ASSIGNMENT - 6

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Assignment-6:

Develop a python code to detect any object using Haar cascade classifier.

Python Code:

```
import cv2
# capture frames from a video
cap = cv2.VideoCapture( 'cars.mp4')
# Trained XML classifiers describes some features of some object we want to detect
car cascade = cv2.CascadeClassifier('cars.xml')
# loop runs if capturing has been initialized.
while True:
    # reads frames from a video
   ret, frames = cap.read()
    # convert to gray scale of each frames
   gray = cv2.cvtColor(frames, cv2.COLOR BGR2GRAY)
    # Detects cars of different sizes in the input image
   cars = car cascade.detectMultiScale( gray, 1.1, 1)
    # To draw a rectangle in each cars
   for (x,y,w,h) in cars:
       cv2.rectangle(frames, (x,y), (x+w,y+h), (0,0,255), 2)
       font = cv2.FONT_HERSHEY_DUPLEX
       cv2.putText(frames, 'Car', (x + 6, y - 6), font, 0.5, (0, 0, 255), 1)
       # Display frames in a window
       cv2.imshow('Car Detection', frames)
        #waitKey(1) - for every 1 millisecond new frame will be captured
       Kev=cv2.waitKev(1)
        if Key==ord('q'):
            #release the camera
           cap.release()
           #destroy all windows
           cv2.destroyAllWindows()
           break
```

```
import cv2 import
numpy as np

# Create our body classifier body_classifier =
cv2.CascadeClassifier('haarcascade_fullbody.xml')
# Initiate video capture for video file cap
= cv2.VideoCapture('cars.mp4') # Loop
```

```
once video is successfully loaded while
cap.isOpened():
  # Read first frame
  ret, frame = cap.read()
        #frame = cv2.resize(frame, None,fx=0.5, fy=0.5, interpolation =
cv2.INTER_LINEAR)
  gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
  # Pass frame to our body classifier bodies =
  body_classifier.detectMultiScale(gray, 1.2, 3)
  # Extract bounding boxes for any bodies identified
  for (x,y,w,h) in bodies:
    cv2.rectangle(frame, (x, y), (x+w, y+h), (0, 255, 255), 2) cv2.imshow('car
    detection', frame) cv2.putText(frame, 'cars', (x,y-10),
cv2.FONT_HERSHEY_SIMPLEX, 1, (255,0,0), 4)
  #waitKey(1)- for every 1 millisecond new frame will be
  captured Key=cv2.waitKey(1) if Key==ord('q'): #release the
  camera cap.release() #destroy allwindows
  cv2.destroyAllWindows() break
```

OUTPUT:

