



COLLEGE OF ENGINEERING
SCHOOL OF AERONAUTICAL AND ASTRONAUTICAL ENGINEERING

AAE 567: INTRODUCTION TO APPLIED STOCHASTIC PROCESSES

HW4

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Problem 1

Let \mathbf{x} be a uniform random variable over the interval $[0,4]$. Moreover, \mathbf{v} is a uniform random variable over the interval $[-1,1]$. Assume that \mathbf{x} and \mathbf{v} are independent. Let \mathbf{y} be the random variable given by $\mathbf{y} = \mathbf{x} + \mathbf{v}$.

Let \mathcal{H} be the space spanned by $\{1, \mathbf{y}, \mathbf{y}^2, \mathbf{y}^3\}$. Then compute

$$P_{\mathcal{H}}\mathbf{x} = a + b\mathbf{y} + c\mathbf{y}^2 + d\mathbf{y}^3 \quad \text{and} \quad d_4^2 = E|\mathbf{x} - P_{\mathcal{H}}\mathbf{x}|^2 \quad .$$

Compute the conditional expectation

$$\hat{g}(y) = E(\mathbf{x}|\mathbf{y} = y) \quad .$$

Plot $\hat{g}(y)$ and its approximation $a + by + cy^2 + dy^3$ on the same graph over the interval $[-1,5]$.

Solution:

For convenience the heavy computations are done using MATLAB. (The code will be at the end of this problem.) Let

$$g = \begin{bmatrix} 1 \\ y \\ y^2 \\ y^3 \end{bmatrix}$$

$$f = \mathbf{x} \quad .$$

Also since \mathbf{x} and \mathbf{v} are uniform distributions

$$\begin{aligned} E\mathbf{x} &= 2 \\ E\mathbf{v} &= 0 \\ f_{\mathbf{x}(x)} &= \frac{1}{4} \\ f_{\mathbf{v}(v)} &= \frac{1}{2} \quad . \end{aligned}$$

Then

$$R_{fg} = R_{\mathbf{x}g} = Exg = Ex \begin{bmatrix} 1 & y & y^2 & y^3 \end{bmatrix} = \begin{bmatrix} Ex & Exy & Exy^2 & Exy^3 \end{bmatrix} .$$

Here

$$\begin{aligned} Exy &= Ex(x + v) = Ex^2 + Exv = Ex^2 + ExEv \\ &= Ex^2 \\ &= \int_{-\infty}^{\infty} x^2 f_{\mathbf{x}}(x) dx = \frac{1}{4} \int_0^4 x^2 dx \\ &= \frac{16}{3} \quad . \end{aligned}$$

Furthermore,

$$\begin{aligned}
Exy^2 &= Ex(x^2 + 2xv + v^2) = Ex^3 + 2Ex^2Ev + ExEv^2 \\
&= \int_{-\infty}^{\infty} x^3 f_{\mathbf{x}}(x) dx + 2 \int_{-\infty}^{\infty} v^2 f_{\mathbf{v}}(v) dv \\
&= \frac{1}{4} \int_0^4 x^3 dx + 2 \int_{-1}^1 v^2 dv \\
&= 16 + \frac{2}{3} = \frac{50}{3}
\end{aligned}$$

Similarly,

$$Exy^3 = \frac{1}{8} \int_{-1}^1 \int_0^4 x(x+v)^3 dx dv = 56.5333$$

Which gives

$$\therefore R_{fg} = \begin{bmatrix} 2 & 5.3333 & 16.6667 & 56.5333 \end{bmatrix}.$$

Next,

$$\begin{aligned}
R_g &= E g g^* = E \begin{bmatrix} 1 \\ y \\ y^2 \\ y^3 \end{bmatrix} \begin{bmatrix} 1 & y & y^2 & y^3 \end{bmatrix} = \begin{bmatrix} E1 & Ey & Ey^2 & Ey^3 \\ Ey & Ey^2 & Ey^3 & Ey^4 \\ Ey^2 & Ey^3 & Ey^4 & Ey^5 \\ Ey^3 & Ey^4 & Ey^5 & Ey^6 \end{bmatrix} \\
&= \begin{bmatrix} 1 & 2 & 5.6667 & 18 \\ 2 & 5.6667 & 18 & 62.0667 \\ 5.6667 & 18 & 62.0667 & 226 \\ 18 & 62.0667 & 226 & 857.2857 \end{bmatrix}.
\end{aligned}$$

Now the coefficients a, b, c , and d become

$$\begin{aligned}
\begin{bmatrix} a & b & c & d \end{bmatrix} &= R_{fg} R_g^{-1} \\
&= \begin{bmatrix} 2 & 5.3333 & 16.6667 & 56.5333 \end{bmatrix} \begin{bmatrix} 1 & 2 & 5.6667 & 18 \\ 2 & 5.6667 & 18 & 62.0667 \\ 5.6667 & 18 & 62.0667 & 226 \\ 18 & 62.0667 & 226 & 857.2857 \end{bmatrix}^{-1} \\
&= \begin{bmatrix} 0.4320 & 0.4286 & 0.2666 & -0.0444 \end{bmatrix}.
\end{aligned}$$

Hence,

$$P_{\mathcal{H}} \mathbf{x} = 0.4320 + 0.4286y + 0.2666y^2 - 0.0444y^3.$$

Then the error becomes

$$\begin{aligned}
d_4^2 &= R_{\mathbf{x}} - R_{fg} R_g^{-1} R_{gf} \\
&= 0.2525
\end{aligned}$$

Thus,

$$\therefore d_4 = 0.5024 \quad .$$

Now we will compute the conditional expectation

$$\hat{g}(y) = E(\mathbf{x}|\mathbf{y} = y) \quad .$$

Which is equivalent to

$$\hat{g}(y) = \int_{-\infty}^{\infty} x f_{\mathbf{x}|\mathbf{y}}(x|y) dx = \int_{-\infty}^{\infty} x \frac{f_{\mathbf{x},\mathbf{y}}(x, y)}{f_{\mathbf{y}}(y)} dx \quad .$$

If the two random variables are statistically independent we know that

$$\begin{aligned} f_{\mathbf{x},\mathbf{y}}(x, y) &= f_{\mathbf{x}}(x) f_{\mathbf{y}}(y - x) \\ f_{\mathbf{y}}(y) &= \int_{-\infty}^{\infty} f_{\mathbf{x}}(x) f_{\mathbf{y}}(y - x) dx \end{aligned}$$

and if the range is defined to be $y \in [-1, 5]$, we can solve the first one to be

$$\begin{aligned} f_{\mathbf{x},\mathbf{y}}(x, y) &= f_{\mathbf{x},\mathbf{v}}(x, v) \cdot \left| \det(\nabla(x, x + v)) \right|^{-1} \\ &= \frac{1}{4} \times \frac{1}{2} \left| \begin{array}{cc} 1 & 0 \\ 1 & 1 \end{array} \right|^{-1} \\ &= \frac{1}{8} \end{aligned}$$

Thus,

$$f_{\mathbf{x},\mathbf{y}}(x, y) = \frac{1}{8} \quad \text{for } -1 \leq y \leq 5 \quad .$$

Now for the marginal probability density function we use the range relations of

$$\begin{aligned} 0 &\leq x \leq 4 \\ -1 &\leq y - x \leq 1 \end{aligned}$$

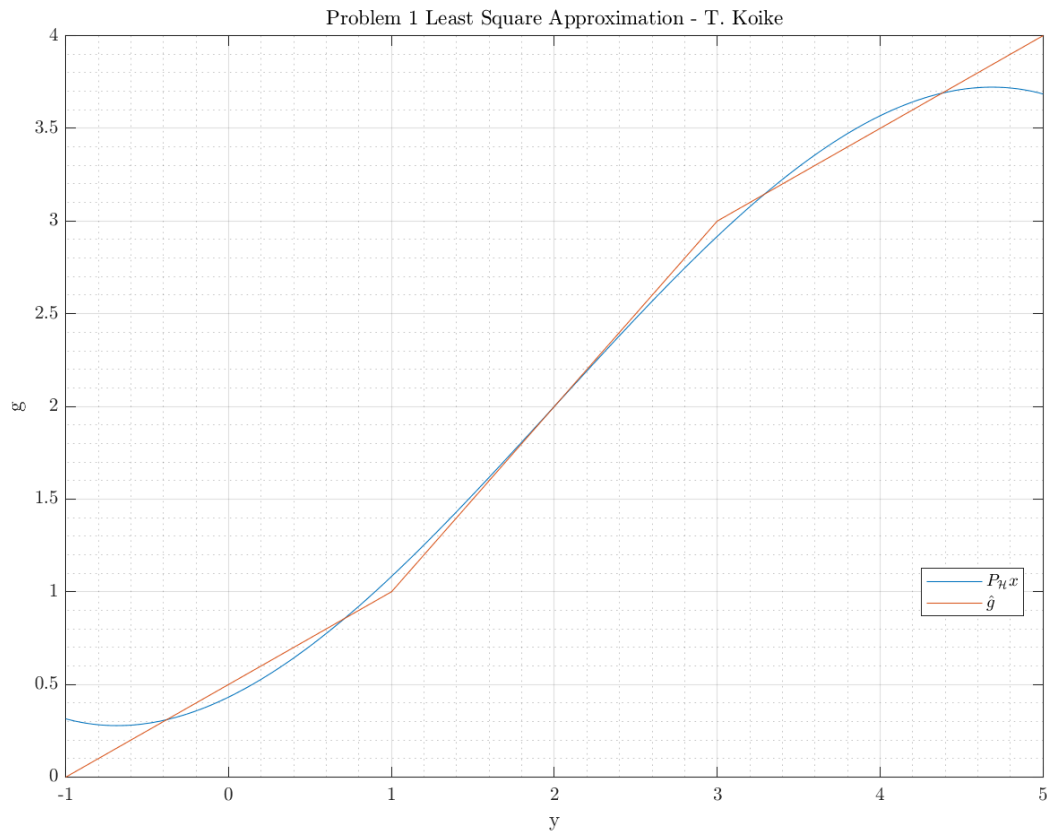
and we obtain

$$f_{\mathbf{y}}(y) = \begin{cases} \frac{1}{8} \int_0^{y+1} dx = \frac{y+1}{8} & \text{if } -1 \leq y \leq 1 \\ \frac{1}{8} \int_{y-1}^{y+1} dx = \frac{1}{4} & \text{if } 1 \leq y \leq 3 \\ \frac{1}{8} \int_{y-1}^4 dx = \frac{5-y}{8} & \text{if } 3 \leq y \leq 5 \end{cases}$$

Therefore

$$\hat{g}(y) = \begin{cases} \int_0^{y+1} x \left(\frac{1}{8}\right) \left(\frac{y+1}{8}\right)^{-1} dx = \frac{1}{2}y + \frac{1}{2} & \text{if } -1 \leq y \leq 1 \\ \int_{y-1}^{y+1} x \left(\frac{1}{8}\right) \left(\frac{1}{4}\right)^{-1} dx = y & \text{if } 1 \leq y \leq 3 \\ \int_{y-1}^4 x \left(\frac{1}{8}\right) \left(\frac{5-y}{8}\right)^{-1} dx = \frac{1}{2}y + \frac{3}{2} & \text{if } 3 \leq y \leq 5 \end{cases}$$

Finally we plot our results,



and the MATLAB code is as follows.

```

1 %% AAE 567 HW4 Problem1
2
3 % Housekeeping commands
4 clear all; close all; clc;
5 set(groot, 'defaulttextinterpreter','latex');
6 set(groot, 'defaultAxesTickLabelInterpreter','latex');
7 set(groot, 'defaultLegendInterpreter','latex');
8 outdir = pwd + "\output\hw4";
9 mdir = pwd + "\mfiles\hw4";
10 %%
11 % Define expectations
12 syms x v y g
13 y = x + v;
14 g = [1; y; y^2; y^3];
15 EX = @(A) int(1/4 * x.^A, 0, 4);

```

```

16 EV = @(A) int(1/2 * v.^A, -1, 1);
17 EY = @(A) 1/8 * int(int(y.^A, x, 0, 4), -1, 1);
18 EXY = @(A,B) 1/8 * int(int(x.^A * y.^B, x, 0, 4), -1, 1);
19
20 % P_Hx
21 Rfg = EXY(1, [0 1 2 3]);
22 A = [0:3; 1:4; 2:5; 3:6];
23 Rg = EY(A);
24 coef = Rfg * inv(Rg);
25 coef = eval(coef);
26 % Error d4
27 d4sq = EX(2) - Rfg*inv(Rg)*Rfg';
28 d4 = sqrt(d4sq);
29 %%
30 % Plotting
31 t = -1:0.01:5;
32 % ghat piecewise
33 t1 = t(-1 <= t & t < 1);
34 t2 = t(1 <= t & t < 3);
35 t3 = t(3 <= t & t <= 5);
36 ghat = [0.5*t1 + 0.5, t2, 0.5*t3 + 1.5];
37
38 Phx = coef(1) + coef(2)*t + coef(3)*t.^2 + coef(4)*t.^3;
39
40 fig = figure("Renderer","painters",'Position',[60 60 900 650]);
41 plot(t, Phx)
42 grid on; grid minor; box on; hold on;
43 plot(t, ghat)
44 hold off;
45 title('Problem 1 Least Square Approximation — T. Koike')
46 legend('$P_{\mathcal{H}}x$', '$\hat{g}$', "Location","best")
47 xlabel('y')
48 ylabel('g')
49 saveas(fig, fullfile(outdir, 'p1_lsqr_plot.png'));
50 %%
51 % Save file as .m
52 matlab.internal.liveeditor.openAndConvert('hw4_p1.mlx', ...
53     convertStringsToChars(fullfile(mdir, 'hw4_p1.m')));

```

Problem 2

Let \mathbf{x} and \mathbf{y} be two uniform random variables over the interval $[0,1]$. Let \mathbf{a} be the random variable defined by the area $\mathbf{a}=\mathbf{xy}$. Clearly, the area is $0 \leq \mathbf{a} \leq 1$. Our problem is given the area \mathbf{a} find the best estimate of $\hat{\mathbf{x}}$ of \mathbf{x} .

Let \mathcal{H} be the space spanned by $\{1, \mathbf{a}, \mathbf{a}^2, \mathbf{a}^3\}$. Then compute

$$P_{\mathcal{H}}\mathbf{x} = \alpha + \beta\mathbf{a} + \gamma\mathbf{a}^2 + \delta\mathbf{a}^3 \quad \text{and} \quad d_4^2 = E|\mathbf{x} - P_{\mathcal{H}}\mathbf{x}|^2 \quad .$$

Compute the conditional expectation

$$\hat{g}(a) = E(\mathbf{x}|\mathbf{a} = a) \quad \text{and} \quad d_{\infty}^2 = E|\mathbf{x} - \hat{g}(\mathbf{a})|^2 \quad .$$

Plot $\hat{g}(a)$ and its approximation $\alpha + \beta a + \gamma a^2 + \delta a^3$ on the same graph over the interval $[0,1]$. Is $d_{\infty} < d_4$? Explain why or why not.

Solution:

For convenience the heavy computations are done using MATLAB. (The code will be at the end of this problem.) Let

$$g = \begin{bmatrix} 1 \\ a \\ a^2 \\ a^3 \end{bmatrix}$$

$$f = \mathbf{x} \quad .$$

Also since \mathbf{x} and \mathbf{y} are uniform distributions

$$\begin{aligned} E\mathbf{x} &= 0.5 \\ E\mathbf{y} &= 0.5 \\ f_{\mathbf{x}(x)} &= 1 \\ f_{\mathbf{y}(y)} &= 1 \quad . \end{aligned}$$

Then

$$R_{fg} = R_{\mathbf{x}g} = E\mathbf{x}g = \begin{bmatrix} 1 & a & a^2 & a^3 \end{bmatrix} = \begin{bmatrix} E\mathbf{x} & E\mathbf{x}a & E\mathbf{x}a^2 & E\mathbf{x}a^3 \end{bmatrix} .$$

Here

$$\begin{aligned} E\mathbf{x}a &= E\mathbf{x}(xy) = E\mathbf{x}^2 E\mathbf{y} \\ &= \int_{-\infty}^{\infty} x^2 f_{\mathbf{x}}(x) dx = \int_0^1 x^2 dx \\ &= 1.6667 \quad . \end{aligned}$$

Furthermore,

$$\begin{aligned}
Exa^2 &= Ex(x^2y^2) = Ex^3Ey^2 \\
&= \left(\int_{-\infty}^{\infty} x^3 f_{\mathbf{x}}(x) dx \right) \left(\int_{-\infty}^{\infty} y^2 f_{\mathbf{y}}(y) dy \right) \\
&= \left(\int_0^1 x^3 dx \right) \left(\int_0^1 y^2 dy \right) \\
&= 0.0833
\end{aligned}$$

Similarly,

$$Exa^3 = \int_0^1 \int_0^1 x(xy)^3 dx dy = 0.5$$

Which gives

$$\therefore R_{fg} = \begin{bmatrix} 0.5 & 0.1667 & 0.0833 & 0.5 \end{bmatrix}.$$

Next,

$$\begin{aligned}
R_g = E g g^* &= E \begin{bmatrix} 1 \\ a \\ a^2 \\ a^3 \end{bmatrix} \begin{bmatrix} 1 & a & a^2 & a^3 \end{bmatrix} = \begin{bmatrix} E1 & Ea & Ea^2 & Ea^3 \\ Ea & Ea^2 & Ea^3 & Ea^4 \\ Ea^2 & Ea^3 & Ea^4 & Ea^5 \\ Ea^3 & Ea^4 & Ea^5 & Ea^6 \end{bmatrix} \\
&= \begin{bmatrix} 1 & 0.2500 & 0.1111 & 0.0625 \\ 0.2500 & 0.1111 & 0.0625 & 0.0400 \\ 0.1111 & 0.0625 & 0.0400 & 0.0278 \\ 0.0625 & 0.0400 & 0.0278 & 0.0204 \end{bmatrix}.
\end{aligned}$$

Now the coefficients α, β, γ , and δ become

$$\begin{aligned}
\begin{bmatrix} \alpha & \beta & \gamma & \delta \end{bmatrix} &= R_{fg} R_g^{-1} \\
&= \begin{bmatrix} 0.5 & 0.1667 & 0.0833 & 0.5 \end{bmatrix} \begin{bmatrix} 1 & 0.2500 & 0.1111 & 0.0625 \\ 0.2500 & 0.1111 & 0.0625 & 0.0400 \\ 0.1111 & 0.0625 & 0.0400 & 0.0278 \\ 0.0625 & 0.0400 & 0.0278 & 0.0204 \end{bmatrix}^{-1} \\
&= \begin{bmatrix} 0.2140 & 1.8416 & -2.3412 & 1.3717 \end{bmatrix}.
\end{aligned}$$

Hence,

$$P_{\mathcal{H}} \mathbf{x} = 0.2140 + 1.8416a - 2.3412a^2 - 1.3717a^3 \quad .$$

Then the error becomes

$$\begin{aligned}
d_4^2 &= R_{\mathbf{x}} - R_{fg} R_g^{-1} R_{gf} \\
&= 0.0459
\end{aligned}$$

Thus,

$$\therefore d_4 = 0.2143 \quad .$$

Now we will compute the conditional expectation

$$\hat{g}(y) = E(\mathbf{x}|\mathbf{y} = y) \quad .$$

Which is equivalent to

$$\hat{g}(a) = \int_{-\infty}^{\infty} x f_{\mathbf{x}|\mathbf{a}}(x|a) dx = \int_{-\infty}^{\infty} x \frac{f_{\mathbf{x},\mathbf{a}}(x, a)}{f_{\mathbf{a}}(a)} dx \quad .$$

and if the range is defined to be $y \in [0, 1]$, we can solve the first one to be

$$\begin{aligned} f_{\mathbf{x},\mathbf{a}}(x, a) &= f_{\mathbf{x},\mathbf{y}}(x, y) \cdot \left| \det(\nabla(x, xy)) \right|^{-1} \\ &= \left| \begin{array}{cc} 1 & 0 \\ y & x \end{array} \right|^{-1} \\ &= \frac{1}{x} \end{aligned}$$

Thus,

$$f_{\mathbf{x},\mathbf{a}}(x, a) = \frac{1}{x} \quad \text{for } 0 \leq a \leq 1 \quad .$$

Now for the marginal probability density function we use the range relations of

$$\begin{aligned} 0 &\leq xy \leq 1 \\ 0 &\leq y \leq 1 \\ 0 &\leq x \leq 1 \end{aligned}$$

which leads to

$$0 \leq a \leq x \leq 1$$

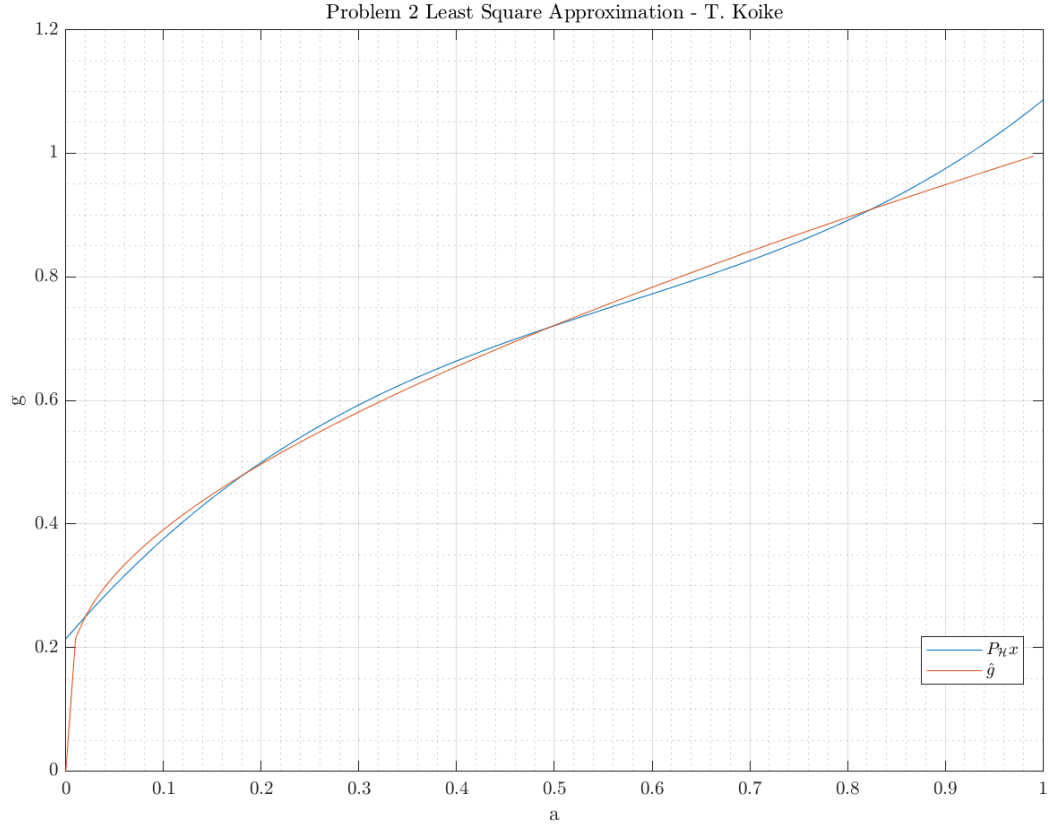
and we obtain

$$\begin{aligned} f_{\mathbf{a}}(a) &= \int_a^1 \frac{1}{x} dx \\ &= -\ln a \end{aligned}$$

Therefore

$$\begin{aligned} \hat{g}(y) &= \int_a^1 x \frac{1/x}{-\ln a} dx \\ &= \frac{1}{-\ln a} \left\{ x \right\}_a^1 \\ &= \frac{a-1}{\ln a} \quad . \end{aligned}$$

Finally we plot our results,



The error of $\hat{g}(y)$, which is also denoted as d_∞ is equal to 0. This is because the $\hat{g}(y)$ is the exact value of the conditional expectation of products for 2 uniform distributions. This can be achieved by having \mathcal{H} span infinite order which allows the rough estimation converge to $\hat{g}(t)$. This also means that $d_\infty < d_4$.

MATLAB code:

```
1 %% AAE 567 HW4 Problem2
2
3 % Housekeeping commands
4 clear all; close all; clc;
5 set(groot, 'defaulttextinterpreter','latex');
6 set(groot, 'defaultAxesTickLabelInterpreter','latex');
7 set(groot, 'defaultLegendInterpreter','latex');
8 outdir = pwd + "\output\hw4";
9 mdir = pwd + "\mfiles\hw4";
10 %%
11 m = 3;
12 % Define expectations
13 syms x v y g
14 y = x*v;
15 g = [];
16 for n = 0:m
17     g = [g; y^n];
18 end
19 %g = [1; y; y^2; y^3; y^4; y^5; y^6];
20 xl = 0; xu = 1; % range of x
21 vl = 0; vu = 1; % range of v
22 EX = @(A) int(x.^A, xl, xu);
23 EV = @(A) int(v.^A, vl, vu);
24 EY = @(A) int(int(y.^A, x, xl, xu), vl, vu);
25 EXY = @(A,B) int(int(x.^A * y.^B, x, xl, xu), vl, vu);
26
27 % P_Hx
28 Rfg = EXY(1, 0:m);
29 %%
30 A = [];
31 for n = 0:m
32     A = [A; n:n+m];
33 end
34 Rg = EY(A);
35 coef = Rfg * inv(Rg);
36 coef = eval(coef);
37 % Error d4
38 d4sq = EX(2) - Rfg*inv(Rg)*Rfg';
39 d4 = sqrt(d4sq);
40 %%
41 % Plotting
42 t = 0:0.01:1;
```

```

43 % ghat
44 Phx = 0;
45 for n = 1:length(coef)
46     Phx = Phx + coef(n)*t.^(n-1);
47 end
48
49 fig = figure("Renderer","painters",'Position',[60 60 900 650]);
50 plot(t, Phx)
51 grid on; grid minor; box on; hold on;
52 plot(t, (t-1)./log(t))
53 hold off;
54 title('Problem 2 Least Square Approximation — T. Koike')
55 legend('$P_{\mathcal{H}}x$', '$\hat{g}$', "Location","best")
56 xlabel('a')
57 ylabel('g')
58 saveas(fig, fullfile(outdir, 'p2_lsqr_plot.png'));
59 %%
60 % Save file as .m
61 matlab.internal.liveeditor.openAndConvert('hw4_p2.mlx', ...
62     convertStringsToChars(fullfile(mdir, 'hw4_p2.m')));

```

Problem 3

[Problem 1 from the Notes p.34.] Let \mathbf{x} be a uniform random variable over the interval $[0,10]$ and \mathbf{v} a uniform random variable over $[0,4]$. Moreover, assume \mathbf{x} and \mathbf{v} are independent random variables. Now let \mathbf{y} be the random variable defined by $\mathbf{y} = \mathbf{x} + \mathbf{v}$. Let \mathcal{H}_3 be the subspace spanned by $\{1, \mathbf{y}, \mathbf{y}^2\}$. Then compute the optimal estimate $\hat{\mathbf{x}} = P_{\mathcal{H}_3} \mathbf{x}$ and the error in estimation $E(\mathbf{x} - \hat{\mathbf{x}})^2$. Notice that in this case, $\mathbf{g} = [1, \mathbf{y}, \mathbf{y}^2]^tr$. Compute the conditional expectation $E(\mathbf{x}|\mathbf{y})$ and compare your answer $P_{\mathcal{H}_3} \mathbf{x}$ to the solution computed by the conditional expectation.

Hint: According to Lemma 12.3.1 in the Appendix, the joint probability density function $f_{\mathbf{x},\mathbf{y}}(x, y) = f_{\mathbf{x}}(x)f_{\mathbf{v}}(y - x)$. (The notation $f_{\mathbf{x}}(x)$ is the density function for the random variable \mathbf{x} evaluated at the point x on the real line.) Moreover, the density $f_{\mathbf{y}}$ for the random variable \mathbf{y} is obtained by convolving $f_{\mathbf{x}}$ with $f_{\mathbf{v}}$. In other words, show that

$$\begin{aligned} f_{\mathbf{y}}(y) &= y/40 & \text{if } 0 \leq y \leq 4 \\ &= 1/10 & \text{if } 4 \leq y \leq 10 \\ &= (14 - y)/40 & \text{if } 10 \leq y \leq 14 \end{aligned}$$

Verify that the conditional density $f_{\mathbf{x}|\mathbf{y}}$ is given by

$$\begin{aligned} f_{\mathbf{x}|\mathbf{y}} &= 1/y & \text{if } 0 \leq x \leq y & \text{ and } 0 \leq y \leq 4 \\ &= 1/4 & \text{if } y - 4 \leq x \leq y & \text{ and } 4 \leq y \leq 10 \\ &= 1/(14 - y) & \text{if } y - 4 \leq x \leq 10 & \text{ and } 10 \leq y \leq 14 \end{aligned}$$

Finally, show that the conditional expectation is given by

$$\begin{aligned} E(\mathbf{x}|\mathbf{y} = y) &= y/2 & \text{if } 0 \leq y \leq 4 \\ &= y - 2 & \text{if } 4 \leq y \leq 10 \\ &= (y + 6)/2 & \text{if } 10 \leq y \leq 14 \end{aligned}$$

Recall that $P_{\mathcal{H}_1} \mathbf{x} = 130\mathbf{y}/176$ was the best estimate of \mathbf{x} corresponding to the one dimensional subspace \mathcal{H}_1 spanned by $\{\mathbf{y}\}$, and $P_{\mathcal{H}_2} \mathbf{x} = -30/29 + 25\mathbf{y}/29$ was the best estimate of \mathbf{x} corresponding to the two dimensional subspace \mathcal{H}_2 spanned by $\{1, \mathbf{y}\}$; see Section 2.2.1. Plot $130\mathbf{y}/176$ and $-30/29 + 25\mathbf{y}/29$ and the conditional expectation $E(\mathbf{x}|\mathbf{y} = y)$ along with your estimate $P_{\mathcal{H}_3} \mathbf{x}$ on the same graph. Finally, comment on the resulting graph.

Solution:

For convenience the heavy computations are done using MATLAB. (The code will be at the end of this problem.) Let

$$g = \begin{bmatrix} 1 \\ y \\ y^2 \end{bmatrix}$$

$$f = \mathbf{x} \quad .$$

Also since \mathbf{x} and \mathbf{v} are uniform distributions

$$\begin{aligned} E\mathbf{x} &= 5 \\ E\mathbf{v} &= 2 \\ f_{\mathbf{x}(x)} &= \frac{1}{10} \\ f_{\mathbf{v}(v)} &= \frac{1}{4} \quad . \end{aligned}$$

Then

$$R_{fg} = R_{\mathbf{x}g} = Exg = Ex \begin{bmatrix} 1 & y & y^2 \end{bmatrix} = \begin{bmatrix} Ex & Exy & Exy^2 \end{bmatrix} .$$

Here

$$\begin{aligned} Exy &= Ex(x + v) = Ex^2 + Exv = Ex^2 + ExEv \\ &= \int_{-\infty}^{\infty} x^2 f_{\mathbf{x}}(x) dx + 10 = \frac{1}{10} \int_0^{10} x^2 dx + 10 \\ &= 43.3333 \quad . \end{aligned}$$

Furthermore,

$$\begin{aligned} Exy^2 &= Ex(x^2 + 2xv + v^2) = Ex^3 + 2Ex^2Ev + ExEv^2 \\ &= \int_{-\infty}^{\infty} x^3 f_{\mathbf{x}}(x) dx + \frac{200}{3} \times 2 + 5 \int_{-\infty}^{\infty} v^2 f_{\mathbf{v}}(v) dv \\ &= \frac{1}{10} \int_0^4 x^3 dx + \frac{400}{3} + 5 \int_0^4 v^2 dv \\ &= 410 \end{aligned}$$

Which gives

$$\therefore R_{fg} = \begin{bmatrix} 5 & 43.3333 & 410 \end{bmatrix} .$$

Next,

$$\begin{aligned} R_g &= E g g^* = E \begin{bmatrix} 1 \\ y \\ y^2 \end{bmatrix} \begin{bmatrix} 1 & y & y^2 \end{bmatrix} = \begin{bmatrix} E1 & Ey & Ey^2 \\ Ey & Ey^2 & Ey^3 \\ Ey^2 & Ey^3 & Ey^4 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 7 & 58.6667 \\ 7 & 58.6667 & 546 \\ 58.6667 & 546 & 5.4379\text{e}+03 \end{bmatrix} . \end{aligned}$$

Now the coefficients a, b , and c become

$$\begin{aligned} \begin{bmatrix} a & b & c \end{bmatrix} &= R_{fg} R_g^{-1} \\ &= \begin{bmatrix} 5 & 43.3333 & 410 \end{bmatrix} \begin{bmatrix} 1 & 7 & 58.6667 \\ 7 & 58.6667 & 546 \\ 58.6667 & 546 & 5.4379\text{e}+03 \end{bmatrix}^{-1} \\ &= \begin{bmatrix} -1.0345 & 0.8621 & 0 \end{bmatrix}. \end{aligned}$$

Hence,

$$P_{\mathcal{H}}\mathbf{x} = -1.0345 + 0.8621y \quad .$$

Then the error becomes

$$\begin{aligned} d_4^2 &= R_{\mathbf{x}} - R_{fg} R_g^{-1} R_{gf} \\ &= 1.1494 \end{aligned}$$

Thus,

$$\therefore d_4 = 1.0721 \quad .$$

Now we will compute the conditional expectation

$$\hat{g}(y) = E(\mathbf{x}|\mathbf{y} = y) \quad .$$

Which is equivalent to

$$\hat{g}(y) = \int_{-\infty}^{\infty} x f_{\mathbf{x}|\mathbf{y}}(x|y) dx = \int_{-\infty}^{\infty} x \frac{f_{\mathbf{x},\mathbf{y}}(x, y)}{f_{\mathbf{y}}(y)} dx \quad .$$

If the two random variables are statistically independent we know that

$$\begin{aligned} f_{\mathbf{x},\mathbf{y}}(x, y) &= f_{\mathbf{x}}(x) f_{\mathbf{y}}(y - x) \\ f_{\mathbf{y}}(y) &= \int_{-\infty}^{\infty} f_{\mathbf{x}}(x) f_{\mathbf{y}}(y - x) dx \end{aligned}$$

and if the range is defined to be $y \in [0, 14]$, we can solve the first one to be

$$\begin{aligned} f_{\mathbf{x},\mathbf{y}}(x, y) &= f_{\mathbf{x},\mathbf{v}}(x, v) \cdot \left| \det \left(\nabla(x, x + v) \right) \right|^{-1} \\ &= \frac{1}{10} \times \frac{1}{4} \left| \begin{array}{cc} 1 & 0 \\ 1 & 1 \end{array} \right|^{-1} \\ &= \frac{1}{40} \end{aligned}$$

Thus,

$$f_{\mathbf{x},\mathbf{y}}(x, y) = \frac{1}{40} \quad \text{for } 0 \leq y \leq 14 \quad .$$

Now for the marginal probability density function we use the range relations of

$$\begin{aligned} 0 &\leq x \leq 10 \\ 0 &\leq y - x \leq 4 \end{aligned}$$

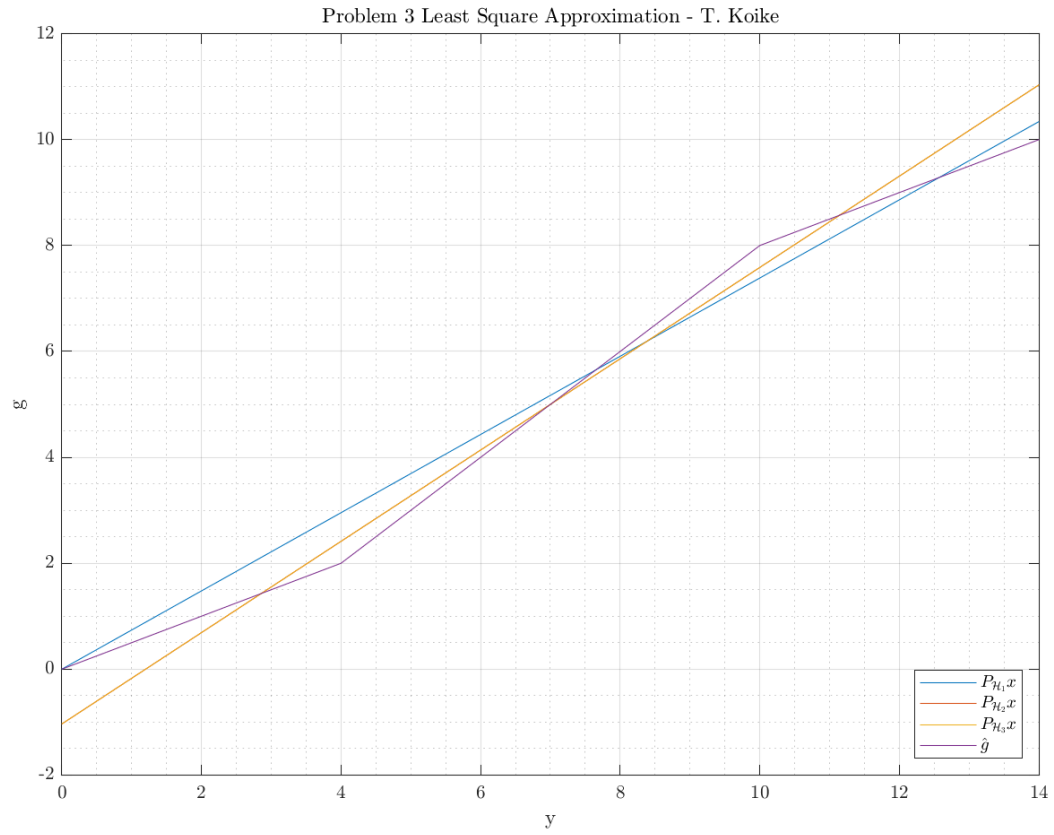
and we obtain

$$f_{\mathbf{y}}(y) = \begin{cases} \frac{1}{40} \int_0^y dx = \frac{y}{40} & \text{if } 0 \leq y \leq 4 \\ \frac{1}{40} \int_{y-4}^y dx = \frac{1}{10} & \text{if } 4 \leq y \leq 10 \\ \frac{1}{40} \int_{y-4}^{10} dx = \frac{14-y}{40} & \text{if } 10 \leq y \leq 14 \end{cases}$$

Therefore

$$\hat{g}(y) = \begin{cases} \int_0^y x \left(\frac{1}{40}\right) \left(\frac{y}{40}\right)^{-1} dx = \frac{y}{2} & \text{if } 0 \leq y \leq 4 \\ \int_{y-4}^y x \left(\frac{1}{40}\right) \left(\frac{1}{10}\right)^{-1} dx = y & \text{if } 4 \leq y \leq 10 \\ \int_{y-4}^{10} x \left(\frac{1}{40}\right) \left(\frac{14-y}{40}\right)^{-1} dx = \frac{1}{2}y + 3 & \text{if } 10 \leq y \leq 14 \end{cases}$$

Finally we plot our results,



From the graph we can see that for \mathcal{H}_2 and \mathcal{H}_3 there is no difference in the approximation. Thus, to achieve a better approximation we would have to span the space for more than \mathcal{H}_4 like we did in Problem 1 of this homework.

MATLAB code:

```
1 %% A AE 567 HW4 Problem 3
2
3 % Housekeeping commands
4 clear all; close all; clc;
5 set(groot, 'defaulttextinterpreter','latex');
6 set(groot, 'defaultAxesTickLabelInterpreter','latex');
7 set(groot, 'defaultLegendInterpreter','latex');
8 outdir = pwd + "\output\hw4";
9 mdir = pwd + "\mfiles\hw4";
10 %%
11 m = 2;
12 % Define expectations
13 syms x v y g
14 y = x + v;
15 g = [];
16 for n = 0:m
17     g = [g; y^n];
18 end
19 xl = 0; xu = 10; % range of x
20 vl = 0; vu = 4; % range of v
21 fx = 1 / (xu - xl);
22 fv = 1 / (vu - vl);
23
24 EX = @(A) int(fx * x.^A, xl, xu);
25 EV = @(A) int(fv * v.^A, vl, vu);
26 EY = @(A) fx * fv * int(int(y.^A, x, xl, xu), vl, vu);
27 EXY = @(A,B) fx * fv * int(int(x.^A * y.^B, x, xl, xu), vl, vu);
28
29 % P_Hx
30 Rfg = EXY(1, 0:m);
31 A = [];
32 for n = 0:m
33     A = [A; n:n+m];
34 end
35 Rg = EY(A);
36 coef = Rfg * inv(Rg);
37 coef = eval(coef);
38 % Error d4
39 d4sq = EX(2) - Rfg*inv(Rg)*Rfg';
40 d4 = sqrt(d4sq);
41 %%
42 % Plotting
```

```

43 t = 0:0.01:14;
44
45 % ghat piecewise
46 t1 = t(0 <= t & t < 4);
47 t2 = t(4 <= t & t < 10);
48 t3 = t(10 <= t & t <= 14);
49 ghat = [t1 ./ 2, t2 - 2, (t3 + 6)/2];
50
51 % PHx
52 Ph3x = 0;
53 for n = 1:length(coef)
54     Ph3x = Ph3x + coef(n)*t.^(n-1);
55 end
56
57 Ph1x = 130 * t / 176;
58 Ph2x = -30/29 + 25/29*t;
59
60 fig = figure("Renderer","painters",'Position',[60 60 900 650]);
61 plot(t, Ph1x)
62 grid on; grid minor; box on; hold on;
63 plot(t, Ph2x)
64 plot(t, Ph3x)
65 plot(t, ghat)
66 hold off;
67 title('Problem 3 Least Square Approximation — T. Koike')
68 legend('$P_{\mathcal{H}_1}x$', '$P_{\mathcal{H}_2}x$', ...
69 '$P_{\mathcal{H}_3}x$', '$\hat{g}$', "Location","best")
70 xlabel('y')
71 ylabel('g')
72 saveas(fig, fullfile(outdir, 'p3_lsqr_plot.png'));
73 %%
74 % Save file as .m
75 matlab.internal.liveeditor.openAndConvert('hw4_p3.mlx', ...
76     convertStringsToChars(fullfile(mdir, 'hw4_p3.m')));

```

Problem 4

[Problem 2 from the Notes p. 35.] Let \mathbf{y} be a uniform random variable over $[0,1]$ and \mathbf{x} the random variable defined by $\mathbf{x} = e^{\mathbf{y}}$. Let \mathcal{H} be the subspace spanned by $\{1, \mathbf{y}, \mathbf{y}^2\}$. Then compute the optimal estimate $\hat{\mathbf{x}} = P_{\mathcal{H}}\mathbf{x}$ and the error in estimation $E(x - \hat{x})^2$. Show that $E(\mathbf{x}|\mathbf{y} = y) = e^y$. Plot your estimate $P_{\mathcal{H}}\mathbf{x}$ and the conditional expectation $E(\mathbf{x}|\mathbf{y} = y) = e^y$ on the same graph, and compare these two estimates.

Solution:

For convenience the heavy computations are done using MATLAB. (The code will be at the end of this problem.) Let

$$g = \begin{bmatrix} 1 \\ y \\ y^2 \end{bmatrix}$$

$$f = \mathbf{x} \quad .$$

Also since \mathbf{x} and \mathbf{y} are uniform distributions

$$E\mathbf{y} = 0.5$$

$$E\mathbf{x} = \int_0^1 e^y dy = e - 1$$

$$f_{\mathbf{y}}(y) = 1$$

Then

$$R_{fg} = R_{\mathbf{x}g} = E\mathbf{x}g = E\mathbf{x} \begin{bmatrix} 1 & y & y^2 \end{bmatrix} = \begin{bmatrix} E\mathbf{x} & E\mathbf{x}y & E\mathbf{x}y^2 \end{bmatrix} .$$

Here

$$E\mathbf{x}y = E(e^y)y$$

$$= \int_{-\infty}^{\infty} ye^y f_{\mathbf{y}}(y) dy = \int_0^1 ye^y dy$$

$$= 1 \quad .$$

Furthermore,

$$E\mathbf{x}y^2 = E y^2 e^y$$

$$= \int_{-\infty}^{\infty} y^2 e^y f_{\mathbf{y}}(y) dy$$

$$= \int_0^1 y^2 e^y dy$$

$$= e - 2.$$

Which gives

$$\therefore R_{fg} = \begin{bmatrix} (e-1) & 1 & (e-2) \end{bmatrix}.$$

Next,

$$\begin{aligned} R_g = E g g^* &= E \begin{bmatrix} 1 \\ y \\ y^2 \end{bmatrix} \begin{bmatrix} 1 & y & y^2 \end{bmatrix} = \begin{bmatrix} E1 & Ey & Ey^2 \\ Ey & Ey^2 & Ey^3 \\ Ey^2 & Ey^3 & Ey^4 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0.5000 & 0.3333 \\ 0.5000 & 0.3333 & 0.2500 \\ 0.3333 & 0.2500 & 0.2000 \end{bmatrix}. \end{aligned}$$

Now the coefficients a, b , and c become

$$\begin{aligned} \begin{bmatrix} a & b & c \end{bmatrix} &= R_{fg} R_g^{-1} \\ &= \begin{bmatrix} 1.7183 & 1 & 0.7183 \end{bmatrix} \begin{bmatrix} 1 & 0.5000 & 0.3333 \\ 0.5000 & 0.3333 & 0.2500 \\ 0.3333 & 0.2500 & 0.2000 \end{bmatrix}^{-1} \\ &= \begin{bmatrix} 1.0130 & 0.8511 & 0.8392 \end{bmatrix}. \end{aligned}$$

Hence,

$$P_{\mathcal{H}} \mathbf{x} = 1.0130 + 0.8511y + 0.8392y^2 \quad .$$

Then the error becomes

$$\begin{aligned} d_4^2 &= R_{\mathbf{x}} - R_{fg} R_g^{-1} R_{gf} \\ &= 2.7835e - 5 \end{aligned}$$

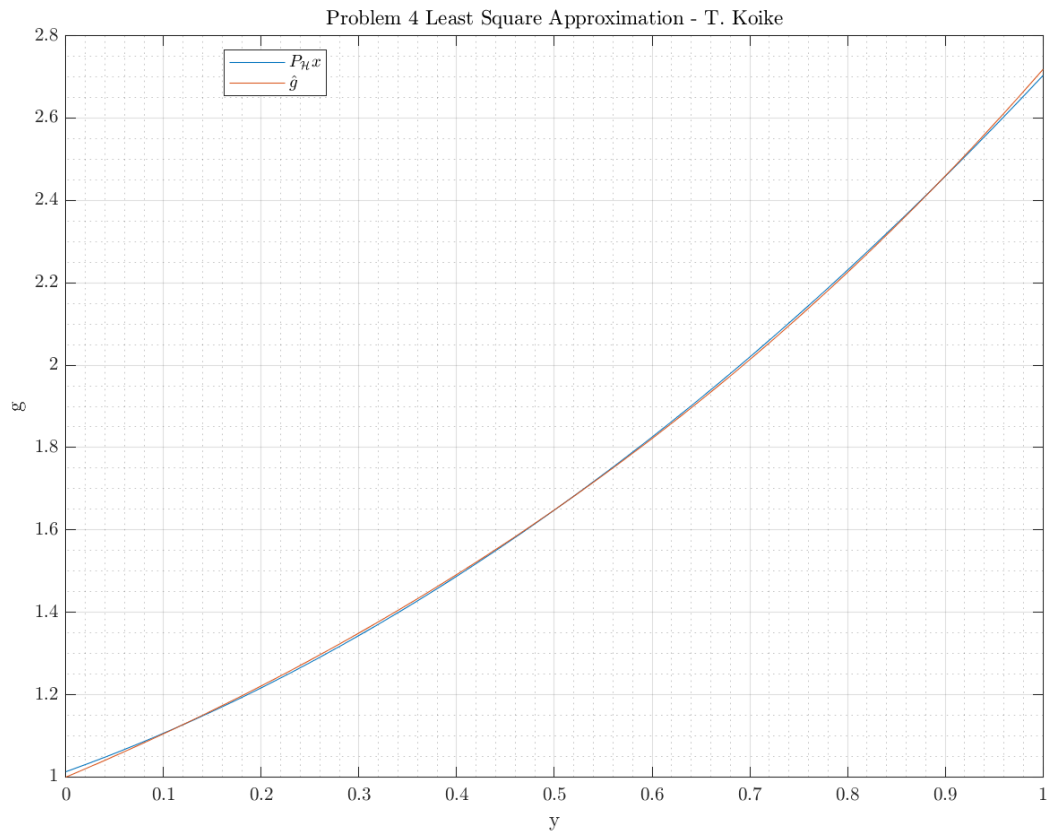
Thus,

$$\therefore d_4 = 0.0053 \quad .$$

It is known that the conditional expectation

$$\hat{g}(y) = E(\mathbf{x} | \mathbf{y} = y) = e^y \quad .$$

Thus, we plot the 2 on the same plot for comparison.



From the plot, we can see that the approximation is very close to the original exponential equation in the range of $[0,1]$. This visual result is coherent with the error value that we have calculated.

The MATLAB code is as follows.

```

1 %% AAE 567 HW4 Problem4
2
3 % Housekeeping commands
4 clear all; close all; clc;
5 set(groot, 'defaulttextinterpreter','latex');
6 set(groot, 'defaultAxesTickLabelInterpreter','latex');
7 set(groot, 'defaultLegendInterpreter','latex');
8 outdir = pwd + "\output\hw4";
9 mdir = pwd + "\mfiles\hw4";
10 %%
11 m = 2;
12 % Define expectations

```

```

13 syms x y
14 g = [];
15 for n = 0:m
16     g = [g; y^n];
17 end
18 yl = 0; yu = 1; % range of y
19 xl = 0; xu = 1; % range of x
20 fy = 1 ;
21
22 EY = @(A) int(y.^A, yl, yu);
23 EX = @(A) int(expm(A*y), yl, yu);
24 EXY = @(A,B) int(y.^B .* expm(A*y), yl, yu);
25
26 % P_Hx
27 Rfg = EXY(1, 0:m);
28 A = [];
29 for n = 0:m
30     A = [A; n:n+m];
31 end
32 Rg = EY(A);
33
34 coef = Rfg * inv(Rg);
35 coef = eval(coef);
36 % Error d4
37 d4sq = EX(2) - Rfg*inv(Rg)*Rfg'
38 d4 = sqrt(d4sq);
39 %%
40 % Plotting
41 t = 0:0.01:1;
42 % ghat
43 Phx = 0;
44 for n = 1:length(coef)
45     Phx = Phx + coef(n)*t.^(n-1);
46 end
47
48 fig = figure("Renderer","painters",'Position',[60 60 900 650]);
49 plot(t, Phx)
50 grid on; grid minor; box on; hold on;
51 plot(t, exp(t))
52 hold off;
53 title('Problem 4 Least Square Approximation — T. Koike')
54 legend('$P_{\mathcal{H}}x$', '$\hat{g}$', "Location","best")
55 xlabel('y')
56 ylabel('g')
57 saveas(fig, fullfile(outdir, 'p4_lsqr_plot.png'));

```



```
58 %%  
59 % Save file as .m  
60 matlab.internal.liveeditor.openAndConvert('hw4_p4.mlx', ...  
61     convertStringsToChars(fullfile(mdir, 'hw4_p4.m')));
```