## Numerical Solutions of nonlinear equations.

Problem: Given f(x): continuous, real-valued, possibly non-linear. Find a root r of f(x) such that f(r)=0.

- Bisection
- · Fixed point iteration
- · Newton's method
- · Secant method

#### **Bisection Method**

Basic idea: Given f(x), a continuous function. If we find some a and b, such that f(a) and f(b) are of opposite sign, then, there exists a point c, between a and b, such that f(c) = 0.

This fact follows from the continuity of f.

#### Procedure:

- Initialization: Find a,b such that  $f(a)\cdot f(b)<0$ . This means there is a root  $r\in(a,b)$  s.t. f(r)=0.
- $\bullet \ \ \mathsf{Let} \ c = \tfrac{a+b}{2}, \, \mathsf{mid}\text{-point}.$ 
  - If f(c) = 0, done (lucky!)
  - else:
    - $\circ$  if  $f(c) \cdot f(a) < 0$ , pick the interval [a,c]
    - $\circ$  if  $f(c) \cdot f(b) < 0$ , pick the interval [c,b],
  - Iterate the procedure until stop criteria satisfied.

#### Stop Criteria:

- 1) interval small enough, i.e.,  $(b-a) \leq \epsilon$ ,
- 2) |f(c)| very small, i.e,  $|f(c)| \leq \epsilon$
- 3) max number of iteration reached. (to avoid dead loop, in case the method does not converge.)
- 4) any combination of the previous ones.

### Convergence Analysis

Consider  $[a_0,b_0]$  ,  $c_0=rac{a_0+b_0}{2}$  , let  $r\in(a_0,b_0)$  be a root. The error:  $e_0=|r-c_0|\leqrac{b_0-a_0}{2}$ 

Denote the further intervals as  $[a_n, b_n]$  for iteration number n.

$$|e_n = |r - c_n| \leq rac{b_n - a_n}{2} \leq rac{b_0 - a_0}{2^{n+1}} = rac{e_0}{2^n}.$$

If the error tolerance is  $\varepsilon$ , we require  $e_n \leq \varepsilon$ , then

$$rac{b_0-a_0}{2^{n+1}} \leq arepsilon \Rightarrow n \geq rac{\ln(b-a)-\ln(2arepsilon)}{\ln 2}, \quad ( ext{$\#$ of steps})$$

#### Fixed point iteration

We rewrite the equation f(x) = 0 into the form x = g(x). Remark: This can always be achieved, for example: x = f(x) + x. However, the choice of g makes a difference in convergence.

Main idea: Make a guess of the solution, say  $\bar{x}$ . If the function g(x) is "nice", then hopefully,  $g(\bar{x})$  should be closer to the answer than  $\bar{x}$ . If that is the case, then we can iterate.

Iteration algorithm:

- Choose a start point  $x_0$ ,
- Do the iteration  $x_{k+1}=g\left(x_{k}\right)$  ,  $k=0,1,2,\cdots$  until meeting stop criteria.

Stop Criteria: Let  $\varepsilon$  be the tolerance

- $|x_k x_{k-1}| \leq \varepsilon$ ,
- max # of iteration reached,
- any combination.

#### Example 1

 $x_2 = 0.8576$ 

Find an approximate solution to  $f(x) = x - \cos x = 0$ , with 4 digits accuracy.

Choose  $g(x)=\cos x$ , we have  $x=\cos x$ . Choose  $x_0=1$ , and do the iteration  $x_{k+1}=\cos(x_k)$  :

```
In [ ]: import math
         # Define the function g(x) = cos(x)
         def g(x):
             return math.cos(x)
         # Initial guess
        x0 = 1.0
        # Tolerance for convergence
         tolerance = 1e-4
        # Perform fixed-point iteration
        x_k = x0
        iteration = 0
        while True:
             x_k1 = g(x_k)
             print(f''x_{iteration} = \{x_k:.4f\}'')
             if abs(x_k1 - x_k) < tolerance:
                 break
             x_k = x_{1}
             iteration += 1
        print(f"x_{iteration} + 1) = \{x_k1:.4f\} (converged)")
        x_0 = 1.0000
        x_1 = 0.5403
```

```
x_3 = 0.6543
x_4 = 0.7935
x_5 = 0.7014
x_6 = 0.7640
x_7 = 0.7221
x_8 = 0.7504
x_9 = 0.7314
x_10 = 0.7442
x_{11} = 0.7356
x_12 = 0.7414
x_13 = 0.7375
x_14 = 0.7401
x_15 = 0.7384
x_16 = 0.7396
x_17 = 0.7388
x_18 = 0.7393
x_19 = 0.7389
x_20 = 0.7392
x_21 = 0.7390
x_22 = 0.7391
x_23 = 0.7391 (converged)
```

#### Example 2

 $x_3 = 0.9852$ 

```
Consider f(x)=e^{-2x}(x-1)=0. (root: r=1 ). Rewrite as x=g(x)=e^{-2x}(x-1)+x
```

Choose an initial guess  $x_0 = 0.99$ , very close to the real root.

```
In [ ]: import math
        # Define the function g(x)
        def g(x):
             return math.exp(-2 * x) * (x - 1) + x
        # Initial guess
        x0 = 0.99
        # Tolerance for convergence (just for safety, though the example diverges)
         tolerance = 1e-4
        # Perform fixed-point iteration
        x_k = x0
         iteration = 0
        max_iterations = 30 # Limit iterations to prevent infinite loop
        while iteration < max_iterations:</pre>
             x_k1 = g(x_k)
             print(f''x_{iteration} + 1) = \{x_k1:.4f\}''\}
             if abs(x_k1 - x_k) < tolerance:
                 break
             x_k = x_{1}
             iteration += 1
        # Check if the process diverged
        if iteration == max_iterations:
             print("Diverged. The iteration does not work.")
        else:
             print(f"Converged to {x_k1:.4f} after {iteration + 1} iterations.")
        x_1 = 0.9886
        x_2 = 0.9870
```

```
x_4 = 0.9832
x_5 = 0.9808
x_6 = 0.9781
x_7 = 0.9750
x_8 = 0.9715
x_9 = 0.9674
x_10 = 0.9627
x_11 = 0.9573
x_12 = 0.9510
x_13 = 0.9437
x_14 = 0.9351
x_15 = 0.9251
x_16 = 0.9133
x_17 = 0.8994
x_18 = 0.8828
x_19 = 0.8627
x_20 = 0.8382
x_21 = 0.8080
x_22 = 0.7698
x_23 = 0.7205
x_24 = 0.6543
x_25 = 0.5609
x_26 = 0.4179
x_27 = 0.1655
x_28 = -0.4338
x_29 = -3.8477
x_30 = -10659.9637
Diverged. The iteration does not work.
```

#### Fixed Point iteration, convergence

Our iteration is  $x_{k+1}=g\left(x_{k}\right)$ . Let r be the exact root, s.t., r=g(r). Define the error:  $e_{k}=|x_{k}-r|$ .

$$egin{aligned} e_{k+1} &= \left| x_{k+1} - r 
ight| = \left| g\left( x_k 
ight) - r 
ight| = \left| g\left( x_k 
ight) - g(r) 
ight| \ &= \left| g'(\xi) 
ight| \left| \left( x_k - r 
ight) 
ight| \; \left( \xi \in \left( x_k, r 
ight), \; ext{since $g$ is continuous } 
ight) \ &= \left| g'(\xi) 
ight| e_k \end{aligned}$$

$$\Rightarrow \quad e_{k+1} = \left| g'(\xi) \right| e_k.$$

Observation:

- If  $|g'(\xi)| < 1$ , then  $e_{k+1} < e_k$ , error decreases, the iteration convergence. (linear convergence)
- If  $|g'(\xi)|>1$ , then  $e_{k+1}>e_k$ , error increases, the iteration diverges.

Convergence condition: There exists an interval around r, say [r-a,r+a] for some a>0, such that |g'(x)|<1 for almost all  $x\in[r-a,r+a]$ , and the initial guess  $x_0$  lies in this interval.

In Example 1,  $g(x) = \cos x$ ,  $g'(x) = \sin x$ , r = 0.7391,  $|g'(r)| = |\sin(0.7391)| < 1$ . OK, convergence.

In Example 2, we have

$$g(x) = e^{-2x}(x-1) + x, \ g'(x) = -2e^{-2x}(x-1) + x^{-2x} + 1$$

With r=1, we have

$$|g'(r)| = e^{-2} + 1 > 1$$
, Divergence.

A practical error estimate:

Assume  $|g'(x)| \leq m < 1$  in [r-a, r+a]. We have  $e_{k+1} \leq me_k$ . This gives

$$e_1 \leq me_0, \quad e_2 \leq me_1 \leq m^2e_0, \quad \cdots \quad e_k \leq m^ke_0.$$

This result is useless unless we find a way to estimating  $e_0$ .

$$|e_0| = |r - x_0| = |r - x_1 + x_1 - x_0| \le e_1 + |x_1 - x_0| \le me_0 + |x_1 - x_0|$$

then

$$e_0 \leq rac{1}{1-m}|x_1-x_0|\,, \quad ext{ (can be computed)}$$

Put together

$$e_k \leq \frac{m^k}{1-m}|x_1-x_0|$$

$$e_k \leq \frac{m^k}{1-m}|x_1-x_0|$$

f the error tolerance is  $\varepsilon$ , then

$$\frac{m^k}{1-m}|x_1-x_0|\leq \varepsilon,$$

If the error tolerance is  $\varepsilon$ , then

$$egin{aligned} rac{m^k}{1-m}|x_1-x_0| & \leq arepsilon, \ m^k & \leq rac{arepsilon(1-m)}{|x_1-x_0|} \ k & \geq rac{\ln(arepsilon(1-m)) - \ln|x_1-x_0|}{\ln m} \end{aligned}$$

which give the minimum number of iterations needed to achieve an error  $\leq \varepsilon$ .

Example 3. We want to solve  $\cos x - x = 0$  with the fixed point iteration

$$x = g(x) = \cos x, \quad x_0 = 1,$$

with error tolerance  $\varepsilon=10^{-5}$ . Find the  $\min\#$  iterations. We know  $r\in[0,1]$ . We see that the iteration happens between x=0 and x=1. For  $x\in[0,1]$ , we have

$$|g'(x)| = |\sin x| \le \sin 1 = 0.8415, \quad m \doteq 0.8415$$

And  $x_1=\cos x_0=0.5403.$  Using the formula

$$k \geq rac{\ln(arepsilon(1-m)) - \ln|x_1 - x_0|}{\ln m} pprox 73 \quad \# ext{ iterations needed}$$

In actual simulation k=25 is enough.

#### Newton's Method

Goal: Given f(x), find a root r s.t. f(r) = 0.

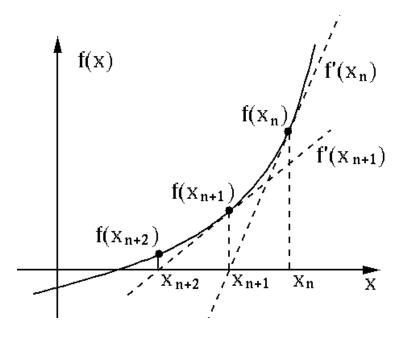
Main idea: Given  $x_k$ , the next approximation  $x_{k+1}$  is determined by approximating f(x) as a linear function at  $x_k$ .

We have

$$rac{f\left(x_{k}
ight)}{x_{k}-x_{k+1}}=f^{\prime}\left(x_{k}
ight)$$

which gives

$$x_{k+1} = x_k - rac{f\left(x_k
ight)}{f'\left(x_k
ight)}$$



Newton's method is a fixed point iteration

$$x_{k+1}=g\left(x_{k}
ight),\quad g(x)=x-rac{f(x)}{f'(x)}.$$

If r is a fixed point, assume f'(r) 
eq 0, then

$$r=g(r),\quad r=r-rac{f(r)}{f'(r)},\quad rac{f(r)}{f'(r)}=0,\quad f(r)=0.$$

then r is a root.

Observation: A fixed point iteration x=g(x) is optimal if  $g^{\prime}(r)=0$  where r=g(r). For Newton, we have

$$g'(x) = 1 - rac{f'(x)f'(x) - f''(x)f(x)}{\left(f'(x)
ight)^2} = rac{f''(x)f(x)}{\left(f'(x)
ight)^2}$$

Then

$$g'(r) = \frac{f''(r)f(r)}{(f'(r))^2} = 0$$

which is the "best" possible scenario!

#### Newton's iteration, convergence

Let r be the root so f(r) = 0 and r = g(r). Recall g'(r) = 0. Define Error:

$$|e_{k+1}| = |x_{k+1} - r| = |g(x_k) - g(r)|$$

Taylor expansion for  $q(x_k)$  at r:

$$egin{align} g\left(x_{k}
ight) = &g(r) + \left(x_{k} - r
ight)g'(r) + rac{1}{2}(x_{k} - r)^{2}g''(\xi), & \xi \in (x_{k}, r) \ = &g(r) + rac{1}{2}(x_{k} - r)^{2}g''(\xi) \ &e_{k+1} = rac{1}{2}(x_{k} - r)^{2}\left|g''(\xi)
ight| = rac{1}{2}e_{k}^{2}\left|g''(\xi)
ight| \ \end{split}$$

Write now  $M=rac{1}{2}\max_x|g''(\xi)|$  , we have

$$e_{k+1} \leq M(e_k)^2$$

This is called quadratic convergence.

Theorem: If  $e_{k+1} \leq Me_k^2$ , then  $\lim_{k \to +\infty} e_k = 0$  if  $e_0$  is sufficiently small. (This means, M can be big, but it would not effect the convergence!)

Proof for the convergence: We have

$$e_1 \leq (Me_0) \, e_0$$

If  $e_0$  is small enough, such that  $(Me_0) < 1$ , then  $e_1 < e_0$ . This means  $(Me_1) < Me_0 < 1$ , and so

$$e_2 \leq (Me_1) e_1 < e_1, \quad \Rightarrow \quad Me_2 < Me_1 < 1$$

By an induction argument, we conclude that  $e_{k+1} < e_k$  for all k, i.e., error is strictly decreasing after each iteration.  $\Rightarrow$  convergence.

#### Example

Find a numerical method to compute  $\sqrt{a}$  using only +,-,\*,/ arithmetic operations. Test it for a=3. Answer. It's easy to see that  $\sqrt{a}$  is a root for  $f(x)=x^2-a$ . Newton's method gives

$$x_{k+1}=x_k-rac{f\left(x_k
ight)}{f'\left(x_k
ight)}=x_k-rac{x_k^2-a}{2x_k}=rac{x_k}{2}+rac{a}{2x_k}$$

Test it on a=3 : Choose  $x_0=1.7$ .

$$egin{aligned} x_0 &= 1.7 & ext{error} \ x_1 &= 1.7324 & 7.2 imes 10^{-2} \ x_2 &= 1.7321 & 3.0 imes 10^{-4} \ x_3 &= 1.7321 & 2.6 imes 10^{-8} \ 4.4 imes 10^{-16} \end{aligned}$$

Note the extremely fast convergence

#### Example

To find the root of  $f(x) = e^{-2x}(x-1)$  using Newton's method, we need to follow these steps:

- 1. Define the function f(x) and its derivative f'(x).
- 2. Choose an initial guess  $x_0$ .
- 3. Perform the iteration  $x_{k+1} = x_k rac{f(x_k)}{f'(x_k)}$  until the result converges.

First, let's compute the derivative f'(x):

$$f(x) = e^{-2x}(x-1)$$

Using the product rule:

$$f'(x) = rac{d}{dx}ig[e^{-2x}(x-1)ig] = e^{-2x}(-2(x-1)) + e^{-2x} = e^{-2x}(-2x+2+1) = e^{-2x}(-2x+3)$$

Now we have:

$$f(x) = e^{-2x}(x-1)$$
  
 $f'(x) = e^{-2x}(-2x+3)$ 

```
In [ ]: import math
        # Define the function f(x)
             return math.exp(-2 * x) * (x - 1)
        # Define the derivative f'(x)
        def f_prime(x):
             return math.exp(-2 * x) * (-2 * x + 3)
        # Initial guess
        x0 = 0.99 # Close to the root
        # Tolerance for convergence
        tolerance = 1e-6
        # Perform Newton's method iteration
        x_k = x0
        iteration = 0
        max_iterations = 100 # Limit iterations to prevent infinite loop
        while iteration < max_iterations:</pre>
            f_xk = f(x_k)
            f_{prime_xk} = f_{prime(x_k)}
```

```
# Ensure we don't divide by zero
if f_prime_xk == 0:
    print("Derivative is zero. No solution found.")
    break

x_k1 = x_k - f_xk / f_prime_xk
print(f"Iteration {iteration + 1}: x = {x_k1:.6f}")

if abs(x_k1 - x_k) < tolerance:
    print(f"Converged to {x_k1:.6f} after {iteration + 1} iterations.")
    break

x_k = x_k1
iteration += 1

if iteration == max_iterations:
    print("Did not converge within the maximum number of iterations.")</pre>
```

```
Iteration 1: x = 0.999804

Iteration 2: x = 1.000000

Iteration 3: x = 1.000000

Converged to 1.000000 after 3 iterations.
```

#### Secant Method

If f(x) is complicated, f'(x) might not be available. Solution for this situation: using approximation for f', i.e.,

$$f'\left(x_{k}
ight)pproxrac{f\left(x_{k}
ight)-f\left(x_{k-1}
ight)}{x_{k}-x_{k-1}}$$

This is secant method:

$$x_{k+1} = x_k - rac{x_k - x_{k-1}}{f\left(x_k
ight) - f\left(x_{k-1}
ight)} f\left(x_k
ight)$$

Initial guess needed:  $x_0, x_1$ .

Advantages include

- No computation of f';
- One f(x) computation each step;
- · Also rapid convergence.

A bit on convergence: One can show that

$$e_{k+1} \leq C e_k^lpha, \quad lpha = rac{1}{2}(1+\sqrt{5}) pprox 1.62$$

This is called super linear convergence.  $(1 < \alpha < 2)$ 

It converges for all function f if  $x_0$  and  $x_1$  are close to the root r.

#### Example

Use secant method for computing  $\sqrt{a}$ . Answer. The iteration now becomes

$$x_{k+1} = x_k - rac{\left(x_k^2 - a
ight)\left(x_k - x_{k-1}
ight)}{\left(x_k^2 - a
ight) - \left(x_{k-1}^2 - a
ight)} = x_k - rac{x_k^2 - a}{x_k + x_{k-1}}$$

Test with a=3, with initial data  $x_0=1.65, x_1=1.7$ .

$$x_1 = 1.7$$
 error  
 $x_2 = 1.7328$   $7.2 \times 10^{-2}$   
 $x_3 = 1.7320$   $7.9 \times 10^{-4}$   
 $x_4 = 1.7321$   $7.3 \times 10^{-6}$   
 $x_5 = 1.7321$   $3.7 \times 10^{-9}$ 

It is a little but slower than Newton's method, but not much.

## Example

- 1. Define the function f(x).
- 2. Choose two initial guesses  $x_0$  and  $x_1$ .
- 3. Perform the iteration  $x_{k+1}=x_k-f\left(x_k\right)rac{x_k-x_{k-1}}{f(x_k)-f(x_{k-1})}$  until the result converges.

```
In [ ]: import math
        # Define the function f(x)
        def f(x):
            return math.exp(-2 * x) * (x - 1)
        # Initial guesses
        x0 = 0.5 # First initial guess
        x1 = 0.6 # Second initial guess
        # Tolerance for convergence
        tolerance = 1e-6
        # Perform secant method iteration
        iteration = 0
        max_iterations = 100 # Limit iterations to prevent infinite loop
        while iteration < max_iterations:</pre>
            f_x0 = f(x0)
            f_x1 = f(x1)
            # Ensure we don't divide by zero
            if f_x1 == f_x0:
                print("f(x1)) and f(x0) are equal. Division by zero encountered.")
            x2 = x1 - f_x1 * (x1 - x0) / (f_x1 - f_x0)
            print(f"Iteration {iteration + 1}: x = {x2:.6f}")
             if abs(x2 - x1) < tolerance:
                print(f"Converged to {x2:.6f} after {iteration + 1} iterations.")
                break
             x0, x1 = x1, x2
             iteration += 1
        if iteration == max_iterations:
             print("Did not converge within the maximum number of iterations.")
```

```
Iteration 1: x = 0.789842
Iteration 2: x = 0.896355
Iteration 3: x = 0.966937
Iteration 4: x = 0.993979
Iteration 5: x = 0.999617
Iteration 6: x = 0.999995
Iteration 7: x = 1.000000
Iteration 8: x = 1.000000
Converged to 1.000000 after 8 iterations.
```

# System of Linear Equations

#### Direct methods for systems of linear equations

The problem: n equations, n unknowns,

$$\left\{egin{array}{lll} a_{11}x_1+a_{12}x_2+\cdots+a_{1n}x_n &=& b_1\ a_{21}x_1+a_{22}x_2+\cdots+a_{2n}x_n &=& b_2\ &&&dots\ a_{n1}x_1+a_{n2}x_2+\cdots+a_{nn}x_n &=& b_n \end{array}
ight.$$

In matrix-vector form:

$$A\vec{x} = \vec{b},$$

where  $A \in {m R}^{n imes n}, \quad \vec{x} \in {m R}^n, \quad \vec{b} \in {m R}^n$ 

$$A = \left\{a_{ij}
ight\} = egin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \ a_{21} & a_{22} & \cdots & a_{2n} \ dots & dots & \ddots & dots \ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix}, \quad ec{x} = egin{pmatrix} x_1 \ x_2 \ dots \ x_n \end{pmatrix}, \quad ec{b} = egin{pmatrix} b_1 \ b_2 \ dots \ b_n \end{pmatrix}.$$

```
plaintext
Algorithm GaussianElimination(A, b)
    Input: Matrix A (n \times n) and vector b (n)
    Output: Solution vector x (n) such that Ax = b
    Step 1: Forward Elimination
    for k from 1 to n-1 do
        for i from k+1 to n do
            if A[k][k] == 0 then
                swap rows k and a row below it with a non-zero element
in the k-th column
            end if
            factor = A[i][k] / A[k][k]
            for j from k to n do
                A[i][j] = A[i][j] - factor * A[k][j]
            end for
            b[i] = b[i] - factor * b[k]
        end for
    end for
    Step 2: Back Substitution
```

```
x[n] = b[n] / A[n][n]
for i from n-1 to 1 do
    sum = 0
    for j from i+1 to n do
        sum = sum + A[i][j] * x[j]
    end for
    x[i] = (b[i] - sum) / A[i][i]
end for
return x
```