## Homework nr. 4

Let n be the system's size,  $\epsilon$  - the computation error,  $A \in \mathbb{R}^{n \times n}$  - a real squared matrix,  $k_{max}$  - the maximum number of computing steps.

- 1. Using all the iterative methods described below, approximate the inverse of matrix A. Use formula (5), (6) for choosing the initial matrix  $V_0$ .
- 2. For each method, at the end of the algorithm display the number of computed steps. If the method converged, display the norm:

$$|||A * A_{\text{approx}}^{-1} - I_n||_1.$$

3. Consider the matrix:

$$A = \begin{pmatrix} 1 & 2 & 0 & \cdots & 0 \\ 0 & 1 & 2 & \cdots & 0 \\ \vdots & & & & \\ 0 & 0 & 0 & \cdots & 2 \\ 0 & 0 & 0 & \cdots & 1 \end{pmatrix}$$

Deduce inductively the general form of the inverse of matrix A, by successively running your program using different values for n,the size of the matrix A. Denote by  $A_{\rm exact^{-1}}$  the exact inverse (computed with the deduced formula) and  $A_{\rm approx^{-1}}$  the inverse approximated using the iterative methods. Display the norm:

$$||A_{\text{approx}}^{-1} - A_{\text{exact}}^{-1}||.$$

**Bonus 15 pt.**: Adapt one of the iterative algorithms for approximating the inverse of a matrix, for a non-square matrix,  $A \in \mathbb{R}^{m \times n}$ ,  $m \neq n$ .

Iterative Methods for Approximating the Inverse of a Matrix

The inverse of a nonsingular matrix A is approximated by computing a sequence of matrices  $\{V_k : k \geq 0\}$  that converges to  $A^{-1}$ ..

The Schultz method computes the sequence  $\{V_k\,;\,k\geq 0\}$  in the following way:

$$V_{k+1} = V_k (2I_n - AV_k)$$
,  $k = 0, 1, 2, \dots$ ,  $V_0$  given (1)

This method is also known as the Hotelling-Bodewig algorithm of the hyper-power iterative method.

Li and Li proposed the following two iterative methods for approximating the inverse of a matrix:

$$V_{k+1} = V_k \left[ 3I_n - AV_k (3I_n - AV_k) \right], \ k = 0, 1, 2, \dots$$
 (2)

$$V_{k+1} = \left[ I_n + \frac{1}{4} (I_n - V_k A) (3I_n - V_k A)^2 \right] V_k , \ k = 0, 1, 2, \dots$$
 (3)

To ensure the convergence of the sequence  $\{V_k; k \geq 0\}$ , the first matrix of the sequence,  $V_0$ , must be chosen such that the following relation holds:

$$||AV_0 - I_n|| < 1. (4)$$

Ways of choosing  $V_0$  that ensure the sequence's convergence

1.

$$V_0 = \frac{A^T}{\|A\|_1 \|A\|_{\infty}} \tag{5}$$

$$||A||_{1} = \max \left\{ \sum_{i=1}^{n} |a_{ij}|; j = 1, 2, \dots, n \right\},$$

$$||A||_{\infty} = \max \left\{ \sum_{j=1}^{n} |a_{ij}|; i = 1, 2, \dots, n \right\}.$$
(6)

2. If matrix A is row diagonally dominant or column diagonally dominant:

$$|a_{ii}| > \sum_{\substack{j=1 \ j \neq i}}^{n} |a_{ij}|$$
 ,  $\forall i = 1, \dots, n$  - row diagonally dominant

$$|a_{ii}| > \sum_{\substack{i=1\\i\neq j}}^{n} |a_{ij}|$$
 ,  $\forall i=1,\ldots,n$  – column diagonally dominant

the formula that ensure the sequence's convergence is:

$$V_0 = \mathbf{diag}\left(\frac{1}{a_{11}}, \frac{1}{a_{22}}, \dots, \frac{1}{a_{nn}}\right)$$
 (7)

3. If matric A is symmetric an positive definite, a good choice of  $V_0$  is:

$$V_0 = \frac{1}{\|A\|_F} I_n \quad , \quad \|A\|_F = \left(\sum_{i=1}^n \sum_{j=1}^n |a_{ij}|\right)^{\frac{1}{2}}$$
 (8)

4. 
$$V_0 = \alpha A^T \quad , \quad 0 < \alpha < \frac{2}{\|A\|_2^2} \quad , \quad \|A\|_2 = \sqrt{\rho(A^T A)}$$
 (9)

5.

$$V_0 = \alpha I_n$$
,  $\alpha \in \mathbb{R}$ ,  $\max\{|1 - \lambda_i \alpha|; \lambda_i \text{ eigenvalue for } A\} < 1$  (10)

The algorithm stops if:

- 1)  $||V_k V_{k-1}|| < \epsilon$  (or  $||I_n V_k A||| < \epsilon$ ) in this case matrix  $V_k$  approximates the inverse,  $V_k \approx A^{-1}$ ; (one can use any norm described in (6))
- 2)  $k > k_{max}$  the maximum number of iterations has been exceeded, the approximation of the inverse with the desired precision failed ;

3)  $||V_k - V_{k-1}|| > 10^{10}$ - the computed sequence does not converge, the algorithm failed to approximate the inverse of matrix A.

Not all the elements of the sequence  $\{V_k\}$  must be stored in order to obtain an approximation for  $A^{-1}$ , it suffice to use only two matrices, one for storing  $V_k$  and the other for  $V_{k+1}$ .

For economically computing a matrix of type  $C = aI_n - AV$  (where a is a real value,  $a \in \mathbb{R}$ ), one computes only once in the program the matrix B = (-A), then the matrix C = B \* V is calculated. The required aI - AV matrix is obtained from C by adding the constant a to all the diagonal elements of matrix C ( $c_{ii} = c_{ii} + a$ ,  $\forall i$ ).

A possible approximation scheme for computing an approximation for the inverse of a matrix is the following:

Iterative Method for Approximating the Inverse of a Matrix

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V0 = V1 = \frac{A^T}{\|A\|_1 \|A\|_\infty}; k = 0; k_{max} = 10000; // a possible value do \{ V0 = V1 \; ; \; // \; \text{deep copy compute } V1 \; \text{using } V0 \; \text{and one of the formulae } (1), (2), (3); compute \Delta V = \|V1 - V0\| \; ; k = k + 1; \} \quad \text{while } (\Delta V \geq \epsilon \; \text{and } k \leq k_{max} \; \text{and } \Delta V \leq 10^{10}) if (\Delta V < \epsilon) \; V1 \approx A^{-1}; else divergence; // the algorithm fails to approximate the inverse
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