Assignment 2

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void loop()

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Develop an "Automatic garage door opening system". Use an Ultrasonic sensor to detect if there is a vehicle in front of the garage. if any vehicle is detected open the garage door (rotate the servo motor) for some time and close it.

```
AURDINO CODE:

//Garage opens when vehicle is in proximity of 200cm or less to it int t=2; //trigger=t

#define e 3 //echo=e

#include <Servo.h>
Servo s;

void setup()
{

pinMode(2, OUTPUT);

pinMode(3, INPUT);

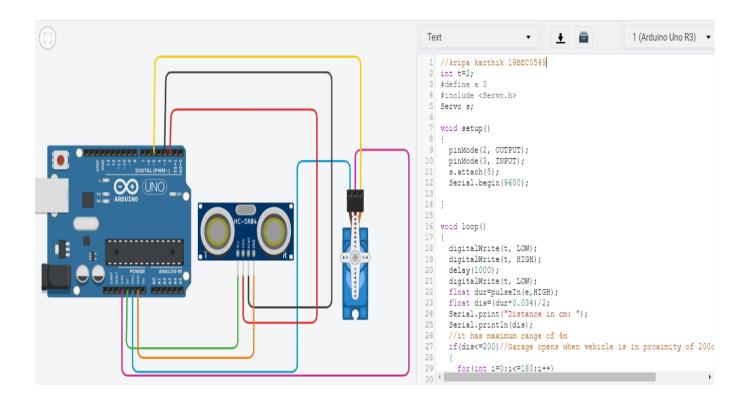
s.attach(5);

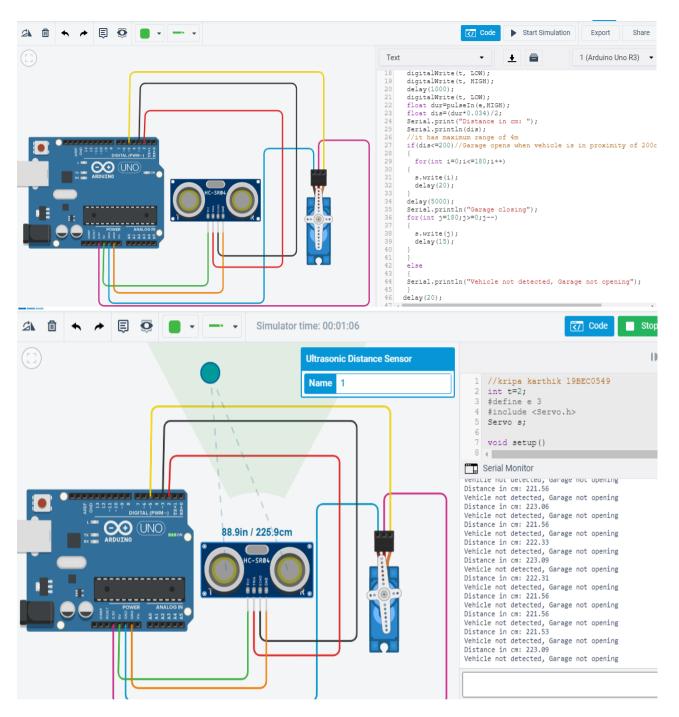
Serial.begin(9600);
}
```

```
{
 digitalWrite(t, LOW);
 digitalWrite(t, HIGH);
 delay(1000);
 digitalWrite(t, LOW);
 float dur=pulseIn(e,HIGH);
 float dis=(dur*0.034)/2;
 Serial.print("Distance in cm: ");
 Serial.println(dis);
 //it has maximum range of 4cm
 if(dis<=200) // Garage opens when vehicle is in proximity of 125cm or less to it
 {
  for(int i=0;i<=180;i++)
  s.write(i);
  delay(20);
 }
 delay(5000);
 Serial.println("Garage closing");
 for(int j=180;j>=0;j--)
 {
  s.write(j);
  delay(15);
 }
 else
```

```
{
   Serial.println("Vehicle not detected, Garage not opening");
}
delay(20);
}
```

SCREENSHOTS





When the object is detected at distance greater than 200 the garage will be closed.

When the object is detected at a distance less than 200 the garage opens and remains open for 5sec as we have given the delay like that and then closes



