AAE 666 Spring 2021

Homework Five

Due: Friday, February 26

Exercise 1 Using linearization, determine (if possible) the stability properties of the following system about the zero solution.

$$\frac{d^4q}{dt^4} - \sin(q) = 0.$$

If not possible, explain why.

Exercise 2 Using linearization, determine (if possible) the stability properties of the following system about the zero solution.

$$\ddot{q} + \dot{q} - q^3 = 0$$

If not possible, explain why.

Exercise 3 If possible, use linearization to determine the stability properties of each of the following systems about the zero equilibrium state.

(i)

$$\dot{x}_1 = (1 + x_1^2)x_2
\dot{x}_2 = -x_1^3$$

(ii)

$$\dot{x}_1 = \sin x_2
\dot{x}_2 = (\cos x_1)x_3
\dot{x}_3 = e^{x_1}x_2$$

Exercise 4 If possible, use linearization to determine the stability properties of the following system about the zero equilibrium state.

$$x_1(k+1) = x_1(k)^2 + \sin(x_2(k))$$

 $x_2(k+1) = 0.4 \cos(x_2(k)) x_1(k)$

Exercise 5 If possible, use linearization to determine the stability properties of the following system about the zero equilibrium state.

$$x_1(k+1) = (1+x_1(k)^3)x_2(k)$$

 $x_2(k+1) = x_1(k)^3 + x_2(k)^5$

Exercise 6 If possible, use linearization to determine the stability properties of the following system about the zero equilibrium state.

$$x_1(k+1) = x_2(k)$$

 $x_2(k+1) = \sin(x_1(k)) + x_2(k)^5$

Exercise 7 Recall the Lorenz system

$$\dot{x}_1 = \sigma(x_2 - x_1)
\dot{x}_2 = rx_1 - x_2 - x_1x_3
\dot{x}_3 = -bx_3 + x_1x_2$$

with $\sigma, r, b > 0$. Prove that all solutions of this system are bounded. (Hint: Consider $V(x) = rx_1^2 + \sigma x_2^2 + \sigma (x_3 - 2r)^2$.)