

Last time: ① Examples of Finding MLE:

$$\hat{\theta}_{MLE} = \underset{\theta \in \Theta}{\operatorname{argmax}} L(\theta; x_1, \dots, x_n) \text{ or } l(\theta; x_1, \dots, x_n)$$

where $\bar{x}_1, \dots, \bar{x}_n \stackrel{iid}{\sim} f_{\bar{x}}(x; \theta_0)$ for some $\theta_0 \in \Theta$

$$\textcircled{2} \quad \theta_0 = \underset{\theta \in \Theta}{\operatorname{argmax}} E[l(\theta; \bar{x})] \quad \text{where } \bar{x} \sim f_{\bar{x}}(x; \theta_0)$$

$$\text{where } l(\theta; x) = \ln(f_{\bar{x}}(x; \theta))$$

By the WLLN:

$$\frac{1}{N} \sum_{i=1}^N l(\theta; x_i) \xrightarrow{P} E[l(\theta; \bar{x})] \quad \text{for all } \theta \in \Theta$$

③ Bias, Variance and MSE:

$$MSE(\hat{\theta}) = \operatorname{Var}(\hat{\theta}) + \operatorname{Bias}(\hat{\theta})^2$$

$$\text{where } \operatorname{Bias}(\hat{\theta}) = E[\hat{\theta}] - \theta_0 = E[\hat{\theta} - \theta_0]$$

$$\hat{\theta} \text{ unbiased} \iff \operatorname{Bias}(\hat{\theta}) = 0 \text{ for all } \theta_0 \in \Theta$$

$$\implies MSE(\hat{\theta}) = \operatorname{Var}(\hat{\theta})$$

There is a trade-off between bias and variance.

Today : ① Efficiency + Cramer-Rao Lower Bound

② Consistency

③ Bayesian Estimation

① Efficiency: See previous lecture notes

"Lecture-Nov09-Sheng.pdf"

② Consistency:

An estimator $\hat{\theta}_N$ based on $\bar{x}_1, \dots, \bar{x}_N$ is consistent if $\hat{\theta}_N \xrightarrow{P} \theta_0$:

For every $\varepsilon > 0$, $\lim_{N \rightarrow \infty} P(|\hat{\theta}_N - \theta_0| > \varepsilon) = 0$

Example 1: $\bar{x}_1, \bar{x}_2, \dots \stackrel{iid}{\sim} \text{Ber}(\theta_0)$

$$\text{let } \hat{\theta}_N = \frac{1}{N} \sum_{i=1}^N \bar{x}_i$$

$$P(|\hat{\theta}_N - \theta_0| > \varepsilon) = P(|\hat{\theta}_N - \theta_0|^2 > \varepsilon^2)$$

$$\text{Markov's Inequality} \longrightarrow \leq \frac{E[|\hat{\theta}_N - \theta_0|^2]}{\varepsilon^2}$$

$$E[\hat{\theta}_N] = \theta_0 \longrightarrow = \frac{\text{Var}(\hat{\theta}_N)}{\varepsilon^2}$$

$$= \frac{\theta_0(1-\theta_0)}{N\varepsilon^2} \longrightarrow 0 \text{ as } N \rightarrow \infty$$

So $\hat{\theta}_N$ is consistent.

Example 2: $\bar{x}_1, \bar{x}_2, \dots \stackrel{iid}{\sim} N(\mu, \sigma^2)$

$$\text{let } \hat{\mu}_N = \frac{1}{N} \sum_{i=1}^N \bar{x}_i \sim N(\mu, \frac{\sigma^2}{N})$$

$$\begin{aligned}
& P(|\hat{\mu}_N - \mu| > \varepsilon) \\
&= P\left(\frac{|\hat{\mu}_N - \mu|}{\frac{\sigma}{\sqrt{N}}} > \frac{\varepsilon}{\frac{\sigma}{\sqrt{N}}}\right) \\
&= P(|Z_N| > \frac{\sqrt{N}\varepsilon}{\sigma}) \quad \left[Z_N = \frac{\hat{\mu}_N - \mu}{\frac{\sigma}{\sqrt{N}}} \sim N(0, 1) \right] \\
&= 2\left(1 - \Phi\left(\frac{\sqrt{N}\varepsilon}{\sigma}\right)\right) \rightarrow 0 \quad \left[\begin{array}{l} \Phi(\cdot) = \text{standard normal CDF} \\ \lim_{z \rightarrow \infty} \Phi(z) = 1 \end{array} \right]
\end{aligned}$$

$$\text{Let } \hat{\sigma}_N^2 = \frac{1}{N} \sum_{i=1}^N (\bar{x}_i - \bar{\bar{x}})^2$$

$$E[\hat{\sigma}_N^2] = \frac{N-1}{N} \sigma^2, \quad \text{Var}(\hat{\sigma}_N^2) = \frac{2(N-1)}{N^2} \sigma^4$$

$$\Rightarrow \text{MSE}(\hat{\sigma}_N^2) = E[|\hat{\sigma}_N^2 - \sigma^2|^2] = \frac{2N-1}{N^2} \sigma^4$$

$$\begin{aligned}
\text{So } P(|\hat{\sigma}_N^2 - \sigma^2| > \varepsilon) &\leq \frac{E[|\hat{\sigma}_N^2 - \sigma^2|^2]}{\varepsilon^2} \\
&= \frac{2N-1}{N^2} \frac{\sigma^4}{\varepsilon^2} \rightarrow 0 \quad \text{as } N \rightarrow \infty
\end{aligned}$$

Biased but consistent example!

How about unbiased but not consistent?

For example: $\bar{x}_1, \bar{x}_2, \dots \stackrel{\text{i.i.d.}}{\sim}$ with mean μ , let $\hat{\mu}_N = \bar{x}_N$
then $E[\hat{\mu}_N] = \mu$ but $\hat{\mu}_N \not\rightarrow \mu$ as $N \rightarrow \infty$.

③ Bayesian Estimation

When estimating a parameter $\theta_0 \in \Theta$, the MLE framework makes almost no assumptions.

It is often the case that some values of $\theta \in \Theta$ are a priori more likely than others.

Bayes rule allows us to incorporate information like this.

Let A, B be two events, since

$$P(A \cap B) = P(A|B)P(B) = P(B|A)P(A)$$

then we have

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{P(B|A)P(A)}{P(B)}$$

More generally, in Bayesian estimation, the unknown parameter θ is treated as a random variable, and prior information for θ is encoded in a distribution $f_{\Theta}(\theta)$:

$$\Theta \sim f_{\Theta}(\theta)$$

The observable random variable \bar{X} is related to θ through the conditional distribution:

$$\bar{X} \sim f_{\bar{X}}(x | \Theta = \theta)$$

Given an observation $\bar{\mathbf{x}} = \mathbf{x}$, we update our model for Θ according to the Bayes rule:

$$f_{\Theta}(\theta | \bar{\mathbf{x}} = \mathbf{x}) = \frac{\overset{\text{likelihood}}{f_{\bar{\mathbf{x}}}(\mathbf{x} | \Theta = \theta)} \overset{\text{prior}}{f_{\Theta}(\theta)}}{\underset{\text{posterior}}{f_{\bar{\mathbf{x}}}(\mathbf{x})}}$$

$$\downarrow \text{marginal likelihood}$$

$$= \int_{\Theta \in \mathcal{H}} f_{\bar{\mathbf{x}}}(\mathbf{x} | \Theta = \theta) f_{\Theta}(\theta) d\theta$$

How do we turn the posterior $f_{\Theta}(\theta | \bar{\mathbf{x}} = \mathbf{x})$ into an estimate of θ ? There are two popular approaches:

① Posterior mean or MMSE:

$$\hat{\theta}_{\text{MMSE}} = E[\Theta | \bar{\mathbf{x}} = \mathbf{x}] = \underset{\theta}{\operatorname{argmin}} E[|\Theta - \theta|^2 | \bar{\mathbf{x}} = \mathbf{x}]$$

② Posterior mode or MAP:

$$\hat{\theta}_{\text{MAP}} = \underset{\theta \in \mathcal{H}}{\operatorname{argmax}} f_{\Theta}(\theta | \bar{\mathbf{x}} = \mathbf{x})$$

$$= \underset{\theta \in \mathcal{H}}{\operatorname{argmax}} f_{\bar{\mathbf{x}}}(\mathbf{x} | \Theta = \theta) f_{\Theta}(\theta)$$

If $f_{\Theta}(\theta) = \frac{1}{|\mathcal{H}|}$ for all $\theta \in \mathcal{H}$, then

$$\hat{\theta}_{\text{MAP}} = \underset{\theta \in \mathcal{H}}{\operatorname{argmax}} f_{\bar{\mathbf{x}}}(\mathbf{x} | \Theta = \theta) = \hat{\theta}_{\text{MLE}}$$

Example: $\bar{x}_1, \dots, \bar{x}_N \stackrel{iid}{\sim} \text{Ber}(\theta)$, $\theta \in \text{Uniform}(0, 1)$

observations: $\bar{x}_1 = x_1, \dots, \bar{x}_N = x_N$

$$f_{\bar{x}}(x_1, x_2, \dots, x_N | \theta = \theta) f_{\theta}(\theta) = \prod_{i=1}^N \theta^{x_i} (1-\theta)^{1-x_i} \cdot 1$$

$$= \theta^{\sum_{i=1}^N x_i} (1-\theta)^{N - \sum_{i=1}^N x_i}$$

$$= \theta^{S_N} (1-\theta)^{N-S_N} \quad \text{where } S_N \triangleq \sum_{i=1}^N x_i$$

$$f_{\bar{x}}(x_1, \dots, x_N) = \int_0^1 f_{\bar{x}}(x_1, \dots, x_N | \theta = \theta) f_{\theta}(\theta) d\theta$$

$$= \int_0^1 \theta^{S_N} (1-\theta)^{N-S_N} d\theta$$

$$= B(S_N+1, N-S_N+1) \quad \text{where } B(x, y) = \frac{\Gamma(x)\Gamma(y)}{\Gamma(x+y)} \text{ is}$$

therefore

the Beta function

$$f_{\theta}(\theta | x_1, \dots, x_N) = \frac{f_{\bar{x}}(x_1, \dots, x_N | \theta = \theta) f_{\theta}(\theta)}{f_{\bar{x}}(x_1, \dots, x_N)}$$

$$= \frac{\theta^{S_N} (1-\theta)^{N-S_N}}{B(S_N+1, N-S_N+1)}$$

This is the PDF of the $\text{Beta}(S_N+1, N-S_N+1)$ distribution.

We compute explicitly the marginal $f_{\bar{x}}(x_1, \dots, x_N)$ above, but this was not necessary to find the posterior. Indeed,

$$f_{\mathbf{z}}(x_1, \dots, x_N | \Theta = \theta) f_{\Theta}(\theta) = \theta^{S_N} (1-\theta)^{N-S_N}$$

tells us the PDF of the posterior distribution of Θ .

Since $\theta | x_1, \dots, x_N \sim \text{Beta}(S_N+1, N-S_N+1)$ has

$$\text{mean } E[\theta | x_1, \dots, x_N] = \frac{S_N+1}{(S_N+1)+(N-S_N+1)} = \frac{S_N+1}{N+2}$$

$$\text{mode } \frac{(S_N+1)-1}{(S_N+1)+(N-S_N+1)-2} = \frac{S_N}{N}$$

$$\text{then } \hat{\theta}_{\text{mmse}} = \frac{S_N+1}{N+2} \quad \text{and} \quad \hat{\theta}_{\text{map}} = \frac{S_N}{N}$$