

JS BP

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11:47 PM

## Orbital Maneuvers

relative  
2 BP

Thus far, only consider orbit characteristics

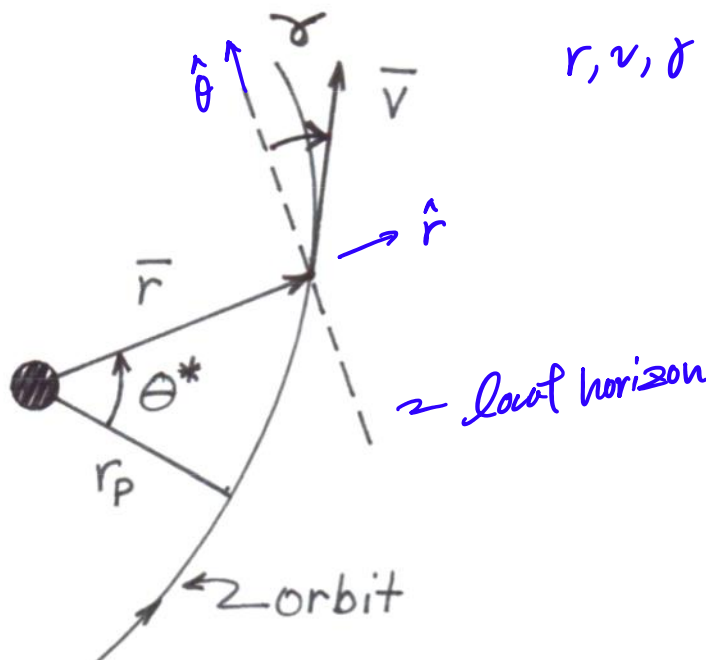
But, artificial satellites change orbits  $\longrightarrow$  consider maneuvers and estimate velocity changes required for particular mission objectives

Discussion:

1. Orbit establishment ✓
2. Single impulse adjustments ✓
3. Transfers ✓

### 1. Orbit Establishment

Relating position/velocity to orbit characteristics



$$\vec{v} = \underbrace{v_{sr}}_{v_r} \hat{r} + \underbrace{v_{ct}}_{v_\theta} \hat{\theta}$$

$r, v, \gamma$  characterize orbit (in orbit plane)

Known:  $\vec{h} = \vec{r} \times \vec{v} \Rightarrow h = rv_\theta \quad h = r \underbrace{v \cos \gamma}_{v_\theta}$

$$v_\theta = \frac{h}{r} = \frac{\mu}{h} (1 + e \cos \theta^*)$$

(JS.1)

$$v_r = \dot{r} = \frac{dr}{d\theta} \dot{\theta} = \left( \frac{dr}{d\theta} \right) \frac{h}{r^2} \quad v_r = v \sin \gamma$$

$$= \frac{d}{d\theta} \left( \frac{h^2/\mu}{1 + e \cos(\theta - \omega)} \right) \frac{h}{r^2}$$

$$v_r = \frac{\mu e}{h} \sin \theta^*$$

(JS.2)

Rearrange (JS.1) and (JS.2)

$$e \cos \theta^* = \frac{h v_\theta}{\mu} - 1$$

$$e \sin \theta^* = \frac{h v_r}{\mu} = \frac{r v_\theta v_r}{\mu}$$

$$e^2 = \left[ (e \cos \theta^*)^2 + (e \sin \theta^*)^2 \right]$$

$$= \left( \frac{h v \cos \gamma}{\mu} - 1 \right)^2 + \frac{r^2 v^2 (\cos^2 \gamma) v^2 (\sin^2 \gamma)}{\mu^2}$$

$$= \frac{r^2 v^4 (\cos^4 \gamma)}{\mu^2} - \frac{2 r v^2 \cos^2 \gamma}{\mu} + 1 + \frac{r^2 v^4 (\cos^2 \gamma) (\sin^2 \gamma)}{\mu^2}$$

$$\sin^2 \gamma + \cos^2 \gamma$$

$$1 - \cos^2 \gamma$$

un known in

no change in  $r$

JS3

change  $v \rightarrow$  how to keep  $e$  a constant

$$e^2 = \left( \frac{rv^2}{\mu} - 1 \right)^2 \cos^2 \gamma + \sin^2 \gamma$$

(JS.3)

$$\tan \theta^* = \frac{rv_\theta v_r / \mu}{\frac{h v_\theta}{\mu} - 1} = \frac{rv^2 \sin \gamma \cos \gamma}{\mu \left( \frac{rv^2 \cos^2 \gamma}{\mu} - 1 \right)}$$

$$\tan \theta^* = \frac{\sin \theta^*}{\cos \theta^*}$$

$$\tan \theta^* = \frac{\left( \frac{rv^2}{\mu} \right) \cos \gamma \sin \gamma}{\left( \frac{rv^2}{\mu} \right) \cos^2 \gamma - 1}$$

(JS.4)

$r, v, \gamma \rightarrow$  define other orbital parameters

## 2. Single Impulse Adjustments

Use a single impulse to adjust / change an orbit:

- Eliminate launch errors
  - Bring s/c to a more desirable orbit
  - Planned correction maneuvers
- limited

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·  
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Note: Transfer to a new orbit with a single impulse is not possible unless the new orbit intersects the original orbit

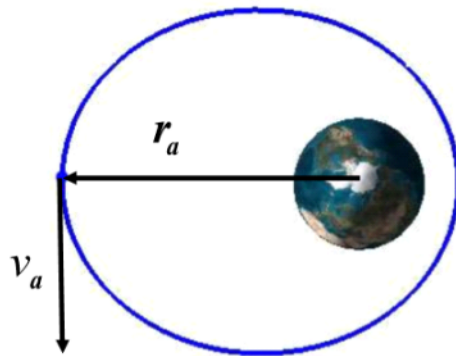
→ must intersect!

Assume: only in plane changes  
impulsive thrust applications

thrust possible in any directions

### Example 1

Satellite in an established Earth orbit:  $a = 3R_{\oplus}$   $e = .5$  ( $r_p = 1.5R_{\oplus}$ )



Goal to change orbit subject to:

$e$  constant

$$a_N = 4R_{\oplus}$$

$\Delta v$  (thrust) must be applied at apogee

Determine magnitude and direction of  $\Delta \vec{v}$  to accomplish goal

Solution

- (a) Current orbit already established  *$a, e$  in plane  $\rightarrow r, v, \delta$*   
 (b) Conditions at thrust point before maneuver/thrust

$$r_a = a(1 + e) = 4.5R_{\oplus}$$

$$\frac{v_a^2}{2} = \frac{\mu_{\oplus}}{r_a} - \frac{\mu_{\oplus}}{2a} \Rightarrow v_a = 2.64 \text{ km/s}$$

$$\delta = 0^\circ$$

$$\theta^* = 180^\circ$$

Note: to increase  $a$ , likely requires increase in  $v$

$$\frac{v^2}{2} = \frac{\mu}{r} - \frac{\mu}{2a}$$

*same*  
 $r^- = r^+$

$a \uparrow$  term  $-\frac{\mu}{2a}$  becomes  
 less negative  
 RHS  $\uparrow$



← away from Earth  
q is +

→ q is -

JS7

Cosine Law

$$\Delta v^2 = v_N^2 + v_a^2 - 2v_N v_a \cos \Delta \gamma_N$$

OR

$$\Delta v = \left[ v_N^2 + v_a^2 - 2v_N v_a \cos \Delta \gamma_N \right]^{1/2}$$

$$\Delta v = 1.75 \text{ km/s}$$

At angle  $\alpha$  wrt initial velocity

Sine law or geometry

$$\alpha = 76^\circ$$

$$r^+ = r^-$$

$$v^+, \sigma^+$$

Know  $r_N, v_N, \gamma_N \rightarrow \theta_N^* = \tan^{-1} \left\{ \frac{\left( \frac{rv^2}{\mu} \right) \cos \gamma \sin \gamma}{\left( \frac{rv^2}{\mu} \right) \cos^2 \gamma - 1} \right\}$

$$\theta^{*+} = \theta_N^* = -46.4^\circ \text{ OR } +131.6^\circ$$

which one?

$$j^+ > 0 \Rightarrow \theta_N^* = +131.6^\circ$$

How do I know the quadrant??

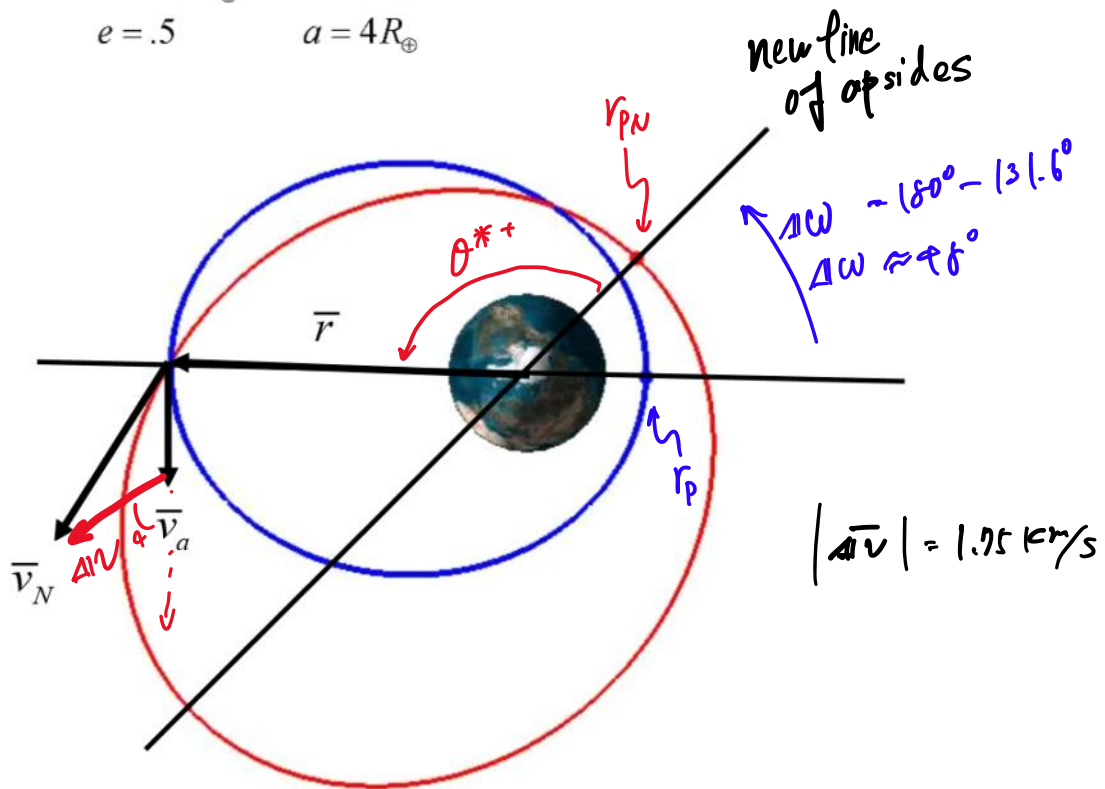


Originally  $\theta^* = 180^\circ \rightarrow$  Now  $\theta^* = 131.6^\circ$

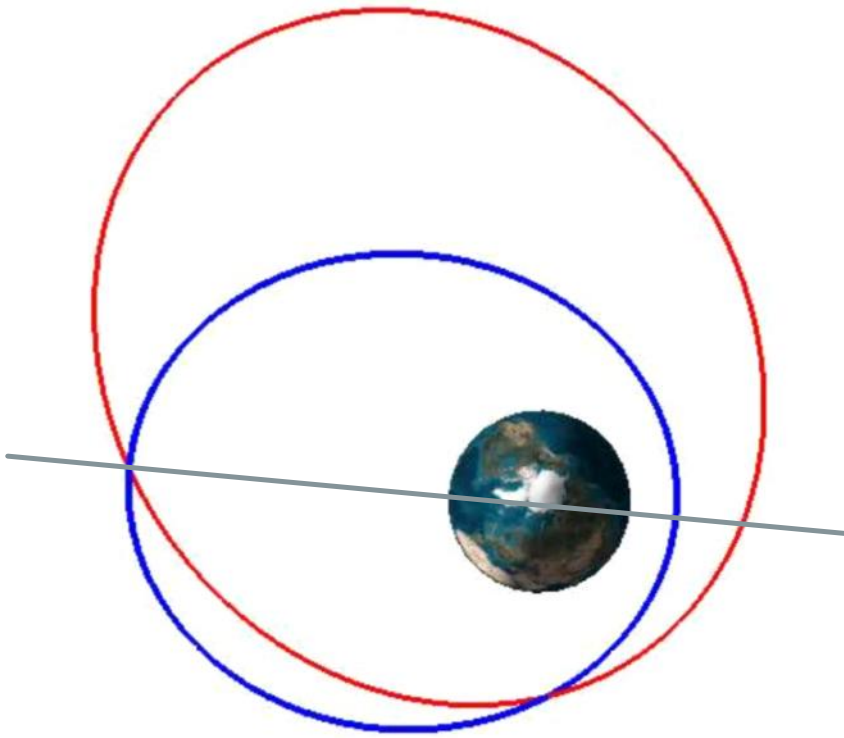
New orbit:

$$r = 4.5R_\oplus \quad v = 3.49 \text{ km/s}$$

$$e = .5 \quad a = 4R_\oplus$$

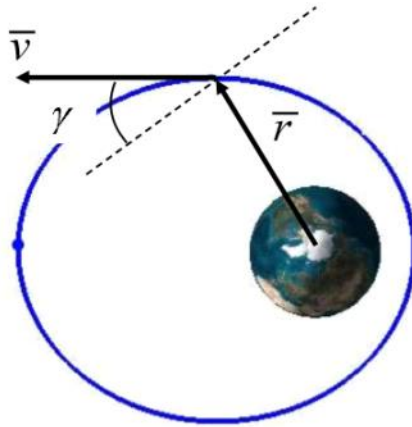


If  $\Delta\gamma = -29.23^\circ$  ← enter new orbit in descending part of the orbit.



Can same be accomplished for lower cost?  
Put maneuver in a different location?

Currently:  $a = 3R_{\oplus}$   $e = .5$  ( $r_p = 1.5R_{\oplus}$ )



Maneuver at  $\theta^* = 120^\circ$   
 $e_N = e = .5$  constant  
 $a_N = 4R_{\oplus}$

Solution

- (a) Current orbit already established
- (b) Conditions at thrust point before maneuver/thrust

$$r = 3R_{\oplus} \rightarrow r = a \Rightarrow \text{end of minor axis}$$

$$v = 4.5642 \text{ km/s}$$

$$\gamma = 30^\circ \text{ ascending}$$

Consider how to accomplish objective –  
Increase/decrease velocity?

$$\frac{v^2}{2} = \frac{\cancel{\mu}}{\cancel{r}} - \frac{\mu}{2a} \Rightarrow a \uparrow v \uparrow$$

Is a tangential  $\Delta v$  possible?

$$e^2 = \left( \frac{rv^2}{\mu} - 1 \right)^2 \cos^2 \gamma + \sin^2 \gamma \Rightarrow \text{cannot keep } e \text{ const. unless change } \delta$$

$\uparrow$   
 no change

(c) Desired conditions after maneuver

$$r_N = r_a = 3R_{\oplus}$$

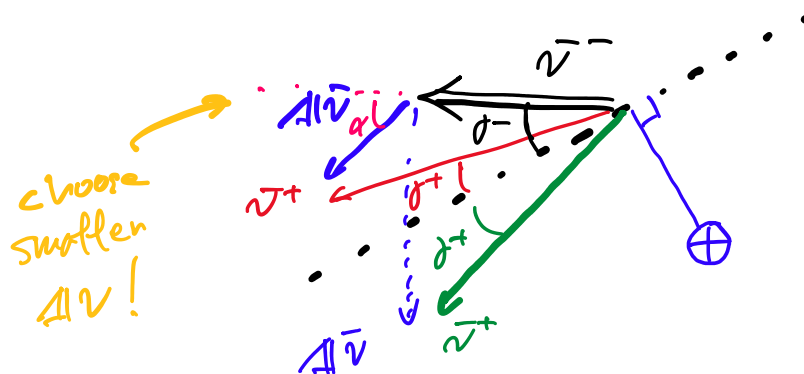
$$v^+ = v_N = 5.103 \text{ km/s}$$

$$a_N = 4R_{\oplus} \quad e = .5$$

$$h = r v C_{\theta} \quad \leftarrow \pm$$

(d) Vector diagram

Sketch a vector diagram of the situation



Cosine Law

$$\Delta v^2 = v_N^2 + v_a^2 - 2v_N v_a \cos \Delta \gamma_N$$

$$\Delta v = 0.6115 \text{ km/s}$$

Sine Law

$$\frac{\Delta v}{\sin \Delta \gamma} = \frac{v_N}{\sin \beta} \Rightarrow \beta = 150^\circ$$

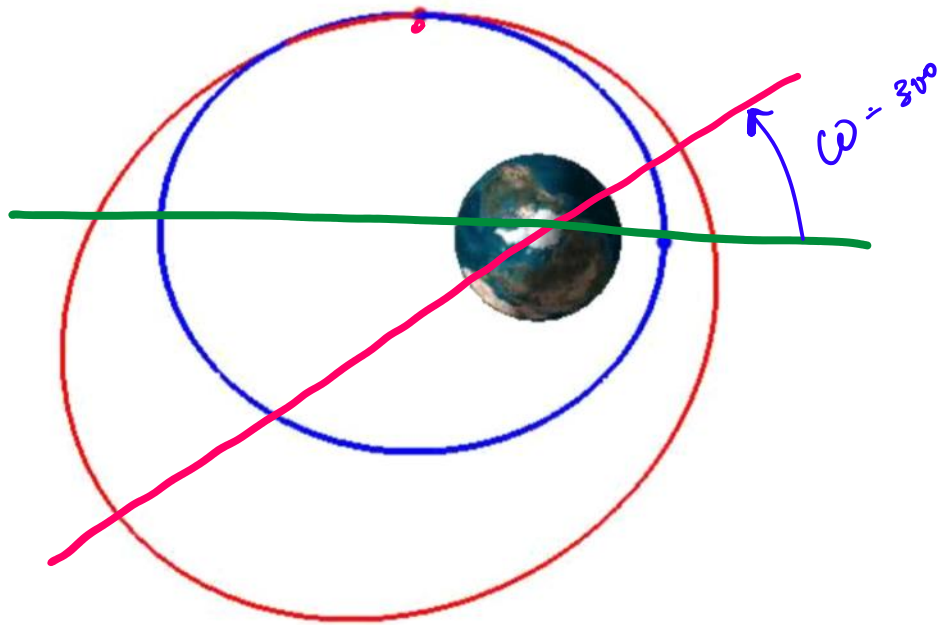
$$\theta = -30^\circ$$

$$\uparrow$$

$$r^+, v^+, \theta^+ \Rightarrow \theta^* = \pm 90^\circ (?)$$

we  $\gamma^+ > 0$   $\theta^{*+}$  ascending

$$\Delta\omega = \theta_o^* - \theta_N^* \approx +30^\circ$$



**Example**

At a certain instant, an Earth observing satellite is described in terms of the following state

$$\begin{aligned} r &= 1.65R_{\oplus} \\ v &= 5.7 \text{ km/s} \\ \gamma &= -10.2^\circ \end{aligned}$$

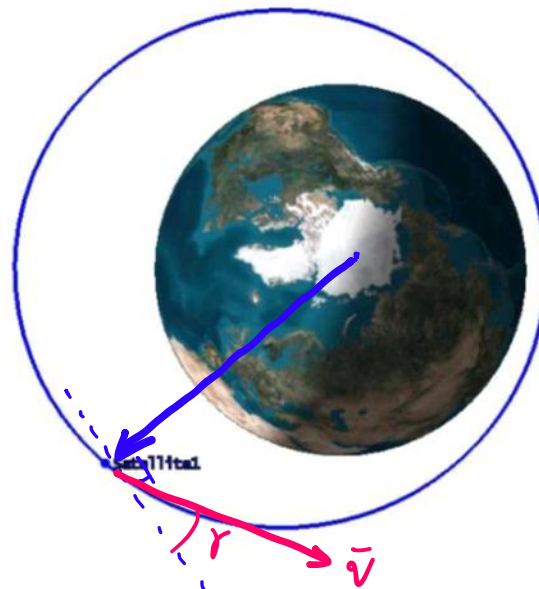
At this point, a maneuver such that  $\Delta v = 1.2 \text{ km/s}$  and  $\alpha = +25^\circ$ . Determine the final orbit.

Solution:

(a) Establish current orbit / current location

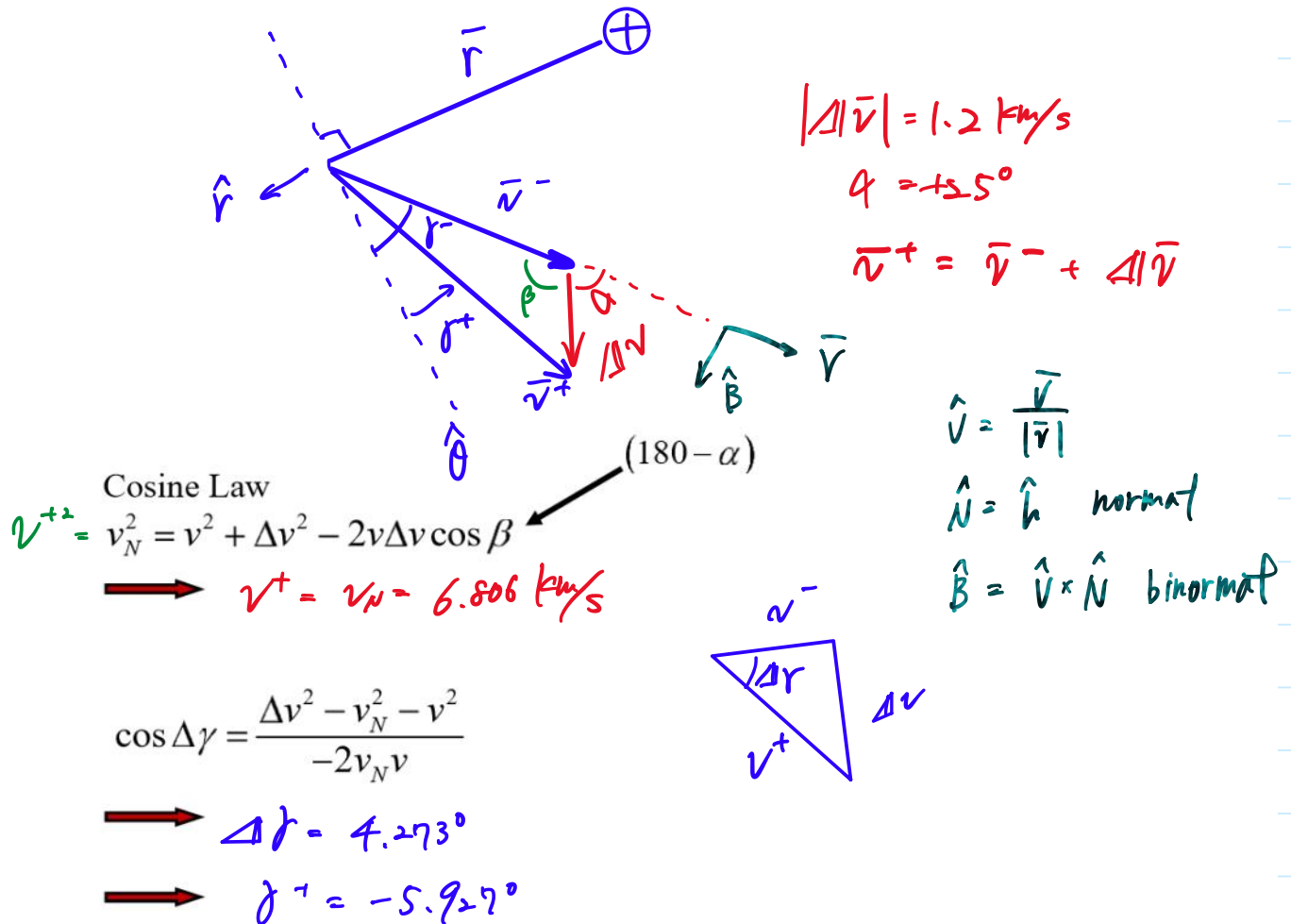
$$\begin{aligned} a &= 1.4446R_{\oplus} & E &= -129.05^\circ \\ e &= .22571 & \theta^* &= -138.52^\circ \\ r_p &= 1.1185R_{\oplus} & IP &= 2.4449 \text{ hr} = .10187 \text{ da} \\ r_a &= 1.7710R_{\oplus} & (t - t_p) &= -.80823 \text{ hr} \end{aligned}$$

(b) Conditions immediately prior to maneuver are given



Add  $\Delta \vec{v}$ :  
 $|\Delta \vec{v}| = 1.2 \text{ km/s}$   
 $\alpha = +25^\circ$

(c) Conditions immediately after the impulse



(d) Establish the new orbit

$$\begin{aligned}
 a^+ &= a_N = 2.124 R_\oplus \\
 e^+ &= e_N = 0.2448 \\
 r_p^+ &= r_{pN} = 1.6496 R_\oplus
 \end{aligned}$$

$$\begin{aligned}
 E^+ &= E_N = -24.76^\circ \\
 \theta^+ &= \theta_N^* = -30.814^\circ
 \end{aligned}$$

