

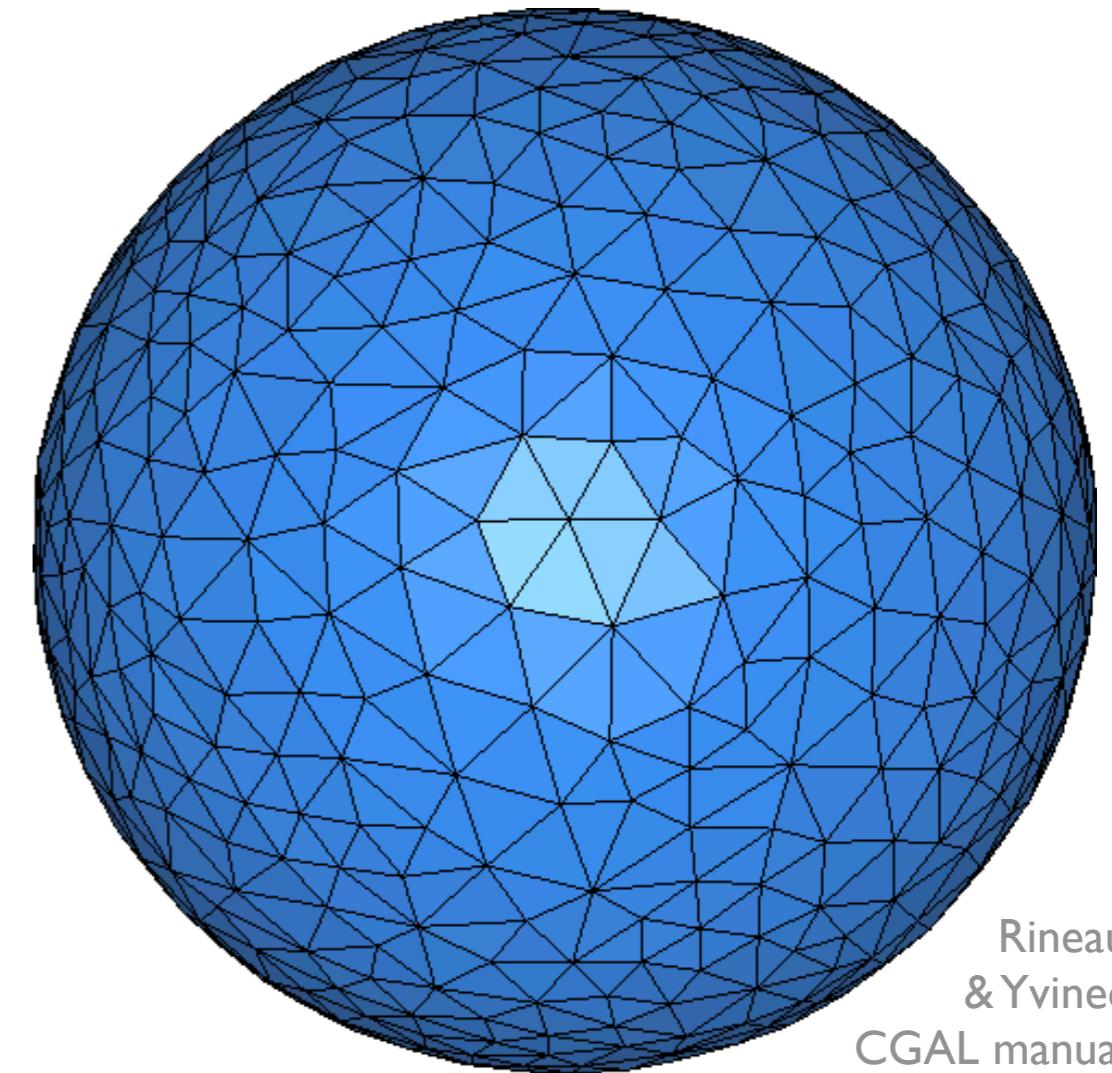
Triangle meshes I

CS 4620 Lecture 4



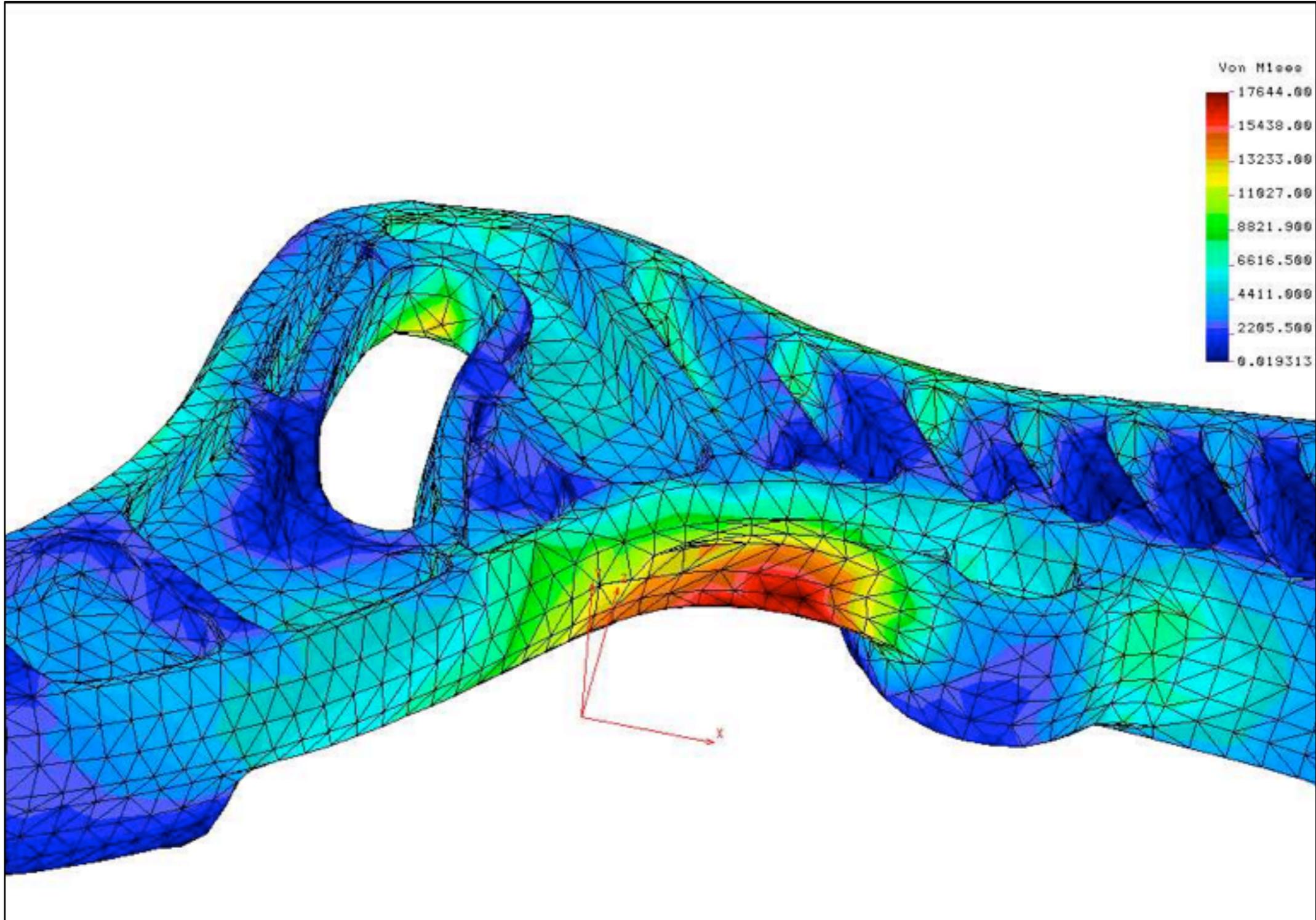
Andrzej Barabasz

spheres



approximate sphere

Rineau
& Yvinec
CGAL manual



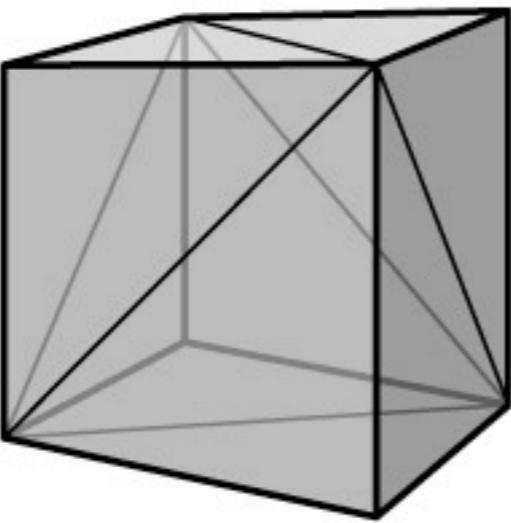
PATRIOT Engineering

finite element analysis



Ottawa Convention Center

A small triangle mesh

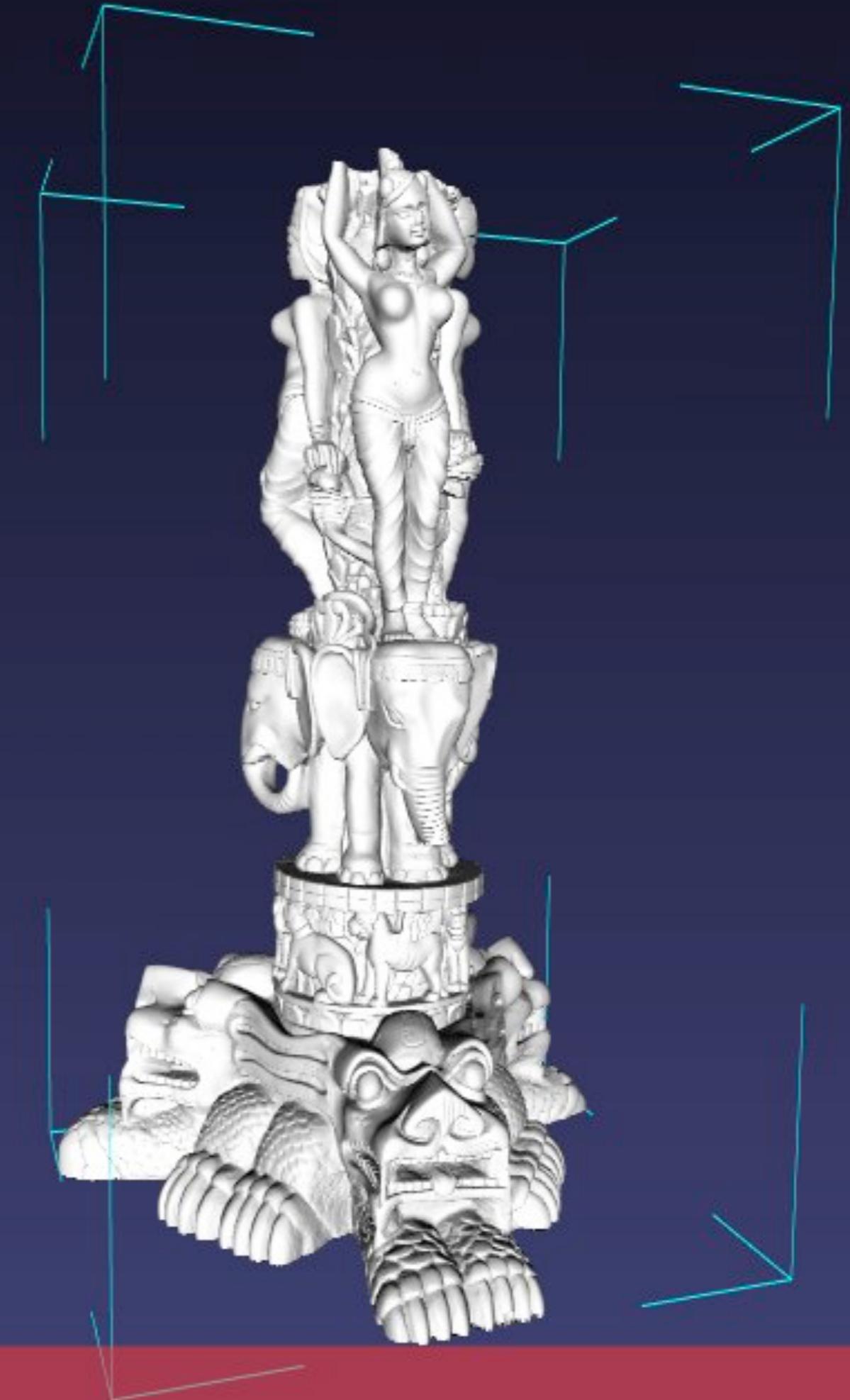


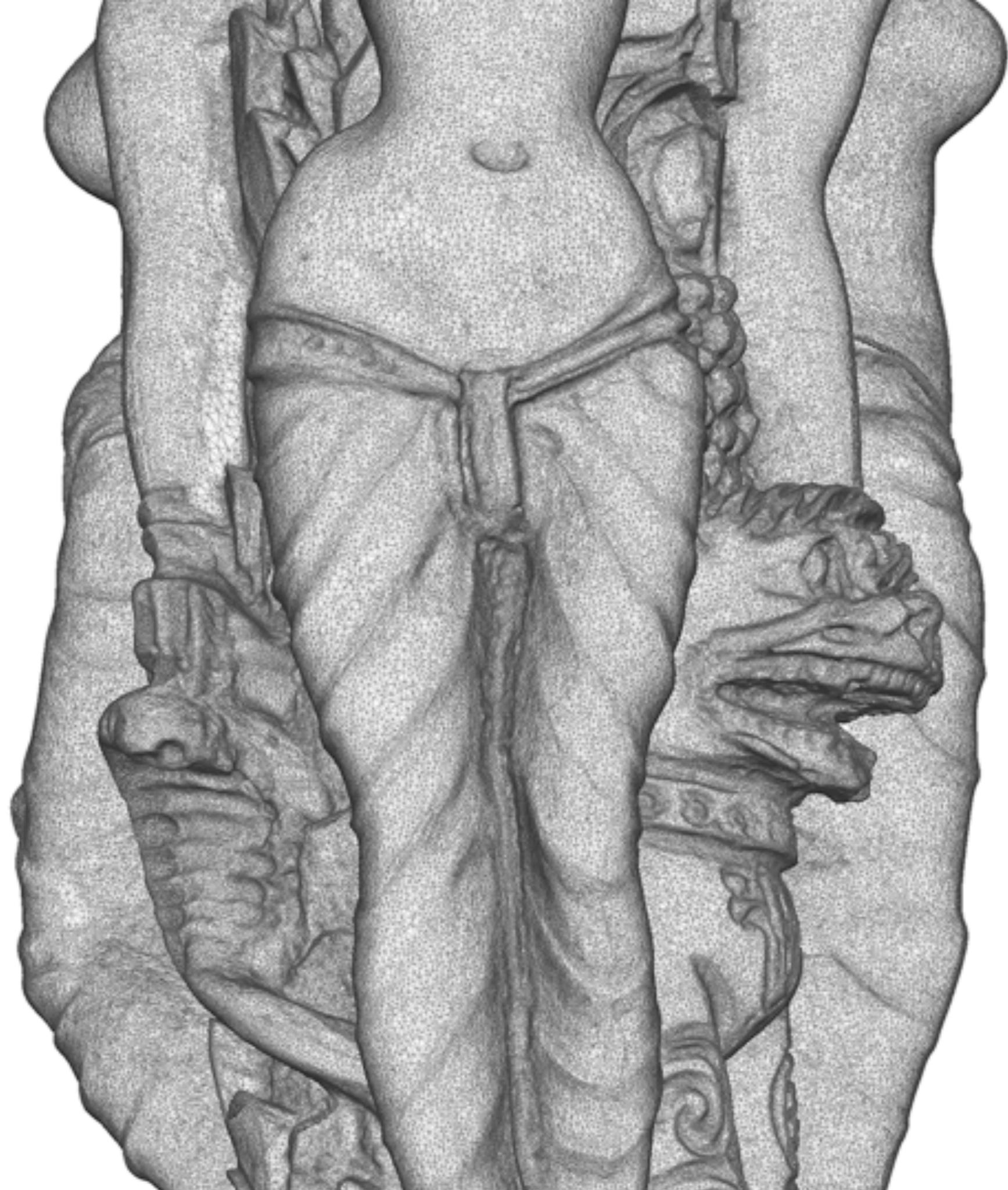
12 triangles, 8 vertices

A large mesh

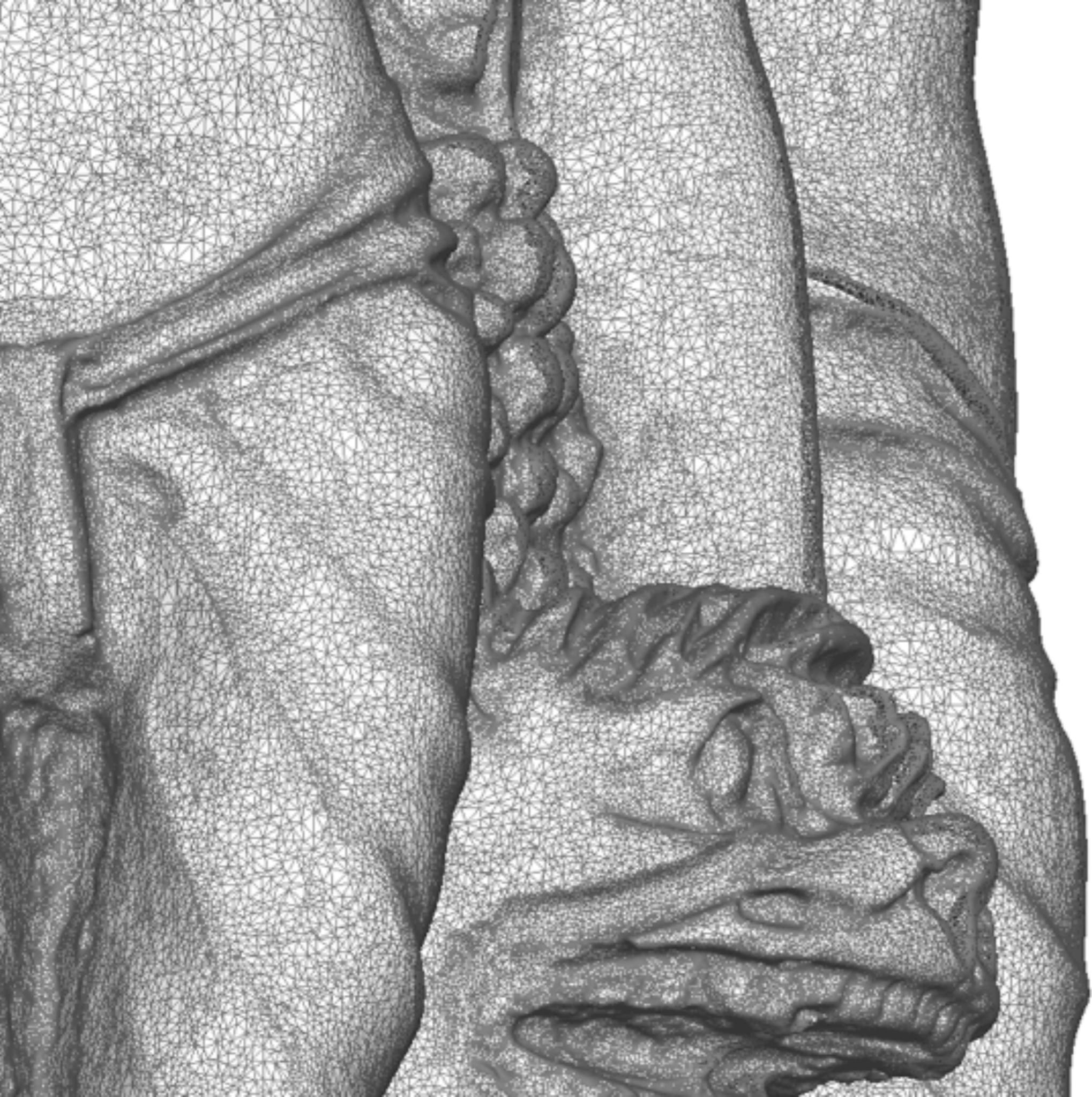
10 million triangles
from a high-resolution
3D scan

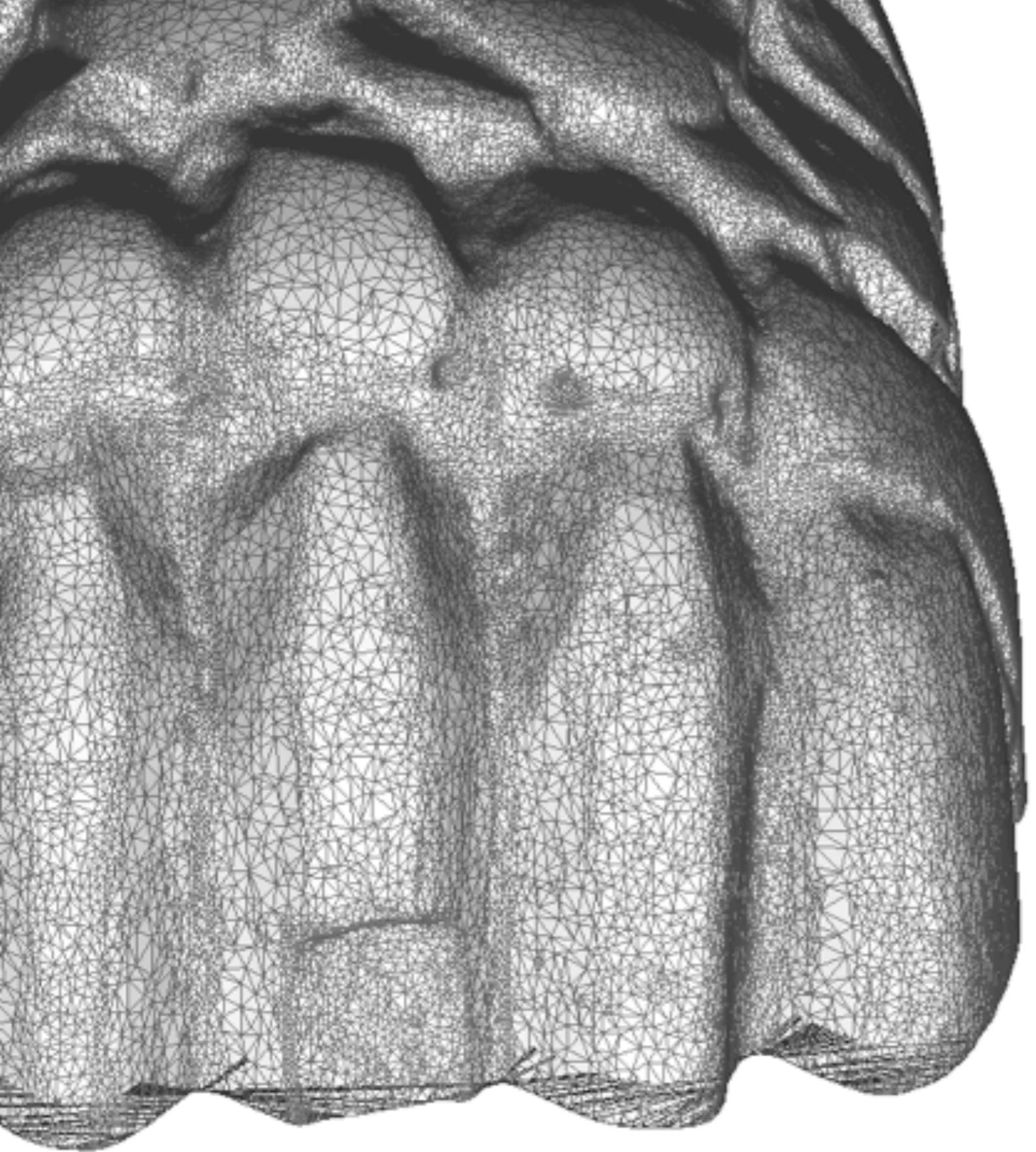
Traditional Thai sculpture—scan by XYZRGB, inc., image by MeshLab project

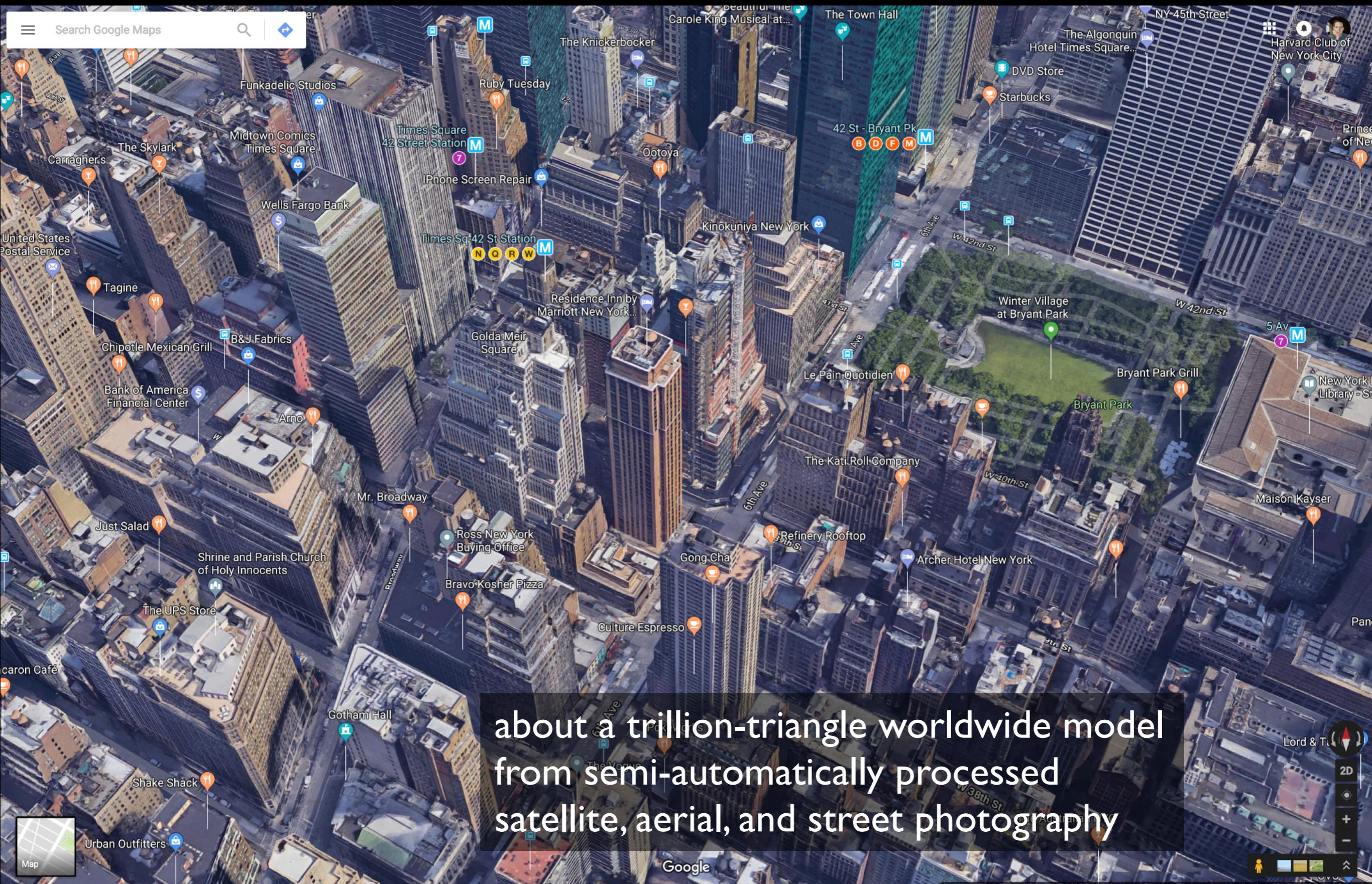












Triangles

- **Defined by three vertices**
- **Lives in the plane containing those vertices**
- **Vector normal to plane is the triangle's normal**
- **Conventions (for this class, not everyone agrees):**
 - vertices are counter-clockwise as seen from the “outside” or “front”
 - surface normal points towards the outside (“outward facing normals”)

Triangle meshes

- **A bunch of triangles in 3D space that are connected together to form a surface**
- **Geometrically, a mesh is a *piecewise planar* surface**
 - almost everywhere, it is planar
 - exceptions are at the edges where triangles join
- **Often, it's a piecewise planar approximation of a smooth surface**
 - in this case the creases between triangles are artifacts—we don't want to see them

Representation of triangle meshes

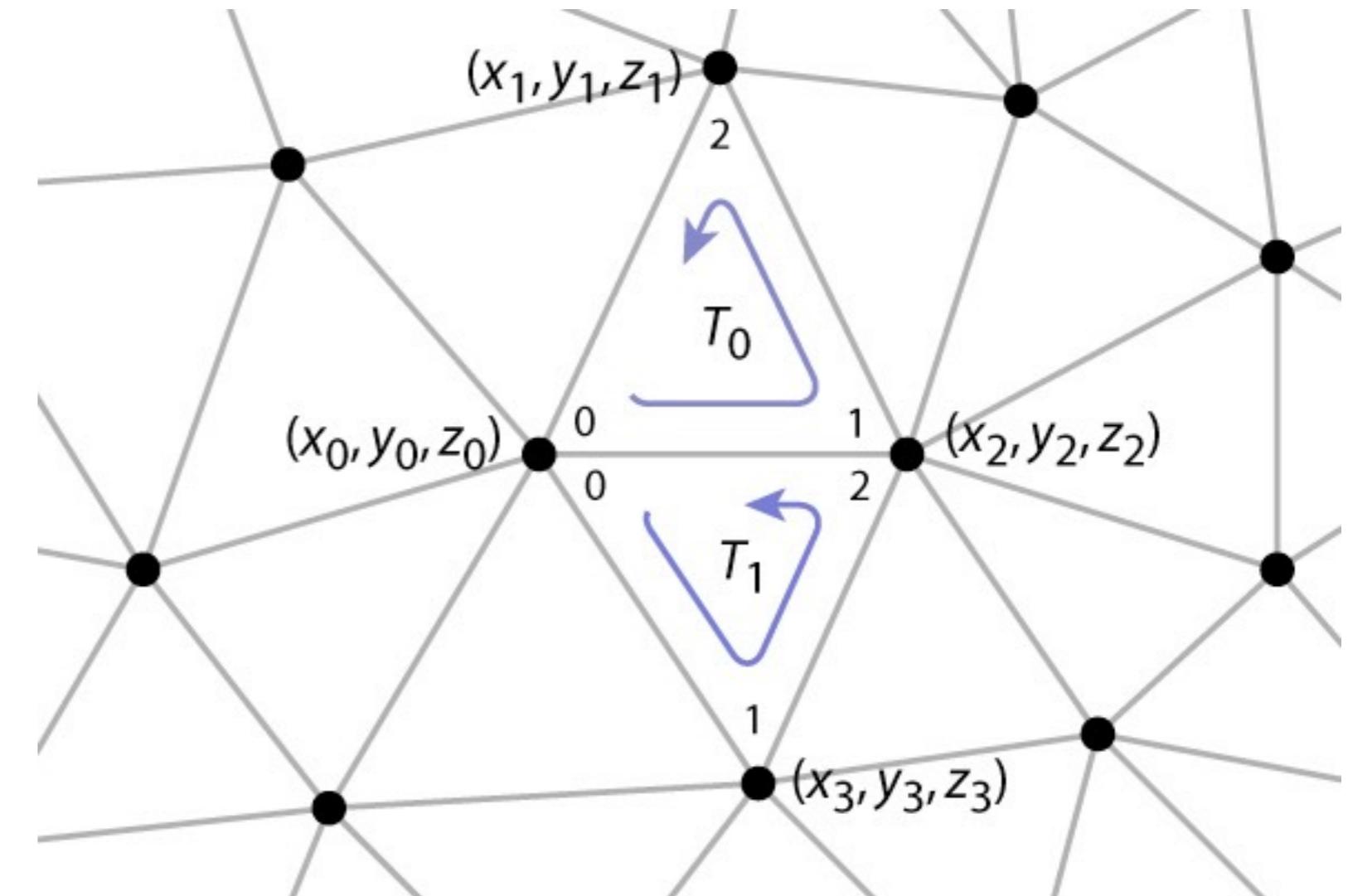
- **Compactness**
- **Efficiency for rendering**
 - enumerate all triangles as triples of 3D points
- **Efficiency of queries**
 - all vertices of a triangle
 - all triangles around a vertex
 - neighboring triangles of a triangle
 - (need depends on application)
 - finding triangle strips
 - computing subdivision surfaces
 - mesh editing

Representations for triangle meshes

- **Separate triangles**
 - **Indexed triangle set**
 - shared vertices
 - **Triangle strips and triangle fans**
 - compression schemes for fast transmission
 - **Triangle-neighbor data structure**
 - supports adjacency queries
 - **Winged-edge data structure**
 - supports general polygon meshes
- ← crucial for Mesh assignment
- }
- Interesting and useful but not used in Mesh assignment

Separate triangles

	[0]	[1]	[2]
tris[0]	x_0, y_0, z_0	x_2, y_2, z_2	x_1, y_1, z_1
tris[1]	x_0, y_0, z_0	x_3, y_3, z_3	x_2, y_2, z_2
	\vdots	\vdots	\vdots



Separate triangles

- **array of triples of points**
 - float[n_T][3][3]: about 72 bytes per vertex
 - 2 triangles per vertex (on average)
 - 3 vertices per triangle
 - 3 coordinates per vertex
 - 4 bytes per coordinate (float)
- **various problems**
 - wastes space (each vertex stored 6 times)
 - cracks due to roundoff
 - difficulty of finding neighbors at all

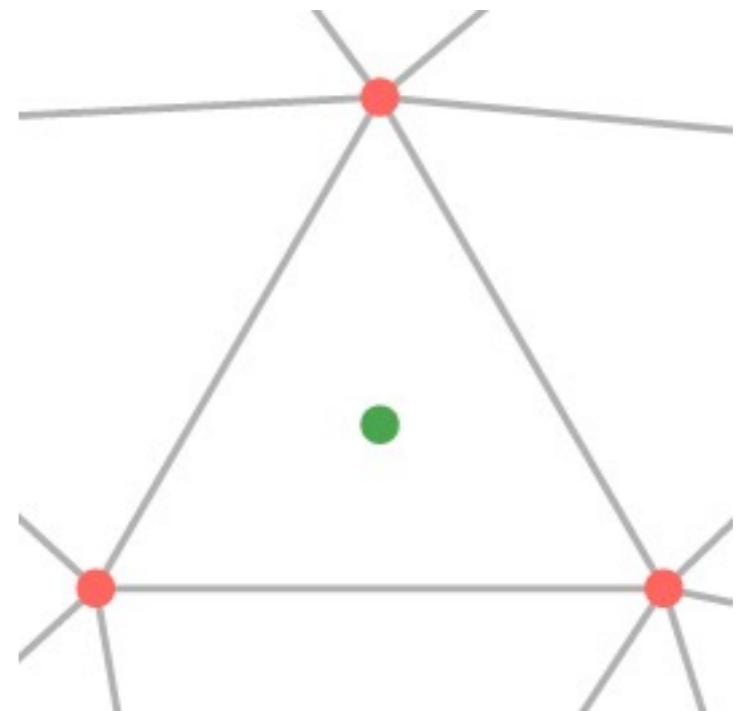
Indexed triangle set

- **Store each vertex once**
- **Each triangle points to its three vertices**

```
Triangle {  
    Vertex vertex[3];  
}
```

```
Vertex {  
    float position[3]; // or other data  
}  
// ... or ...
```

```
Mesh {  
    float verts[nv][3]; // vertex positions (or other data)  
    int tInd[nt][3]; // vertex indices  
}
```



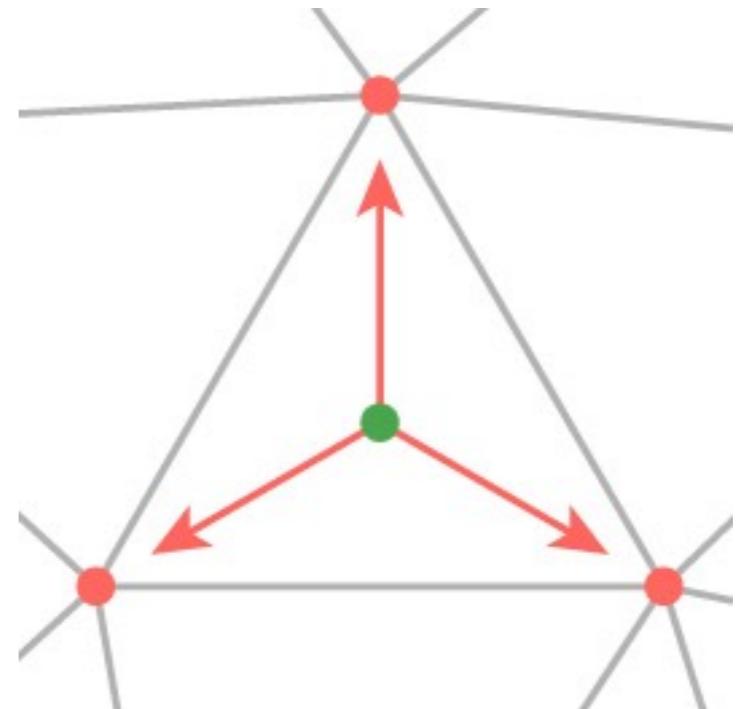
Indexed triangle set

- **Store each vertex once**
- **Each triangle points to its three vertices**

```
Triangle {  
    Vertex vertex[3];  
}
```

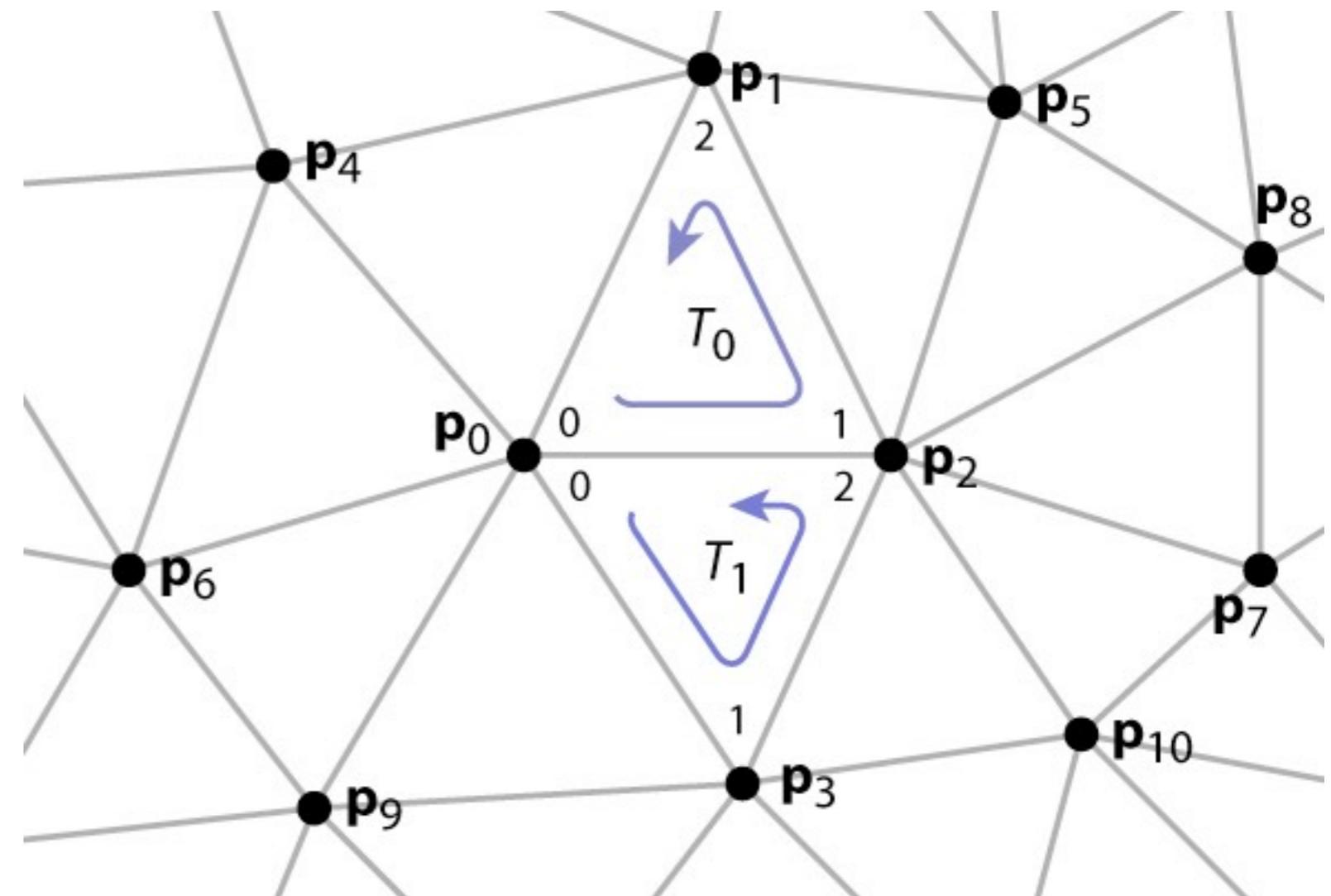
```
Vertex {  
    float position[3]; // or other data  
}  
// ... or ...
```

```
Mesh {  
    float verts[nv][3]; // vertex positions (or other data)  
    int tInd[nt][3]; // vertex indices  
}
```



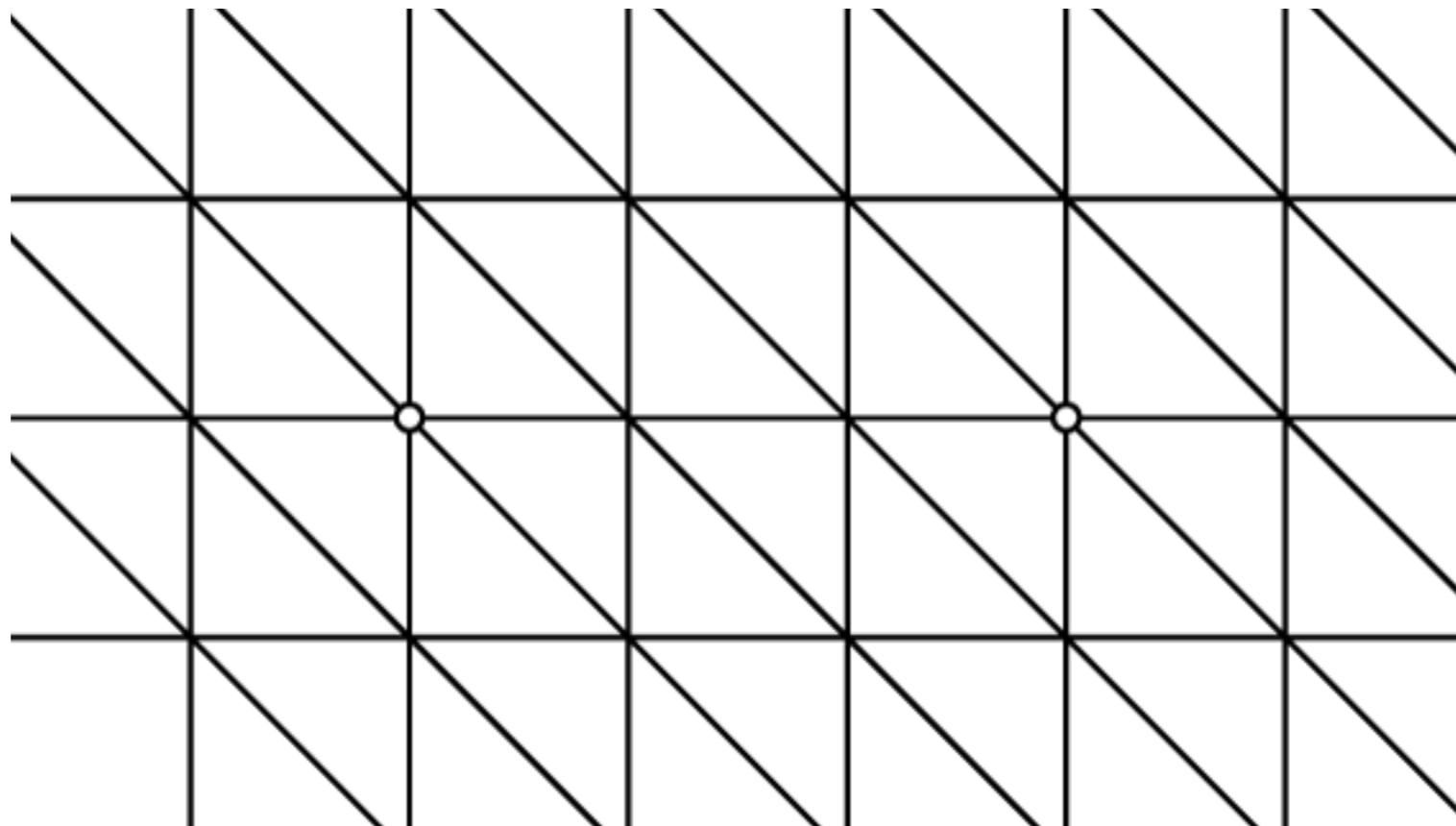
Indexed triangle set

verts[0]	x_0, y_0, z_0
verts[1]	x_1, y_1, z_1
	x_2, y_2, z_2
	x_3, y_3, z_3
:	
tInd[0]	0, 2, 1
tInd[1]	0, 3, 2
:	



Estimating storage space

- $n_T = \# \text{tris}$; $n_V = \# \text{verts}$; $n_E = \# \text{edges}$
- **Rule of thumb:** $n_T:n_E:n_V$ is about 2:3:1



[Alec Jacobson]

Indexed triangle set

- **array of vertex positions**
 - float[n_V][3]: 12 bytes per vertex
 - (3 coordinates × 4 bytes) per vertex
- **array of triples of indices (per triangle)**
 - int[n_T][3]: about 24 bytes per vertex
 - 2 triangles per vertex (on average)
 - (3 indices × 4 bytes) per triangle
- **total storage: 36 bytes per vertex (factor of 2 savings)**
- **represents topology and geometry separately**
- **finding neighbors is at least well defined**

Practical encoding of meshes

- **OBJ file format**
 - widely used format for polygon meshes in indexed form
 - supports the usual attributes: position, normal, texture coordinate
 - allows triangles or polygons (only triangles and quads widely supported)
 - comes with a crude mechanism for adding materials
- **Demo**
 - simple file with one triangle

Data on meshes

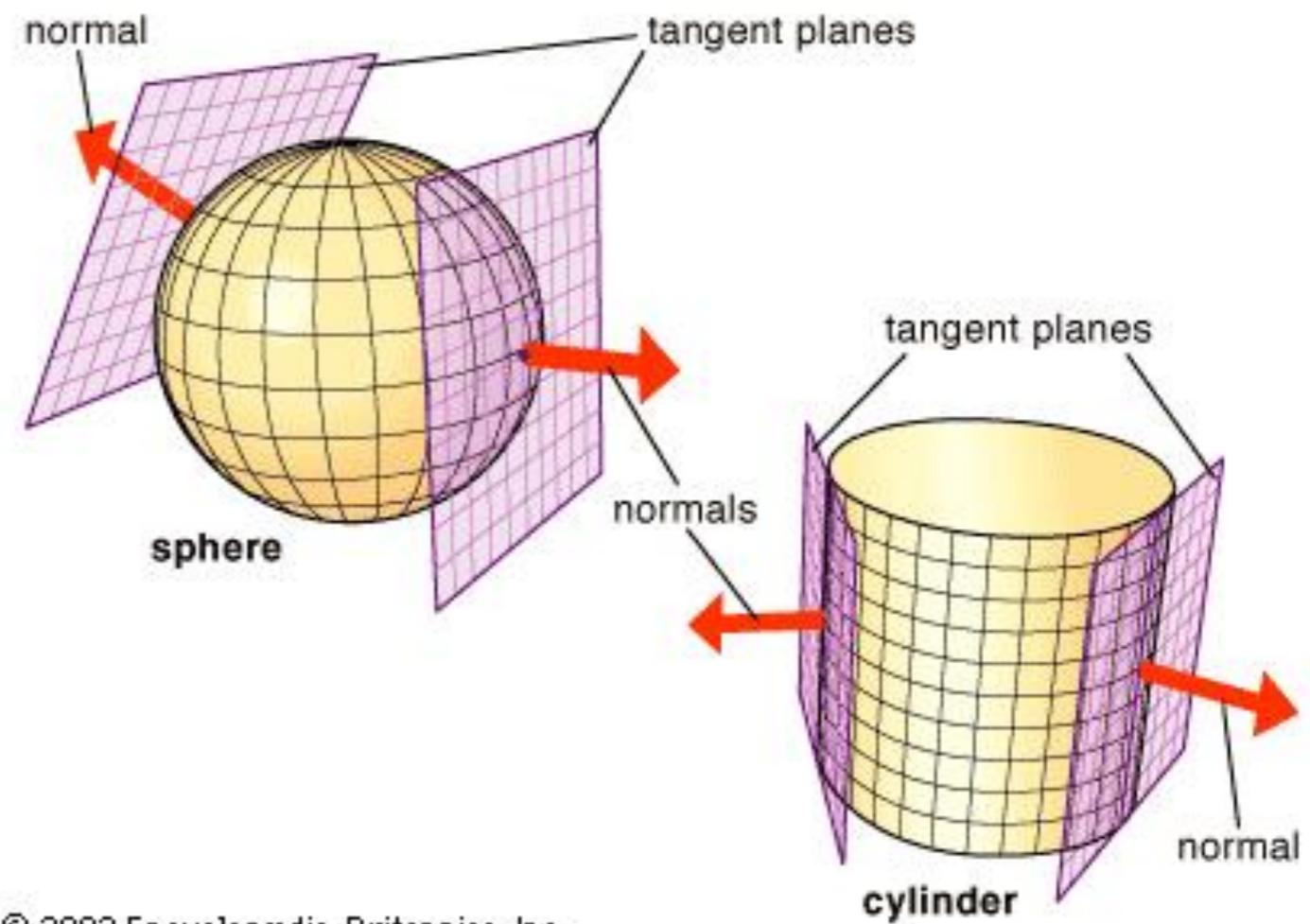
- **Often need to store additional information besides just the geometry**
- **Can store additional data at faces, vertices, or edges**
- **Examples**
 - colors stored on faces, for faceted objects
 - information about sharp creases stored at edges
 - any quantity that varies continuously (without sudden changes, or *discontinuities*) gets stored at vertices

Key types of vertex data

- **Surface normals**
 - when a mesh is approximating a curved surface, store normals at vertices
- **Surface parameterizations**
 - providing a 2D coordinate system on the surface
- **Positions**
 - at some level this is just another piece of data
 - position varies continuously between vertices

Differential geometry 101

- **Tangent plane**
 - at a point on a smooth surface in 3D, there is a unique plane tangent to the surface, called the *tangent plane*
- **Normal vector**
 - vector perpendicular to a surface (that is, to the tangent plane)
 - only unique for smooth surfaces (not at corners, edges)



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Surface parameterization

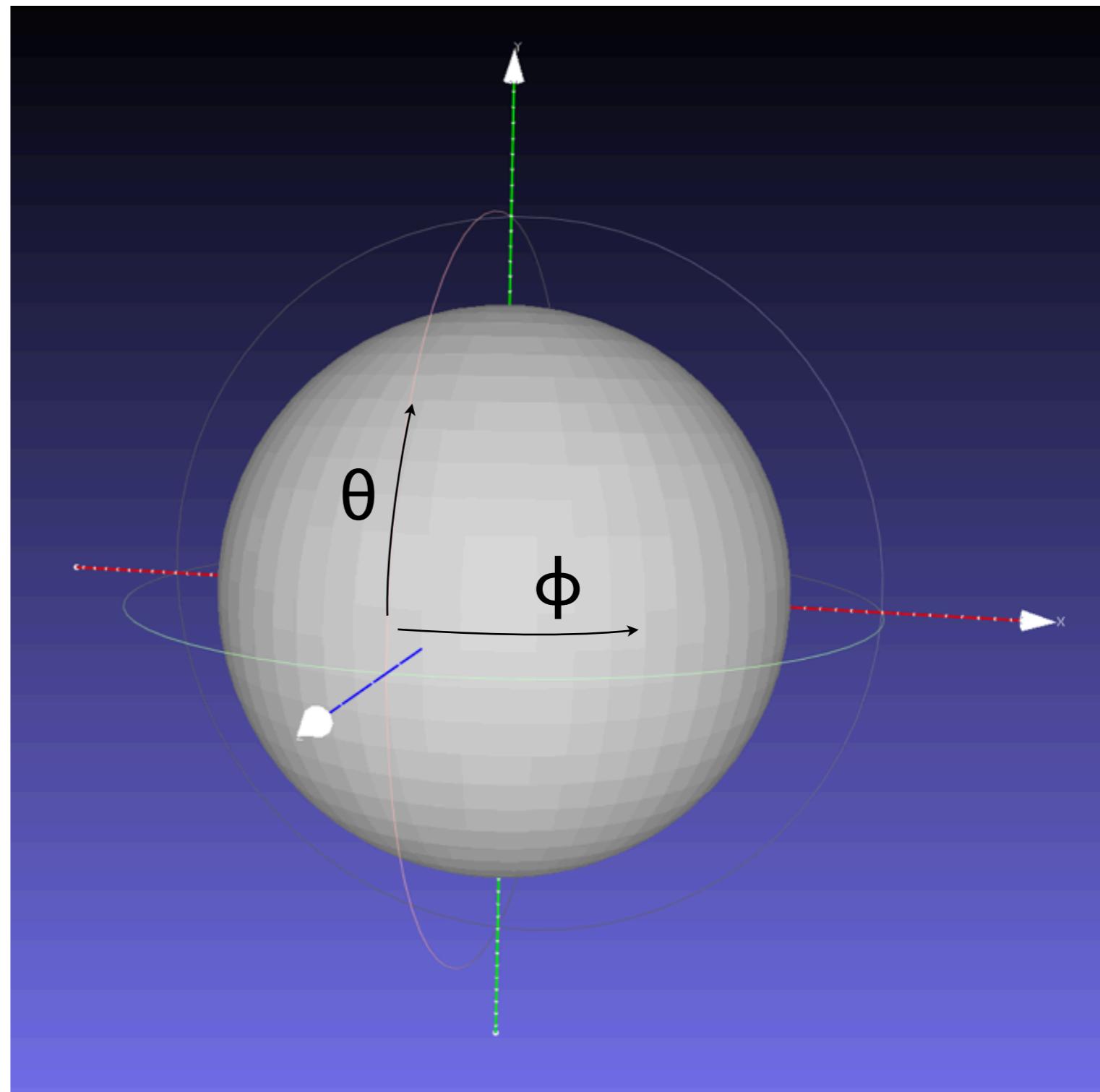
- **A surface in 3D is a two-dimensional thing**
- **Sometimes we need 2D coordinates for points on the surface**
- **Defining these coordinates is *parameterizing* the surface**
- **Examples:**
 - cartesian coordinates on a rectangle (or other planar shape)
 - cylindrical coordinates (θ, y) on a cylinder
 - latitude and longitude on the Earth's surface
 - spherical coordinates (θ, ϕ) on a sphere
- **Spoiler alert:**
 - in graphics, parameterizations are most often used for *texture mapping*.
 - therefore many systems call the parameters “texture coordinates.”

Example: unit sphere

- **position:**
$$x = \cos \theta \sin \phi$$
$$y = \sin \theta$$
$$z = \cos \theta \cos \phi$$
- **normal is position (easy!)**
- **texture coordinates**

$$u = \frac{\theta}{\pi} + \frac{1}{2}$$

$$v = \frac{\phi}{2\pi} + \frac{1}{2}$$

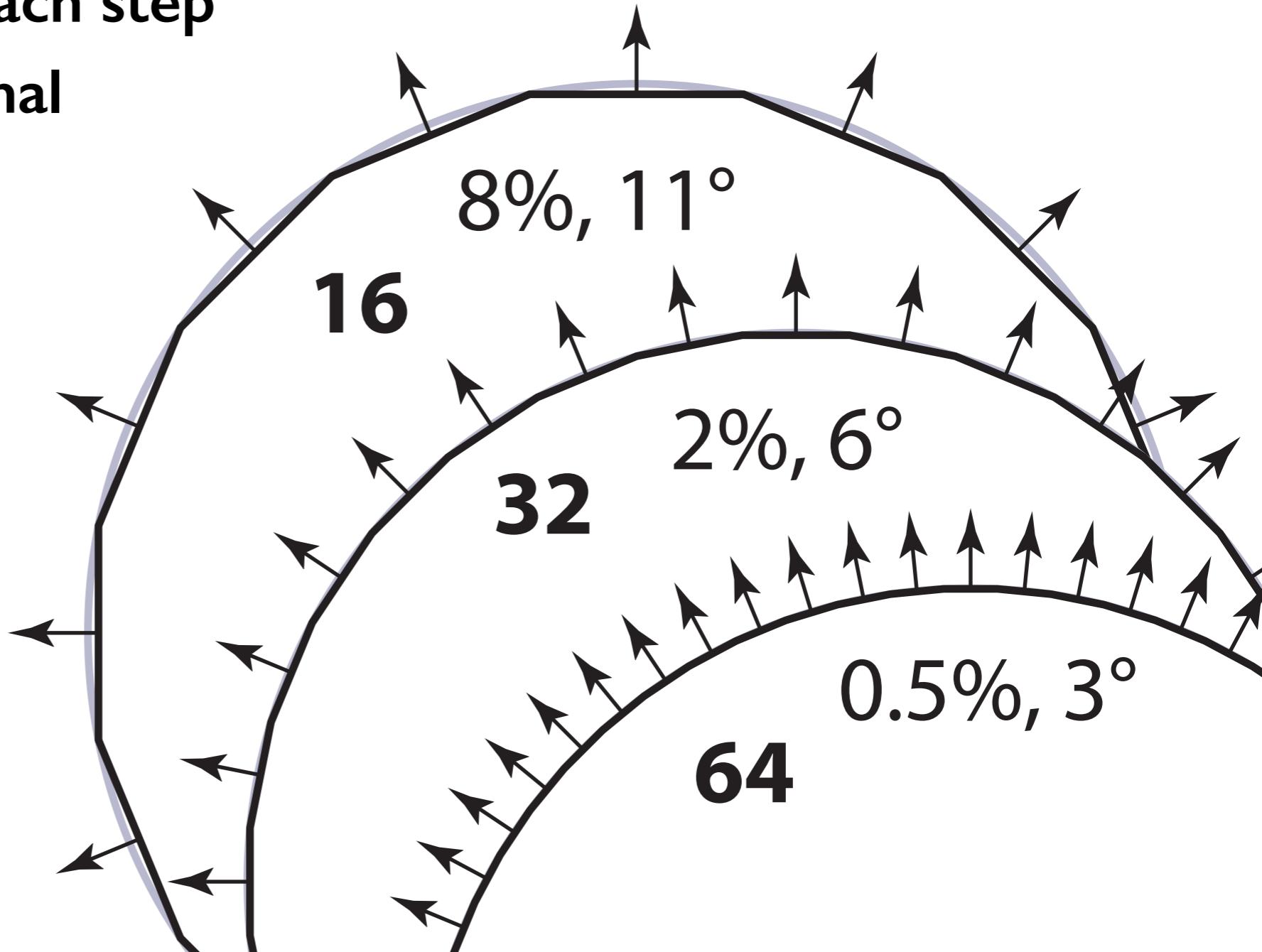


How to think about vertex normals

- **Piecewise planar approximation converges pretty quickly to the smooth geometry as the number of triangles increases**
 - for mathematicians: error is $O(h^2)$
- **But the surface normals don't converge so well**
 - normal is constant over each triangle, with discontinuous jumps across edges
 - for mathematicians: error is only $O(h)$
- **Better: store the “real” normal at each vertex, and interpolate to get normals that vary gradually across triangles**

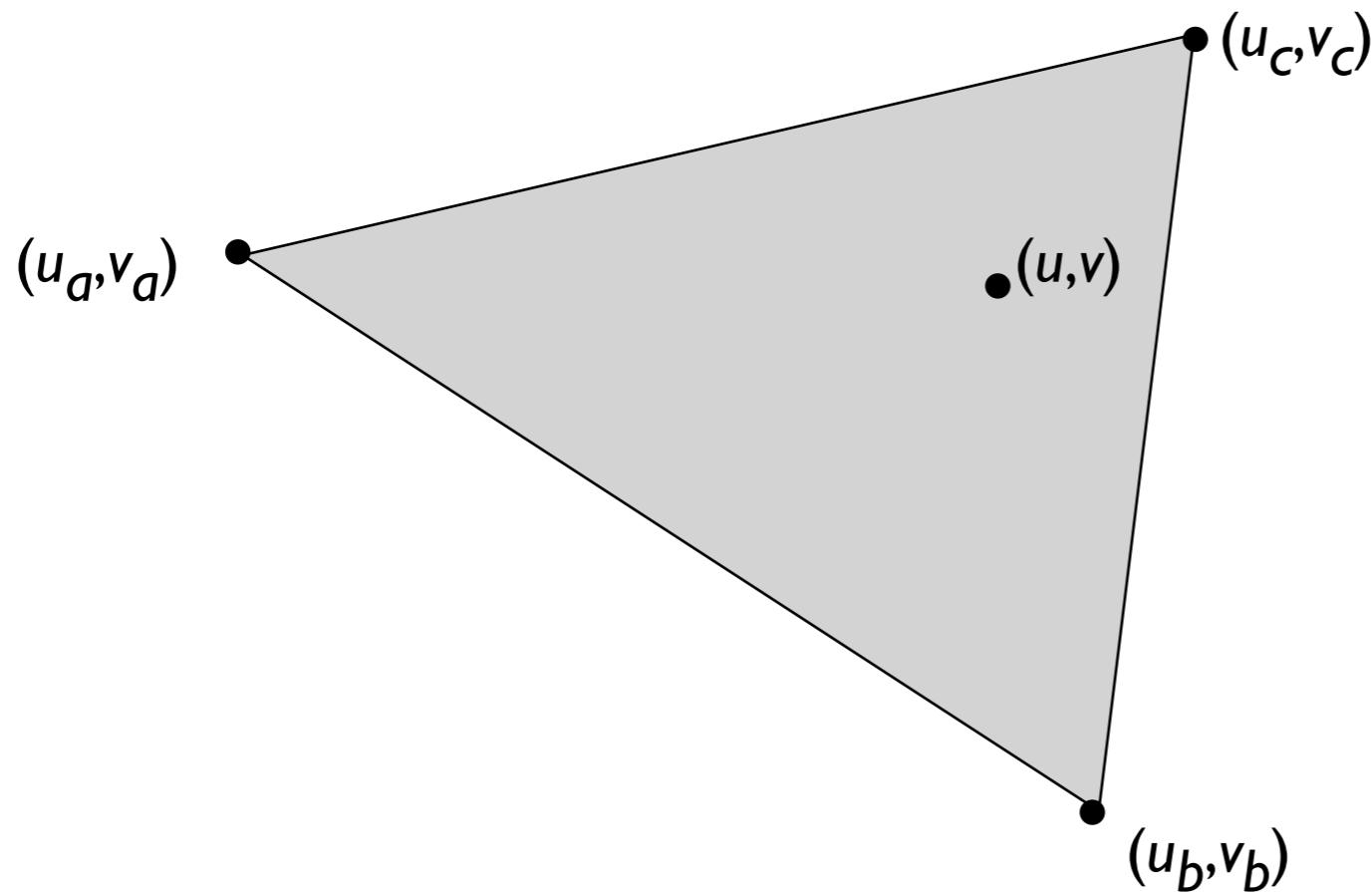
Interpolated normals—2D example

- Approximating circle with increasingly many segments
- Max error in position error drops by factor of 4 at each step
- Max error in normal only drops by factor of 2

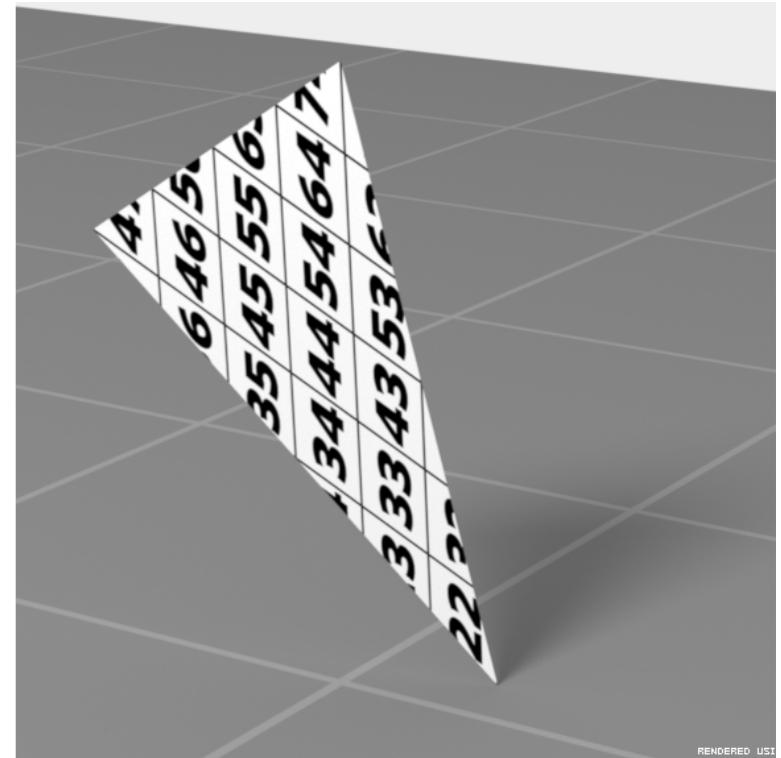


Parameterizing a single triangle

- **Triangles**
 - specify (u,v) for each vertex
 - define (u,v) for interior by linear interpolation



09	19	29	39	49	59	69	79	89	99
08	18	28	38	48	58	68	78	88	98
07	17	27	37	47	57	67	77	87	97
06	16	26	36	46	56	66	76	86	96
05	15	25	35	45	55	65	75	85	95
04	14	24	34	44	54	64	74	84	94
03	13	23	33	43	53	63	73	83	93
02	12	22	32	42	52	62	72	82	92
01	11	21	31	41	51	61	71	81	91
00	10	20	30	40	50	60	70	80	90



Practical encoding of mesh attributes

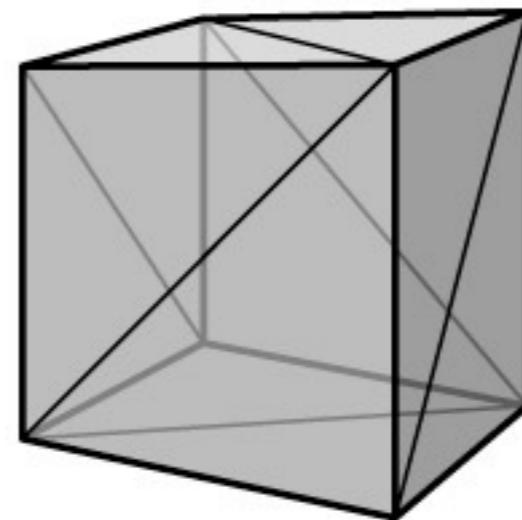
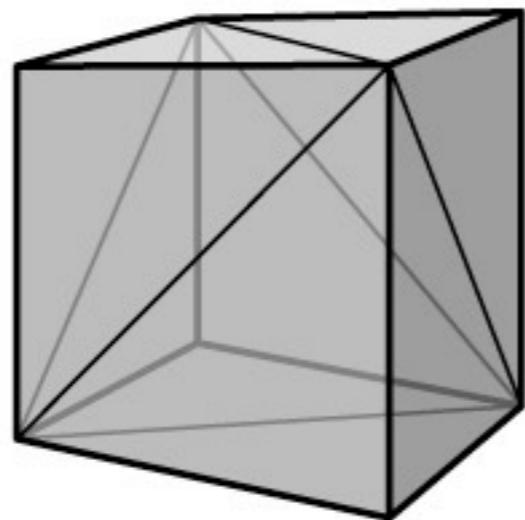
- **OBJ file format**
 - supports specifying normals and texture coordinates at vertices
 - particularly flexible about continuity of attributes
- **Demo**
 - simple file with one triangle
 - effects of normals and texture coords
 - exploration of continuity and discontinuity

Validity of triangle meshes

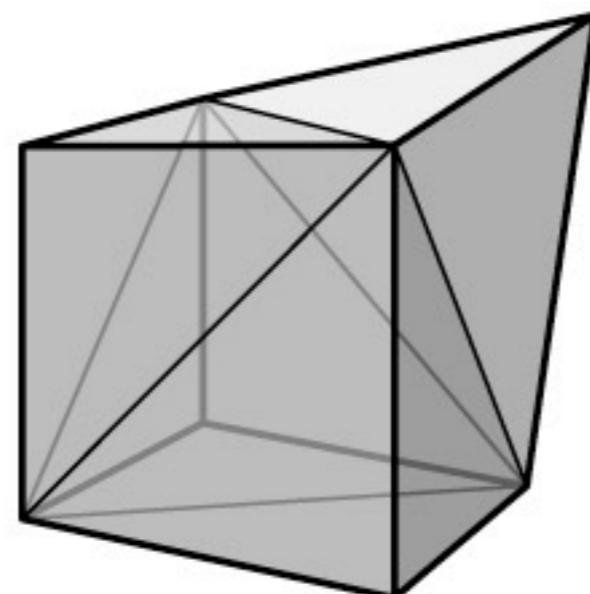
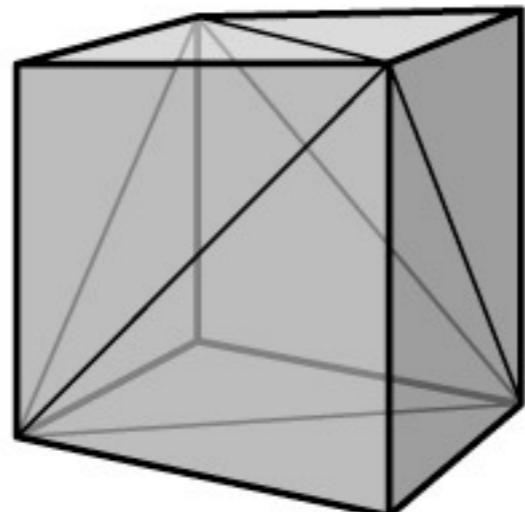
- in many cases we care about the mesh being able to bound a region of space nicely
- in other cases we want triangle meshes to fulfill assumptions of algorithms that will operate on them (and may fail on malformed input)
- two completely separate issues:
 - **mesh topology**: how the triangles are connected (ignoring the positions entirely)
 - **geometry**: where the triangles are in 3D space

Topology/geometry examples

- **same geometry, different mesh topology:**



- **same mesh topology, different geometry:**

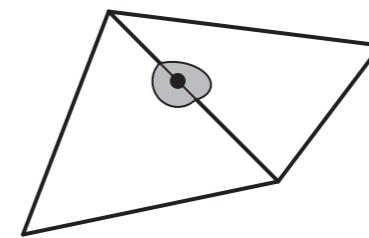


Topological validity

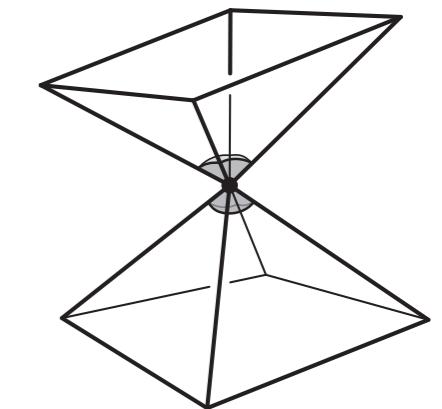
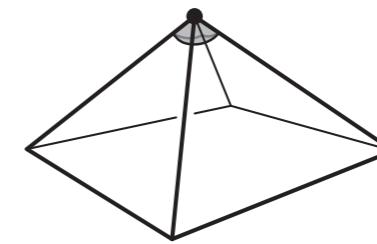
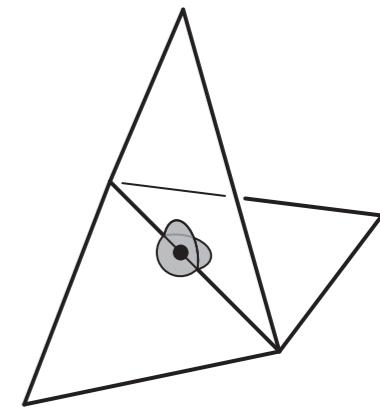
- **strongest property: be a manifold**

- this means that no points should be "special"
- interior points are fine
- edge points: each edge must have exactly 2 triangles
- vertex points: each vertex must have one loop of triangles

manifold



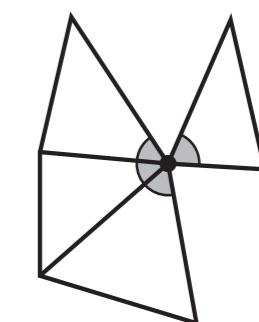
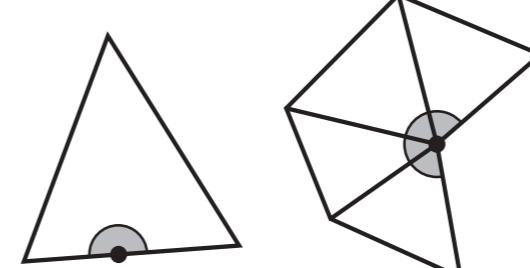
not
manifold



- **slightly looser: manifold with boundary**

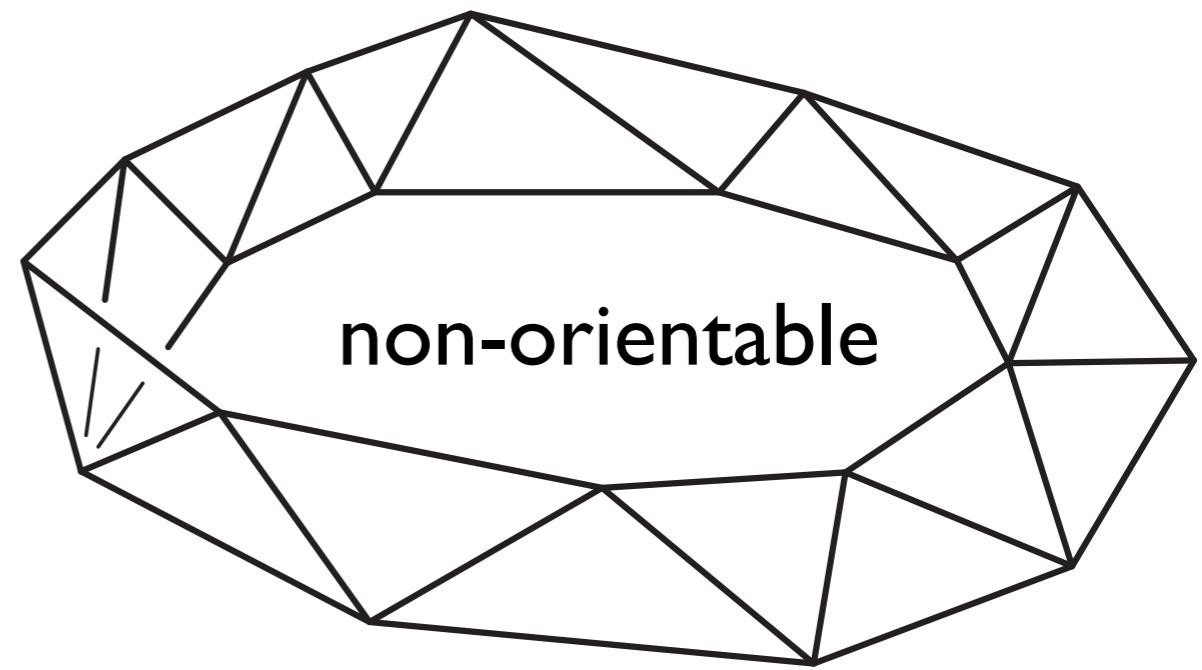
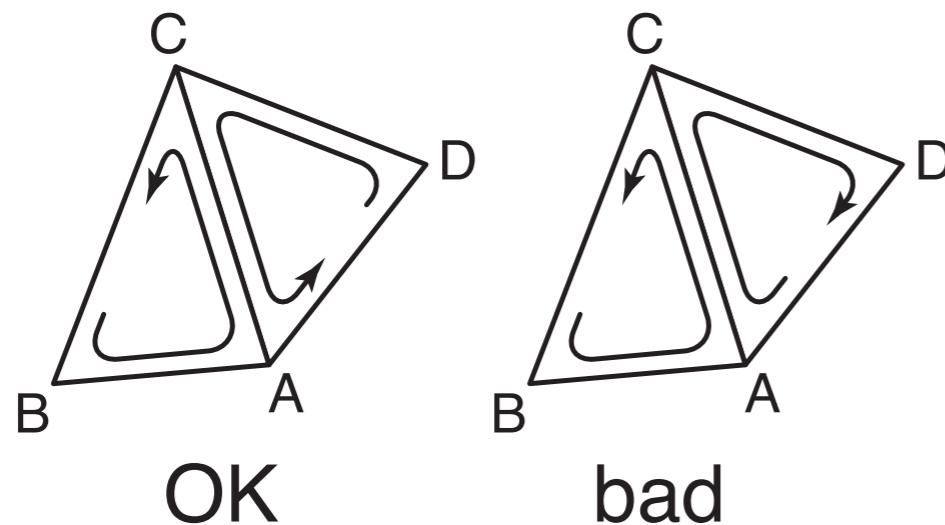
- weaken rules to allow boundaries

with boundary



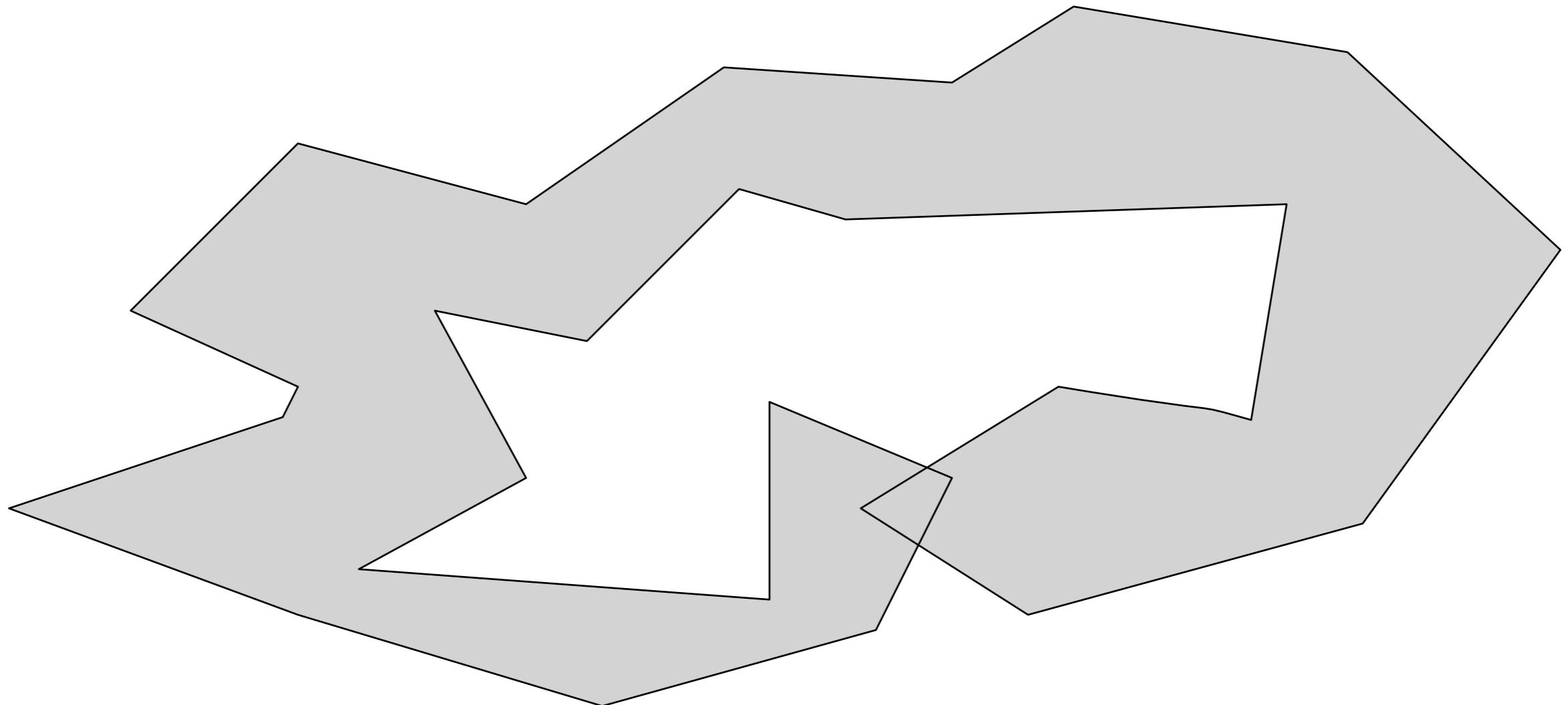
Topological validity

- **Consistent orientation**
 - Which side is the “front” or “outside” of the surface and which is the “back” or “inside?”
 - rule: you are on the outside when you see the vertices in counter-clockwise order
 - in mesh, neighboring triangles should agree about which side is the front!
 - caution: not always possible



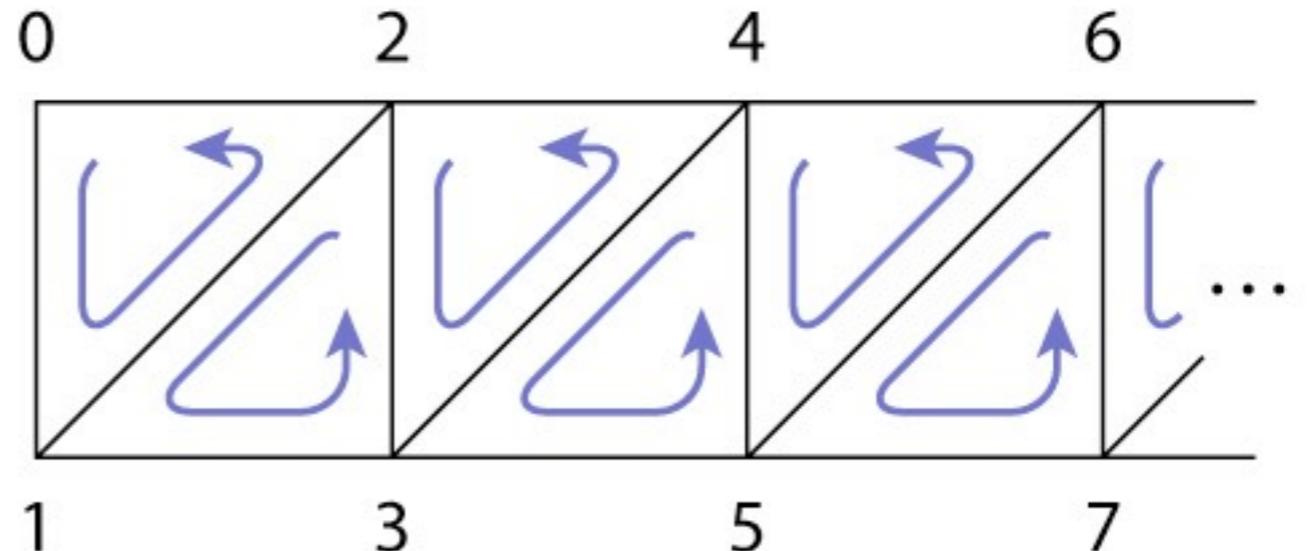
Geometric validity

- **generally want non-self-intersecting surface**
- **hard to guarantee in general**
 - because far-apart parts of mesh might intersect



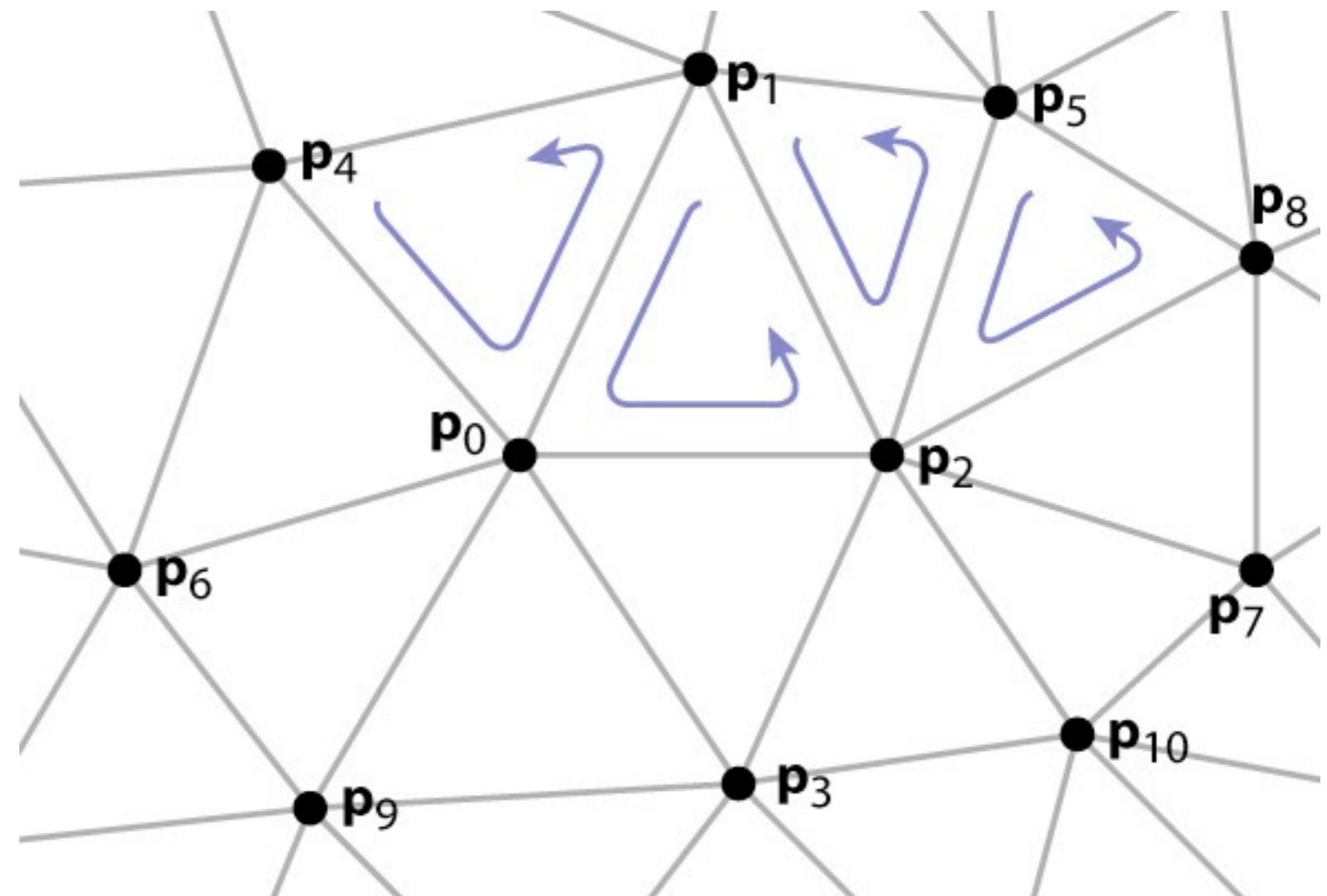
Triangle strips

- **Take advantage of the mesh property**
 - each triangle is usually adjacent to the previous
 - let every vertex create a triangle by reusing the second and third vertices of the previous triangle
 - every sequence of three vertices produces a triangle (but not in the same order)
 - e. g., $0, 1, 2, 3, 4, 5, 6, 7, \dots$ leads to $(0 \mid 2), (2 \mid 3), (2 \ 3 \ 4), (4 \ 3 \ 5), (4 \ 5 \ 6), (6 \ 5 \ 7), \dots$
 - for long strips, this requires about one index per triangle



Triangle strips

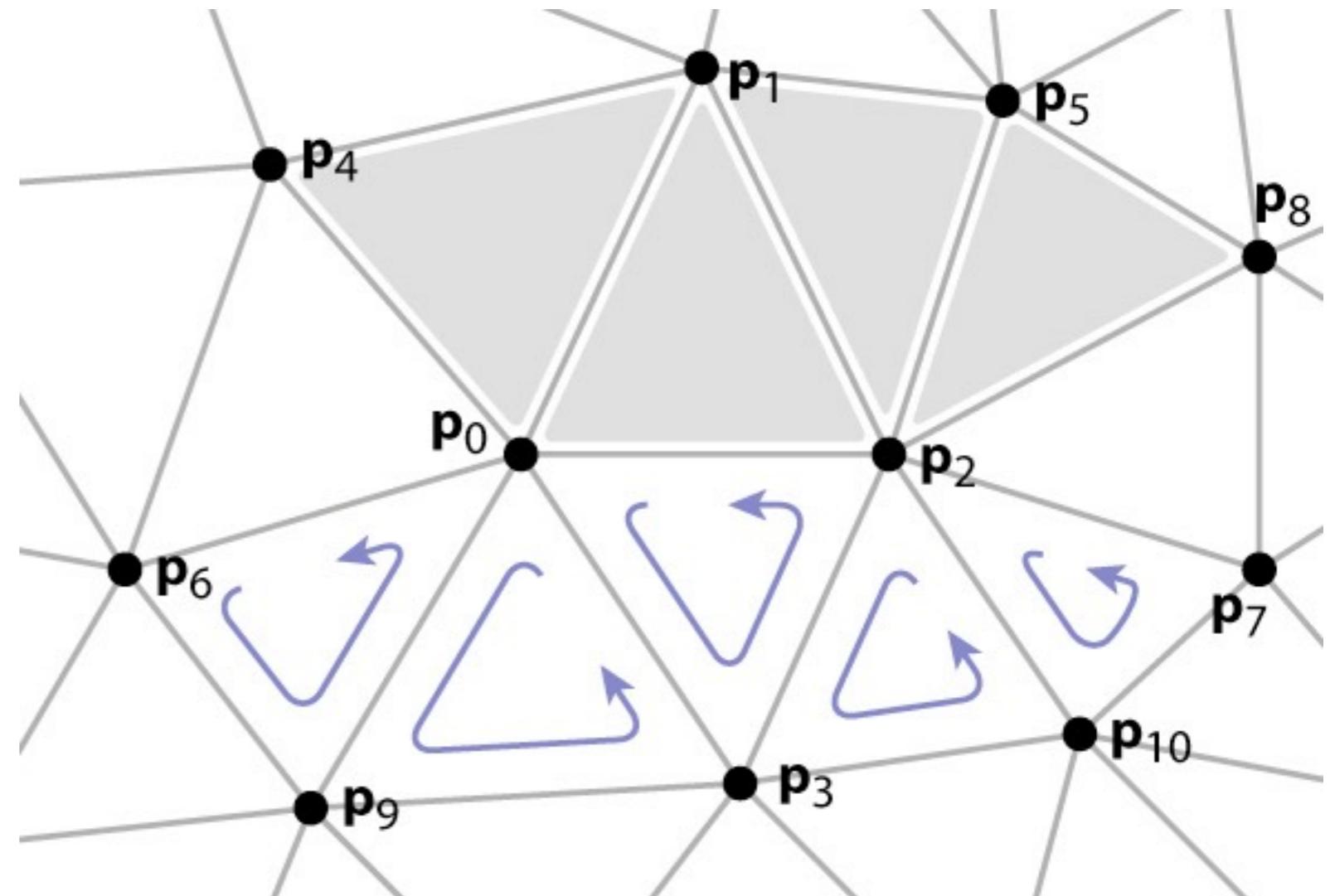
verts[0]	x_0, y_0, z_0
verts[1]	x_1, y_1, z_1
	x_2, y_2, z_2
	x_3, y_3, z_3
	\vdots
tStrip[0]	4, 0, 1, 2, 5, 8
tStrip[1]	6, 9, 0, 3, 2, 10, 7
	\vdots



Triangle strips

verts[0]	x_0, y_0, z_0
verts[1]	x_1, y_1, z_1
	x_2, y_2, z_2
	x_3, y_3, z_3
	\vdots

tStrip[0]	4, 0 , 1, 2, 5, 8
tStrip[1]	6, 9, 0, 3, 2, 10, 7
	\vdots



Triangle strips

- **array of vertex positions**
 - float[n_V][3]: 12 bytes per vertex
 - (3 coordinates × 4 bytes) per vertex
- **array of index lists**
 - int[n_S][variable]: 2 + n indices per strip
 - on average, (1 + ϵ) indices per triangle (assuming long strips)
 - 2 triangles per vertex (on average)
 - about 4 bytes per triangle (on average)
- **total is 20 bytes per vertex (limiting best case)**
 - factor of 3.6 over separate triangles; 1.8 over indexed mesh

Triangle fans

- **Same idea as triangle strips, but keep oldest rather than newest**
 - every sequence of three vertices produces a triangle
 - e.g., 0, 1, 2, 3, 4, 5, ... leads to
 $(0 \ 1 \ 2), (0 \ 2 \ 3), (0 \ 3 \ 4), (0 \ 4 \ 5), \dots$
 - for long fans, this requires
about one index per triangle
- **Memory considerations exactly the same as triangle strip**

