

# COLLEGE OF ENGINEERING SCHOOL OF AEROSPACE ENGINEERING

AE 6705: Introduction to Mechatronics

# LAB1

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# Table of Contents

1	Question 1	2
2	Question 2	2
3	Question 3	2
4	Question 4	3

### Question 1

#### **Solution:**

We are given that

$$R_f = 4k\Omega, \quad R_g = 1k\Omega.$$

We also know that the resistance of the resistor at the non-inverting terminal is computed as the equivalent resistance of the parallel combination of resistors involved in the feedback path  $(R - f \text{ and } R_g)$ . Thus,

$$\frac{1}{R_{in}} = \frac{1}{R_f} + \frac{1}{R_g}$$

$$\frac{1}{R_{in}} = \frac{1}{4000} + \frac{1}{1000}$$

$$\frac{1}{R_{in}} = \frac{5}{4000}$$

Hence,

$$R_{in} = 800\Omega$$

# Question 2

#### **Solution:**

Let one of the resistors have the resistance of  $R_1 = 700\Omega$ . With the formula for the voltage divider we can compute the other resistance,  $R_2$  to be

$$5 = \frac{R_2}{700 + R_2} 12$$
$$5R_2 + 3500 = 12R_2$$
$$7R_2 = 3500$$

Hence,

$$R_1 = 700\Omega, \quad R_2 = 500\Omega$$

## Question 3

#### **Solution:**

If  $R_g = 1k\Omega$  and if the sensor amplifier requires a gain of 10, we can compute the other resistance,  $R_f$  in the following way.

$$10 = 1 + \frac{R_f}{R_g}$$
$$10 = 1 + \frac{R_f}{1000}$$
$$\frac{R_f}{1000} = 9$$

Hence,

$$R_g = 1k\Omega, \quad R_f = 9k\Omega$$

### Question 4

#### **Solution:**

The temperature sensor is designed to have  $10mV/^{\circ}F$ . If 0.4V corresponds to  $10^{\circ}F$  which is an output of 100mV from the sensor, we can compute the gain to be

$$G=4.$$

If the MCU reads the voltage in the range of 400mV to 5V, we can tell that the range for the sensor's voltage output will be the range divided by the gain of 4. Hence, the range of 100mV to 1025mV. Since the sensor reads  $10mV/^{\circ}F$ , we know that the temperature range that can be measured by the MCU is