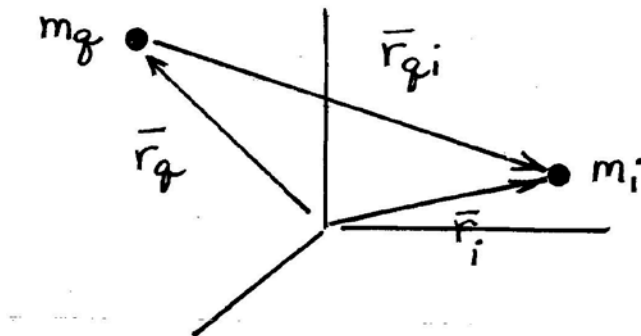


n – Body Problem

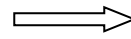
Problem: only 10 integrals of motion
12 are required to solve the 2BP

Observation: Do we really care about



We really want to know how it moves
relative to some other point such as

\oplus ; \odot



Redo the problem:

How to get the EOM governing \bar{r}_{qi} ? ($\ddot{\bar{r}}_{qi}$)

For any acceleration
still necessary to consider

To apply Newton's Law of Motion MUST differentiate in inertial frame and
base point of the position vector must be fixed in that frame

→ CANNOT use $\bar{F} = m \bar{A}$ directly with \bar{r}_{qi}

But \bar{r}_{qi} can be written in terms of appropriate vectors

$$\begin{aligned}\bar{r}_i &= \bar{r}_{qi} + \bar{r}_q \\ \ddot{\bar{r}}_i &= \ddot{\bar{r}}_{qi} + \ddot{\bar{r}}_q\end{aligned}$$

Apply Newton's law of motion validly to \bar{r}_i and \bar{r}_q

$$\begin{aligned}\ddot{\bar{r}}_i &= -G \sum_{\substack{j=1 \\ j \neq i}}^n \frac{m_j}{r_{ji}^3} \bar{r}_{ji} \\ \ddot{\bar{r}}_q &= -G \sum_{\substack{j=1 \\ j \neq q}}^n \frac{m_j}{r_{jq}^3} \bar{r}_{jq}\end{aligned}$$

Sub into $\ddot{\bar{r}}_{qi} + \ddot{\bar{r}}_q = \ddot{\bar{r}}_i$



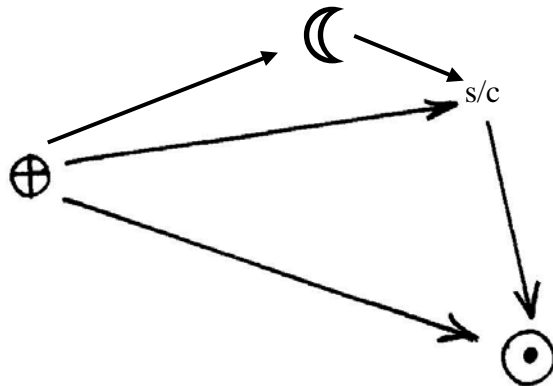
$$\ddot{\bar{r}}_{qi} - \underbrace{G \sum_{\substack{j=1 \\ j \neq q}}^n \frac{m_j}{r_{jq}^3} \bar{r}_{jq}}_{\text{remove } i \text{ term}} = - \underbrace{G \sum_{\substack{j=1 \\ j \neq i}}^n \frac{m_j}{r_{ji}^3} \bar{r}_{ji}}_{\text{remove } q \text{ term}} \quad \leftarrow \text{Note: only relative positions appear}$$

$$\ddot{\bar{r}}_{qi} - G \frac{m_i}{r_{iq}^3} \bar{r}_{iq} - \underbrace{G \sum_{\substack{j=1 \\ j \neq i, q}}^n \frac{m_j}{r_{jq}^3} \bar{r}_{jq}}_{\text{move to right}} = \underbrace{-G \frac{m_q}{r_{qi}^3} \bar{r}_{qi}}_{\text{move to left}} - G \sum_{\substack{j=1 \\ j \neq i, q}}^n \frac{m_j}{r_{ji}^3} \bar{r}_{ji}$$

Equation for motion of m_i relative to m_q :



Example: \oplus \odot \mathbb{C} s/c



How does s/c move
relative to \oplus ?

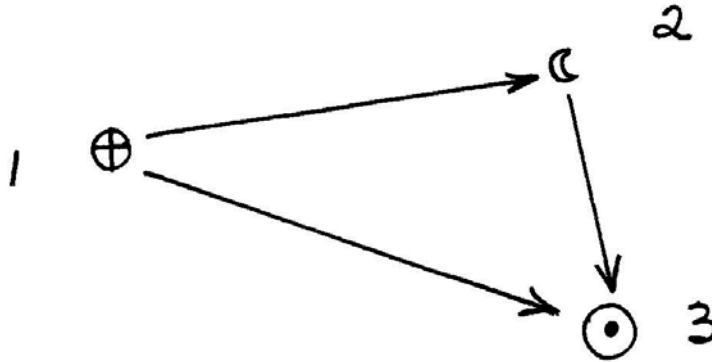
Motion of mass 2 relative
to mass 1; perturbed
by masses 3,4

$\therefore q =$ $i =$ $j =$

$$\ddot{\bar{r}}_{12} + G \underbrace{\frac{(m_1 + m_2)}{r_{12}^3}} \bar{r}_{12} = G m_3 \left(\underbrace{\frac{\bar{r}_{23}}{r_{23}^3}} - \underbrace{\frac{\bar{r}_{13}}{r_{13}^3}} \right) + G m_4 \left(\frac{\bar{r}_{24}}{r_{24}^3} - \frac{\bar{r}_{14}}{r_{14}^3} \right)$$

$$\ddot{\bar{r}}_{\oplus s/c} + G \frac{(m_{\oplus} + m_{s/c})}{r_{\oplus s/c}^3} \bar{r}_{\oplus s/c} = G m_{\odot} \left(\frac{\bar{r}_{s/c \odot}}{r_{s/c \odot}^3} - \frac{\bar{r}_{\oplus \odot}}{r_{\oplus \odot}^3} \right) + G m_{\mathbb{C}} \left(\frac{\bar{r}_{s/c \mathbb{C}}}{r_{s/c \mathbb{C}}^3} - \frac{\bar{r}_{\oplus \mathbb{C}}}{r_{\oplus \mathbb{C}}^3} \right)$$

Example: \oplus \odot \mathbb{C}



How does \mathbb{C} move relative to \oplus ?

Motion of mass 2 relative to mass 1;
perturbed by mass 3

$$\rightarrow \ddot{\bar{r}}_{12}$$

$$\therefore q=1 \quad i=2 \quad j=3$$

$$\ddot{\bar{r}}_{12} + \underbrace{G \frac{(m_1 + m_2)}{r_{12}^3}}_{\text{Keplerian}} \bar{r}_{12} = G m_3 \left(\underbrace{\frac{\bar{r}_{23}}{r_{23}^3}}_{\text{perturbation}} - \underbrace{\frac{\bar{r}_{13}}{r_{13}^3}}_{\text{perturbation}} \right)$$

$$\ddot{\bar{r}}_{\oplus\mathbb{C}} + G \frac{(m_{\oplus} + m_{\mathbb{C}})}{r_{\oplus\mathbb{C}}^3} \bar{r}_{\oplus\mathbb{C}} = G m_{\odot} \left(\frac{\bar{r}_{\mathbb{C}\odot}}{r_{\mathbb{C}\odot}^3} - \frac{\bar{r}_{\oplus\odot}}{r_{\oplus\odot}^3} \right)$$

Careful – indirect effects frequently forgotten but can be significant!!!

Given the equation of motion, do we now have an equation that we can solve?

⇒ Still can't solve if $n \geq 3$

$n = 3$: requires position of \odot relative to \oplus or \mathbb{C} ; an additional vector EOM is necessary



to solve two 2nd-order vector DE requires 12 integrals of the motion; we only know 10 !!

$n = 2$: no m_j perturbing bodies
a 2nd-order vector DE in only one unknown position vector!



6 scalar EOMs ; 6 dependent scalar variables ; requires only 6 integrals of motion (we have 10 !!)

→ Relative motion of two bodies solvable

$$\ddot{\vec{r}}_{12} + G \frac{(m_1 + m_2)}{r_{12}^3} \vec{r}_{12} = \vec{0} \quad \text{solvable but nontrivial}$$

OR

$$\ddot{\vec{r}} + \frac{\mu}{r^3} \vec{r} = \vec{0} \quad \text{where} \quad \mu = G(m_1 + m_2)$$