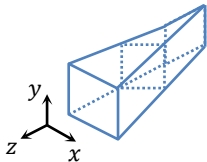
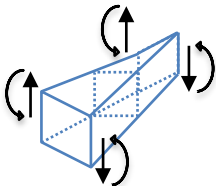


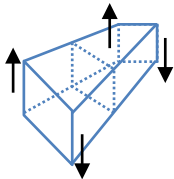
(a) Eulerian frame



(c) 2D co-moving frame & remap



(b) 2D co-moving frame



(d) Rotating flux-tube model

