

# Lab 2 ELEC4400: Z Transform and Convolution

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## Part 1: Fibonacci

Last time we used Z Transform Techniques to determine a closed form expression for the Fibonacci Sequence, shown in equation form below.

$$y[n] = \frac{1}{\sqrt{5}} \left( \left[ \frac{1 + \sqrt{5}}{2} \right]^n - \left[ \frac{1 - \sqrt{5}}{2} \right]^n \right)$$

This was derived via Z transform from the difference equation

$$y[n + 2] = y[n + 1] + y[n]$$

## Problem 1

Verify that both of these equations output Fibonacci Numbers, then use the python `time` built in library to time how long it takes to solve for the n-th Fibonacci Number using both versions of the Fibonacci sequence.

**Please Generate a plot with n on the horizontal axis, and time on the vertical axis, comparing the speed of each method for computing the first 30 fibonacci numbers**

## Some Helpful Things

To write to a file

```
f = open('data.csv', 'w')
```

```
f = write('%s,%s,%s'%(t,x1,x2))
```

```
textttf.close()
```

## Convolution

Today's event is all about convolution in discrete time and some of its applications. We said that  $x[n]$  was a vector of input values, and that  $y[n]$  was a vector of output values.  $h[n]$  is a function associated with a system which is the “unit sample response of the system”. Another way of phrasing this is to say that

$h[n]$  is a function that describes what the system WILL DO to a unit sample in  $x[n]$ . Here is this big equation defining the convolution.

$$y[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

What I want to tell you, and what I hope to show you by the end of this activity is that convolution is multiplying **each** element in the input  $x[n]$  by **every** element in a time shifted version of  $h[n]$ , and then adding all the results together.

The property of time invariance allows us to use shifted versions of  $h[n]$ , and the property of linearity allows us to sum the results.

This idea is important because it allows us to determine the output response  $y[n]$  of any system (described by  $h[n]$ ) to any input  $x[n]$ , so long as the system obeys the property of linearity and time invariance.

## You've done Convolution a $10^6$ times already

We've all done convolution from a young age, and we did it when we performed the operation of multiplying two polynomials together. Consider two polynomials which are dear to my own heart,

$$x = s^2 + 4s + 3 \tag{1}$$

and also

$$h = s + 5 \tag{2}$$

### Problem 1

By the traditional FOIL method, carefully multiply these two polynomials together.

## Convolution for Polynomial

Multiplying polynomials can be thought of as a convolution of the vectors containing the coefficients of each polynomial. So say I want to FOIL (or from now on let's say "convolve" or "convolute") the polynomials  $q = 2s + 4$  and also  $v = 5s + 3$  together. I can list their coefficients into a vector in the following way

$$q = [2 \quad 4] \tag{3}$$

$$v = [5 \quad 3] \tag{4}$$

### Problem 2

Multiply the polynomials  $q$  and  $v$  by the convolution method.

### Problem 3

Multiply my favorite two polynomials ( $x$  and  $h$  from problem 1) via the convolution method.

### Part 3

Math describes parts of our lives in a rigorous way, and convolution is the math that describes what the output of a digital signal is when it passes through a system. I want to try and show you that that's the truth now. Consider the RC circuit below, with  $R = 1k\Omega$ , and  $C = 1nF$ . There are various ways of figuring

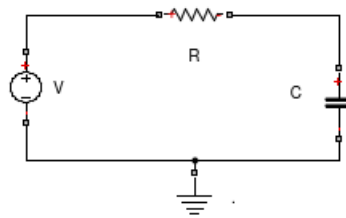


Figure 1: Figure of Part 3

out what the impulse response of this circuit is, but I'm here to just tell you that its

$$h(t) = 10^6 e^{-10^6 t} \quad (5)$$

### Problem 4

I'd like to ask you to please find the response of this circuit to a constant input (the step response) using the `np.conv()`. Set  $t = nT$  with  $T = 10^{-8}$ , and use an input vector that is 1000 samples long, and plot the first 10 microseconds of the response. One small subtlety of this problem; since we're using discrete math to approximate the continuous time response of the function, instead of using  $u[k]$ , we'll use  $Tu[k]$  where  $T$  is the width between samples.

**Hand in a printed copy of your answers to each problem, as well as the code used to generate the final result.**