

SafeZone : Real-time Video Analytics for Industrial Safety

TEAM NAME: The Tech Titians

TEAM MEMBERS:

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Problem Statement:

To develop a system that can automatically and accurately detect whether or not workers are wearing personal protective equipment (PPE). PPE is essential for protecting workers from hazards in the workplace, and non-compliance with PPE requirements can lead to serious injuries or death.

The problem statement for ***SafeZone: Real-time Video Analytics for Industrial Safety*** can be broken down into the following sub-problems:

- **Object detection:** The system must be able to detect people and PPE items in images or video. This is a challenging problem due to the variability in the appearance of PPE items, the occlusion of PPE items by other objects, and the cluttered background in many workplace environments.

- **Classification:** The system must be able to classify each PPE item as either present or not present. This is also a challenging problem due to the variability in the appearance of PPE items and the possibility of PPE items being partially obscured.
- **Real-time operation:** The system must be able to operate in real time, so that it can be used to monitor workers in a dynamic workplace environment.

MILESTONE 1 : Pre-Requisite

Tools Used:

1. ultralytics - For YOLO
2. YOLOv8 - For dataset and model training
3. CVzone – To connect with videos and webcam
4. Programming Language – Python 11
5. Environment – PyCharm

Data Collection:

- We have collected the dataset from Roboflow which is a untrained dataset and by using YOLO (Version 8) we are training those dataset.

Explanation Video

https://drive.google.com/file/d/109oWMxce_kqNcficUxwPHAG_KHCbyg87/view?usp=sharing

Custom Data Training:

- As the accuracy of the readily available dataset is low, we have collected the images and trained the images for developing the model.
- Custom data training in PPE is the process of training a machine learning model to detect personal protective

equipment (PPE) in images or videos. This can be done by collecting a dataset of images or videos that contain PPE, and then annotating each image or video with the location and type of PPE. The annotated dataset is then used to train the machine learning model.

Explanation Video

https://drive.google.com/file/d/1jhBb8in9uQbwBZVW3leWOec8v9xNKu_H/view?usp=sharing

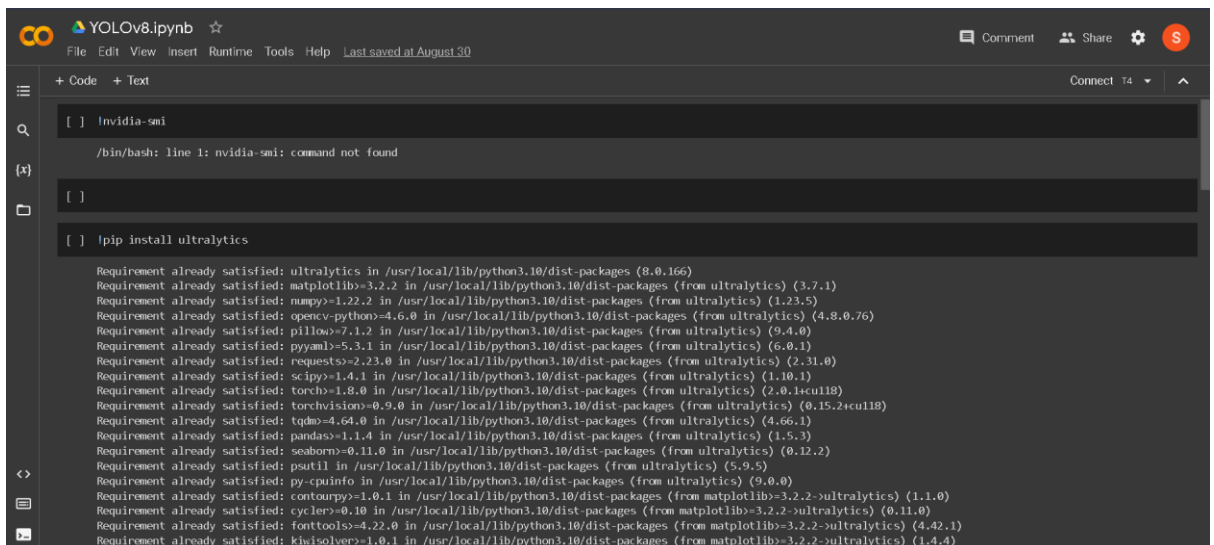
MILESTONE 2 : BUILD SOLUTION

2.1 – CUSTOM DATA TRAINING:

- For Custom Data Training, we have chosen Google Colab as the environment because we doesn't have any dedicated graphics card in my laptop. Google Colab provides a virtual GPU to some extend .
- We are dividing the 10 groups in the model

Class Names are:

['bare_arm', 'boot', 'glasses', 'glove', 'hard_hat', 'mask', 'no_glove', 'no_hard_hat', 'no_mask', 'no_vest', 'person', 'vest']



```
YOLOv8.ipynb
File Edit View Insert Runtime Tools Help Last saved at August 30
+ Code + Text
[ ] Invidia-smi
/bin/bash: line 1: nvidia-smi: command not found
[ ]
[ ] !pip install ultralytics
Requirement already satisfied: ultralytics in /usr/local/lib/python3.10/dist-packages (8.0.166)
Requirement already satisfied: matplotlib>=3.2.2 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (3.7.1)
Requirement already satisfied: numpy>=1.22.2 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (1.23.5)
Requirement already satisfied: opencv-python>=4.6.0 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (4.8.0.76)
Requirement already satisfied: pillow>=7.1.2 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (9.4.0)
Requirement already satisfied: pyyaml>=5.3.1 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (6.0.1)
Requirement already satisfied: requests>=2.23.0 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (2.31.0)
Requirement already satisfied: scipy>=1.4.1 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (1.10.1)
Requirement already satisfied: torchvision>=0.9.0 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (0.15.2+cu118)
Requirement already satisfied: tqdm>=4.64.0 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (4.66.1)
Requirement already satisfied: pandas>=1.1.4 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (1.5.3)
Requirement already satisfied: seaborn>=0.11.0 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (0.12.2)
Requirement already satisfied: psutil in /usr/local/lib/python3.10/dist-packages (from ultralytics) (5.9.5)
Requirement already satisfied: py-cpuinfo in /usr/local/lib/python3.10/dist-packages (from ultralytics) (9.0.0)
Requirement already satisfied: contourpy>=1.0.1 in /usr/local/lib/python3.10/dist-packages (from matplotlib>=3.2.2->ultralytics) (1.1.0)
Requirement already satisfied: cyclo>=0.10 in /usr/local/lib/python3.10/dist-packages (from matplotlib>=3.2.2->ultralytics) (0.11.0)
Requirement already satisfied: fonttools>=4.22.0 in /usr/local/lib/python3.10/dist-packages (from matplotlib>=3.2.2->ultralytics) (4.42.1)
Requirement already satisfied: kisisolver>=1.0.1 in /usr/local/lib/python3.10/dist-packages (from matplotlib>=3.2.2->ultralytics) (1.4.4)
```

```
[ ] from ultralytics import YOLO

[ ] from google.colab import drive
drive.mount('/content/drive')

Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", force_remount=True).

[ ] lyolo task = detect mode = predict model = yolov8l.pt conf = 0.25 source='https://ultralytics.com/images/bus.jpg' epochs = 50 imgsz = 640

Ultralytics YOLOv8.0.166 Python-3.10.12 torch-2.0.1+cu118 CPU (Intel Xeon 2.20GHz)
YOLOv8l summary (fused): 268 layers, 43668288 parameters, 0 gradients

Downloading https://ultralytics.com/images/bus.jpg to 'bus.jpg'...
100% 476k/476k [00:00<00:00, 13.6MB/s]
image 1/1 /content/bus.jpg: 640x480 5 persons, 1 bicycle, 1 bus, 2515.0ms
Speed: 19.9ms preprocess, 2515.0ms inference, 35.4ms postprocess per image at shape (1, 3, 640, 480)
Results saved to runs/detect/predict

[ ] lyolo task = detect mode = train model = yolov8l.pt data = ../content/drive/MyDrive/Dataset/data.yaml epochs = 50 imgsz = 640

Ultralytics YOLOv8.0.166 Python-3.10.12 torch-2.0.1+cu118 CPU (Intel Xeon 2.20GHz)
engine/trainer: task=detect, mode=train, model=yolov8l.pt, data=../content/drive/MyDrive/Dataset/data.yaml, epochs=50, patience=50, batch=16, imgsz=640, save=True, save_period
Overriding model.yaml nc=80 with nc=10
```

	from	n	params	module	arguments
0	-1	1	1856	ultralytics.nn.modules.conv.Conv	[3, 64, 3, 2]
1	-1	1	73984	ultralytics.nn.modules.conv.Conv	[64, 128, 3, 2]

```
[ ] lyolo task = detect mode = train model = yolov8l.pt data = ../content/drive/MyDrive/Dataset/data.yaml epochs = 50 imgsz = 640

Ultralytics YOLOv8.0.166 Python-3.10.12 torch-2.0.1+cu118 CPU (Intel Xeon 2.20GHz)
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Overriding model.yaml nc=80 with nc=10
```

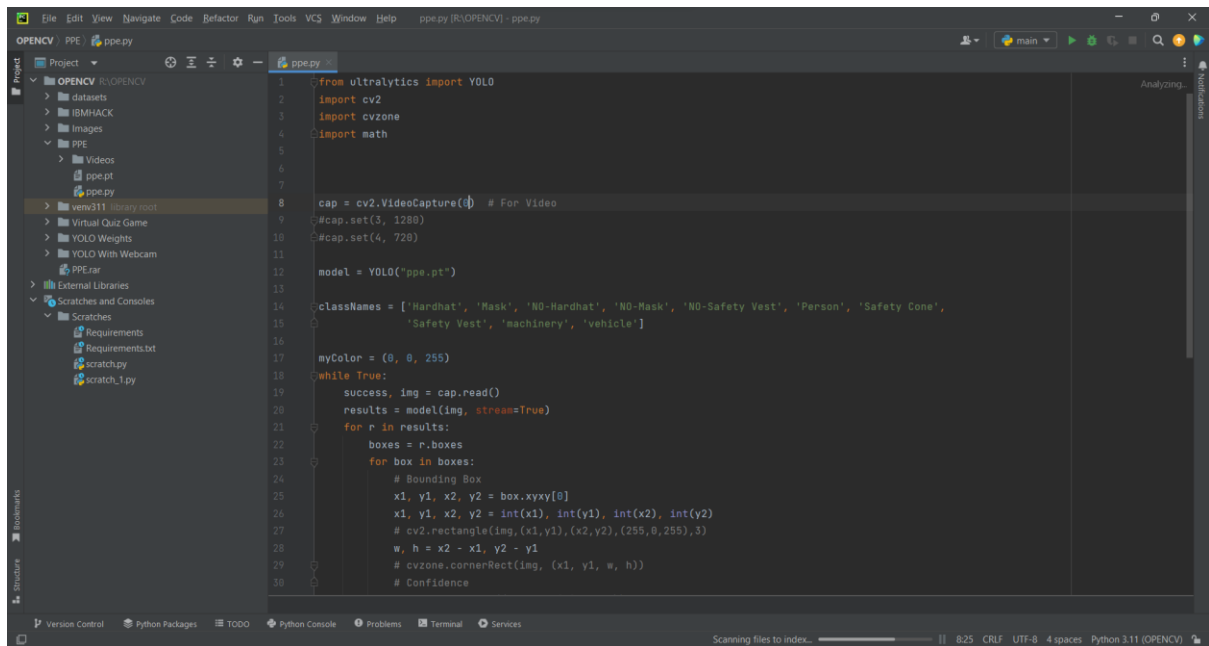
	from	n	params	module	arguments
0	-1	1	1856	ultralytics.nn.modules.conv.Conv	[3, 64, 3, 2]
1	-1	1	73984	ultralytics.nn.modules.conv.Conv	[64, 128, 3, 2]
2	-1	3	279808	ultralytics.nn.modules.block.C2f	[128, 128, 3, True]
3	-1	1	295424	ultralytics.nn.modules.conv.Conv	[128, 256, 3, 2]
4	-1	6	2181248	ultralytics.nn.modules.block.C2f	[256, 256, 6, True]
5	-1	1	1180672	ultralytics.nn.modules.conv.Conv	[256, 512, 3, 2]
6	-1	6	8396800	ultralytics.nn.modules.block.C2f	[512, 512, 6, True]
7	-1	1	2360320	ultralytics.nn.modules.conv.Conv	[512, 512, 3, 2]
8	-1	3	4461568	ultralytics.nn.modules.block.C2f	[512, 512, 3, True]
9	-1	1	656896	ultralytics.nn.modules.block.SPPF	[512, 512, 5]
10	-1	1	0	torch.nn.modules.upsampling.Upsample	[None, 2, 'nearest']
11	[-1, 6]	1	0	ultralytics.nn.modules.conv.Concat	[1]
12	-1	3	4723712	ultralytics.nn.modules.block.C2f	[1024, 512, 3]
13	-1	1	0	torch.nn.modules.upsampling.Upsample	[None, 2, 'nearest']
14	[-1, 4]	1	0	ultralytics.nn.modules.conv.Concat	[1]
15	-1	3	1247744	ultralytics.nn.modules.block.C2f	[768, 256, 3]
16	-1	1	590336	ultralytics.nn.modules.conv.Conv	[256, 256, 3, 2]
17	[-1, 12]	1	0	ultralytics.nn.modules.conv.Concat	[1]
18	-1	3	4592640	ultralytics.nn.modules.block.C2f	[768, 512, 3]
19	-1	1	2360320	ultralytics.nn.modules.conv.Conv	[512, 512, 3, 2]
20	[-1, 9]	1	0	ultralytics.nn.modules.conv.Concat	[1]
21	-1	3	4723712	ultralytics.nn.modules.block.C2f	[1024, 512, 3]

- After the completion of all the epochs, Download the Trained Weights from Colab as "ppe.pt".

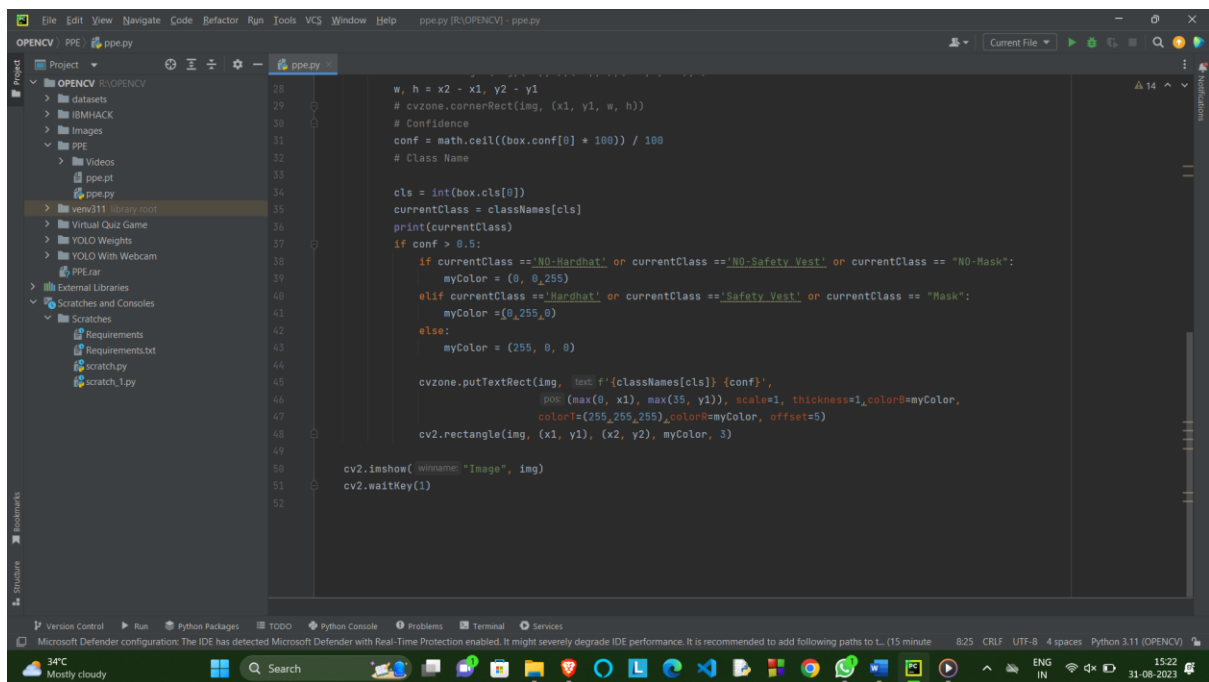
2.2 MODEL TRAINING:

- After training the dataset we take weights from it.
- We train models with the help of opencv library.
- Explanation Video

<https://drive.google.com/file/d/165Gul19dcheMsKU3Uf1X-AZ5A0Haonrp/view?usp=sharing>



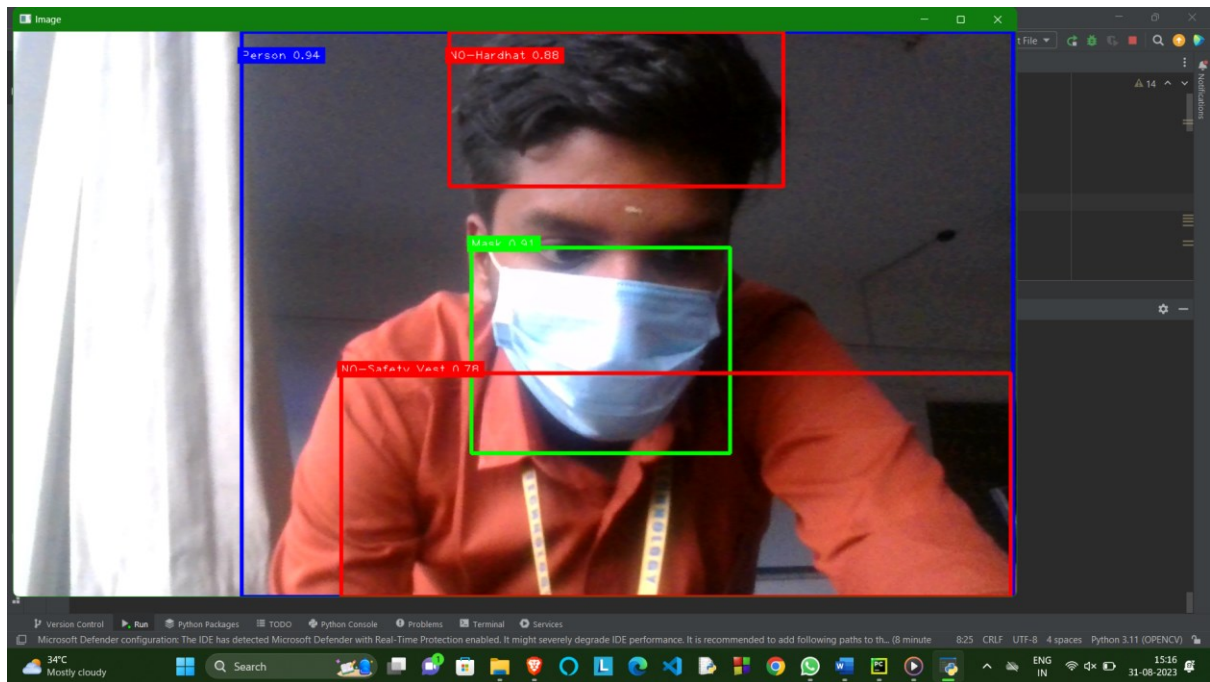
```
1 from ultralytics import YOLO
2 import cv2
3 import cvzone
4 import math
5
6
7
8 cap = cv2.VideoCapture(0) # For Video
9 #cap.set(3, 1280)
10 #cap.set(4, 720)
11
12 model = YOLO("ppe.pt")
13
14 classNames = ['Hardhat', 'Mask', 'NO-Hardhat', 'NO-Mask', 'NO-Safety Vest', 'Person', 'Safety Cone',
15              'Safety Vest', 'machinery', 'Vehicle']
16
17 myColor = (0, 0, 255)
18 while True:
19     success, img = cap.read()
20     results = model(img, stream=True)
21     for r in results:
22         boxes = r.boxes
23         for box in boxes:
24             # Bounding Box
25             x1, y1, x2, y2 = box.xyxy[0]
26             x1, y1, x2, y2 = int(x1), int(y1), int(x2), int(y2)
27             # cv2.rectangle(img, (x1,y1), (x2,y2), (255,0,255), 3)
28             w, h = x2 - x1, y2 - y1
29             # cvzone.cornerRect(img, (x1, y1, w, h))
30             # Confidence
```



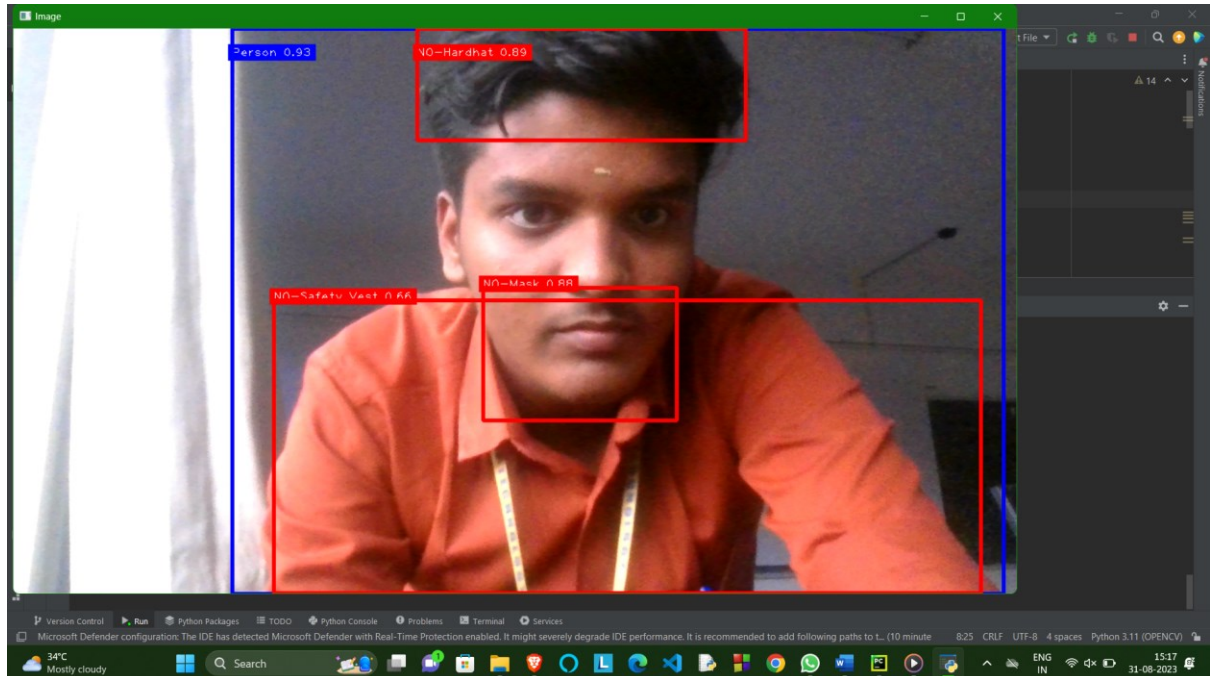
```
28 w, h = x2 - x1, y2 - y1
29 # cvzone.cornerRect(img, (x1, y1, w, h))
30 # Confidence
31 conf = math.ceil((box.conf[0] * 100)) / 100
32 # Class Name
33
34 cls = int(box.cls[0])
35 currentClass = classNames[cls]
36 print(currentClass)
37 if conf > 0.5:
38     if currentClass == 'NO-Hardhat' or currentClass == 'NO-Safety Vest' or currentClass == 'NO-Mask':
39         myColor = (0, 0, 255)
40     elif currentClass == 'Hardhat' or currentClass == 'Safety Vest' or currentClass == 'Mask':
41         myColor = (0, 255, 0)
42     else:
43         myColor = (255, 0, 0)
44
45     cvzone.putTextRect(img, text=f'{classNames[cls]} {conf}',
46                       pos=(max(0, x1), max(35, y1)), scale=1, thickness=1, color=myColor,
47                       colorI=(255, 255, 255), colorB=myColor, offset=5)
48     cv2.rectangle(img, (x1, y1), (x2, y2), myColor, 3)
49
50 cv2.imshow( winname="Image", img)
51 cv2.waitKey(1)
52
```

OUTPUT:

1-With Mask



2-Without Mask



NOTE:

- I have enclosed all the documents related to this project in the GitHub repository, Kindly refer it.