VelaLab reference Manual

November 28, 2017

1 System Architecture

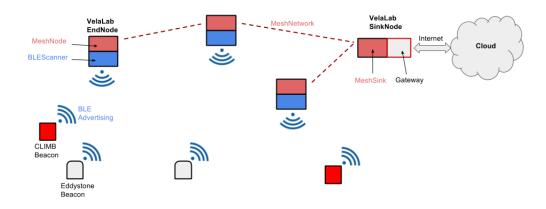


Figure 1:

1.1 Namings and definitions

BLE_Beacon

Any beacon device that can be detected from the system. Now it can be of two types: $CLIMB_Beacon$ and $Eddystone_Beacon$.

VelaLab_EndNode

One of the nodes forming the BLE+mesh network. It is formed by a $BLE_Scanner$ and a $Mesh_Node$, which communicate via a serial connection (UART).

BLE_Scanner

BLE part of an EndNode, based on the Nordinc nRFxx and implemented on the nRFxxx development board.

Mesh_Node

Mesh/Contiki part of an EndNode, based on the TI CCxxxxx and implemented on the Lauchpad xxx dev board.

VelaLab_SinkNode

The sink/gateway node of the network. It combines the Mesh_Sink and the Gateway, which are connected using the serial to USB feature on the Mesh_Sink. It does not have the BLE_Scanner (only mesh and gateway)

Mesh_Sink

The sink node for the mesh/contiki network. Its hardware is equivalent to a Mesh_Node, but it has a different firmware.

Gateway

The gateway between the network and the internet/cloud. It is implemented using a Raspberry PI 3 (RPI). The Mesh_Sink is connected through a USB port and it connects to the internet through Ethernet or WiFi.

Contact_Data Structure

Contact_Data is the data structure containing the information about the contact of one BLE Beacon. A Report is an array of Contact_Data containing all the data received during the last epoch. All the reported parameters refer to the last epoch.

Field	Type	Size (Byte)
NodeID	uint	6
lastRSSI	int	1
maxRSSI	int	1
${\tt pktCounter}$	u8	1

Back-End Data Structure (as in CLIMB)

Data structure containing the information to be sent from the gateway to the server, encoded as a json object. Each call send an array of such objects.

Field	Type
wsnNodeId	string
${\tt eventType}$	\inf
timestamp	$_{ m int}$
payload	object

Payload may contain:

Field	Type
passengerId	string
latitude	float
longitude	float
accuracy	float

2 Beacons

Types:

- CLIMB (custom)
- Eddystone

3 VelaLab End-Node

Components:

- BLE Scanner
- Mesh Node

3.1 Hardware interconnection

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The Launchpad image refers to the revision 1.0 of the hardware. In that version the DIO2 and DIO3 pins were incorrectly labelled (labels are swapped with respect to actual pin location). This scheme refers to the actual wiring position, then discard any label on the board and just wire as shown.

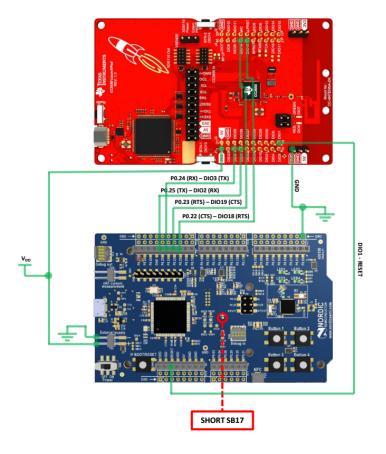


Figure 2:

3.2 Communication protocol

UART communication protocol between BLE Scanner and Mesh Node

4 VelaLab Sink-Node

Components:

- Mesh Sink
- Gateway

4.1 Hardware interconnection

Launchpad usb output to RPI's USB

4.2 Communication protocol

UART communication protocol between Mesh Sink and Gateway