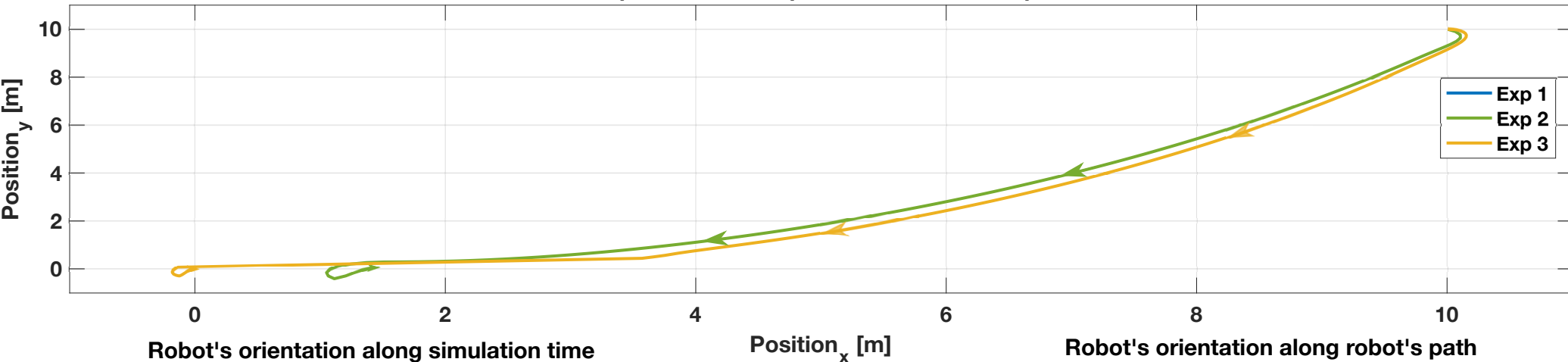
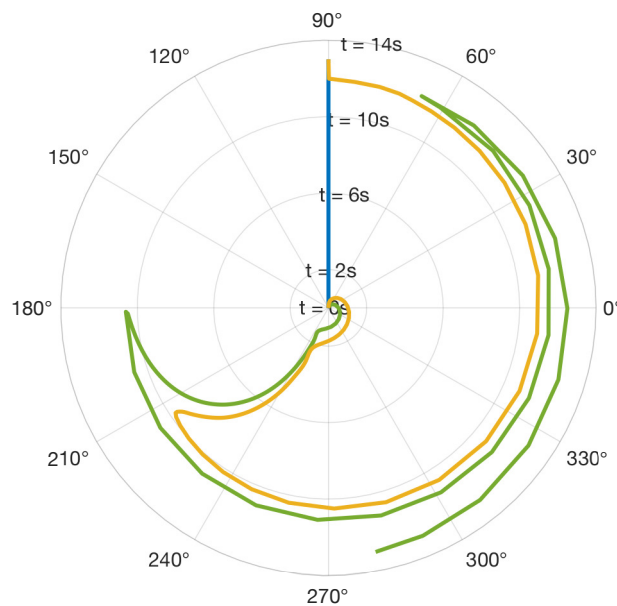


Robot's path from initial position till reference position



Robot's orientation along simulation time



Robot's orientation along robot's path

