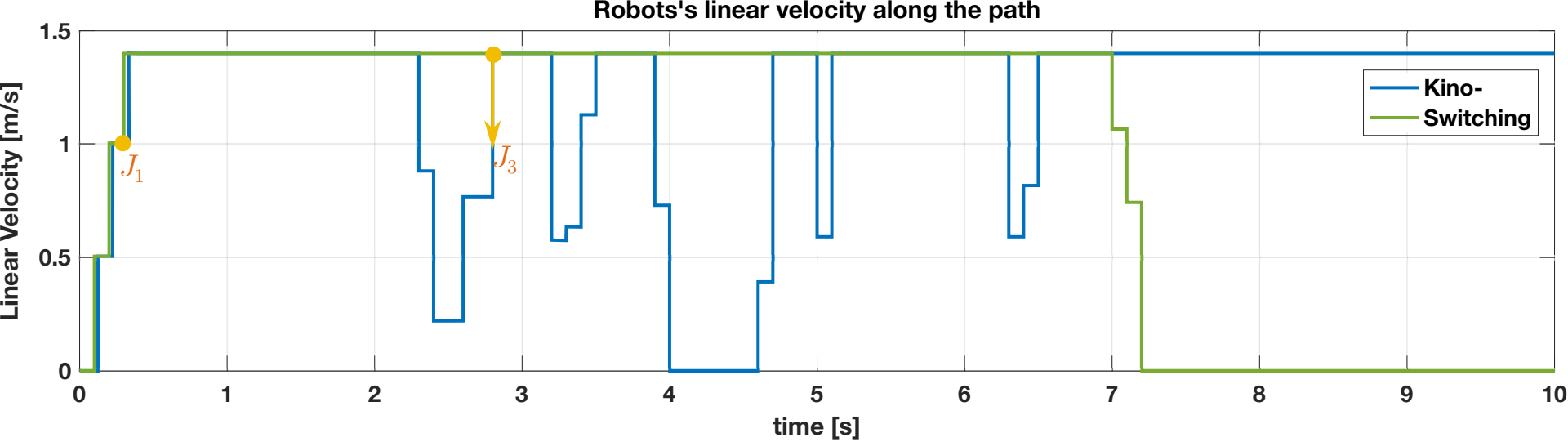
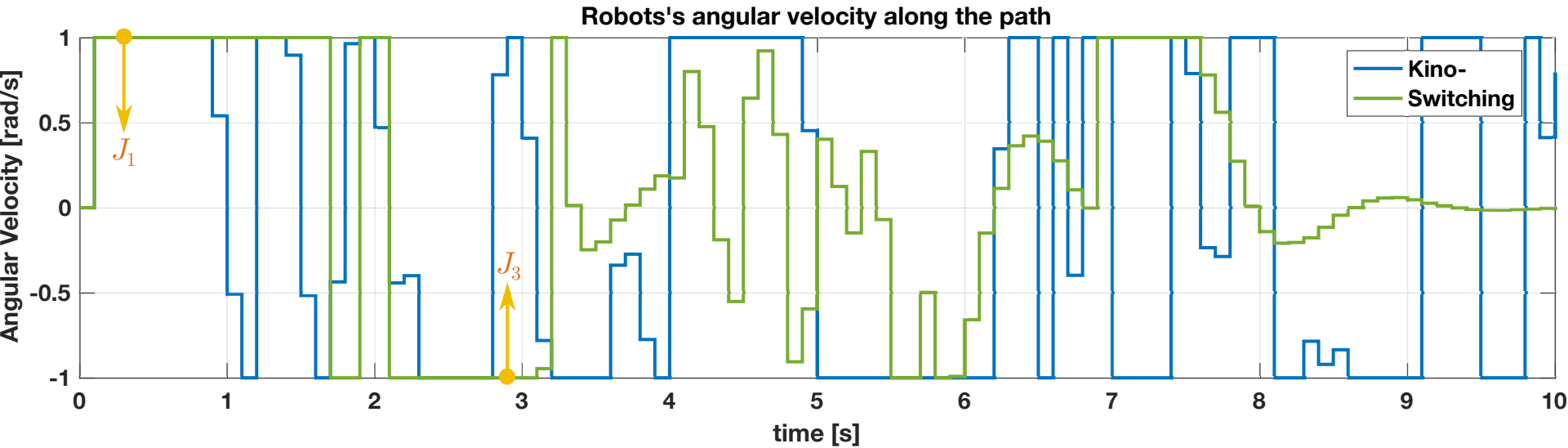

Robots's linear velocity along the path
Linear Velocity [m/s]
time [s]
Kino-
Switching
J_1
J_3
1.5
1
0.5
0
0
1
2
3
4
5
6
7
8
9
10


Robots's angular velocity along the path
Angular Velocity [rad/s]
time [s]
Kino-
Switching
J_1
J_3
1
0.5
0
-0.5
-1
0
1
2
3
4
5
6
7
8
9
10