-\infty}^{\infty} x(nT) \underbrace{h(t - nT)}$$

↑  
shifted sinc  $f^h$

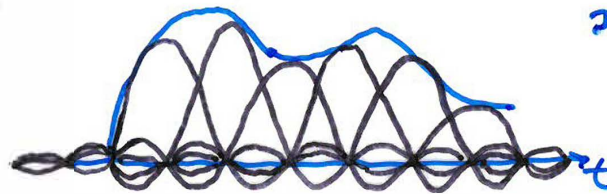
ORIGINAL



SAMPLED



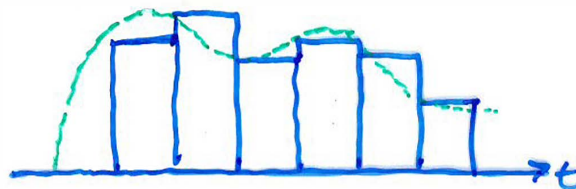
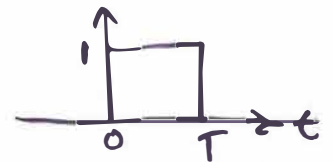
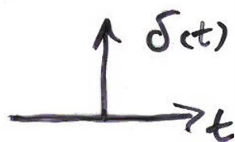
RECONSTRUCTED



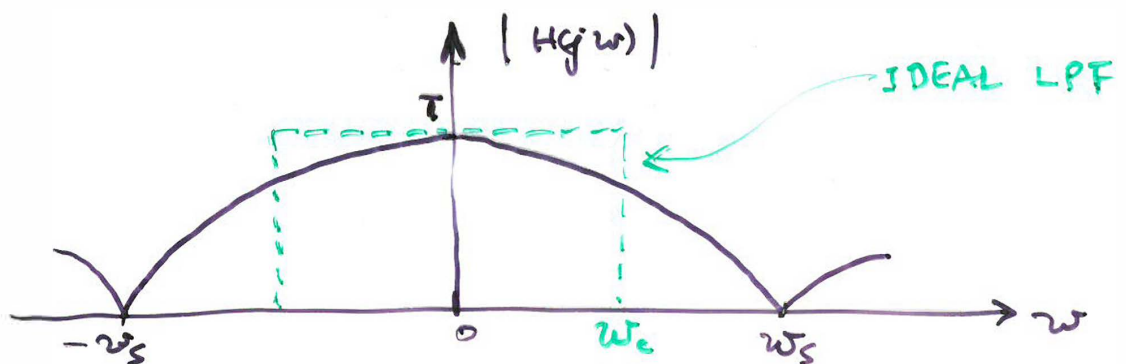
$$x_r(t) = x_p(t) * h(t)$$

RECONSTRUCTED EXACTLY IF NYQUIST SATISFIED

ZERO ORDER HOLD

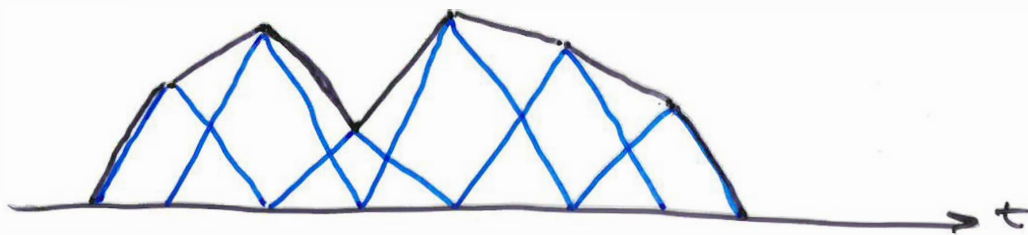
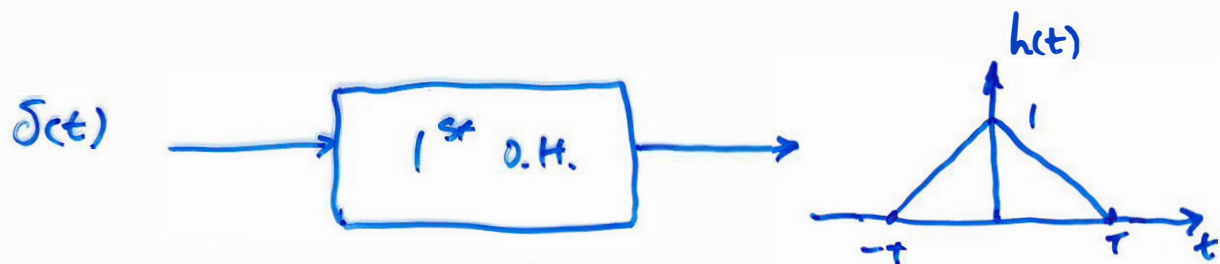
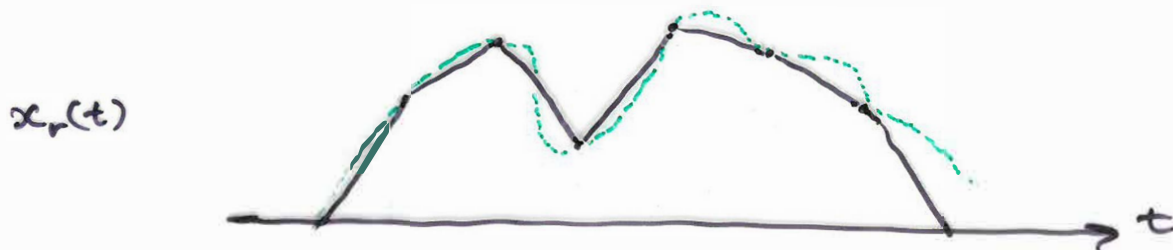
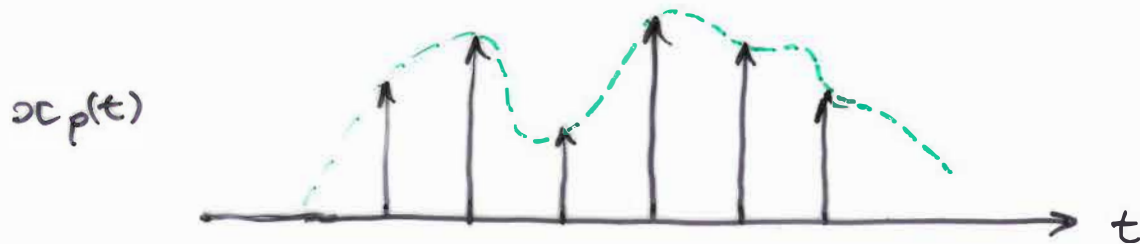


$$H(j\omega) = e^{-j\omega T/2} \frac{2 \sin(\omega T/2)}{\omega}$$

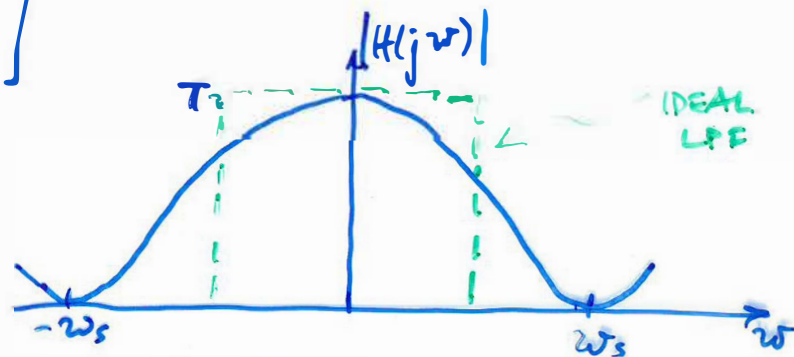




# FIRST ORDER HOLD (LINEAR INTERPOLATION)

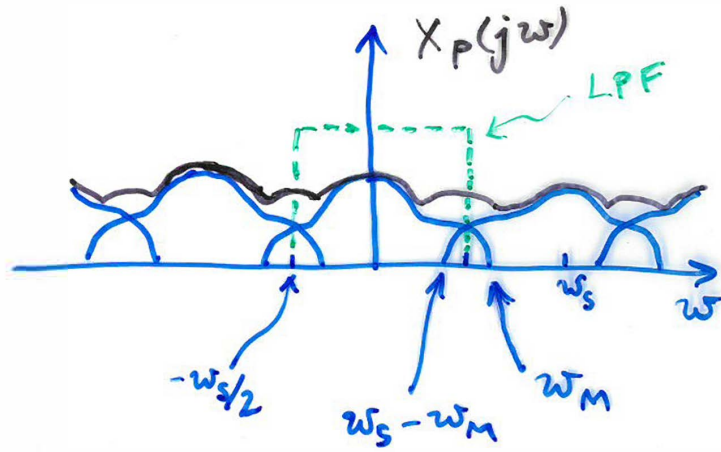
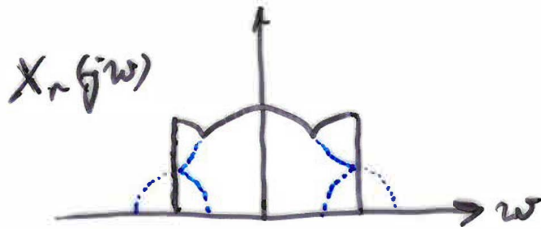
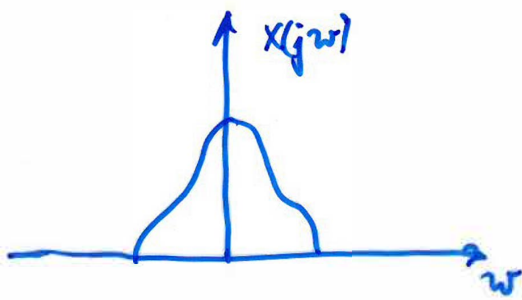


$$H(j\omega) = \frac{1}{T} \left[ \frac{\sin(\frac{\omega T}{2})}{\omega/2} \right]^2$$



## ALIASING (p 527)

SUPPOSE  $w_s < 2w_m$



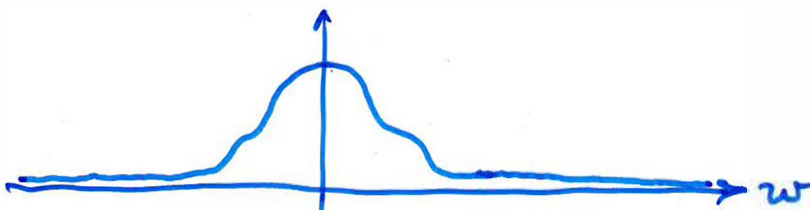
$$\left[ \begin{array}{l} \text{HERE, } w_s - w_m < w_m \\ \Rightarrow w_s < 2w_m \end{array} \right]$$

USING IDEAL LPF DOES NOT RECOVER SIGNAL

\* HIGH FREQUENCIES ARE MAPPED TO LOW FREQS!!  
 ↑  
 (FOLDED BACK)

SINCE "NOISE" IN A SYSTEM HAS BROAD SPECTRUM

A TYPICAL SIGNAL REALLY LOOKS LIKE:



∴ NEED TO L.P.F. BEFORE SAMPLING SO THAT THE HIGH FREQ NOISE DOESN'T GET FOLDED BACK AND RECONSTRUCTION!

