Programming for Mechatronic Systems Autumn 2017/1012-2017-AUTUMN-CITY♥

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Aaron Dinoia

Publishing Pose Array to ROS Topic

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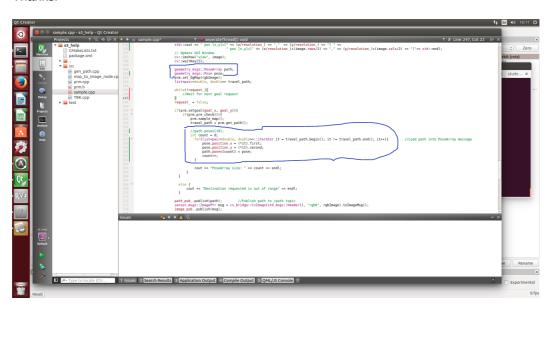
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Hi Alen,

I'm unsure about how to publish the poseArray to a ROS topic. In the help file you've said that we need to copy and paste the following, however surely you don't mean literally copy and paste do you? Because if so, where are we copying and pasting to? That doesn't make sense.

I figured this is how we're meant to do it? This makes more sense. However this seg faults and I'm not sure why. Do we need to initialise the array, if so, how do we know how large to create it? Because I've seen other code where they do not initialise the array (It'll still seg fault regardless if I initialise the array or not so that's not what's causing the problem).

Thanks!



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