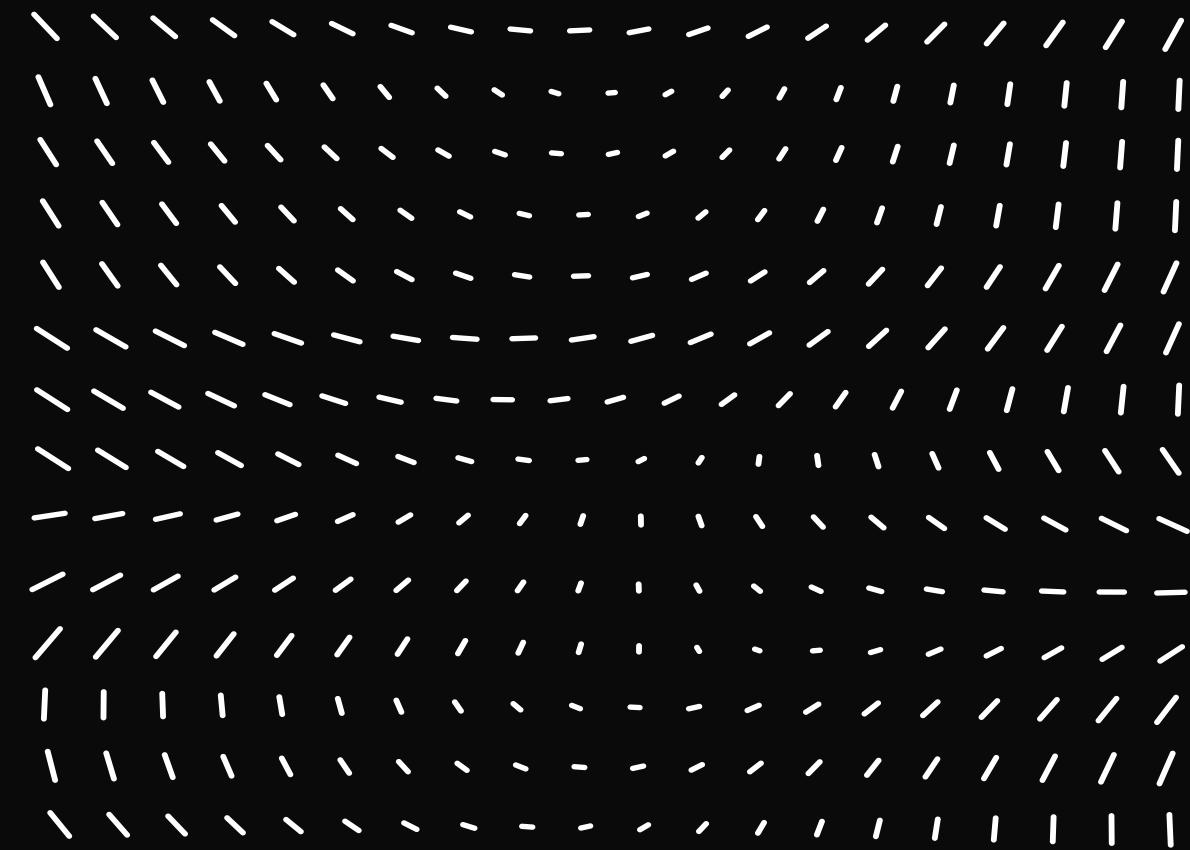


电动力学听课随记

Electronic Dynamics

Lecture Notes



-1. Foreword

2023 Spring 读陶鑫老师的 ED, 助教是某热心的 Au moon him 大佬.

收获颇丰, 在 pk 社区上也写了长评短评. 可以说是学的最认真的一集.

fall 学期粗粗整了一下 notes, 其中不足, 还请各路大佬多多批评.

0. Contents

Chapter 1. Vector & Tensor Analysis

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Chapter 1 Vector & Tensor Analysis

Vectors

$$\vec{r}(\vec{r}) \quad \vec{r} = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} x' \\ y' \end{pmatrix} = T \vec{r}'$$

In Minkowski space for special relativity has the displacement

$$\begin{pmatrix} ct \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \gamma - \beta r & & & \\ \beta r & \gamma & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} \rightarrow (ct, \vec{r})$$

so do all the 4-vectors like
 $(\frac{w}{c}, \vec{k})$
 $(\frac{\xi}{c}, \vec{p})$
 $(\frac{\beta\xi}{c}, \vec{j})$

Einstein Summation Rule

Rule #1 : repeated indices \rightarrow dummy indices

Rule #2 : non-repeated indices \rightarrow free indices

Rule #3 : each index can appear at most twice in any term !

Kronecker delta $\delta_i^j = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$ Levi-Civita symbol

置換

$$\epsilon_{ijk} = \begin{cases} +1 & \text{if } i,j,k \text{ form an even permutation of 1,2,3.} \\ -1 & \text{if } i,j,k \text{ form an odd permutation of 1,2,3.} \\ 0 & \text{otherwise} \end{cases}$$

Useful : $\sum_{ijk} \epsilon_{ijk} \delta_{im} \delta_{jn} = \delta_m^j \delta_n^k - \delta_m^k \delta_n^j$

nabla operator : $\nabla = e_i \frac{\partial}{\partial x_i} \rightarrow$ vector & operator Both !

then $\nabla \times (\vec{A} \times \vec{B}) = \nabla_A \times (\vec{A} \times \vec{B}) + \nabla_B \times (\vec{A} \times \vec{B})$
 $= (\vec{B} \cdot \nabla) \vec{A} - (\nabla \cdot \vec{A}) \vec{B} + (\nabla \cdot \vec{B}) \vec{A} - (\vec{A} \cdot \nabla) \vec{B}$

$\nabla(\vec{A} \cdot \vec{B}) = \nabla_A (\vec{A} \cdot \vec{B}) + \nabla_B (\vec{A} \cdot \vec{B})$
 $= \vec{B} \times (\nabla \times \vec{A}) + (\vec{B} \cdot \nabla) \vec{A} + \vec{A} \times (\nabla \times \vec{B}) + (\vec{A} \cdot \nabla) \vec{B}$
not simply replace!
 $\nabla \times (\nabla \times \vec{A}) = \nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A}$

also we have to use indices to calculate these formulas !

$$\begin{aligned} \nabla \times (\vec{A} \times \vec{B}) &= \vec{e}_i \epsilon_{ijk} \frac{\partial}{\partial x_j} (\epsilon_{kmn} A_m B_n) = \epsilon_{kij} \epsilon_{kmn} \vec{e}_i \frac{\partial}{\partial x_j} (A_m B_n) \\ &= (\delta_{im} \delta_{jn} - \delta_{in} \delta_{jm}) \left(\frac{\partial A_m}{\partial x_j} B_n + \frac{\partial B_n}{\partial x_j} A_m \right) \vec{e}_i \\ &= \left(\frac{\partial A_i}{\partial x_j} B_j + \frac{\partial B_j}{\partial x_j} A_i - \frac{\partial A_j}{\partial x_i} B_i - \frac{\partial B_i}{\partial x_i} A_j \right) \vec{e}_i \\ &= (\vec{B} \cdot \nabla) \vec{A} + (\nabla \cdot \vec{B}) \vec{A} - (\nabla \cdot \vec{A}) \vec{B} - (\vec{A} \cdot \nabla) \vec{B} \end{aligned}$$

this process it quite difficult !

Tensors (2nd order)

define : flux (amount of X passing through unit area per unit time)

Energy flux : $\varepsilon \vec{v}$ (ε : energy density)

Momentum flux : $(g_x \vec{v}, g_y \vec{v}, g_z \vec{v}) \Leftrightarrow \vec{T} = \vec{g} \vec{v} = \rho_M \vec{v} \vec{v}$ (量纲 $J \cdot m^{-3}$)

here T_{xx}, T_{yy}, T_{zz} 压强 \rightarrow 应力张量

$T_{xy} \dots \dots$ 切力

$$\text{Unit tensor } \vec{I} = \delta_{ij} \vec{e}_i \vec{e}_j = \nabla \vec{r}$$

passing through area \vec{S} ? $\vec{T} \cdot \vec{S}$

transform for tensor : $T'_{ij} = M_{ik} M_{jl} T_{kl}$

$$\text{prove : } \nabla \cdot (\vec{f} \vec{g} \times \vec{r}) = \underline{\nabla_f} (\vec{f} \vec{g} \times \vec{r}) + \underline{\nabla_g} (\vec{f} \vec{g} \times \vec{r}) + \underline{\nabla_r} (\vec{f} \vec{g} \times \vec{r})$$

$$(\nabla_f \cdot \vec{f}) \vec{g} \times \vec{r} = (\nabla \cdot \vec{f}) \vec{g} \times \vec{r} \quad (\vec{f} \cdot \nabla g) \times \vec{r} \quad \boxed{\nabla_r \cdot \vec{f}} \vec{g} \times \vec{r} = \vec{g} \times [\nabla_r \vec{f} / r] \\ = \vec{g} \times (\vec{f} \cdot \nabla r) = \vec{g} \times \vec{f}$$

Dirac delta function

$$\text{definition } \delta(x) = \begin{cases} 0, & x \neq 0 \\ \infty, & x=0 \end{cases} \quad \& \quad \int_{-\infty}^{\infty} f(x) \delta(x-a) dx = 1, \quad f(x) \delta(x-a) = f(a) \delta(x-a)$$

related to Fourier Transformation $\int e^{i(\omega-w)t} dt = 2\pi \delta(\omega-w)$

$$\text{Thus } \int_{-\infty}^{\infty} f(x) \delta(x-a) dx = f(a) \quad \text{用于微观(尺度足够小! A)}$$

e.g. 1D particle density distribution $\rho(x, t)$ where $x_p(t)$. then $\rho(x, t) = m \delta(x - x_p), \quad x = x_p(t)$

$$\delta[g(x)] = \sum_i \frac{\delta(x-x_i)}{|g'(x_i)|}, \text{ where } g(x_i)=0 \quad + \int_{-\infty}^{\infty} f(x) D(x) dx = \int_{-\infty}^{\infty} f(x) D(x) dx \text{ then } D(x) = D(x)$$

$$\text{let } y = g(x), \text{ then } \delta(g(x)) = \delta(y) \quad \therefore \int_{y_0}^{y_0+dx} \delta(y) dy = \int_{x_0}^{x_0+dx} \delta(g(x)) \cdot g'(x) dx \Rightarrow \delta(g(x)) = \frac{\delta(x)}{|g'(x)|} \leftarrow ? \text{ Jacob}$$

3-D dirac function $\delta(\vec{r}) = \delta(x) \delta(y) \delta(z), \quad \vec{r} = (x, y, z)$

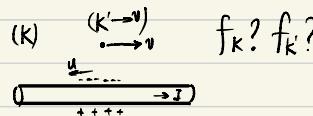
$$\text{三维位形空间 } (\vec{r}, \vec{v}) \text{ 中的 } \delta \text{ 函数} \quad f = \sum_i [\delta(\vec{r} - \vec{x}_i(t)) \delta(\vec{v} - \vec{v}_i(t))]$$

Chapter 2 Foundations of Theory of Relativity

Electrodynamics of Moving Body:

Principle of Relativity

Constancy of Speed of Light



$$\text{interval} : ds = (c^2 dt^2 - dx^2 - dy^2 - dz^2)^{1/2} \quad \text{OR} \quad ds^2 = (cdt, d\vec{r})$$

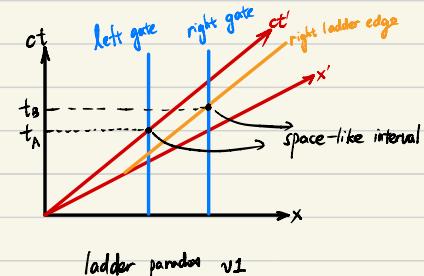
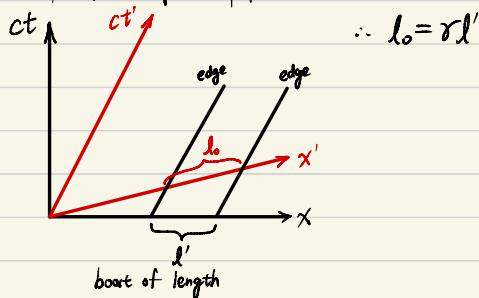
s is invariant between internal references!

$$\text{proper time} \quad dt = \frac{ds}{c} = \frac{dt}{\gamma} \Rightarrow d\tau < dt$$

Lorentz Transformation

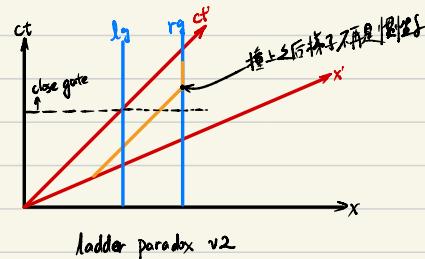
$$\begin{pmatrix} A^0 \\ A^1 \\ A^2 \\ A^3 \end{pmatrix} = \begin{pmatrix} \gamma & \gamma\beta & 0 & 0 \\ \gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} A'^0 \\ A'^1 \\ A'^2 \\ A'^3 \end{pmatrix} \Leftrightarrow A^\mu = \Delta_\nu^\mu A'^\nu$$

世界线观点来理解 Paradox



Most paradox is based on space-like intervals!

In v2: 前端撞上铜门后，“停顿”的信号传播到后端的速度上限为光速，故后端不会同时停止，因此仍会继续前进，能够被关进门。



volume in spacetime

$$dV_0 = dV r, \quad d\tau = dt/r \Rightarrow dV_0 d\tau = dV dt = dS^2 \text{ (unit volume in 4-D spacetime)}$$

Conversion between covariant and contravariant components IN MINKOWSKI SPACE

the metric coefficient $g^{\alpha\beta} = g_{\alpha\beta} = \begin{cases} 0 & \alpha \neq \beta \\ 1 & \alpha = \beta = 0 \\ -1 & \text{otherwise} \end{cases}, \quad g^\alpha_{\beta} = \begin{cases} 0 & \alpha \neq \beta \\ 1 & \alpha = \beta = 0, 1, 2, 3 \end{cases} = \delta^\alpha_\beta \text{ (unit tensor)}$

definition: $g^{ij} = \vec{e}^i \cdot \vec{e}^j, \quad g^i_j = \vec{e}^i \cdot \vec{e}_j = \delta^i_j$

thus $g_\alpha^\beta = \delta_\alpha^\beta$ and $A_\alpha = g_{\alpha\beta} A^\beta$ e.g. $\begin{cases} A_0 = g_{0\beta} A^\beta = g_{00} A^0 = A^0 \\ A_i = g_{ij} A^j = g_{ii} A^i \end{cases}$ (no summation)

Minkowski space: 4-scalar invariant between conversions!

Minkowski space: 4-tensor

$$F^{\mu\nu} \sim A^\mu B^\nu \quad \& \quad F^{\mu\nu\alpha} \sim A^\mu B^\nu C^\alpha \text{ (dyad form)}$$

$$\begin{aligned} F^{\mu\nu} \sim A^\mu B^\nu &= \gamma(A^0 + \beta A^1) \gamma(B^0 + \beta B^1) = \gamma^2 (A^0 B^0 + \beta A^0 B^1 + \beta A^1 B^0 + \beta^2 A^1 B^1) \\ &= \gamma^2 [F^{00} + \beta(F^{01} + F^{10}) + \beta^2 F^{11}] \end{aligned}$$

如果反对称性|该取消

thus

$$A^\alpha = \Lambda^\alpha_\beta A'^\beta, \quad A^\alpha B^\beta = \Lambda^\alpha_\mu \Lambda^\beta_\nu A'^\mu B'^\nu \Leftrightarrow F^{\alpha\beta} = \Lambda^\alpha_\mu \Lambda^\beta_\nu F'^{\mu\nu}$$

and

$$F^{\alpha\beta} = g^{\alpha\mu} F_{\mu\nu} g^{\nu\beta}$$

$$\Rightarrow \text{useful rules } \begin{cases} F^0 \leftrightarrow F_0 \\ F^i \leftrightarrow (-) F_i, \quad i=1,2,3 \end{cases}$$

$$\text{i.e. } \begin{cases} F_{01} = -F_0 \\ F_{ii} = F^i \end{cases}$$

Construct 4-scalar

$$F^{\alpha\beta} F_{\beta\alpha} \quad F^\alpha_{\alpha} \text{ (trace)} \quad A^\alpha F_{\alpha\beta} B^\beta = \overline{B} \cdot \overline{A} \cdot \overline{F}$$

Basic Differential Calculus

4-scalar gradient $d\phi = \frac{\partial \phi}{\partial x^\mu} dx^\mu$

$$\frac{\partial \phi}{\partial x^\mu} = \left(\frac{\partial \phi}{\partial x^0}, \frac{\partial \phi}{\partial x^1}, \frac{\partial \phi}{\partial x^2}, \frac{\partial \phi}{\partial x^3} \right) = \partial_\mu \phi = \left(\frac{1}{c} \frac{\partial \phi}{\partial t}, \nabla \phi \right)$$

$$\frac{\partial \phi}{\partial x_\mu} = \partial^\mu \phi = \left(\frac{1}{c} \frac{\partial \phi}{\partial t}, -\nabla \phi \right)$$

and $\partial_\mu \partial^\mu = \frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 = \square$

4-vector divergence $\partial_\alpha A^\alpha (= \partial^\alpha A_\alpha) = \frac{\partial A^\alpha}{\partial x^\alpha} (= \frac{\partial A_\alpha}{\partial x^\alpha}) = \frac{1}{c} \frac{\partial A^0}{\partial t} + \nabla \cdot \vec{A}$

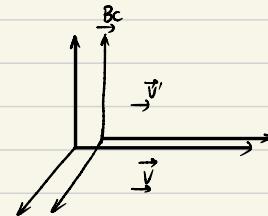
e.g.: $\partial_\mu j^\mu = \frac{1}{c} \frac{\partial \rho_0}{\partial t} + \nabla \cdot \vec{j} = 0$

Important 4-vectors:

(1) 4-velocity $u^\alpha = dx^\alpha / dt$ 四标量均可使用，比例不行
 $= (rc, \vec{v})$

transformation:

$$\begin{cases} rc' = \gamma(r'c + B\gamma'v_x) & ① \\ r'v_x = \gamma(rv_x + Brc) & ② \\ r'v_y = \gamma'v'_y & ③ \\ r'v_z = \gamma'v'_z & ④ \end{cases}$$



$$②/① \Rightarrow \frac{v_x}{c} = \frac{v'_x + Bc}{c + Bv_x} = \frac{v'_x/c + B}{1 + Bv'_x/c}, \quad ③/① \Rightarrow \frac{v_y}{c} = \frac{v'_y}{\gamma} = \frac{1}{c + Bv_x} \cdot \frac{v'_y}{c} = \frac{1}{1 + Bv'_x/c} \cdot \frac{v'_y}{c}$$

& $u^\alpha u_\alpha = c^2$ (inv) $\quad p^\alpha = mu^\alpha = (\gamma mc, \gamma m\vec{v}) = \left(\frac{\gamma}{c}, \vec{p} \right)$
 $\hookrightarrow p^\alpha p_\alpha = \frac{\gamma^2}{c^2} - \vec{p}^2 = m^2 c^2$ (inv)

$$\epsilon^2 = (mc^2)^2 + \vec{p}^2 c^2$$

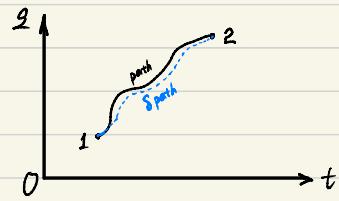
Chapter 3. Relastic Dynamics

The Euler-Lagrange eq.

$$S = \int_{t_1}^{t_2} ds = \int_{t_1}^{t_2} L(q, \dot{q}, t) dt$$

扰动 $q = q + \delta q$, $\dot{q} = \dot{q} + \delta \dot{q}$, 则有

$$\delta S = \int_{t_1}^{t_2} \left(\frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \delta \dot{q} \right) dt \xrightarrow{\text{target}} \int_{t_1}^{t_2} (\dots) \delta q dt = 0$$



同理对于某场中, $\phi = \phi(\vec{r}, t)$, 其 Lagrangian density $\mathcal{L} = \mathcal{L}(\phi, \phi_{\text{ext}})$
求解其运动方程一步便为 $\delta S = \int (\dots) \delta \phi = 0$

$$\text{注意到 } \delta \dot{q} = \frac{d}{dt} \delta q, \text{ 故 } \int_{t_1}^{t_2} \frac{\partial L}{\partial \dot{q}} \delta \dot{q} dt = \int_{t_1}^{t_2} \frac{\partial L}{\partial \dot{q}} d\delta q = \left[\frac{\partial L}{\partial \dot{q}} \delta q \right] \Big|_{t_1}^{t_2} - \int_{t_1}^{t_2} \delta q d \left(\frac{\partial L}{\partial \dot{q}} \right)$$

$$\text{即 } \delta S = \int_{t_1}^{t_2} \left[\frac{\partial L}{\partial q} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}} \right] \delta q dt = 0 \Rightarrow \frac{\partial L}{\partial q} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) = 0$$

$$L' = L + \frac{d}{dt} f(q, t)$$

Total Lagrangian for the uncoupled system

$$L = L_1 + L_2 \Rightarrow \begin{cases} \frac{\partial L}{\partial q_1} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_1} = 0 \\ \frac{\partial L}{\partial q_2} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_2} = 0 \end{cases}$$

Total Lagrangian for the coupled system

$$L = L_1 + L_2 + L_c, L_c = \alpha q_1 q_2 \quad \begin{cases} \frac{\partial L}{\partial q_1} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_1} = -\alpha q_2 \\ \frac{\partial L}{\partial q_2} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_2} = -\alpha q_1 \end{cases}$$

Lagrangian for particle in a potential field

$$L = \frac{1}{2} m v^2 + \alpha \phi \quad \alpha: \text{coupling coefficient}$$

The covariant eq. of motion

operator: $\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 = \partial_\alpha \partial^\alpha$ 达朗贝尔算符, 方具有相对论不变性.

$$\text{Key: } x^\alpha \rightarrow \underline{x^\alpha + \delta x^\alpha}$$

Chapter 4 Charges in Given EM Field.

$$\delta s = \sqrt{dx^\alpha dx_\alpha}$$

covariant eq. of motion

$$S = \int_a^b (-mc^2 dt - g A_\alpha dx^\alpha) \quad \delta S_p = - \int mc \delta(s) = \int \frac{dP_\alpha}{dt} \delta x^\alpha dt$$

$$\delta S_{pf} = -g \int_a^b (g A_\alpha dx^\alpha + A_\alpha d\delta x^\alpha)$$

integrating by parts

$$-g \int_a^b g A_\alpha dx^\alpha + g \int_a^b g x^\alpha dA_\alpha$$

according to: $\delta A_\alpha = \frac{\partial A_\alpha}{\partial x_\beta} \delta x_\beta$, $dA_\alpha = \frac{\partial A_\alpha}{\partial x_\beta} dx_\beta$, we have:

$$\begin{aligned} \delta S_{pf} &= g \int_a^b \left(\frac{\partial A_\alpha}{\partial x^\beta} dx^\beta \delta x^\alpha - \frac{\partial A_\alpha}{\partial x^\beta} dx^\alpha \delta x^\beta \right) \\ &= g \int_a^b \left(\frac{\partial A_\alpha}{\partial x^\beta} u^\beta dt \delta x^\alpha - \frac{\partial A_\alpha}{\partial x^\alpha} u^\beta dt \delta x^\alpha \right) \\ &= - \int_a^b g \left(\frac{\partial A_\alpha}{\partial x^\beta} - \frac{\partial A_\beta}{\partial x^\alpha} \right) u^\beta dt \delta x^\alpha \end{aligned}$$

we define 4-tensor $F_{\alpha\beta}$ by:

$$F_{\alpha\beta} = \partial_\alpha A_\beta - \partial_\beta A_\alpha \quad F_{ij} = -F_{ji}$$

then

$$\delta S = \int_a^b \left[\frac{dP_\alpha}{dt} - g F_{\alpha\beta} u^\beta \right] dt \delta x^\alpha$$

$\Rightarrow \frac{dP_\alpha}{dt} = g F_{\alpha\beta} u^\beta$ (co-form of eq. of motion)

$$F_{\alpha\beta} = \begin{bmatrix} 0 & E_x/c & E_y/c & E_z/c \\ -E_x/c & 0 & -B_z & B_y \\ -E_y/c & B_z & 0 & -B_x \\ -E_z/c & -B_y & B_x & 0 \end{bmatrix}.$$

Moreover: $\begin{cases} F_{0i} = E_i/c \\ F_{i0} = -E_i/c \end{cases} \quad F_{ij} = -\epsilon_{ijk} B^k \quad i=1,2,3 \quad (i \neq 0!)$

Further More

$$E_i = c F_{oi}$$

$$\Delta B^k = -\frac{1}{2} \varepsilon^{ijk} F_{ij}$$

Prove: $-\frac{1}{2} \varepsilon^{ijk} F_{ij} = -\frac{1}{2} \varepsilon^{ijk} (-\varepsilon_{ijk} B^l) = \frac{1}{2} [\delta_{jk}^i \delta_{il}^k - \delta_{jl}^k \delta_{ik}^j] B^l = \frac{1}{2} [3 \delta_{il}^k - \delta_{ii}^k] B^l = \delta_{il}^k B^l = B^k$

For **eg. motion**, it has

$$\frac{dp^\alpha}{dt} = g F^{\alpha\beta} u_\beta \Rightarrow \frac{d(\varepsilon/c)}{dt} = g (+\frac{E^i}{c}) \gamma v_i \Rightarrow \frac{d\varepsilon}{dt} = g \vec{E} \cdot \vec{v}$$

$$\frac{dp^i}{dt} = g F^{i\beta} u_\beta = g F^{i\alpha} u_\alpha + g F^{i\beta} u_\beta = g \frac{E^i}{c} \gamma c + g \varepsilon^{ijk} B_k \gamma v_j$$

$$\Leftrightarrow \frac{dp^i}{dt} = g \vec{E} + g \vec{v} \times \vec{B}$$

$$C^T C = I \quad \text{两矩阵} \quad (\text{转置矩阵} \times \text{自己} = \text{unit})$$

$$\begin{array}{ccc} x_0 & \xrightarrow{\hspace{2cm}} & C x_0 \\ \downarrow & & \downarrow \\ A x_0 & \xrightarrow{\hspace{2cm}} & A C x_0 \end{array}$$

Transformation of the EM field

$$\left\{ \begin{array}{l} A^\alpha = (\phi/c, \vec{A}) \\ F^{\alpha\beta} = \partial^\alpha A^\beta - \partial^\beta A^\alpha \end{array} \right.$$

Lorentz's Matrix $\Lambda^\alpha_\beta = \begin{pmatrix} \gamma & 0 & 0 & 0 \\ 0 & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

$$A^\alpha = \Lambda^\alpha_\beta A^\beta$$

$$F^{12} = \gamma F'^{12} + \gamma \beta F'^{02} \Rightarrow B_2 = \gamma B'_2 + \gamma \beta E'_y / c$$

$$\Rightarrow \begin{cases} E_x = E'_x, \quad E_y = \gamma E'_y + \gamma \beta B'_2, \quad E_z = \gamma E'_z - \gamma \beta B'_y \\ B_x = B'_x, \quad B_y = \gamma B'_y - \gamma \beta E'_z, \quad B_z = \gamma B'_z + \gamma \beta E'_y \end{cases}$$

for the **non-relativistic** situation $V/c \ll 1$, we have

$$\vec{E} = \vec{E}' + \vec{B}' \times \vec{V}, \quad \vec{B} = \vec{B}' - \frac{1}{c^2} \vec{E}' \times \vec{V}$$

Important invariants related to EM field

* 1) $F^{\alpha\beta} F_{\alpha\beta} = \text{inv.} = c^2 B^2 - E^2$

2) 4th order unit tensor $e^{\alpha\beta\mu\nu}$

i) $e^{0123} = 1$

ii) $e^{\alpha\beta\mu\nu} = 0$ if any two indices are the same

iii) $e^{\alpha\beta\mu\nu}$ changes sign if interchanging any pair of indices

thus $F_{\alpha\beta} e^{\alpha\beta\mu\nu} F_{\mu\nu} = \text{inv.} \Rightarrow \vec{E} \cdot \vec{B} = \text{inv.}$

e.g. ① If $E > cB$ in K, then $E' > cB'$ in ALL K'

② If $\vec{E} \perp \vec{B}$ in K, then $\vec{E}' \perp \vec{B}'$ in ALL K'

e.g. Non-Relativity, Faraday: $\frac{ck}{\omega} \times \vec{E} = \vec{B}c$, prove: $(v_{||} - \omega/k)^2 + v_{\perp}^2 = \text{const.}$, when $k/\omega \gg 1$
 似动能能量关系

Proof: $cB - E = (n-1)E \geq 0$ and $\vec{E} \cdot \vec{B} = 0$

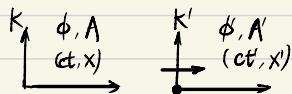
thus, we can find a reference frame K', where $E' = 0$.

$$\Rightarrow \vec{E} = \vec{B} \times \vec{V}$$

therefore $\vec{V} = \frac{\omega}{k} \hat{k}$

then in K' frame, we have $v'_{||} + v'^2_{\perp} = (v_{||} - \frac{\omega}{k})^2 + v_{\perp}^2 = \text{const.}$

Example: Fields of a moving particle
 refer to TX's lecture P52.



Chapter 5 The EM Field Equations

$$\Delta x = \frac{L}{N}$$

$$m = \rho \frac{L}{N}$$

Principle of Least Action in **Scalar Field**

$$\delta S_p = 0 \Rightarrow f(g_i, \dot{g}_i, t) = 0$$

$$\delta S_f = 0 \Rightarrow f(\phi, \partial_\mu \phi) = 0$$

$$L_f = \int \mathcal{L}_f dV, \quad \mathcal{L}_f = f(\phi, \partial_\mu \phi)$$

$$\text{thus } S_f = \int L_f dt = \int \mathcal{L}_f dV/dt, \quad \text{here } dV/dt = d\Omega \text{ (4-Dimension Unit Volume)}$$

$$L = L(g_i, \dot{g}_i, t)$$

\Rightarrow $\frac{\delta S}{\delta g_i} = n \uparrow$ Euler-Lagrange eq.

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{g}_i} \right) - \frac{\partial L}{\partial g_i} = 0 \quad (i=1, 2, \dots, N)$$

$\sum N \rightarrow +\infty$, 上述方程变成矩阵微分方程

方程

For those scalar field, we can have its evlue eq.

$$1) \phi = \phi(t), \quad S_f = \int \mathcal{L} dt, \quad \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{\phi}} \right) - \frac{\partial \mathcal{L}}{\partial \phi} = 0$$

$$2) \phi = \phi(x, y, z), \quad S_f = \int \mathcal{L} dx dy dz dt, \quad \partial_i \left(\frac{\partial \mathcal{L}}{\partial (\partial_i \phi)} \right) - \frac{\partial \mathcal{L}}{\partial \phi} = 0$$

$$3) \phi = \phi(x^\mu), \quad S_f = \int \mathcal{L} dx dy dz dt, \quad \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi)} \right) - \frac{\partial \mathcal{L}}{\partial \phi} = 0$$

* Example: $\mathcal{L} = \frac{1}{2} \partial_\alpha \phi \partial^\alpha \phi$

$$\text{Lagrang eq. } \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi)} \right) - \boxed{\frac{\partial \mathcal{L}}{\partial \phi}} = 0$$

(根据时同对称 $\partial_\nu \phi = \delta_{\nu}^{\alpha} \partial_\alpha \phi$, $\partial^\nu \phi = g^{\nu\alpha} \partial_\alpha \phi$)

$$\frac{\partial \mathcal{L}}{\partial (\partial_\alpha \phi)} = \frac{1}{2} \frac{\partial}{\partial (\partial_\alpha \phi)} (\partial_\beta \phi \partial^\beta \phi) = \frac{1}{2} \frac{\partial (\partial_\alpha \phi)}{\partial (\partial_\alpha \phi)} \partial^\beta \phi + \frac{\partial (\partial^\beta \phi)}{\partial (\partial_\alpha \phi)} \partial_\beta \phi$$

$$= \frac{1}{2} [\delta_{\nu}^{\alpha} \partial^\nu \phi + g^{\nu\alpha} \partial_\nu \phi]$$

$$= \frac{1}{2} [\partial^\alpha \phi + \partial^\alpha \phi] = \partial^\alpha \phi$$

$$\text{thus } \Rightarrow \partial_\alpha (\partial^\alpha \phi) = \partial_\alpha \partial^\alpha \phi = \underline{\underline{\left(\frac{1}{c^2} \frac{\partial}{\partial t} - \nabla^2 \right) \phi}} = 0$$

□: d'Alembert Operator

* Example field + particle

$$\mathcal{L}_f = \frac{1}{2} \partial_\alpha \phi \partial^\alpha \phi, \quad S_f = \int \mathcal{L}_f dV dt, \quad S_{pf} = \int -g \phi(t, x_p) dt \quad ; \quad S = S_f + S_{pf}$$

along the trace

To do this, we have to construct \mathcal{L}_{pf} for S_{pf} !!!

i.e. $\int \mathcal{L}_{pf} dx dy dz = -g \phi(t, x_p) \Rightarrow \underline{\mathcal{L}_{pf}} = -g \phi(t, x_p) \delta(\vec{x} - \vec{x}_p)$

For Lagrangian eq.: $\frac{\partial}{\partial x^\alpha} \left(\frac{\partial \mathcal{L}}{\partial (\partial_\alpha \phi)} \right) - \frac{\partial \mathcal{L}}{\partial \phi} = 0$ Only

$$\Rightarrow \square \phi = -g \delta(\vec{x} - \vec{x}_p)$$

Vector Field

field: $A^\nu = A^\nu(x^\mu)$, its Lagrangian density: $\mathcal{L} = \mathcal{L}(A^\nu, \partial_\mu A^\nu)$

$$\xrightarrow{E-L eq.} \boxed{\frac{\partial}{\partial x^\mu} \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu A^\nu)} \right) - \frac{\partial \mathcal{L}}{\partial A^\nu} = 0}$$

from now we define

$$S = \int \mathcal{L} d\Omega, \quad d\Omega = c dt \cdot dx dy dz$$

About (Simply) EM Field

Noting this:

1. \mathcal{L} a 4-scalar;
2. Gauge invariance;
3. accord with Experiments !!!

\Rightarrow linear in $E, B \Rightarrow$ linear in $\partial_\mu A^\nu$

.....

$$\Rightarrow \mathcal{L} = -\frac{1}{4\mu_0 c} F_{\alpha\beta} F^{\alpha\beta}$$

$$= -\frac{1}{4\mu_0 c} (\partial_\alpha A_\beta - \partial_\beta A_\alpha)(\partial^\alpha A^\beta - \partial^\beta A^\alpha)$$

$$= -\frac{1}{4\mu_0 c} (\boxed{\partial_\alpha A_\beta \partial^\alpha A^\beta} - \boxed{\partial_\alpha A_\beta \partial^\beta A^\alpha} - \boxed{\partial_\beta A_\alpha \partial^\alpha A^\beta} + \boxed{\partial_\beta A_\alpha \partial^\beta A^\alpha})$$

$$= -\frac{1}{2\mu_0 c} (\partial_\alpha A_\beta \partial^\alpha A^\beta - \partial_\alpha A_\beta \partial^\beta A^\alpha)$$

put the simplified \mathcal{L} into E-L eq., we have

$$ALSO: \partial_\alpha A_\beta = \delta_\alpha^\mu g_{\mu\nu} \partial_\mu A^\nu, \quad \partial^\alpha A^\beta = \delta_\mu^\alpha g^{\mu\nu} \partial_\mu A^\nu$$

$$THUS: \frac{\partial (\partial_\alpha A_\beta \partial^\alpha A^\beta)}{\partial (\partial_\mu A^\nu)} = \underbrace{\delta_\alpha^\mu g_{\mu\nu} \partial^\alpha A^\beta}_{\partial^\mu A_\nu} + \underbrace{\delta_\mu^\alpha g^{\mu\nu} \partial_\alpha A_\beta}_{\partial_\mu A^\nu} = \partial^\mu A_\nu + \partial_\mu A^\nu = 2 \partial_\mu A^\nu$$

$$\frac{\partial(\partial_\mu A_\rho \partial^\rho A^\alpha)}{\partial(\partial_\mu A^\nu)} = \underbrace{\delta_\alpha^\mu g_{\rho\nu} \partial^\rho A^\alpha}_{\partial_\nu A^\mu} + \partial_\nu A^\mu + \partial^\nu A_\mu = 2\partial_\nu A^\mu$$

AND: $\frac{\partial \mathcal{L}}{\partial A^\nu} = \frac{\partial(\dots)}{\partial A^\nu} = 0$

SO: $\frac{\partial}{\partial x^\mu} \frac{\partial \mathcal{L}}{\partial(\partial_\mu A^\nu)} - \frac{\partial \mathcal{L}}{\partial A^\nu} = 0 \Rightarrow \frac{\partial}{\partial x^\mu} \left(\frac{1}{\mu c} (\partial_\nu A^\mu - \partial_\mu A^\nu) \right) = \frac{\partial}{\partial x^\mu} \left(\frac{1}{\mu c} F_\nu^\mu \right) = 0 \quad (*)$

Considering $(*)$ $0 = \frac{\partial}{\partial x^\mu} (\partial_\nu A^\mu - \partial^\mu A_\nu) = \partial_\nu \boxed{\partial_\mu A^\mu} - \partial_\mu \partial^\mu A_\nu \xrightarrow{\text{Lorenz G}} -\square A_\nu$
 Choose Lorenz Gauge AND IT becomes "0": $\frac{1}{c^2} \frac{\partial^2 \phi}{\partial t^2} + \nabla \cdot \vec{A} = 0$
 $\Rightarrow \square A^\nu = 0 \xrightarrow{\text{Components}} \left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) \phi = 0, \quad \nu = 0, \quad \nabla \cdot \vec{E} = 0$
 $\left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) A = 0, \quad \nu = 1, 2, 3. \Rightarrow \nabla \times \vec{B} = \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$

$\nabla \cdot \vec{E} = -\nabla^2 \psi + \frac{\partial}{\partial t} (\nabla \cdot \vec{A}) = -\frac{1}{c^2} \frac{\partial^2}{\partial t^2} \psi + \frac{\partial}{\partial t} (\nabla \cdot \vec{A})$
Lorenz G (NEXT PAGE)

而光从 \vec{E}, \vec{B} 的定义上即可获得
 $\nabla \cdot \vec{B} = 0$
 $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

Consider the effects of particles

$$\begin{aligned} S &= S_f + S_{pf} = \int L_f d\Omega + \int \sum_i -g_i A_\alpha(t, \vec{x}_i) dx^\alpha \\ &= \int L_f d\Omega + \int \sum_i -g_i A_\alpha(t, \vec{x}) \delta(\vec{x} - \vec{x}_i) dV dx^\alpha \end{aligned}$$

AND: $\sum_i g_i \delta(\vec{x} - \vec{x}_i) = \rho(t, \vec{x}) \quad \text{so: } \underline{L_{pf} = -\frac{1}{c} \rho A_\alpha \frac{dx^\alpha}{dt}}$

Here, we can define the current density 4-vector $\vec{j}^\alpha = \rho \frac{dx^\alpha}{dt} = (\rho c, \vec{j})$

Then

$$L = L_f + L_{pf} = -\frac{1}{4\mu_0 c} \cdot F^{\alpha\beta} F_{\alpha\beta} - \frac{1}{c} j^\alpha A_\alpha$$

Put it into E-L eq.

$$\frac{\partial F_{\alpha\nu}}{\partial x_\mu} - \mu_0 j_\nu = 0$$

Using Lorenz Gauge: $\square A_\nu - \mu_0 j_\nu = 0 \xrightarrow{\text{Components}} \left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) \phi - \frac{\rho}{\mu_0 c} = 0, \nu = 0$
 $\left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) \vec{A} - \mu_0 \vec{j} = 0, \text{ otherwise}$

According to (4):

$$\nabla \cdot \vec{E} = \nabla \cdot \frac{\partial \vec{A}}{\partial t} - \nabla^2 \varphi \xrightarrow{(4)} \nabla \cdot \frac{\partial \vec{A}}{\partial t} + \frac{\rho}{\epsilon_0} - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \varphi \stackrel{LG}{=} \frac{\rho}{\epsilon_0}$$

$$(\text{Lorenz Gauge}) \quad 0 = \frac{\partial}{\partial t} \nabla \cdot \vec{A} + \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \varphi$$

$$\square \vec{A} = \frac{1}{c^2} \frac{\partial^2 \vec{A}}{\partial t^2} - \nabla^2 \vec{A} \xrightarrow{LG} \left[\frac{1}{c^2} \frac{\partial^2 \vec{A}}{\partial t^2} + \frac{1}{c^2} \nabla^2 \varphi \right] + \boxed{\nabla (\nabla \cdot \vec{A}) - \nabla^2 \vec{A}} = -\frac{1}{c^2} \frac{\partial}{\partial t} (-\nabla \varphi - \frac{\partial \vec{A}}{\partial t}) + \nabla \times (\nabla \times \vec{A}) \\ (\text{Lorenz Gauge}) \quad 0 = \frac{1}{c^2} \frac{\partial^2 \varphi}{\partial t^2} + \nabla (\nabla \cdot \vec{A}) \\ = -\frac{1}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2} + \nabla \times \vec{B}$$

$$\Leftrightarrow \nabla \times \vec{B} = \mu_0 \vec{j} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

Charge Conservation Law, Equation of Continuity

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \vec{j} = 0 \quad (\text{charge})$$

$$\frac{\partial \rho_A}{\partial t} + \nabla \cdot \vec{F}_A = 0 \quad \text{conservative form}$$

what if A has a source ($\dot{\rho}/\dot{V}$) or a sink (\dot{I}/V)

$$\frac{\partial \rho_A}{\partial t} + \nabla \cdot \vec{F}_A = S_A$$

$$\begin{cases} \frac{\partial n}{\partial t} + \nabla \cdot n \vec{v} = 0 & (\text{num}) \\ \frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{v} = 0 & (\text{mass}) \end{cases}$$

$$2) \frac{\partial \varphi}{\partial t} + v \frac{\partial \varphi}{\partial x} = 0, \text{ 遍解 } \varphi = \varphi(x-vt)$$



$$2) \left(\frac{\partial^2}{\partial t^2} - v^2 \frac{\partial^2}{\partial x^2} \right) \varphi = 0 \quad \text{波动方程}$$

$$3) \frac{\partial \varphi}{\partial t} = D \frac{\partial^2 \varphi}{\partial x^2} \quad \text{扩散方程}$$

$$\begin{array}{l} \text{边值} \\ \text{初值} \end{array} \Rightarrow \frac{\partial \varphi}{\partial t} + \frac{\partial}{\partial x} \left[-D \frac{\partial \varphi}{\partial x} \right] = 0 \quad \text{直流传导方程}$$

$$4) \nabla^2 \varphi = \begin{cases} 0 \\ -\rho/\epsilon_0 \end{cases} \quad \text{Laplacian eq.}$$

The Continuity Equation of Field Energy and Momentum

noting that 1. \vec{S} is only related to field }
 2. E, B is symmetric
 3. satisfy continuity equation }

$$\frac{\partial \vec{S}}{\partial t} + \nabla \cdot \vec{P} = S_{\vec{S}}$$

ALSO $\frac{d\vec{S}_p}{dt} = \rho \vec{E} \cdot \vec{v}$ FOR dv : $\frac{d\vec{S}_p}{dt} = \rho dV \vec{E} \cdot \vec{v} = \vec{E} \cdot \vec{j} dV$

FOR Unit volume : $S_p = -\frac{d\vec{S}_p}{dt} = -\vec{j} \cdot \vec{E}$

Ampère Thr : $\vec{j} = \frac{1}{\mu_0} \nabla \times \vec{B} - \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} \Rightarrow \vec{j} \cdot \vec{E} = \frac{1}{\mu_0} \nabla \times \vec{B} \cdot \vec{E} - \epsilon_0 \frac{\partial \vec{E}}{\partial t} \cdot \vec{E}$

Applying Faraday Thr .
 $= \frac{1}{\mu_0} (\nabla \times \vec{B} \cdot \vec{E} - \nabla \times \vec{E} \cdot \vec{B}) + \frac{1}{\mu_0} \nabla \times \vec{E} \cdot \vec{B} - \frac{\epsilon_0}{2} \frac{\partial \vec{E}^2}{\partial t}$
 $= -\frac{1}{\mu_0} \nabla \cdot (\vec{E} \times \vec{B}) - \left(\frac{1}{\mu_0} \frac{\partial \vec{B}^2}{\partial t} + \frac{\epsilon_0}{2} \frac{\partial \vec{E}^2}{\partial t} \right)$

Thus

$$\frac{\partial \vec{S}}{\partial t} + \nabla \cdot \vec{P} = \frac{1}{\mu_0} \nabla \cdot (\vec{E} \times \vec{B}) + \left(\frac{1}{\mu_0} \frac{\partial \vec{B}^2}{\partial t} + \frac{\epsilon_0}{2} \frac{\partial \vec{E}^2}{\partial t} \right)$$

$$\Rightarrow \begin{cases} \vec{S} = \frac{1}{\mu_0} \vec{B}^2 + \frac{\epsilon_0}{2} \vec{E}^2 \\ \vec{P} = \frac{1}{\mu_0} \vec{E} \times \vec{B} \quad (= \vec{E} \times \vec{H} \text{ Poynting flux}) \end{cases}$$

FOR momentum

$$\frac{\partial \vec{g}}{\partial t} + \nabla \cdot \vec{G} = S_g$$

AND FOR S_g , we have $S_g = -\rho(\vec{E} + \vec{v} \times \vec{B}) = -\rho \vec{E} + \vec{j} \times \vec{B}$

ALSO $\vec{P} = \epsilon_0 \nabla \cdot \vec{E} \quad \vec{j} = \frac{1}{\mu_0} \nabla \times \vec{B} - \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$

i.e. $\frac{\partial \vec{g}}{\partial t} + \nabla \cdot \vec{G} = -\epsilon_0 (\nabla \cdot \vec{E}) \vec{E} - \frac{1}{\mu_0} (\nabla \times \vec{B}) \times \vec{B} + \underline{\epsilon_0 \frac{\partial \vec{E}}{\partial t} \times \vec{B}}$
 $= -\epsilon_0 (\nabla \cdot \vec{E}) \vec{E} - \frac{1}{\mu_0} (\nabla \times \vec{B}) \times \vec{B} + \underline{\epsilon_0 \frac{\partial}{\partial t} (\vec{E} \times \vec{B})} + \underline{\epsilon_0 \vec{E} \times (\nabla \times \vec{E})}$
 $= \epsilon_0 \frac{\partial}{\partial t} (\vec{E} \times \vec{B}) - \epsilon_0 (\nabla \cdot \vec{E}) \vec{E} - \frac{1}{\mu_0} (\nabla \times \vec{B}) \vec{B} - \frac{1}{\mu_0} (\nabla \times \vec{B}) \times \vec{B} + \underline{\epsilon_0 \vec{E} \times (\nabla \times \vec{E})}$

mathematical trick : $\vec{E} \times (\nabla \times \vec{E}) = (\nabla \cdot \vec{E}) \vec{E} - \nabla \cdot (\vec{E} \vec{E} - \frac{1}{2} \vec{E}^2 \vec{I})$

so $\frac{\partial \vec{g}}{\partial t} + \nabla \cdot \vec{G} = \frac{\partial}{\partial t} (\epsilon_0 \vec{E} \times \vec{B}) - \nabla \cdot \left[\epsilon_0 \vec{E} \vec{E} + \frac{1}{\mu_0} \vec{B} \vec{B} - \frac{1}{2} (\epsilon_0 \vec{E}^2 + \frac{1}{\mu_0} \vec{B}^2) \vec{I} \right]$

$$\Rightarrow \begin{cases} \vec{g} = \epsilon_0 \vec{E} \times \vec{B} \\ \vec{G} = -\vec{T}, \quad \vec{T} = \epsilon_0 \vec{E} \vec{E} + \frac{1}{\mu_0} \vec{B} \vec{B} - \frac{1}{2} (\epsilon_0 \vec{E}^2 + \frac{1}{\mu_0} \vec{B}^2) \vec{I} \end{cases}$$

\vec{T} is Maxwell stress tensor.

$$\Rightarrow E \vec{v} = m \vec{v} c^2$$

Noting that $\vec{P} = c^2 \vec{g}$ \Rightarrow energy flux = $c^2 \times$ momentum density

Force on Particles in unit volume:

For static EM Field, $\frac{\partial \vec{g}}{\partial t} = 0$,

$$\vec{f} = - \frac{\partial \vec{g}}{\partial t} - \nabla \cdot \vec{G}$$

$$\vec{f} = \nabla \cdot \vec{T}$$

For all particles within a volume V :

$$\vec{F} = \int \nabla \cdot \vec{T} dV = \oint d\vec{S} \cdot \vec{T}$$

$$d\vec{F} = \vec{e}_i T_{ij} dS_j$$

$$\Rightarrow dF_x = T_{xj} dS_j = T_{xx} dS_x + \underline{T_{xy} dS_y + T_{xz} dS_z}$$

when $\vec{E} = 0$, $\vec{f} = \frac{1}{\mu_0} (\vec{B} \cdot \nabla) \vec{B} - \underline{\nabla \left(\frac{1}{2\mu_0} B^2 \right)}$ magnetic pressure (plasma physics)

Shear

EXAMPLE

Calculate the force on the northern hemisphere?

$$\vec{F} = \int \nabla \cdot \vec{T} dV = \int d\vec{S} \cdot \vec{T} = \int \vec{T} \cdot d\vec{S}$$

$$(\vec{T} \cdot d\vec{S}) = T_{zj} dS_j = T_{zx} dS_x + T_{zy} dS_y + T_{zz} dS_z$$

$$\text{AND } \vec{T} = \epsilon_0 \vec{E} \vec{E} - \frac{1}{2} \epsilon_0 E^2 \vec{I} \quad (\vec{B} = 0)$$

$$d\vec{S} = R^2 \sin \theta d\phi \vec{e}_r, \vec{E} = \frac{Q}{4\pi \epsilon_0 R^2} \vec{e}_r, \vec{e}_r = \cos \theta \vec{e}_z + \sin \cos \phi \vec{e}_x + \sin \phi \vec{e}_y$$

$$\text{Bowl} \rightarrow T_{zx} = \epsilon_0 E_z E_x = \epsilon_0 \left(\frac{Q}{4\pi \epsilon_0 R^2} \right)^2 \sin \theta \cos \phi$$

$$\text{Disk} \rightarrow T_{zz} = \epsilon_0 E_z^2 - \frac{1}{2} \epsilon_0 E^2 = \frac{1}{2} \epsilon_0 (E_x^2 + E_y^2 + E_z^2)$$

....

积分区域
包含电荷的自由边界

Chapter 6 General Electrostatics

Energy of Electrostatic Field

$$U = \frac{1}{2} \sum_i q_i \varphi_i = U_{\text{self}} + U_{\text{inter}} , \quad U_{\text{self}} = \frac{1}{2} q_a \varphi_a(\vec{r}_a) = +\infty \text{ for a point charge}$$

don't consider

Assume the electron is a sphere of uniform charge with radius R_0

$$U = \frac{1}{2} \int \rho \phi dV \sim \frac{e^2}{4\pi \epsilon_0 R_0} = mc^2$$

General Solution of Electrostatic Problems

$$\Rightarrow R_0 = \frac{e^2}{4\pi \epsilon_0 m c^2} \sim 10^{-15} \text{m} \quad \text{classical electron radius}$$

$$\nabla^2 \phi = -2\epsilon_0 \delta(\vec{r} - \vec{r}_i)/\epsilon_0$$

Green function

$$\hat{L}\phi = \text{source} \quad (\hat{L}: \text{linear operator}, \quad \phi = \hat{L}^{-1} \text{source})$$

$$\nabla^2 G(\vec{r}, \vec{r}') = \delta(\vec{r} - \vec{r}'), \quad \int G(\vec{r} - \vec{r}') S(\vec{r}') dV' = S(\vec{r})$$

$$\int \nabla^2 G(\vec{r}, \vec{r}') S(\vec{r}') dV' = S(\vec{r})$$

$$\text{Electrostatics} \Rightarrow \phi(\vec{r}) = \frac{1}{4\pi \epsilon_0} \int \frac{\rho(\vec{r}') dV'}{|\vec{r} - \vec{r}'|}$$

↓ Expand

$$\text{Magnetostatics} \quad \nabla^2 \vec{A} = -\mu_0 \vec{j} \Rightarrow \vec{A} = \frac{\mu_0}{4\pi} \int \frac{\vec{j}(\vec{r}') dV'}{|\vec{r} - \vec{r}'|} \xrightarrow[\nabla(\text{not } \nabla)]{\text{rotation}} \text{(Biot-Savart Th.)}$$

Approximate Solution (using Taylor Expand 电势级展开)

Taylor expansion:

$$f(\vec{r} - \vec{r}') = f(\vec{r}) + \nabla f(\vec{r}) \cdot (-\vec{r}') + \frac{1}{2} x_i' x_j' \frac{\partial^2}{\partial x_i \partial x_j} f(\vec{r})$$

$$\begin{aligned} \text{For here: } \varphi(\vec{r} - \vec{r}') &= \frac{1}{4\pi \epsilon_0} \sum_a \frac{q_a}{|\vec{r} - \vec{r}'|} , \quad \epsilon = \frac{|\vec{r}'|}{|\vec{r}|} \ll 1 \\ &= \varphi_0 + \varphi_1 + \varphi_2 + \dots \\ &\quad \uparrow \quad \uparrow \quad \uparrow \\ &\quad O(1) \quad O(\epsilon) \quad O(\epsilon^2) \end{aligned}$$

Applying them, we arrive the conclusion that:

$$\varphi_0 = \frac{1}{4\pi \epsilon_0} \frac{\sum_a q_a}{r} = \frac{1}{4\pi \epsilon_0} \frac{Q}{r} \quad r = |\vec{r}|$$

$$Q = \sum_a q_a \text{ (zero order)}$$

电荷矩

Source point

$$\varphi_1 = \frac{1}{4\pi \epsilon_0} \sum_a -2q_a \vec{r}' \cdot \nabla \frac{1}{r} = \frac{\vec{P} \cdot \vec{r}'}{4\pi \epsilon_0 r^3} \quad \vec{P} = \sum_a q_a \vec{r}' \text{ (first order moment of electron)}$$

电一阶矩

$$\varphi_2 = \frac{1}{4\pi \epsilon_0} \cdot \frac{1}{2} \sum_a 2q_a x_i x_j \frac{\partial^2}{\partial x_i \partial x_j} \frac{1}{r}$$

Consider φ_2 , define quadrupole moment \vec{D} as

$$\vec{D} = \sum_a q_a (3\vec{r}' \vec{r}' - r^2 \vec{I}) , \quad D_{ij} = \sum_a q_a (3x_i x_j - r^2 \delta_{ij})$$

$$\therefore \varphi_2 = \frac{1}{24\pi \epsilon_0} \cdot D_{ij} \frac{\partial^2}{\partial x_i \partial x_j} \frac{1}{r}$$

Consider φ , the Electric field can be obtained by adding an operator on φ , i.e.:

$$\begin{aligned}\vec{E}_1 &= -\nabla \left(\frac{1}{4\pi\epsilon_0} \frac{\vec{P} \cdot \vec{x}}{r^3} \right) = \frac{1}{4\pi\epsilon_0} \nabla (\vec{P} \cdot \vec{x}) \frac{1}{r^3} - \frac{1}{4\pi\epsilon_0} \nabla \frac{1}{r^3} \vec{P} \cdot \vec{x} \\ &= \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} \vec{P} \cdot \nabla \vec{x} - \frac{1}{4\pi\epsilon_0} \vec{P} \cdot \vec{x} \left(-3 \right) \frac{1}{r^4} \nabla r \\ &= \frac{1}{4\pi\epsilon_0} \left(\frac{3(\vec{P} \cdot \vec{x}) \vec{x}}{r^5} - \frac{\vec{P}}{r^3} \right) = \frac{1}{4\pi\epsilon_0} \frac{3(\vec{P} \cdot \vec{n}) \vec{n} - \vec{P}}{r^3}\end{aligned}$$

Potential energy of a system of charges in an external field

spatial scale of ϕ : $\frac{\phi}{\nabla \phi} \sim \frac{\phi}{\phi/L} = L$ define $\epsilon = \frac{l}{L} \ll 1$
 2: $x' \sim l$

potential is $U = \sum_a q_a \phi(\vec{x}_a) = \sum_a q \phi(\vec{x}')$

here expand ϕ : $\begin{cases} \phi(\vec{x}') = \phi(0) + \vec{x}' \cdot \nabla \phi + \frac{1}{2} x'_i x'_j \frac{\partial^2 \phi}{\partial x_i \partial x_j} \\ U = U^{(0)} + U^{(1)} + U^{(2)} + \dots \end{cases}$

thus

$$U^{(0)} = \sum_a q \phi^{(0)} = Q \phi^{(0)}$$

$$U^{(1)} = \sum_a q \vec{x}' \cdot \nabla \phi^{(0)} = \vec{P} \cdot (\nabla \phi)^{(0)} = -\vec{P} \cdot \vec{E}$$

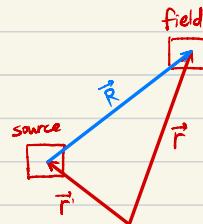
$$U^{(2)} = \sum_a \frac{1}{2} x'_i x'_j \frac{\partial^2 \phi}{\partial x_i \partial x_j} = \frac{1}{6} D_{ij} \frac{\partial^2 \phi}{\partial x_i \partial x_j} = \frac{1}{6} \vec{D} \cdot \nabla \nabla \phi = -\frac{1}{6} \vec{D} \cdot \nabla \vec{E}$$

the Force on the charges, can be written as

$$\begin{aligned}\vec{f} &= -\nabla U \simeq -\nabla U^{(0)} - \nabla U^{(1)} \\ &= Q \vec{E}^{(0)} + \underline{\nabla(\vec{P} \cdot \vec{E})} = (\vec{P} \cdot \nabla) \vec{E}\end{aligned}$$

the torque felt by an electric dipole

$$\vec{\tau} = \vec{P} \times \vec{E}$$



Polarized

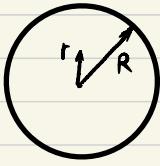
$$\varphi = \frac{1}{4\pi\epsilon_0} \int \frac{\vec{P} \cdot \vec{R}}{R^3} dV, \quad \vec{R} = \vec{P} - \vec{r}$$

$$\begin{aligned}\nabla'(\frac{1}{R}) &= \frac{\vec{R}}{R^3}, \quad \nabla' = \frac{\partial}{\partial \vec{r}}, \quad \therefore \varphi = \frac{1}{4\pi\epsilon_0} \int \vec{P} \cdot \nabla'(\frac{1}{R}) dV' = \frac{1}{4\pi\epsilon_0} \int \frac{\vec{P}}{R} \cdot dS' + \frac{1}{4\pi\epsilon_0} \int \frac{-\nabla \cdot \vec{P}}{R} dV' \\ &= \frac{1}{4\pi\epsilon_0} \int \frac{\sigma_b}{R} dS' + \frac{1}{4\pi\epsilon_0} \int \frac{\rho_b}{R} dV'\end{aligned}$$

i.e.: $\sigma_b = \vec{P} \cdot \vec{n}$, $\rho_b = -\nabla \cdot \vec{P}$

Electric Field inside a Dielectric

宏观上足够大，宏观上足够小。(见hw #4 问题)



$$\vec{E}(\vec{r}) = \vec{E}_{in} + \vec{E}_{out}$$

$$\langle \phi \rangle_{out} = \frac{1}{4\pi\epsilon_0} \int_{out} \frac{\vec{P} \cdot \vec{R}}{R^3} dV, \quad \langle \phi \rangle_{in} = \frac{1}{4\pi\epsilon_0} \int_{in} \frac{\vec{P} \cdot \vec{R}}{R^3} dV'$$

$$\Rightarrow \langle \phi \rangle = \frac{1}{4\pi\epsilon_0} \int_{ALL} \frac{\vec{P} \cdot \vec{R}}{R^3} dV' \text{ 成立}$$

Boundary Problems

1. Laplace eq. $\nabla^2 \phi = 0$

$$\begin{cases} \vec{j} = -D \nabla \phi \\ \nabla \cdot \vec{j} = -\frac{\partial n}{\partial t} \\ \Rightarrow \frac{\partial n}{\partial t} = D \nabla^2 \phi \end{cases}$$

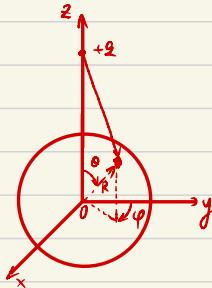
stable solution $\nabla^2 \phi = 0$

1-D Laplace eq. $\frac{\partial^2 \phi}{\partial x^2} = 0$ Solution: $\phi = Ax + B$
 2-D Laplace eq. $\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0$ Solution: $\phi = \frac{1}{2\pi R} \oint \phi dS$
 3-D Laplace eq. $\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} = 0$, Solution: $\phi = \frac{1}{4\pi R^2} \oint \phi dS$

Proof: $\phi = \frac{1}{4\pi\epsilon_0} \frac{q}{Z}$

$$\frac{1}{4\pi R^2} \oint \phi dS = \frac{1}{4\pi\epsilon_0} \int_0^\pi \frac{1}{4\pi\epsilon_0} \frac{q}{\sqrt{z^2 + R^2 - 2zR\cos\theta}} R^2 \sin\theta d\theta d\phi$$

$$= \frac{q}{4\pi\epsilon_0} \cdot \frac{1}{2\pi R} \left[\sqrt{z^2 + R^2 - 2zR\cos\theta} \right]_0^\pi = \frac{1}{4\pi\epsilon_0} \cdot \frac{q}{Z} \quad QED.$$



What about adding boundary conditions on ∂V ?

first uniqueness theorem: ϕ is uniquely determined in ϕ on ∂V is given.

Proof: assume that ϕ_1 & ϕ_2 . thus $\nabla^2 \phi_1 = 0, \nabla^2 \phi_2 = 0$. define $\phi_3 = \phi_2 - \phi_1$
 $\phi_3 = 0$ on ∂V

Considering $\begin{cases} \nabla^2 \phi_3 = 0 \\ \phi_3 = 0 \text{ on } \partial V \end{cases}$ ϕ_3 has the max/min on boundary $\Rightarrow \phi_3 = 0$ (inside V) $\Rightarrow \phi_1 = \phi_2$

*first theorem can also be applied to $\nabla^2 \phi = \rho/\epsilon_0$.

Second uniqueness theorem:

Proof: $\nabla \vec{E}_1 = \frac{\rho}{\epsilon_0}, \nabla \vec{E}_2 = \frac{\rho}{\epsilon_0}, \oint \vec{E}_1 \cdot d\vec{S} = \frac{Q_1}{\epsilon_0}, \oint \vec{E}_2 \cdot d\vec{S} = \frac{Q_2}{\epsilon_0}, \oint \vec{E}_1 \cdot d\vec{S} = \frac{Q_{tot}}{\epsilon_0}, \oint \vec{E}_2 \cdot d\vec{S} = \frac{Q_{tot}}{\epsilon_0}$

define $\vec{E}_3 = \vec{E}_2 - \vec{E}_1$. $\begin{cases} \nabla \cdot \vec{E}_3 = 0 \\ \vec{E}_3 \cdot d\vec{S} = 0 \end{cases}$ & $\nabla \cdot (\phi_3 \vec{E}_3) = -\vec{E}_3^2$, Considering $\int \nabla \cdot (\phi_3 \vec{E}_3) dV = - \int \vec{E}_3^2 dV = 0 \Rightarrow \vec{E}_3 = 0$

Separation of Variables

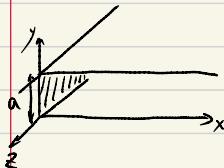
Completeness $f(y) = \sum_n C_n f_n(y)$

Orthogonality $\int_0^a f_n(y) f_m(y) dy = 0 \text{ if } n \neq m$

Example:

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \varphi = 0, \quad \varphi = X(x)Y(y)$$

$$\Rightarrow \frac{1}{X} \frac{d^2 X}{dx^2} + \frac{1}{Y} \frac{d^2 Y}{dy^2} = 0$$



$$\begin{cases} \frac{1}{X} \frac{d^2 X}{dx^2} = C_1 = k^2, & X = A e^{kx} + B e^{-kx} \\ \frac{1}{Y} \frac{d^2 Y}{dy^2} = C_2 = -k^2, & Y = A_{\text{sinky}} + B_{\text{cosky}} = A_{\text{sinky}} \end{cases}$$

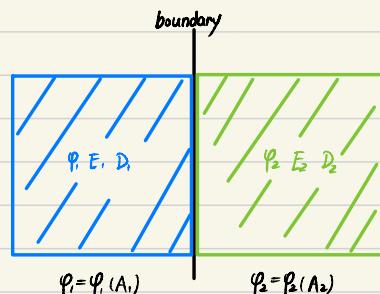
$$\therefore \varphi = C e^{kx} \text{sinky}, \quad k = \frac{n\pi}{a}, \quad n=1,2,3,\dots$$

Connection boundary conditions for electric field and potential

We can solve $\varphi_i = \varphi_i(A_i)$ where A_1, A_2 should be determined by the boundary conditions on 'Black Line'.



$$\begin{cases} D_{in} - D_{2n} = \sigma_f \\ E_{1c} = E_{2c} \\ \varphi_1 = \varphi_2 \end{cases}$$



Example: 求一个质点在匀强场中的运动

$$\nabla^2 \varphi = 0, \quad \frac{\partial \varphi}{\partial r} = 0 \Rightarrow \varphi(r, \theta) = \sum_{l=0}^{\infty} \left(A_l r^l + \frac{B_l}{r^{l+1}} \right) P_l(\cos\theta) = \begin{cases} \sum_{l=0}^{\infty} \frac{B_l}{r^{l+1}} P_l(\cos\theta) - E \cos\theta & \text{outside} \\ \sum_{l=0}^{\infty} A_l r^l P_l(\cos\theta) & \text{inside} \end{cases}$$

$$B/C: \quad \varphi_{in} = \varphi_{out} \quad \text{at } r=R, \quad \frac{\partial \varphi_{in}}{\partial r} = \epsilon_0 \frac{\partial \varphi_{out}}{\partial r}$$

$$\Rightarrow A_1 = B_1 = 0 \quad (l \neq 1), \quad A_2 = \frac{-3}{\epsilon_0 r^2} E_0, \quad B_2 =$$

$$\therefore \varphi_{in} = \frac{-3}{\epsilon_0 r^2} E_0 \cos\theta, \quad \vec{E}_{in} = \frac{3}{\epsilon_0 r^2} \vec{E}_0$$

2nd/3rd 1st/2nd order

order

$$\nabla \times \vec{B} = 0$$

$$\Rightarrow \vec{B} = -\nabla \phi \text{ (磁场势)}$$

Chapter 7 General Magnetostatics

Using Coulomb Gauge, we have

$$\nabla \times (\nabla \times \vec{A}) = \nabla (\nabla \cdot \vec{A}) - \nabla^2 \vec{A} = -\nabla^2 \vec{A} = \mu_0 \vec{j}$$

similar to $\nabla^2 \phi = -\frac{\rho}{\epsilon_0}$

$$\Rightarrow \nabla^2 \vec{A} = -\mu_0 \vec{j} \Rightarrow \vec{A} = \frac{\mu_0}{4\pi r} \int \frac{\vec{j}(r') dr'}{|r-r'|}$$

$$\vec{B} = \nabla \times \vec{A} \xrightarrow{R=\vec{r}-\vec{r}'} \frac{\mu_0}{4\pi r} \int \nabla \times \left(\frac{\vec{j}(r')}{R} \right) dr' \quad \text{let } \vec{j} dr' = Id\vec{l}$$

magnetic multiple moments

considering current $\vec{j}(r')$ get magnetic field at \vec{r} , where $|\vec{r}|/|r'| = \epsilon \ll 1$, & $r=|\vec{r}|$

Taylor Expand:

$$\begin{aligned} f(\vec{r}-\vec{r}') &= f(\vec{r}) + \nabla f(\vec{r}) \cdot (-\vec{r}') + \dots \\ \Leftrightarrow \frac{1}{|\vec{r}-\vec{r}'|} &\simeq \frac{1}{r} + \nabla \frac{1}{r} \cdot (-\vec{r}') + \dots \end{aligned}$$

Hence we have

$$\begin{aligned} \vec{A} &= \vec{A}^{(0)} + \vec{A}^{(1)} + \dots \\ \vec{A}^{(0)} &= \frac{\mu_0}{4\pi r} \int \vec{j} dr', \quad \vec{A}^{(1)} = -\frac{\mu_0}{4\pi} \int \vec{j} (\vec{r} \cdot \nabla \frac{1}{r}) dr' = -\frac{\mu_0 \vec{r}}{4\pi r^3} \cdot \int \vec{r} \cdot \vec{j} dr'. \end{aligned}$$

And: $\nabla \cdot (\vec{j} fg) = \nabla \cdot \vec{j} fg + \vec{j} \cdot \nabla fg = \vec{j} \cdot \nabla fg$, Gauss Law: $\int \nabla \cdot (fg \vec{j}) dr' = \int fg \boxed{\vec{j} d\vec{s}} = 0$

$f=g$ eq: $\Rightarrow \int \vec{j} \cdot \nabla' fg dr' = \int (f \vec{j} \cdot \nabla g + g \vec{j} \cdot \nabla f) dr' = 0$

Considering $\vec{A}^{(0)}$, let $f=1$, $g=x'_i$, hence $\nabla fg = \nabla x'_i = \vec{e}_i$

$$\vec{A}_i^{(0)} = \int \vec{j} \cdot \nabla fg dr' = \int \vec{j} \cdot \vec{e}_i dr' = 0 \quad i=1,2,3 \Rightarrow \vec{A}^{(0)} = 0$$

Considering $\vec{A}^{(1)}$, let $f=x'_i$, $g=x'_j$, thus

$$\rightarrow \text{与角动量关系} \quad \vec{\mu} = \frac{q}{2m} \vec{L}$$

The force felt by a small current system

$$\vec{F} = \int \vec{j} \times \vec{B} dr' = \vec{F}^{(0)} + \vec{F}^{(1)} + \dots$$

$$\vec{F}^{(0)} = \left(\int \vec{j} dr' \right) \times \vec{B}^{(0)} = 0 \times \vec{B}^{(0)} = 0$$

$$\overline{F}^0 = \int \vec{J} \times (\vec{x} \cdot \nabla) \overrightarrow{B}(\theta) dV$$

$$\Rightarrow F_i^0 =$$

Chapter 8 Time-varying EM field

前置知识

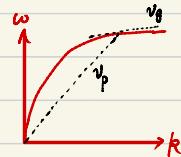
1. 色散 $n(\omega) = \frac{ck}{\omega} \Rightarrow \frac{\omega}{k} = f(\omega)$ 色散关系

2. phase velocity & group velocity $v_{\text{phase}} = \frac{\omega}{k}$, $v_{\text{group}} = \frac{\partial \omega}{\partial k}$

3. $\phi = \phi_0 e^{i(kx - \omega t)}$, (虚波代表了振幅的衰减)

replace relationship $\frac{\partial}{\partial t} = -i\omega$, $\frac{\partial}{\partial x} = ik$ OR $\nabla = i\vec{k}$

e.g.: $i\hbar\omega = \frac{1}{2m}(\hbar k)^2 + V \Rightarrow i\hbar\frac{\partial}{\partial t} = \frac{\hbar^2}{2m}\left(-\frac{\partial^2}{\partial x^2}\right) + V \Rightarrow \underbrace{i\hbar\frac{\partial \psi}{\partial t} + \frac{\hbar^2}{2m}\nabla^2\psi}_{V\psi} = 0$



Time-dependent EM field in vacuum

$$\Rightarrow \left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) \vec{B} = 0 \quad \left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) \vec{E} = 0$$

Properties for:

Plane wave \curvearrowleft only one spacial coordinate

Complex Notation for monochromatic $f = \text{Re}[\hat{A} e^{i(kx - \omega t)}] = \text{Re}[\hat{f}]$

here, \hat{A} is complex Amplitude $\hat{A} = A_0 e^{i\phi_0}$

more general: $\hat{f} = \hat{A} e^{i(\vec{k}\vec{x} - \omega t)}$, hence $\nabla = i\vec{k}$

$$f(t, x) = \sum_i \hat{A}_i(\vec{k}_i) e^{i(\vec{k}_i \cdot \vec{x} - \omega_i t)} \\ = \int \hat{B}(\vec{k}) e^{i(\vec{k} \cdot \vec{x} - \omega t)} dk \quad \left. \begin{array}{l} \text{Two type of Fourier Transformation} \\ \text{E. B. have the same phase} \end{array} \right\}$$

Thus $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \Rightarrow \vec{k} \times \vec{E} = \omega \vec{B}$ $\left. \begin{array}{l} \text{E. B. are perpendicular to each other} \\ B_0 = E_0 \frac{k}{\omega} = E_0 / c \end{array} \right\}$

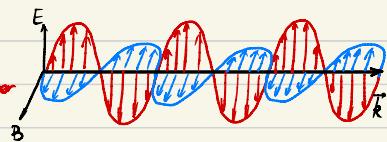
$$\left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) \vec{E} = \left(\frac{1}{c^2} \omega^2 + k^2 \right) \vec{E} = 0 \quad C = \frac{\omega}{k}$$

Field Energy Density: $\left. \begin{array}{l} w = \frac{1}{2} \epsilon_0 E^2 + \frac{1}{2} \mu_0 B^2 \\ w = \epsilon_0 E^2, \langle w \rangle = \frac{1}{2} \epsilon_0 E^2 \end{array} \right\}$ group velocity
 Poynting flux: $\vec{S} = w c \hat{k}$, momentum density: $\vec{q} = \vec{S}/c = \frac{w}{c} \hat{k}$

then how to use complex notation to express these density?

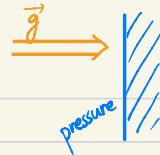
$$\langle w \rangle = \frac{\epsilon_0}{2} \hat{E}_0 \hat{E}_0^* \quad \langle \vec{S} \rangle = \frac{1}{2} c \epsilon_0 E_0^2 \hat{k} = c \langle w \rangle \hat{k}, \quad \langle \vec{q} \rangle = \frac{\langle w \rangle}{c} \hat{k} = \frac{\epsilon_0 E_0^2}{2c} \hat{k}$$

ep: 波的强度 I



$$\text{辐射光压 } p = \langle g \rangle c = \frac{1}{2} \epsilon_0 E^2 = \frac{I}{c}$$

$$2\langle g \rangle c = \epsilon_0 E^2 = 2 \frac{I}{c}$$



EM field in homogeneous linear media

\vec{E}, \vec{B} satisfies: $\frac{1}{c^2} \frac{\partial^2}{\partial t^2} u - \nabla^2 u = 0$ where $v = \frac{1}{\sqrt{\epsilon_0 \mu}}$ is the phase velocity

Solve for plane wave: $\tilde{u} = u_0 e^{i(kx - wt)}$

$$\tilde{n} = c k / \omega \text{ (real & image part)} \quad \tilde{n} = n_r + i n_i$$

A model for refraction index and its frequency dependence

$$F = -\frac{\partial V}{\partial x} \approx -x \frac{\partial^2 V}{\partial x^2} \triangleq -m\omega_0^2 x \Rightarrow m\ddot{x} = -m\omega_0^2 x \text{ (model equation without EM field)}$$

Considering $\frac{Bc}{E} \sim \frac{v}{c} \sim 0$ (for Non-relativity), and δx is small,

$$F_{\text{em}} \approx -eE_0 e^{i(kx - wt)} = -eE_0 e^{-iwt}$$

$$\text{thus } m\ddot{x} = -m\omega_0^2 x - eE_0 e^{-iwt} - my \dot{x} \Leftrightarrow \ddot{x} + \gamma \dot{x} + \omega_0^2 x = -\frac{e}{m} E_0 e^{-iwt}$$

$$\tilde{x} = x e^{iwt}, \quad \tilde{x} = -\frac{e}{m} \frac{1}{\omega_0^2 - \omega^2 - i\omega\gamma} \tilde{E}$$

the dipole moment is $\tilde{p} = -e\tilde{x}$

$$\text{thus } \tilde{p} = n\tilde{x}, \quad \epsilon_r = 1 + \chi_e = 1 + \frac{ne^2}{m\epsilon_0} \sum_j \frac{f_j}{\omega_j^2 - \omega^2 - i\omega\gamma_j}$$

$$n = \sqrt{\epsilon_r} \approx 1 + \frac{1}{2} \cdot \frac{ne^2}{m\epsilon_0} \sum_j \frac{f_j}{\omega_j^2 - \omega^2 - i\omega\gamma_j}$$

we define $\tilde{k} = \tilde{n} \frac{\omega}{c} = \boxed{\beta + \frac{\alpha}{2} i}$, then the intense will decline with $e^{-\alpha x}$

Fourier Series

1. 周期函数的 Fourier Series

对于周期为 $2L$ 的 $f(x)$

$$f(x) = a_0 + \sum_{n=1}^{\infty} (a_n \cos \frac{n\pi x}{L} + b_n \sin \frac{n\pi x}{L})$$

$$a_0 = \frac{1}{2L} \int_{-L}^L f(x) dx, \quad a_n = \frac{1}{L} \int_{-L}^L f(x) \cos \frac{n\pi x}{L} dx, \quad b_n = \frac{1}{L} \int_{-L}^L f(x) \sin \frac{n\pi x}{L} dx$$

e.g.: 锯齿函数 $\sum_{n=1}^{\infty} \frac{\sin nx}{n} = \frac{1}{2}(\pi - x), 0 < x < 2\pi$

2. 带限 Fourier Series

对定义在 $0 < x < L$ 上的 $\phi(x)$, 有几种展开式

$$\int_0^L \sin \frac{m\pi x}{L} \sin \frac{n\pi x}{L} dx = \frac{L}{2} \delta_{mn}$$

正弦式 $\phi(x) = \sum_{n=1}^{\infty} C_n \sin \frac{n\pi x}{L}, \quad C_n = \frac{2}{L} \int_0^L \phi(x) \sin \frac{n\pi x}{L} dx$

余弦式 $\phi(x) = D_0 + \sum_{n=1}^{\infty} D_n \cos \frac{n\pi x}{L}, \quad D_0 = \frac{1}{L} \int_0^L \phi(x) dx, \quad D_n = \frac{2}{L} \int_0^L \phi(x) \cos \frac{n\pi x}{L} dx$

更一般地 在 $[a, b]$ 上, $L = \frac{b-a}{2}, \quad a_0 = \frac{1}{b-a} \int_a^b \phi(x) dx, \quad a_n = \frac{1}{b-a} \int_a^b \phi(x) \cos \frac{n\pi x}{L} dx$
 $b_n = \frac{1}{b-a} \int_a^b \phi(x) \sin \frac{n\pi x}{L} dx$

3. Fourier Integrate

若 x 在 $(-\infty, +\infty)$ 上的函数 $f(x)$ 绝对可积, 即 $\int_{-\infty}^{\infty} |f(t)| dt = A$ (有限值), 展开有

$$f(x) = \int_0^{\infty} [A(\omega) \cos \omega x + B(\omega) \sin \omega x] d\omega$$

$$A(\omega) = \frac{1}{\pi} \int_{-\infty}^{\infty} f(t) \cos \omega t dt, \quad B(\omega) = \frac{1}{\pi} \int_{-\infty}^{\infty} f(t) \sin \omega t dt$$

偶

$$\text{Dirichlet Integrate: } \int_0^{\infty} \frac{\sin \omega t}{\omega} dt = \frac{\pi}{2} \quad \& \quad \int_0^{\infty} \frac{\cos(\omega \pi/2)}{1-\omega^2} d\omega = \frac{\pi}{2}$$

Fourier Transform

$$f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(t) e^{-iwt} dt e^{iwx} dw$$

F(w)

18.31 Fourier transform: $F(w) = \int_{-\infty}^{\infty} f(x) e^{-iwx} dx, -\infty < w < \infty \iff F(w) = \mathcal{F}\{f(x)\}$

Fourier inverse transform: $f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(w) e^{iwx} dw, -\infty < x < \infty \iff f(x) = \mathcal{F}^{-1}\{F(w)\}$

Fourier Transform is a Linear Transform !!!

Properties of Fourier Transform:

1) Differential th.1: if $f(x) \leftrightarrow F(w)$

$$\text{then } \frac{df(x)}{dx} \leftrightarrow i\omega F(w), \quad f^{(n)}(x) \leftrightarrow (i\omega)^n F(w)$$

$$\vec{D} = \vec{E} \vec{E}$$

2) Differential th.2: $x f(x) \leftrightarrow i \frac{d}{dw} F(w)$

$$\Rightarrow \vec{E} \cdot \frac{d\vec{D}}{dt} = \vec{D} \cdot \frac{d\vec{E}}{dt}$$

3) Integral th.: $\int_x^y f(x) dx \leftrightarrow \frac{F(y) - F(x)}{iw}$

4) Displacement th.: $f(x+z) \longleftrightarrow e^{i\omega z} F(\omega)$

5) Convolution

① definition: $f_1(x) * f_2(x) = \int_{-\infty}^{\infty} f_1(z) f_2(x-z) dz$

② convolution th.: $f_1(x) * f_2(x) \longleftrightarrow F_1(\omega) F_2(\omega)$

Method of separation of variables

\mathcal{L} is a Linear Operator, then we have

$$\mathcal{L} u(x,t) = 0 \Rightarrow \begin{cases} \mathcal{L}_x X(x) = 0 \\ \mathcal{L}_t T(t) = 0 \end{cases}, \text{ thus } u(x,t) = X(x) T(t)$$

其次!

* 是数理方程里的东西，不作为重点

EM Waves in conductors

For atoms in conductors { bound ele (束缚电荷) $\sim \epsilon$
free ele (自由电荷) $\sim \sigma$

$$\left\{ \begin{array}{l} \nabla \cdot \vec{E} = \frac{\rho_f}{\epsilon} \\ \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \\ \nabla \cdot \vec{B} = 0 \\ \nabla \times \vec{B} = \mu \epsilon \frac{\partial \vec{E}}{\partial t} + \mu \sigma \vec{E} \end{array} \right.$$

$$\frac{\partial \rho_f}{\partial t} = -\nabla \cdot \vec{j}_f = -\nabla \cdot \sigma \vec{E} = -\frac{\sigma}{\epsilon} \rho_f \Rightarrow \rho_f = \rho_{f0} e^{-t/\tau} \sim \tau$$

$$\text{for good conductors: } \tau = \frac{\epsilon}{\sigma} \ll \omega$$

after a few τ 's, $\rho_f \rightarrow 0$.

then we have

$$\left\{ \begin{array}{l} \nabla \cdot \vec{E} = 0 \\ \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \\ \nabla \cdot \vec{B} = 0 \\ \nabla \times \vec{B} = \mu \epsilon \frac{\partial \vec{E}}{\partial t} + \mu \sigma \vec{E} \end{array} \right.$$

$$\begin{aligned} \nabla \times (\nabla \times \vec{E}) &= -\nabla^2 \vec{E} = -\mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2} - \mu \sigma \frac{\partial \vec{E}}{\partial t} \\ \nabla \times (\nabla \times \vec{B}) &= -\nabla^2 \vec{B} = -\mu \epsilon \frac{\partial^2 \vec{B}}{\partial t^2} - \mu \sigma \frac{\partial \vec{B}}{\partial t} \end{aligned}$$

$$\Rightarrow \nabla^2 \vec{E} = \mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2} + \mu \sigma \frac{\partial \vec{E}}{\partial t} \sim m \ddot{x} + m\omega^2 x = -m\dot{x}$$

similar to oscillator with damping term

using Plane Wave Solution $\vec{E} = E_0 e^{i(kz-\omega t)}$, then we have

$$k^2 = \mu \epsilon \omega^2 + i \mu \sigma \omega$$

Put $k = kr + ik_i$ into it, then $\left\{ \begin{array}{l} kr = \beta = \sqrt{\frac{\mu \epsilon}{2}} \omega \left[\sqrt{1 + \left(\frac{\sigma}{\epsilon \omega} \right)^2} + 1 \right]^{1/2} \\ k_i = \frac{\alpha}{2} = \sqrt{\frac{\mu \epsilon}{2}} \omega \left[\sqrt{1 + \left(\frac{\sigma}{\epsilon \omega} \right)^2} - 1 \right]^{1/2} \end{array} \right.$

♦ for good conductor, $\frac{\sigma}{\epsilon \omega} \gg 1$, $k_r \approx k_i = \sqrt{\frac{\mu \sigma \omega}{2}}$, $k = \sqrt{\mu \sigma \omega} e^{i\frac{\pi}{4}} = K e^{i\phi}$

$$\text{then } \vec{E} = E_0 e^{-k_r z} e^{i(k_r z - \omega t)} \hat{x}$$

$$\text{using Faraday th., we get } \vec{B} = \frac{k \times \vec{E}}{\omega} = \frac{i}{\omega} E_0 e^{-k_r z} e^{i(k_r z - \omega t + \frac{\pi}{4})} \hat{y}$$

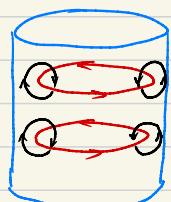


Also, the attenuation of the field, reduce by a factor of e^{-t} is the skin depth (趋肤深度) s ,

$$s = \frac{1}{k_i} = \sqrt{\frac{2}{\mu \sigma \omega}} \quad \text{for a higher frequency } \omega, \text{ the EM Wave has a smaller skin depth}$$

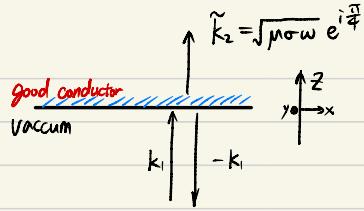
Considering the EM energy,

$$\frac{W_E}{E_E} = \frac{B^2 / M}{\epsilon E^2} = \frac{\mu \sigma / M}{\epsilon} = \frac{\sigma}{\omega \epsilon} \gg 1 \quad (\text{however } \frac{W_E}{E_E} = 1 \text{ in vacuum})$$



Reflection at a conducting surface

$$\left\{ \begin{array}{l} E_{Io} + E_{Ro} = E_{To} \\ \frac{k_1}{\mu\omega} (E_{Io} - E_{Ro}) = \frac{\tilde{k}_2}{\mu\omega} E_{To} \Leftrightarrow E_{Io} - E_{Ro} = \frac{\mu_1 \tilde{k}_2}{\mu_2 k_1} E_{To} = \tilde{\beta} E_{To} \end{array} \right.$$



$$\text{thus } \left\{ \begin{array}{l} E_{Ro} = \frac{1 - \tilde{\beta}}{1 + \tilde{\beta}} E_{Io} \\ E_{To} = \frac{2}{1 + \tilde{\beta}} E_{Io} \end{array} \right| \quad \sigma \rightarrow \infty, \tilde{k}_2 \& \tilde{\beta} \rightarrow \infty$$

$E_{Ro} = -E_{Io}$ (half-wave loss)

$$\text{we define } R = \left| \frac{E_{Ro}}{E_{Io}} \right|^2 = \left| \frac{\mu_1 k_1 - \mu_2 \tilde{k}_2}{\mu_1 k_1 + \mu_2 \tilde{k}_2} \right|^2$$

$$\approx 1 - 2 \sqrt{\frac{2\omega}{\sigma}}$$

Propagation of EM Waves in Wave Guide (波导)

$$\left\{ \begin{array}{l} \vec{E}(x, y, z, t) = \vec{E}(x, y) e^{i(kz - \omega t)} \\ \vec{B}(x, y, z, t) = \vec{B}(x, y) e^{i(kz - \omega t)} \end{array} \right.$$

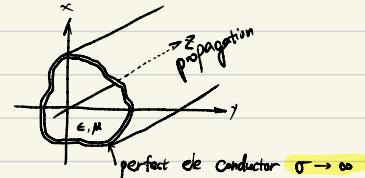
boundary condition : $\vec{E}^{\parallel} = 0, \vec{B}^{\perp} = 0$.

$$\text{wave eq: } \nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} - k^2, \frac{\partial^2}{\partial t^2} = -\omega^2$$

$$\Rightarrow \left[\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \left(\frac{\omega^2}{c^2} - k^2 \right) \right] \left[\begin{array}{c} \vec{E} \\ \vec{B} \end{array} \right] = 0$$

also with Faraday th: $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

$$\text{Ampere th: } \nabla \times \vec{B} = \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$



$$E_x = \frac{i}{\mu\epsilon\omega^2 - k^2} \left(k \frac{\partial E_z}{\partial x} + \omega \frac{\partial B_z}{\partial y} \right), \quad ①$$

$$E_y = \frac{i}{\mu\epsilon\omega^2 - k^2} \left(k \frac{\partial E_z}{\partial y} - \omega \frac{\partial B_z}{\partial x} \right), \quad ②$$

$$B_x = \frac{i}{\mu\epsilon\omega^2 - k^2} \left(k \frac{\partial B_z}{\partial x} - \mu\epsilon\omega \frac{\partial E_z}{\partial y} \right), \quad ③$$

$$B_y = \frac{i}{\mu\epsilon\omega^2 - k^2} \left(k \frac{\partial B_z}{\partial y} + \mu\epsilon\omega \frac{\partial E_z}{\partial x} \right). \quad ④$$

here we gave three types of Wave Mode $\left\{ \begin{array}{l} 1) E_z = 0 (\text{TE}) \\ 2) B_z = 0 (\text{TM}) \text{ called transverse wave mode} \\ 3) \text{Both} = 0 (\text{TEM}) \end{array} \right.$

for 3) TEM we get $\left\{ \begin{array}{l} \frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} = 0 \\ \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} = 0 \end{array} \right. \Rightarrow \vec{E} = E_x \hat{x} + E_y \hat{y}$ \Rightarrow divergence & curl free with BC: $\vec{E}^{\parallel} = 0 \Rightarrow \vec{E} = 0$

however, for a coaxial transmission line it will be possible

The Coaxial Transmission Line

$$E_z = 0, B_z = 0$$



$$k = \omega/c$$

$$cB_y = E_x \quad \frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} = 0, \quad \frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y} = 0,$$

$$cB_x = -E_y \quad \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} = 0, \quad \frac{\partial B_y}{\partial x} - \frac{\partial B_x}{\partial y} = 0.$$

$$CB = \vec{n} \times \vec{E}$$

$$E_0(s, \phi, z, t) = \frac{A \cos(kz - \omega t)}{s} \hat{s}, \quad B_0(s, \phi, z, t) = \frac{A \cos(kz - \omega t)}{cs} \hat{\phi},$$

$$E(s, \phi, z, t) = \frac{A \cos(kz - \omega t)}{s} \hat{s}, \quad B(s, \phi, z, t) = \frac{A \cos(kz - \omega t)}{cs} \hat{\phi}.$$

for 1) TE mode in rectangular wave guide

Using separation of variables $B_2 = X(x)Y(y)$

$$(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \mu\epsilon\omega^2 - k^2)B_2 = 0 \Rightarrow \frac{1}{X}\frac{d^2X}{dx^2} + \frac{1}{Y}\frac{d^2Y}{dy^2} + \mu\epsilon\omega^2 - k^2 = 0$$

Considering B.C. with ③④: $\frac{\partial B_2}{\partial x} = 0$ at $x=0, a$; $\frac{\partial B_2}{\partial y} = 0$ at $y=0, b$

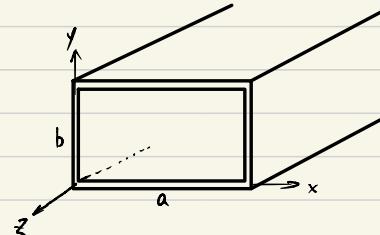
$$X(x) = B \cos(k_x x), \text{ with } k_x = m\pi/a,$$

$$Y(y) = D \cos(k_y y), \text{ with } k_y = n\pi/b.$$

$$\Rightarrow B_2 = B_0 \cos(m\pi x/a) \cos(n\pi y/b) e^{ikz}, \quad k = \sqrt{\mu\epsilon\omega^2 - \pi^2 \left[\left(\frac{m}{a}\right)^2 + \left(\frac{n}{b}\right)^2 \right]}$$

phase velocity $v_{ph} = \frac{\omega}{k} = \frac{1}{\sqrt{\mu\epsilon} \sqrt{1 - (\omega_{mn}/\omega)^2}}$

group velocity $v_g = \frac{d\omega}{dk} = \frac{1}{dk/d\omega} = \frac{1}{\sqrt{\mu\epsilon}} \sqrt{1 - (\omega_{mn}/\omega)^2}$.



for 1) TE mode in cavity (腔)

$$z=0, d, B_2 = 0 \Rightarrow B_2 = B_0 \cos(m\pi x/a) \cos(n\pi y/b) \sin(p\pi z/d)$$

$$\omega_{mnp} = c\pi \sqrt{\left(\frac{m}{a}\right)^2 + \left(\frac{n}{b}\right)^2 + \left(\frac{p}{d}\right)^2}$$

$$\lambda_{110} = \sqrt{2}a \sim \text{紫金葫芦}$$

Chapter 9 Fields of Moving Particle

Solution of the EM field eq.:

$$\left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) \phi = \frac{\rho(t, \vec{r})}{\epsilon_0} = \frac{dg(t) S(\vec{r} - \vec{R})}{\epsilon_0} \quad \text{Green Function Method}$$

Let $\vec{R} = \vec{r} - \vec{r}'$

$$= \frac{dg(t) S(\vec{R})}{\epsilon_0} = \begin{cases} 0, & \text{away from charge} \\ \frac{dg(t) S(\vec{R})}{\epsilon_0}, & \text{near the charge} \end{cases} \quad \begin{array}{l} \textcircled{1} \\ \textcircled{2} \end{array}$$

general solution for \textcircled{2} (in sphere coordinate):

$$\frac{1}{c^2} \frac{\partial^2 \phi}{\partial t^2} - \frac{1}{R^2} \frac{\partial}{\partial R} \left(R^2 \frac{\partial \phi}{\partial R} \right) = \frac{1}{c^2} \frac{\partial^2 \phi}{\partial t^2} - \frac{\partial^2}{\partial R^2} (R \phi) = 0$$

$$\Rightarrow \phi = \frac{f(t - \frac{R}{c})}{R} + \frac{g(t + \frac{R}{c})}{R}$$

propagate in +R direction propagate in -R direction, give up

Solution for \textcircled{2} when $R \rightarrow 0$,

$$\nabla^2 \phi = - \frac{dg(t) S(\vec{R})}{\epsilon_0}, \quad \frac{\partial \phi}{\partial r} \text{ is always finite}$$

$$\Rightarrow \phi = \frac{dg(t)}{4\pi\epsilon_0 R}$$

Boundary Condition:

$$R \rightarrow 0, \quad \phi_A \rightarrow \phi_N \Rightarrow \chi(t) = \frac{dg(t)}{4\pi\epsilon_0}$$

hence we get

$$\phi = \frac{dg(t - \frac{R}{c})}{4\pi\epsilon_0 R} \quad \frac{R}{c} \text{ earlier than we get the signal.}$$

moreover

$$\begin{aligned} \phi(\vec{r}, t) &= \frac{1}{4\pi\epsilon_0} \int \frac{1}{R} S(\vec{r}', t - \frac{R}{c}) dV' \\ \vec{A}(\vec{r}, t) &= \frac{\mu_0}{4\pi} \int \frac{1}{R} \vec{J}'(\vec{r}', t - \frac{R}{c}) dV' \end{aligned}$$

retarded potential (solution of general EM field eq.)

Fields of a moving charge : The Lienard-Wiechert potential

$$\rho(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} S[\vec{r} - \vec{r}_p(t)]$$

$$\rho(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} S[\vec{r} - \vec{r}_p(t - \frac{R}{c})]$$

$$\phi(\vec{r}, t) = \frac{q}{4\pi\epsilon_0 c} \int \frac{S[\vec{r} - \vec{r}_p(t')]}{|\vec{r} - \vec{r}|} dV'$$

