

B-7-3

$$(1) \quad G_1(s) = \frac{1+s}{1+2s}$$

$$G_2(s) = \frac{1-s}{1+2s}$$

Solution:

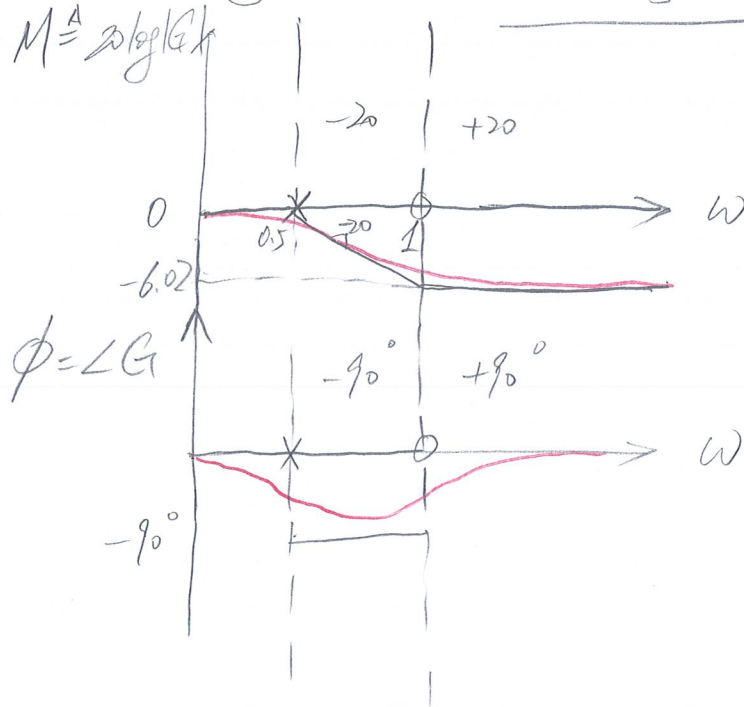
(1) For $G_1(j\omega)$, the corner frequencies include:

$\omega_c = 1$ ("stable zero"), 0.5 ("stable pole")

Initial angle $\lim_{\omega \rightarrow 0} \angle G_1(j\omega) = 0^\circ$

Initial magnitude $\lim_{\omega \rightarrow 0} |G_1(j\omega)| = 1 = 0 \text{ dB}$

$M \triangleq 20 \log |G_k|$



Also $\lim_{\omega \rightarrow \infty} |G(j\omega)| = 0.5$
 $\approx -6.02 \text{ dB}$

(2) Corner frequencies:

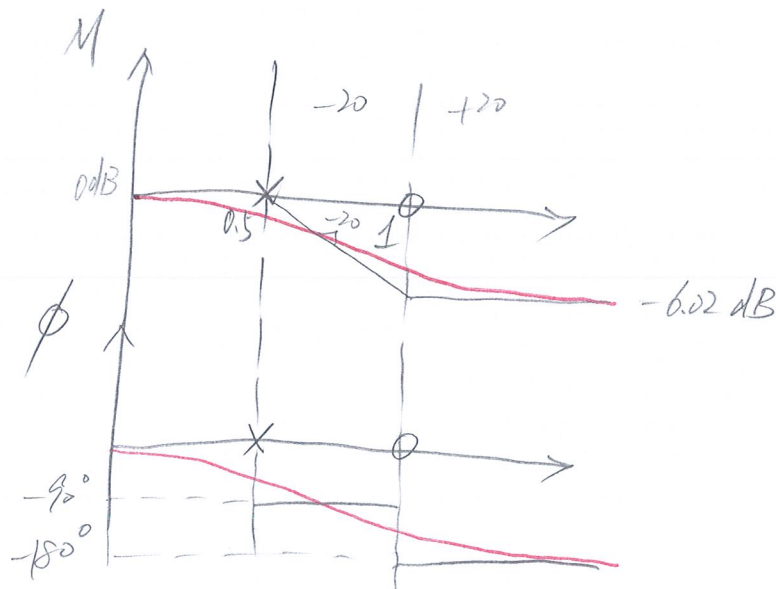
ω_c : 1 ("unstable zero"), 0.5 ("stable pole")

$$\lim_{\omega \rightarrow 0} \angle G(j\omega) = 0^\circ$$

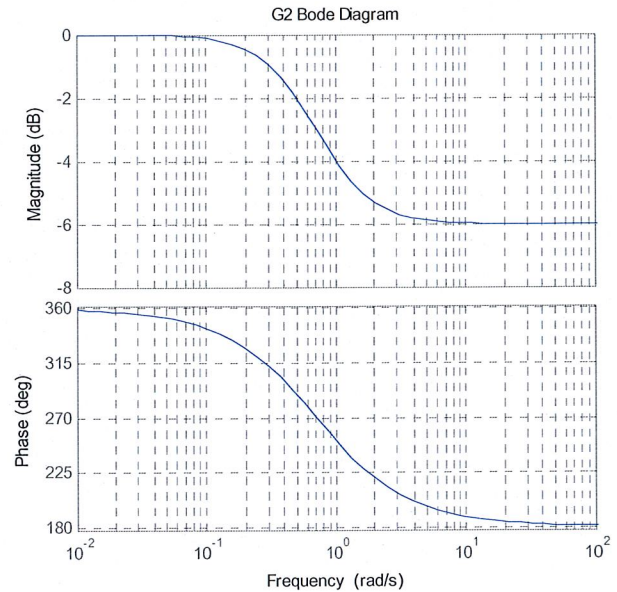
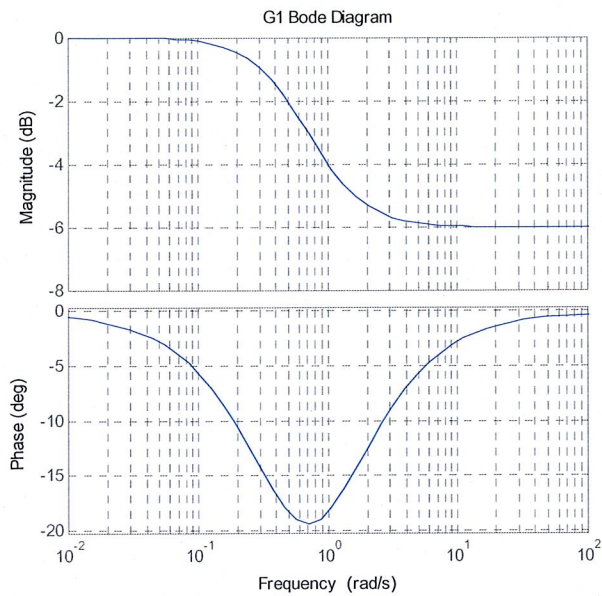
$$\lim_{\omega \rightarrow 0} |G(j\omega)| = 1$$

$$\lim_{\omega \rightarrow \infty} |G(j\omega)| = \frac{1}{2}$$

- Unstable zeroes result in a non-minimum phase behavior. The magnitude response corresponding to such a zero stays the same as for stable zeroes, but the phase angle at $\omega = \infty$ becomes -90° . [Pg 415 in Section 7-2]
- Unstable poles result in a non-minimum phase behavior. The magnitude response corresponding to such a pole is unchanged, but the phase angle at $\omega = \infty$ becomes $+90^\circ$.



Problem B-7-3



[Matlab code]

```
clear all; close all; clc

num1=[1 1]; %numerator of G1(s)
den1=[2 1]; %denominator of G1(s)

num2=[-1 1]; %numerator of G2(s)
den2=[2 1]; %denominator of G2(s)

figure()
subplot(1,2,1)
bode(num1, den1)
grid on
title ('G1 Bode Diagram')

subplot(1,2,2)
bode(num2, den2)
grid on
title ('G2 Bode Diagram')
```

B-7-4

$$G(s) = \frac{10(s^2 + 0.4s + 1)}{s(s^2 + 0.8s + 9)}$$

Solution:

Corner frequencies: 1^{x2} ("stable zero")

3^{x2} ("stable pole")

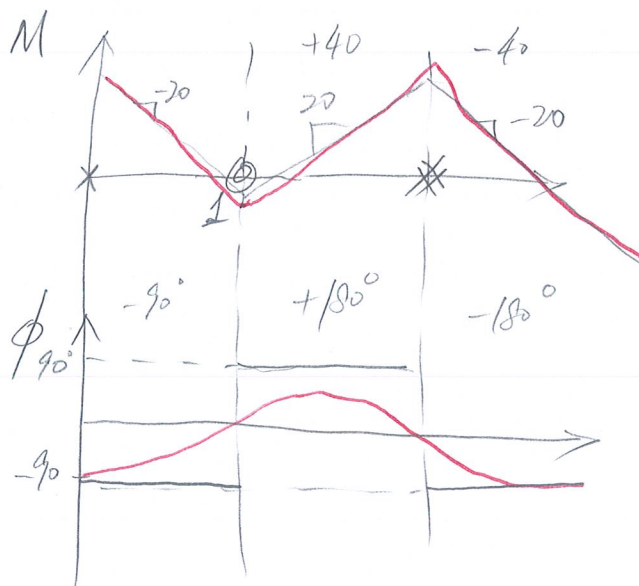
0

$$\lim_{\omega \rightarrow 0^+} \angle G(j\omega) = \lim_{\omega \rightarrow 0} \angle \frac{10(-\omega^2 + 0.4j\omega + 1)}{j\omega(-\omega^2 + 0.8j\omega + 9)}$$

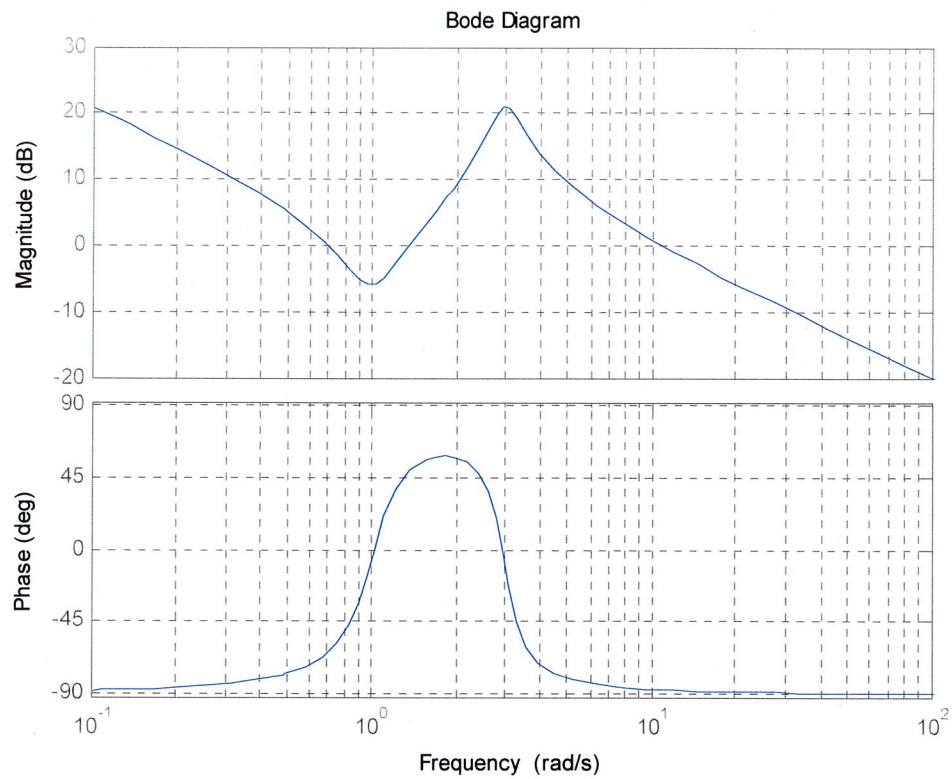
$$= \lim_{\omega \rightarrow 0} \left(\angle 10 + \angle(-\omega^2 + 0.4j\omega + 1) \right.$$

$$\left. = -90^\circ - \angle j\omega - \angle(-\omega^2 + 0.8j\omega + 9) \right)$$

(Crossover frequency: $|G(j\omega^*)| = 1$ or 0 dB)



B-7-4



[Matlab code]

```
sys=tf([10 4 10],[1 0.8 9 0])  
  
figure()  
bode(sys)  
grid on
```


B-7-7

$$G(s) = K \frac{(T_a s + 1)(T_b s + 1)}{s^2 (T s + 1)}$$

(a) $T_a > T_b > T$

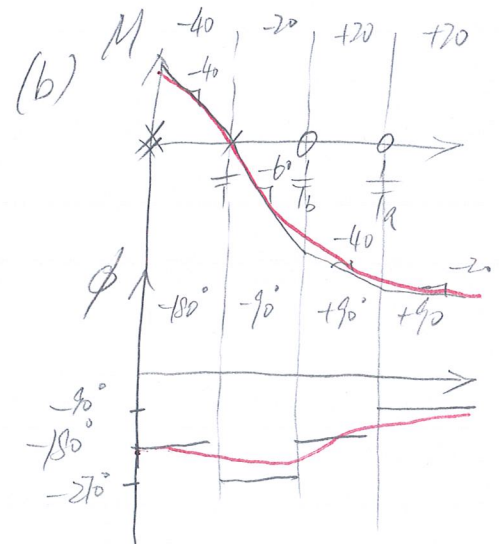
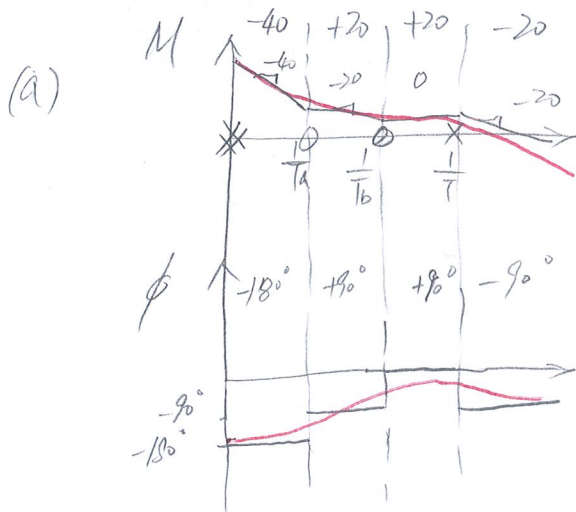
(b) $T > T_a > T_b$

Assume $T_a > T_b$ WLOG

Solution:

Corner frequencies: $\underbrace{\frac{1}{T_a}, \frac{1}{T_b}}_{\text{"stable zero"}}, \underbrace{\frac{1}{T}}_{\text{"stable pole"}}, 0^{x2}$

$$\lim_{\omega \rightarrow 0} \angle G(j\omega) = -180^\circ$$



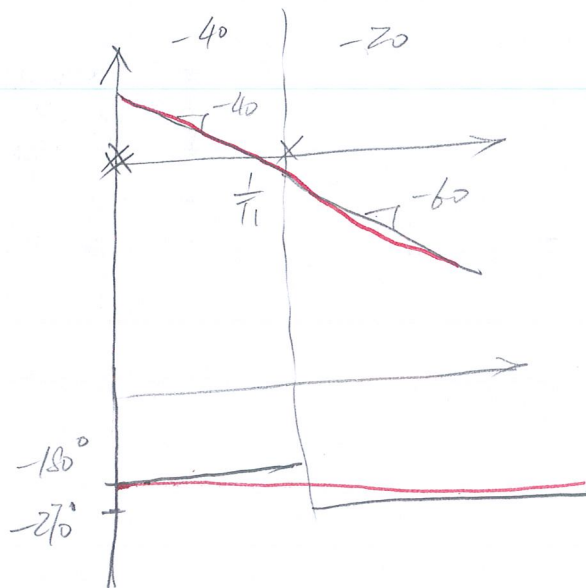
B-7-9.

$$G = \frac{K}{s^2(T_1 s + 1)}$$

Solution:

Corner frequencies: 0^{x2} , $\frac{1}{T_1}$
("stable pole")

As $\omega \rightarrow 0$, $G(j\omega) \rightarrow +\infty \angle -180^\circ$



B-7-13

$$G = \frac{1}{s^3 + 0.2s^2 + s + 1}$$

Solution:

poles of G : -0.7246 , $0.2623 \pm j1.1451$ ^{"unstable"}

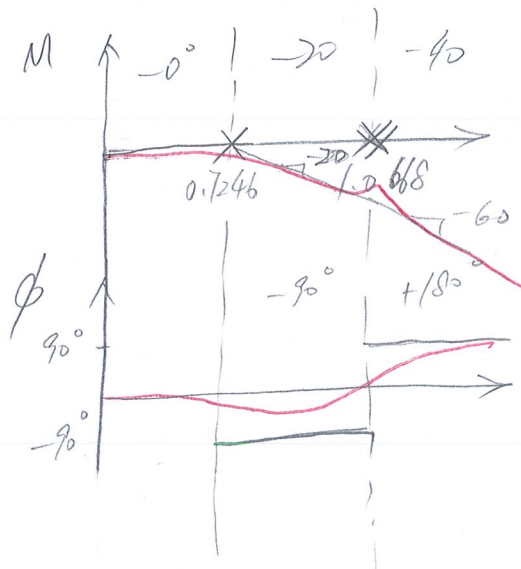
\Downarrow

$$G = \frac{1}{(s + 0.7246)(s^2 - 0.5246s + 1.1381)}$$

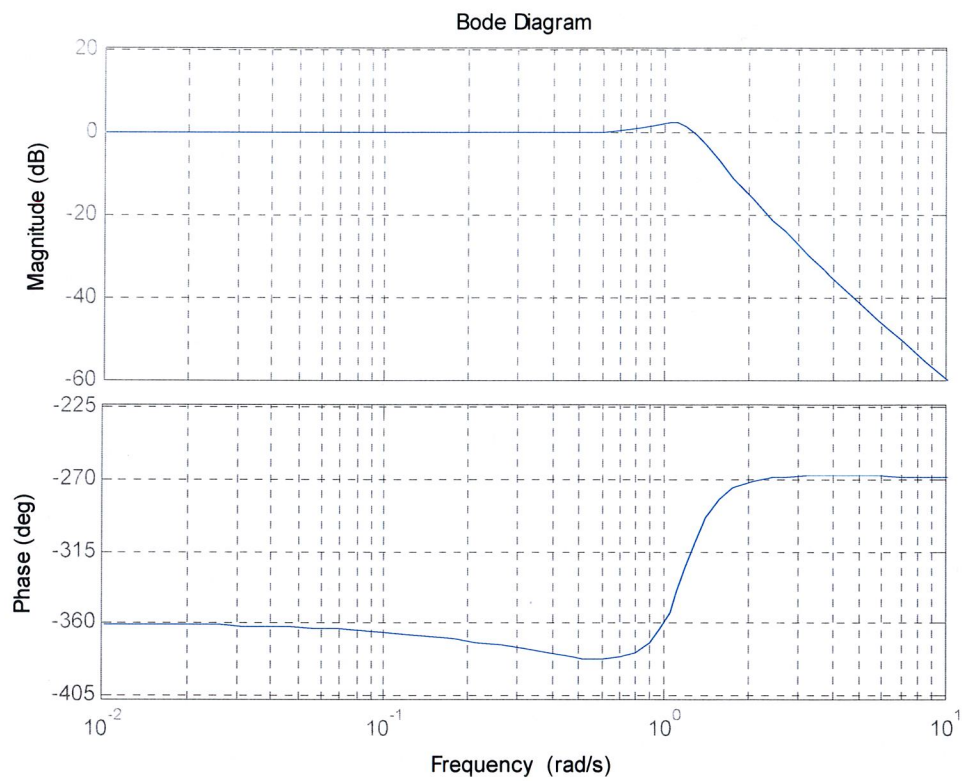
$$G(j\omega) = \frac{1}{0.7246 \times 1.1381 \left(\frac{j\omega}{0.7246} + 1 \right) \left(1 - \frac{0.5246}{1.1381} j\omega + \frac{(j\omega)^2}{1.1381} \right)}$$

Corner frequencies: $+0.7246$, $\sqrt{1.1381} \times 2$
(unstable poles")

$$\lim_{\omega \rightarrow 0} \angle G(j\omega) = 0^\circ \quad \lim_{\omega \rightarrow 0} |G(j\omega)| = 1 = 0 \text{ dB}$$



B-7-13



[Matlab code]

```
sys=tf(1,[1 0.2 1 1])  
  
figure()  
bode(sys)  
grid on
```

B-7-14.

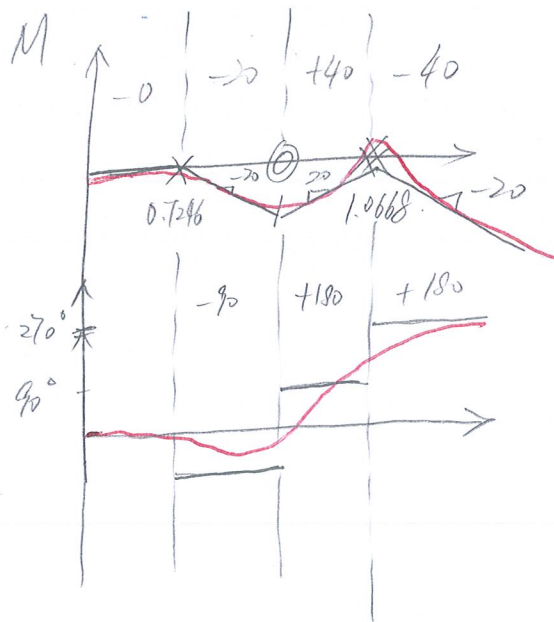
$$G = \frac{s^2 + 2s + 1}{s^3 + 0.2s^2 + s + 1}$$

Solution:

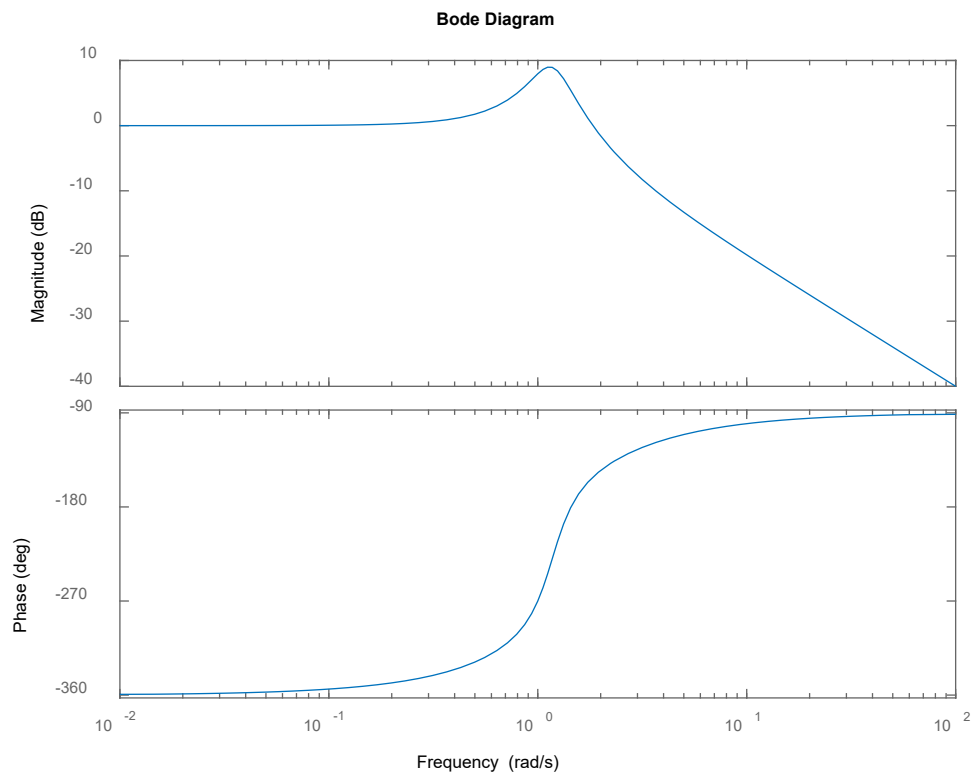
From B-7-13, we know poles are -0.7246 and $0.7623 \pm j1.1451$.

Corner frequencies: $\underbrace{0.7246}_{\text{"stable pole"}}, \underbrace{1}_{\text{"stable zeros"}}, \underbrace{1.0668}_{\text{"unstable poles"}}$

As $\omega \rightarrow 0$, $G(j\omega) \rightarrow 1 \angle 0^\circ$



B-7-14



$G = \text{tf}([1 \ 2 \ 1], [1 \ 0.2 \ 1 \ 1])$

`bode(G)`