

The Neural Energy Decoder

Energy Disaggregation by Combining Binary
Subcomponents

Henning Lange

PhD Student

henningl@andrew.cmu.edu

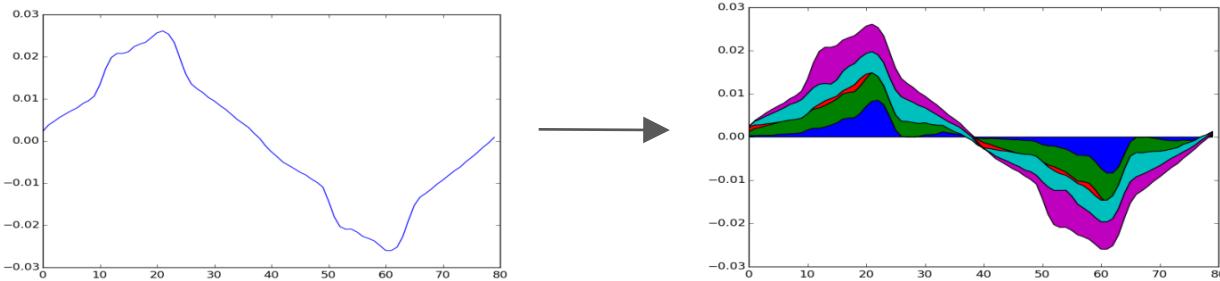
Mario Berges

Associate Professor

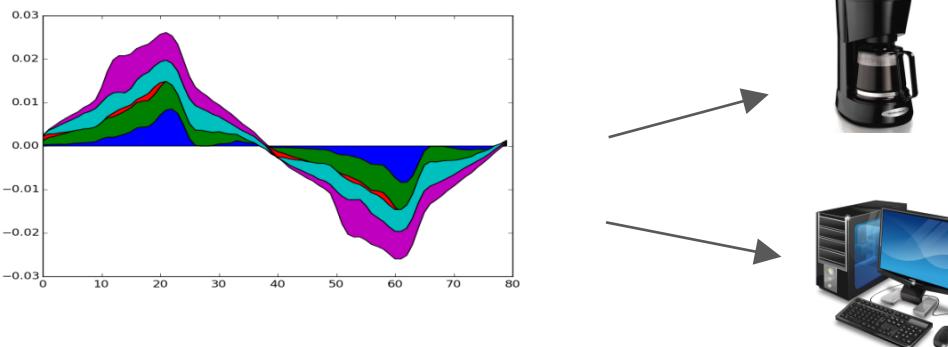
marioberges@cmu.edu

Introduction: Disaggregation in two steps

1) Find recurring building blocks in the aggregate current waveforms



2) Combine inferred subcomponents into appliances

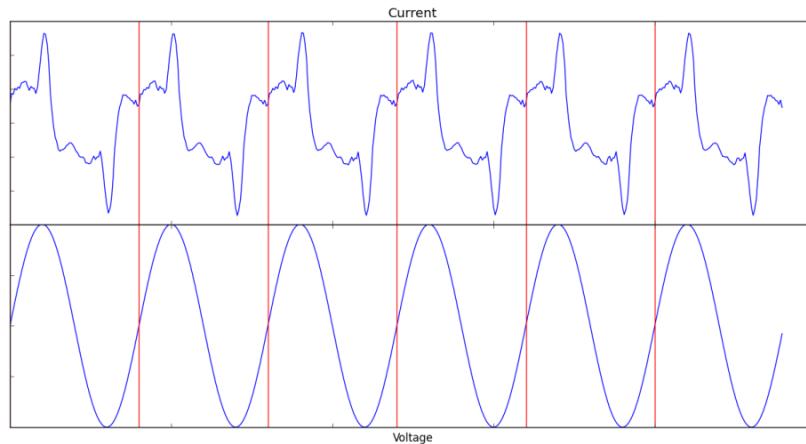


Step 1: Inferring additive subcomponents

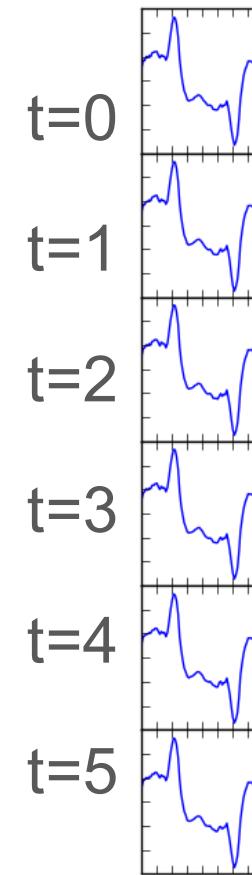
- Fully unsupervised

Step 1: Data pre-processing

Preserving phase info by slicing current
according to zero-crossings in voltage:



Matrix containing current $Y \in \mathbb{R}^{T \times N}$:



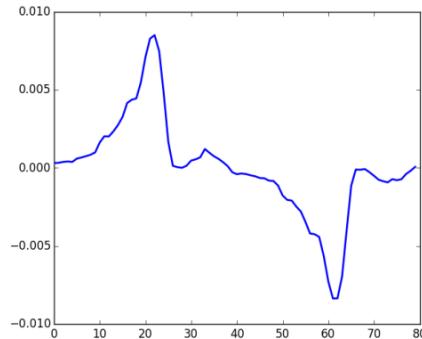
Step 1: Identifying sub-components

- Fully unsupervised
- Binary Matrix Factorization: minimize $\|XG - Y\|$
 - $X \in \{0,1\}^{T \times C}$: temporal information
 - $G \in \mathbb{R}^{C \times N}$: shape of component waveform
 - $Y \in \mathbb{R}^{T \times N}$: matrix containing aggregate waveforms
- BMF is NP-complete problem

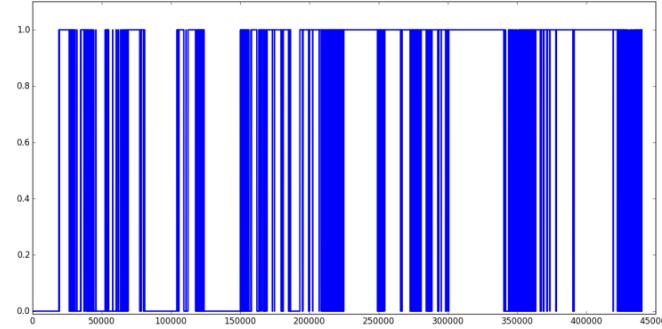
Step 1: One slice of X and G

- minimize $\|XG - Y\|$
- Let's consider the i th row of X and the i th column of G

What: G_i



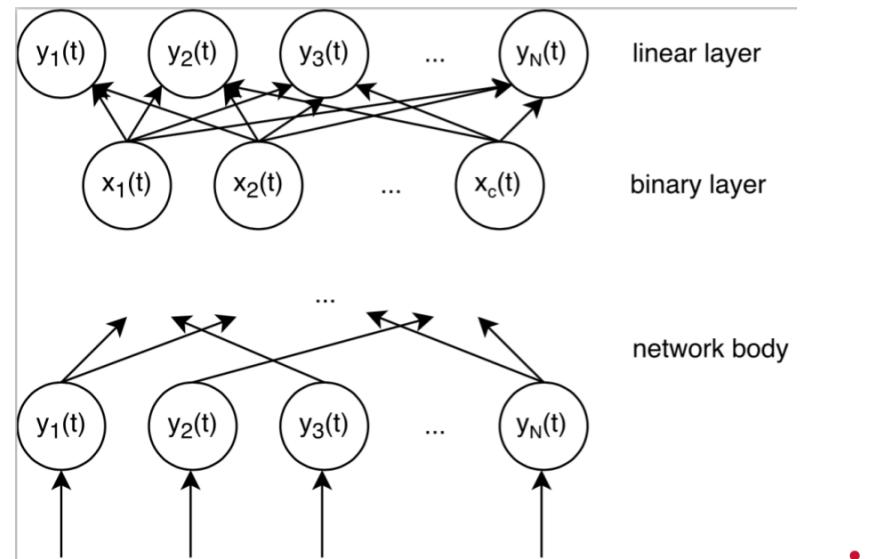
When: X_i



Step1: Neural Binary Matrix Factorization

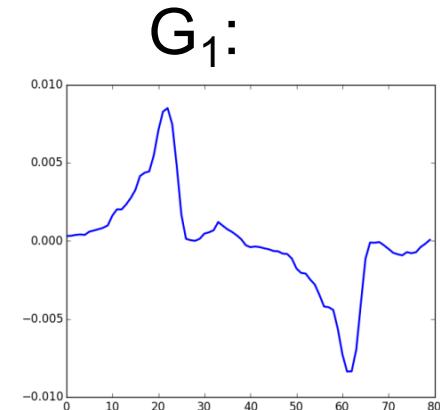
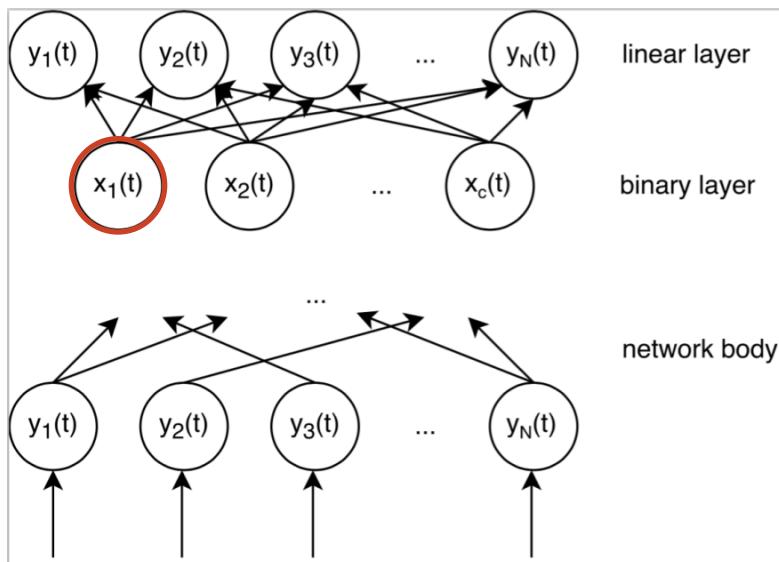
- Approximation using Neural Network

- special topology
- Autoencoder
- Output: XG with X being binary
- Learning: minimize $||XG - Y||$ given some input

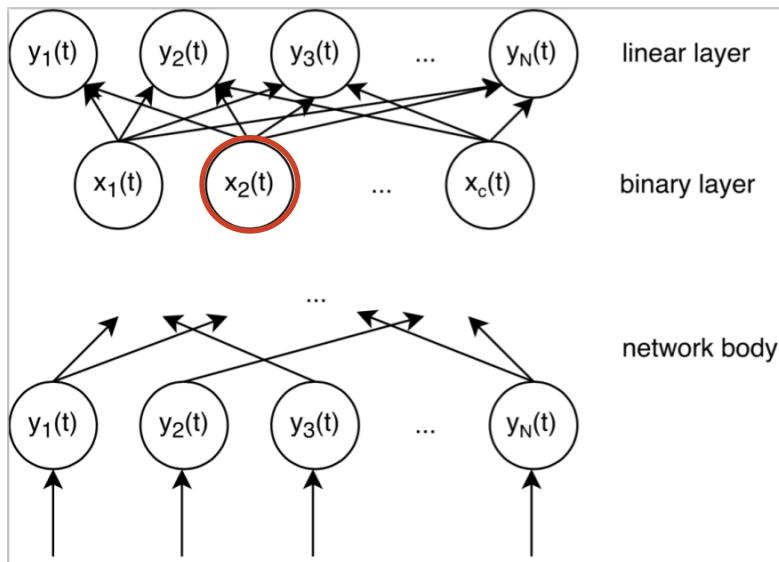


ing on GPU possible
recommended)

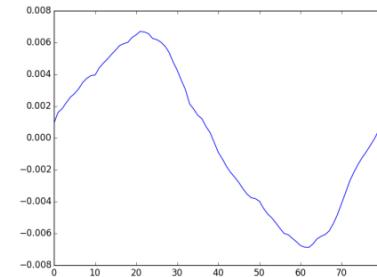
Step1: Neural Binary Matrix Factorization



Step1: Neural Binary Matrix Factorization



G_2 :

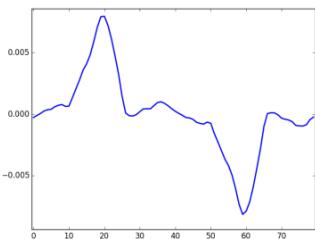


Step1: Application to Phase B of BLUED

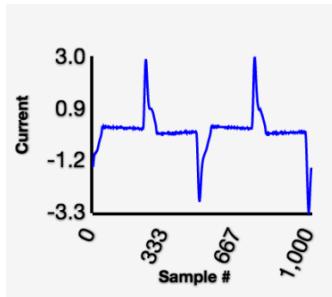
- BLUED: sampling frequency of 12kHz but resampled to 4.8kHz, i.e N=80
- 5 layer neural network created with keras*
 - 60 cycles fed into network at once in freq domain
 - layers: 4800 -> 2000 -> 1000 -> 100 -> 4800
- C = 100, i.e. 100 inferred subcomponents

Step1: Application to Phase B of BLUED

Component 63:



Laptop: *



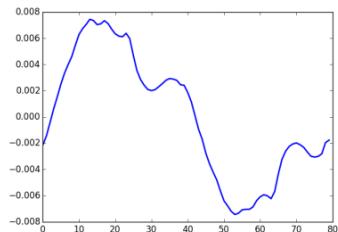
AC-DC converter?

- Electronics
 - Computer
 - Laptop
- ...

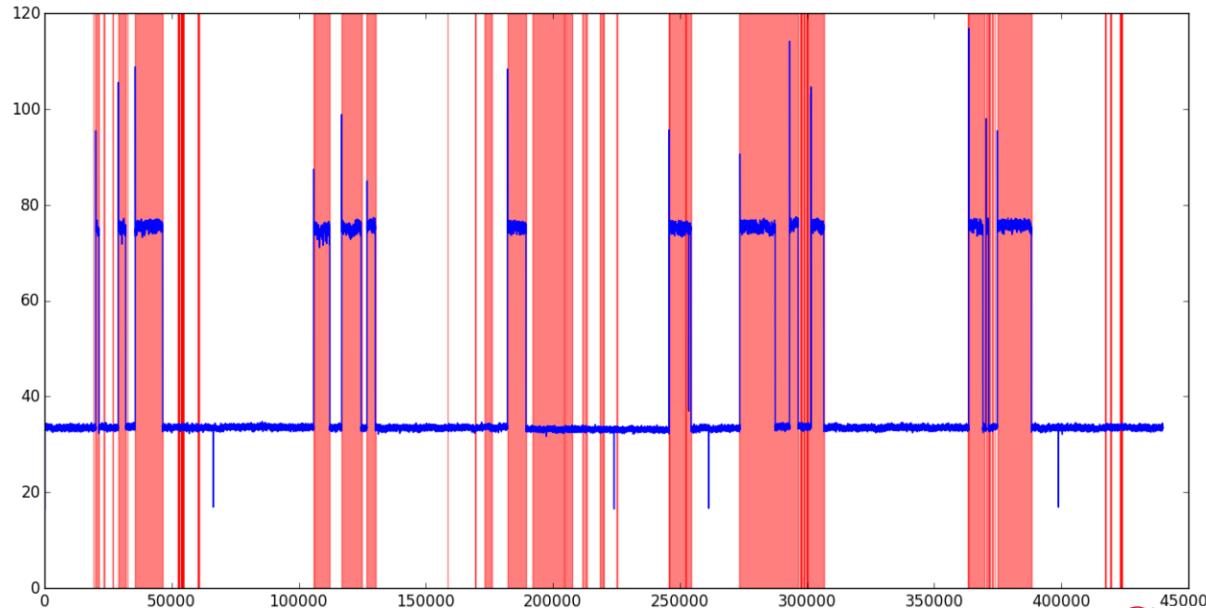
* taken from PLAID (www.plaidplug.com)

Step1: Application to Phase B of BLUED

Component 34:



X_{34} :

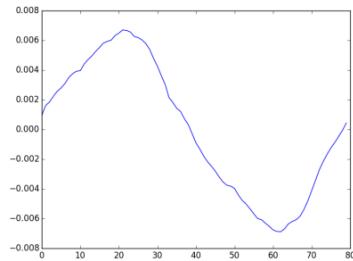


Note: DVR and TV
have a temporal
correlation of 1

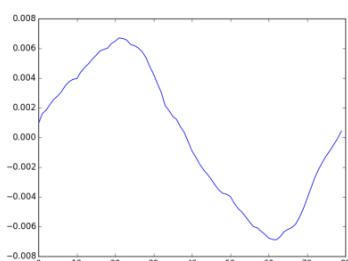
= component 34 is turned on

Step 1: Some components cannot be appliances

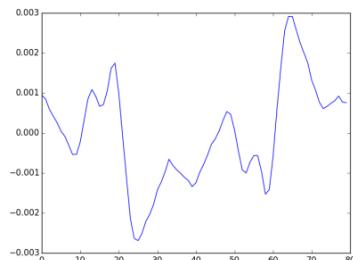
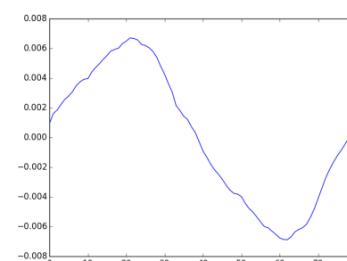
- A single appliance as a superposition of components



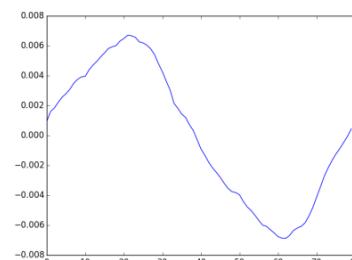
+



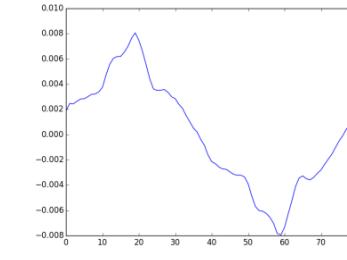
=



+



=



Step 2: Combining additive subcomponents

- supervised
- unsupervised

Step 2: Supervised Re-Aggregation

- Assuming knowledge $Q \in \{0,1\}^{T \times A}$ containing ground truth of appliance
 - 2-state appliances: *on* or *off*
- Find mapping between X and Q
 - Logistic Regression
 $[0, 1, 0, 1, 1, 0, \dots] \rightarrow [0, 1, \dots]$



Results: Logistic Regression

$$mde(p, \hat{p}) = \sum_{i,t} \frac{|p_i(t) - \hat{p}_i(t)|}{p_i(t)}$$

Appliance	Active	Boolean F1	Logit F1	MDE(\hat{p})	MDE(p)
A/V LR	60%	0.89	0.98	0.04	0.009
Computer 1	27.3%	0.88	0.99	0.05	0.042
Desk Lamp	21.4%	0.84	0.95	0.06	0.013
DVR	20.7%	0.94	0.99	0.006	0.005
Socket LR	> 0.1%	0.96	0.92	0.09	0.089
Garage Door	0.4 %	0.49	0.89	0.07	0.063
Iron	0.1 %	0.74	0.92	0.12	0.115
Laptop 1	33.3%	0.75	0.92	0.34	0.272
LCD Monitor	16.2%	0.73	0.94	0.12	0.029
Monitor 2	17.3%	0.80	0.92	0.20	0.089
Printer	0.1%	0.45	0.70	0.05	0.045
Tall Desk Lamp	21.4%	0.84	0.95	0.06	0.008
TV Basement	20.7%	0.94	0.99	0.05	0.029
Random	30%	0	0	-	-
Overall				0.058	0.037

TABLE I

Results: Logistic Regression

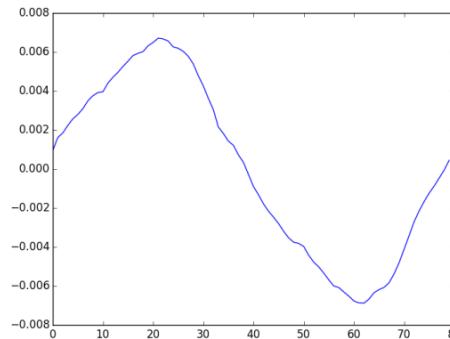
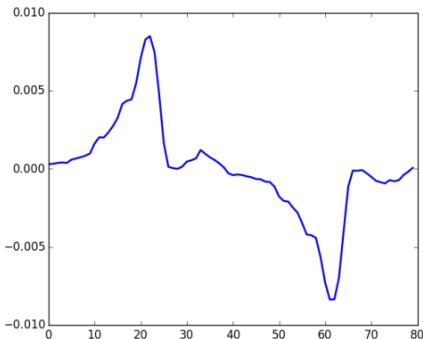
$$mde(p, \hat{p}) = \sum_{i,t} \frac{|p_i(t) - \hat{p}_i(t)|}{p_i(t)}$$

Appliance	Active	Boolean F1	Logit F1	MDE(\hat{p})	MDE(p)
A/V LR	60%	0.89	0.98	0.04	0.009
Computer 1	27.3%	0.88	0.99	0.05	0.042
Desk Lamp	21.4%	0.84	0.95	0.06	0.013
DVR	20.7%	0.94	0.99	0.006	0.005
Socket LR	> 0.1%	0.96	0.92	0.09	0.089
Garage Door	0.4 %	0.49	0.89	0.07	0.063
Iron	0.1 %	0.74	0.92	0.12	0.115
Laptop 1	33.3%	0.75	0.92	0.34	0.272
LCD Monitor	16.2%	0.73	0.94	0.12	0.029
Monitor 2	17.3%	0.80	0.92	0.20	0.089
Printer	0.1%	0.45	0.70	0.05	0.045
Tall Desk Lamp	21.4%	0.84	0.95	0.06	0.008
TV Basement	20.7%	0.94	0.99	0.05	0.029
Random	30%	0	0	-	-
Overall				0.058	0.037

TABLE I

Step 2: Unsupervised Re-Aggregation

- Waveform clustering by ‘appliance type’ conceivable
 - Electronics
 - Resistive loads, etc ..



Step 2: Best component for each appliance

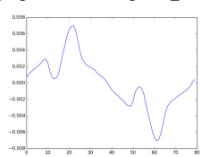
- For each appliance, the component that resulted in highest F1 score
- Random baseline:
 - 0.3

Appliance	Active	Lower Bound F1	Naïve F1
A/V LR	60%	0.85	0.85
Computer 1	27.3%	0.67	0.74
Desk Lamp	21.4%	0.70	0.70
DVR	20.7%	0.85	0.85
Socket LR	> 0.1%	0.0	0.0
Garage Door	0.4 %	0.24	0.3
Iron	0.1 %	0.09	0.30
Laptop 1	33.3%	0.71	0.71
LCD Monitor	16.2%	0.63	0.63
Monitor 2	17.3%	0.67	0.70
Printer	0.1%	0.07	0.07
Tall Desk Lamp	21.4%	0.70	0.70
TV Basement	20.7%	0.85	0.85

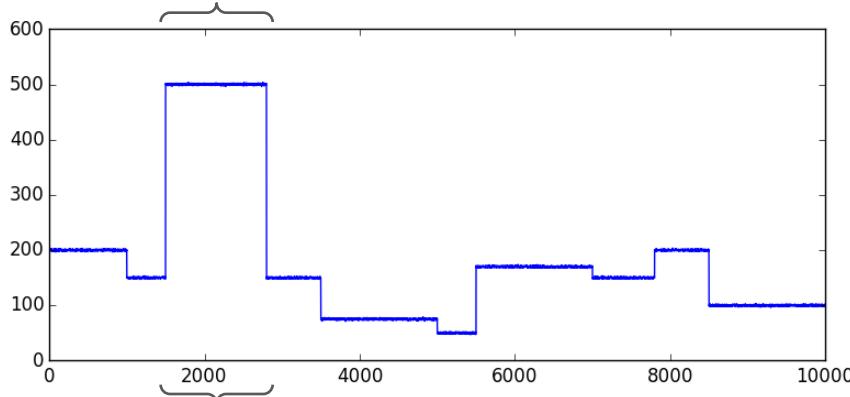
TABLE IV

Step 2: Augmenting existing approaches

- Existing NILM systems can be improved using NED
- A hypothesis could be tested:



ced:



?

Conclusion

- Supervised: a single cycle of current sufficient to infer activity of appliance with decent precision
- Unsupervised:
 - Cluster according to waveform type?
 - Combine components in an unsupervised way possible?
 - Augment existing approaches with waveform information?
 - Regularization, sparse coding?

Thank you!

- Special thanks to Jack Kelly and Jingkun Gao for the feedback in our Skype calls :)
- Code for image and sound disaggregation available at:
 - <http://henning.inferlab.org/neural-bmf/>
- BLUED dataset can be found here:
 - <http://portoalegre.andrew.cmu.edu:88/BLUED/>
- Interested in a dump of the inferred matrices X, G and ground truth Q?



INFERLab
Intelligent Infrastructure
Research Laboratory

ningl@andrew.cmu.edu

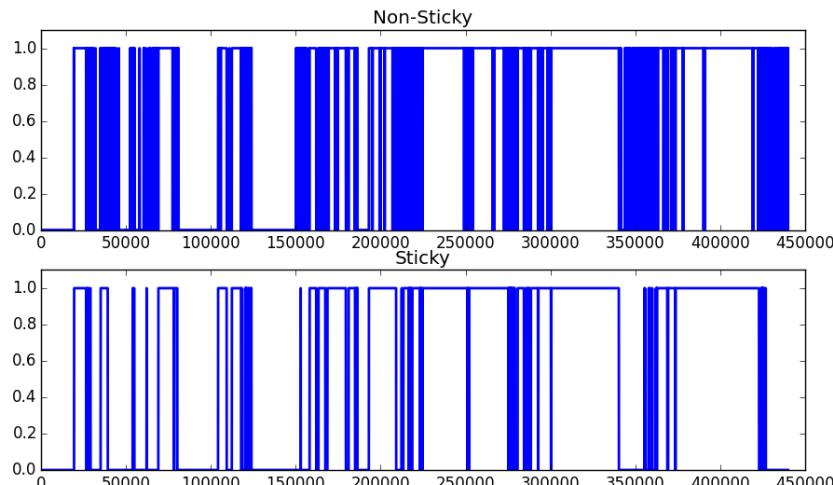
Carnegie
Mellon
University

Step 1: Factorial HMMs and BMF

- Inference in additive FHMMs can be represented as a BMF problem with some temporal regularization

- minimize $\|XG - Y\| + f(X)$

- $f(X)$ temporal regularization
 - makes states 'sticky'

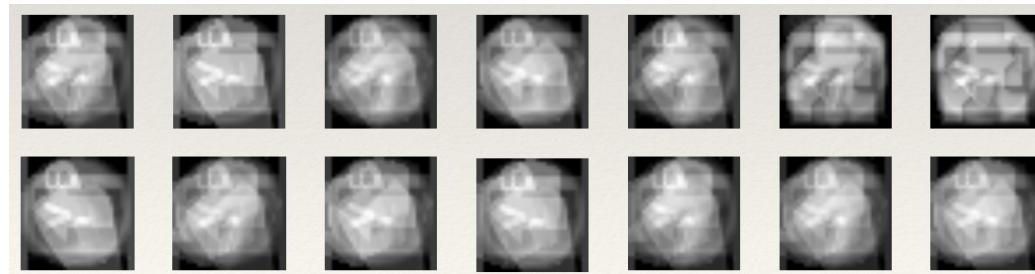


Disentangling Images

Source images:



Grayscale superpositions of images:



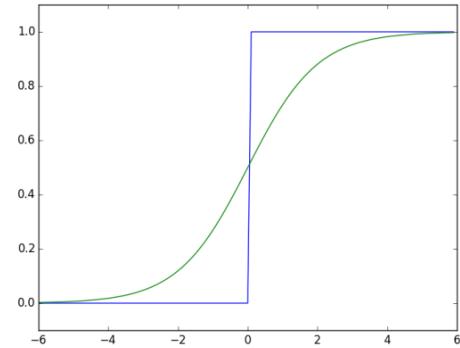
Disentangling Images

Weights of the components inferred by Neural BMF:



Non-Smoothness

- Binary Units: Output of the network is non-smooth
- Aggregate power trace is also non-smooth
 - Jumps or drops when appliance is turned on/off
- Stochastic Gradient Descent requires gradients to be defined
 - $f(x) = 1$ iff $x > 0$, 0 else: gradient either 0 or not defined ($x=0$)



approximation: Set gradient of binary derivative of $(1 - \exp(-x))^{-1}$