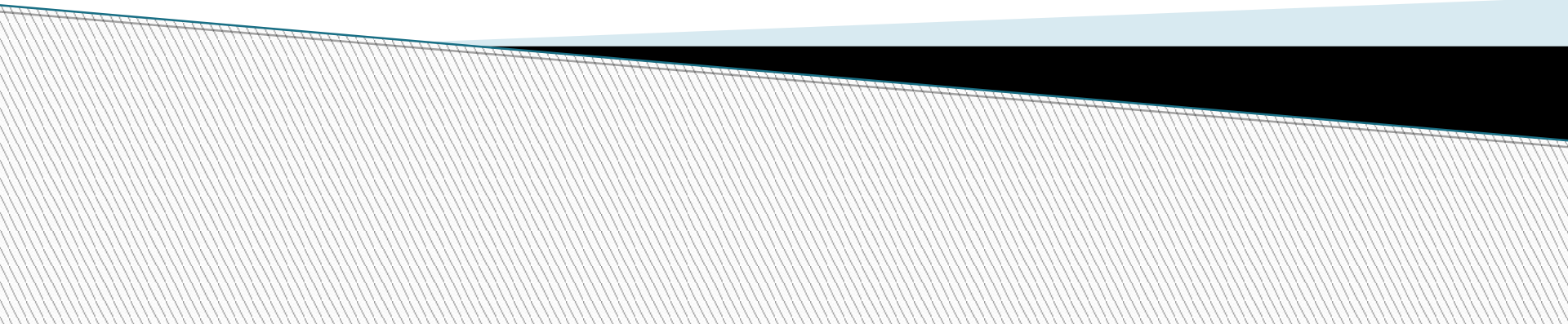


# **41012 Programming for Mechatronic Systems**

Week 2



# Overview

- Staff
- Link to Industry Needs
- Objectives
- Class Structure
- Assignments
- General Rules
  - ▢ Plagiarism
  - ▢ Late submissions
  - ▢ Peer Review
- In-class exercises

# Subject Staff

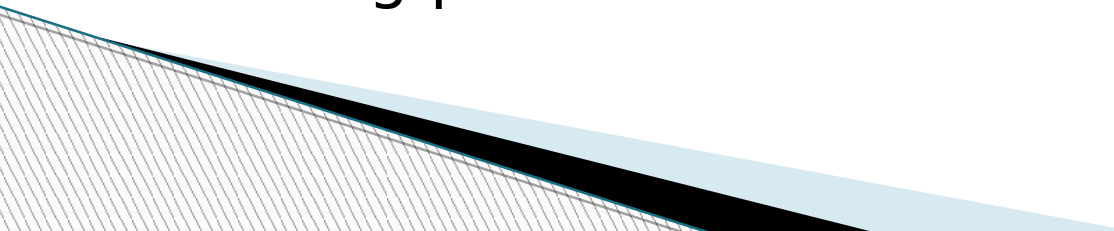
- ▶ Subject Coordinators
  - Alen Alempijevic
- ▶ Teaching Staff
  - Alex Virgona



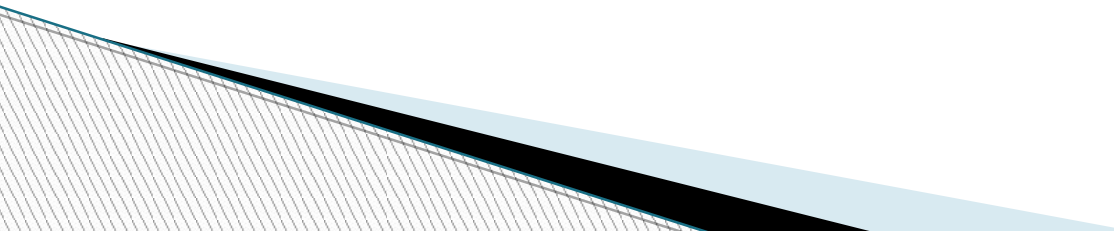
# Mechatronic Systems

- ▶ 6.4B Devices Interconnected + System on
- ▶ Chip Devices Explosion
- ▶ Beyond Single Monolithic Code
- ▶ OO Paradigm – More Admissible to Systems
- ▶ C++ Essential on Many Layers
  - Android Backbone, Libraries, Applications
- ▶ Code Reuse / Testing / Documentation
- ▶ Robotics Jobs (demand)

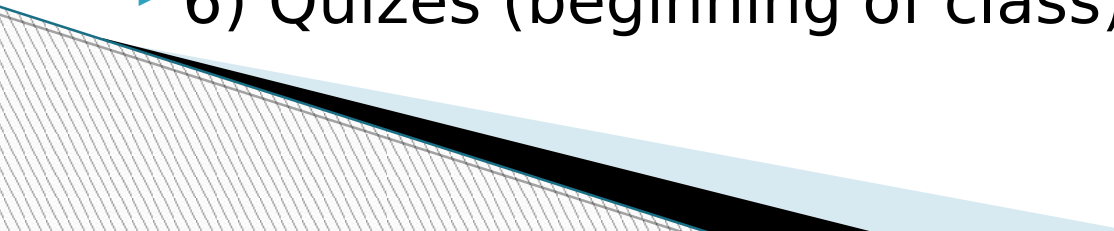
# Subject objectives

- ▶ 1. **Design** classes that are reusable, reliable and maintainable
  - ▶ 2. **Apply theoretical knowledge** of sensors and control to practical programming problems
  - ▶ 3. **Select** appropriate class structures and data handling methods for task at hand
  - ▶ 4. **Implement and test** object-oriented applications of moderate complexity
  - ▶ 5. **Communicate** programming design decisions, dependencies, interconnections, use cases and testing procedures in a written document
- 

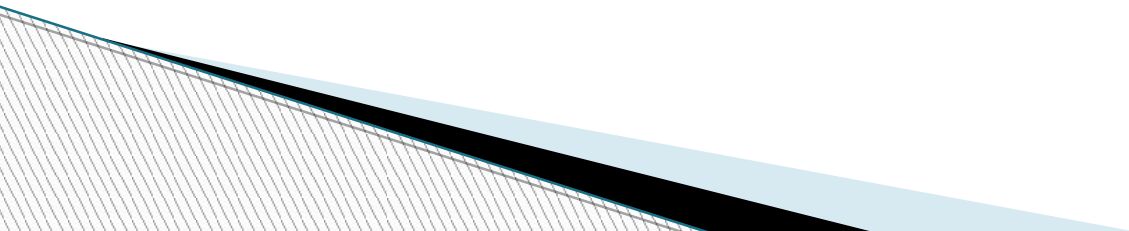
# Class Structure

- ▶ Pre-readings given
  - ▶ Students view readings, attempt and come to class
  - ▶ We clarify concepts and push forward with examples
  - ▶ We build knowledge base (stratify knowledge) towards the assignments; more complex layers of understanding
- 

# Assessment

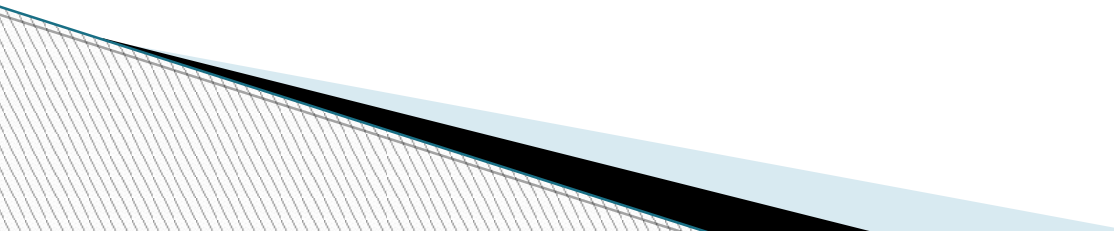
- ▶ 1) Assessment I:  
Developing Sensor Class (5%)
  - ▶ 2) Assessment II:  
Utilising Abstraction for a Range of Sensor Classes (20%)
  - ▶ 3) Assessment III:  
Threading, Synchronization and Data Integrity (20%)
  - ▶ 4) Individual Project: (40%)
  - ▶ 5) Code Review: (9% : 3%+3%+3%)
  - ▶ 6) Quizzes (beginning of class): 6% ( 6 x 1%)
- 

# Practise Quiz





# Teaching Delivery

- ▶ OS: Ubuntu
  - ▶ C++11
  - ▶ Compilation + Tools: CMake
  - ▶ Documentation: Doxygen
  - ▶ IDE: QtCreator
  - ▶ Unit Testing: gtest
  - ▶ OpenCV (Library)
  - ▶ ROS (Middleware CBSE)
- 

# What you should have done in Week 1

- ▶ Download the examples from [Lynda.com](https://www.lynda.com)
- ▶ Enable compiling of `working.cpp` from Chap1
- ▶ with CMake
  - Command line
  - QtCreator / Eclipse
- ▶ Reviewed C

# Pointers & Reference

- ▶ Pointers are extremely powerful, allow access to memory (memory address) and to manipulate their contents

Computer		Programmers		
Address	Content	Name	Type	Value
90000000	00	sum	int (4 bytes)	000000FF (255 <sub>10</sub> )
90000001	00			
90000002	00			
90000003	FF			
90000004	FF	age	short (2 bytes)	FFFF (-1 <sub>10</sub> )
90000005	FF			
90000006	1F			
90000007	FF			
90000008	FF	average	double (8 bytes)	1FFFFFFFFFFFFFFF (4.45015E-308 <sub>10</sub> )
90000009	FF			
9000000A	FF			
9000000B	FF			
9000000C	FF	ptrSum	int* (4 bytes)	90000000
9000000D	FF			
9000000E	90			
9000000F	00			
90000010	00			
90000011	00			

# Pointers & Reference

- ▶ The *address-of operator* (&) operates on a variable, and returns the address of the variable
- ▶ Pointer:
  - stores a memory address
  - must be declared before they can be used
  - syntax of declaring, place a \* in front of the name
  - is associated with a type

# Dereference / Indirection

- ▶ To get the value pointed to by a pointer (retrieve or modify), you need to use the dereferencing operator \*

# Pointers & Reference

- ▶ `int number = 88;`
- ▶ `int * pNumber = &number;`
- ▶ `cout << pNumber<< endl;`
- ▶ `cout << *pNumber << endl;`
- ▶ `*pNumber = 99;`
- ▶ `cout << *pNumber << endl;`
- ▶ `cout << number << endl;`

# Functions

- ▶ Functions allow to structure programs in segments of code to perform individual tasks.
- ▶ Generally segmented to be able to be reused

```
type name ( parameter1, parameter2, ...)  
{ statements }
```


- ▶ What about **void**
- 

# Functions

- ▶ Create a function that accepts a double value as a parameter and
  - 1. Returns a square value
  - 2. Returns a bool value if the double is greater than zero and the square value instead of initial passed value
  - 3. Returns bool value if the double is greater than zero, the square value, the cube value and the passed value incremented by one



# Header / Source File

- ▶ Why needed?
    - It allows you to separate *interface* from *implementation*
    - It speeds up compile time
  - ▶ Generally the interface file is all that is needed
  - ▶ Allows to have a library with header, inner implementation hidden
  - ▶ Further Details
  - ▶ <http://www.cplusplus.com/articles/Gw6AC542/>
- 

# Coding Style Guide

- ▶ Code style important for readability of code
- ▶ Most important : **CONSISTENCY**
- ▶ Common to Adopt Coding Standard
  - <http://wiki.ros.org/CppStyleGuide>
  - <https://google.github.io/styleguide/cppguide.html>
- ▶ **We will use ROS C++ Style Guide**

# Classes

- ▶ *Classes* are an expanded concept of *data structures*:
  - they can contain data members
  - they can also contain functions as members.
- ▶ C Struct?
  - Arguably not the same beast!

# Classes

```
class Rectangle {
```

```
    Rectangle();
```

```
    ~Rectangle();
```

```
public:
```

```
    void setValues (int,int);
```

```
    int getArea (void);
```

```
    int getPerimeter (void);
```

```
private:
```

```
    int width_, height_;
```

```
};
```



# Classes

```
class Rectangle {  
public:  
void setValues (int,int);  
int getArea (void);  
int getPerimeter(void);  
private:  
int width_, height_;  
};
```

## Questions:

- ▶ What are the functions of the class?
- ▶ What do they take / return?
- ▶ What are the access specifiers?
- ▶ Why do we have the setValues method?
- ▶ What do the access specifiers guarantee
- ▶ Where is the implementation of this class
- ▶ What might be the pitfall of this class?
- ▶ How can we resolve the pitfall?