

INFORMATION, INCENTIVES AND AIR QUALITY: NEW EVIDENCE FROM MACHINE LEARNING PREDICTIONS

GARESC CONFERENCE

Luna Yue Huang¹ Minghao Qiu²

April 14, 2018

¹University of California, Berkeley

²Massachusetts Institute of Technology

Motivation

●○○

Testable Hypothesis

○

Policy

○○

Data

○○○○○○

Empirical Strategy

○○

Results

○○○○○

STYLIZED FACT 1: RAMPANT DATA MANIPULATION

- Anecdotal evidence: *The Ministry of Environmental Protection inspected 8,500 businesses in Beijing and surrounding areas and found that over 3,100 factories had tampered with their emission monitoring equipment and altered reported data*¹
- Statistical evidence: Local government officials also manipulate air quality data to satisfy targets assigned by the central government

¹Source: Caixin Global News Article

Motivation
○●○

Testable Hypothesis
○

Policy
○○

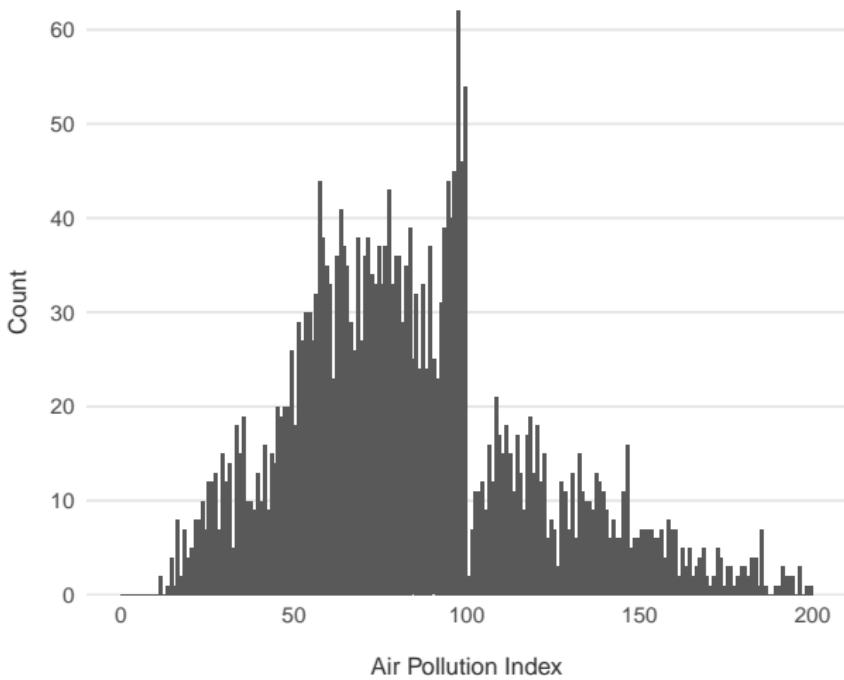
Data
○○○○○

Empirical Strategy
○○

Results
○○○○○

STYLIZED FACT 1: RAMPANT DATA MANIPULATION

Figure 1: Histogram of Reported Air Pollution Index in Beijing, 2005–2013



Motivation
○○●

Testable Hypothesis
○

Policy
○○

Data
○○○○○

Empirical Strategy
○○

Results
○○○○○

STYLIZED FACT 2: RECENT IMPROVEMENT IN DATA QUALITY

- Recent surge in investments in monitoring equipments in China that amount to approximately **0.95 billion USD** in just 2015 (Clean Air Act incurred approximately 65 billion USD in 30 years).
- Much more stringent regulations on maintaining the fidelity of air quality data:
 - Require **real-time hourly data** to be **automatically** publicized on data center websites and mobile apps
 - Employees at local environmental protection bureaus cannot have keys to monitoring stations²

²Source: Jinchu News Article

Motivation
ooo

Testable Hypothesis
●

Policy
oo

Data
oooooo

Empirical Strategy
oo

Results
ooooo

TESTABLE HYPOTHESIS

Testable Hypothesis

Does building national monitoring stations reduce information asymmetry between central and local regulators, incentivize local regulators to reduce emission, and thus improve air quality?

Institutional Context:

- Lack of any PM_{2.5} information before 2012
- Intensive inter-jurisdiction competition for political promotion
- In 2013, the central government signed separate “contracts” with provincial leaders promising reduction in ambient PM_{2.5} levels of up to 25% in five years

Motivation
○○○

Testable Hypothesis
○

Policy
●○

Data
○○○○○○

Empirical Strategy
○○

Results
○○○○○

POLICY

Testable Hypothesis

Does building national monitoring stations reduce information asymmetry between central and local regulators, incentivize local regulators to reduce emission, and thus improve air quality?

- Treatment: Reporting of Fine Particulate Matter ($PM_{2.5}$) monitoring data to the central government.
- “Contracts” were signed between central and local government to reduce $PM_{2.5}$ by a specific target value (ranging from 5% to 25%) by 2017
- The central government imposed the regulation on 74 cities in Jan 2013, over 100 cities in Jan 2014, and the rest in Jan 2015.

Motivation
○○○

Testable Hypothesis
○

Policy
○●

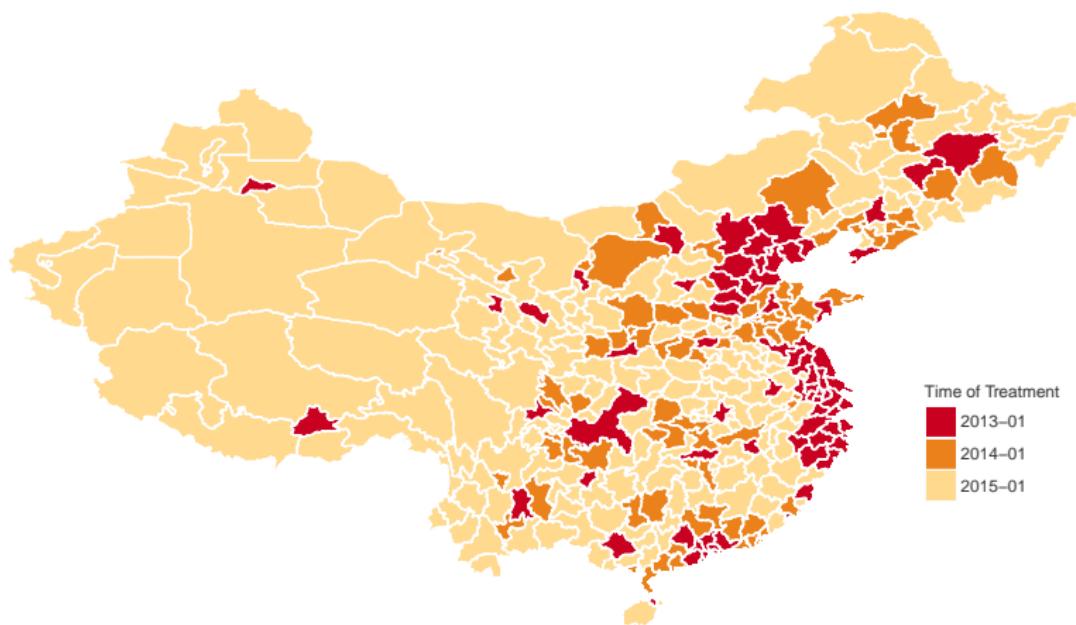
Data
○○○○○○

Empirical Strategy
○○

Results
○○○○○

POLICY

Figure 2: Time of Treatment: Dates when Cities Start Reporting PM_{2.5} Values



Motivation
ooo

Testable Hypothesis
o

Policy
oo

Data
●ooooo

Empirical Strategy
oo

Results
ooooo

KEY CONTRIBUTION: DATA

- Challenge: Data did not exist before monitoring stations were built—**pre-treatment data are unavailable**
- Solution: Recent development in **machine learning**, combined with **satellite images** collected by NASA, allows us to reconstruct historical air pollution datasets
- Compared to directly using satellite observations, we recover **ground-level concentrations**, with real welfare and health consequences, whereas raw satellite products report **column concentrations**

Motivation
○○○

Testable Hypothesis
○○○○○

Policy
○○○○○

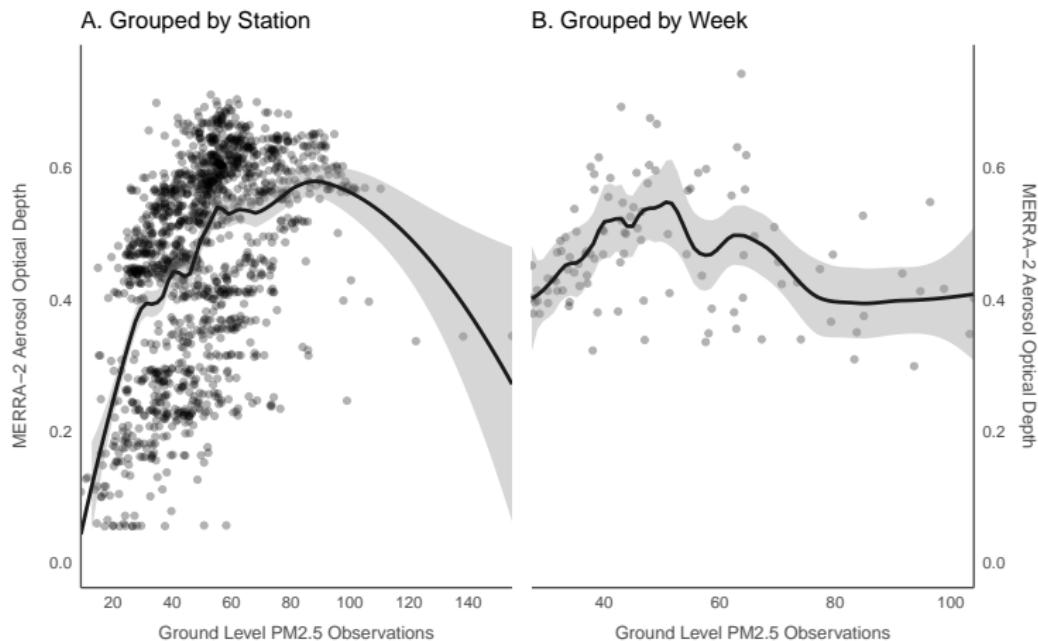
Data
○●○○○○

Empirical Strategy
○○○○○

Results
○○○○○

COLUMN CONCENTRATIONS CAPTURE LITTLE TEMPORAL VARIATION

Figure 3: Aerosol Optical Depth and PM_{2.5} in China, 2015–2016



Motivation
ooo

Testable Hypothesis
o

Policy
oo

Data
oo•ooo

Empirical Strategy
oo

Results
ooooo

DATA: OVERVIEW

- We feed our machine learning model with **satellite data throughout 2005–2016 as features**, train our model on **2015–2016 ground-level observations**, and use it to predict **2005–2016 ground-level concentrations**, when official data were either non-existent (for PM_{2.5}, O₃ and CO) or shown to be subject to human manipulation (for PM₁₀, SO₂ and NO₂).
- We train a different model for every single station amongst about 1500 stations, and drop half of the stations which do not yield satisfactory performance.
- We use **Extreme Gradient Boosting**, which is a variant of Random Forest and a regression-tree-based algorithm. It conducts surrogate splits to do “smart” imputations for observations with missing features.

Motivation
ooo

Testable Hypothesis
o

Policy
oo

Data
oooo•oo

Empirical Strategy
oo

Results
ooooo

DATA: TARGETS AND FEATURES

Table 1: Targets, Features and Data Sources

Targets (2015–2016 for Training, 2014 for Test)	Dataset	Source
Monitoring Station Measurements (PM _{2.5} , PM ₁₀ , NO ₂ , SO ₂ , O ₃ , CO) Reconstructed Air Pollution Index	AQI	Harvard Dataverse
Features (2005–2016)	Dataset	Source
Day of Year		
Aerosol Optical Depth (Aqua and Terra)	MODIS	NASA EarthData
SO ₂ , NO ₂ , O ₃ Column Concentrations	OMI	NASA EarthData
CO, O ₃ and AOD Reanalysis Product	MERRA2	NASA EarthData
Temperature, Relative Humidity, Pressure, Eastward and Northward Wind Speed, Planetary Boundary Layer Height	MERRA2	NASA EarthData

Motivation
○○○Testable Hypothesis
○Policy
○○Data
○○○○●○Empirical Strategy
○○Results
○○○○○

DATA: PERFORMANCE

Table 2: Predictive Performance: Cross Validated Weekly R²

Target Variable	Overall R ²	Station-Specific R ² Percentiles				
		5%	10%	50%	90%	95%
API	0.82	0.38	0.42	0.54	0.68	0.72
PM ₁₀	0.80	0.37	0.40	0.52	0.66	0.70
PM _{2.5}	0.87	0.42	0.46	0.57	0.70	0.73
O ₃	0.92	0.54	0.56	0.69	0.84	0.86
SO ₂	0.86	0.19	0.24	0.48	0.76	0.81
NO ₂	0.85	0.34	0.39	0.56	0.71	0.74
CO	0.92	0.16	0.21	0.43	0.69	0.73

Notes: (i) We use 5-fold cross validation on training data to obtain predicted and true value pairs. (ii) We include only half of all the stations.

Motivation
○○○

Testable Hypothesis
○

Policy
○○

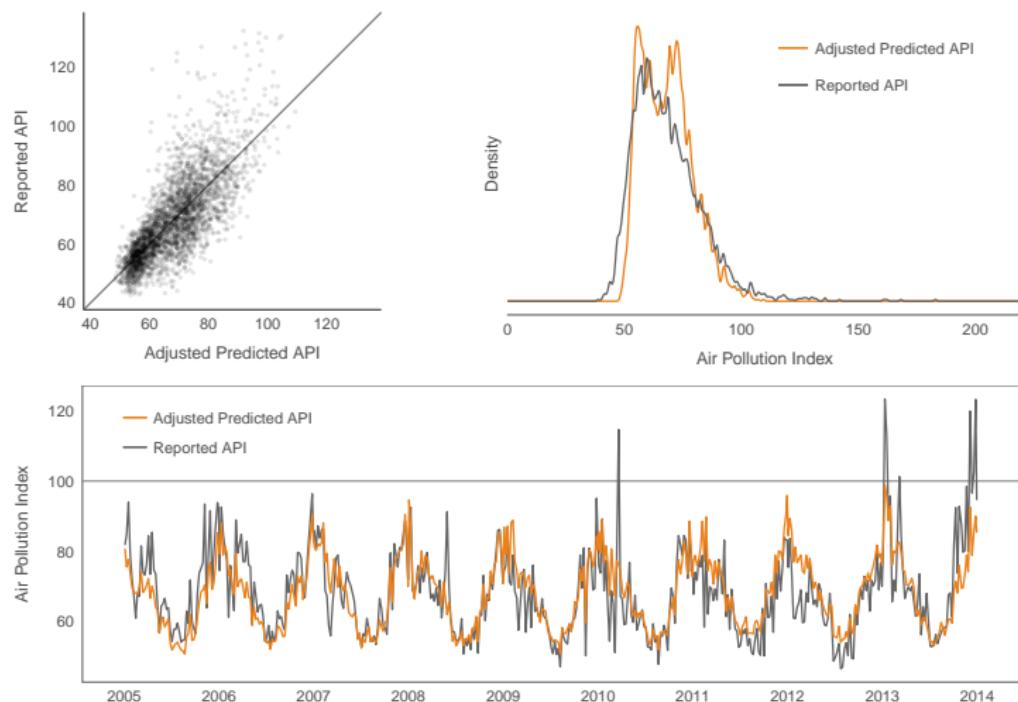
Data
○○○○●

Empirical Strategy
○○

Results
○○○○○

DATA: PERFORMANCE

Figure 4: Comparing Predicted and Reported Air Pollution Index in China



Motivation
○○○

Testable Hypothesis
○

Policy
○○

Data
○○○○○○

Empirical Strategy
●○

Results
○○○○○

EMPIRICAL STRATEGY: EVENT STUDY

$$Y_{iwy} = \alpha_i + \beta_{wy} + \sum_{k \in [-10, 4] \setminus \{-8, -1\}} \tau_k \mathbf{1}\{K_{iwy} = k\} + \epsilon_{iwy} \quad (1)$$

- Each i indicates one monitoring station;
- Each t indicates one week;
- K_{iwy} is the year relative to treatment;
- $Y_{i,t}$ is average weekly air pollution levels;
- $\epsilon_{i,t}$ is clustered at the city level.

Motivation
○○○

Testable Hypothesis
○

Policy
○○

Data
○○○○○

Empirical Strategy
○●

Results
○○○○○

EMPIRICAL STRATEGY: STRUCTURAL BREAK

$$Y_{iwy} = \alpha_{iw} + \beta_y + \tau_j 1\{K_{iwy} \geq j\} + \epsilon_{iwy} \quad (2)$$

- Each i indicates one monitoring station;
- Each w indicates one week, each y indicates one year;
- K_{iwy} is the year relative to treatment;
- $j \in [-8, 2]$ is the placebo or actual treatment time;
- Y_{iwy} is average weekly air pollution levels;
- ϵ_{iwy} is clustered at the city level.

Motivation
○○○

Testable Hypothesis
○

Policy
○○

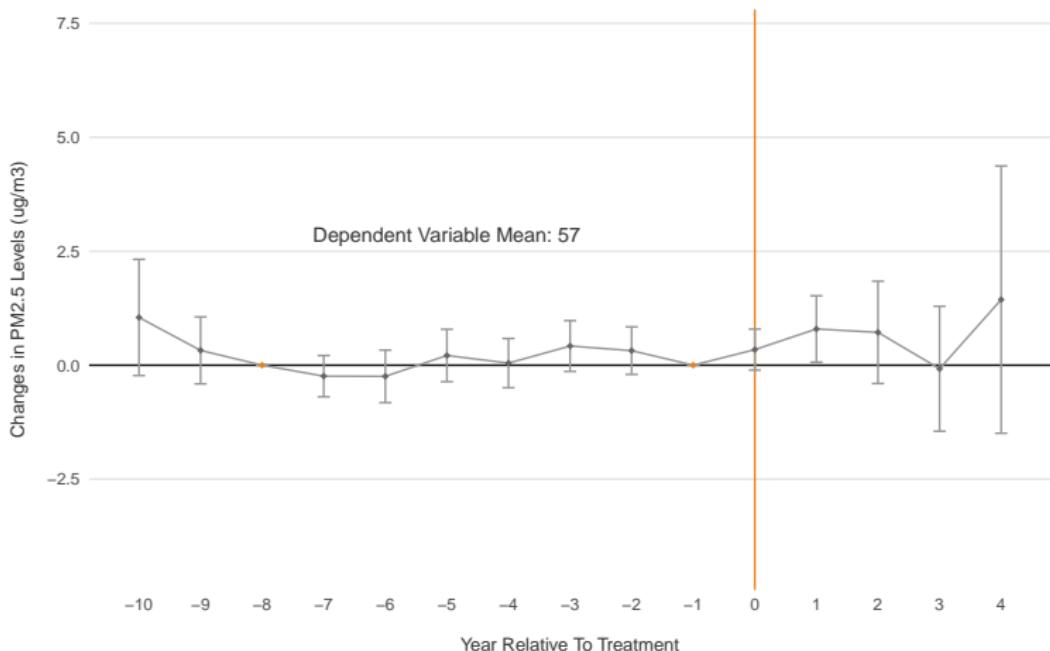
Data
○○○○○

Empirical Strategy
○○

Results
●○○○○

TREATMENT EFFECTS ARE TIGHTLY BOUNDED AROUND ZERO

Figure 5: Event Study Estimates: PM_{2.5} Levels



Motivation
○○○

Testable Hypothesis
○

Policy
○○

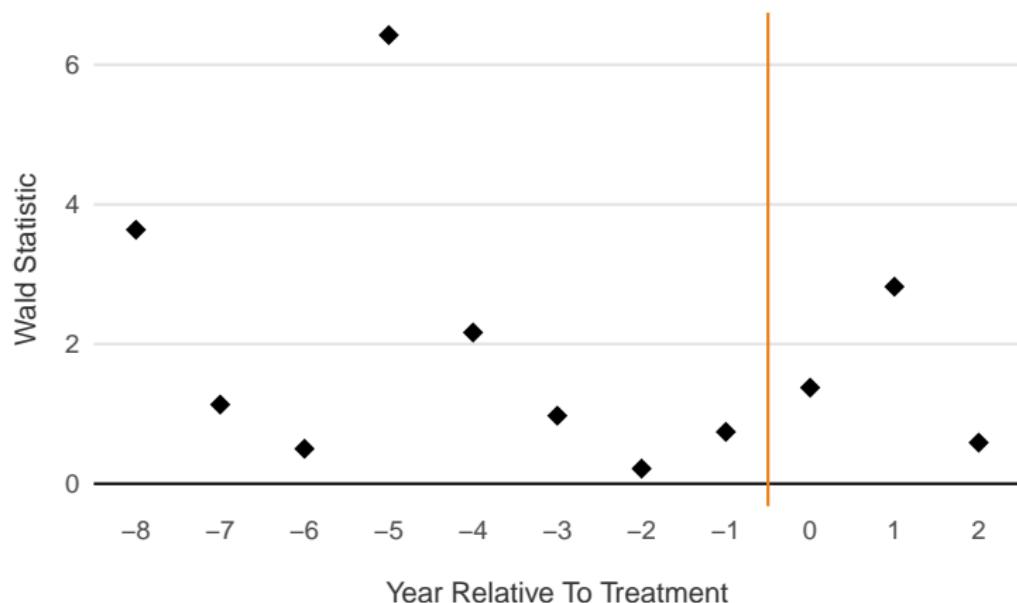
Data
○○○○○

Empirical Strategy
○○

Results
○●○○○

TREATMENT HAS NO EFFECTS ON AIR QUALITY

Figure 6: Structural Break Estimates: Machine Learning Predictions for PM_{2.5}



Motivation
○○○

Testable Hypothesis
○

Policy
○○

Data
○○○○○

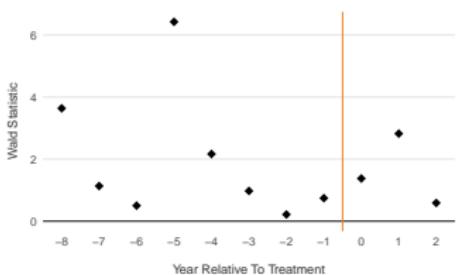
Empirical Strategy
○○

Results
○○●○○

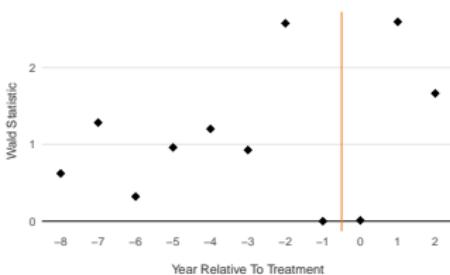
TREATMENT HAS NO EFFECTS ON AIR QUALITY

Figure 7: Structural Break Estimates: Machine Learning Predictions

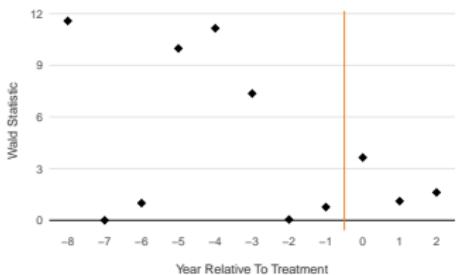
(a) PM_{2.5}



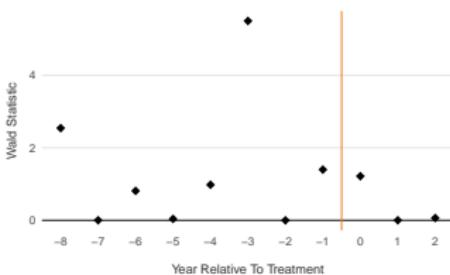
(b) SO₂



(c) NO₂



(d) O₃



Motivation
○○○

Testable Hypothesis
○

Policy
○○

Data
○○○○○

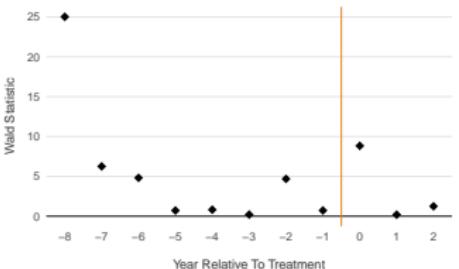
Empirical Strategy
○○

Results
○○○●○

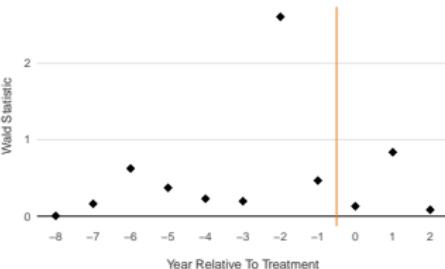
TREATMENT HAS NO EFFECTS ON AIR QUALITY

Figure 9: Structural Break Estimates: Satellite Observations

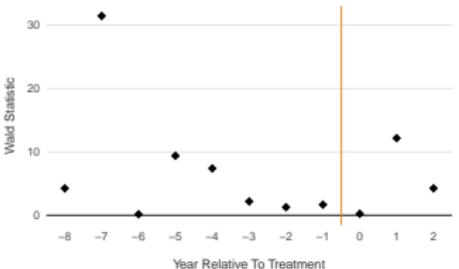
(a) AOD (MERRA2)



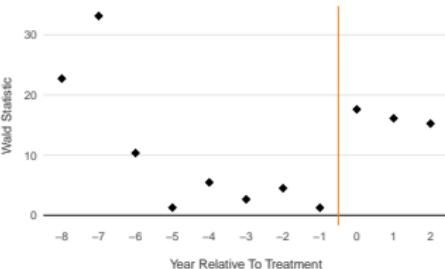
(b) AOD (Terra)



(c) O₃ (Aura)



(d) SO₂ (Aura)



Motivation
○○○

Testable Hypothesis
○

Policy
○○

Data
○○○○○

Empirical Strategy
○○

Results
○○○●

A CONCEPTUAL MODEL TO RECONCILE RESULTS

Local regulators are evaluated with either emissions (which may be mis-reported)

$$\underbrace{b(e + l)}_{\text{benefit of reported emission reduction}} - \underbrace{c(e)}_{\text{cost of effort}} - \underbrace{p(l)}_{\text{punishment for being caught}} \quad (3)$$

or ambient concentrations

$$\underbrace{q(e, \epsilon)}_{(\text{air}) \text{ quality depends on effort but is uncertain}} - \underbrace{c(e)}_{\text{cost of effort}} \quad (4)$$

The relative effectiveness of the two regulations depend on the extent of information asymmetry $p(\cdot)$ and the uncertainty in ambient concentrations ϵ , conditional on emissions.