

P2: K

2020年2月28日 金曜日 午後0:33

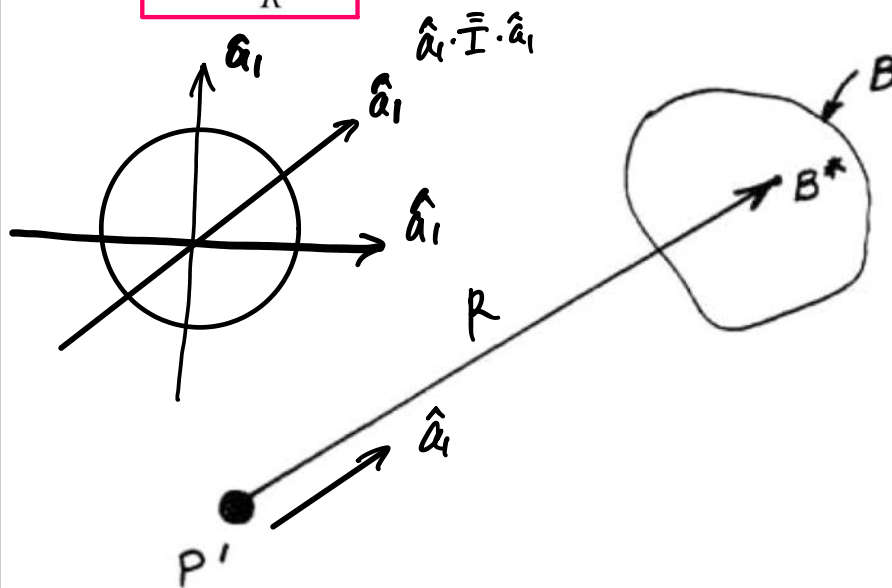
Centrobatic Body

$$Cm = Cg$$

→ gravity torque is 0

Body B is centrobatic if its exact gravity force can be written

$$\bar{F} = -\frac{Gm'm}{R^2} \hat{a}_1 \text{ for all attracting bodies } P' \text{ (outside B)}$$



* replace body w/ a particle

• Newton treated planets as centrobatic bodies

So body B has the same gravity as a particle *inverse square law point mass*

Body B can be replaced with a particle of mass m at B^*

$$\longrightarrow Cg = Cm$$

Examples: particle

sphere → *satellite*

spherical shell → *uniform mass density*

exact
↙

$$\bar{\mathbf{F}} = - \int G m' \bar{\rho} (p^2)^{-\frac{3}{2}} v d\tau \quad \text{for any body B} \quad cm = cg$$

↓

$$\bar{\mathbf{F}} = - \frac{G m' m}{R^2} \left[\hat{\mathbf{a}}_1 + \sum_{i=2}^{\infty} \bar{\mathbf{f}}^{(i)} \right]$$

$\Sigma = 0$
 $\bar{\mathbf{f}}^{(2 \rightarrow \infty)} = 0$

Proving a body IS centrobatic means integrating to determine the form of the total gravity force

Proving a body IS NOT centrobatic means finding that $\sum_{i=2}^{\infty} \bar{\mathbf{f}}^{(i)} \neq 0$

Note:

$$\bar{\mathbf{f}}^{(2)} \propto R^{-2}$$

$$\bar{\mathbf{f}}^{(3)} \propto R^{-3}$$

\vdots

$$\therefore \bar{\mathbf{f}}^{(i)} = 0 \quad i = 1, 2, 3, \dots, \infty$$

body is not centrobatic

to make sum equal to zero, each $\bar{\mathbf{f}}^{(i)}$ must vanish separately.

One consequence of this fact is associated with $\bar{f}^{(2)}$

→ To be centrobatic, ONE requirement: $\bar{f}^{(2)} = 0$

If $\bar{f}^{(2)} = 0$, all components must be zero

$\hat{a}_1 \cdot \bar{f}^{(2)} = 0 \longrightarrow$ component along the orbit radial direction

$$\hat{a}_1 \cdot \frac{1}{mR^2} \left\{ \frac{3}{2} \left[\text{tr}(\bar{I}) - 5\hat{a}_1 \cdot \bar{I} \cdot \hat{a}_1 \right] \hat{a}_1 + 3\bar{I} \cdot \hat{a}_1 \right\} = 0$$

$\bar{f}^{(2)}$

$$\frac{3}{2} [\text{tr}(\bar{I}) - 5\hat{a}_1 \cdot \bar{I} \cdot \hat{a}_1] + 3\hat{a}_1 \cdot \bar{I} \cdot \hat{a}_1 = 0$$

$$\frac{3}{2} \text{tr}(\bar{I}) - \frac{9}{2} \hat{a}_1 \cdot \bar{I} \cdot \hat{a}_1 = 0$$

OR

$$\hat{a}_1 \cdot \bar{I} \cdot \hat{a}_1 = \frac{1}{3} \text{tr}(\bar{I})$$

$= \text{const.}$

→ necessary condition for body to be centrobatic

Trace is invariant (constant)

$\hat{a}_1 \cdot \bar{I} \cdot \hat{a}_1$ must have the same value no matter how body is oriented

→ $\text{tr}(\bar{I})$ is invariant, no matter which unit vector \hat{I} is expressed $\text{tr}(\bar{I})$ is always constant.

Centrobatic body has the same moment of inertia about every line passing through the mass center

→ Central inertial ellipsoid is a sphere

→ definition of centrobatic

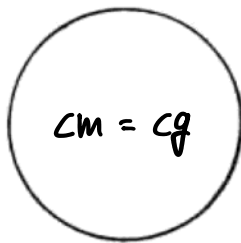
Central inertia ellipsoid is a sphere

So, all centrobaric bodies have a spherical inertia ellipsoid

BUT

All bodies with a spherical inertia ellipsoid are not centrobaric

$$\bar{f}^{(2)} = 0 \rightarrow \text{necessary condition}$$



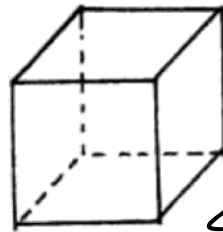
{ shell
sphere
collection of spherical shells

$$\bar{f}^{(2)} = 0$$



$$\text{all } \bar{f}^{(i)} = 0$$

is centrobaric



$$\text{cm} \neq \text{cg}$$

density const.

→ central inertia ellipsoid is a sphere

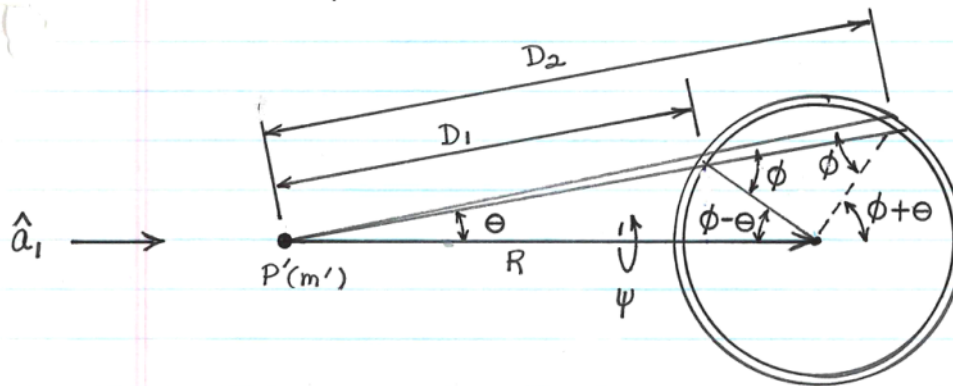
$$\hat{a}_1 \cdot \bar{f}^{(2)} = 0$$

$$\text{not all } \bar{f}^{(i)} = 0$$

* meets one of the cond.
but not all.

not centrobaric

Example: Spherical Shell is centrobatic (radius r)



Resultant of all gravity forces

$$\vec{F} = -Gm' \int \bar{\rho} (p^2)^{-3/2} \rho d\tau$$

What follows is one of a number of ways in which the integral can be evaluated:

[Note: Components in \hat{a}_2 and \hat{a}_3 directions will cancel because of symmetry so it is necessary only to be concerned with the \hat{a}_1 direction]

Force on a differential element

$$\hat{a}_1 \cdot d\vec{F} = -\frac{Gm' dm \cos \theta}{D^2}$$

So

$$\hat{a}_1 \cdot \vec{F} = -Gm' \int \underbrace{\rho dt}_{dm} \cos \theta$$

Differential elements (rings)

$$\begin{aligned} d\tau_1 &= [r d(\phi - \theta)] [r \sin(\phi - \theta) d\psi] \\ &= \left[\frac{D_1 d\theta}{\cos \phi} \right] [D_1 \sin \theta d\psi] \\ &= \sec \phi D_1^2 \sin \theta d\theta d\psi \end{aligned}$$

$$\begin{aligned} d\tau_2 &= [r d(\phi + \theta)] [r \sin(\phi + \theta) d\psi] \\ &= \left[\frac{D_2 d\theta}{\cos \phi} \right] [D_2 \sin \theta d\psi] \\ &= \sec \phi D_2^2 \sin \theta d\theta d\psi \end{aligned}$$

$$\hat{a}_1 \cdot \bar{F} = -Gm' \int_{\psi=0}^{2\pi} \int_{\theta=0}^{\sin^{-1} \frac{r}{R}} \left[\frac{\sec \phi \rho D_1^2 \sin \theta d\theta d\psi}{D_1^2} + \frac{\sec \phi \rho D_2^2 \sin \theta d\theta d\psi}{D_2^2} \right] \cos \theta$$

$$\hat{a}_1 \cdot \bar{F} = -4\pi Gm' \rho \int_{\theta=0}^{\sin^{-1} \frac{r}{R}} \sec \phi \sin \theta \cos \theta d\theta$$

Change variable of integration to ϕ

$$R \sin \theta = r \sin \phi$$

$$R \cos \theta d\theta = r \cos \phi d\phi$$

$$\hat{a}_1 \cdot \vec{F} = -4\pi G m' \rho \int_{\phi=0}^{\pi/2} \sec \phi \left(\frac{r}{R} \sin \phi \right) \frac{r}{R} \cos \phi d\phi$$

$$= -4\pi G m' \rho \int_{\phi=0}^{\pi/2} \left(\frac{r}{R} \right)^2 \sin \phi d\phi$$

$$= -4\pi G m' \rho \frac{r^2}{R^2} (-\cos \phi)_0^{\pi/2}$$

$$= -\frac{G m'}{R^2} \rho 4\pi r^2 \quad \text{but } 4\pi r^2 = \text{area of a thin spherical shell}$$

$$\text{So } m = \rho 4\pi r^2$$

$$\boxed{\vec{F} = -\frac{G m' m \hat{a}_1}{R^2}} \quad \leftarrow \text{centrobaric}$$

A sphere is a collection of thin spherical shells.
It is also centrobaric.