

Robotics- ROS Assignment 6

Name: Shrirang Alias Samarth Patil

University: Vellore Institute of Technology, Bhopal

Contact No.: 8999171921

Email ID: shrirang.alias2019@vitbhopal.ac.in

Build the 4 wheeled Robot using ROS URDF and Xacro methods.

Adding two more wheels to 2 wheeled robot and changing its x position such that it aligns properly like a 4 wheeled robot.

