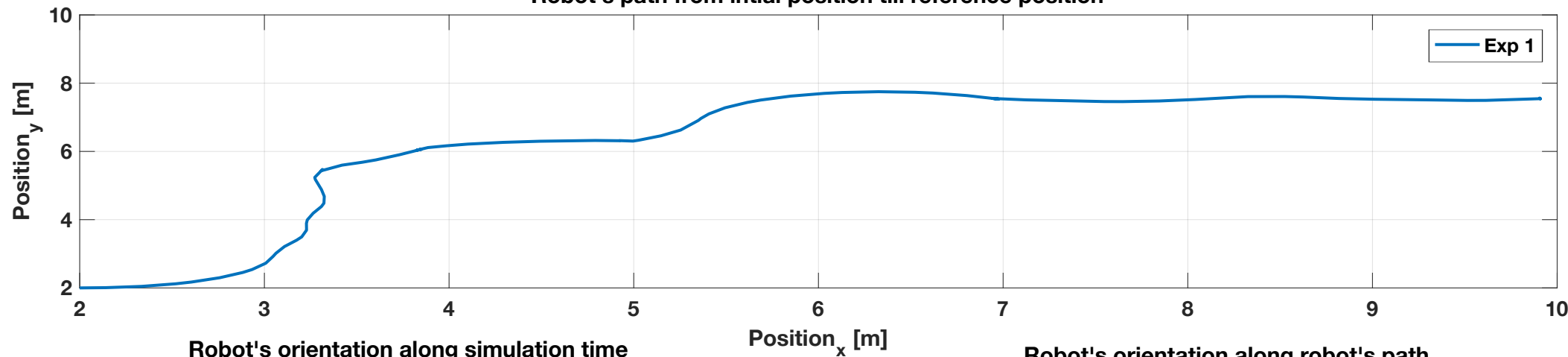
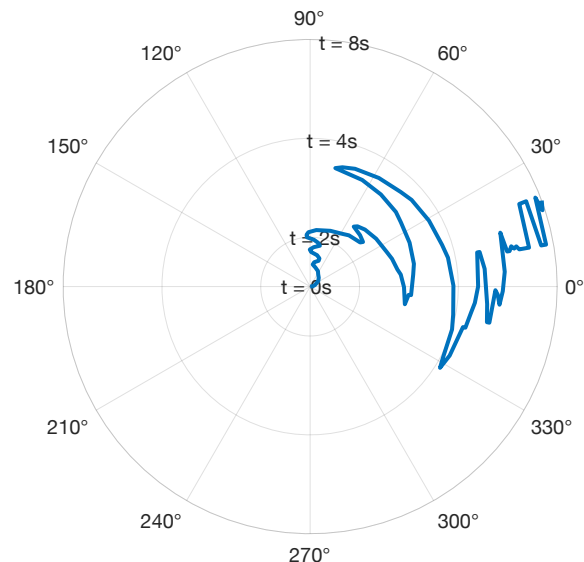


Robot's path from intial position till reference position



Robot's orientation along simulation time



$\text{Position}_x \text{ [m]}$

Robot's orientation along robot's path

