#### Exercise 1

A computational introduction to stochastic differential equations FTN0332 TN22H006

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#### How to pass this exercise

This exercise round is concerned with Lectures 2 - 3. To pass this exercise, score  $\geq$  12 points and finish the assignment(s) marked with  $\star$ . Please submit your assignments in an email sent to zheng.zhao@it.uu.se before 13:15, 2 Nov, 2022.

### Assignment 1 (1 point)

Let W be a standard Brownian motion, and  $f: \mathbb{R} \to \mathbb{R}$  be a continuously differentiable function. Show that

$$\int_0^t f(W(s)) \, dW(s) = \int_0^{W(t)} f(s) \, ds - \frac{1}{2} \int_0^t f'(W(s)) \, ds,$$

where f' denotes the derivative of f. (Hint:  $F(u) := \int_0^u f(s) ds$  and Itô's formula.)

## Assignment 2 (1 point)

Let W be a standard Brownian motion, and define

$$X(t) := \sin(\alpha W(t)).$$

Show that X satisfies the SDE

$$dX(t) = -\frac{\alpha^2}{2} X(t) dt + \alpha \sqrt{1 - X(t)^2} dW(t), \quad X(0) = 0,$$

or does it? (Hint: Itô's formula)

### Assignment 3 (1 point)

Consider an SDE

$$dX(t) = a(X(t)) dt + b dW(t),$$

where  $X: [0, \infty) \to \mathbb{R}^d$ ,  $a: \mathbb{R}^d \to \mathbb{R}^d$ ,  $b \in \mathbb{R}^d$ , and W is a standard Brownian motion. Suppose that the drift function a is smooth and is the gradient of a smooth mapping  $\phi: \mathbb{R}^d \to \mathbb{R}$ , viz.,

$$a(X(t)) := \nabla \phi(X(t)).$$

Show that

$$d\phi(X(t)) = \left( ||a(X(t))||_2^2 + \frac{1}{2} \operatorname{tr} \left( b \, b^{\mathsf{T}} \mathbf{J}_X a(X(t)) \right) \right) dt + a(X(t))^{\mathsf{T}} \, b \, dW(t),$$

where  $\|\cdot\|_2$  and  $J_X a$  denote the Euclidean norm and Jacobian of a, respectively. (Hint: Itô's formula.)

### Assignment 4 (2 points)

Let W be a standard Brownian motion, and define X by

$$X(t) := X_0 \exp\left(\left(a - \frac{b^2}{2}\right)t + bW(t)\right).$$

Verify that X satisfies the SDE

$$dX(t) = a X(t) dt + b X(t) dW(t), X(0) = X_0,$$

This process is also known as the geometric Brownian motion. (Hint: Itô's formula.)

# Assignment 5 (5 points)

Let  $X_{1:T} := \begin{bmatrix} X_1 & X_2 & \cdots & X_T \end{bmatrix} \in \mathbb{R}^T$  be a vector of zero-mean joint Normal random variables, distributed according to  $X_{1:T} \sim \mathcal{N}(x_{1:T} \mid 0, C_{1:T})$  with a covariance matrix  $C_{1:T} \in \mathbb{R}^{T \times T}$  whose i, j-th element is

$$(C_{1:T})_{ij} := e^{-\Delta |i-j|},$$

for  $1 \le i, j \le T$ . Set T = 100 and  $\Delta = 0.1$ .

• Compute the matrix  $C_{1:T}$  and implement the PDF  $N(x_{1:T} \mid 0, C_{1:T})$  as a function of vector  $x_{1:T}$ . It is allowed to use e.g., scipy.stats.multivaria te\_normal.

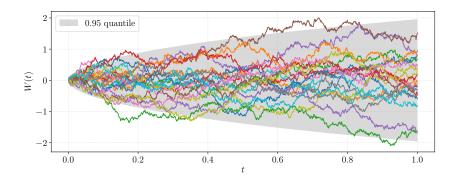


Figure 1: Trajectories of Brownian motion

The random variables  $X_{1:T}$  are in fact can be generated from an SDE (which we will see in a later lecture). By the Markov property of the SDE, we can factorise the joint PDF in terms of its transition densities as follows.

$$\begin{split} p(x_{1:T}) &\coloneqq p(x_1) \prod_{k=2}^{T} p(x_k \mid x_{k-1}), \\ p(x_1) &\coloneqq \mathrm{N}(x_1 \mid 0, 1), \\ p(x_k \mid x_{k-1}) &\coloneqq \mathrm{N}\big(x_k \mid \mathrm{e}^{-\Delta} \, x_{k-1}, 1 - \mathrm{e}^{-2\,\Delta}\big). \end{split}$$

• Implement  $p(x_{1:T})$ , and numerically verify that  $p(x_{1:T}) = N(x_{1:T} \mid 0, C_{1:T})$  for any input  $x_{1:T}$ . Compare the speed of the two PDF implementations and see which is faster, in particular, try let T be some huge values.

**Note**: you may want to implement the PDFs in log scale for better numerical representation.

• (Bonus +2 points) We can also verify that the samples drawn from the joint density and the Markov-factorised density are the same. 1) Draw a sample  $X_{1:T}^{(1)} \sim \mathcal{N}(x_{1:T} \mid 0, C_{1:T})$  from this multivariate Normal distribution. 2) Sequentially draw  $X_1^{(2)} \sim p(x_1)$  then draw  $X_2^{(2)} \mid X_1^{(2)} \sim p(x_2 \mid x_1)$  and so on until  $X_T^{(2)} \mid X_{T-1}^{(2)} \sim p(x_T \mid x_{T-1})$ . Collect these samples in a vector  $X_{1:T}^{(2)}$ . 3) Verify that  $X_{1:T}^{(1)} = X_{1:T}^{(2)}$ , and compare which sampling method is faster (recall to let the two sampling routines share the same randomness).

# \* Assignment 6 (1 point)

This assignment is mandatory, as you have to simulate a Brownian motion in order to simulate any SDE. Simulate and plot 20 independent paths from a

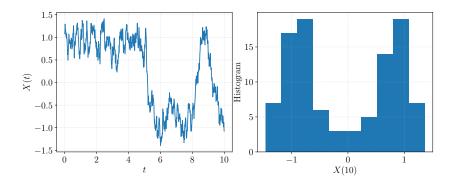


Figure 2: Left: a trajectory from the double-well SDE. Right: the histogram of the trajectories at t=10.

standard Brownian motion on the time interval [0,1]. In the same figure, plot the 0.95 quantile/interval of the Brownian motion at the times, and verify that the trajectories are mostly within the interval. You should get a similar result as in Figure 1. Note: since Var[W(t)] = t, the 0.95 quantile is a function  $t \mapsto 1.96 t$ .

### Assignment 7 (2 point)

Using the Euler–Maruyama scheme to simulate 100 independent trajectories from the double-well SDE

$$dX(t) = 4(X(t) - X(t)^3) dt + dW(t), \quad X(0) = 1,$$

at evenly placed times  $t_1 = 0.01, t_2 = 0.02, \dots, t_{1000} = 10$ . Demonstrate one trajectory, and plot the histogram of the 100 trajectories at the terminal time  $t_{1000}$ . You should get a similar plot as in Figure 2.

# Assignment 8 (2 points)

Consider a Cox-Ingersoll-Ross (CIR) process given by

$$dX(t) = a \left(b - X(t)\right) dt + \sigma \sqrt{X(t)} dW(t), \quad X(0) = 0.1,$$

where we let a=2, b=0.5, and  $\sigma=1.5$ . Remark that this CIR process is by definition non-negative (i.e.,  $X(t) \geq 0$  for all  $t \geq 0$ ). Now consider evenly placed times  $t_1=0.001, t_2=0.002, \ldots, t_{10000}=10$ .

- Use Euler–Maruyama to simulate multiple independent trajectories of this SDE at the times. Check if any of the simulations numerically fails, and explain why.
- Use Milstein's method or any other higher order method to simulate the trajectory, and compare to that of Euler–Maruyama.

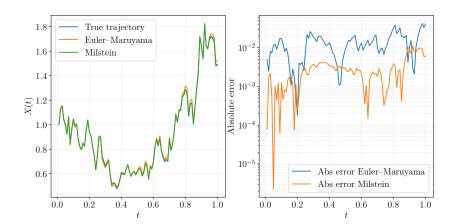


Figure 3: Left: trajectories of the SDE in Assignment 9. Right: absolute errors compared to the true trajectory.

### Assignment 9 (3 points)

Recall the SDE in Assignment 4:

$$dX(t) = aX(t) dt + bX(t) dW(t),$$

and we have shown that

$$X(t) := X_0 \exp\left(\left(a - \frac{b^2}{2}\right)t + bW(t)\right)$$

solves the SDE. Now set  $a=-1, b=1, X_0=1$ , and consider times  $t_1=\Delta, t_2=2\Delta, \ldots, t_T=T\Delta$ . Let T=10 and  $\Delta=0.1$ .

- Simulate a trajectory of X at the times by using the explicit solution.
- Use Euler—Maruyama to simulate a path of the SDE at the times, then compare to the true path. (recall to use the same realisation of the Brownian motion path to control the randomness)
- Keep  $T\Delta = 1$  and increase the number of times T, for example,  $(T = 100, \Delta = 0.01), (T = 1000, \Delta = 0.001), ...$  Check if the Euler–Maruyama approximation gets better as the discretisation gets finer.
- (bonus +2 point) use Milstein's method to simulate X at the times, then compare to that of Euler–Maruyama (e.g., plot the absolute differences w.r.t. the true trajectory in log scale). As an example, Figure 3 compares the errors when T=100 and  $\Delta=0.01$ .

### Assignment 10 (2 points)

Consider a three-dimensional stochastic Lorenz model

$$\mathbf{d} \begin{bmatrix} X(t) \\ Y(t) \\ Z(t) \end{bmatrix} = \begin{bmatrix} \eta \left( Y(t) - X(t) \right) \\ X(t) \left( \rho - Z(t) \right) - Y(t) \\ X(t) Y(t) - \beta Z(t) \end{bmatrix} \mathbf{d}t + \sigma \, \mathbf{d}W(t),$$
$$\begin{bmatrix} X(0) \\ Y(0) \\ Z(0) \end{bmatrix} \sim \mathbf{N}(0, I_3),$$

where W is a three-dimensional Brownian motion (and its components are mutually independent). Let  $\eta=10, \rho=28, \beta=8/3$ , and  $\sigma=2$ . Simulate a trajectory from this SDE by using Euler–Maruyama. The discretisation times are up to you.

(bonus +4 points) Use the order 1.5 strong Taylor scheme to simulate a trajectory, and compare to that of Euler–Maruyama. Recall the Gaussian-increment based simulation in the lecture note, so that you can compare them under the same randomness. The following figure is an example.

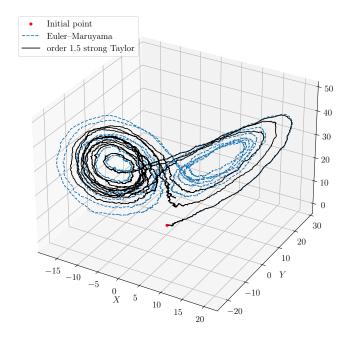


Figure 4: Euler–Maruyama and order 1.5 strong Taylor for simulating the Lorenz model ( $T = 10^4, \Delta = 10^{-3}$ ). Due to the non-linearity of the model, two methods deviate significantly as t increases.