AAE 567 Spring 2018 Homework 2 Solutions

February 22, 2018

2.2.2 Problem 1

We are given that \mathbf{x} is a uniform random variable over [0, 10], \mathbf{v} is a uniform random variable over [0, 4], \mathbf{x} and \mathbf{v} are independent random variables, $\mathbf{y} = \mathbf{x} + \mathbf{v}$, and \mathcal{H}_3 is the subspace spanned by $\{1, \mathbf{y}, \mathbf{y}^2\}$. We want to compute the optimal estimate $\hat{x} = P_{\mathcal{H}_3}x$ and the error $E(x - \hat{x})^2$. We will then compare this result to the conditional expectation E(x|y).

Because x is uniform over [0, 10], we have $f_{\mathbf{x}}(x) = \frac{1}{10}$ on the interval [0, 10] and 0 elsewhere. Similarly, $f_{\mathbf{v}}(v) = \frac{1}{4}$ on the interval [0, 4] and 0 elsewhere. By consulting Lemma 12.3.1, we obtain

$$f_{\mathbf{x},\mathbf{y}}(x,y) = f_{\mathbf{x}}(x)f_{\mathbf{v}}(y-x) = \frac{1}{40}$$
 if $0 \le x \le 10$ and $0 \le y-x \le 4$
= 0 otherwise.

Also from the lemma we have $f_{\mathbf{y}}(y) = \int_{-\infty}^{\infty} f_{\mathbf{x},\mathbf{y}}(x,y)dx$. For this we have 3 regions for \mathbf{y} : [0, 4], [4, 10], and [10, 14]. We obtain

$$f_{\mathbf{y}}(y) = \int_0^y \frac{1}{40} dx = \frac{y}{40} \text{ if } 0 \le y \le 4$$

$$= \int_{y-4}^y \frac{1}{40} dx = \frac{1}{10} \text{ if } 4 \le y \le 10$$

$$= \int_{y-4}^{10} \frac{1}{40} dx = \frac{14-y}{40} \text{ if } 10 \le y \le 14$$

$$= 0 \text{ otherwise.}$$

Finally, it is noted that $f_{\mathbf{y}}(y)$ is positive and the area under $f_{\mathbf{y}}(y)$ equals one. So $f_{\mathbf{y}}(y)$ is indeed a density function.

We can now use the expression for $f_{\mathbf{y}}(y)$ to obtain the conditional density function as defined in Lemma 12.3.1:

$$f_{\mathbf{x}|\mathbf{y}}(x|y) = \frac{f_{\mathbf{x}}(x)f_{\mathbf{v}}(y-x)}{f_{\mathbf{y}}(y)} = \frac{1}{40f_{\mathbf{y}}(y)}$$

where the last equality holds for all values of x and y for which the probability density functions are non-zero. We obtain:

$$\begin{split} f_{\mathbf{x}|\mathbf{y}}(x|y) &= \frac{1}{40} \frac{40}{y} = \frac{1}{y} & \text{if } 0 \leq x \leq y \text{ and } 0 \leq y \leq 4 \\ &= \frac{1}{40} 10 = \frac{1}{4} & \text{if } y - 4 \leq x \leq y \text{ and } 4 \leq y \leq 10 \\ &= \frac{1}{40} \frac{40}{14 - y} = \frac{1}{14 - y} & \text{if } y - 4 \leq x \leq 10 \text{ and } 10 \leq y \leq 14 \end{split}$$

From section 12.2 equation (2.2) we have the conditional expectation given by $E(\mathbf{x}|\mathbf{y}=y)=\int_{-\infty}^{\infty}xf_{\mathbf{x}|\mathbf{y}}(x|y)dx$. Substituting in the known conditional probability density function, we obtain

$$E(\mathbf{x}|\mathbf{y} = y) = \int_0^y \frac{x}{y} dx = \frac{y}{2}$$
 if $0 \le y \le 4$
= $\int_{y-4}^y \frac{x}{4} dx = y - 2$ if $4 \le y \le 10$
= $\int_{y-4}^{10} \frac{x}{14 - y} dx = \frac{y+6}{2}$ if $10 \le y \le 14$.

Let $g = \begin{bmatrix} 1 & \mathbf{y} & \mathbf{y}^2 \end{bmatrix}^*$. Recall that the orthogonal projection $P_{\mathcal{H}_3}x = R_{xg}R_g^{-1}g$ and $E(x-\hat{x})^2 = R_x - R_{xg}R_g^{-1}R_{gx}$. For arbitrary vectors a and b, we have $R_a = E(aa^*)$ and $R_{ab} = E(ab^*)$. Then R_g is the 3x3 matrix given by

$$R_g = E \begin{bmatrix} 1 \\ \mathbf{y} \\ \mathbf{y}^2 \end{bmatrix} \begin{bmatrix} 1 & \mathbf{y} & \mathbf{y}^2 \end{bmatrix} = \begin{bmatrix} 1 & \mathbf{y} & \mathbf{y}^2 \\ \mathbf{y} & \mathbf{y}^2 & \mathbf{y}^3 \\ \mathbf{y}^2 & \mathbf{y}^3 & \mathbf{y}^4 \end{bmatrix}.$$

Using the fact that x and v are independent random variables we can compute $E\mathbf{y}^k = E(\mathbf{x} + \mathbf{v})^k$ for k = 1, 2, 3, 4. Notice that R_x is a scalar given by

$$R_x = Ex^2 = \int_0^{10} \frac{x^2}{10} dx = \frac{100}{3}.$$

Moreover, R_{xq} is a row vector of length three, that is,

$$R_{xq} = E \begin{bmatrix} \mathbf{x} & \mathbf{x}\mathbf{y} & E\mathbf{x}\mathbf{y}^2 \end{bmatrix} = \begin{bmatrix} E\mathbf{x} & E\mathbf{x}(\mathbf{x} + \mathbf{v}) & \mathbf{x}(\mathbf{x} + \mathbf{v})^2 \end{bmatrix}.$$

Evaluating the previous matrices yields

$$R_g = \begin{bmatrix} 1 & 7 & \frac{176}{3} \\ 7 & \frac{176}{3} & 546 \\ \frac{176}{3} & 546 & \frac{81568}{15} \end{bmatrix}$$

$$R_{xg} = \begin{bmatrix} 5 & \frac{130}{3} & 410 \end{bmatrix}$$

$$R_x = \frac{100}{3}$$

Using $\hat{\mathbf{x}} = R_{xg}R_q^{-1}g$, we now find the estimate and the error covariance:

$$\hat{x} = \frac{25}{29}\mathbf{y} - \frac{30}{29}$$
$$E(x - \hat{x})^2 = R_x - R_{xg}R_g^{-1}R_{gx} = \frac{100}{87}$$

Note that including the y^2 term does not add any accuracy to the estimate, as the coefficient for this term is 0.

Note also that both the conditional expectation and the projection onto \mathcal{H}_3 are linear, but while the projection is linear over the entire domain [0,10], the conditional expectation is defined piecewise over three separate intervals. Plotting both the conditional expectation and $P_{\mathcal{H}_3}\mathbf{x}$ together we obtain Figure 1

The following Matlab code solves this problem:

```
%2.2.2 #1 syms x v y  R_{-g} = zeros(3,3);  for i=1:3  for j = 1:3 \\  R_{-g}(i,j) = int(y^{(i+j-1)/40},y,0,4) + int(y^{(i+j-2)/10},y,4,10) \dots \\  + int(y^{(i+j-2)*(14-y)/40},y,10,14);  end end  Ex = int(x/10,x,0,10);   Ex2 = int(x^2/10,x,0,10);   Ex3 = int(x^3/10,x,0,10);
```

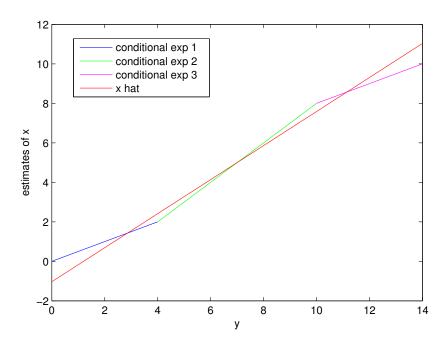


Figure 1: Plot for y on the interval [0,14] of the conditional expectation E(x|y) and the optimal estimate $P_{\mathcal{H}_3}x$ for 2.2.2 Exercise 1

```
Ev = int(v/4, v, 0, 4);
Ev2 = int(v^2/4, v, 0, 4);
R_fg = [Ex, Ex2+Ex*Ev, Ex3+2*Ex2*Ev+Ex*Ev2];
alphas1 = R_fg/R_g;
est_err1 = Ex2 - R_fg/R_g*R_fg';
figure(1)
y1 = 0:.01:4;
y2 = 4:.01:10;
y3 = 10:.01:14;
y_full = 0:.01:14;
plot(y1,y1/2,'b')
hold on
plot(y2,y2-2,'g')
plot(y3,(y3+6)/2,'m')
plot(y_full,alphas1(1)*y_full/y_full+alphas1(2)*y_full+alphas1(3)*y_full.^2,'r')
legend('conditional exp 1', 'conditional exp 2', 'conditional exp 3', 'x hat')
xlabel('y')
ylabel('estimates of x')
hold off
```

2.2.2 Problem 2

We are given that \mathbf{y} is a uniform random variable on [0,1] and $\mathbf{x} = e^{\mathbf{y}}$. We also have that \mathcal{H} is the subspace spanned by $\{1, \mathbf{y}, \mathbf{y}^2\}$. We want to compute the optimal estimate $\hat{x} = P_{\mathcal{H}}x$ and the error $E(x - \hat{x})$. We will also show that $E(x|\mathbf{y} = y) = e^y$ and plot both \hat{x} and e^y to compare them.

We have $P_{\mathcal{H}}x = R_{xg}R_g^{-1}g$ with $g = [1 \mathbf{y} \mathbf{y}^2]^{tr}$, $R_g = E(gg^*)$, and $R_{xg} = [E(x1) E(x\mathbf{y}) E(x\mathbf{y}^2)]$. For this particular g we have $R_{i,j} = E(\mathbf{y}^{i+j-2})$. We first compute the components of R_g :

$$E1 = 1$$

$$E\mathbf{y} = \int_0^1 y dy = \frac{1}{2}$$

$$E\mathbf{y}^2 = \int_0^1 y^2 dy = \frac{1}{3}$$

$$E\mathbf{y}^3 = \int_0^1 y^3 dy = \frac{1}{4}$$

$$E\mathbf{y}^4 = \int_0^1 y^4 dy = \frac{1}{5}$$

We also have the components of R_{xg} given by:

$$E\mathbf{x}1 = \int_0^1 e^y dy = e - 1$$

$$E\mathbf{x}\mathbf{y} = \int_0^1 e^y y dy = 1$$

$$E\mathbf{x}\mathbf{y}^2 = \int_0^1 e^y y^2 dy = e - 2$$

Putting this all together, we obtain

$$\hat{x} = \begin{bmatrix} e - 1 & 1 & e - 2 \end{bmatrix} \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ \mathbf{y} \\ \mathbf{y}^2 \end{bmatrix}$$

which results in

$$\hat{x} \approx 1.0130 + 0.8511\mathbf{y} + 0.8392\mathbf{y}^2$$

The error is given by $E(x-\hat{x})^2=R_x-R_{xg}R_g^{-1}R_{gx}=Ex^2-R_{xg}R_g^{-1}R_{xg}^{tr}$. We obtain

$$E(x - \hat{x})^2 = \int_0^1 e^{2y} dy - \begin{bmatrix} e - 1 & 1 & e - 2 \end{bmatrix} \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \end{bmatrix}^{-1} \begin{bmatrix} e - 1 \\ 1 \\ e - 2 \end{bmatrix}$$

$$\approx 2.7835 \times 10^{-5}$$

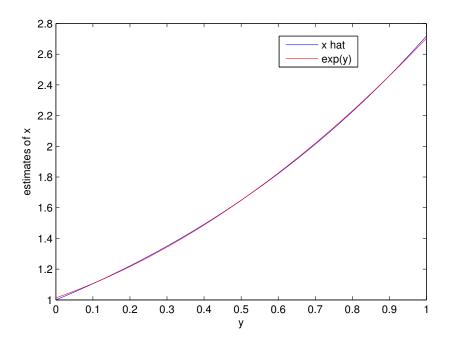


Figure 2: Plot for y on the interval [0,14] of the conditional expectation E(x|y) and the optimal estimate $P_{mathcalH_3}x$ for 2.2.2 Exercise 2

From theorem 12.2.1, the conditional expectation of x given y, $\hat{g}(\mathbf{y}) = E(\mathbf{x}|\mathbf{y})$ is the function of y which gives the infimum (and in this case minimum) of $E|\mathbf{x} - g(\mathbf{y})|^2$. Since $\mathbf{x} = e^{\mathbf{y}}$, clearly we have zero error when $g(\mathbf{y}) = e^{\mathbf{y}}$, so we must have $E(\mathbf{x}|\mathbf{y}) = e^{\mathbf{y}}$

The conditional expectation has zero error since it is the exact expression that it attempts to estimate, but the error for the projection is also very low with magnitude 10^{-5} . As can be seen in Figure 2, the two curves are closely matched.

The following Matlab code solves this problem:

```
%2.2.2 #2
R_g = zeros(3,3);
R_fg = zeros(1,3);
for i = 1:3
    R_fg(i) = int(exp(y)*y^(i-1),y,0,1);
    for j = 1:3
        R_g(i,j) = int(y^(i+j-2),y,0,1);
```

end
end

alphas2 = R_fg/R_g;
est_err = eval(int(exp(2*y),y,0,1) - R_fg/R_g*R_fg');

z = 0:.001:1;
x_hat = alphas(1)*z./z + alphas(2)*z + alphas(3) * z.^2;
ey = exp(z);
figure(2)
plot(z,ey,'b')
hold on
plot(z,x_hat,'r')
ylabel('estimates of x')
xlabel('y')

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legend('x hat','exp(y)')

We are given a random variable \mathbf{x} with finite $E|\mathbf{x}|^2$ and $\mathcal{H} = \text{span }\{2\}$, and we wish to find $\hat{\mathbf{x}} = P_{\mathcal{H}}\mathbf{x}$ and $E|\mathbf{x} - \hat{\mathbf{x}}|^2$.

We begin by denoting $\mu_x = E\mathbf{x}$, the mean of \mathbf{x} . We note that $R_f = E|\mathbf{x}|^2$, $R_g = 4$, and $R_{fg} = R_{gf} = 2\mu_x$.

We then have

$$\hat{\mathbf{x}} = P_{\mathcal{H}}\mathbf{x} \tag{1}$$

$$=R_{fg}R_g^{-1}g\tag{2}$$

$$=2\mu_x \frac{1}{4}2\tag{3}$$

$$=\mu_x\tag{4}$$

and

$$E|\mathbf{x} - \hat{\mathbf{x}}|^2 = R_f - R_{fg}R_{gf}R_g^{-1} \tag{5}$$

$$= E|\mathbf{x}|^2 - (\mu_x 2)(2\mu_x)/4 \tag{6}$$

$$=E|\mathbf{x}|^2 - \mu_x^2\tag{7}$$