

a6.py - C:/Users/USER/Desktop/ib iot/a6.py (3.9.6)

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```
import cv2
import datetime

face_classifier=cv2.CascadeClassifier("haarcascade_frontalface_default.xml")
eye_classifier=cv2.CascadeClassifier("haarcascade_eye.xml")
smile_classifier=cv2.CascadeClassifier("haarcascade_smile.xml")
#It will read the first frame/image of the video
video=cv2.VideoCapture(0)

while True:
    #capture the first frame
    check,frame=video.read()
    gray=cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)

    #detect the faces from the video using detectMultiScale function
    faces=face_classifier.detectMultiScale(gray,1.3,5)
    eyes=eye_classifier.detectMultiScale(gray,1.3,5)
    smiles=smile_classifier.detectMultiScale(gray,1.3,5)
    print(faces)

    #drawing rectangle boundaries for the detected face
    for(x,y,w,h) in faces:
        cv2.rectangle(frame, (x,y), (x+w,y+h), (127,0,255), 2)
        cv2.imshow('Face detection', frame)
        cv2.putText(frame, 'Face', (x,y-20),cv2.FONT_HERSHEY_SIMPLEX,0.8, (0,255,0),2)
        picname=datetime.datetime.now().strftime("%y-%m-%d-%H-%M")
        cv2.imwrite(picname+".jpg",frame)

    #drawing rectangle boundaries for the detected eyes
    for(ex,ey,ew,eh) in eyes:
        cv2.rectangle(frame, (ex,ey), (ex+ew,ey+eh), (127,0,255), 2)
        cv2.imshow('Face detection', frame)

    #drawing rectangle boundaries for the detected smile
    for (sx, sy, sw, sh) in smiles:
        cv2.rectangle(frame, (sx,sy), ((sx+sw), (sy+sh)), (0,0,255),2)
        cv2.imshow('Smile detection', frame)
        cv2.putText(frame, 'Smile', (sx,sy-20),cv2.FONT_HERSHEY_SIMPLEX,0.8, (0,255,0),2)

    #waitKey(1)- for every 1 millisecond new frame will be captured
    Key=cv2.waitKey(1)
    if Key==ord('q'):
        #release the camera
        video.release()
        #destroy all windows
        cv2.destroyAllWindows()
```

```

face_classifier=cv2.CascadeClassifier("haarcascade_frontalface_default.xml")
eye_classifier=cv2.CascadeClassifier("haarcascade_eye.xml")
smile_classifier=cv2.CascadeClassifier("haarcascade_smile.xml")
#It will read the first frame/image of the video
video=cv2.VideoCapture(0)

while True:
    #capture the first frame
    check,frame=video.read()
    gray=cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)

    #detect the faces from the video using detectMultiScale function
    faces=face_classifier.detectMultiScale(gray,1.3,5)
    eyes=eye_classifier.detectMultiScale(gray,1.3,5)
    smiles=smile_classifier.detectMultiScale(gray,1.3,5)
    print(faces)

    #drawing rectangle boundaries for the detected face
    for(x,y,w,h) in faces:
        cv2.rectangle(frame, (x,y), (x+w,y+h), (127,0,255), 2)
        cv2.imshow('Face detection', frame)
        cv2.putText(frame, 'Face', (x,y-20),cv2.FONT_HERSHEY_SIMPLEX,0.8, (0,255,0),2)
        picname=datetime.datetime.now().strftime("%y-%m-%d-%H-%M")
        cv2.imwrite(picname+".jpg",frame)

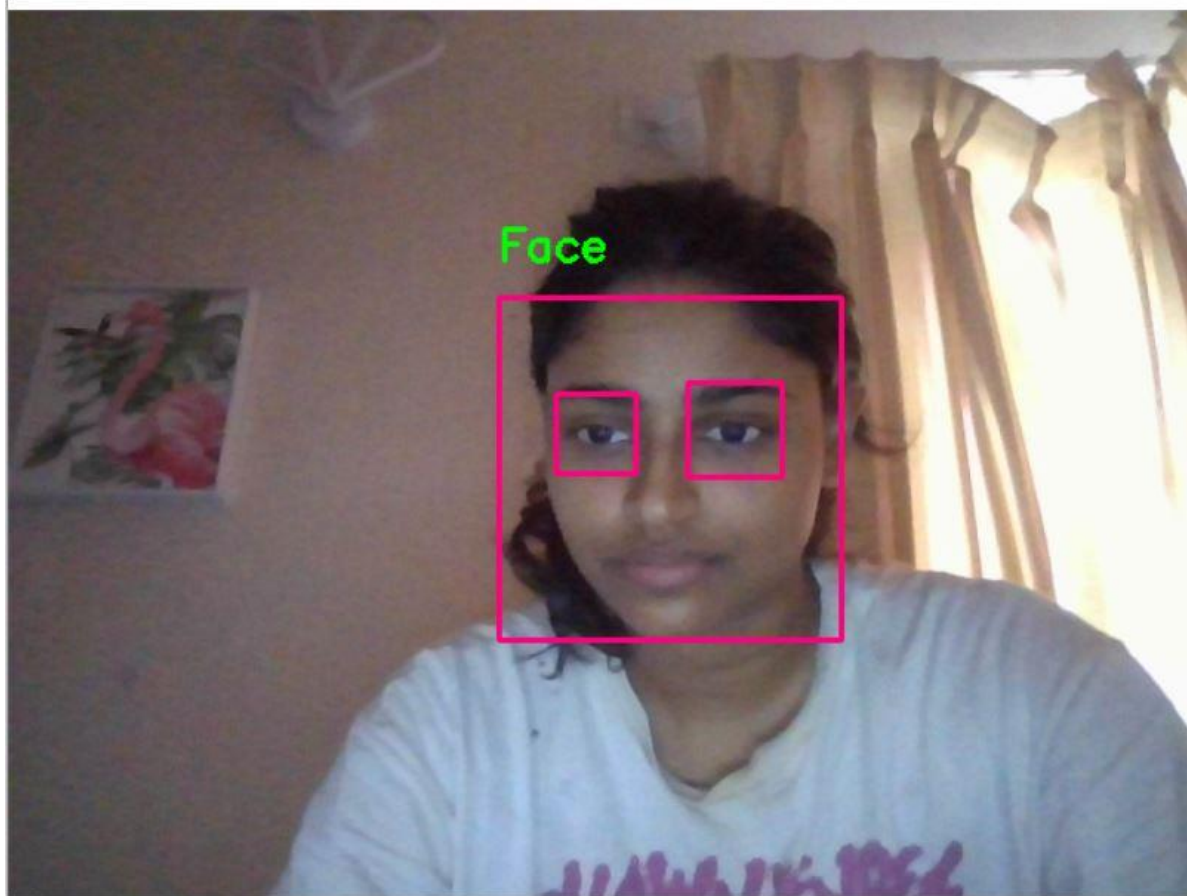
    #drawing rectangle boundaries for the detected eyes
    for(ex,ey,ew,eh) in eyes:
        cv2.rectangle(frame, (ex,ey), (ex+ew,ey+eh), (127,0,255), 2)
        cv2.imshow('Face detection', frame)

    #drawing rectangle boundaries for the detected smile
    for (sx, sy, sw, sh) in smiles:
        cv2.rectangle(frame, (sx,sy), ((sx+sw), (sy+sh)), (0,0,255),2)
        cv2.imshow('Smile detection', frame)
        cv2.putText(frame, 'Smile', (sx,sy-20),cv2.FONT_HERSHEY_SIMPLEX,0.8, (0,255,0),2)

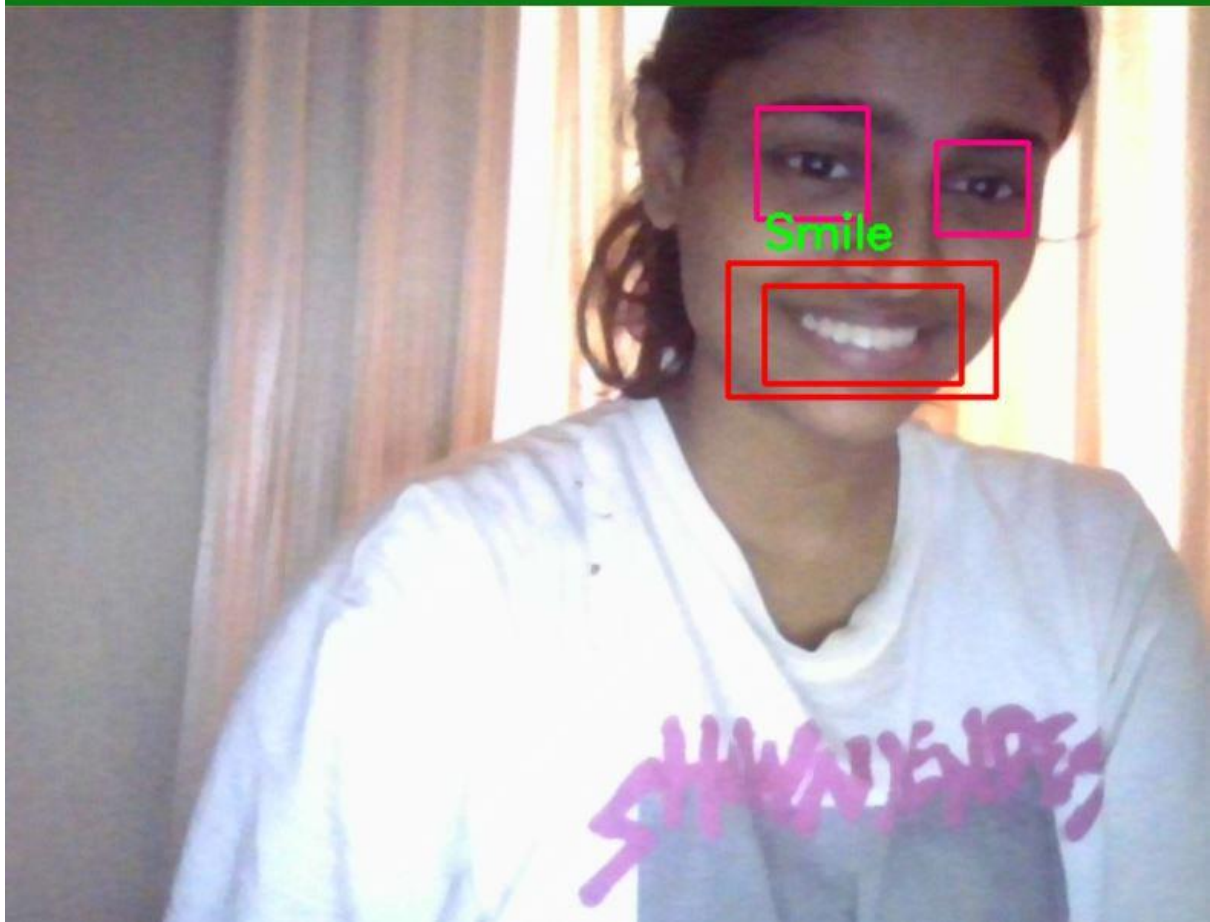
    #waitKey(1)- for every 1 millisecond new frame will be captured
    Key=cv2.waitKey(1)
    if Key==ord('q'):
        #release the camera
        video.release()
        #destroy all windows
        cv2.destroyAllWindows()
        break

```

Face detection



Smile detection



CAT

a62.py - C:/Users/USER/Desktop/ib iot/a62.py (3.9.6)

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```
import cv2
#Read video file from the folder by giving its path
video = cv2.VideoCapture(r'C:\Users\USER\Desktop\ib iot\new.mp4')
face_cascade = cv2.CascadeClassifier('haarcascade_frontalcatface.xml')

while True:
    ret, img = video.read()
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
    faces = face_cascade.detectMultiScale(gray, 1.3, 5)
    print(faces)

    for (x,y,w,h) in faces:
        # To draw a rectangle in a face
        cv2.rectangle(img, (x,y), (x+w,y+h), (0,0,255), 2)
        roi_gray = gray[y:y+h, x:x+w]
        roi_color = img[y:y+h, x:x+w]
        cv2.imshow('Cat', img)

    k = cv2.waitKey(30) & 0xff
    if k == 27:
        break

video.release()
cv2.destroyAllWindows()
```

IDLE Shell 3.9.6

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```

Ln: 247 Col: 4

