

## HOMEWORK NINE

**Exercise 1** Obtain the describing function of the nonlinear function

$$\phi(y) = y^5$$

**Exercise 2** Determine whether or not the following Duffing system has a periodic solution. Determine the approximate amplitude and period of all periodic solutions.

$$\ddot{y} - y + y^3 = 0$$

**Exercise 3** Determine whether or not the following system has a periodic solution. Determine the approximate amplitude and period of all periodic solutions.

$$\ddot{y} + \mu(\dot{y}^3/3 - \dot{y}) + y = 0$$

where  $\mu$  is a positive real number.

**Exercise 4** Use the describing function method to predict period solutions to

$$\dot{x}(t) = -x(t) - 2 \operatorname{sgm}(x(t-h))$$

Illustrate your results with numerical simulations.

**Exercise 5** Consider the double integrator

$$\ddot{q} = u$$

subject to a saturating PID controller

$$u = -k_P q - k_D \dot{q} - \operatorname{sat}(\tilde{u}) \quad \text{where} \quad \tilde{u} = k_I \int q$$

- (a) For  $k_P = 1$  and  $k_D = 2$  determine the largest of  $k_I \geq 0$  for which the closed loop system is asymptotically stable about  $q(t) \equiv 0$ .
- (b) For  $k_P = 1$  and  $k_D = 2$ , use the describing function method to determine the smallest value  $k_I \geq 0$  for which the closed loop system has a periodic solution.