Week 04

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今日 Topic: ch23、ch34、ch35、期末複習(另外一份)

Ch 23 講義;

$$\hat{w}(u,v) = w(u,v) + h(u) - h(v)$$

rewighting

- We have h(v) ≤ h(u) + w(u, v) if there is no negative weight cycle (why?)
- $\hat{w}(u, v) = w(u, v) + h(u) h(v) \ge 0$

絕對是正的

- 1 Computing G', where G'.V = G.V \cup {s} and G'.E= G.E \cup {(s, v): $v \in G.V$ } and w(s, v) = 0.
- 2 if BELLMAN-FORD(G', w, s)= FALSE
- 3 print "the input graph contains negative weight cycle"
- 4 else for each vertex $v \in G'.V$
- 5 set h(v) to be the value of $\delta(s, v)$ computed by the BF algorithm
- 6 for each edge $(u, v) \in G'.E$, $\hat{w}(u, v) = w(u, v) + h(u) h(v)$

```
7 Let D = (d_{uv}) be a new n x n matrix

8 for each vertex u \in G.V

run DIJKSTRA (G, \hat{w}, u) to compute \hat{\delta}(u, v)

for all v \in V[G].

10 for each vertex v \in G.V

11 d_{uv} = \hat{\delta}(u, v) + h(v) - h(u)

12 return D

Complexity: Using Fibonacci heap O(V^2|gV + VE)

Using Binary heap implementation: O(VE|gV)
```

Ch 23 習題:

Suppose that you also want to compute the vertices on shortest paths in the algorithms of this section. Show how to compute the predecessor matrix Π from the completed matrix L of shortest-path weights in $O(n^3)$ time.

簡單來說當前的 shortest path 一定會是 I -> j 或是 經過某個 k 的最短路徑相加,也就是說我們只需要檢查 L[I,j] == L[I,k] + L[k,j],如果都沒有就是第一種 case,有的話就是我的前一步會更新到 k,預設 PI[I,j] = I。

Modify FASTER-ALL-PAIRS-SHORTEST-PATHS so that it can determine whether the graph contains a negative-weight cycle.

time for each assignment.

```
FASTER-APSP(W, n)

1 let L and M be new n \times n matrices

2 L = W

3 r = 1

4 while r < n - 1

5 M = \infty // initialize M

6 EXTEND-SHORTEST-PATHS(L, L, M, n) // compute M = L^2

7 r = 2r

8 L = M // ready for the next iteration

9 return L
```

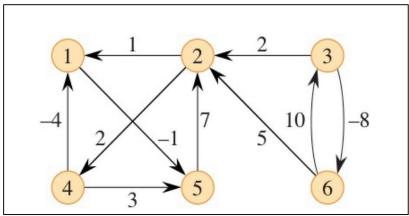
我們知道 $2^{(k+1)} > n-1$,因為 $2^{k} > n-1$,所以我們可以在多乘一次,也就是在 return 前多加一行,extended-shortest-path(M,M,M',n),以及 check M' = M or not。

Give an efficient algorithm to find the length (number of edges) of a minimum-length negativeweight cycle in a graph.

可以利用 APSP 每一次迭代都檢查對角線,時間複雜度是 O(n^4)。

Run the Floyd-Warshall algorithm on the weighted, directed graph of Figure 25.2. Show the matrix $D^{(k)}$ that results for each iteration of the outer loop.

算算看



建議要

As it appears above, the Floyd-Warshall algorithm requires $\Theta(n^3)$ space, since we compute $d_{ij}^{(k)}$ for $i,j,k=1,2,\ldots,n$. Show that the following procedure, which simply drops all the superscripts, is correct, and thus only $\Theta(n^2)$ space is required.

```
FLOYD-WARSHALL'(W)

n = W.rows

D = W

for k = 1 to n

for j = 1 to n

d[i, j] = min(d[i, j], d[i, k] + d[k, j])

return D
```

只會根據前一次的來做改變,且改變的時候是 dij^(m+1) = min(dij^m, dik^m + dkj^m),這代表,我只要在跟心之前,或者是在跟跟心的時候 dik、dkj 都不會被動到就好,那這是對的,因為如果會被動到就代表 dik + dkk < dik 或者是 dkk + dkj < dkj,那這是不可能發生的當圖沒有負環的時候。

How can we use the output of the Floyd-Warshall algorithm to detect the presence of a negative-weight cycle?

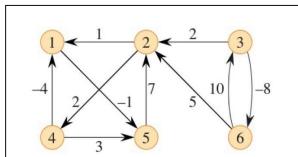
迭代完之後檢查對角線是否有非0元素。



Give an O(VE)-time algorithm for computing the transitive closure of a directed graph G=(V,E). Assume that |V|=O(E) and that the graph is represented with adjacency lists.

這邊使用 dfs 對於每一個點,但這樣時間複雜度是 O(VE + V*V),且|V| = O(E),所以時間複雜就是 O(VE + VE) = O(VE)

Use Johnson's algorithm to find the shortest paths between all pairs of vertices in the graph of Figure 25.2. Show the values of h and \hat{w} computed by the algorithm.



算算看,建議要

What is the purpose of adding the new vertex s to V', yielding V'?

This is only important when there are negative-weight cycles in the graph. Using a dummy vertex gets us around the problem of trying to compute $-\infty + \infty$ to find \hat{w} . Moreover, if we had instead used a vertex v in the graph instead of the new vertex s, then we run into trouble if a vertex fails to be reachable from v.

Suppose that $w(u,v) \ge 0$ for all edges $(u,v) \in E$. What is the relationship between the weight functions w and \hat{w} ?

If all the edge weights are nonnegative, then the values computed as the shortest distances when running Bellman-Ford will be all zero. This is because when constructing G' on the first line of Johnson's algorithm, we place an edge of weight zero from s to every other vertex. Since any path within the graph has no negative edges, its cost cannot be negative, and so, cannot beat the trivial path that goes straight from s to any given vertex. Since we have that h(u) = h(v) for every u and v, the reweighting that occurs only adds and subtracts 0, and so we have that $w(u,v) = \hat{w}(u,v)$

Suppose that we run Johnson's algorithm on a directed graph G with weight function w. Show that if G contains a 0-weight cycle c, then $\hat{w}(u,v)=0$ for every edge (u,v) in c.

我們知道 rewight 後,一個圈圈的權重不會變,也知道 rewight 後如果沒有負環,他就會都大於等於 0,所以她一定全部都等於 0。

Ch 34 講義:

Cook-Levin Theorem

 If SAT is in P, then all problems in NP are also in P

這說明 SAT 是 NP 裡面最難的問題

Problem Reduction

- · e.g., A = Finding median, B = Sorting
- · We can solve A if we know how to solve B
 - → sorting is as hard as finding median
- eq., A = Topological Sort, B = DFS
- · We can solve A if we know how to solve B
 - → DFS is as hard as topological sort

說是 reduction,但是其實是 show 更難

Problem Reduction CIRCUIT-SAT SAT 3-CNF-SAT SUBSET-SUM

The structure of NP-

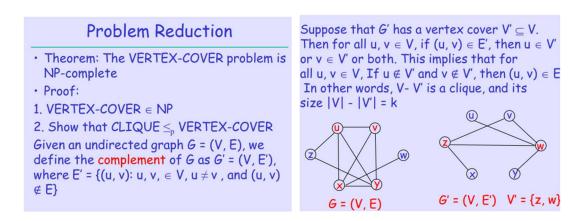
Proofs in Section 34.3

Completeness

越往下的問題越難,我們可以透過後面的證明,說明如果我解決下面的問題, 那上面的問題就被解決了。

HAM-CYCLE

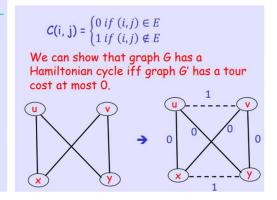
TSP



我們想要 show 點覆蓋也是 NPC, 首先我們先說明他會落在 NP裡, 那它的難度一定小於 NPC, 再來要說明另一邊, 也就是說, 我要說明如果點覆蓋可以解, 那某一個 NPC 的問題也可以解, 那這邊取的 NPC 問題是點團。

Problem Reduction

- Theorem: The traveling-salesman problem (TSP) is NP-complete
- · Proof:
- 1. TSP ∈ NP
- 2. Show that HAM-CYCLE \leq_p TSP Let G = (V, E) be an instance of HAM-CYCLE. We construct an instance of TSP as follows. We form a complete graph G' = (V, E'), where $E' = \{(i, j) | i, j, \in V, \text{ and } i \neq j\}$ and we define the cost function



同理,自己想一下。

- NP-Complete: a problem A is in NPC iff
 (i) A is in NP, and (ii) any problem in NPC
 can be reduced to it in O(nk) time.
- If any problem in NPC can be solved in O(n^k) time, then P=NP. It is believed (but not proved) that P ≠ NP.
- NP-Hard: a problem A is in NPH iff a problem in NPC can be reduced to A in O(nk) time.

NPC 的 decision problem,他的最佳化問題是 NPH。

 Give a polynomial algorithm to solve the 2-CNF satisfiability problem

演算法

假設 Boolean formula 有 n 種布林變數, m 個子句

- 將 Boolean formula 轉成一有向圖 G (Implication Graph):
 建構方式:
 - (1) 對每個 x_i ,新增兩個點 X_i 和 \hat{X}_i
 - (2) 對每個子句 $(x_i ee x_j)$,新增兩條有向邊 (\hat{X}_i, X_j) 和 (\hat{X}_j, X_i)
- 2. 利用 Kosaraju's Algorithm 找出所有強連通分量。
- 3. 檢查每組 x_i 和 \hat{x}_i 是否在同一個強連通分量中。如果存在一組相同代表 Unsatisfiable 則回傳 False。若每組 x_i 和 \hat{x}_i 都在不同的強連通分量中,代表此 Boolean formula 為 Satisfiable,回傳 True。

- If a problem is NPC, it cannot be solved by any polynomial time algorithm in the worst cases.
- If a problem is NPC, we have not found any polynomial time algorithm to solve it in the worst cases until now.
- If a problem is NPC, then it is unlikely that a polynomial time algorithm can be found in the future to solve it in the worst cases.

FTF

- If we can prove that the lower bound of an NPC problem is exponential, then we have proved that NP ≠ P.
- Any NP-hard problem can be solved in polynomial time if an algorithm can solve the satisfiability problem in polynomial time.

ΤF

- Suppose that all edge weights in a graph are integers ranging from 1 to |V|. How fast can you make Prim's algorithm run?
- How do you solve the single-source shortest paths problem in directed acyclic graphs (DAGs)?

O(V+E) \quad DAG-shotest-path (use topologic sort)

Ch 34 習題:

Is the dynamic-programming algorithm for the 0-1 knapsack problem that is asked for in Exercise 16.2-2 a polynomial-time algorithm? Explain your answer.

```
0-1-KNAPSACK(n, W)
    Initialize an (n + 1) by (W + 1) table K
    for i = 1 to n
        K[i, 0] = 0
    for j = 1 to W
        K[0, j] = 0
    for i = 1 to n
        for j = 1 to W
        if j < i.weight
              K[i, j] = K[i - 1, j]
        else
              K[i, j] = max(K[i - 1, j], K[i - 1, j - i.weight] + i.value)</pre>
```

這是 fake polynomial,因為如果背包大小大到 2ⁿ,那就是不是 P 了。

Prove that if ${\cal G}$ is an undirected bipartite graph with an odd number of vertices, then ${\cal G}$ is nonhamiltonian.

他會從 A 到 B,但因為是奇數的關係,所以最後停的那一塊一定跟原本的不同塊。

Show that the hamiltonian-path problem from Exercise 34.2-6 can be solved in polynomial time on directed acyclic graphs. Give an efficient algorithm for the problem.

Use topologic sort,檢查相鄰的是否都有邊連接。

Ch 35 講義:

```
Let us consider the following algorithm:
1. C = an empty set
2. while (there is an edge in G) {
3. Pick an edge, say (u,v);
4. Put u and v into C;
5. Remove u, v, and all edges adjacent to u or v;
}
6. return C
```

- What is so special about C?
 - Vertices in C must cover all edges.
 - But ... it may not be the smallest one
- How far is it from the optimal?
 - At most two times (why?)
 - Because each edge in line 3 of the algorithm can only be covered by its endpoints > in each iteration, one of the selected vertexes must be in the optimal vertex cover

$APPROX_{TSP_{TOUR}(G, c)}$

- 1 Select a vertex $r \in G.V$ to be a root vertex
- 2 grow an MST T for G from root r using $MST_PRIM(G, c, r)$
- 3 Let H be the list of vertices visited in a preorder walk of T
- 4 return the Hamiltonian cycle H that visits the vertices in the order H

Time complexity: $O(E) = O(V^2)$

- Clearly, |W|=2|T|. Thus, |W|≤2|H*|.
 Note that W is not a tour. It visits a vertex more than once. However, by triangle inequality, we can delete unnecessary visits to a vertex without increasing the cost to obtain H. In our example, H=(a, b, c, h, d, e, f, g) Thus, |H|≤|W|≤2|H*|. #
- Can we find an approximation algorithm for the general TSP Problem?

```
    V<sub>1</sub> = V<sub>2</sub> = empty set;
    Label the vertices by x<sub>1</sub>, x<sub>2</sub>, ..., x<sub>n</sub>
    For (k = 1 to n) {
        /* Fix location of x<sub>k</sub> */
        Fix x<sub>k</sub> to the set such that more
        in-between edges (with those already fixed
        vertices x<sub>1</sub>, x<sub>2</sub>, ..., x<sub>k-1</sub>) are obtained;
    }
    return the cut (V<sub>1</sub>, V<sub>2</sub>);
```

- How far is our cut from the optimal?
 - At most two times (why?)
 - When a vertex v is fixed, we will add some edges into the cut and discard some edges (u, v) if u is placed in the same set as v
 - But when each vertex is fixed:
 #edges added > #edges discarded
 - → total #edges added ≥ m/2

Ch 35 習題:

Give an efficient greedy algorithm that finds an optimal vertex cover for a tree in linear time.

Algorithm 1 GREEDY-VERTEX-COVER(G)

```
1: V' = \emptyset
2: let L be a list of all the leaves of G
3: while V \neq \emptyset do
       if |V| == 1 or 0 then
4:
           return V'
5:
       end if
6:
       let v be a leaf of G = (V, E), and \{v, u\} be its incident edge
7:
       V = V - v
8:
       V' = V' \cup u
9:
       for each edge \{u, w\} \in E incident to u do
10:
           if d_w == 1 then
11:
               L.insert(w)
12:
           end if
13:
           E = E - \{u, w\}
14:
       end for
15:
       V = V - u
16:
17: end while
```

From the proof of Theorem 34.12, we know that the vertex-cover problem and the NP-complete clique problem are complementary in the sense that an optimal vertex cover is the complement of a maximum-size clique in the complement graph. Does this relationship imply that there is a polynomial-time approximation algorithm with a constant approximation ratio for the clique problem? Justify your answer.

It does not imply the existence of an approximation algorithm for the maximum size clique. Suppose that we had in a graph of size n, the size of the smallest vertex cover was k, and we found one that was size 2k. This means that in the compliment, we found a clique of size n-2k, when the true size of the largest clique was n-k. So, to have it be a constant factor approximation, we need that there is some λ so that we always have $n-2k \geq \lambda(n-k)$. However, if we had that k was close to $\frac{n}{2}$ for our graphs, say $\frac{n}{2} - \epsilon$, then we would have to require $2\epsilon \geq \lambda \frac{n}{2} + \epsilon$. Since we can make ϵ stay tiny, even as n grows large, this inequality cannot possibly hold.