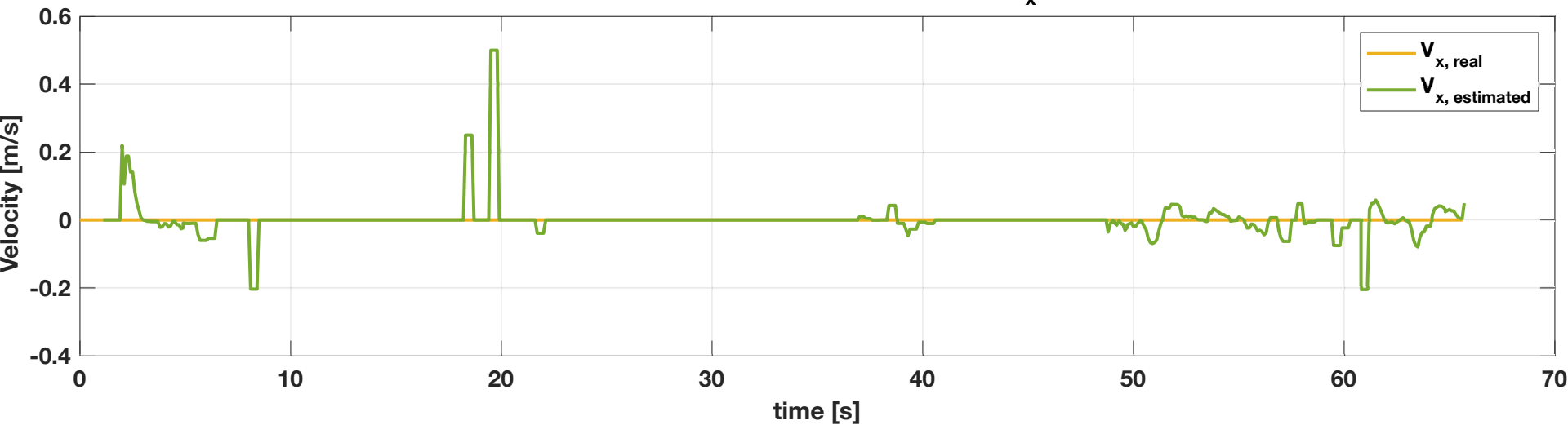


Robot's linear velocity in the x-axis [v_x]



Robot's linear velocity in the y-axis [v_y]

