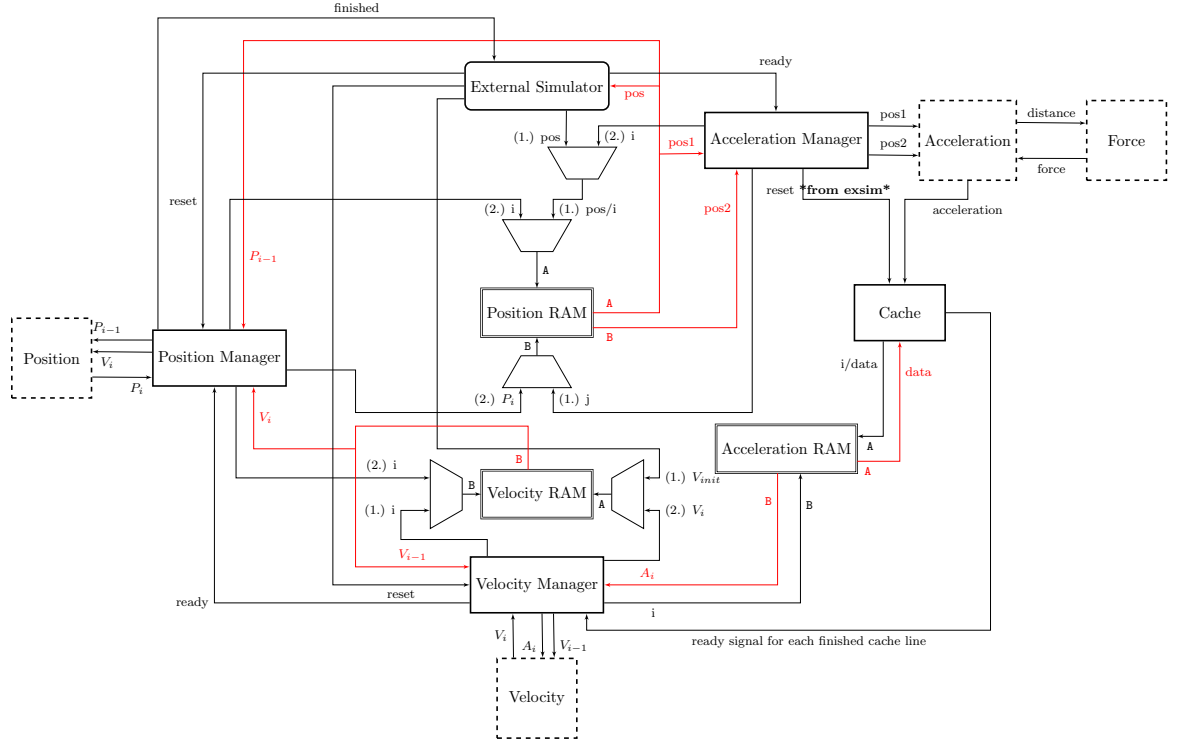Figure 1: Velocity-(/Position)-update module 1.1

Figure 2: Full LJ circuit

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