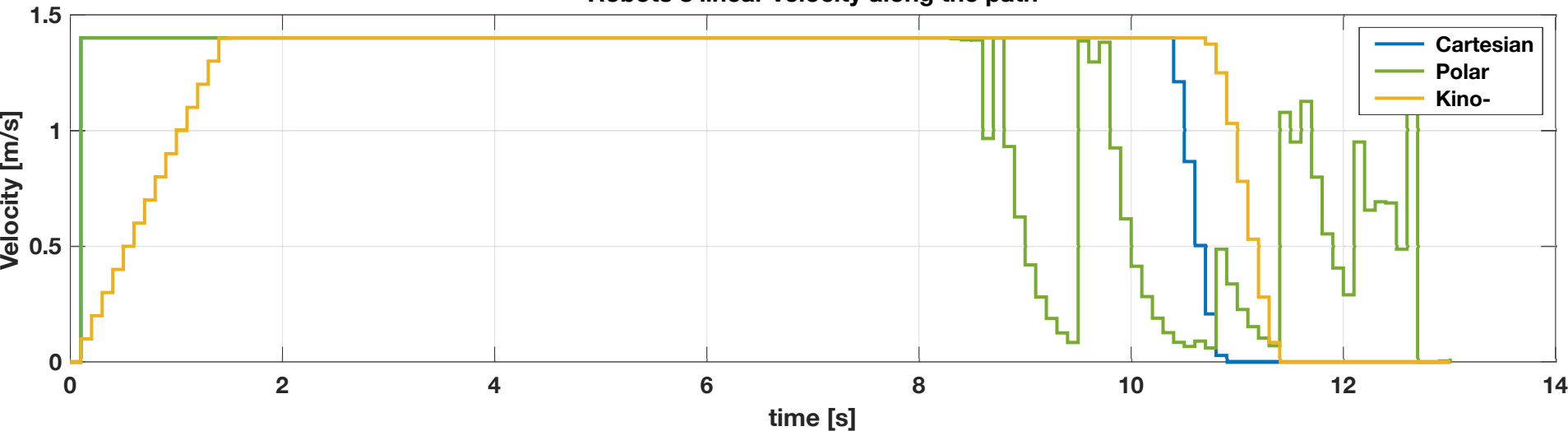


Robots's linear velocity along the path



Robots's angular velocity along the path

