Table of Contents

```
_ ...... 2
function [approx_ln3, abs_diff] = PS09_ln3_noloop_koike(num_terms)
% ENGR 132
% Program Description
% This program calculates the estimate of ln3 and the absolute
% difference with the matlab calculated ln3 the without using a
% loop command
% Function Call
% [estimate, abs_diff] = PS09_ln3_noloop_koike(num_terms);
9
% Input Arguments
% 1. num_terms: the number of terms for the approximate summation
% Output Arguments
% 1. estimate: the approximate value of ln3
% 2. abs_diff: the absolute difference between the approximate and the
% matlab calculated value for ln3.
% Assignment Information
 Assignment: PS 09, Problem 2
응
              Tomoki Koike, koike@purdue.edu
응
  Author:
  Team ID:
્ર
              002-08
응
  Contributor: Name, login@purdue [repeat for each]
  My contributor(s) helped me:
   [ ] understand the assignment expectations without
응
응
      telling me how they will approach it.
응
   [ ] understand different ways to think about a solution
     without helping me plan my solution.
9
   [ ] think through the meaning of a specific error or
     bug present in my code without looking at my code.
```

INITIALIZATION

```
% initialization of output
approx_ln3 = -99;
abs_diff = -99;
```

CALCULATIONS

COMMAND WINDOW OUTPUT

```
% test case 2 <n=8>
% num_terms = 12;
% [estimate, abs_diff] = PS09_ln3_noloop_koike(num_terms)
% the approximate value of ln3 is 1.098612 and the absolute difference
is 0.000000
% estimate =
્ટ
    1.0986
% abs_diff =
    3.1038e-09
응
% test case 3 < n=24 >
% num terms = 24;
% [estimate, abs_diff] = PS09_ln3_noloop_koike(num_terms)
% the approximate value of ln3 is 1.098612 and the absolute difference
is 0.000000
% estimate =
9
응
    1.0986
% abs diff =
    6.6613e-16
% test case 4 <n=-0.25>
% num terms = -0.25;
% [estimate, abs_diff] = PS09_ln3_noloop_koike(num_terms)
% Error, invalid n
% estimate =
응
응
    -99
응
% abs diff =
9
응
    -99
```

ACADEMIC INTEGRITY STATEMENT

```
% Call your academic integrity statement here
PS07_academic_integrity_koike("Tomoki Koike");
```

I am submitting code that is my own original work. I have not used source code, either modified or unmodified, obtained from any

unauthorized source. Neither have I provided access to my code to any peer or unauthorized source. Signed, <Tomoki Koike>

Published with MATLAB® R2018a