# **Generative Adversarial Networks**

: From Theory to Practice

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#### **Generative Adversarial Networks**

Given a dataset, we want to generate new data which seem to be obtained from the dataset, i.e., given  $p_{\text{data}}$ , we want to learn the generator's distribution  $p_g$  over data x s.t.  $p_{\text{data}} = p_g$ .

### How?

- Define a prior  $p_z(\cdot)$  on input noise/latent variable z (e.g., Gaussian), and
- represent a mapping G to a data space as  $G(z; \theta_g)$ , which is the generator.
- Define the discriminator  $D(\cdot; \theta_d)$  that outputs a single scalar. D(x) represents the probability that x came from  $p_{\text{data}}$  rather than  $p_g$ .
- Train *D* to maximize the probability of assigning the correct label to both training examples (real, label=1) and samples from *G* (fake, label=0).
- Simultaneously train G to minimize  $\log(1 D(G(z)))$ .

### **Objective Function**

$$\min_{G} \max_{D} V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_{z}(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))]$$

$$\approx \frac{1}{m} \sum_{i=1}^{m} [\log D(\mathbf{x}_{i}) + \log(1 - D(G(\mathbf{z}_{i})))].$$

Recall: Binary Cross Entropy Loss for logistic regression

For binary dataset  $\left\{x^n, y^n\right\}_{n=1}^N$  where  $y^n \in \{0, 1\}$  with hypothesis model  $h_{\theta}$ ,

$$BCE(\theta) = \frac{1}{N} \sum_{n=1}^{N} \left[ -y^n \log (h_{\theta}(\mathbf{x}^n)) - (1 - y^n) \log (1 - h_{\theta}(\mathbf{x}^n)) \right]$$

• For D,  $x \sim p_{\text{data}}(x)$  should have label 1, and  $G(z) \sim p_g(x)$  should have label 0. Hence, maximizing V(D, G) w.r.t. D is equivalent to minimizing BCE.

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- Minimizing V(D, G) w.r.t. G may not provide sufficient gradient for G early in learning. Hence, we train G to minimize  $-\log D(G(z))$  instead of  $\log(1 - D(G(z)))$ .
- Hence, minimizing  $-\log D(G(z))$  w.r.t. G is equivalent to minimizing BCE.

#### **Theoretical Results**

**Proposition 1.** For G fixed, the optimal discriminator D is  $D_G^*(x) = \frac{p_{\text{data}}(x)}{p_{\text{data}}(x) + p_g(x)}$ .

The proposition gives the analytic form of the optimal discriminator given a generator G.

With the optimal discriminator, the objective w.r.t. G can be reformulated as follows:

$$\begin{split} C(G) &= \max_{D} V(D,G) = V(D_{G}^{*},G) \\ &= \mathbb{E}_{x \sim p_{\text{data}}} \left[ \log D_{G}^{*}(\boldsymbol{x}) \right] + \mathbb{E}_{z \sim p_{z}} \left[ \log (1 - D_{G}^{*}(G(\boldsymbol{z}))) \right] \\ &= \mathbb{E}_{x \sim p_{\text{data}}} \left[ \log D_{G}^{*}(\boldsymbol{x}) \right] + \mathbb{E}_{\boldsymbol{x} \sim p_{g}} \left[ \log (1 - D_{G}^{*}(\boldsymbol{x})) \right] \\ &= \mathbb{E}_{x \sim p_{\text{data}}} \left[ \log \frac{p_{\text{data}}(\boldsymbol{x})}{p_{\text{data}}(\boldsymbol{x}) + p_{g}(\boldsymbol{x})} \right] + \mathbb{E}_{\boldsymbol{x} \sim p_{g}} \left[ \log \frac{p_{g}(\boldsymbol{x})}{p_{\text{data}}(\boldsymbol{x}) + p_{g}(\boldsymbol{x})} \right] \end{split}$$

#### **Theoretical Results**

**Theorem 1.** The global minimum of C(G) is achieved if and only if  $p_g = p_{\text{data}}$ .

$$\therefore \operatorname{Recall} D_{KL}(p \parallel q) = \mathbb{E}_{x \sim p} \left[ \log \frac{p(x)}{q(x)} \right] \text{ and } D_{JS}(p,q) = \frac{1}{2} D_{KL} \left( p \parallel \frac{p+q}{2} \right) + \frac{1}{2} D_{KL} \left( q \parallel \frac{p+q}{2} \right).$$

$$C(G) = \mathbb{E}_{x \sim p_{\text{data}}} \left[ \log \frac{p_{\text{data}}(\mathbf{x})}{p_{\text{data}}(\mathbf{x}) + p_g(\mathbf{x})} \right] + \mathbb{E}_{\mathbf{x} \sim p_g} \left[ \log \frac{p_g(\mathbf{x})}{p_{\text{data}}(\mathbf{x}) + p_g(\mathbf{x})} \right]$$

$$= D_{KL} \left( p_{\text{data}} \left\| \frac{p_{\text{data}} + p_g}{2} \right) + D_{KL} \left( p_g \left\| \frac{p_{\text{data}} + p_g}{2} \right) - 2 \log 2 \right.$$

$$= D_{JS} \left( p_{\text{data}}, p_g \right) - \log 4$$

Since the Jensen-Shannon divergence is a metric, the only solution is  $p_g = p_{\text{data}}$ , i.e., the generator G perfectly replicates the data generating process.

### **Training Algorithm**

**Algorithm 1** Minibatch stochastic gradient descent training of GAN. The number of steps to apply to the discriminator, k, is a hyperparameter.

- 1: **for** number of epochs **do** Train discriminator to achieve optimality given a generator.
- 2: **for** k steps **do**
- 3: Sample minibatch of m noise samples  $\{z^{(1)}, \ldots, z^{(m)}\}$  from noise prior  $p_z$ .
- 4: Sample minibatch of m examples  $\{ \boldsymbol{x}^{(1)}, \dots, \boldsymbol{x}^{(m)} \}$  from data generating distribution  $p_{\text{data}}$ .
- 5: Update the discriminator by gradient ascent method:

$$abla_{m{ heta}_d} rac{1}{m} \sum_{i=1}^m \left[ \log D\left(m{x}^{(i)}
ight) + \log \left(1 - D\left(G\left(m{z}^{(i)}
ight)
ight) 
ight) 
ight].$$

- 6: end for
- 7: Sample minibatch of m noise samples  $\{z^{(1)}, \ldots, z^{(m)}\}$  from noise prior  $p_z$ .
- 8: Update the generator by gradient *descent* method:

$$\nabla_{\boldsymbol{\theta}_g} \frac{1}{m} \sum_{i=1}^{m} \left[ -\log \left( D\left( G\left( \boldsymbol{z}^{(i)} \right) \right) \right) \right].$$