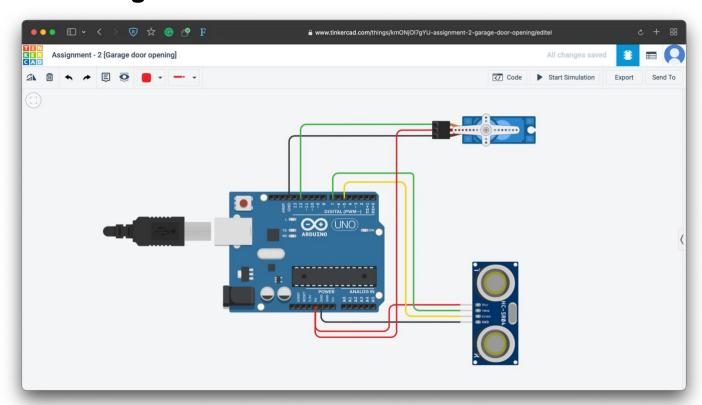
## **Assignment – 2**

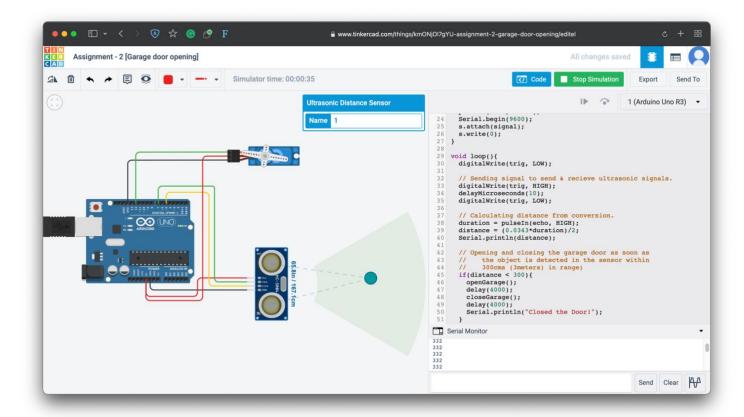
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**Application ID**: SPS\_APL\_20210013738

**Q.** Develop an "Automatic garage door opening system". Use an Ultrasonic sensor to detect if there is a vehicle in front of the garage. if any vehicle is detected open the garage door (rotate the servo motor) for some time and close it.

## **Circuit Diagram:**





## Code:

```
// Code to open Garage-door using servo motor,
// when the object is detected by ultrasonic sensor.
#include<Servo.h>

Servo s;
int trig = 7;
int echo = 5;
int signal = 12;
int duration, distance; // Distance in cms.

void openGarage(){
    // To Open the Garage Door.
    s.write(180);
}

void closeGarage(){
    // To close the Garage Door.
    s.write(0);
}
```

```
void setup(){
 pinMode(trig, OUTPUT);
 pinMode(echo, INPUT);
 Serial.begin(9600);
 s.attach(signal);
 s.write(0);
void loop(){
 digitalWrite(trig, LOW);
 // Sending signal to send & recieve ultrasonic signals.
 digitalWrite(trig, HIGH);
 delayMicroseconds(10);
 digitalWrite(trig, LOW);
 // Calculating distance from conversion.
 duration = pulseIn(echo, HIGH);
 distance = (0.0343*duration)/2;
 Serial.println(distance);
 // Opening and closing the garage door as soon as
     the object is detected in the sensor within
     300cms (3meters) in range)
 if(distance < 300){
  openGarage();
  delay(4000);
  closeGarage();
  delay(4000);
  Serial.println("Closed the Door!");
```