

# Games with Texture Mapping

**CS 4620 Lecture 13**

# Recall first definition...

**Texture mapping:** a technique of defining surface properties (especially shading parameters) in such a way that they vary as a function of position on the surface.

# A refined definition

**Texture mapping:** a set of techniques for defining functions on surfaces, for a variety of uses.

- Let's look at some examples of more general uses of texture maps.

# Reflection mapping

- **Early (earliest?) non-decal use of textures**
- **Appearance of shiny objects**
  - Phong highlights produce blurry highlights for glossy surfaces.
  - A polished (shiny) object reflects a sharp image of its environment.
- **The whole key to a shiny-looking material is providing something for it to reflect.**



(a)



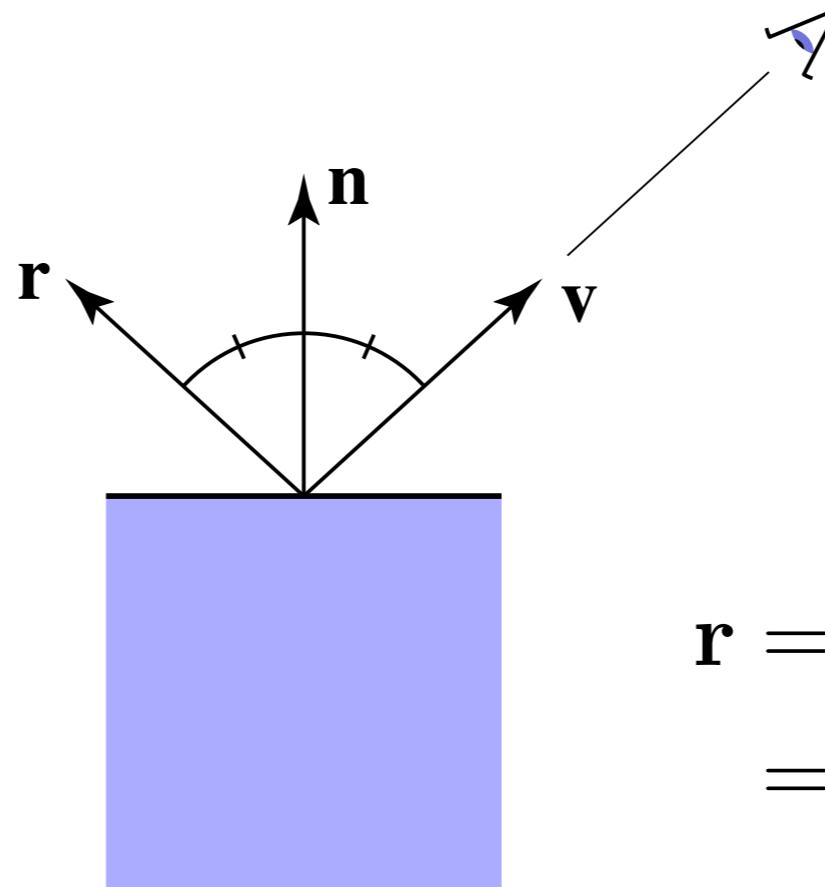
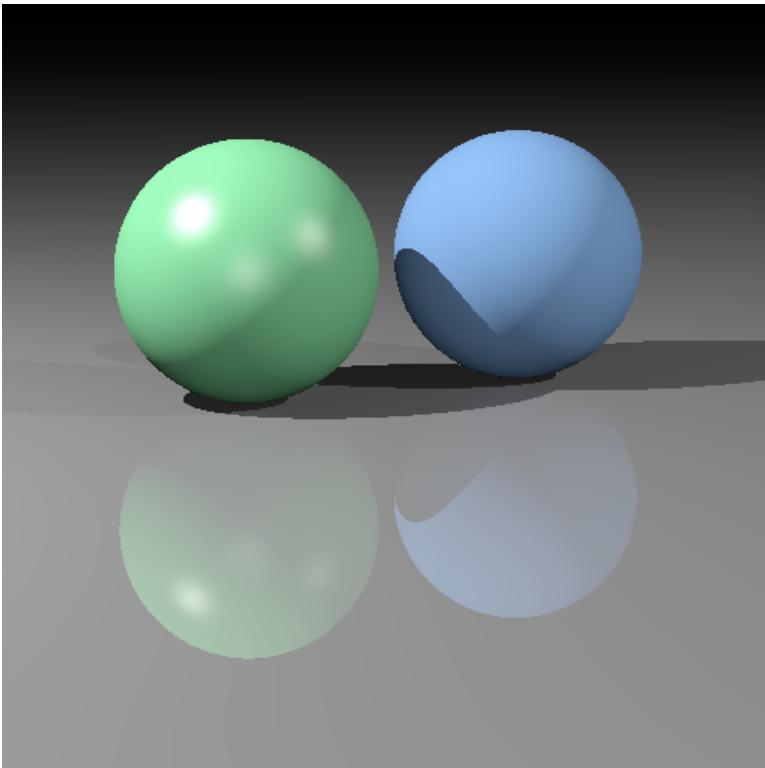
(b)

[Dror, Willsky, & Adelson 2004]

Figure 2. (a). A shiny sphere rendered under photographically acquired real-world illumination. (b). The same sphere rendered under illumination by a point light source.

# Reflections in ray tracing

- Recall how we can make mirror reflections in ray tracing



$$\begin{aligned}\mathbf{r} &= \mathbf{v} + 2((\mathbf{n} \cdot \mathbf{v})\mathbf{n} - \mathbf{v}) \\ &= 2(\mathbf{n} \cdot \mathbf{v})\mathbf{n} - \mathbf{v}\end{aligned}$$

# Reflection mapping

- **If scene is infinitely far away, the color seen by the reflection ray depends only on the direction of the ray**
  - a two-dimensional function
  - represent it with a texture!
- **Environment map: texture that maps directions to colors**
  - one option: axes are (theta, phi)
  - better option: cube map



**A spherical panorama, aka. environment map**

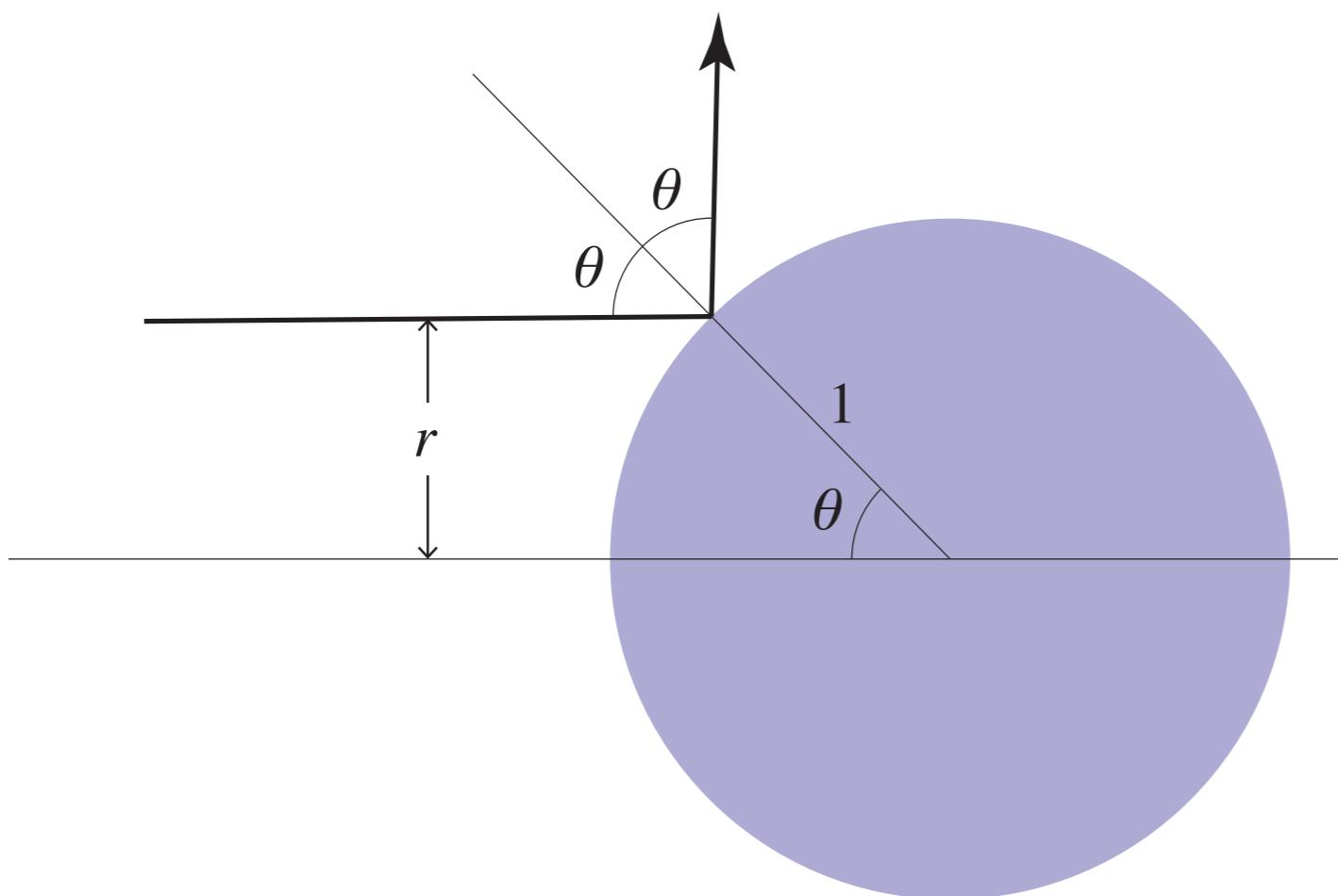
# Environment map

- A function from the sphere to colors, stored as a texture.



[Blinn & Newell 1976]

# Spherical environment map



*Hand with Reflecting Sphere.* M. C. Escher, 1935. lithograph

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# Environment Maps

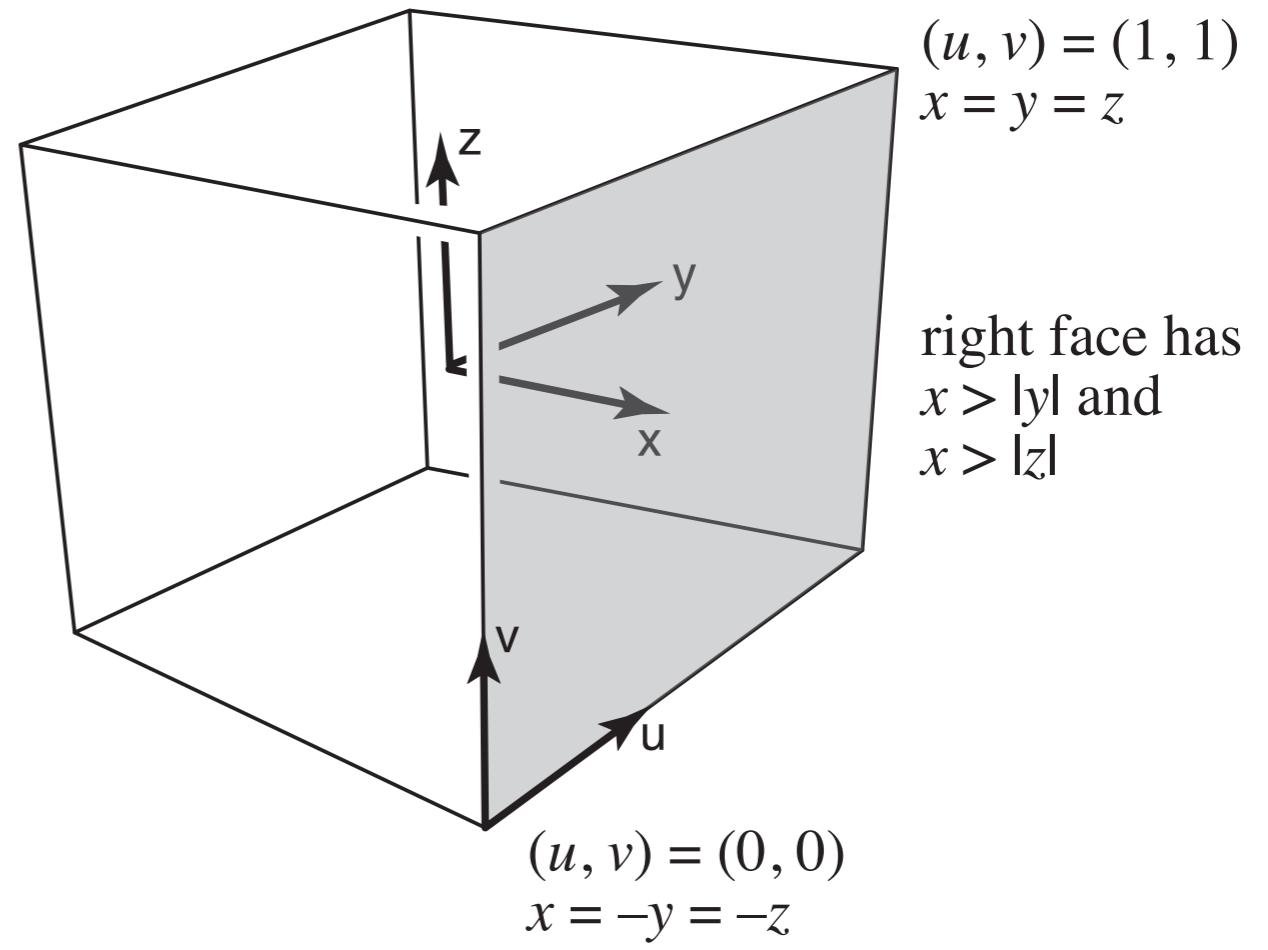
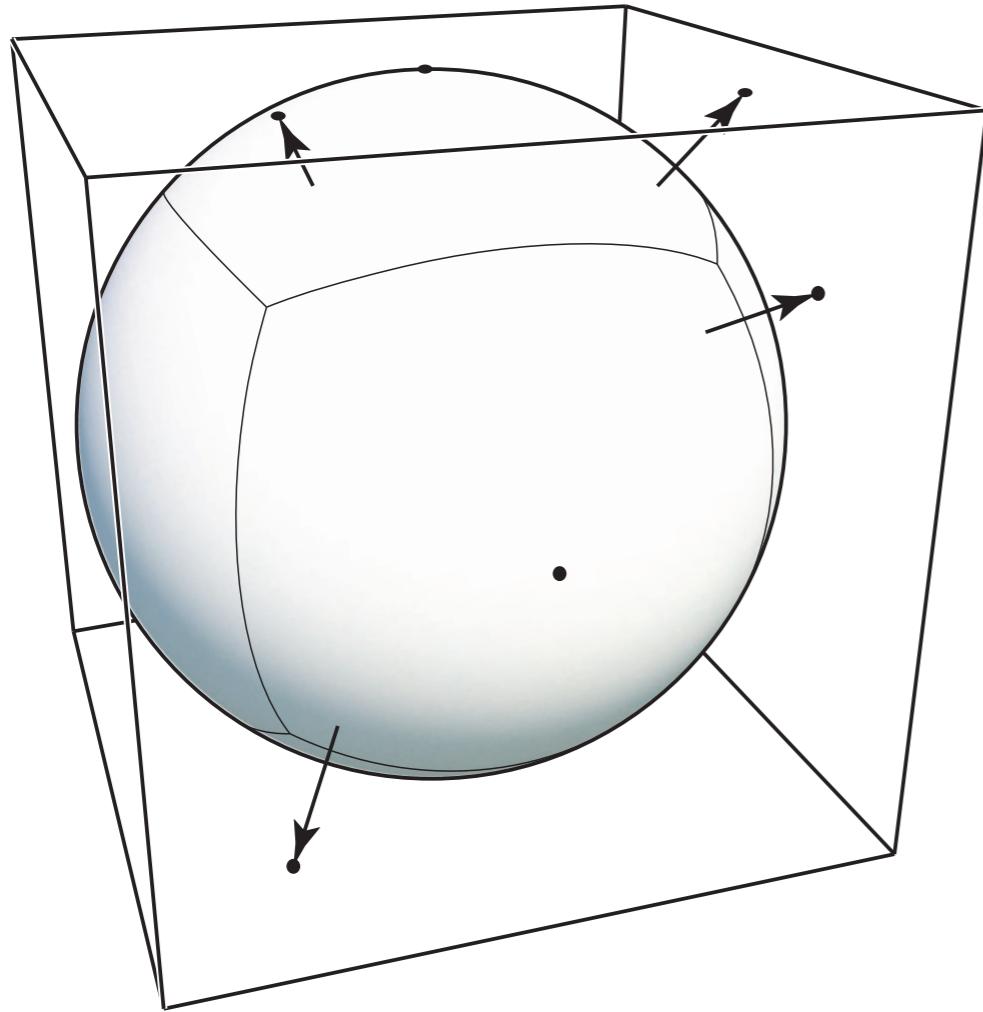


[Paul Debevec]

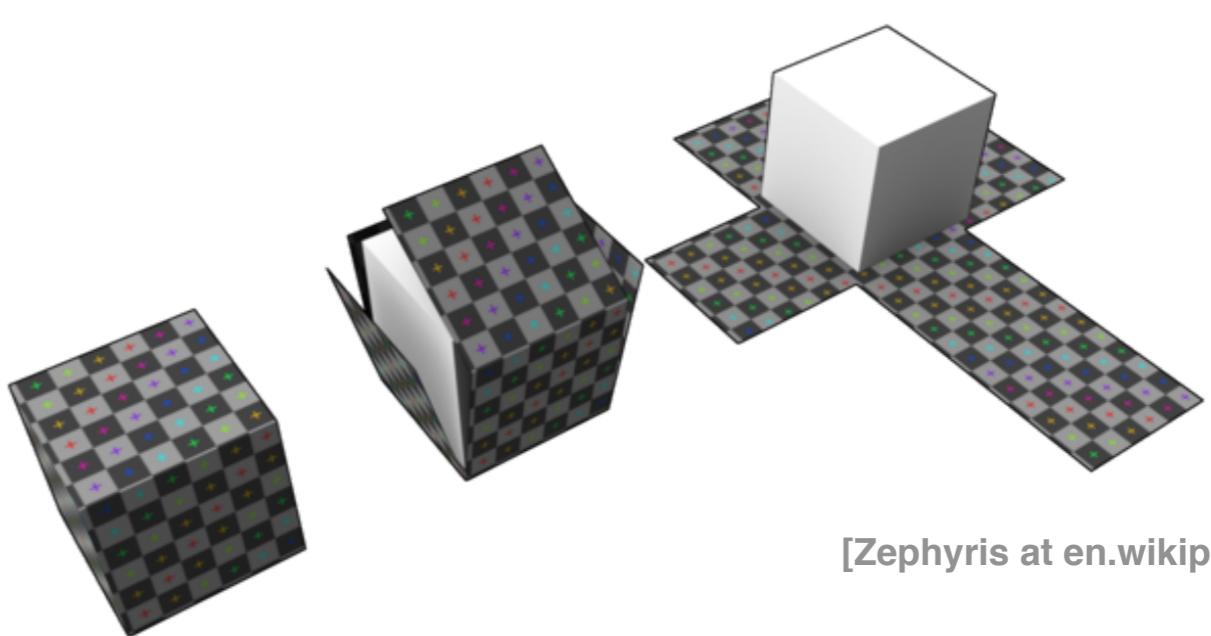
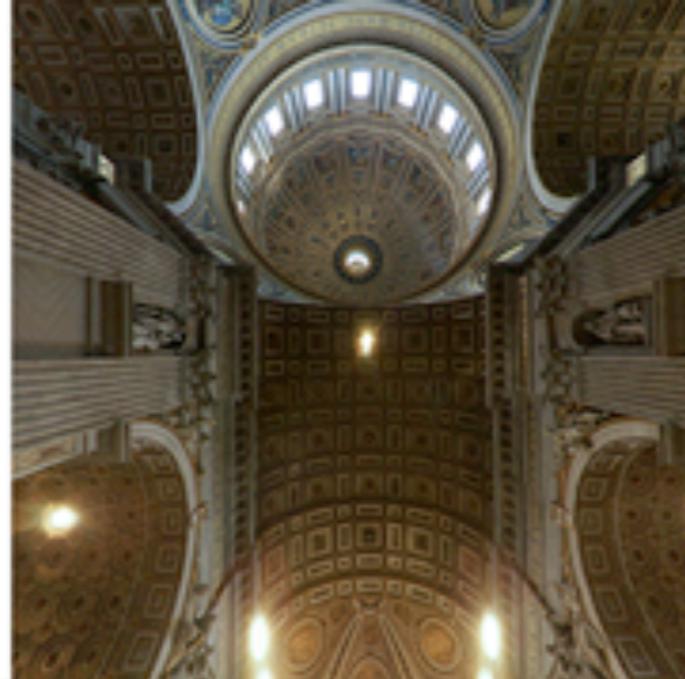


[CS467 slides]

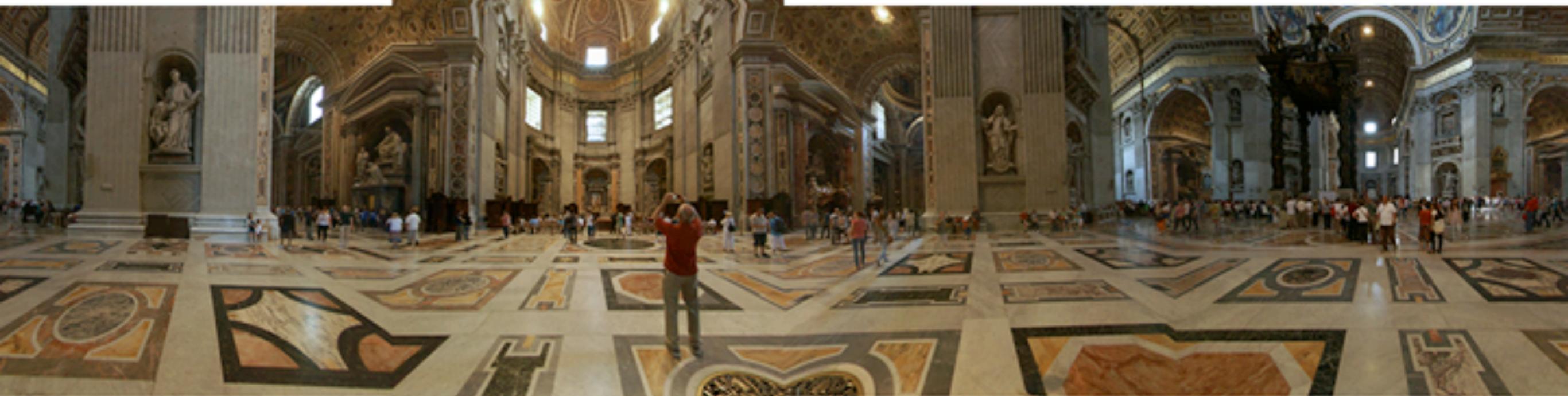
# Cube map



a direction vector maps to the point on the cube that is along that direction.  
The cube is textured with 6 square texture maps.



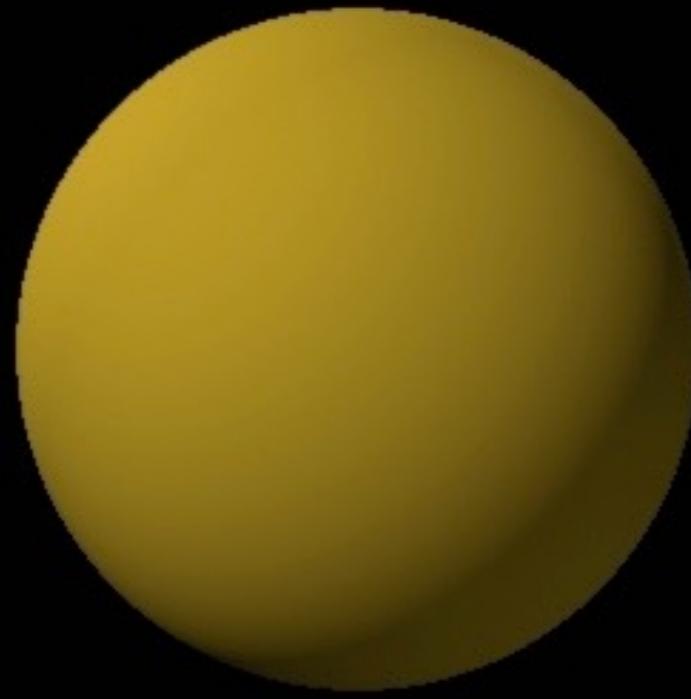
[Zephyris at en.wikipedia]



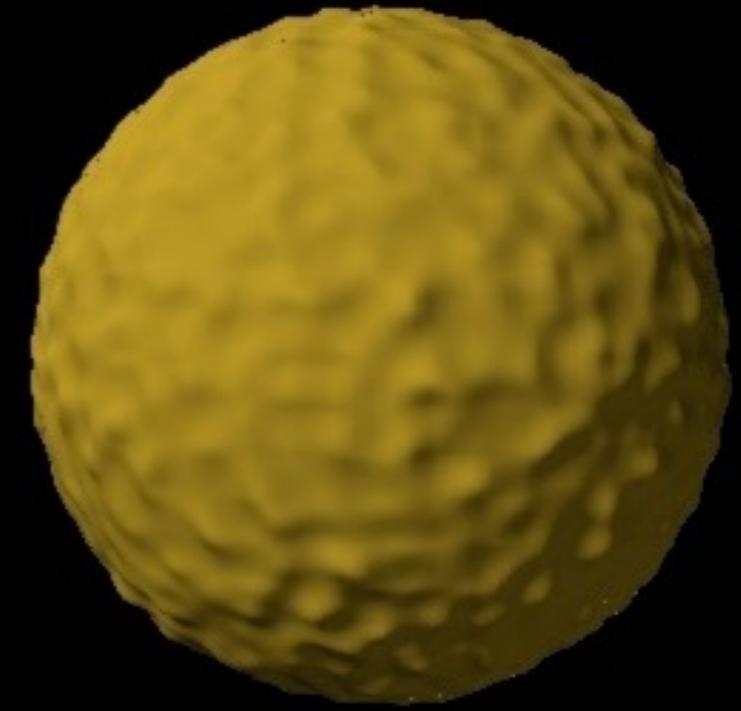
[Emil Persson]

# Reflection mapping in GLSL

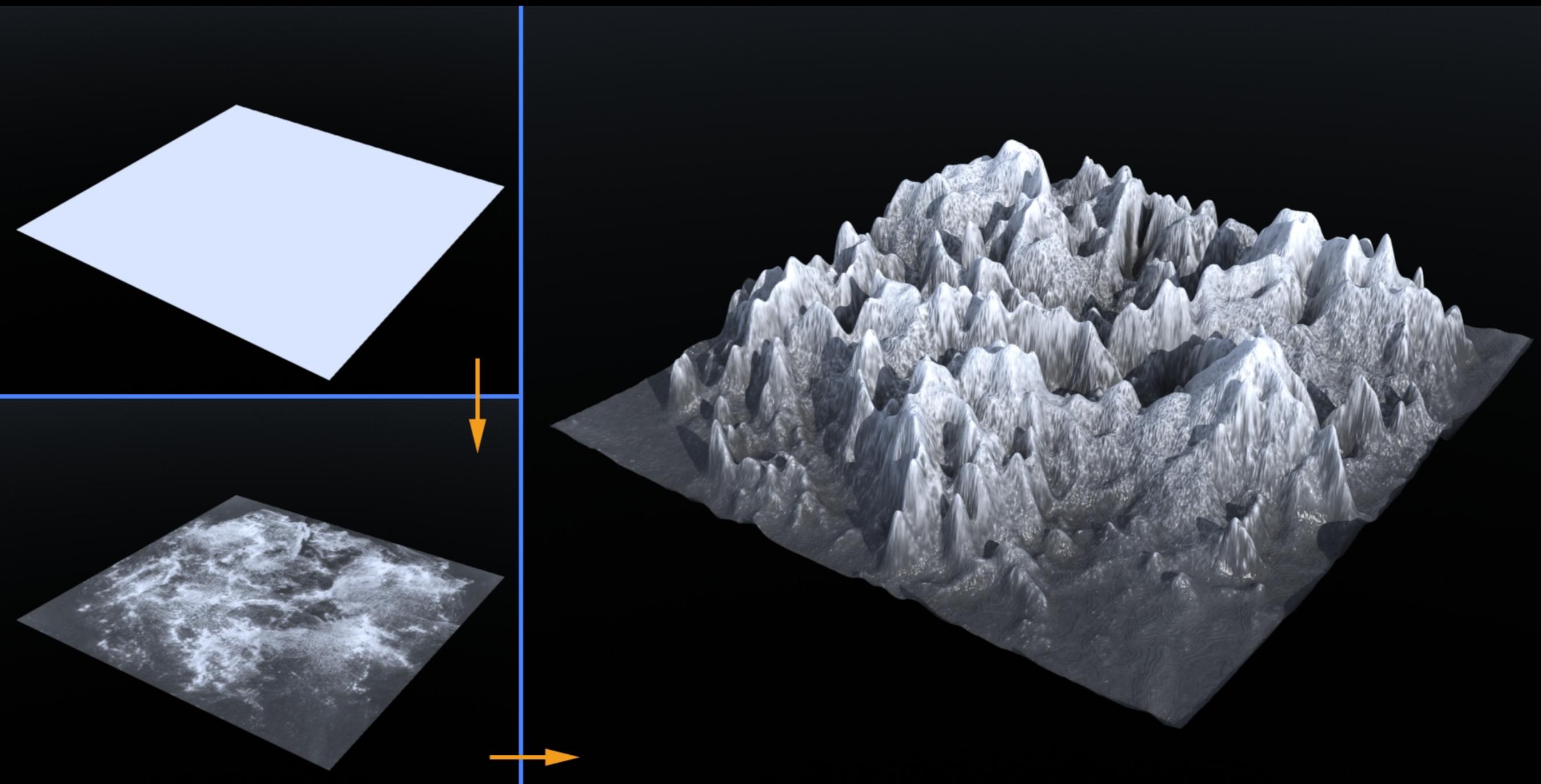
- **A fragment operation**
  - requires surface normal and a way to get the view direction
- **GLSL handles cubemaps by itself**
  - you just give it the reflection vector and it figures out where to sample and on which face
  - sample using `textureCube()`
- **Don't overlook built-in functions**
  - e.g. `reflect()`



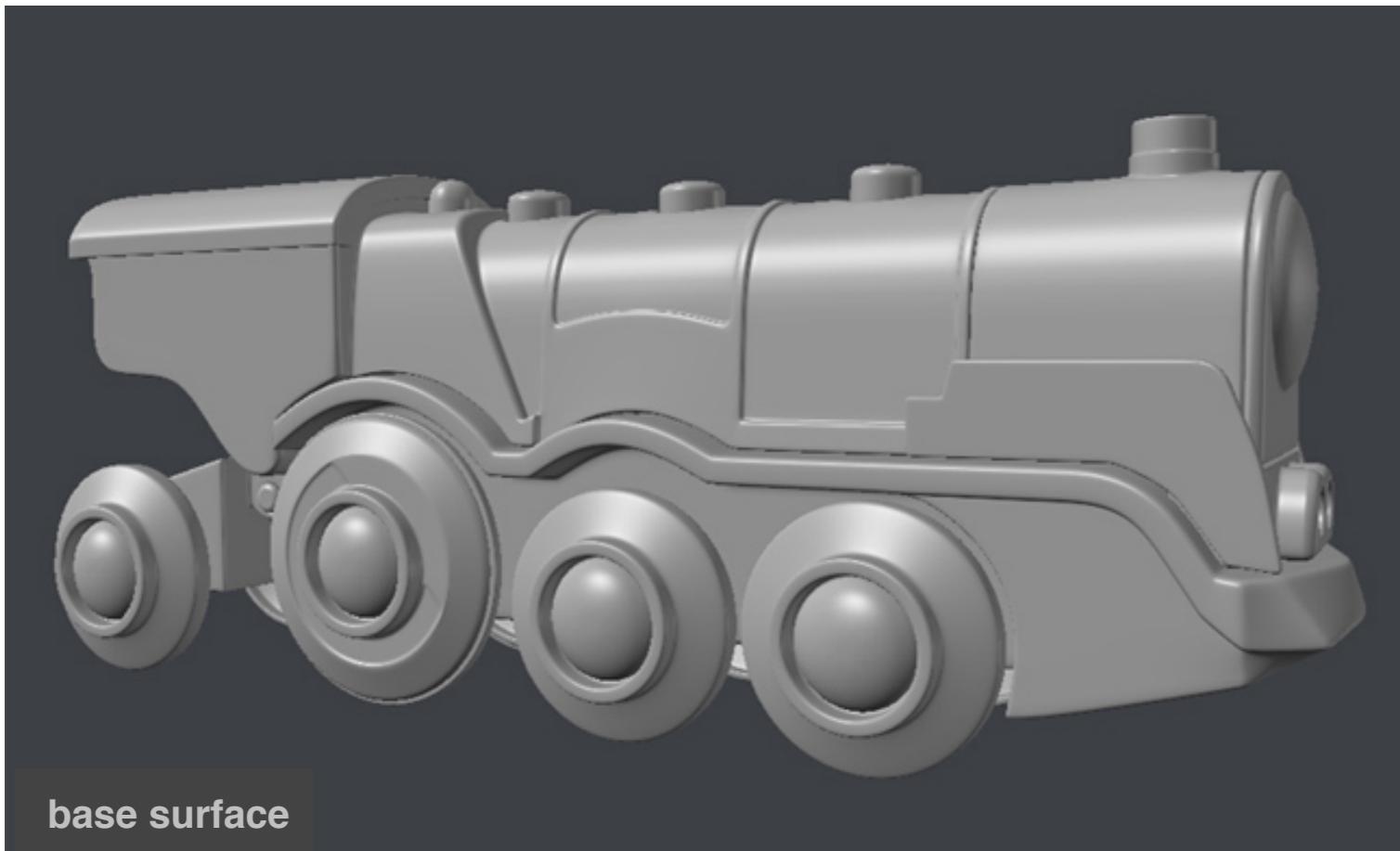
Geometry



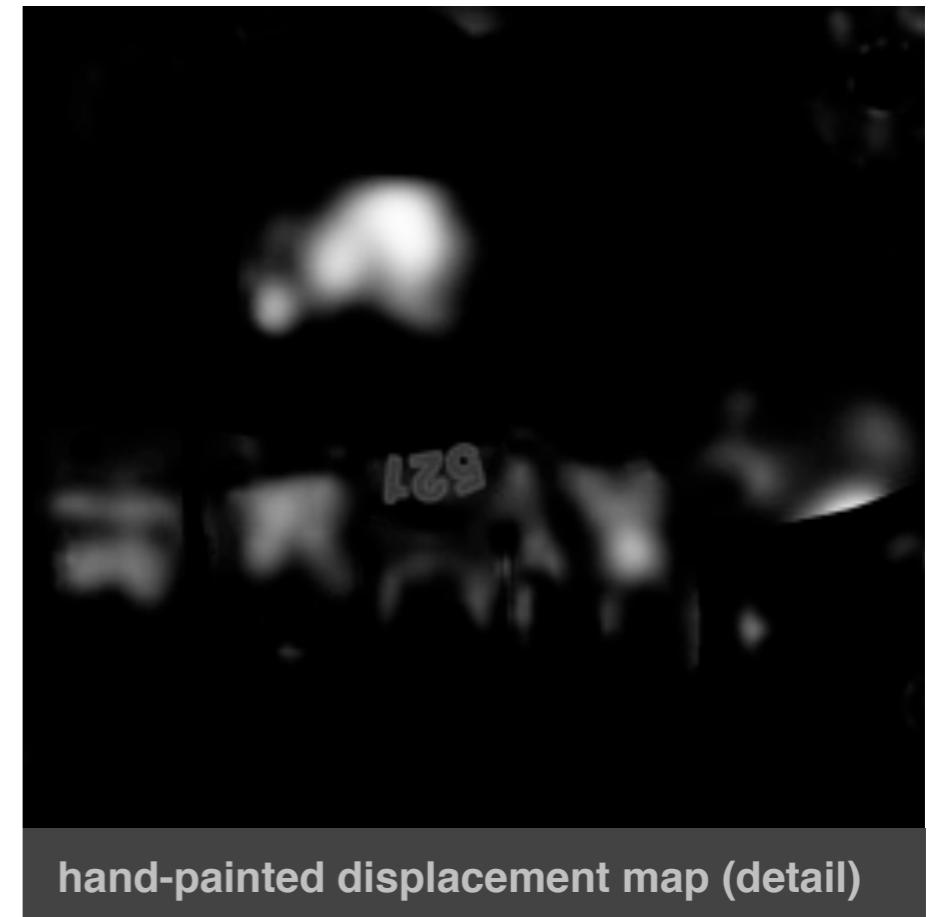
Displacement  
mapping



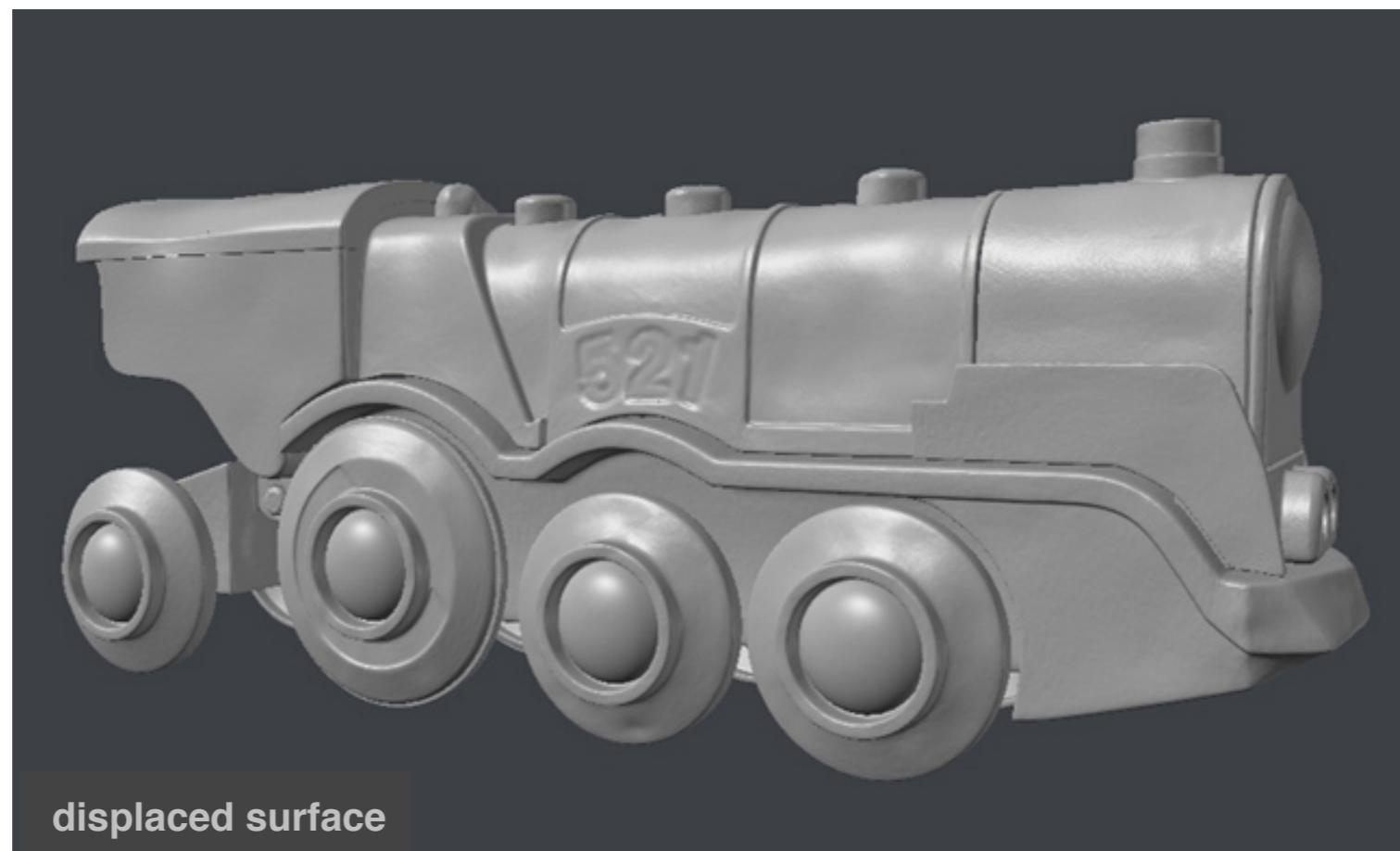
[wikiwand]



base surface



hand-painted displacement map (detail)



Paweł Filip  
[tolas.wordpress.com](http://tolas.wordpress.com)

displaced surface



fryrender

physically-based render engine

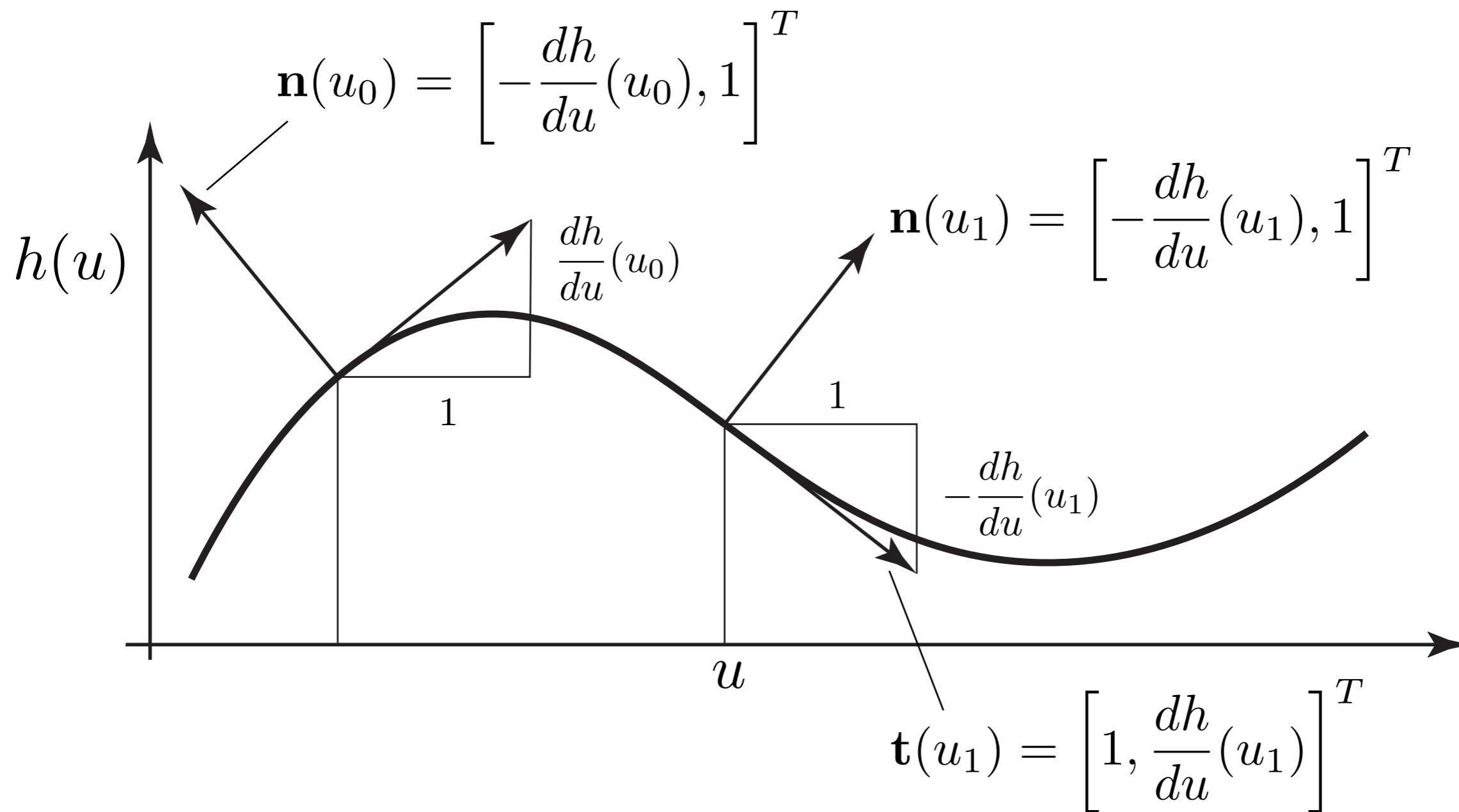
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# Displacement mapping

- **A powerful tool for modeling detail**
  - used heavily in film production
- **Geometric prerequisites**
  - texture map representing height field
  - smooth normals
  - dense triangulation
- **In GLSL**
  - a vertex operation (because it moves geometry)
  - displace vertices along normal vectors
  - displacement distance proportional to texture map value

# Normals in displacement mapping

- **Displacing the surface changes the surface normal**



# Normals in displacement mapping

- **In the 3D case the correct normal is**

$$\mathbf{n}(u, v) = \left[ -\frac{\partial h}{\partial u}, -\frac{\partial h}{\partial v}, 1 \right]^T$$

- normalized, of course!
- this is measured in the coordinates of the height field
- **This needs to be computed and transformed to object space**
  - the necessary transformation is the *tangent frame* of the surface
  - a basis defined by the three vectors:
    - tangent in  $u$  direction
    - tangent in  $v$  direction
    - surface normal

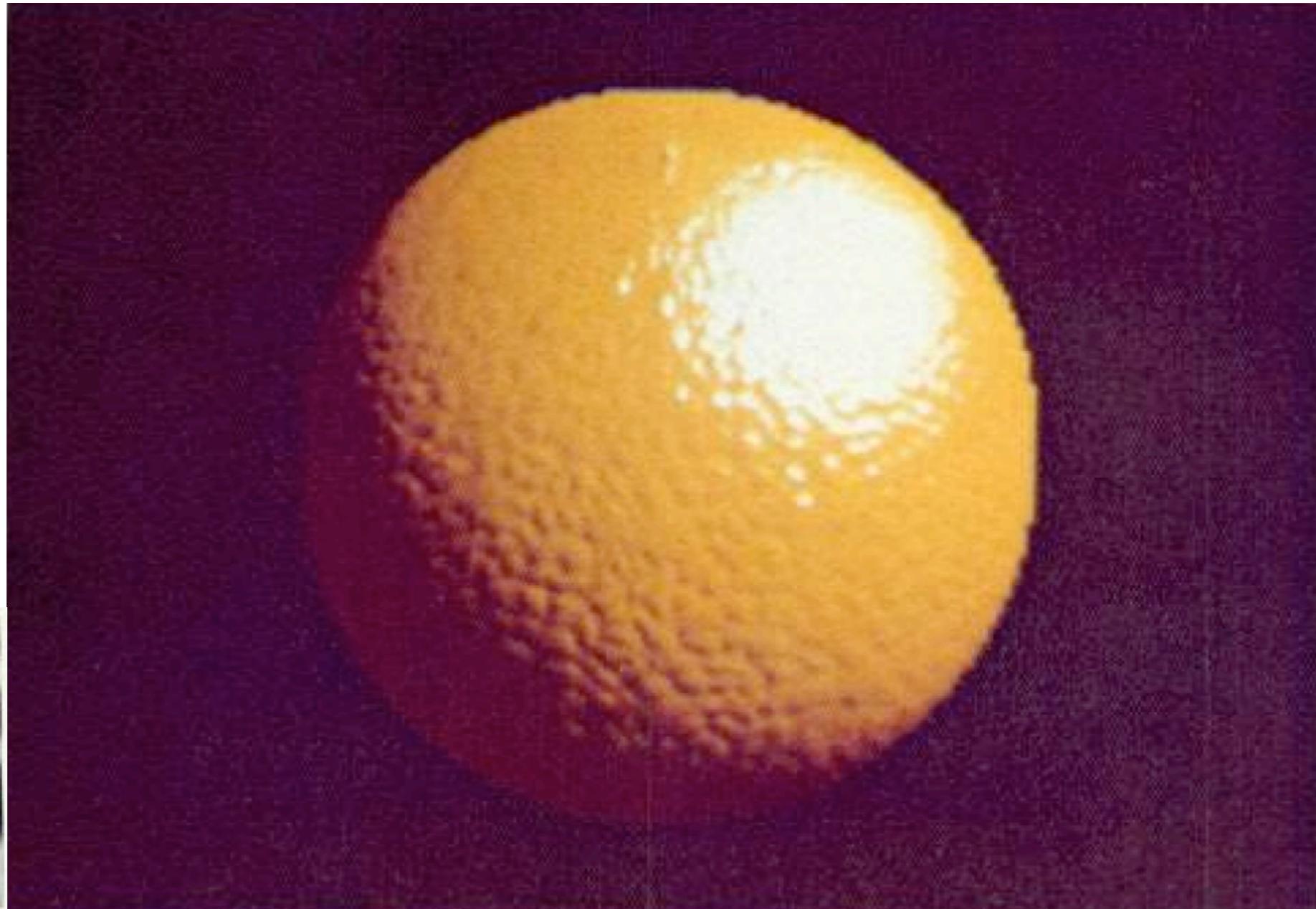
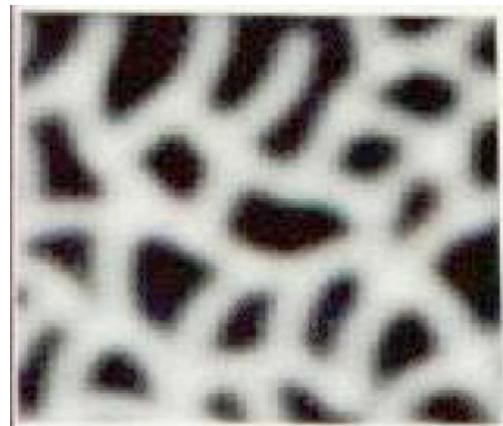
# Geometry for displacement

- **geometric data**
  - normal
  - $u$  tangent
  - $v$  tangent
  - height field texture
- **geometric logic**
  - look up displacement value from texture
  - compute normal to displaced surface
    - compute derivatives of height by finite differences
    - or precompute these normals (see normal mapping in a moment)
  - transform normal to (tangent- $u$ , tangent- $v$ , normal) space

**in A4 we don't worry  
about normals in  
displacement mapping**

(since normal mapping is its  
own part)

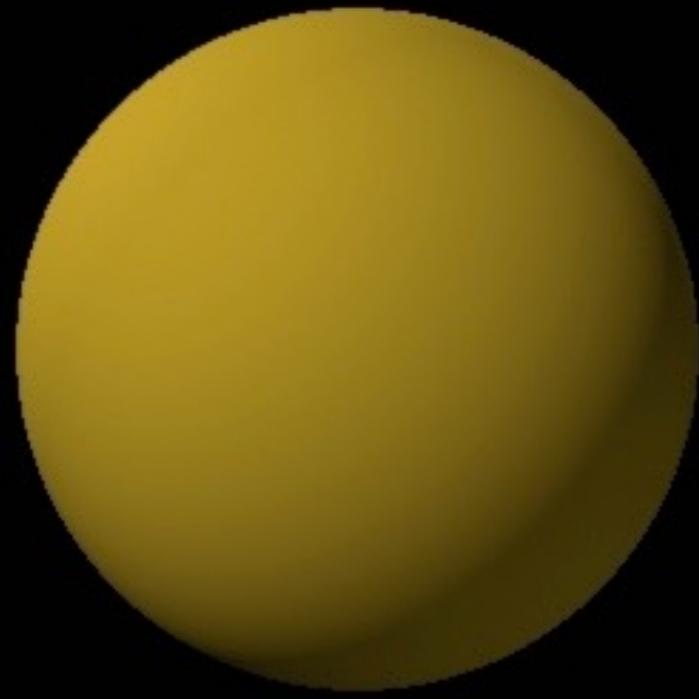
# Bump mapping



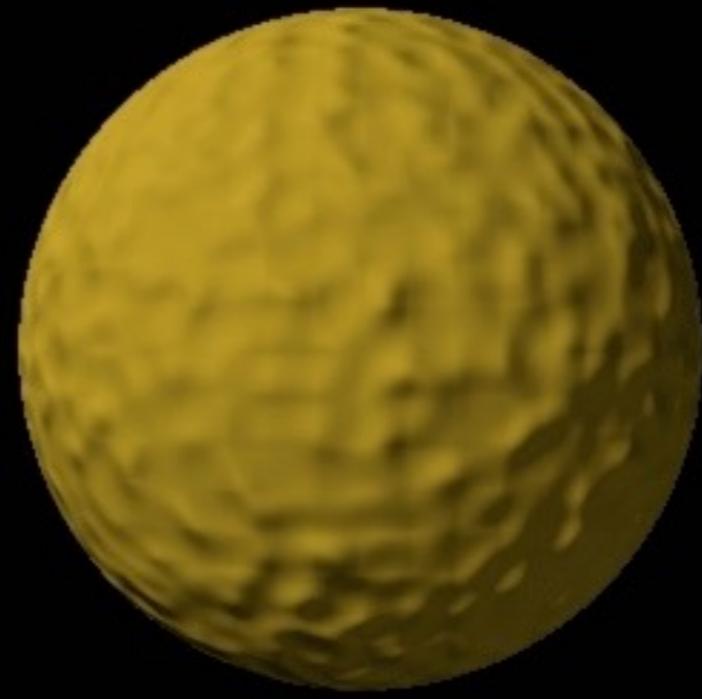
[Blinn 1978]

# Bump mapping

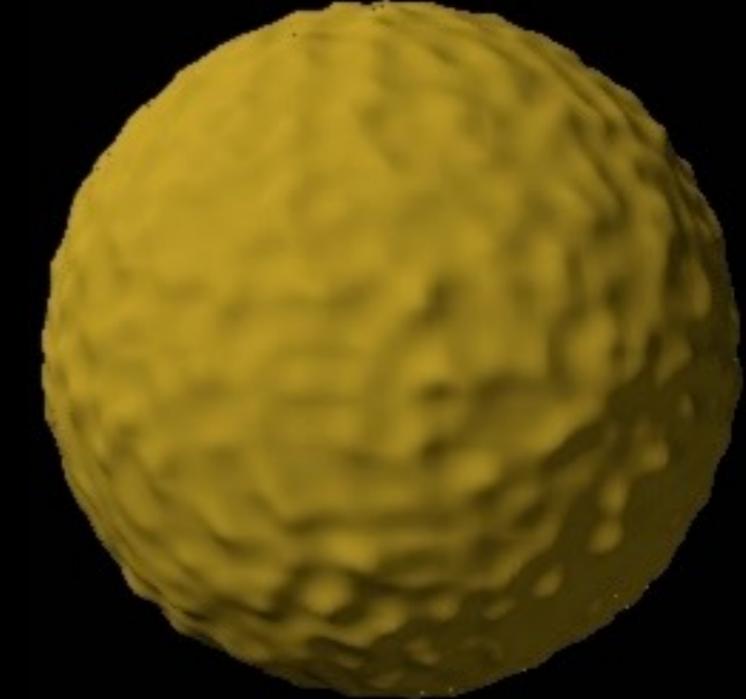
- **Displacement mapping is expensive**
  - requires densely tessellated geometry
  - many triangles to rasterize
- **For small displacements, the most important effect is on the normal**
  - so just do that part; don't displace the surface
- **Bump mapping is then a fragment operation**
  - doesn't require dense tessellation
  - doesn't actually displace the surface
  - gives shading that looks just like displaced surface



Geometry



Bump  
mapping

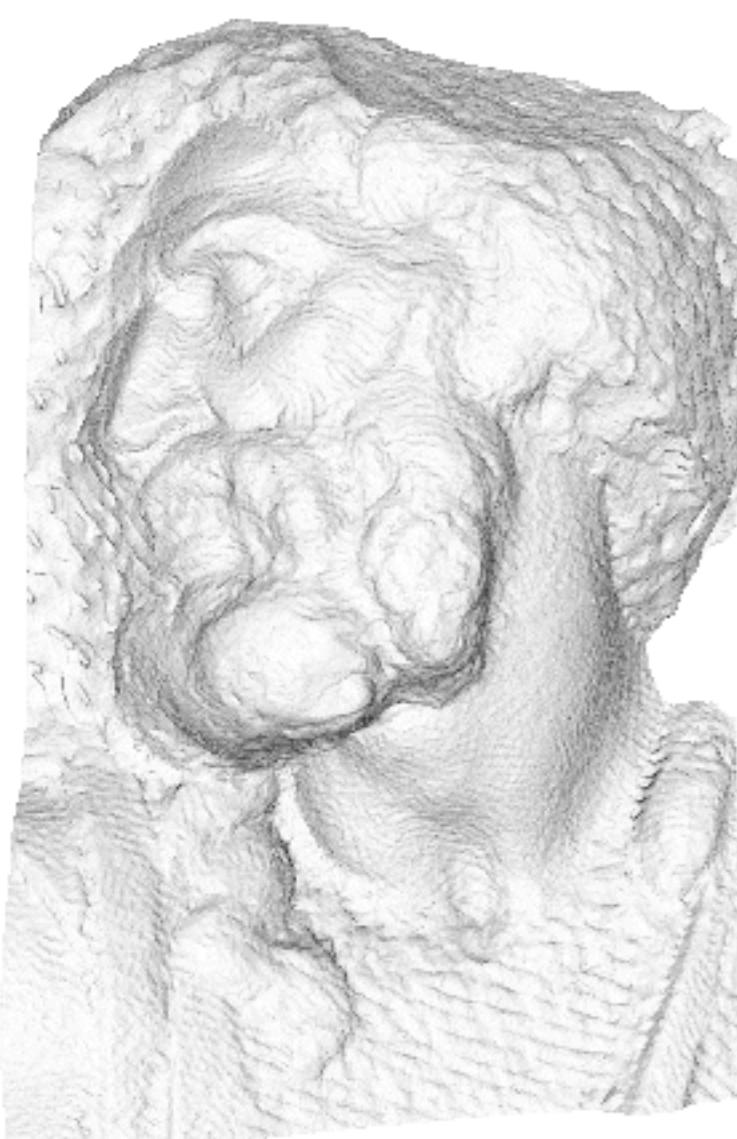


Displacement  
mapping

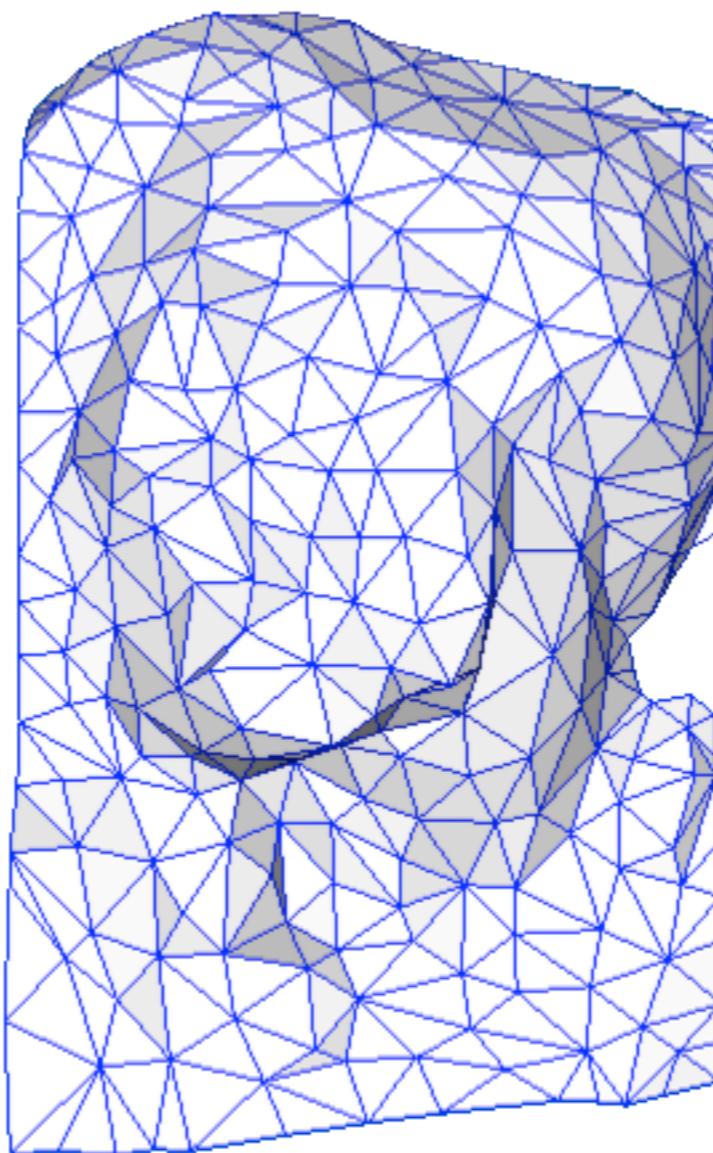
# Bump mapping

- **Geometric prerequisites**
  - texture map representing height field
  - smooth normals
  - tangent vectors
  - no dense triangulation needed
- **Geometric logic**
  - compute normal to displaced surface
    - compute derivatives of height by finite differences
  - transform normal to (tangent-u, tangent-v, normal) space

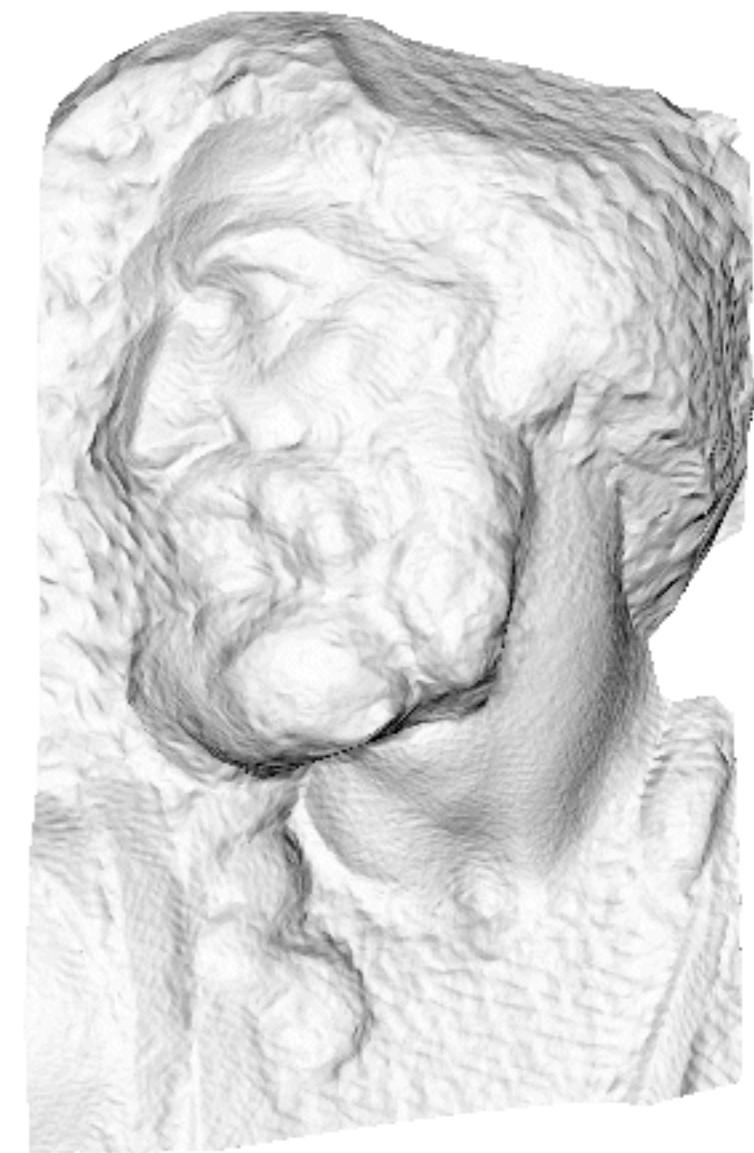
# Normal mapping



original mesh  
4M triangles



simplified mesh  
500 triangles



simplified mesh  
and normal mapping  
500 triangles

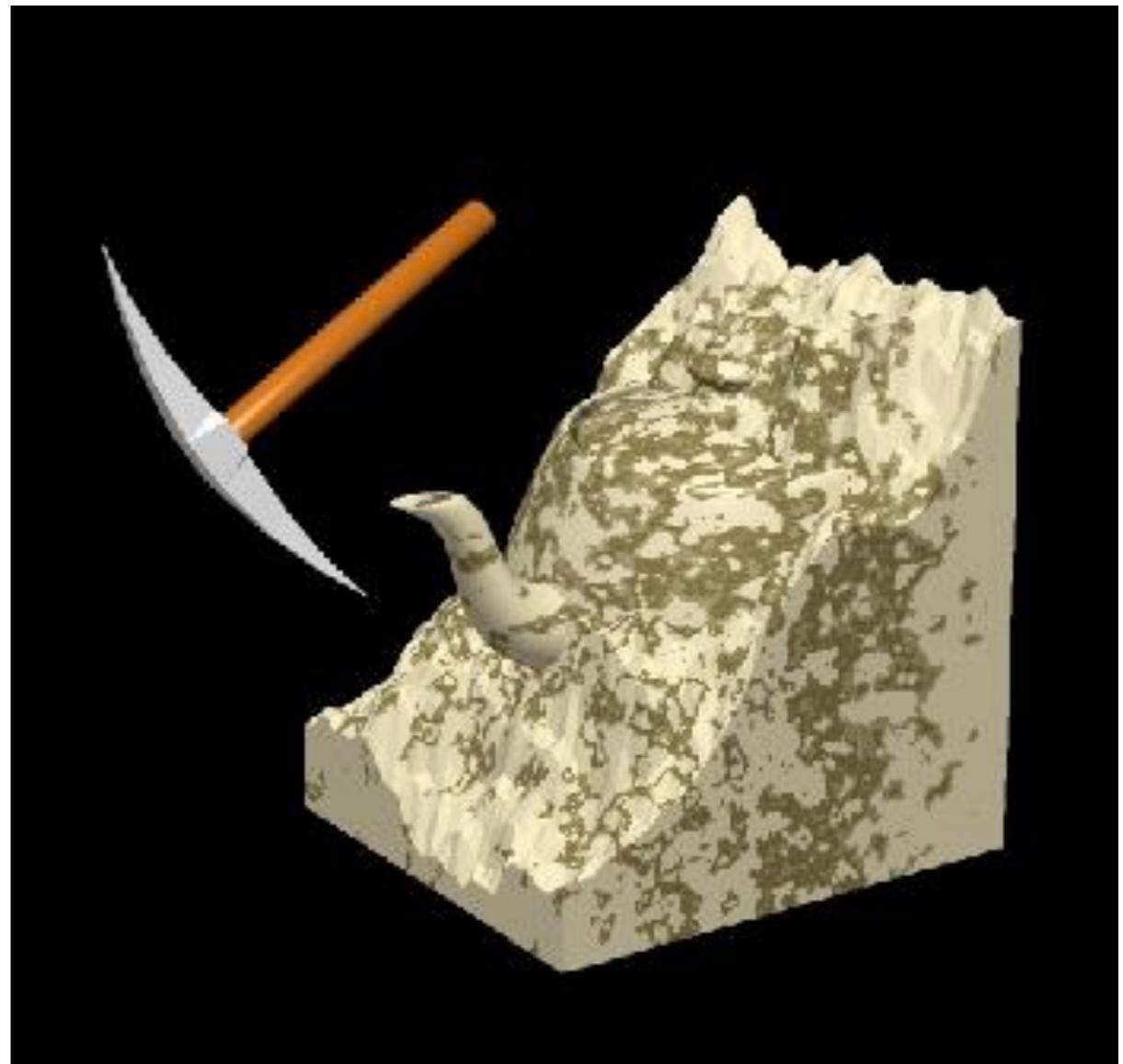
[Paolo Cignoni]

# Normal mapping

- **Geometric prerequisites**
  - Texture map (3 channels) representing normal field
    - single lookups into normal map required
  - Smooth normals
  - Tangent vectors
    - if you want to store normals in tangent space (and you do)
  - No dense triangulation needed
  - No finite differencing needed
- **Geometric logic**
  - look up normal from map
  - transform into (tangent-u, tangent-v, normal) space

# 3D textures

- **Texture is a function of  $(u, v, w)$** 
  - can just evaluate texture at 3D surface point
  - good for solid materials
  - often defined procedurally
  - see book for more!



[Wolfe / SG97 Slide set]