



College of Engineering  
School of Aeronautics and Astronautics

AAE 36401 Lab  
Control Systems Lab

Lab 2 Pre-Lab  
The Cart on a Track with Pendulum

*Author:*  
Tomoki Koike

*Supervisor:*  
A. E. Frazho

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Purdue University  
West Lafayette, Indiana

Using Matlab and Simulink, the best gain were the following values

K	GAINS
$K_1$	38.9466
$K_2$	-33.0734
$K_3$	14.9005
$K_4$	2.9887

The plot with my gains and the gains  $K = [0, 0, 0, 0]$  is the following

