

# Continuous (Unilateral) Laplace Transform Correspondence Table

$$\mathcal{L}\{f(t)\} = F(s) = \int_0^\infty f(t) e^{-st} dt, \quad s \in \mathbb{C}$$

*Notes:* Unless stated otherwise, time-domain signals are assumed causal and multiplied by the step function  $\epsilon(t)$ . “ROC” denotes the region of convergence (typical/standard conditions).

## A. Common Transform Pairs

Time domain $f(t)$	Laplace $F(s)$	ROC (typ.)	Notes
$\delta(t)$	1	all $s$	Dirac delta
$\delta(t - a), a \geq 0$	$e^{-as}$	all $s$	Time shift of impulse
$\epsilon(t)$	$\frac{1}{s}$	$\Re\{s\} > 0$	Step function
$t^n \epsilon(t), n \in \mathbb{N}_0$	$\frac{n!}{s^{n+1}}$	$\Re\{s\} > 0$	$n = 0, 1, 2, \dots$
$e^{at} \epsilon(t)$	$\frac{1}{s - a}$	$\Re\{s\} > \Re\{a\}$	Real/complex $a$
$e^{at} t^n \epsilon(t)$	$\frac{n!}{(s - a)^{n+1}}$	$\Re\{s\} > \Re\{a\}$	Polynomial $\times$ exponential
$\sin(bt) \epsilon(t)$	$\frac{b}{s^2 + b^2}$	$\Re\{s\} > 0$	$b \in \mathbb{R}$
$\cos(bt) \epsilon(t)$	$\frac{s}{s^2 + b^2}$	$\Re\{s\} > 0$	$b \in \mathbb{R}$
$e^{at} \sin(bt) \epsilon(t)$	$\frac{b}{(s - a)^2 + b^2}$	$\Re\{s\} > \Re\{a\}$	Damped sinusoid
$e^{at} \cos(bt) \epsilon(t)$	$\frac{s - a}{(s - a)^2 + b^2}$	$\Re\{s\} > \Re\{a\}$	Damped cosine
$\sinh(bt) \epsilon(t)$	$\frac{b}{s^2 - b^2}$	$\Re\{s\} >  b $	$b \in \mathbb{R}$
$\cosh(bt) \epsilon(t)$	$\frac{s}{s^2 - b^2}$	$\Re\{s\} >  b $	$b \in \mathbb{R}$
$\frac{1}{k} (1 - e^{-kt}) \epsilon(t)$	$\frac{1}{s(s + k)}$	$\Re\{s\} > -k, k > 0$	1st-order step response
$(\epsilon(t) - \epsilon(t - T))$	$\frac{1 - e^{-sT}}{s}$	$\Re\{s\} > 0$	Rectangular pulse, width $T > 0$
$(t - T) \epsilon(t - T)$	$\frac{e^{-sT}}{s^2}$	$\Re\{s\} > 0$	Delayed ramp
$\int_0^t f(\tau) d\tau$	$\frac{1}{s} F(s)$	depends on $F$	Time integral

**Tip for students.** Always check the ROC (e.g.,  $\Re\{s\} > 0$  for many causal signals) and remember that unilateral Laplace includes initial conditions in differentiation properties.

## B. Useful Properties (Unilateral)

Operation in $t$	Effect in $s$	Conditions / Notes
Linearity: $\mathcal{L}\{af + bg\}$	$aF + bG$	$a, b \in \mathbb{C}$
Time shift (delay): $f(t - a) \epsilon(t - a)$	$e^{-as} F(s)$	$a \geq 0$
Frequency shift: $e^{at} f(t)$	$F(s - a)$	shifts the $s$ -axis
Time scaling: $f(bt)$ , $b > 0$	$\frac{1}{b} F\left(\frac{s}{b}\right)$	$b > 0$
Differentiation in $t$ : $f'(t)$	$sF(s) - f(0^+)$	unilateral form (IC term)
Second derivative: $f''(t)$	$s^2 F(s) - sf(0^+) - f'(0^+)$	include ICs
Integration in $t$ : $\int_0^t f(\tau) d\tau$	$\frac{1}{s} F(s)$	as in Table A
Multiplication by $t$ : $tf(t)$	$-\frac{d}{ds} F(s)$	frequency differentiation
Convolution: $(f * g)(t)$	$F(s) G(s)$	$(f * g)(t) = \int_0^t f(\tau)g(t - \tau)d\tau$
Initial value theorem	$f(0^+) = \lim_{s \rightarrow \infty} sF(s)$	if limit exists
Final value theorem	$f(\infty) = \lim_{s \rightarrow 0} sF(s)$	system stable, poles of $sF(s)$ in $\Re\{s\} < 0$ except possibly at $s = 0$