Homework no. 7

Let P be a polynomial of degree n with real coefficients:

$$P(x) = a_0 x^n + a_1 x^{n-1} + \dots + a_k x^{n-k} + \dots + a_{n-1} x + a_n$$
, $a_0 \neq 0$

and $\epsilon = 10^{-p}$ the computation error and k_{max} the maximum number of iterations in Halley's method.

Compute the interval [-R, R] where all the real roots of the polynomial P can be found. Implement Halley's method for approximating the real roots of a polynomial. In all computations use Horner's algorithm for calculating the value of the polynomial in a point. Approximate as many as possible real roots of the polynomial P with Halley's method, starting from distinct values for x_0 . Display the results on screen and also write them in a file. Write in the file only the distinct roots (2 real values v_1 and v_2 are considered distinct if $|v_1 - v_2| > \epsilon$).

Bonus 20 pt.: Implement the methods (N^4) and (N^5) from the article posted here, for approximating the root of a general function f, not necessarly polynomial. The derivatives of function f will be declared in your program as the function f is.

Halley's Method for Approximating Real Roots of Polynomials

Let P be a polynomial of degree n:

$$P(x) = a_0 x^n + a_1 x^{n-1} + \dots + a_n , \quad (a_0 \neq 0)$$
 (1)

A root for a polynomial P is a real or complex number $r \in \mathbb{R}$ or $r \in \mathbb{C}$ for which:

$$P(r) = a_0 r^n + a_1 r^{n-1} + \dots + a_n = 0.$$

All the polynomials of degree n, with real coefficients have n real and/or complex roots. If r=c+id is a complex root for polynomial P then $\bar{r}=c-id$ is also a complex root of the polynomial P. If $r \in \mathbb{R}$ is a real root for polynomial P then:

$$P(x) = (x - r)Q(x)$$
, Q is a polynomial of degree $n - 1$.

If the complex numbers $c \pm id$ are complex roots for polynomial P then:

$$P(x) = (x^2 - 2cx + c^2 + d^2)Q(x)$$
, Q is a polynomial of degree $n-2$.

(the second degree polynomial $x^2 - 2cx + c^2 + d^2$ has the roots $c \pm id$)

All the real roots of the polynomial P are in the interval [-R, R] where R is given by:

$$R = \frac{|a_0| + A}{|a_0|} \quad , \quad A = \max\{|a_i| \ ; \ i = \overline{1, n}\}$$
 (2)

The real root $x^* \in [-R, R]$ of polynomial P defined by (1), is approximated by building a sequence of real numbers, $\{x_k\}$, that converges to a real root of $P(x_k \longrightarrow x^* \text{ for } k \to \infty)$.

In order to build the sequence $\{x_k\}$, one needs the first element x_0 , then, the other elements are computed in the following way $(x_{k+1}$ is computed using x_k :

$$x_{k+1} = x_k - \frac{1}{a_k},$$

$$a_k = \frac{P'(x_k)}{P(x_k)} - \frac{P''(x_k)}{2P'(x_k)}.$$
(3)

This method is called Halley's method and can be applied not only for approximating roots of polynomials but also for roots of any nonlinear twice differentiable function.

Important remark: The way the first element of the sequence, x_0 , is selected can influence the convergence of the sequence x_k to x^* (or the divergence). Usually, a selection of the initial iteration x_0 in the neighborhood of a root x^* , guarantees the convergence $x_k \longrightarrow x^*$ for $k \to \infty$.

Not all the elements of the sequence $\{x_k\}$ must be memorized, in order to obtain an approximation for the root we only need the 'last' computed value x_{k_0} . A value $x_{k_0} \approx x^*$ approximates a root (thus, is the 'last' computed

element of the sequence) when the difference between two successive elements of the sequence is sufficiently small, i.e.:

$$|x_{k_0} - x_{k_0 - 1}| < \epsilon$$

where ϵ is the precision with which we want to approximate the root x^* .

A possible approximation scheme for Halley's method for approximating the root x^* , is the following:

Halley's Method

```
x randomly chosen; k=1; (for the convergence of the sequence \{x_k\} is preferable to choose x_0 in the neighborhood of a root) do \{
\star compute A=2[P'(x)]^2-P(x)P''(x);
\star if (|A|<\epsilon) STOP;
//(\text{try restarting the algorithm, changing }x_0)
\star compute \Delta=\frac{2P(x)P'(x)}{A};
\star x=x-\Delta;
\star k++;
\}
while (|\Delta| \geq \epsilon \text{ and } k \leq k_{\text{max}} \text{ and } |\Delta| \leq 10^8) if (|\Delta| < \epsilon) x \approx x^*; else divergence; //(\text{try new values for }x_0)
```

 $k_{\text{max}} \in \{1000, 2000, 5000, ...\}$

Horner's method for computing P(v)

Let P be a polynomial of degree p:

$$P(x) = c_0 x^p + c_1 x^{p-1} + \dots + c_{p-1} x + c_p$$
, $(c_0 \neq 0)$

We can write polynomial P also as:

$$P(x) = ((\cdots((c_0x + c_1)x + c_2)x + c_3)x + \cdots)x + c_{p-1})x + c_p$$

Taking into account this grouping of the coefficients, one obtains an efficient way to compute the value of polynomial P in any point $v \in \mathbf{R}$, this procedure is knowns as Horner's method:

In the above sequence:

$$P(v) := d_p$$

the rest of the computed elements of the sequence d_i , i = 1, ..., p - 1, are the coefficients of the quotient polynomial Q, obtained in the division:

$$P(x) = (x - v)Q(x) + r ,$$

$$Q(x) = d_0x^{p-1} + d_1x^{p-2} \cdots + d_{p-2}x + d_{p-1} ,$$

$$r = d_p = P(v).$$

Computing P(v) (d_p) with formula (4) can be performed using only one real variable $d \in \mathbf{R}$ instead of using a vector $d \in \mathbf{R}^p$.

Examples

$$\begin{split} P(x) &= (x-1)(x-2)(x-3) = x^3 - 6x^2 + 11x - 6 \;, \\ a_0 &= 1.0 \;, \quad a_1 = -6.0 \;, \quad a_2 = 11.0 \;, \quad a_3 = -6. \end{split}$$

$$P(x) &= (x-\frac{2}{3})(x-\frac{1}{7})(x+1)(x-\frac{3}{2}) \\ &= \frac{1}{42}(42x^4 - 55x^3 - 42x^2 + 49x - 6) \\ a_0 &= 42.0 \;, \quad a_1 = -55.0 \;, \quad a_2 = -42.0 \;, \quad a_3 = 49.0 \;, \quad a_4 = -6.0. \end{split}$$

$$P(x) &= (x-1)(x-\frac{1}{2})(x-3)(x-\frac{1}{4}) \\ &= \frac{1}{8}(8x^4 - 38x^3 + 49x^2 - 22x + 3) \\ a_0 &= 8.0 \;, \quad a_1 = -38.0 \;, \quad a_2 = 49.0 \;, \quad a_3 = -22.0 \;, \quad a_4 = 3.0. \end{split}$$

$$P(x) &= (x-1)^2(x-2)^2 \\ &= x^4 - 6x^3 + 13x^2 - 12x + 4 \\ a_0 &= 1.0 \;, \quad a_1 = -6.0 \;, \quad a_2 = 13.0 \;, \quad a_3 = -12.0 \;, \quad a_4 = 4.0 \;, \end{split}$$

$$f(x) &= e^x - \sin(x) \;, \quad f'(x) = e^x - \cos(x) \;, \\ f'''(x) &= e^x + \sin(x) \;, \quad x^* = -3.18306301193336. \end{split}$$