

# Assignment 2

# Smart

# Bridge

---

**Name :- Vikas Kumar Nigam**

**SBID:- SB20210142800**

**Question :** Develop an "Automatic garage door opening system". Use an Ultrasonic sensor to detect if there is a vehicle in front of the garage. if any vehicle is detected open the garage door (rotate the servo motor) for some time and close it.

**COMPONENT REQUIRED :-** 1.Ultra sonic Sensor  
2.wires & USB cable .  
3. Arduino uno  
4.Servo Motor

**CODE:-**

```
#include <Servo.h>
```

```
#define trigPin 12

#define echoPin 11

Servo servo;

int sound = 250;

void setup() {

  Serial.begin (9600);

  pinMode(trigPin, OUTPUT);

  pinMode(echoPin, INPUT);

  servo.attach(9);

}

void loop() {

  long duration, distance;

  digitalWrite(trigPin, LOW);

  delayMicroseconds(2);

  digitalWrite(trigPin, HIGH);

  delayMicroseconds(10);

  digitalWrite(trigPin, LOW);

  duration = pulseIn(echoPin, HIGH);

  distance = (duration/2) / 29.1;

  if (distance < 10) {

    Serial.println("the distance is less than 10");

    servo.write(90);

    delay(1500);

  }

  else {

    servo.write(0);

  }

  if (distance > 60 || distance <= 0){

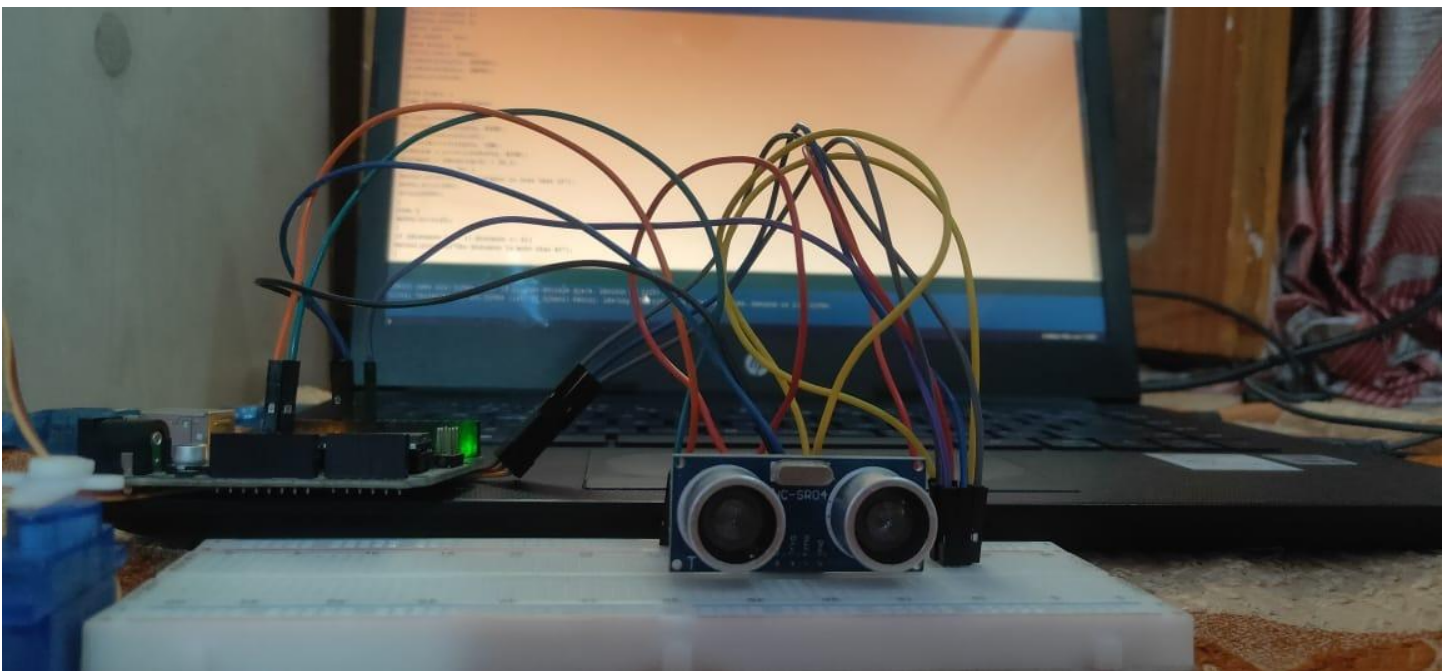
    Serial.println("The distance is more than 60");

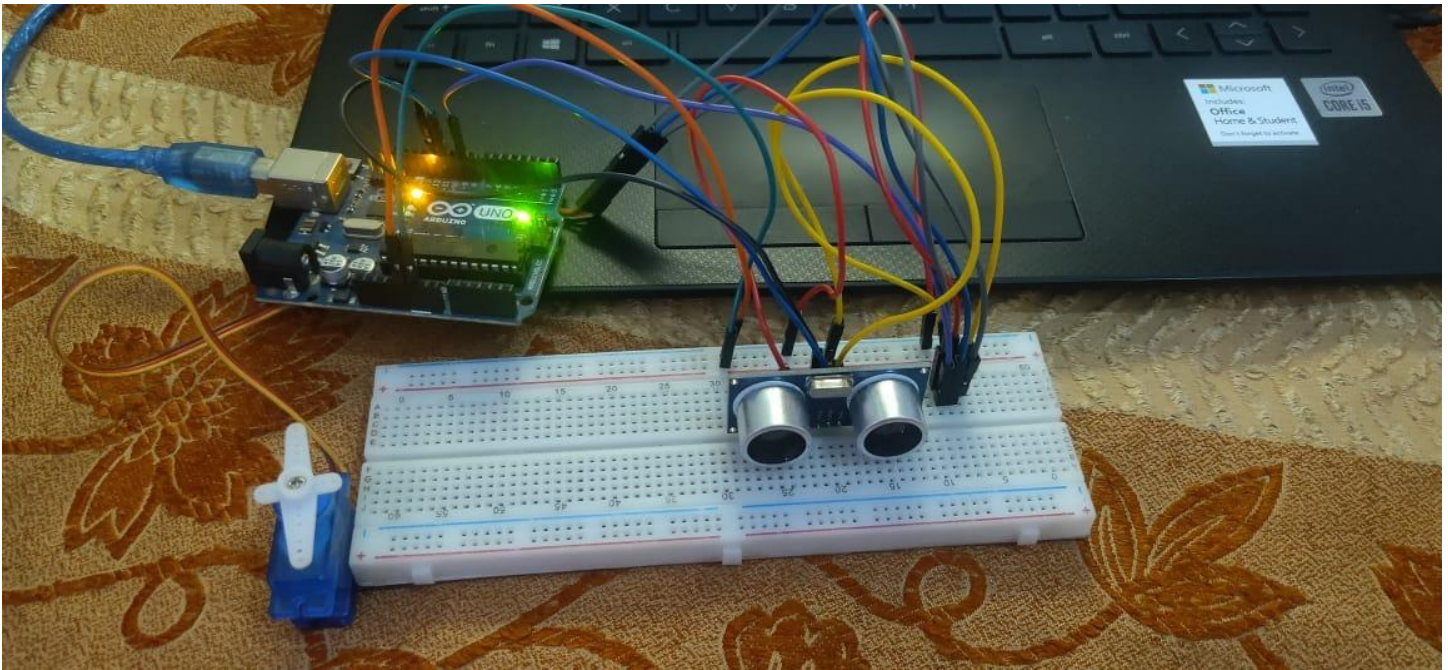
  }

}
```

```
}  
else {  
  Serial.print(distance);  
  Serial.println(" cm");  
}  
delay(500);  
}
```

RESULT:- PERFORMED EXPERNIMENT, IF THE DISTANCE MEASURE IS LESS THAN 10 THE SERVO MOTOR WILL ROTATE 90 DEGREE, WAIT FOR SOME SECOND AND AGAIN ROTATE TO 0 DEGREE.





TINKER  
CAD

Glorious Hillar-Juttuli

All changes saved

Code

Start Simulation

Export

Share

Text

1 (Arduino Uno R3)

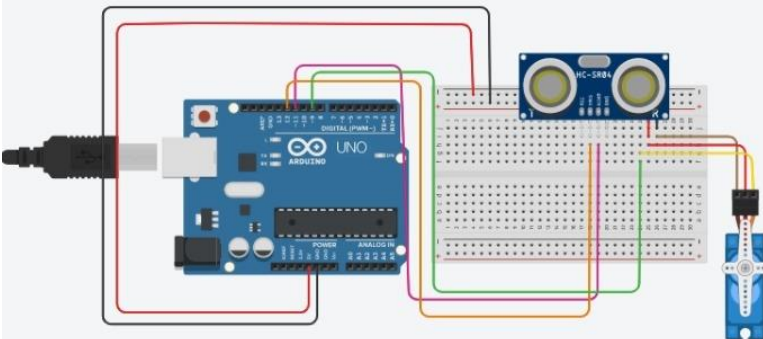
```
1 #include <Servo.h>
2 #define trigPin 12
3 #define echoPin 11
4 Servo servo;
5 int sound = 250;
6 void setup() {
7   Serial.begin(9600);
8   pinMode(trigPin, OUTPUT);
9   pinMode(echoPin, INPUT);
10  servo.attach(9);
11 }
12 void loop() {
13   long duration, distance;
14   digitalWrite(trigPin, LOW);
15   delayMicroseconds(2);
16   digitalWrite(trigPin, HIGH);
17   delayMicroseconds(10);
18   digitalWrite(trigPin, LOW);
19   duration = pulseIn(echoPin, HIGH);
20   distance = (duration/2) / 29.1;
21   if (distance < 10) {
22     Serial.println("The distance is less than 10");
23   }
24   if (distance > 60) {
25     Serial.println("The distance is more than 60");
26   }
27 }
```

Serial Monitor

the distance is less than 10  
The distance is more than 60  
the distance is less than 10  
The distance is more than 60  
the distance is less than 10  
The distance is more than 60

Send

Clear



servo\_with\_ultrasonic\_sensor\$

```
#include <Servo.h>
#define trigPin 12
#define echoPin 11
Servo servo;
int sound = 250;
void setup() {
  Serial.begin(9600);
  pinMode(trigPin, OUTPUT);
  pinMode(echoPin, INPUT);
  servo.attach(9);
}
void loop() {
  long duration, distance;
  digitalWrite(trigPin, LOW);
  delayMicroseconds(2);
  digitalWrite(trigPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigPin, LOW);
  duration = pulseIn(echoPin, HIGH);
  distance = (duration/2) / 29.1;
  if (distance < 10) {
    Serial.println("the distance is less than 10");
    servo.write(90);
    delay(1500);
  }
  else {
    servo.write(0);
  }
  if (distance > 60 || distance <= 0) {
    Serial.println("The distance is more than 60");
  }
}
```

Sketch uses 4248 bytes (13%) of program storage space. Maximum is 32256 bytes.

Global variables use 291 bytes (14%) of dynamic memory, leaving 1757 bytes for local variables. Maximum is 2048 bytes.

```
the distance is less than 10
7 cm
50 cm
25 cm
21 cm
48 cm
11 cm
the distance is less than 10
7 cm
the distance is less than 10
4 cm
the distance is less than 10
2 cm
the distance is less than 10
1 cm
the distance is less than 10
2 cm
the distance is less than 10
2 cm
the distance is less than 10
2 cm
the distance is less than 10
2 cm
the distance is less than 10
1 cm
the distance is less than 10
1 cm
the distance is less than 10
2 cm
the distance is less than 10
1 cm
the distance is less than 10
2 cm
the distance is less than 10
1 cm
36 cm
35 cm
38 cm
41 cm
```

.....