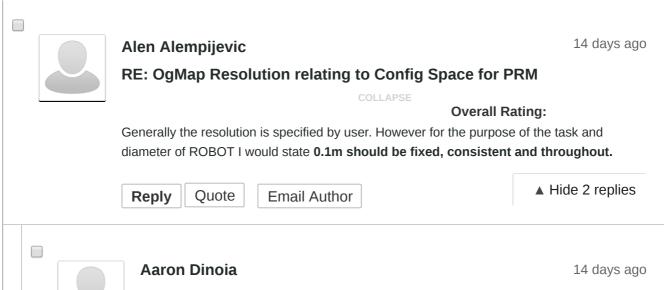
Programming for Mechatronic Systems Autumn 2017/1012-2017-AUTUMN-CITY♥

Discussion Board

Forum: Assignment 5 - Individual project Thread: OgMap Resolution relating to Config Space for PRM

Thread: OgMap Resolution relating to coming Space for PRM





Thread: OgMap Resolution relating to Config Space for PRM &...



RE: OgMap Resolution relating to Config Space for PRM

Overall Rating:

Right, so are you saying that the number of rows and columns should be 20/0.1 = 200?

Also, would you like us to still implement a function which allowed the user to specify the resolution?

▲ Hide 1 reply



Alen Alempijevic

10 days ago

RE: OgMap Resolution relating to Config Space for PRM

Overall Rating:

The user is needed can already specify the resolution when running local_map.

There is a problem of the your component finding out that resolution when it gets hold of the OpenCV Image as there is no meta-data available.

Thus, we removed this as a requirement as it is not crucial to the Assignment implementation.

Select: All None

Message Actions 👋 Expand All Collapse All

← OK