

ASSIGNMENT-2

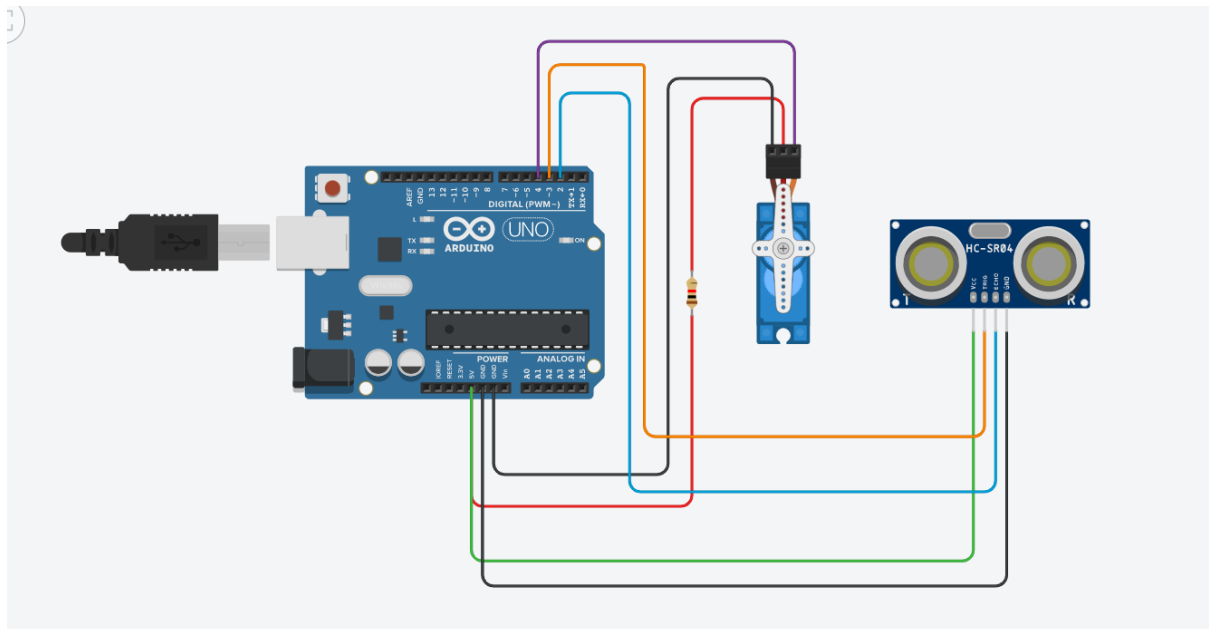
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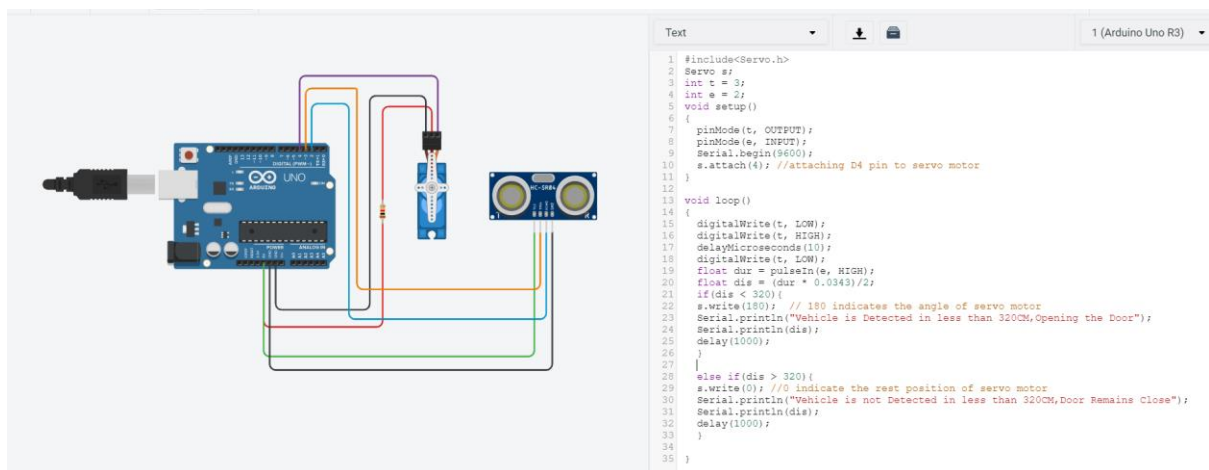
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Develop an "Automatic garage door opening system". Use an Ultrasonic sensor to detect if there is a vehicle in front of the garage. if any vehicle is detected open the garage door (rotate the servo motor) for some time and close it.

Circuit Diagram:



Code:



```

#include<Servo.h>

Servo s;

int t = 3;

int e = 2;

void setup()
{
    pinMode(t, OUTPUT);
    pinMode(e, INPUT);
    Serial.begin(9600);
    s.attach(4); //attaching D4 pin to servo motor
}

void loop()
{
    digitalWrite(t, LOW);
    digitalWrite(t, HIGH);
    delayMicroseconds(10);
    digitalWrite(t, LOW);
    float dur = pulseIn(e, HIGH);
    float dis = (dur * 0.0343)/2;
    if(dis < 320){ // 320CM is maximum distance of the sensor
        s.write(180); // 180 indicates the angle of servo motor
        Serial.println("Vehicle is Detected in less than 320CM,Opening the Door");
        Serial.println(dis);
        delay(1000);
    }

    else if(dis > 320){
        s.write(0); //0 indicate the rest position of servo motor
        Serial.println("Vehicle is not Detected in less than 320CM,Door Remains Close");
        Serial.println(dis);
    }
}

```

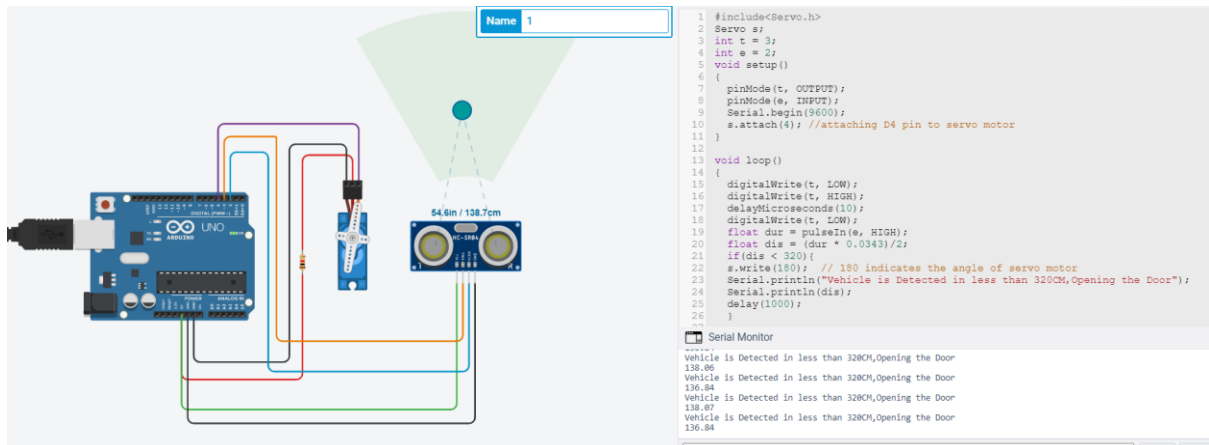
```
delay(1000);
```

```
}
```

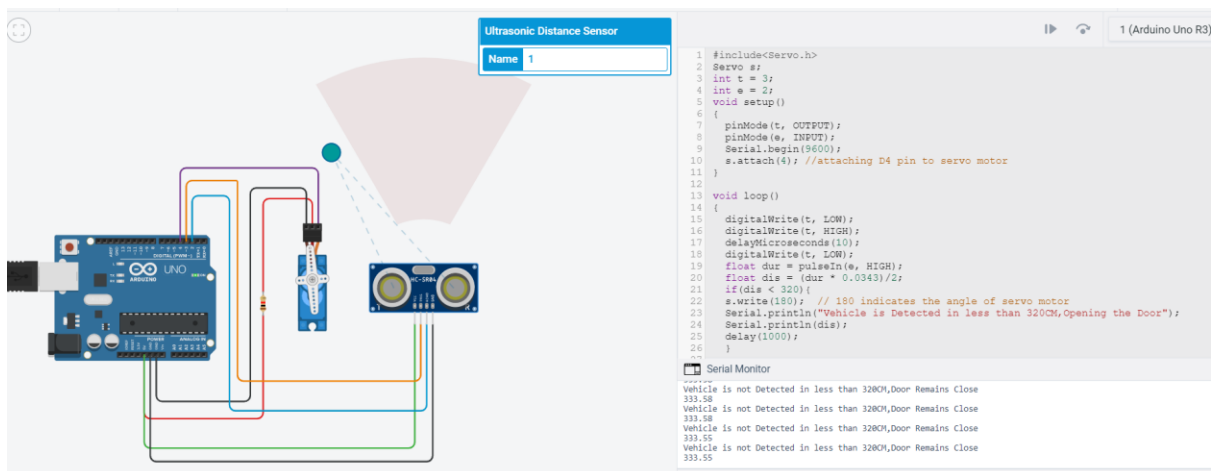
```
}
```

OUTPUT:

When vehicle is in sensor range, then door will open.



When the vehicle is not in sensor range, then door remains close.



Link: <https://www.tinkercad.com/things/jWsKj4tz9dX-fantastic-juttuli/editel>