

AAE340 HW8 PROBLEM 5

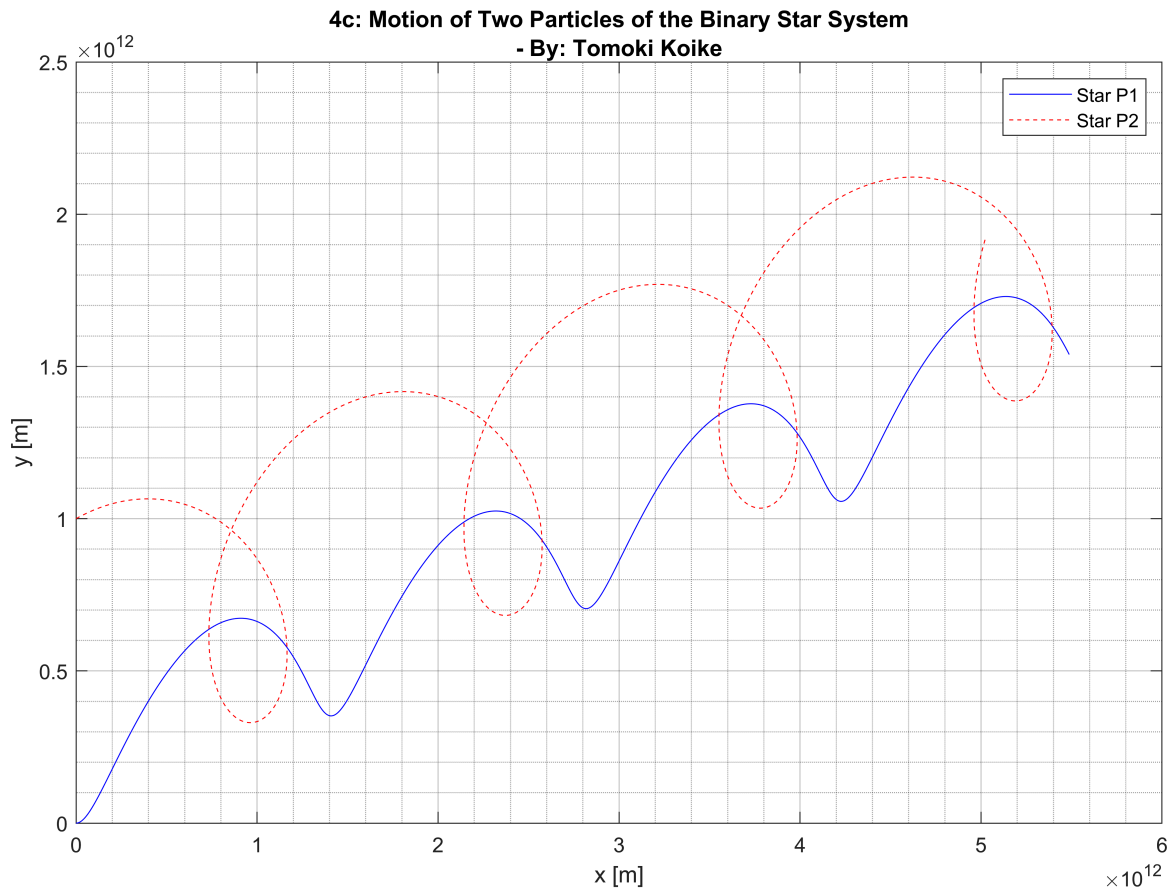
```
close all
clear all
clc
```

<5c>

```
% Defining constants
m = 1.987*10^30; % Solar mass [kg]
G = 6.673*10^(-11); % Gravitational constant [m^3/kg^2]

% Solving the differential equation
tspan = 0:1000:1.000*10^9; % Time interval [s]
ICs = [0, 0, 0, 1.000*10^12, 2000.0, 0, 12000.0, 4000.0]; % [m] and [m/s]
options = odeset('RelTol',1e-12, 'AbsTol',1e-12); % Ode options
[t, z] = ode45(@(t,z) dfcn(t,z), tspan, ICs, options); % Ode45
x1 = z(:,1); % Assigning the x1 values
y1 = z(:,2); % Assigning the y1 values
x2 = z(:,3); % Assigning the x2 values
y2 = z(:,4); % Assigning the y2 values
x1_dot = z(:,5); % Assigning the x1 dot values
y1_dot = z(:,6); % Assigning the y1 dot values
x2_dot = z(:,7); % Assigning the x2 dot values
y2_dot = z(:,8); % Assigning the y2 dot values

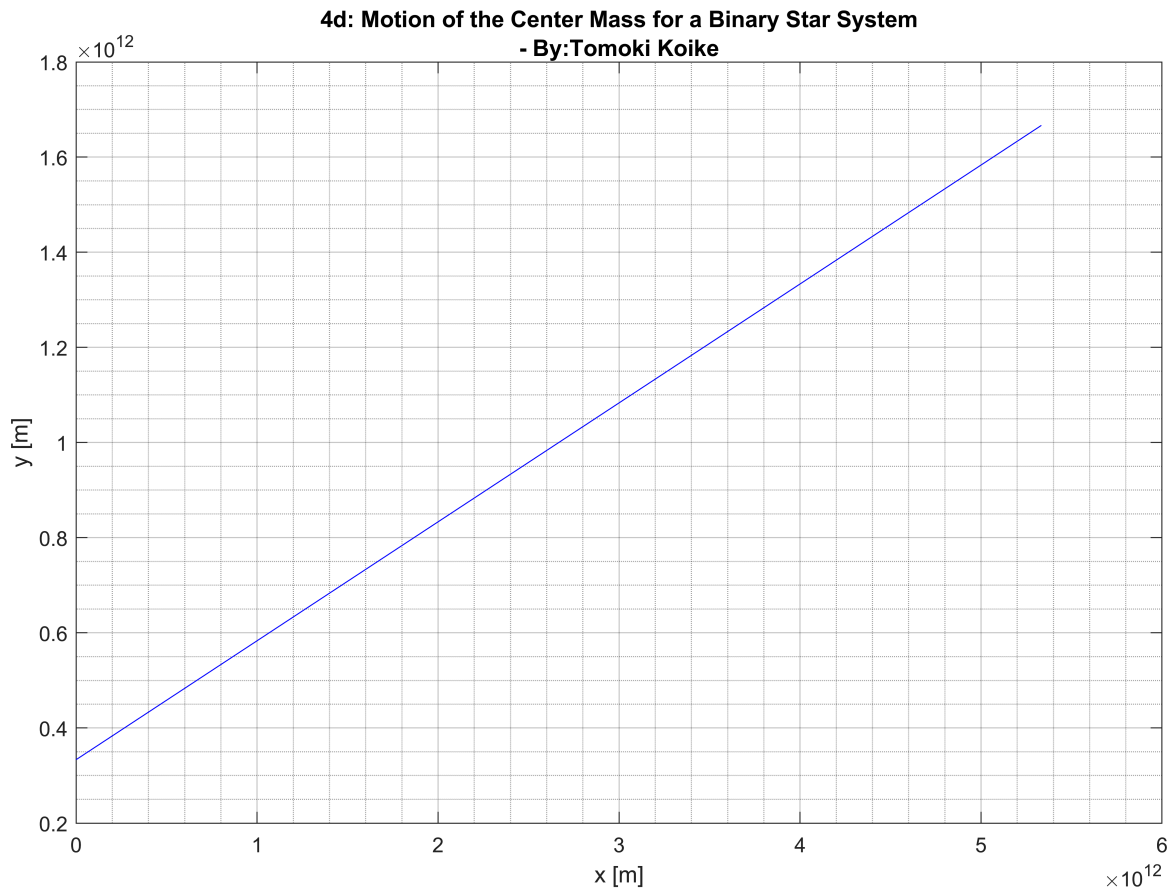
% Plotting
figure('Renderer','painters','Position',[20 20 900 600])
plot(x1, y1, '-b')
xlabel('x [m]')
ylabel('y [m]')
title({'4c: Motion of Two Particles of the Binary Star System', ['- By: ' ...
    'Tomoki Koike']})
hold on
plot(x2, y2, '--r')
hold off
grid on
grid minor
box on
legend('Star P1', 'Star P2')
```



<4d>

```
% Defining the position of the center of mass
x_c = (2*x1 + x2)/3; % x-positions
y_c = (2*y1 + y2)/3; % y-positions

% Plotting
figure('Renderer','painters',"Position",[20 20 900 600])
plot(x_c, y_c, '-b')
xlabel('x [m]')
ylabel('y [m]')
title({'4d: Motion of the Center Mass for a Binary Star System', ['- By:' ...
    'Tomoki Koike']})
grid on
grid minor
box on
```



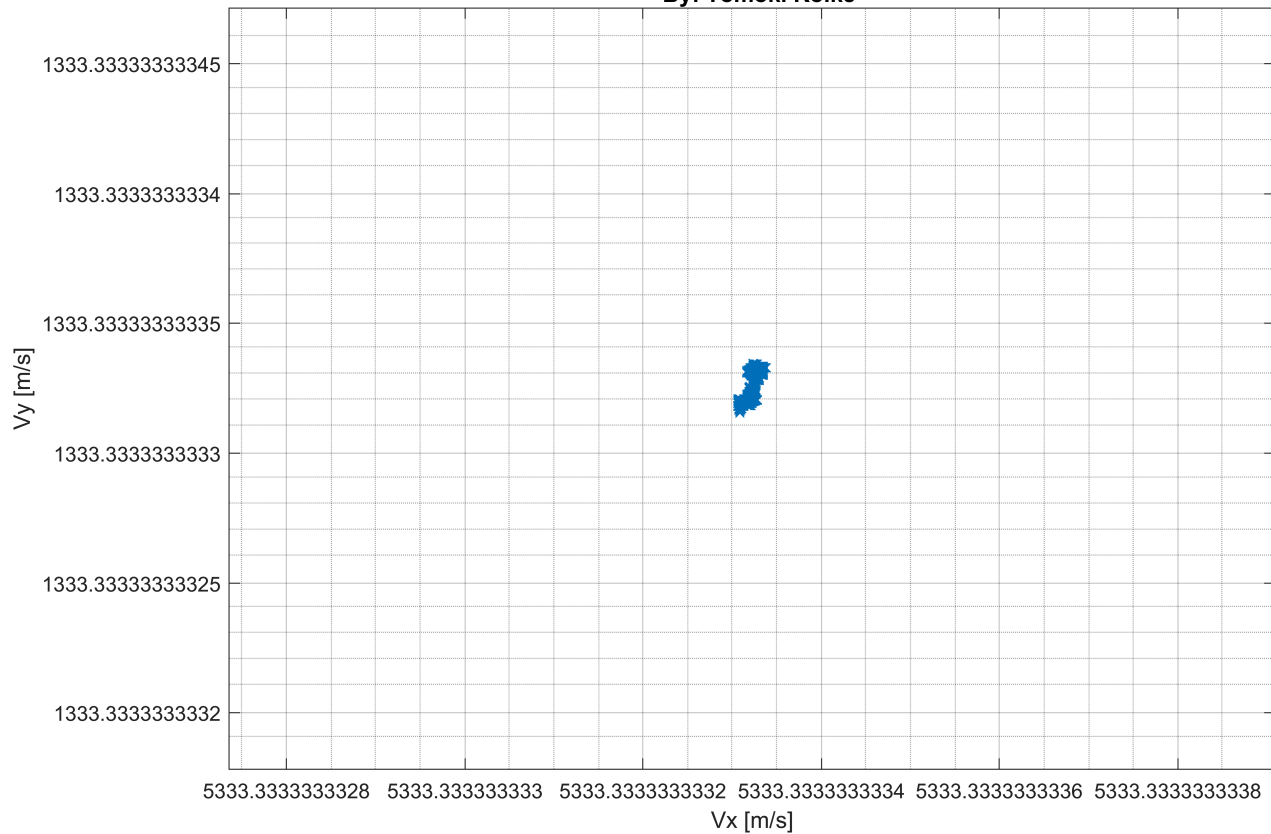
<4e>

```
% Defining the velocity vector of the center of mass
x_c_dot = (2*x1_dot + x2_dot)/3; % e1 direction
y_c_dot = (2*y1_dot + y2_dot)/3; % e2 direction

% Plotting
figure('Renderer','painters','Position',[20 20 900 600])
plot(x_c_dot, y_c_dot, 'x')
xlabel('Vx [m/s]')
ylabel('Vy [m/s]')
title({'4e: Velocity field of the Center of Mass for a Binary Star System', ['- ' ' ...
    'By: Tomoki Koike']})
grid on
grid minor
box on
```

4e: Velocity field of the Center of Mass for a Binary Star System

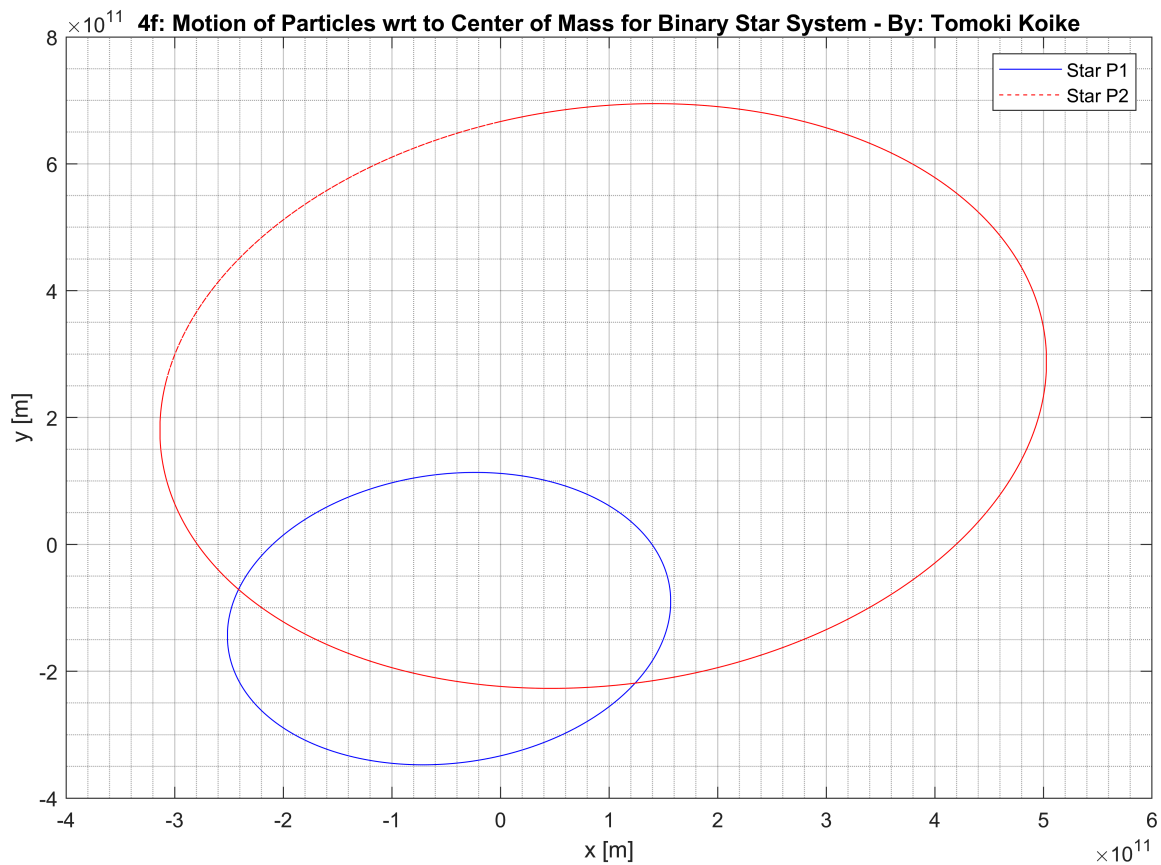
- By: Tomoki Koike



<4f>

```
% Defining the position of particles with respect to the center of mass
p1_x = x1 - x_c; % Particle 1 x position wrt to center of mass
p1_y = y1 - y_c; % Particle 1 y position wrt to center of mass
p2_x = x2 - x_c; % Particle 2 x position wrt to center of mass
p2_y = y2 - y_c; % Particle 2 y position wrt to center of mass

% Plotting
figure('Renderer','painters','Position',[20 20 900 600])
plot(p1_x, p1_y, '-b')
xlabel('x [m]')
ylabel('y [m]')
title({'4f: Motion of Particles wrt to Center of Mass for Binary Star' ...
    ' System', ' - By: Tomoki Koike'}})
hold on
plot(p2_x, p2_y, '--r')
hold off
grid on
grid minor
box on
legend('Star P1', 'Star P2')
```



Function

```
function dzdt = dfcn(t,z)
    % Defining constants
    m = 1.987*10^30; % Solar mass [kg]
    G = 6.673*10^(-11); % Gravitational constant [m^3/kg^2]

    dzdt = zeros(8,1); % Preallocate the derivative term vector
    % State variable forms
    dzdt(1) = z(5);
    dzdt(2) = z(6);
    dzdt(3) = z(7);
    dzdt(4) = z(8);
    dzdt(5) = (G*m*(z(3)-z(1))) / (2*((z(1)-z(3))^2 + (z(2)-z(4))^2)^(1.5));
    dzdt(6) = (G*m*(z(4)-z(2))) / (2*((z(1)-z(3))^2 + (z(2)-z(4))^2)^(1.5));
    dzdt(7) = (G*m*(z(1)-z(3))) / (((z(1)-z(3))^2 + (z(2)-z(4))^2)^(1.5));
    dzdt(8) = (G*m*(z(2)-z(4))) / (((z(1)-z(3))^2 + (z(2)-z(4))^2)^(1.5));
end
```