Homework no. 6

Given (n+1) distinct points, x_0, x_1, \ldots, x_n $(x_i \in \mathbb{R} \ \forall i, x_i \neq x_j, i \neq j)$ and the (n+1) values of an unknown function f at these points, $y_0 = f(x_0)$, $y_1 = f(x_1), \ldots, y_n = f(x_n)$:

approximate the value of function f in \bar{x} , $f(\bar{x})$, for a given \bar{x} , a value which is not in the above table, $\bar{x} \neq x_i$, $i = 0, \ldots, n$ using:

- polynomial approximation computed with the least squares method. For computing the value of least squares polynomial in \bar{x} , use Horner's algorithm; display $P_m(\bar{x})$, $|P_m(\bar{x}) f(\bar{x})|$ and $\sum_{i=0}^n |P_m(x_i) y_i|$. For m introduce values smaller than 6.
- trigonometric interpolation. In this case one considers that the function f is periodic with period 2π and the number of interpolation nodes is odd, $n = 2m, 0 \le x_0 < x_1 < \cdots < x_{2m} < 2\pi$. Display $T_n(\bar{x})$ şi $|T_n(\bar{x}) f(\bar{x})|$.

For solving the linear systems involved in solving the above interpolation problems use the library employed in $Homework\ 2$.

Generate the interpolation nodes $\{x_i, i=0,...,n\}$ in the following way: read $x_0 ext{ si } x_n$ from keyboard or from a file such that $x_0 < x_n$. The interpolation points x_i are randomly generated such that $x_i \in (x_0, x_n)$ and $x_{i-1} < x_i$; the values $\{y_i, i=0,...,n\}$ are computed using a function f hard-coded in your program (examples of initialization for nodes x_0, x_n and function f(x) are displayed at the end of this document), $y_i = f(x_i), i=0,...,n$;

Bonus (10 pt): Draw the graphs of function f and of the approximative computed functions P_m and T_n .

Least Squares Interpolation

Let $a = x_0 < x_1 < \cdots < x_n = b$. Given $\bar{x} \in [a, b]$ approximate $f(\bar{x})$ knowing that the n + 1 values y_i of function f in the interpolation nodes. One computes a polynomial of degree m:

$$S_m(x) = S_m(x; a_0, a_1, \dots, a_m) = a_m x^m + a_{m-1} x^{m-1} + \dots + a_1 x + a_0 = \sum_{k=0}^m a_k x^k$$

the coefficients $\{a_i; i = \overline{0, m}\}$ being the solution to the optimization problem:

$$\min \left\{ \sum_{r=0}^{n} \left| S_m(x_r; a_0, a_1, \dots, a_m) - y_r \right|^2 ; \ a_0, a_1, \dots, a_m \in \mathbb{R} \right\}$$

Solving this problem leads to solving the linear system:

$$Ba = f$$

$$B = (b_{ij})_{i,j=0,\dots,m} \in \mathbb{R}^{(m+1)\times(m+1)} \quad f = (f_i)_{i=0,\dots,m} \in \mathbb{R}^{m+1}$$

$$\sum_{j=0}^{m} \left(\sum_{k=0}^{n} x_k^{i+j}\right) a_j = \sum_{k=0}^{n} y_k x_k^i \quad , \quad i = 0,\dots,m$$

This linear system can be solved with the same numerical library that was used for *Homework* 2.

The value of function f in \bar{x} is approximated by the value of the polynomial S_m in \bar{x} :

$$f(\bar{x}) \approx S_m(\bar{x}; a_0, a_1, \dots, a_m)$$

For computing the value of polynomial $S_m(\bar{x})$ use Horner's method described below.

Horner's method for computing P(v)

Let P be a polynomial of degree p:

$$P(x) = c_0 x^p + c_1 x^{p-1} + \dots + c_{p-1} x + c_p$$
, $(c_0 \neq 0)$

We can write polynomial P also as:

$$P(x) = ((\cdots (((c_0x + c_1)x + c_2)x + c_3)x + \cdots)x + c_{p-1})x + c_p$$

Taking into account this grouping of the coefficients, one obtains an efficient way to compute the value of polynomial P in any point $v \in \mathbb{R}$, this procedure is knowns as Horner's method:

In the above sequence:

$$P(v) := d_p$$

the rest of the computed elements of the sequence d_i , i = 1, ..., p - 1, are the coefficients of the quotient polynomial Q, obtained in the division:

$$P(x) = (x - v)Q(x) + r ,$$

$$Q(x) = d_0x^{p-1} + d_1x^{p-2} \cdots + d_{p-2}x + d_{p-1} ,$$

$$r = d_p = P(v).$$

Computing P(v) (d_p) with formula (1) can be performed using only one real variable $d \in \mathbb{R}$ instead of using a vector $d \in \mathbb{R}^p$.

Trigonometric Interpolation

The trigonometric interpolation is used for approximating periodic functions of period T:

$$f(x+T) = f(x)$$
 , $\forall x$.

We consider the case when $T=2\pi$. Assume we have an odd number of interpolation node n=2m placed in the interval $[0,2\pi)$:

$$0 \le x_0 < x_1 < \dots < x_{n-1} < x_n < 2\pi.$$

The function f is approximated by a linear combination of sin and cos function in the following way:

$$f(x) \approx T_n(x) = a_0 + \sum_{k=1}^m a_k \cos(kx) + \sum_{k=1}^m b_k \sin(kx).$$

Denote by:

$$\phi_0(x) = 1$$
 , $\phi_{2k-1}(x) = \sin(kx)$, $\phi_{2k}(x) = \cos(kx)$, $k = 1, \dots, m$.

The coefficients $\{a_k; k=0,\ldots m\}$ si $\{b_k; k=1,\ldots m\}$ are computed by solving the linear system:

$$TX = Y$$
 , $X = (a_0, b_1, a_1, b_2, a_2, \dots, b_m, a_m)^T$

$$T = \begin{pmatrix} \phi_0(x_0) & \phi_1(x_0) & \phi_2(x_0) & \dots & \phi_{n-1}(x_0) & \phi_n(x_0) \\ \phi_0(x_1) & \phi_1(x_1) & \phi_2(x_1) & \dots & \phi_{n-1}(x_1) & \phi_n(x_1) \\ \phi_0(x_2) & \phi_1(x_2) & \phi_2(x_2) & \dots & \phi_{n-1}(x_2) & \phi_n(x_2) \\ \vdots & & & & & \\ \phi_0(x_{n-1}) & \phi_1(x_{n-1}) & \phi_2(x_{n-1}) & \dots & \phi_{n-1}(x_{n-1}) & \phi_n(x_{n-1}) \\ \phi_0(x_n) & \phi_1(x_n) & \phi_2(x_n) & \dots & \phi_{n-1}(x_n) & \phi_n(x_n) \end{pmatrix} \in \mathbb{R}^{(n+1)\times(n+1)}$$

$$Y = \begin{pmatrix} y_0 \\ y_1 \\ y_2 \\ \vdots \\ y_{n-1} \\ y_n \end{pmatrix} \in \mathbb{R}^{n+1} , \quad X = \begin{pmatrix} a_0 \\ b_1 \\ a_1 \\ \vdots \\ b_m \\ a_m \end{pmatrix} \in \mathbb{R}^{2m+1}.$$

For solving this linear system use the library employed in *Homework 2*.

$$f(\bar{x}) \approx T_n(\bar{x}) = a_0 \phi_0(\bar{x}) + b_1 \phi_1(\bar{x}) + a_1 \phi_2(\bar{x}) + \dots + b_m \phi_{2m-1}(\bar{x}) + a_m \phi_{2m}(\bar{x}).$$

Input data - examples

$$x_0 = a = 1$$
 , $x_n = b = 5$, $f(x) = x^4 - 12x^3 + 30x^2 + 12$
 $x_0 = 0$, $x_n = \frac{31\pi}{16}$, $f(x) = \sin(x) - \cos(x)$
 $x_0 = 0$, $x_n = \frac{31\pi}{16}$, $f(x) = \sin(2x) + \sin(x) + \cos(3x)$
 $x_0 = 0$, $x_n = \frac{63\pi}{32}$, $f(x) = \sin^2(x) - \cos^2(x)$