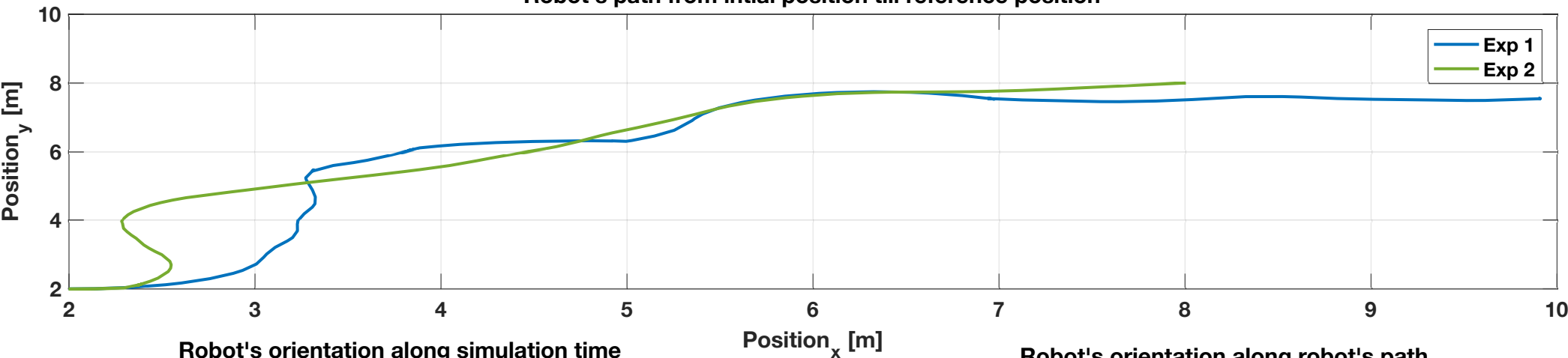
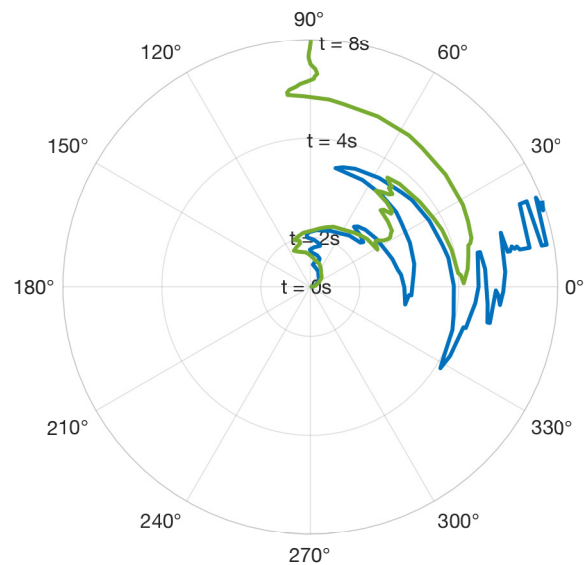


Robot's path from intial position till reference position



Robot's orientation along simulation time



Position_x [m]

Robot's orientation along robot's path

