

Investigation: Axisymmetric Body in Circular Orbit

EOM: Particular Solution (motion of interest)

Nominal motion to be investigated MUST be a solution to the **nonlinear** differential equations

some time history for dep vars

*nonlinear soln $\rightarrow \omega$'s, ϵ 's
as func of time ???*

Easiest to obtain (and to investigate) a particular solution when the dependent variables are **constants**

\Rightarrow To determine a particular solution, first consider the possibility that a constant solution even exists

$$\omega_j = \text{const.} \quad ; \quad \epsilon_j = \text{const.}$$

does this exist

yes if we get help.

not same as torque-free

S

Consider the following motion: symmetry axis remains normal to the orbit

$$\frac{N}{\omega} \hat{b} = \omega_3 \hat{a}_3 = \omega_3 \hat{b}_3 \quad (\omega_1 = \omega_2 = 0, \quad \underbrace{\varepsilon_i = \varepsilon_{i0}}_{??})$$

↑
const.

Check differential equations to see if such a motion can exist
(Remove zero ω terms first)

$$\dot{\omega}_3 = 0 \quad \rightarrow \omega_3 = \omega_{3_0} = \text{constant} \quad \checkmark$$

$$\dot{\omega}_1 = -s\omega_2 + \left(1 - \frac{J}{I}\right) \left[\cancel{\omega_2\omega_3} - 12\Omega^2 (\varepsilon_1\varepsilon_2 - \varepsilon_3\varepsilon_4)(\varepsilon_3\varepsilon_1 + \varepsilon_2\varepsilon_4) \right]$$

$$\dot{\omega}_2 = s\omega_1 - \left(1 - \frac{J}{I}\right) \left[\cancel{\omega_1\omega_3} - 6\Omega^2 (\varepsilon_3\varepsilon_1 + \varepsilon_2\varepsilon_4)(1 - 2\varepsilon_2^2 - 2\varepsilon_3^2) \right]$$

$$2\dot{\varepsilon}_1 = \varepsilon_2(\omega_3 - s + \Omega) - \cancel{\varepsilon_3\omega_2} + \cancel{\varepsilon_4\omega_1}$$

$$2\dot{\varepsilon}_2 = \varepsilon_3\cancel{\omega_1} + \cancel{\varepsilon_4\omega_2} - \varepsilon_1(\omega_3 - s + \Omega)$$

$$2\dot{\varepsilon}_3 = \varepsilon_4(\omega_3 - s - \Omega) + \cancel{\varepsilon_1\omega_2} - \cancel{\varepsilon_2\omega_1}$$

$$2\dot{\varepsilon}_4 = -\cancel{\varepsilon_1\omega_1} - \cancel{\varepsilon_2\omega_2} - \varepsilon_3(\omega_3 - s - \Omega)$$

start with these

if soln constant then ALL 1st deriv must equal 0

What ε equations are left?

$$2\dot{\varepsilon}_1 = \varepsilon_2(\omega_3 - s + \Omega)$$

what constant ε

$$2\dot{\varepsilon}_1 = \varepsilon_2(\omega_3 - s + \Omega)$$

$$2\dot{\varepsilon}_2 = -\varepsilon_1(\omega_3 - s + \Omega)$$

$$2\dot{\varepsilon}_3 = \varepsilon_4(\omega_3 - s - \Omega)$$

$$2\dot{\varepsilon}_4 = -\varepsilon_3(\omega_3 - s - \Omega)$$

what constant Σ

be to make
derivative

To obtain a "constant" solution, all

$$\dot{\Sigma} = 0, \quad \dot{\omega} = 0$$

Either ALL $\varepsilon_i = 0$

← not possible cuz does not
satisfy constraint $\Sigma_1^2 + \Sigma_2^2 + \Sigma_3^2 + \Sigma_4^2 = 1$

OR

$\Sigma_3 = \Sigma_4 = 0$ $\Sigma_1 = \Sigma_2 = 0$

some $\varepsilon_i = 0$ AND	$(\omega_{3_0} - s + \Omega) = 0$	or	$(\omega_{3_0} - s - \Omega) = 0$
	option 2		option 1

Option #1

$$\varepsilon_1 = \varepsilon_2 = 0$$

$$(\omega_{3_0} - s - \Omega) = 0$$

$$\rightarrow \text{true if } s = \omega_{3_0} - \Omega$$

What does this mean for the values of ε_i ?

$$\frac{N}{\omega} B = \frac{N}{\omega} A + \frac{A}{\omega} C + \frac{C}{\omega} B$$

$$\begin{array}{ccccc} \uparrow & & \uparrow & & \uparrow \\ \omega_{3_0} \hat{a}_3 = -\Omega \hat{e}_3 & & \frac{A}{\omega} C & & \frac{C}{\omega} B \end{array}$$

$$(\omega_{3_0} = \Omega)$$

assuming
 $\hat{e}_3 = \hat{p}_3 = \hat{a}_3$

\Rightarrow if $s = \omega_{3_0} - \Omega$ then

$$\frac{A}{\omega} C = 0 \quad \text{or} \quad \hat{C} = \hat{a}$$

$$\rightarrow A \cdot A \cdot A \cdot A \quad A \cdot C \quad A$$

\Rightarrow if $s = \omega_{3_0} - \Omega$ then $\bar{\omega}^u = 0$ or $\bar{c} = a$

$\Rightarrow A_{\varepsilon^C}^C = \hat{\lambda} \sin \frac{\theta}{2} \quad A_{\varepsilon^C}^C = \cos \frac{\theta}{2}$

$$\varepsilon_1 = \varepsilon_2 = \varepsilon_3 = 0 \quad \varepsilon_4 = 1$$

Option #2

$(\omega_{3_0} - s + \Omega) = 0 \rightarrow$ true if $s = \omega_{3_0} + \Omega$

What does this mean for the values of ε_i ?

$${}^N \bar{\omega}^B = {}^N \bar{\omega}^A + {}^A \bar{\omega}^C + {}^C \bar{\omega}^B$$

$\Rightarrow \omega_{3_0} \hat{\lambda}_3 = \Omega \hat{a}_3 + \underbrace{{}^A \bar{\omega}^C}_{\substack{\uparrow \\ \hat{\varepsilon}_3}} + s \hat{c}_3$

$\omega_{3_0} + \Omega$

${}^A \bar{\omega}^C = -2\Omega \hat{a}_3$

differential equations for ε_i

$$2\dot{\varepsilon}_1 = 0$$

$$2\dot{\varepsilon}_2 = 0$$

$$2\dot{\varepsilon}_3 = \varepsilon_4 (-2\Omega)$$

$$2\dot{\varepsilon}_4 = -\varepsilon_3 (-2\Omega)$$

ε 's not const. } can still be a particular solution

Certainly an acceptable nominal solution BUT the dependent variables are not constant!

$$\dot{\varepsilon}_3 + \Omega \varepsilon_3 = 0 \rightarrow \begin{aligned} \varepsilon_3 &= \sin \frac{\Omega t}{2} \\ \varepsilon_4 &= \cos \frac{\Omega t}{2} \end{aligned}$$

So.....use option #1

Motion of interest:

$$s = \omega_{3_0} - \Omega$$

particular solution

Use this particular solution for our investigation

$$\zeta = \omega_{30} - \Omega$$

$$\omega_1 = \omega_2 = 0 \quad \omega_3 = \omega_{30}$$

$$\varepsilon_1 = \varepsilon_2 = \varepsilon_3 = 0 \quad \varepsilon_4 = 1$$

Use this particular solution for our investigation

Check final DE to be sure

$$\dot{\omega}_3 = 0 \quad \rightarrow \omega_3 = \omega_{30} = \text{constant}$$

$$\dot{\omega}_1 = -s\omega_2 + \left(1 - \frac{J}{I}\right) \left[\omega_2\omega_3 - 12\Omega^2 (\varepsilon_1\varepsilon_2 - \varepsilon_3\varepsilon_4)(\varepsilon_3\varepsilon_1 + \varepsilon_2\varepsilon_4) \right]$$

$$\dot{\omega}_2 = s\omega_1 - \left(1 - \frac{J}{I}\right) \left[\omega_1\omega_3 - 6\Omega^2 (\varepsilon_3\varepsilon_1 + \varepsilon_2\varepsilon_4)(1 - 2\varepsilon_2^2 - 2\varepsilon_3^2) \right]$$

$$2\dot{\varepsilon}_1 = \varepsilon_2(\omega_3 - s + \Omega) - \varepsilon_3\omega_2 + \varepsilon_4\omega_1$$

$$2\dot{\varepsilon}_2 = \varepsilon_3\omega_1 + \varepsilon_4\omega_2 - \varepsilon_1(\omega_3 - s + \Omega)$$

$$2\dot{\varepsilon}_3 = \varepsilon_4(\omega_3 - s - \Omega) + \varepsilon_1\omega_2 - \varepsilon_2\omega_1$$

$$2\dot{\varepsilon}_4 = -\varepsilon_1\omega_1 - \varepsilon_2\omega_2 - \varepsilon_3(\omega_3 - s - \Omega)$$