

# Edge-Adaptive Image Interpolation with Contour Stencils

Pascal Getreuer

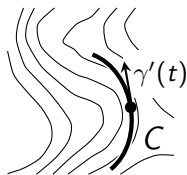
Dec 27, 2010

# TV along Curves

Let  $u$  be an image. For  $C$  a smooth simple curve, define

$$\|u\|_{\text{TV}(C)} = \int_0^T \left| \frac{\partial}{\partial t} u(\gamma(t)) \right| dt, \quad \gamma : [0, T] \rightarrow C.$$

**Strategy:** Find approximate contours of  $u$  by finding curves  $C$  such that  $\|u\|_{\text{TV}(C)}$  is small.

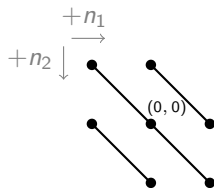


# Contour Stencils

A *contour stencil* is a function  $\mathcal{S} : \mathbb{Z}^2 \times \mathbb{Z}^2 \rightarrow \mathbb{R}$  describing edges between pixels, and TV is estimated as

$$(\mathcal{S} \star [u])(k) := \sum_{m,n \in \mathbb{Z}^2} \mathcal{S}(m,n) |u_{k+m} - u_{k+n}| \approx \|u\|_{\text{TV}(C)}$$

where  $\mathcal{S}$  describes edges that approximate  $C$ .



$$\begin{aligned} (\mathcal{S} \star [u])(i,j) = & (|u_{i,j-1} - u_{i+1,j}| \\ & + |u_{i-1,j-1} - u_{i,j}| + |u_{i,j} - u_{i+1,j+1}| \\ & + |u_{i-1,j} - u_{i,j+1}|). \end{aligned}$$

# Contour Stencils

Estimate the contours locally by finding a stencil with low TV,

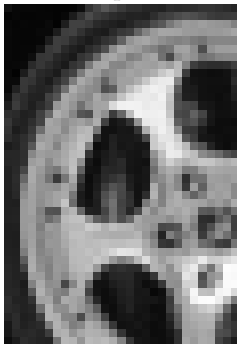
$$\mathcal{S}^*(k) = \arg \min_{\mathcal{S} \in \Sigma} (\mathcal{S} \star [u])(k)$$

where  $\Sigma$  is a set of candidate stencils.

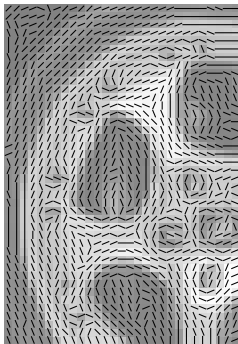
$$\Sigma = \left\{ \begin{array}{cccc} \begin{array}{|c|} \hline \bullet \\ \hline \bullet \\ \hline \bullet \\ \hline \end{array} & \begin{array}{|c|} \hline \bullet \diagup \bullet \\ \hline \bullet \diagup \bullet \\ \hline \bullet \diagup \bullet \\ \hline \end{array} & \begin{array}{|c|} \hline \bullet \diagup \bullet \\ \hline \bullet \diagup \bullet \\ \hline \bullet \diagup \bullet \\ \hline \end{array} & \begin{array}{|c|} \hline \bullet \diagup \bullet \\ \hline \bullet \diagup \bullet \\ \hline \bullet \diagup \bullet \\ \hline \end{array} \\ \begin{array}{|c|} \hline \bullet \\ \hline \bullet \\ \hline \bullet \\ \hline \end{array} & \begin{array}{|c|} \hline \bullet \diagdown \bullet \\ \hline \bullet \diagdown \bullet \\ \hline \bullet \diagdown \bullet \\ \hline \end{array} & \begin{array}{|c|} \hline \bullet \diagdown \bullet \\ \hline \bullet \diagdown \bullet \\ \hline \bullet \diagdown \bullet \\ \hline \end{array} & \begin{array}{|c|} \hline \bullet \diagdown \bullet \\ \hline \bullet \diagdown \bullet \\ \hline \bullet \diagdown \bullet \\ \hline \end{array} \end{array} \right\}$$

# Contour Stencils

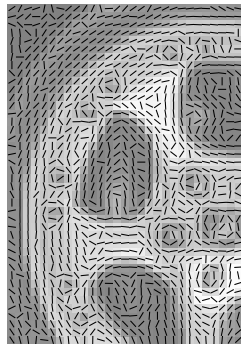
Input



Contour Stencils



Sobel



For each pixel,  $\mathcal{S}^*(k)$  is determined to estimate the local contour orientation.

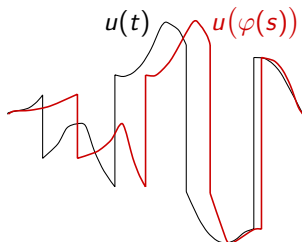
# Why TV?

Total variation is invariant under diffeomorphisms on space.  
Consider the change of variables

$$\begin{aligned}t &= \varphi(s) \\ dt &= \varphi'(s) ds\end{aligned}$$

and suppose that  $\varphi'(s) > 0$ , then

$$\begin{aligned}\int_0^T |u'(t)| dt &= \int_{\varphi^{-1}(0)}^{\varphi^{-1}(T)} |u'(\varphi(s))| \varphi'(s) ds \\ &= \int_{\varphi^{-1}(0)}^{\varphi^{-1}(T)} \left| \frac{\partial}{\partial s} u(\varphi(s)) \right| ds.\end{aligned}$$



# Interpolation Problem

Given discrete image  $v$  and point spread function  $h(x, y)$ , find function  $u(x, y)$  such that

$$v_{i,j} = (h * u)(i, j) \quad \text{for all } i, j.$$

Input  $v$



Interpolation  $u$

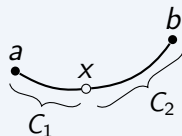


# Edge Directed Interpolation

## Theorem (Edge Directed Interpolation)

Consider approximating  $u(x)$  by

$$\hat{u}(x) = (1 - \lambda)u(a) + \lambda u(b)$$



and let  $C = C_1 \cup C_2$  be a curve passing through  $a$ ,  $x$ , and  $b$ .  
Then the approximation error is bounded by

$$|\hat{u}(x) - u(x)| \leq \max\{|1 - \lambda|, |\lambda|\} \|u\|_{\text{TV}(C)}.$$

Choosing the stencil with the smallest TV minimizes the estimated interpolation error:

$$|\hat{u}(x) - u(x)| \leq \|u\|_{\text{TV}(C)} \approx \frac{1}{|\mathcal{S}^*|} (\mathcal{S}^* \star [u])(k) = \min_{\mathcal{S} \in \Sigma} \frac{1}{|\mathcal{S}|} (\mathcal{S} \star [u])(k).$$



# Contour Stencil Windowed Zooming

Local reconstructions:

$$u_k(x) = v_k + \sum_{n \in \mathcal{N}} c_n \varphi_{\mathcal{S}^*(k)}^n(x - n),$$

where

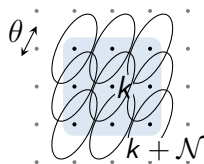
$v_k$  :  $k$ th pixel of input image

$\mathcal{N}$  : neighborhood

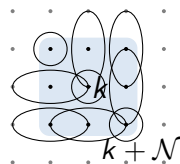
$\varphi_{\mathcal{S}^*(k)}^n$  : function oriented with the best-fitting stencil  $\mathcal{S}^*(k)$

$c_n$  : coefficients such that  
 $(h * u_k)(m) = v_{k+m}$  for  $m \in \mathcal{N}$

if  $\mathcal{S} = \text{X}$



if  $\mathcal{S} = \text{+}$



# Contour Stencil Windowed Zooming

Combine local reconstructions with overlapping windows

$$u(x) = \sum_{k \in \mathbb{Z}^2} w(x - k) u_k(x - k),$$

where  $w$  satisfies

$$\sum_k w(x - k) \equiv 1 \quad \text{s.t. method reproduces constants}$$

$$w(k) = 0 \text{ for } k \notin \mathcal{N} \quad \text{s.t. } \downarrow(h * u) \approx v$$

$$w \text{ compact support} \quad \text{for computational efficiency}$$

*Example:* Cubic B-spline

$$w(x) = B(x_1)B(x_2)$$

$$B(t) = \left(1 - |t| + \frac{1}{6}|t|^3 - \frac{1}{3}|1 - |t||^3\right)^+$$

Original Image (332×300)



Input Image (83×75)



Estimated Orientations



Proposed Interpolation (PSNR 25.97, 0.125 s)



Cubic B-spline (PSNR 25.92, 0.011 s)



Fourier (PSNR 25.34, 0.062 s)



TV Minimization (PSNR 25.73, 0.784 s) Proposed Interpolation (PSNR 25.97, 0.125 s)



AQua-2 (PSNR 24.72, 0.016 s)



Fractal Zooming (PSNR 24.65)



Roussos (PSNR 25.87, 2.518 s)



Proposed Interpolation (PSNR 25.97, 0.125 s)



# Zooming Comparison

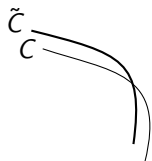
## Average PSNR on the Kodak Image Suite

Zoom Factor	2×	3×	4×
AQua-2	25.06	22.48	21.35
Fractal Zooming	29.00	27.20	25.25
Contour Stencils	29.87	27.77	25.93
Roussos	30.56	27.97	26.19

## Computation Time (s) vs. Output Image Size

Image Size	128 × 128	256 × 256	512 × 512
AQua-2	0.0048	0.017	0.068
Contour Stencils	0.025	0.088	0.34
Roussos	0.23	2.22	8.64

# Analysis of Contour Stencils



$$\tilde{C} \approx C \implies \|u\|_{\text{TV}(\tilde{C})} \approx \|u\|_{\text{TV}(C)}$$

## Curve Perturbation

Let  $C$  and  $\tilde{C}$  be smooth curves parameterized by  $\gamma : [0, T] \rightarrow C$  and  $\tilde{\gamma} : [0, T] \rightarrow \tilde{C}$ . Then if  $u$  is twice continuously differentiable,

$$\begin{aligned} & \left| \|u\|_{\text{TV}(\tilde{C})} - \|u\|_{\text{TV}(C)} \right| \\ & \leq \| |\nabla u| \|_{\infty} \| \tilde{\gamma}' - \gamma' \|_1 \\ & \quad + \| \nabla^2 u \|_{\infty} \left( \frac{|\tilde{C}| + |C|}{2} + \frac{1}{4} \| \tilde{\gamma}' - \gamma' \|_1 \right) \| \tilde{\gamma} - \gamma \|_{\infty}. \end{aligned}$$

# Analysis of Contour Stencils

$u \in C^2 \implies$  discrete TV is first-order accurate

## TV Discretization

Suppose  $u \in C^2[0, T]$  and  $0 = t_0 < t_1 < \dots < t_N = T$ , and define  $h_i = t_i - t_{i-1}$ . Then

$$\|u\|_{\text{TV}} - \frac{1}{3} T \frac{h_{\max}^2}{h_{\text{avg}}} \|u''\|_{\infty} \leq \sum_{i=1}^N |u(t_i) - u(t_{i-1})| \leq \|u\|_{\text{TV}}.$$



# Analysis of Contour Stencils

Let  $\mathcal{S}^{*2}(k)$  denote the second best-fitting stencil and define the separation  $\text{sep}_v(k)$  between the first and second best,

$$\mathcal{S}^{*2}(k) := \arg \min_{\mathcal{S} \in \Sigma \setminus \mathcal{S}^*(k)} (\mathcal{S} \star [v])(k),$$

$$\text{sep}_v(k) := (\mathcal{S}^{*2}(k) \star [v])(k) - (\mathcal{S}^*(k) \star [v])(k).$$

## Stability of the Best-Fitting Stencil

Suppose that for two images  $v$  and  $\tilde{v}$

$$\text{sep}_v(k) > 2M \|v - \tilde{v}\|_2,$$

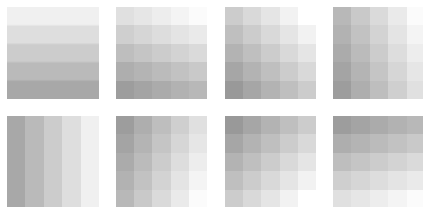
$$M = \max_{\mathcal{S} \in \Sigma} \left[ \sum_{m \in \mathbb{Z}} \left( \sum_{n \in \mathbb{Z}} |\mathcal{S}(m, n) + \mathcal{S}(n, m)| \right)^2 \right]^{1/2}.$$

Then they have the same best-fitting stencil at  $k$ .

# Contour Stencil Design

Let  $\{f^1, \dots, f^J\}$ ,  $f^j : \mathbb{Z}^2 \rightarrow \mathbb{R}$ , be a set of image features.

*Example:*  $f^j(x) = x_1 \sin \frac{\pi}{8}j - x_2 \cos \frac{\pi}{8}j$ ,  $j = 0, \dots, 7$



We want to design stencils  $\mathcal{S}^1, \dots, \mathcal{S}^J$  that distinguish between these features.

# Contour Stencil Design

We want stencil  $\mathcal{S}^j$  to be the best-fitting stencil on  $f^j$ ,

**Want:**  $\frac{1}{|\mathcal{S}^j|}(\mathcal{S}^j \star [f^j])(0) < \frac{1}{|\mathcal{S}^i|}(\mathcal{S}^i \star [f^j])(0)$  for all  $i \neq j$ .

Ignoring the  $\frac{1}{|\mathcal{S}|}$  normalizations, this condition becomes

$$\begin{aligned} & (\mathcal{S}^j \star [f^j])(0) < (\mathcal{S}^i \star [f^j])(0) \\ \implies & ((\mathcal{S}^j - \mathcal{S}^i) \star [f^j])(0) < 0. \end{aligned}$$

We can try to satisfy this condition by minimizing

$$\begin{aligned} \min_{\mathcal{S}^1, \dots, \mathcal{S}^J} & \sum_{i=1}^J \sum_{j=1}^J ((\mathcal{S}^j - \mathcal{S}^i) \star [f^j])(0) + \gamma \sum_{j=1}^J \|\mathcal{S}^j\|_1 \\ \text{s.t. } & 0 \leq \mathcal{S}^j(m, n) \leq 1 \end{aligned}$$

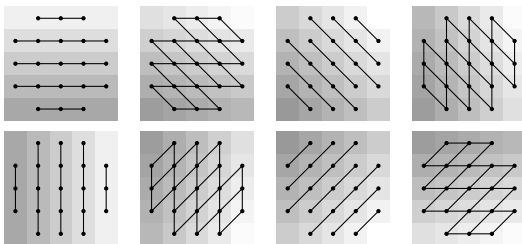
# Contour Stencil Design

$$\min_{\mathcal{S}^1, \dots, \mathcal{S}^J} \sum_{i=1}^J \sum_{j=1}^J ((\mathcal{S}^j - \mathcal{S}^i) \star [f^j])(0) + \gamma \sum_{j=1}^J \|\mathcal{S}^j\|_1$$

s.t.  $0 \leq \mathcal{S}^j(m, n) \leq 1$

The minimization has closed-form solution

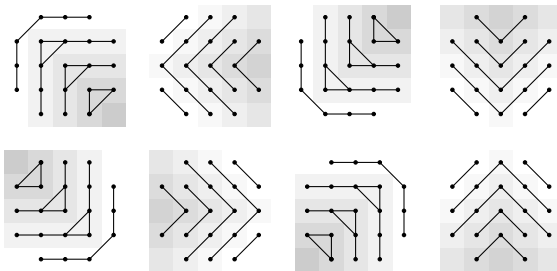
$$\mathcal{S}^j(m, n) = \begin{cases} 1 & \text{if } |f_m^j - f_n^j| < \frac{1}{J} \sum_{i=1}^J |f_m^i - f_n^i| - \frac{\gamma}{J}, \\ 0 & \text{if } |f_m^j - f_n^j| > \frac{1}{J} \sum_{i=1}^J |f_m^i - f_n^i| - \frac{\gamma}{J}. \end{cases}$$



# Corner-Shaped Stencils

*Example:* Corner-shaped stencils designed from the features

$$f^j(x) = \max\{x_1 \cos \frac{\pi}{4}j - x_2 \sin \frac{\pi}{4}j, \\ x_1 \sin \frac{\pi}{4}j + x_2 \cos \frac{\pi}{4}j\}.$$

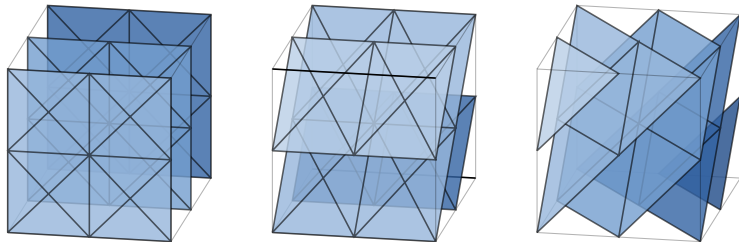


# 3D Stencils

In  $d$  dimensions, a stencil  $\mathcal{S} : \mathbb{Z}^d \times \mathbb{Z}^d \rightarrow \mathbb{R}$  is applied at voxel  $k \in \mathbb{Z}^d$  as

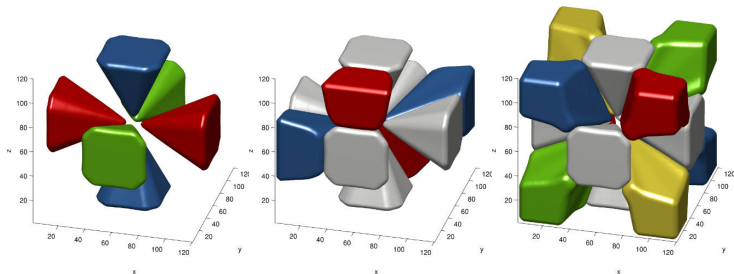
$$(\mathcal{S} \star [u])(k) := \sum_{m,n \in \mathbb{Z}^d} \mathcal{S}(m,n) |u_{k+m} - u_{k+n}|.$$

Small TV detects *isosurfaces*. Some 3D stencils:



# 3D Stencils

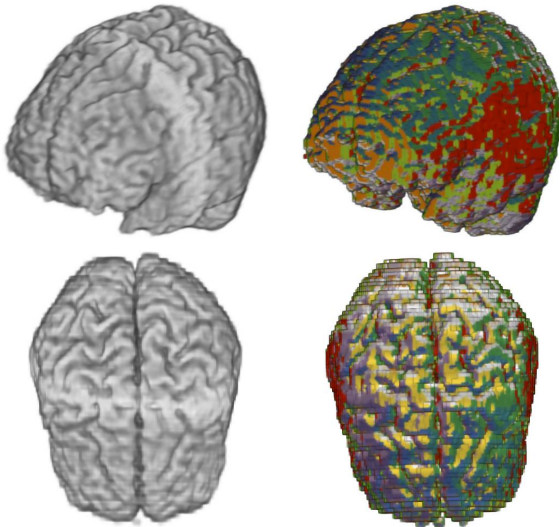
*Example:* Stencils applied to  $u_{i,j,k} = \sqrt{i^2 + j^2 + k^2}$



The results are visualized by assigning a color to the region of space having a particular best-fitting stencil.

# 3D Stencils

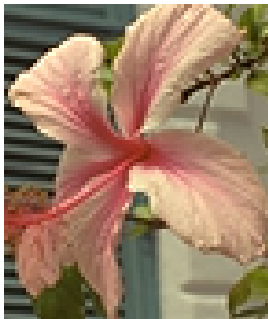
*Example:* Stencils applied to an MRI brain volume



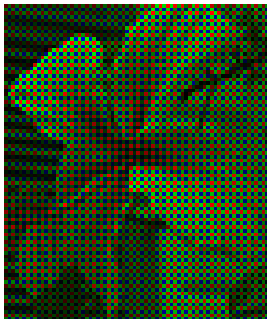


# Demosaicing

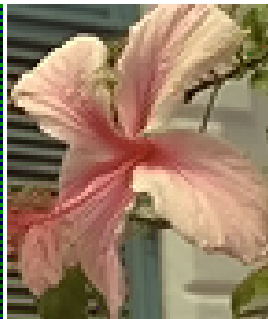
Original



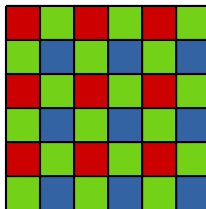
Mosaiced



Demosaiced

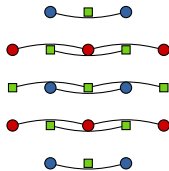


Bayer Grid

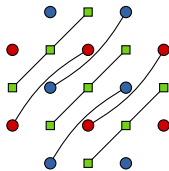


# Demosaicing Stencils

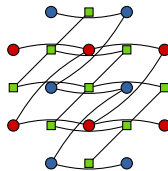
Centered on a green pixel:



Axially-oriented

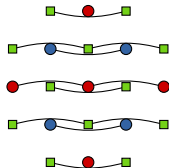


Diagonally-oriented

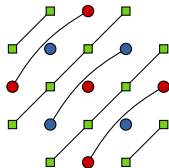


$\frac{\pi}{8}$ -oriented

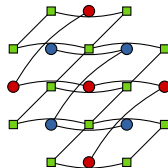
Centered on a red or blue pixel:



Axially-oriented



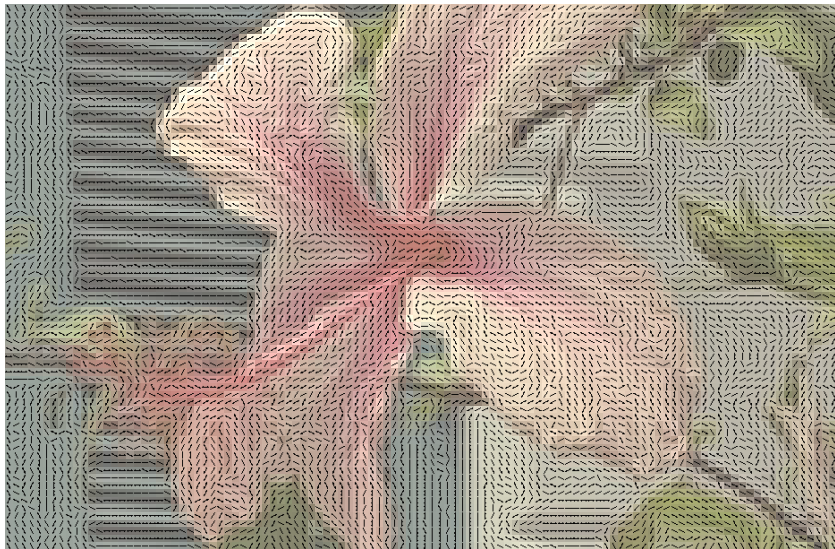
Diagonally-oriented



$\frac{\pi}{8}$ -oriented

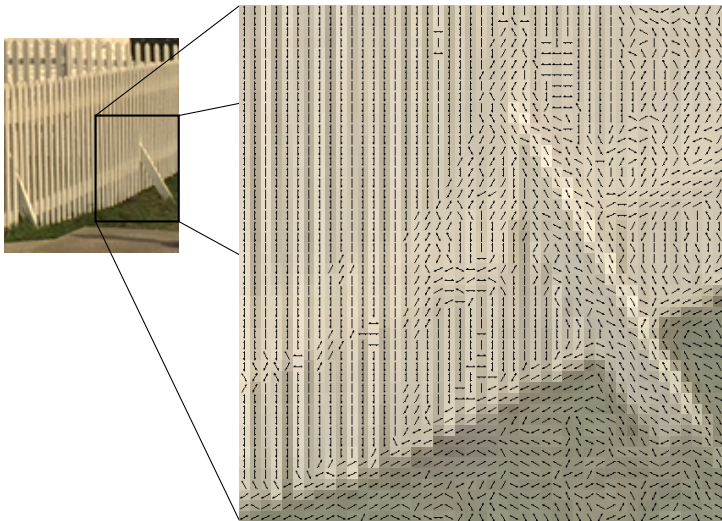
# Demosaicing Stencils

Stencil orientation estimation on mosaiced data:



# Demosaicing Stencils

Stencil orientation estimation on mosaiced data:



# Preliminary Demosaicing Method

Let  $f$  be the given mosaiced image. We consider demosaicing by the minimization of

$$\begin{aligned} \arg \min_u \quad & \sum_{k \in \{Y, C_b, C_r\}} \sum_{n \in \Omega} \sum_{m \in \mathcal{N}(n)} w_{m,n} |u_m^{(k)} - u_n^{(k)}| \\ & + \frac{\lambda}{2} \sum_{k \in \{R, G, B\}} \sum_{n \in \Omega^{(k)}} (f_n - u_n^{(k)})^2 \end{aligned}$$

where

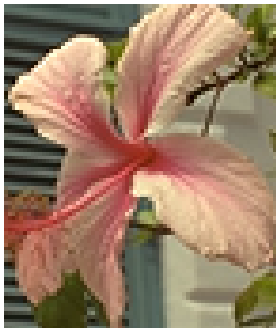
$w_{m,n}$  : weights chosen according the best-fitting stencils

$\mathcal{N}(n)$  : neighbors of pixel  $n$

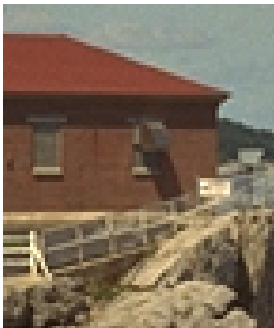
$\lambda$  : fidelity parameter

$\Omega^{(k)}$  : subset of  $\Omega$  where  $k$ th channel is given

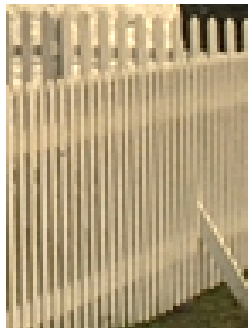
Exact



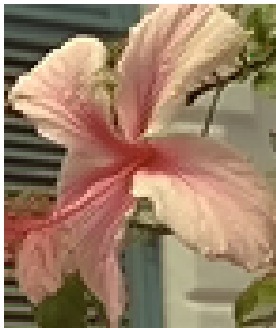
Exact



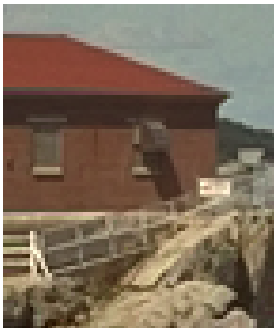
Exact



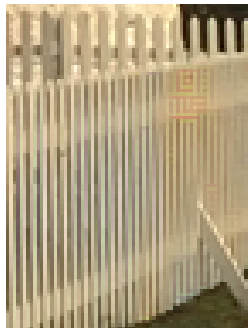
Demosaiced



Demosaiced



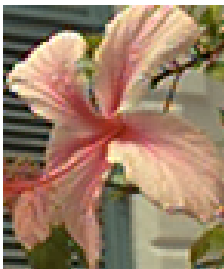
Demosaiced



Exact



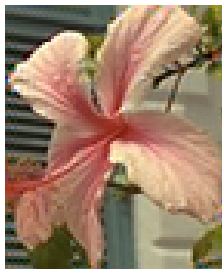
Malvar et al.



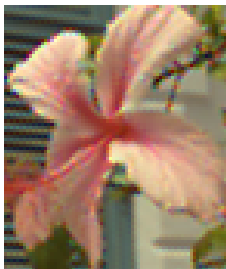
Gunturk et al.



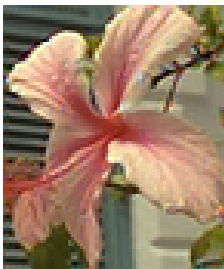
Zhang-Wu



Bilinear



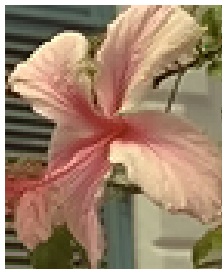
Hamilton-Adams



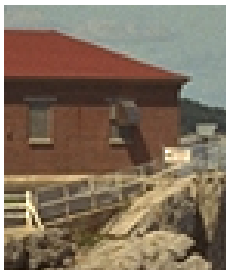
Li



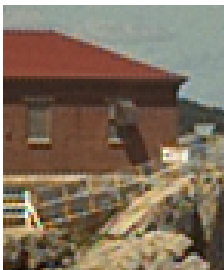
Proposed



Exact



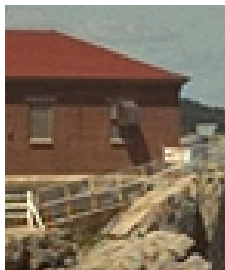
Malvar et al.



Gunturk et al.



Zhang-Wu



Bilinear



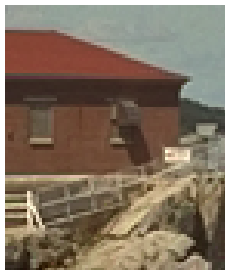
Hamilton-Adams



Li

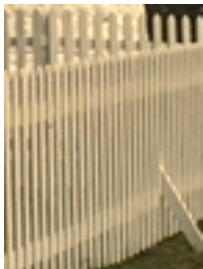


Proposed





Exact



Malvar et al.



Gunturk et al.



Zhang-Wu



Bilinear



Hamilton-Adams



Li



Proposed



# Thanks!

## Webpage

<http://www.math.ucla.edu/~getreuer/contours>

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