

PORTADA

INTEGRANTES =

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ESPECIFICACIONES =

< CFGLR- ϵ > \rightarrow C

< Rules > \rightarrow Ru

< Productions > \rightarrow P

< RHS > \rightarrow RH

< Terminal > \rightarrow T

< No Terminal > \rightarrow NT

EOF \rightarrow *

, \rightarrow \diamond

Caracter Minúscula \rightarrow Mi

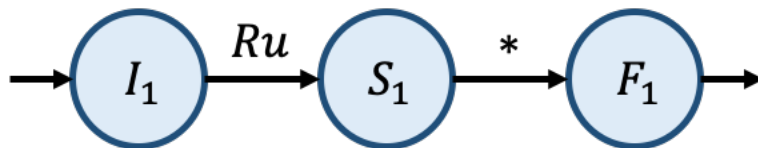
Caracter Mayúscula \rightarrow Ma

INDICE =

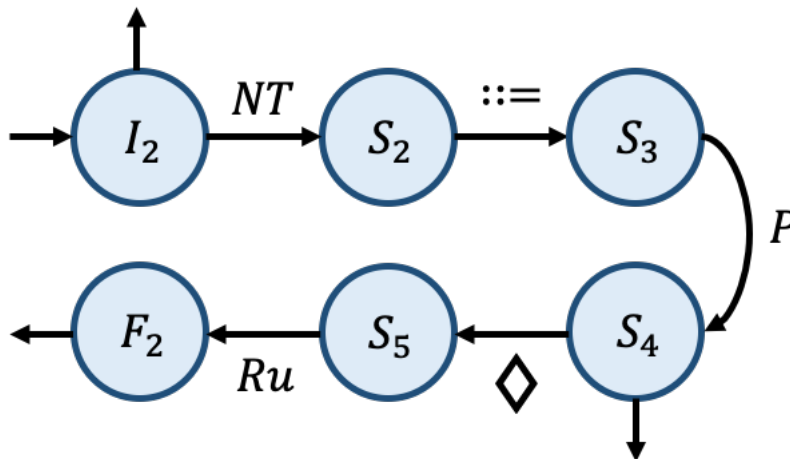
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RED DE AUTOMATAS

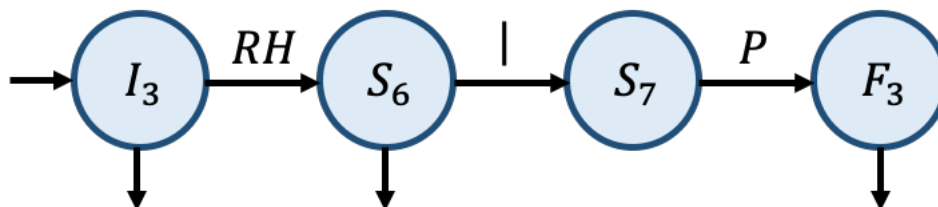
$M_C :$



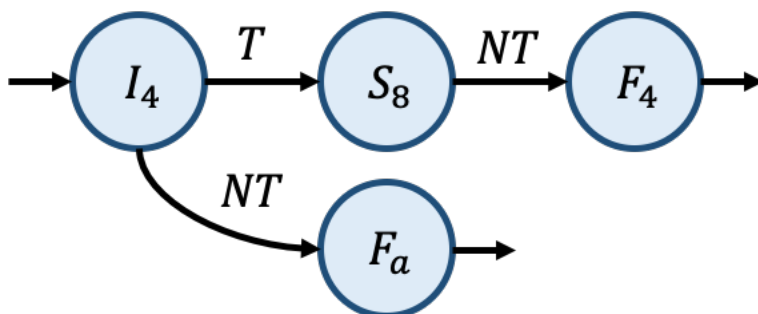
$M_{Ru} :$



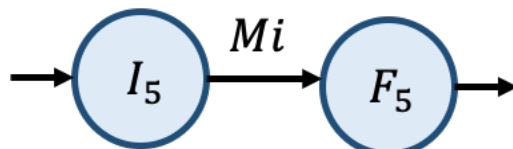
$M_P :$



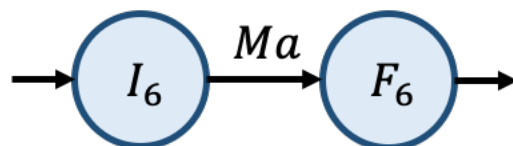
$M_{RH} :$



$M_T :$



$M_{NT} :$



CLAUSURAS

$$Clau(I_1) = \{I_1 - I_2 - I_6\}$$

$$Clau(S_1) = \{S_1\}$$

$$Clau(F_1) = \{F_1\}$$

$$Clau(I_2) = \{I_2 - I_6\}$$

$$Clau(S_2) = \{S_2\}$$

$$Clau(S_3) = \{S_3 - I_3 - I_4 - I_5 - I_6\}$$

$$Clau(S_4) = \{S_4\}$$

$$Clau(S_5) = \{S_5 - I_2 - I_6\}$$

$$Clau(F_2) = \{F_2\}$$

$$Clau(I_3) = \{I_3 - I_4 - I_5 - I_6\}$$

$$Clau(S_6) = \{S_6\}$$

$$Clau(S_7) = \{S_7 - I_3 - I_4 - I_5 - I_6\}$$

$$Clau(F_3) = \{F_3\}$$

$$Clau(I_4) = \{I_4 - I_5 - I_6\}$$

$$Clau(S_8) = \{S_8 - I_6\}$$

$$Clau(F_4) = \{F_4\}$$

$$Clau(F_a) = \{F_a\}$$

$$Clau(I_5) = \{I_5\}$$

$$Clau(F_5) = \{F_5\}$$

$$Clau(I_6) = \{I_6\}$$

$$Clau(F_6) = \{F_6\}$$

FUNCION SIN_NOMBRE

MAQUINA PILOTO LR(0)

$$\begin{aligned}\vartheta(Q_0, Ru) &= Clau[(I_1 - Ru), (I_2 - Ru), (I_6 - Ru)] \\ &= Clau[(I_1 - Ru)] = Clau[S_1] \\ &= S_1 \rightarrow Q_1\end{aligned}$$

$$\begin{aligned}\vartheta(Q_0, NT) &= Clau[(I_1 - NT), (I_2 - NT), (I_6 - NT)] \\ &= Clau[(I_2 - NT)] = Clau[S_2] \\ &= S_2 \rightarrow Q_2\end{aligned}$$

$$\begin{aligned}\vartheta(Q_0, Ma) &= Clau[(I_1 - Ma), (I_2 - Ma), (I_6 - Ma)] \\ &= Clau[(I_6 - Ma)] = Clau[F_6] \\ &= F_6 \rightarrow Q_3\end{aligned}$$

$$\vartheta(Q_1, *) = Clau[F_1] = F_1 \rightarrow Q_4$$

$$\begin{aligned}\vartheta(Q_2, ::=) &= Clau[S_3] \\ &= \{S_3 - I_3 - I_4 - I_5 - I_6\}\end{aligned}$$

“No podemos continuar con este método ya que al llegar a la clausura de S_3 nos damos cuenta que tiene mas de un estado lo que incumple con la condición de $LR(0)$ ”

MAQUINA PILOTO $LR(1) \circ LALR(1)$

$$Q_0 = \{ \langle I_1 - * \rangle , \langle I_2 - * \rangle , \langle I_6 - ::= \rangle \}$$

$$\begin{aligned} \vartheta(Q_0, Ru) &= Clau[\langle \delta(I_1, Ru) - \neg \rangle , \langle \delta(I_2, Ru) - * \rangle , \langle \delta(I_6, Ru) - ::= \rangle] \\ &= Clau[\langle S_1 - \neg \rangle] \\ &= \langle S_1 - * \rangle \rightarrow Q_1 \end{aligned}$$

$$\begin{aligned} \vartheta(Q_0, NT) &= Clau[\langle \delta(I_1, NT) - \neg \rangle , \langle \delta(I_2, NT) - * \rangle , \langle \delta(I_6, NT) - ::= \rangle] \\ &= Clau[\langle S_2 - * \rangle] \\ &= \langle S_2 - * \rangle \rightarrow Q_2 \end{aligned}$$

$$\begin{aligned} \vartheta(Q_0, Ma) &= Clau[\langle \delta(I_1, Ma) - \neg \rangle , \langle \delta(I_2, Ma) - * \rangle , \langle \delta(I_6, Ma) - ::= \rangle] \\ &= Clau[\langle F_6 - ::= \rangle] \\ &= \langle F_6 - ::= \rangle \rightarrow Q_3 \end{aligned}$$

$$Q_1 = \{ \langle S_1 - * \rangle \}$$

$$\begin{aligned} \vartheta(Q_1, *) &= Clau[\langle \delta(S_1, *) - * \rangle] \\ &= Clau[\langle F_1 - * \rangle] \\ &= \langle F_1 - * \rangle \rightarrow Q_4 \end{aligned}$$

$$Q_2 = \{ \langle S_2 - * \rangle \}$$

$$\begin{aligned} \vartheta(Q_2, ::=) &= Clau[\langle \delta(S_2, ::=) - * \rangle] \\ &= Clau[\langle S_3 - * \rangle] \\ &= \langle S_3 - * \rangle \rightarrow Q_5 \end{aligned}$$

MAQUINA PILOTO $LR(1) \circ LALR(1)$

$$Q_5 = \{ \langle S_3 - * \rangle, \langle I_3 - \{ \diamond, * \} \rangle, \langle I_4 - \{ |, \diamond, * \} \rangle, \langle I_5 - Ma \rangle, \langle I_6 - \{ |, \diamond, * \} \rangle \}$$

$$\vartheta(Q_5, P) = Clau \left[\begin{array}{l} \langle \delta(S_3, P) - * \rangle, \langle \delta(I_3, P) - \{ \diamond, * \} \rangle, \\ \langle \delta(I_4, P) - \{ |, \diamond, * \} \rangle, \langle \delta(I_5, P) - Ma \rangle, \\ \langle \delta(I_6, P) - \{ |, \diamond, * \} \rangle \end{array} \right]$$

$$= Clau[\langle S_4 - * \rangle]$$

$$= \langle S_4 - * \rangle \rightarrow Q_6$$

$$\vartheta(Q_5, RH) = Clau \left[\begin{array}{l} \langle \delta(S_3, RH) - * \rangle, \langle \delta(I_3, RH) - \{ \diamond, * \} \rangle, \\ \langle \delta(I_4, RH) - \{ |, \diamond, * \} \rangle, \langle \delta(I_5, RH) - Ma \rangle, \\ \langle \delta(I_6, RH) - \{ |, \diamond, * \} \rangle \end{array} \right]$$

$$= Clau[\langle S_6 - \{ \diamond, * \} \rangle]$$

$$= \langle S_6 - \{ \diamond, * \} \rangle \rightarrow Q_7$$

$$\vartheta(Q_5, T) = Clau \left[\begin{array}{l} \langle \delta(S_3, T) - * \rangle, \langle \delta(I_3, T) - \{ \diamond, * \} \rangle, \\ \langle \delta(I_4, T) - \{ |, \diamond, * \} \rangle, \langle \delta(I_5, T) - Ma \rangle, \\ \langle \delta(I_6, T) - \{ |, \diamond, * \} \rangle \end{array} \right]$$

$$= Clau[\langle S_8 - \{ |, \diamond, * \} \rangle]$$

$$= \langle S_8 - \{ |, \diamond, * \} \rangle \rightarrow Q_8$$

$$\vartheta(Q_5, NT) = Clau \left[\begin{array}{l} \langle \delta(S_3, NT) - * \rangle, \langle \delta(I_3, NT) - \{ \diamond, * \} \rangle, \\ \langle \delta(I_4, NT) - \{ |, \diamond, * \} \rangle, \langle \delta(I_5, NT) - Ma \rangle, \\ \langle \delta(I_6, NT) - \{ |, \diamond, * \} \rangle \end{array} \right]$$

$$= Clau[\langle F_a - \{ |, \diamond, * \} \rangle]$$

$$= \langle F_a - \{ |, \diamond, * \} \rangle \rightarrow Q_9$$

MAQUINA PILOTO $LR(1) \circ LALR(1)$

$$\begin{aligned}
 \vartheta(Q_5, Ma) &= Clau \left[\begin{array}{l} \langle \delta(S_3, Ma) - * \rangle, \langle \delta(I_3, Ma) - \{ \diamond, * \} \rangle, \\ \langle \delta(I_4, Ma) - \{ |, \diamond, * \} \rangle, \langle \delta(I_5, Ma) - Ma \rangle, \\ \langle \delta(I_6, Ma) - \{ |, \diamond, * \} \rangle \end{array} \right] \\
 &= Clau[\langle F_6 - \{ |, \diamond, * \} \rangle] \\
 &= \langle F_6 - \{ |, \diamond, * \} \rangle \rightarrow Q_{10}
 \end{aligned}$$

$$\begin{aligned}
 \vartheta(Q_5, Mi) &= Clau \left[\begin{array}{l} \langle \delta(S_3, Mi) - * \rangle, \langle \delta(I_3, Mi) - \{ \diamond, * \} \rangle, \\ \langle \delta(I_4, Mi) - \{ |, \diamond, * \} \rangle, \langle \delta(I_5, Mi) - Ma \rangle, \\ \langle \delta(I_6, Mi) - \{ |, \diamond, * \} \rangle \end{array} \right] \\
 &= Clau[\langle F_5 - Ma \rangle] \\
 &= \langle F_5 - Ma \rangle \rightarrow Q_{11}
 \end{aligned}$$

$$Q_6 = \{ \langle S_4 - * \rangle \}$$

$$\begin{aligned}
 \vartheta(Q_6, \diamond) &= Clau[\langle \delta(S_4, \diamond) - * \rangle] \\
 &= Clau[\langle S_5 - * \rangle] \\
 &= \langle S_5 - * \rangle \rightarrow Q_{12}
 \end{aligned}$$

$$Q_7 = \{ \langle S_6 - \{ \diamond, * \} \rangle \}$$

$$\begin{aligned}
 \vartheta(Q_7, |) &= Clau[\langle \delta(S_6, |) - \{ \diamond, * \} \rangle] \\
 &= Clau[\langle S_7 - \{ \diamond, * \} \rangle] \\
 &= \langle S_7 - \{ \diamond, * \} \rangle \rightarrow Q_{13}
 \end{aligned}$$

MAQUINA PILOTO $LR(1) \circ LALR(1)$

$$Q_8 = \left\{ \langle S_8 - \{ |, \diamond, * \} \rangle, \langle I_6 - \{ |, \diamond, * \} \rangle \right\}$$

$$\begin{aligned} \vartheta(Q_8, NT) &= Clau[\langle \delta(S_8, NT) - \{ |, \diamond, * \} \rangle, \langle \delta(I_6, NT) - \{ |, \diamond, * \} \rangle] \\ &= Clau[\langle F_4 - \{ |, \diamond, * \} \rangle] \\ &= \langle F_4 - \{ |, \diamond, * \} \rangle \rightarrow Q_{14} \end{aligned}$$

$$\begin{aligned} \vartheta(Q_8, Ma) &= Clau[\langle \delta(S_8, Ma) - \{ |, \diamond, * \} \rangle, \langle \delta(I_6, Ma) - \{ |, \diamond, * \} \rangle] \\ &= Clau[\langle F_6 - \{ |, \diamond, * \} \rangle] \\ &= \langle F_6 - \{ |, \diamond, * \} \rangle \rightarrow Q_{10} \end{aligned}$$

$$Q_{12} = \left\{ \langle S_5 - * \rangle, \langle I_2 - * \rangle, \langle I_6 - ::= \rangle \right\}$$

$$\begin{aligned} \vartheta(Q_{12}, Ru) &= Clau[\langle \delta(S_5, Ru) - * \rangle, \langle \delta(I_2, Ru) - * \rangle, \langle \delta(I_6, Ru) - ::= \rangle] \\ &= Clau[\langle F_2 - * \rangle] \\ &= \langle F_2 - * \rangle \rightarrow Q_{15} \end{aligned}$$

$$\begin{aligned} \vartheta(Q_{12}, NT) &= Clau[\langle \delta(S_5, NT) - * \rangle, \langle \delta(I_2, NT) - * \rangle, \langle \delta(I_6, NT) - ::= \rangle] \\ &= Clau[\langle S_2 - * \rangle] \\ &= \langle S_2 - * \rangle \rightarrow Q_2 \end{aligned}$$

$$\begin{aligned} \vartheta(Q_{12}, Ma) &= Clau[\langle \delta(S_5, Ma) - * \rangle, \langle \delta(I_2, Ma) - * \rangle, \langle \delta(I_6, Ma) - ::= \rangle] \\ &= Clau[\langle F_6 - ::= \rangle] \\ &= \langle F_6 - ::= \rangle \rightarrow Q_3 \end{aligned}$$

MAQUINA PILOTO $LR(1) \circ LALR(1)$

$$Q_{13} = \left\{ \langle S_7 - \{ \diamond, * \} \rangle, \langle I_3 - \{ \diamond, * \} \rangle, \right. \\ \left. \langle I_4 - \{ |, \diamond, * \} \rangle, \langle I_5 - Ma \rangle, \langle I_6 - \{ |, \diamond, * \} \rangle \right\}$$

$$\vartheta(Q_{13}, P) = Clau \left[\begin{array}{l} \langle \delta(S_7, P) - \{ \diamond, * \} \rangle, \langle \delta(I_3, P) - \{ \diamond, * \} \rangle, \\ \langle \delta(I_4, P) - \{ |, \diamond, * \} \rangle, \langle \delta(I_5, P) - Ma \rangle, \\ \langle \delta(I_6, P) - \{ |, \diamond, * \} \rangle \end{array} \right]$$

$$= Clau[\langle F_3 - \{ \diamond, * \} \rangle]$$

$$= \langle F_3 - \{ \diamond, * \} \rangle \rightarrow Q_{16}$$

$$\vartheta(Q_{13}, RH) = Clau \left[\begin{array}{l} \langle \delta(S_7, RH) - \{ \diamond, * \} \rangle, \langle \delta(I_3, RH) - \{ \diamond, * \} \rangle, \\ \langle \delta(I_4, P) - \{ |, \diamond, * \} \rangle, \langle \delta(I_5, P) - Ma \rangle, \\ \langle \delta(I_6, P) - \{ |, \diamond, * \} \rangle \end{array} \right]$$

$$= Clau[\langle S_6 - \{ \diamond, * \} \rangle]$$

$$= \langle S_6 - \{ \diamond, * \} \rangle \rightarrow Q_7$$

$$\vartheta(Q_{13}, T) = Clau[\langle S_8 - \{ |, \diamond, * \} \rangle]$$

$$= \langle S_8 - \{ |, \diamond, * \} \rangle \rightarrow Q_8$$

$$\vartheta(Q_{13}, NT) = Clau[\langle F_a - | \{ |, \diamond, * \} \rangle]$$

$$= \langle F_a - \{ |, \diamond, * \} \rangle \rightarrow Q_9$$

$$\vartheta(Q_{13}, Ma) = Clau[\langle F_6 - \{ |, \diamond, * \} \rangle]$$

$$= \langle F_6 - \{ |, \diamond, * \} \rangle \rightarrow Q_{10}$$

$$\vartheta(Q_{13}, Mi) = Clau[\langle F_5 - Ma \rangle]$$

$$= \langle F_5 - Ma \rangle \rightarrow Q_{11}$$

TABLAS DE M. PILOTO

PARA HACER MAS SIMPLE EL AUTOMATA
PRIMERO HAREMOS LAS TABLAS Y LUEGO
DIBUJAMOS EL AUTOMATA COMO TAL.

Q_0	Regla	L.A.
I_1	$C \rightarrow \bullet Ru^*$	*
I_2	$Ru \rightarrow \bullet NT ::= P, R$ $\quad \bullet NT ::= P$ $\quad \bullet \epsilon$	*
I_6	$NT \rightarrow \bullet Ma$	$::=$

Q_1	Regla	L.A.
S_1	$C \rightarrow Ru \bullet *$	*

Q_2	Regla	L.A.
S_2	$Ru \rightarrow NT \bullet ::= P, R$ $\quad NT \bullet ::= P$ $\quad \epsilon \bullet$	*

Q_3	Regla	L.A.
F_6	$NT \rightarrow Ma \bullet$	$::=$

TABLAS DE M. PILOTO

Q_4	Regla	L.A.
F_1	$C \rightarrow Ru^* \bullet$	*

Q_5	Regla	L.A.
S_3	$Ru \rightarrow NT ::= \bullet P, R$ $ NT ::= \bullet P$ $ \epsilon \bullet$	*
I_3	$P \rightarrow \bullet RH P$ $ \bullet RH$ $ \bullet \epsilon$	$\diamond *$
I_4	$RH \rightarrow \bullet T NT$ $ \bullet NT$	$ \diamond *$
I_5	$T \rightarrow \bullet Mi$	Ma
I_6	$NT \rightarrow \bullet Ma$	$ \diamond *$

Q_6	Regla	L.A.
S_4	$Ru \rightarrow NT ::= P \bullet, R$ $ NT ::= P \bullet$ $ \epsilon \bullet$	*

TABLAS DE M. PILOTO

Q_7	Regla	L.A.
S_6	$P \rightarrow RH \bullet \mid P$ $\mid RH \bullet$ $\mid \epsilon \bullet$	$\diamond \quad *$

Q_8	Regla	L.A.
S_8	$RH \rightarrow T \bullet NT$ $\mid NT$	$\mid \diamond \quad *$
I_6	$NT \rightarrow \bullet Ma$	$\mid \diamond \quad *$

Q_9	Regla	L.A.
F_a	$RH \rightarrow T NT$ $\mid NT \bullet$	$\mid \diamond \quad *$

Q_{10}	Regla	L.A.
F_6	$NT \rightarrow Ma \bullet$	$\mid \diamond \quad *$

Q_{11}	Regla	L.A.
F_5	$T \rightarrow Mi \bullet$	Ma

TABLAS DE M. PILOTO

Q_{12}	Regla	L.A.
S_5	$Ru \rightarrow NT ::= P, \bullet R$ $ NT ::= P \bullet$ $ \epsilon \bullet$	*
I_2	$Ru \rightarrow \bullet NT ::= P, R$ $ \bullet NT ::= P$ $ \bullet \epsilon$	*
I_6	$NT \rightarrow \bullet Ma$::=

Q_{13}	Regla	L.A.
S_7	$P \rightarrow RH \bullet P$ $ RH \bullet$ $ \epsilon \bullet$	\diamond *
I_3	$P \rightarrow \bullet RH P$ $ \bullet RH$ $ \bullet \epsilon$	\diamond *
I_4	$RH \rightarrow \bullet T NT$ $ \bullet NT$	$ \diamond$ *
I_5	$T \rightarrow \bullet Mi$	Ma
I_6	$NT \rightarrow \bullet Ma$	$ \diamond$ *

TABLAS DE M. PILOTO

Q_{14}	Regla	L.A.
F_4	$RH \rightarrow T \ NT \bullet$ $ \ NT$	$ \ \diamond \ *$

Q_{15}	Regla	L.A.
F_2	$Ru \rightarrow NT ::= P, R \bullet$ $ \ NT ::= P \bullet$ $ \ \epsilon \bullet$	$*$

Q_{16}	Regla	L.A.
F_3	$P \rightarrow RH \mid P \bullet$ $ \ RH \bullet$ $ \ \epsilon \bullet$	$\diamond \ *$

$Q_0 = \{Q_1 - Ru\}, \{Q_2 - NT\}, \{Q_3 - Ma\}$
 $Q_1 = \{Q_4 - *\}$
 $Q_2 = \{Q_5 - ::= \}$
 $Q_3 = \epsilon$
 $Q_4 = \epsilon$
 $Q_5 = \{Q_6 - P\}, \{Q_7 - RH\}, \{Q_8 - T\}, \{Q_9 - NT\}, \{Q_{10} - Ma\}, \{Q_{11} - Mi\}$
 $Q_6 = \{Q_{12} - \diamond\}$
 $Q_7 = \{Q_{13} - |\}$
 $Q_8 = \{Q_{14} - NT\}, \{Q_{10} - Ma\}$
 $Q_9 = \epsilon$
 $Q_{10} = \epsilon$
 $Q_{11} = \epsilon$
 $Q_{12} = \{Q_{15} - Ru\}, \{Q_2 - NT\}, \{Q_3 - Ma\}$
 $Q_{13} = \{Q_{16} - P\}, \{Q_7 - RH\}, \{Q_8 - T\}, \{Q_9 - NT\}, \{Q_{10} - Ma\}, \{Q_{11} - Mi\}$
 $Q_{14} = \epsilon$
 $Q_{15} = \epsilon$
 $Q_{16} = \epsilon$

AUTOMATA PILOTO

ES UN AUTOMATA DE CONDICION $LR(1)$

