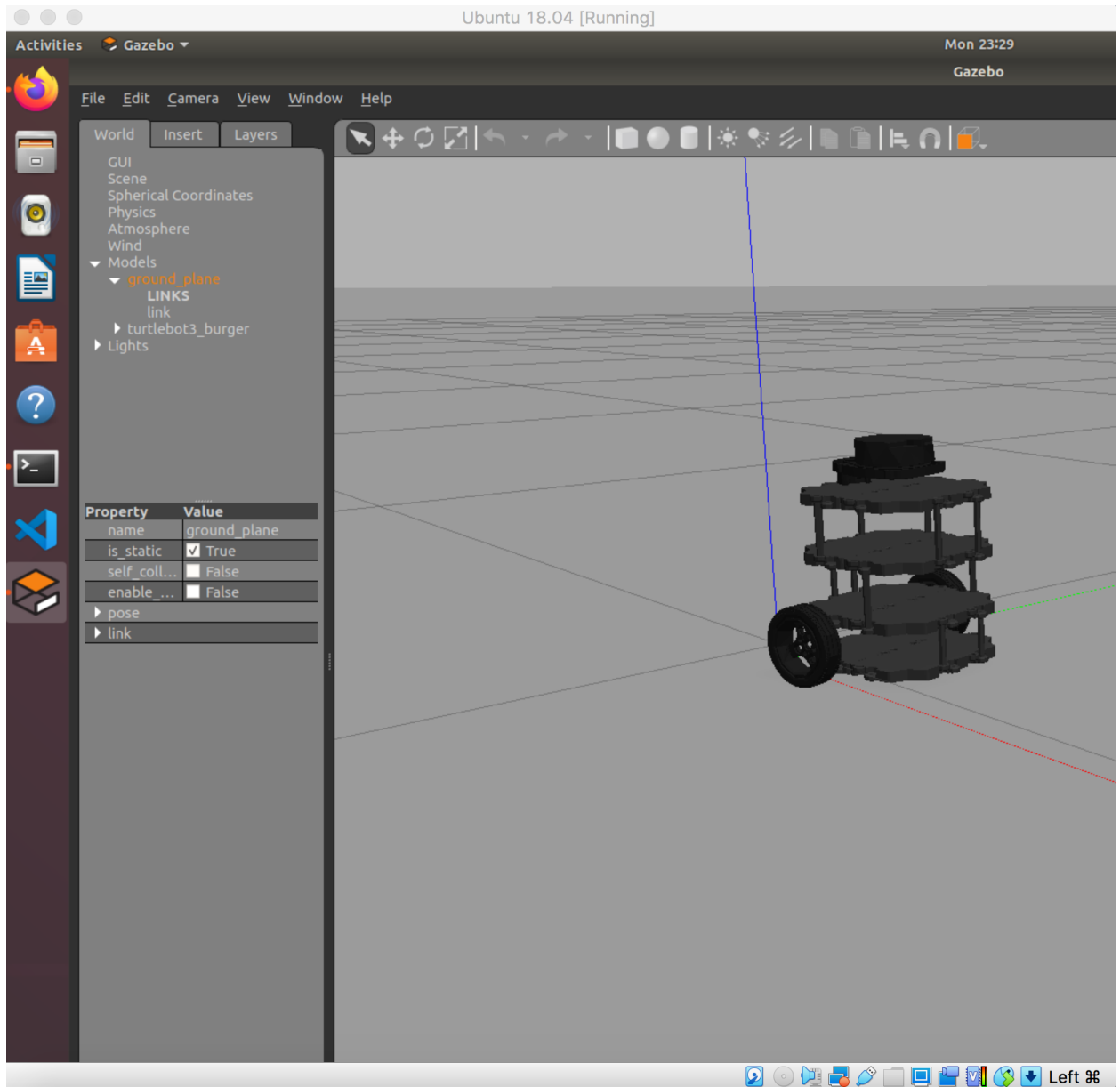


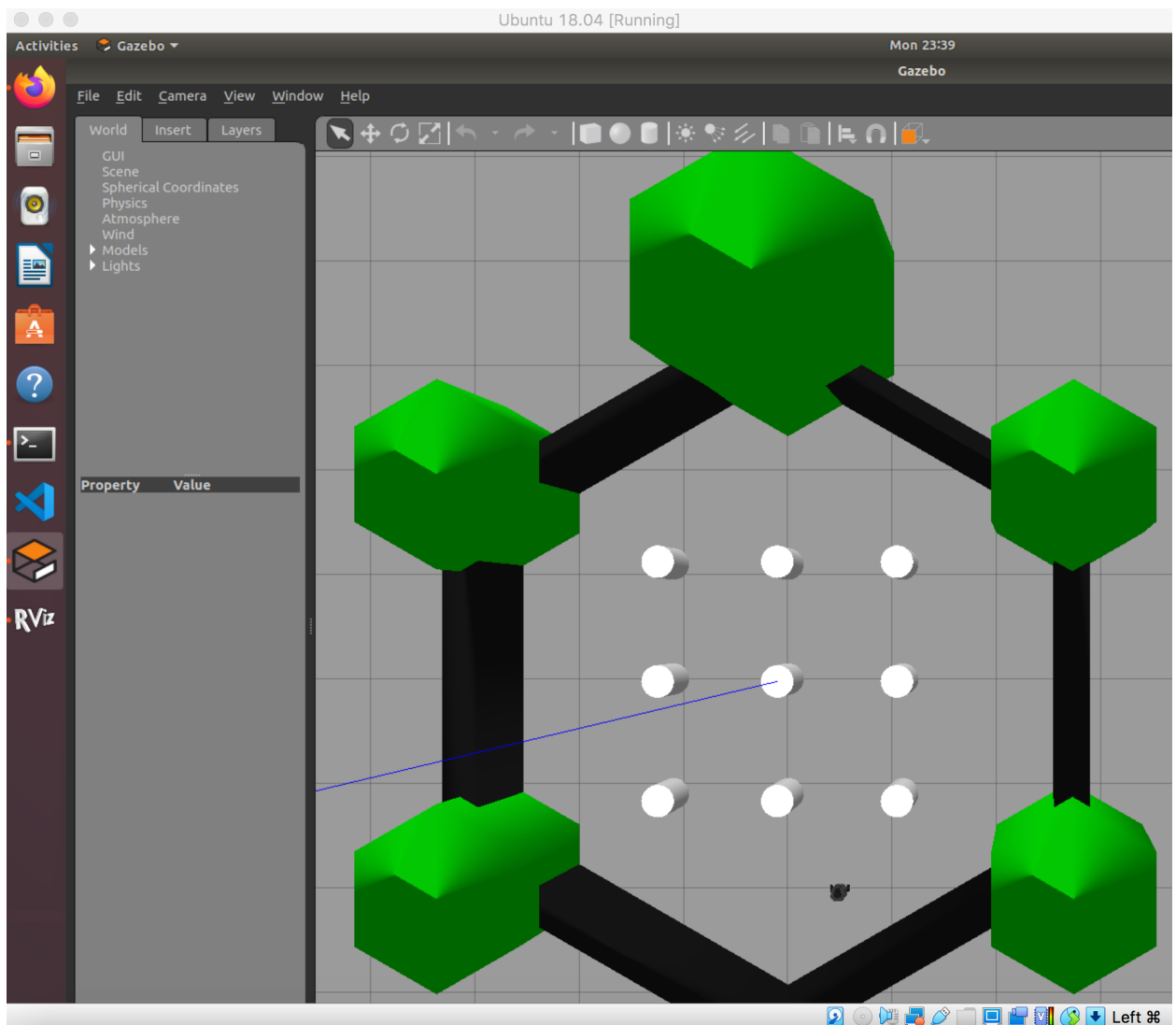
Name: Shalini Das

Robot Simulation Environment and Perform Build navigation applications using Turtlebot3 Burger

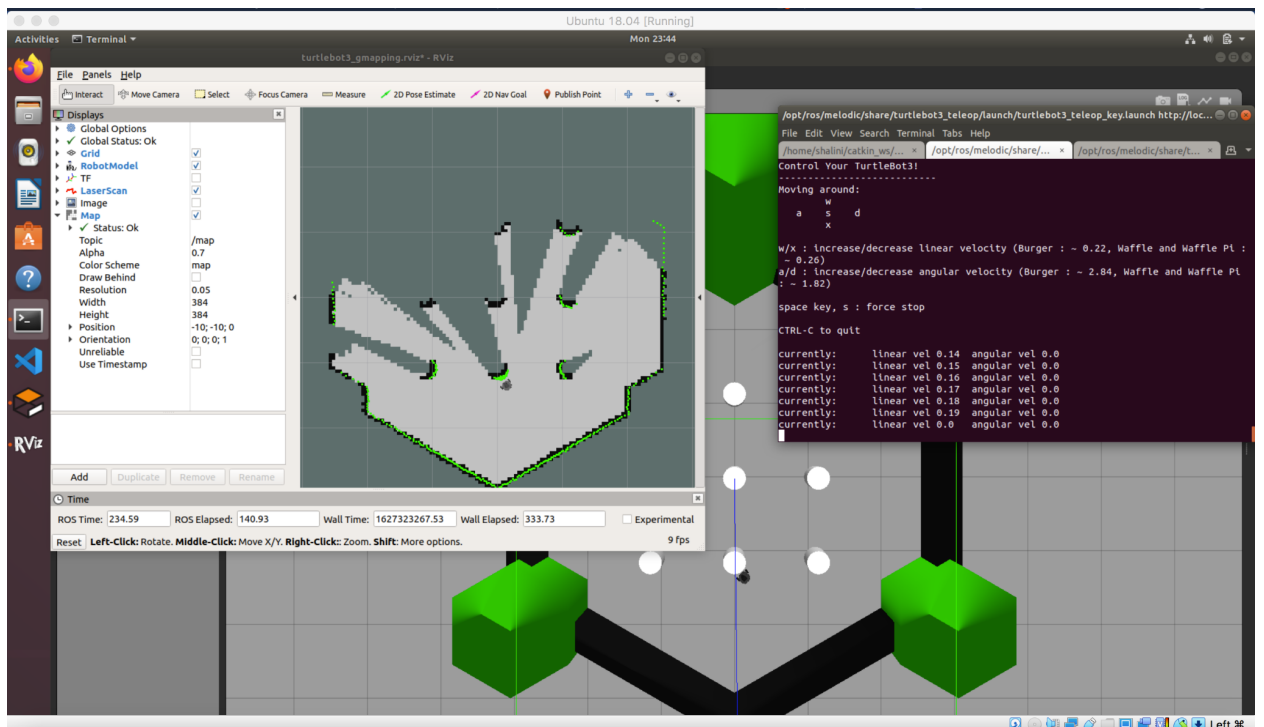
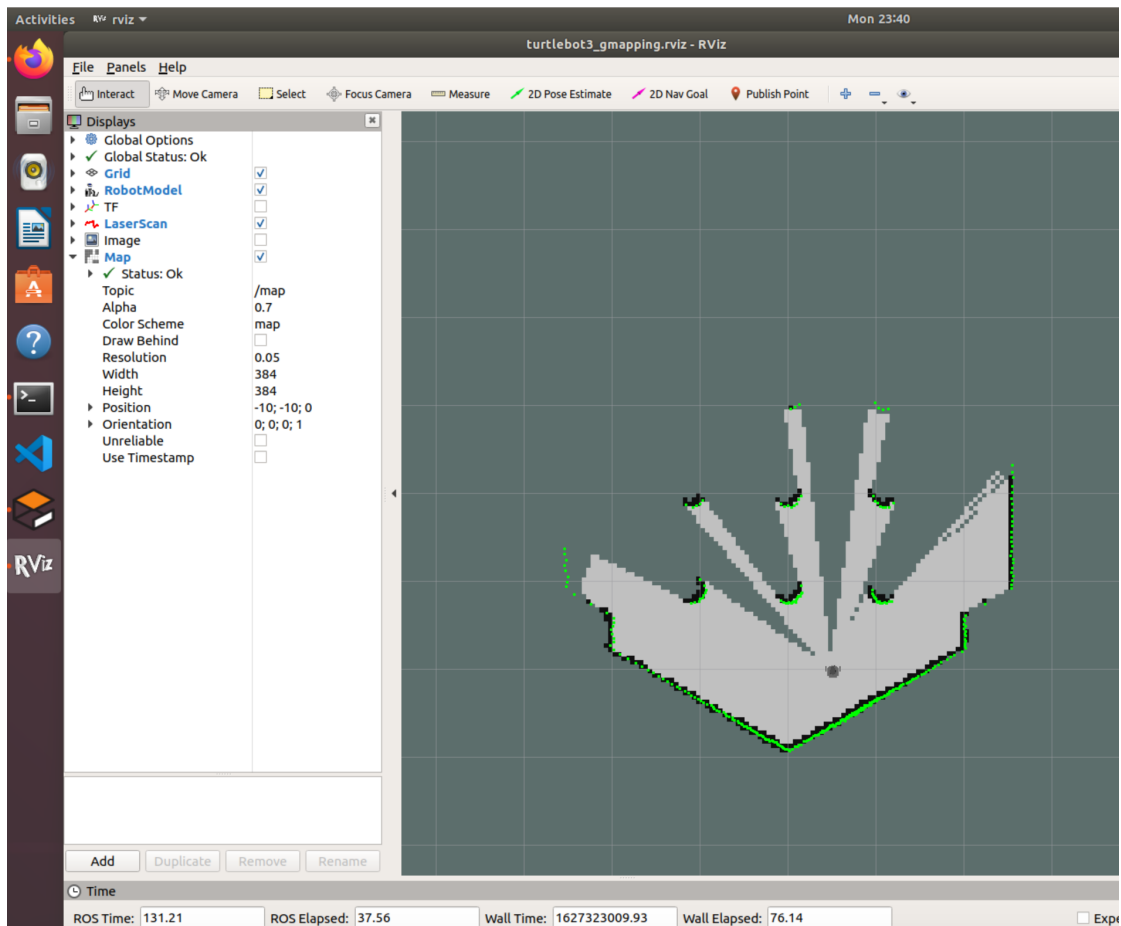
1. We download a turtlebot burger and run it in the gazebo simulator.



2. Opening turtlebot world in gazebo simulator.



3. Visualizing it in rviz.



4. Visualizing navigation mapping in rviz.

