

Max Shi MA227 Exam 3  
Section A.

I declare here that  
I have abided by the  
Stevens Honor System.

1. (a)  $S_1: S(\theta, z) = \langle \cos \theta, \sin \theta, z \rangle$   $0 \leq \theta \leq 2\pi, 0 \leq z \leq 2$

$S_\theta = \langle -\sin \theta, \cos \theta, 0 \rangle$   
 $S_z = \langle 0, 0, 1 \rangle$   
 $S_\theta \times S_z = \langle \cos \theta, \sin \theta, 0 \rangle$   
 at  $\theta = 0, = \langle 1, 0, 0 \rangle$   
 outward  $\checkmark$ .

$P(S) = \langle 2\cos \theta, 2\sin \theta, 2 \rangle$

$P(S) \cdot (S_\theta \times S_z) = 2\cos^2 \theta + 2\sin^2 \theta = 2$ .

$\int_0^2 \int_0^{2\pi} 2 d\theta dz = 2 \cdot 2\pi \cdot 2 = 8\pi = \iint_{S_1} \vec{F} \cdot d\vec{S}$

$S_2: S(\theta, r) = \langle r\cos \theta, r\sin \theta, 2 \rangle, 0 \leq \theta \leq 2\pi, 0 \leq r \leq 1$

$S_\theta = \langle -r\sin \theta, r\cos \theta, 0 \rangle$   
 $S_r = \langle \cos \theta, \sin \theta, 0 \rangle$   
 $S_\theta \times S_r = \langle 0, 0, -r\sin^2 \theta - r\cos^2 \theta \rangle$   
 positive oriented so  
 $S_\theta \times S_r = \langle 0, 0, r \rangle$

$P(S) = \langle 2r\cos \theta, 2r\sin \theta, 0 \rangle$

$P(S) \cdot (S_\theta \times S_r) = 0 \Rightarrow \iint_{S_2} \vec{F} \cdot d\vec{S} = 0$

$S_3: S(\theta, r) = \langle r\cos \theta, r\sin \theta, 0 \rangle, 0 \leq \theta \leq 2\pi, 0 \leq r \leq 1$

$S_\theta = \langle -r\sin \theta, r\cos \theta, 0 \rangle$   
 $S_r = \langle \cos \theta, \sin \theta, 0 \rangle$   
 $S_\theta \times S_r = \langle 0, 0, -r \rangle$   
 outward orientation = down  $\checkmark$ .

$P(S) = \langle 2r\cos \theta, 2r\sin \theta, -2 \rangle$

$P(S) \cdot (S_\theta \times S_r) = 2r$ .

$\int_0^{2\pi} \int_0^1 2r dr d\theta = \int_0^{2\pi} [r^2]_0^1 d\theta = \int_0^{2\pi} 1 d\theta = 2\pi = \iint_{S_3} \vec{F} \cdot d\vec{S}$

$\iint_S \vec{F} \cdot d\vec{S} = \iint_{S_1} \vec{F} \cdot d\vec{S} + \iint_{S_2} \vec{F} \cdot d\vec{S} + \iint_{S_3} \vec{F} \cdot d\vec{S} = 8\pi + 0 + 2\pi = 10\pi$



$$\textcircled{b) \quad} \text{div } F = \frac{\partial}{\partial x}(2x) + \frac{\partial}{\partial y}(2y) + \frac{\partial}{\partial z}(2z) \\ = 2 + 2 + 2 \\ = 6$$

$$\begin{aligned} E: \quad 0 \leq \theta \leq 2\pi \\ 0 \leq r \leq 1 \\ 0 \leq z \leq 2 \end{aligned} \Rightarrow \int_0^{2\pi} \int_0^1 \int_0^2 5r \, dz \, dr \, d\theta \\ = \int_0^{2\pi} \int_0^1 5r [z]_0^2 \, dr \, d\theta = \int_0^{2\pi} \int_0^1 10r \, dr \, d\theta \\ = \int_0^{2\pi} [5r^2]_0^1 \, d\theta = 5 \int_0^{2\pi} d\theta = \boxed{10\pi}$$

$$\textcircled{c) \quad} \boxed{10\pi = 10\pi}$$

The answers should be the same by the Divergence Theorem.

$$\begin{aligned} 2. (a) \quad \text{curl } F = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y & z+x & \sin(z^3)+x^2 \end{vmatrix} = \left( \frac{\partial}{\partial y}(\sin(z^3)+x^2) - \frac{\partial}{\partial z}(z+x) \right) \mathbf{i} - \\ \left( \frac{\partial}{\partial x}(\sin(z^3)+x^2) - \frac{\partial}{\partial z}(-y) \right) \mathbf{j} + \\ \left( \frac{\partial}{\partial x}(z+x) - \frac{\partial}{\partial y}(-y) \right) \mathbf{k} \\ = (0-1)\mathbf{i} - (2x-0)\mathbf{j} + (1-(-1))\mathbf{k} \\ = -\mathbf{i} - 2x\mathbf{j} + 2\mathbf{k} \end{aligned}$$

$$\text{curl } F = -1\mathbf{i} - 2x\mathbf{j} + 2\mathbf{k} = \boxed{\langle -1, -2x, 2 \rangle}$$

$$\textcircled{b) \quad} \oint_C F \cdot dr = \iint_S \text{curl } F \cdot ds$$

$$S(x, y) = \langle x, y, 2-x \rangle, \quad 0 \leq x \leq 2, \quad 0 \leq y \leq 2$$

$$\begin{aligned} S_x &= \langle 1, 0, -1 \rangle \\ S_y &= \langle 0, 1, 0 \rangle \end{aligned} \Rightarrow S_x \times S_y = \langle 1, 0, 1 \rangle$$

positively oriented!

$$\text{curl } F(S) \cdot (S_x \times S_y) = \langle -1, -2x, 2 \rangle \cdot \langle 1, 0, 1 \rangle = -1 + 0 + 2 = 1$$

$$\int_0^2 \int_0^2 1 \, dx \, dy = \int_0^2 \int_0^2 dx \, dy = 2 \cdot 2 = \boxed{4}$$

$$3(a) A = \begin{bmatrix} 2 & 3 \\ 5 & 8 \end{bmatrix}$$

$$A^{-1} = \frac{1}{\det A} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \quad \det A = 16 - 15 = 1$$

$$A^{-1} = \frac{1}{1} \begin{bmatrix} 8 & -3 \\ -5 & 2 \end{bmatrix} = \begin{bmatrix} 8 & -3 \\ -5 & 2 \end{bmatrix}$$

$$\text{check: } \begin{bmatrix} 2 & 3 \\ 5 & 8 \end{bmatrix} \begin{bmatrix} 8 & -3 \\ -5 & 2 \end{bmatrix} = \begin{bmatrix} 16-15 & -6+6 \\ 40-15 & -10+16 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$(b) A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \Rightarrow A^{-1} A \begin{pmatrix} x \\ y \end{pmatrix} = A^{-1} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 8 & -3 \\ -5 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 8-6 \\ -5+4 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$$\boxed{x=2, y=-1.}$$

$$4. \begin{cases} x+y+3z=1 \\ 2x+y+4z=-3 \\ 3x+0y+2z=-14 \end{cases} \Rightarrow \begin{bmatrix} 1 & 1 & 3 & 1 \\ 2 & 1 & 4 & -3 \\ 3 & 0 & 2 & -14 \end{bmatrix} \begin{matrix} r_2-2r_1 \\ r_3-3r_1 \end{matrix}$$

$$\begin{bmatrix} 1 & 1 & 3 & 1 \\ 0 & -1 & -2 & -5 \\ 0 & -3 & -7 & -17 \end{bmatrix} \begin{matrix} -1 \cdot r_2 \\ +1 \cdot r_3 \end{matrix} \Rightarrow \begin{bmatrix} 1 & 1 & 3 & 1 \\ 0 & 1 & 2 & 5 \\ 0 & 3 & 7 & 17 \end{bmatrix} \begin{matrix} \\ \\ r_3-3r_2 \end{matrix} \Rightarrow \begin{bmatrix} 1 & 1 & 3 & 1 \\ 0 & 1 & 2 & 5 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

$$\Rightarrow \begin{cases} x+y+3z=1 \\ y+2z=5 \\ z=2 \end{cases} \Rightarrow \begin{cases} x+y+3(2)=1 \\ y+2(2)=5 \\ z=2 \end{cases} \Rightarrow \begin{cases} x+y+6=1 \\ y+4=5 \\ z=2 \end{cases} \Rightarrow \begin{cases} x+y=-5 \\ y=1 \\ z=2 \end{cases}$$

$$\boxed{x=-6, y=1, z=2}$$