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Assignment-2:

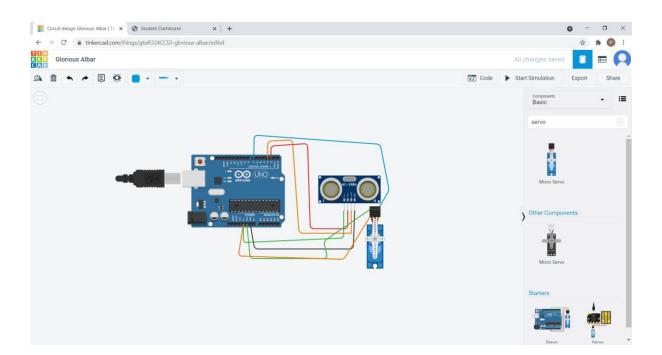
Develop an "Automatic garage door opening system". Use an Ultrasonic sensor to detect if there is a vehicle in front of the garage. if any vehicle is detected open the garage door (rotate the servo motor) for some time and close it.

Software: Thinkercad

```
Code:
#include<Servo.h>
Servo s;
void setup()
{
 s.attach(7);
 pinMode(2, OUTPUT);
 pinMode(3, INPUT);
 Serial.begin(9600);
}
void loop()
{
 digitalWrite(2, LOW);
 digitalWrite(2, HIGH);
 delayMicroseconds(10);
 digitalWrite(2, LOW);
 float dur = pulseln(3, HIGH);
 float dis = (dur * 0.0343)/2;
 Serial.print("Distance in cm: ");
 Serial.println(dis);
 if(dis<100)
 {
   s.write(180);
```

```
delay(1000);
}
else
{
    s.write(0);
    delay(1000);
}
```

Before Simulation:



After simulation:

