



ΠΟΛΥΤΕΧΝΕΙΟ ΚΡΗΤΗΣ
TECHNICAL UNIVERSITY OF CRETE

Optimization

Taylor approximations, Convex sets, Convex functions, Least-Squares

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1 Question 1

1.1 a.

Let $f : \mathbb{R}_+ \rightarrow \mathbb{R}$ with $f(x) = \frac{1}{1+x}$. We will explore the first 2 Taylor approximations around $x_0 \in \mathbb{R}_+$:

$$f_{(1)}(x) = f(x_0) + f'(x_0)(x - x_0)$$

$$f_{(2)}(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{1}{2}f''(x_0)(x - x_0)^2$$

Computing the derivatives:

$$f'(x) = \frac{d}{dx} \frac{1}{1+x} = -\frac{1}{(1+x)^2}$$

$$f''(x) = \frac{d^2}{dx^2} \frac{1}{1+x} = \frac{1}{(1+x)^3}$$

In the end we have:

$$f_{(1)}(x) = \frac{1}{1+x_0} - \frac{x-x_0}{(1+x_0)^2} = \frac{1-x+2x_0}{(1+x_0)^2}$$

and

$$\begin{aligned} f_{(2)}(x) &= \frac{1-x+2x_0}{(1+x_0)^2} + \frac{1}{2} \frac{2}{(1+x_0)^3} (x-x_0)^2 \\ &= \frac{(1-x+2x_0)(1+x_0) + (x-x_0)^2}{(1+x_0)^3} \\ &= \frac{1-x+2x_0+x_0-xx_0+2x_0^2+(x^2+2xx_0+x_0^2)}{(1+x_0)^3} \\ &= \frac{x^2-(3x_0+1)x+3x_0^2+3x_0+1}{(1+x_0)^3} \end{aligned}$$

1.2 b.

Plotting the functions in MATLAB for different values of x_0 :

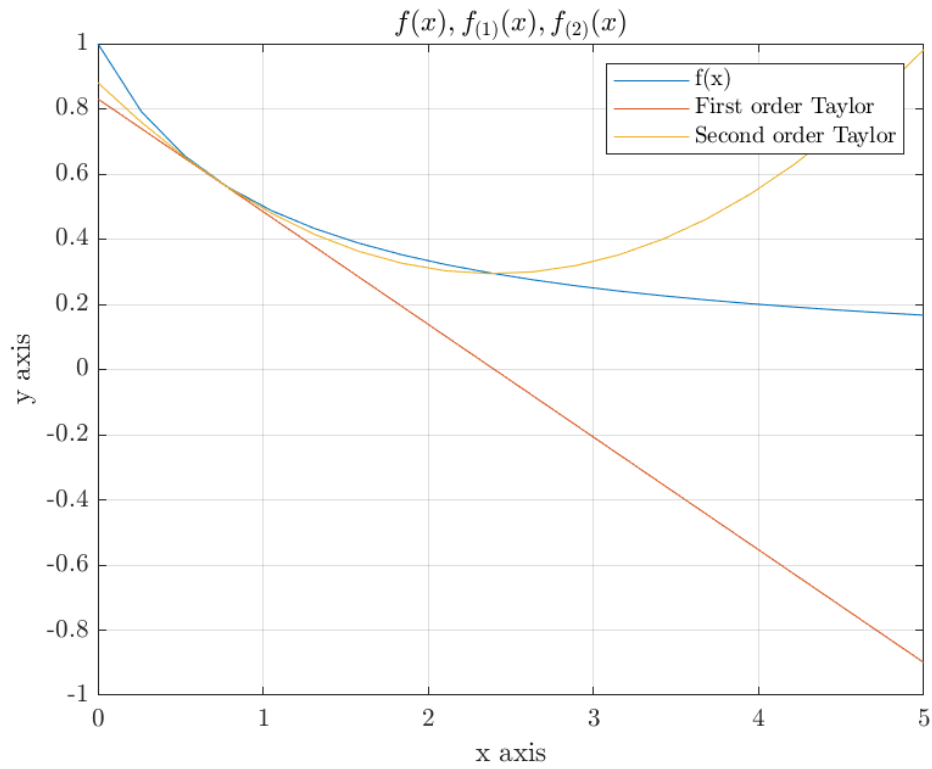


Figure 1: $x_0 = 0.7$

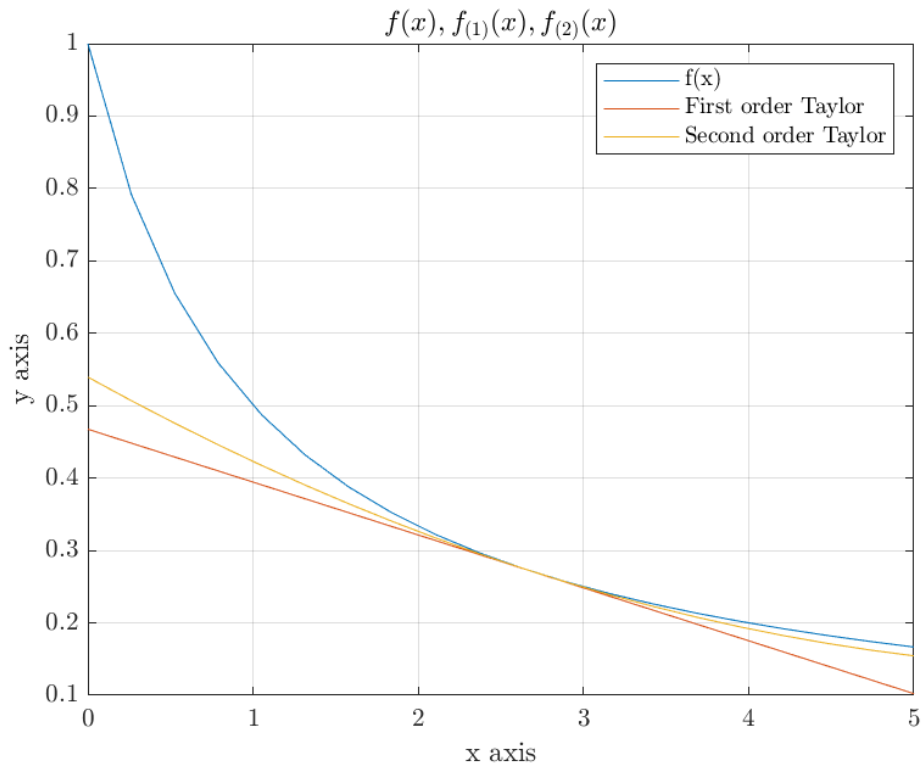


Figure 2: $x_0 = 2.7$

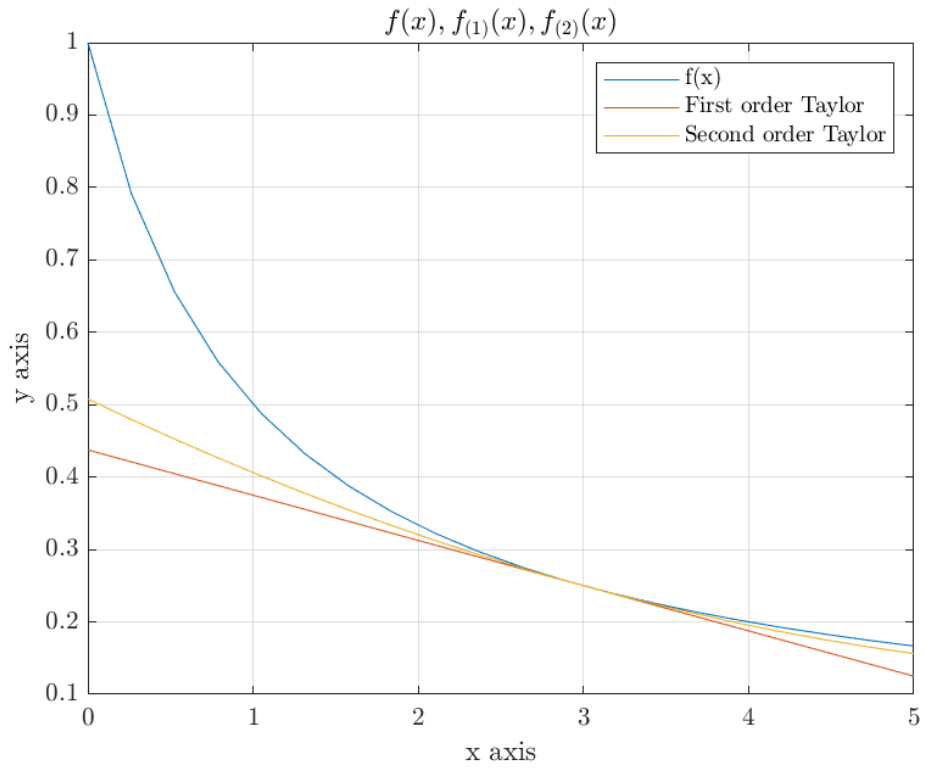


Figure 3: $x_0 = 3$

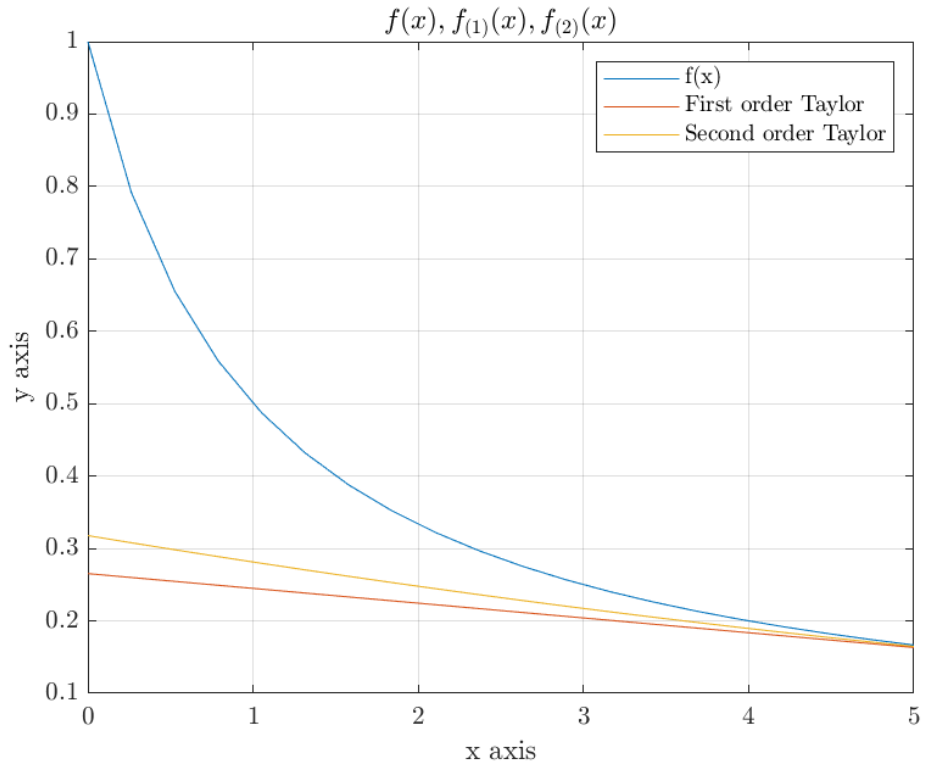


Figure 4: $x_0 = 6$

2 Question 2

2.1 a.

Let $f : \mathbb{R}_+^2 \rightarrow \mathbb{R}$ with $f(x_1, x_2) = \frac{1}{1+x_1+x_2}$. Similarly to Question 1 We will explore the first 2 Taylor approximations around $\vec{x}_0 \in \mathbb{R}_+^2$:

Pick $x_* = 5 > 0$

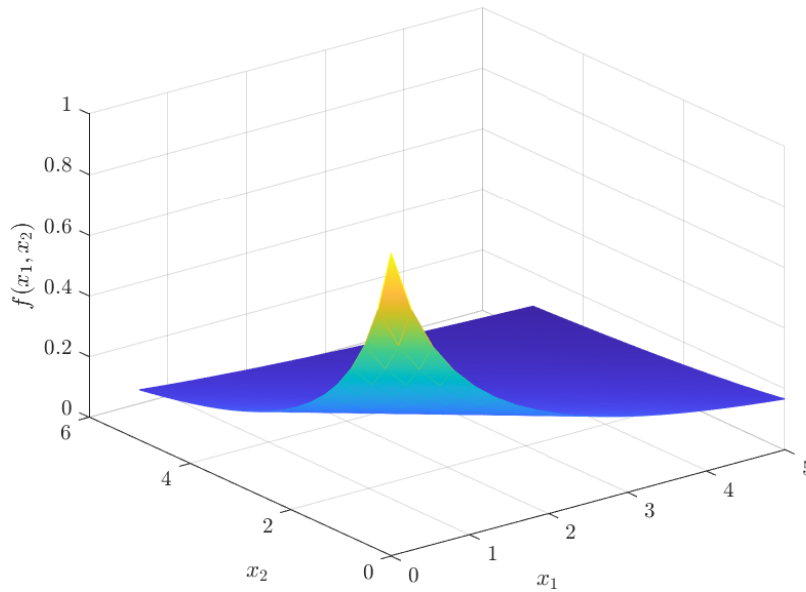


Figure 5: Plot of f

2.2 b.

The levels sets of f are shown in the contour plot:

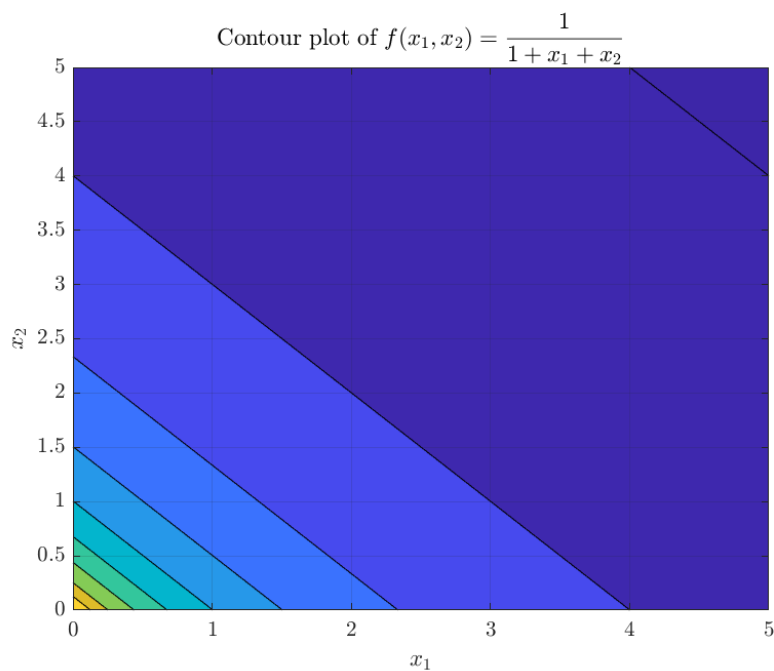


Figure 6: Contour plot of f

From the contour plot we can make the remark that as $x_1, x_2 \rightarrow 0$ the value of the function increases, as shown by the colour map.

2.3 c.

We have chosen point $\vec{x}_0 = (x_{0,1}, x_{0,2})^T = (3, 3)^T$

$$f_{(1)}(\vec{x}) = f(\vec{x}_0) + \nabla f(x_0)^T (\vec{x} - \vec{x}_0)$$

$$f_{(2)}(\vec{x}) = f_{(1)}(\vec{x}_0) + \frac{1}{2}(\vec{x} - \vec{x}_0)^T \mathbf{H}_f(\vec{x} - \vec{x}_0)$$

Where the ∇f is defined as:

$$\nabla f(x_1, x_2) = \begin{bmatrix} \frac{\partial}{\partial x_1} f(x_1, x_2) \\ \frac{\partial}{\partial x_2} f(x_1, x_2) \end{bmatrix} = \begin{bmatrix} -\frac{1}{1+x_1+x_2} \\ -\frac{1}{1+x_1+x_2} \end{bmatrix}$$

and \mathbf{H}_f is the hessian matrix:

$$\begin{aligned} \mathbf{H}_f &= \begin{bmatrix} \frac{\partial^2}{\partial x_1^2} f(x_1, x_2) & \frac{\partial^2}{\partial x_1 \partial x_2} f(x_1, x_2) \\ \frac{\partial^2}{\partial x_2 \partial x_1} f(x_1, x_2) & \frac{\partial^2}{\partial x_2^2} f(x_1, x_2) \end{bmatrix} \\ &= \begin{bmatrix} \frac{\partial}{\partial x_1} \frac{-1}{(1+x_1+x_2)^2} & \frac{\partial}{\partial x_2} \frac{-1}{(1+x_1+x_2)^2} \\ \frac{\partial}{\partial x_1} \frac{-1}{(1+x_1+x_2)^2} & \frac{\partial}{\partial x_2} \frac{-1}{(1+x_1+x_2)^2} \end{bmatrix} \\ &= \begin{bmatrix} \frac{2}{(1+x_1+x_2)^3} & \frac{2}{(1+x_1+x_2)^3} \\ \frac{2}{(1+x_1+x_2)^3} & \frac{2}{(1+x_1+x_2)^3} \end{bmatrix} \end{aligned}$$

using the above equations, we compute the taylor approximations of f :

$$f_{(1)}(\vec{x}) = f(\vec{x}_0) + \nabla f(x_0)^T (\vec{x} - \vec{x}_0) = \frac{-(x_1 + x_2) + 2(x_{0,1} + x_{0,2}) + 1}{(1 + x_{0,1} + x_{0,2})^2}$$

$$\begin{aligned} f_{(2)}(\vec{x}) &= \frac{-(x_1 + x_2) + 2(x_{0,1} + x_{0,2}) + 1}{(1 + x_{0,1} + x_{0,2})^2} + \frac{(x_1 + x_{0,1})^2 + (x_2 - x_{0,2})^2 + 2(x_1 + x_{0,1})(x_2 + x_{0,2})}{(1 + x_1 + x_2)^3} \\ &= \frac{-(x_1 + x_2) + 2(x_{0,1} + x_{0,2}) + 1}{(1 + x_{0,1} + x_{0,2})^2} + \frac{((x_1 - x_{0,1} + x_2 + x_{0,2}))^2}{(1 + x_1 + x_2)^3} \end{aligned}$$

2.4 c. d.

Lets now plot all the functions together:

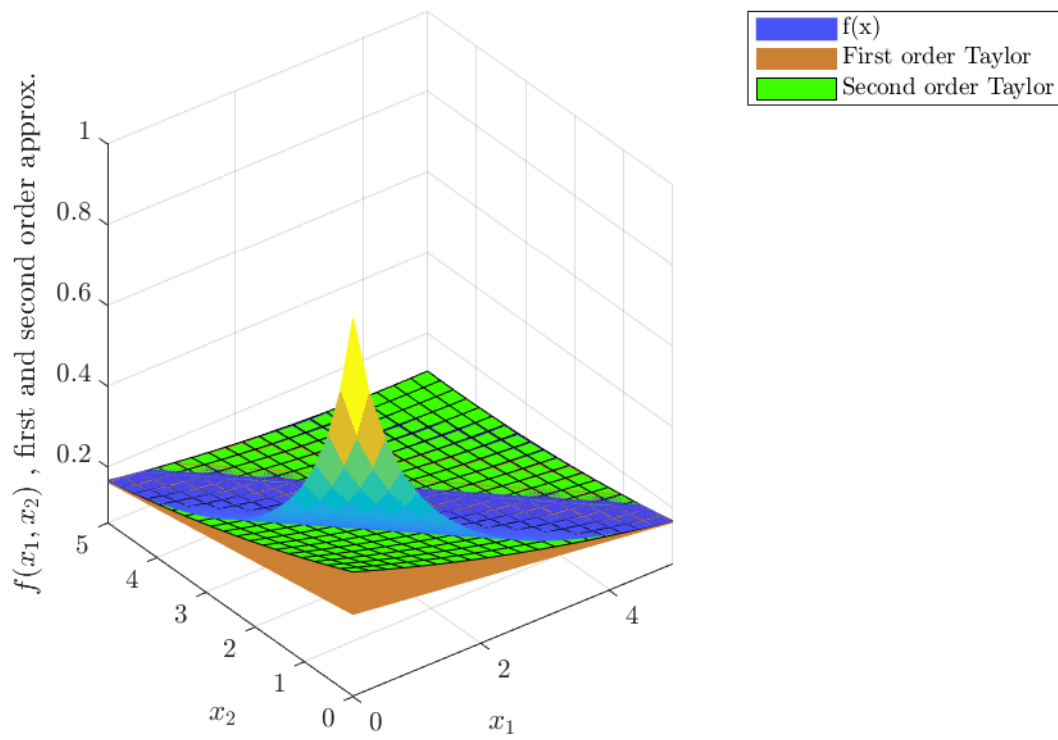


Figure 7: Plot of $f, f_{(1)}, f_{(2)}$

3 Question 3

3.1 a.

Lets use the direct method of proof. Let $x_1, x_2 \in \mathbb{S}_{\vec{a},b} = \{\mathbf{x} \in \mathbb{R}^n \mid \vec{a}^T \mathbf{x} \leq b\}$ and $0 \leq \theta \leq 1$

Multiplying each side by θ and $\theta - 1$ respectively:

$$\vec{a}^T x_1 \leq b \iff \theta(\vec{a}^T x_1) \leq \theta b \quad (1)$$

$$\vec{a}^T x_2 \leq b \iff (1 - \theta)(\vec{a}^T x_2) \leq (1 - \theta)b \quad (2)$$

Performing addition by parts on the above inequalities (1) (2), we end up having:

$$\begin{aligned} \theta(\vec{a}^T x_1) + (1 - \theta)(\vec{a}^T x_2) &\leq \theta b + (1 - \theta)b \\ \iff \vec{a}^T (\theta x_1 + (1 - \theta)x_2) &\leq b \\ \iff \vec{a}^T x_s &\leq b \end{aligned}$$

where x_s is any convex combination of $x_1, x_2 \in \mathbb{S}_{\vec{a},b}$. In conclusion, $\mathbb{S}_{\vec{a},b}$ is convex.

3.2 b.

We shall prove this using a counterexample. Let $\mathbb{S}_{\vec{a},b}$ b affine. This means $\forall x_1, x_2 \in \mathbb{S}_{\vec{a},b}$ and for random $\theta \in \mathbb{R}$ the point $\theta x_1 + (1 - \theta)x_2 \in \mathbb{S}_{\vec{a},b}$.

Choose random $\theta > 1$ and x_1 such that $\vec{a}^T x_1 = b$. Following the same procedure as in question a., we will end up with:

$$\vec{a}^T (\theta x_1 + (1 - \theta)x_2) \geq b$$

Concluding that $\mathbb{S}_{\vec{a},b} = \{\mathbf{x} \in \mathbb{R}^n \mid \vec{a}^T \mathbf{x} \leq b\}$ is not an affine set.

4 Question 4

$\mathbb{H}_{\mathbf{a},b} := \{\mathbf{x} \in \mathbb{R}^n \mid \mathbf{a}^T \mathbf{x} = b\}$.

We have that $\mathbf{a}^T x_* = b$ since $x_* \in \mathbb{H}_{\mathbf{a},b}$. Also $x_* = \lambda a$, since \mathbf{a} and x_* are co-linear.

For non-zero a we have: $\lambda \mathbf{a}^T a = b \iff \lambda = \frac{b}{\|\mathbf{a}\|_2^2}$

In conclusion, $x_* = \frac{ba}{\|\mathbf{a}\|_2^2}$

5 Question 5

5.1 a.

$$f''(x) = \frac{d^2}{dx^2} \frac{1}{1+x} = \frac{1}{(1+x)^3} \geq 0$$

$\forall x \in \mathbb{R}_+$. Thus f is convex.

5.2 b.

Compute the Hessian matrix \mathbf{H}_f :

$$\begin{aligned} \mathbf{H}_f &= \begin{bmatrix} \frac{\partial^2}{\partial x_1^2} f(x_1, x_2) & \frac{\partial^2}{\partial x_1 \partial x_2} f(x_1, x_2) \\ \frac{\partial^2}{\partial x_2 \partial x_1} f(x_1, x_2) & \frac{\partial^2}{\partial x_2^2} f(x_1, x_2) \end{bmatrix} \\ &= \begin{bmatrix} \frac{\partial}{\partial x_1} \frac{-1}{(1+x_1+x_2)^2} & \frac{\partial}{\partial x_2} \frac{-1}{(1+x_1+x_2)^2} \\ \frac{\partial}{\partial x_1} \frac{-1}{(1+x_1+x_2)^2} & \frac{\partial}{\partial x_2} \frac{-1}{(1+x_1+x_2)^2} \end{bmatrix} \\ &= \begin{bmatrix} \frac{2}{(1+x_1+x_2)^3} & \frac{2}{(1+x_1+x_2)^3} \\ \frac{2}{(1+x_1+x_2)^3} & \frac{2}{(1+x_1+x_2)^3} \end{bmatrix} \end{aligned}$$

We can compute the 2 minor determinants and clearly see that they are positive and 0 respectively:

$$\det_1 = \frac{2}{(1+x_1+x_2)^3}$$

$\det_2 = 0$ This is equivalent to the Hessian matrix being p.d.

$$\mathbf{H}_f \succeq 0 \tag{3}$$

hence f : convex.

5.3 c.

Computing the derivative we have:

$$f''(x) = a(a-1)x^{a-2}$$

For every $a \geq 1 \vee a \leq 0$ we have that $f''(x) \geq 0$ so f is convex.

For every $0 \leq a \leq 1$ we have that $f''(x) \leq 0$ so f is concave.

We can plot the different curves to verify our findings:

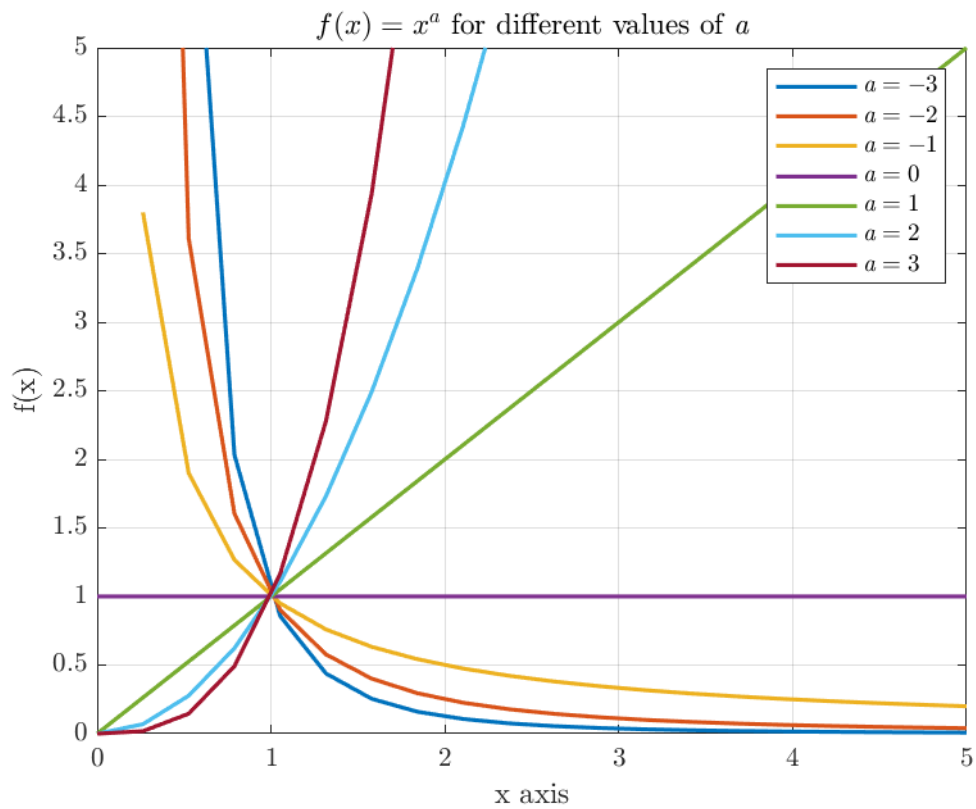


Figure 8: Plot of f , for different values of a

5.4 d.

To prove the convexity of the norm function, we cannot use the normal method of applying the gradient operator, since f is not diff/able everywhere in its domain. Instead we are going to use the **Definition**. But first let us observe the plots in \mathbb{R}^3 :

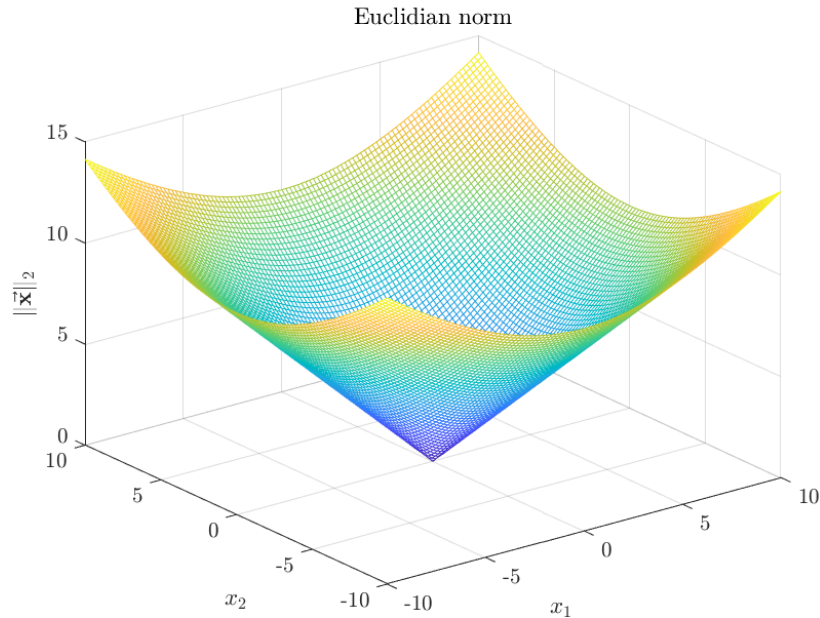


Figure 9: Plot of euclidean norm

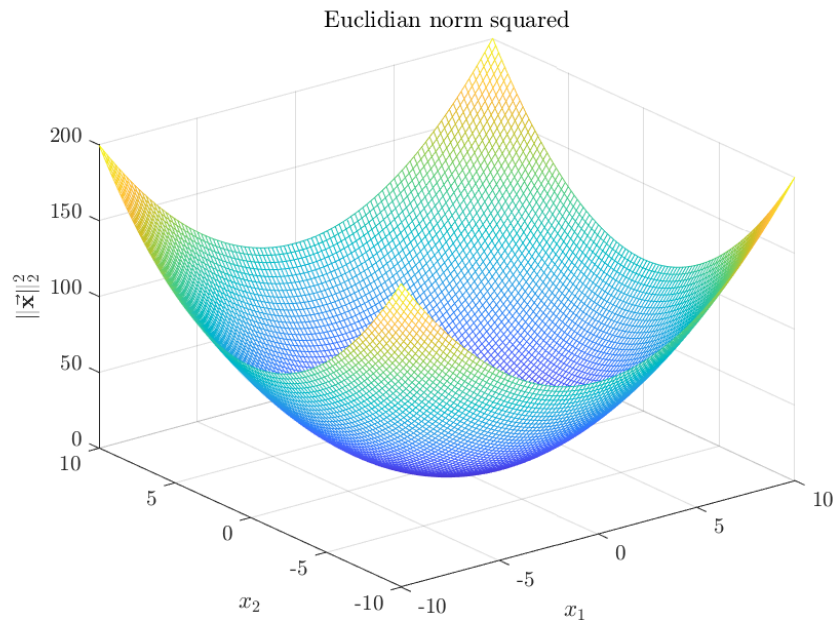


Figure 10: Plot of euclidean norm squared

It is apparent that they are both convex. Lets prove it:

Norm: we shall prove that $\forall x, y \in \mathbb{D}_f$ the following is true:

$$\begin{aligned}
& f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y) \\
\iff & \|\theta x + (1 - \theta)y\|_2 \leq \theta\|x\|_2 + (1 - \theta)\|y\|_2 \\
\iff & \|\theta x + (1 - \theta)y\|_2 \leq \|\theta x\|_2 + \|(1 - \theta)y\|_2
\end{aligned}$$

which is indeed true $\forall x, y \in \mathbb{D}_f$ from the triangle inequality. Thus the equivalent starting proposition is also true, so the norm function is convex.

The proof for the norm squared is much simpler:

$$\nabla^2 = 2\mathbb{I} \succ 0$$

so in conclusion the norm function squared is convex.

6 Question 6

Plot in \mathbb{R}^3 :

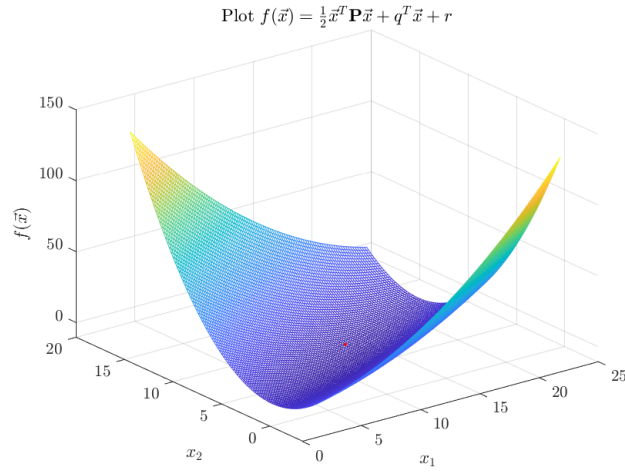


Figure 11: Plot of quadratic function

Contour of quadratic function:

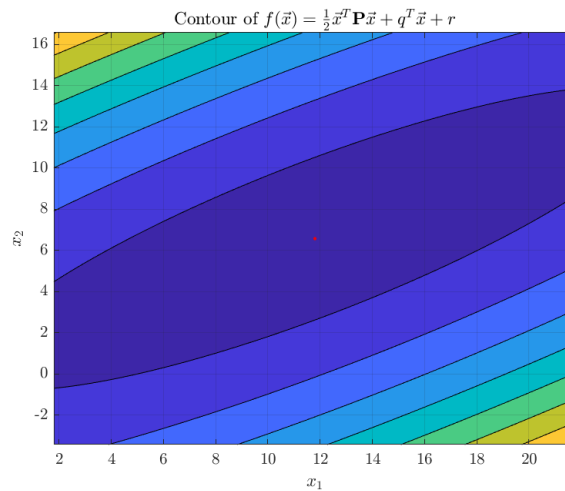


Figure 12: Plot of quadratic function

The marked point (in red) is indeed the minimal.