

## Type 1. Perceptual Error

### Case: Car Crash



**Video LLaVA:** The video shows a traffic scene with **vehicles stopped** at a **red light**. Model fail to detect the **crossing car**, and perpendicular **crossing motorcycle**.

### Case: Protest



**InternVL:** The **police** are standing in a formation facing the **crowd**, and the crowd is not showing **any signs of aggression or disturbance**. Model fails to detect **one protestor is touching a policeman** and showing **signs of shoving**.

## Type 2. Reasoning Error

### Case: Car Crash



**Gemini:** There is **no erratic driving behavior**, and the drivers are maintaining a safe distance. Model failed to reason that **the right front car** is having abnormal driving behavior cutting in front of the ego car.

### Case: Protest



**MiMoRL:** ...The presence of police in riot gear and the close proximity of the protesters suggest a potential for conflict or escalation... Model failed to account for the fact that **moderate proximity is common in protest settings**.

## Type 3. Conclusion Error

### Case: Car Crash



**Qwen-8b:** Answer: **No**. Model made **false negative** conclusion.

### Case: Protest



**Apollo:** Answer: **No**. Model made **false negative** conclusion.