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Automatic garage door opening system
int trigpin=11;
int echopin=10;
#include<Servo.h>
Servo myservo;
void setup()
  Serial.begin(9600);
  myservo.attach(7);
  pinMode(trigpin,OUTPUT);
  pinMode(echopin,INPUT);
  myservo.write(0);
void loop()
  digitalWrite(trigpin,HIGH);
 delay(1000);
 digitalWrite(trigpin,LOW);
 float duration=pulseIn(echopin,HIGH);
  float distance=duration*0.0343/2;
  Serial.print("The distance is ");
  Serial.println(distance);
  if(distance>80) {
     myservo.write(90);
     Serial.println("The garage door is opened");
     delay(5000);
     myservo.write(0);
     Serial.println("The garage door is closed");
  }
  else {
     myservo.write(0);
  }
}
```