## **ASSIGNMENT-2**

Develop an "Automatic garage door opening system". Use an Ultrasonic sensor to detect if there is a vehicle in front of the garage. If any vehicle is detected, open the garage door (rotate the servo motor) for some time and close it.

```
CODE:
#include<Servo.h>
Servo s;
void setup()
pinMode(3, OUTPUT);
pinMode(4, INPUT);
Serial.begin(9600);
s.attach(5);
}
void loop()
digitalWrite(3, LOW);
delayMicroseconds(2);
digitalWrite(3, HIGH);
delayMicroseconds(10);
digitalWrite(3, LOW);
float duration = pulseIn(4, HIGH);
float distance= duration*0.034/2;
Serial.print("Distance: ");
Serial.println(distance);
if (distance<100){
for(int i=0;i<=180;i++){
```

```
s.write(i);
delay(50);}
delay(200);
Serial.print("Open gate!");
for(int j=180;j>=0;j--){
s.write(j);
delay(50);}
delay(200);
}
```

## OUTPUT:



