

Chapter 25: All-Pairs Shortest-Paths

Some Algorithms

- ✓ When no negative edges
 - Using Dijkstra's algorithm with array: $O(V^3)$
 - Using Binary heap implementation: $O(VE \lg V)$
 - Using Fibonacci heap: $O(VE + V^2 \log V)$
- When no negative **cycles**
 - Floyd-Warshall [1962]: $O(V^3)$ time
- When **negative cycles**
 - Using Bellman-Ford algorithm: $O(V^2 E) = O(V^4)$
 - Johnson [1977]: $O(VE + V^2 \log V)$ time based on a clever combination of Bellman-Ford and Dijkstra

A dynamic programming approach

- **Optimal Substructure** (allows recursion)
 - ✓ solution to the problem contains optimal solutions to subproblems.
- **Overlapping Subproblems** (allows speed up)
 - ✓ a recursive algorithm revisits the same subproblem over and over again.
- Compute the value of an optimal solution in a bottom-up fashion.

The structure of an optimal solution

- Consider a shortest path p from vertex i to vertex j , and suppose that p contains **at most m** edges. Assume that there are no negative-weight cycles. Hence, $m \leq n-1$ is finite.

The structure of an optimal solution (cont.)

- If $i = j$, then p has weight 0 and no edge
- If $i \neq j$, we decompose p into $i \overset{p'}{\sim} k \rightarrow j$ where p' contains **at most** $m-1$ edges.
- Moreover, p' is a shortest path from i to k and $\delta(i,j) = \delta(i,k) + w_{kj}$, where $\delta(i,j)$ denote the shortest weight path from i to j

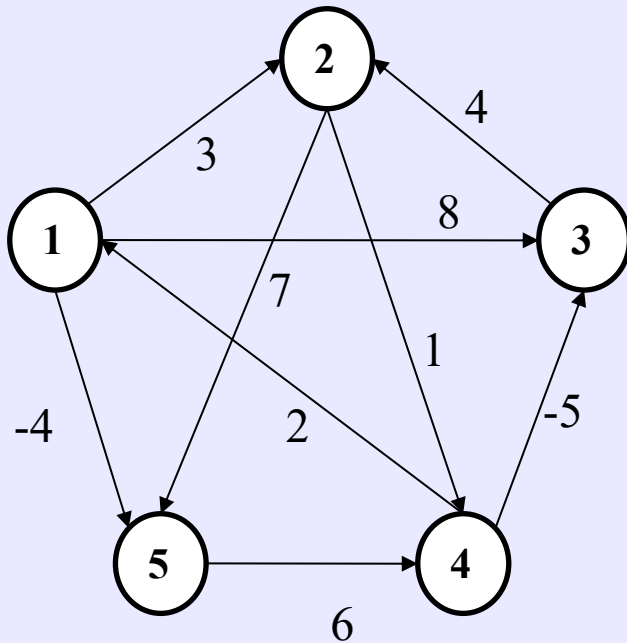
Recursive solution to the all-pairs shortest-path problem

- Define: $l_{ij}^{(m)}$ = minimum weight of any path from i to j that contains **at most m edges**.
- $l_{ij}^{(0)} = \begin{cases} 0 & \text{if } i = j \\ \infty & \text{if } i \neq j \end{cases}$
- Then $l_{ij}^{(m)} = \min\{ l_{ij}^{(m-1)}, \min_{1 \leq k \leq n} \{ l_{ik}^{(m-1)} + w_{kj} \} \}$ = **$\min_{1 \leq k \leq n} \{ l_{ik}^{(m-1)} + w_{kj} \}$** (why?)

Recursive solution to the all-pairs shortest-path problem

- Since shortest path from i to j contains at most $n-1$ edges,
$$\delta(i, j) = l_{ij}^{(n-1)}$$
- Computing the shortest-path weight bottom up:
 - Compute $L^{(1)}, L^{(2)}, \dots, L^{(n-1)}$, where $L^{(m)} = (l_{ij}^{(m)})$ for all i and j
 - Note that $L^{(1)} = W = \text{Adjacency matrix}$.

Example:



$$W = L^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$L^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 2 & -4 \\ 3 & 0 & -4 & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & \infty & 1 & 6 & 0 \end{pmatrix}$$

$$L^{(2)} = L^{(1)} \times W$$

$$L^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \times W = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} = L^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 2 & -4 \\ 3 & 0 & -4 & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & \infty & 1 & 6 & 0 \end{pmatrix}$$

$$l_{ij}^{(2)} = \min_{1 \leq k \leq 5} \{l_{ik}^{(1)} + w_{kj}\}$$

$$= \min \{l_{i1}^{(1)} + w_{1j}, l_{i2}^{(1)} + w_{2j}, l_{i3}^{(1)} + w_{3j}, l_{i4}^{(1)} + w_{4j}, l_{i5}^{(1)} + w_{5j}\}$$

$$l_{14}^{(2)} = \min \{l_{11}^{(1)} + w_{14}, l_{12}^{(1)} + w_{24}, l_{13}^{(1)} + w_{34}, l_{14}^{(1)} + w_{44}, l_{15}^{(1)} + w_{54}\} = \min\{\infty, 4, \infty, \infty, 2\} = 2$$

Matrix Multiplication

Let $l^{(m-1)} \rightarrow a$
 $w \rightarrow b$
 $l^{(m)} \rightarrow c$
 $\min \rightarrow \Sigma$
 $+ \rightarrow \cdot$

$$C_{ij} = \sum_{k=1 \text{ to } n} a_{ik} \cdot b_{kj}$$
$$l_{ij}^{(m)} = \min_{1 \leq k \leq n} \{l_{ik}^{(m-1)} + w_{kj}\}$$

time complexity : $O(n^3)$

$$L^{(3)} = \begin{pmatrix} 0 & 3 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

$$L^{(3)} = L^{(2)} \times W$$

$$L^{(4)} = \begin{pmatrix} 0 & 1 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

$$L^{(4)} = L^{(3)} \times W$$

EXTENDED-SHORTEST-PATHS(L, W)

- Given matrices $L^{(m-1)}$ and W return $L^{(m)}$

```
1  n ← L.row
2  Let  $L' = (l'_{ij})$  be a new  $n \times n$  matrix
3  for i = 1 to n
4    for j = 1 to n
5       $l'_{ij} = \infty$ 
6      for k = 1 to n
7         $l'_{ij} = \min(l'_{ij}, l_{ik} + w_{kj})$ 
8  return  $L'$ 
```

SLOW-ALL-PAIRS-SHORTEST-PATHS(W)

$$L^{(1)} = L^{(0)} \quad \bullet \quad W = W$$

$$L^{(2)} = L^{(1)} \quad \bullet \quad W = W^2$$

$$L^{(3)} = L^{(2)} \quad \bullet \quad W = W^3$$

•

•

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$$L^{(n-1)} = L^{(n-2)} \quad \bullet \quad W = W^{n-1}$$

SLOW-ALL-PAIRS-SHORTEST-PATHS(W)

```
1  n = W.rows
2  L(1) = W
3  for m = 2 to n-1
4      let L(m) be a new n x n matrix
5      L(m) = EXTENDED-SHORTEST-
        PATHS( L(m-1), W )
6  return L(n-1)
```

Time complexity : $O(n^4)$

Improving the running time

$$L^{(1)} = W$$

$$L^{(2)} = W^2 = W \cdot W$$

$$L^{(4)} = W^4 = W^2 \cdot W \cdot W = W^2 \cdot W^2$$

\vdots

$$L^{(n)} = W^n = W^{n/2} \cdot W^{n/2}$$

i.e., using repeating squaring!

Time complexity: $O(n^3 \lg n)$

FASTER-ALL-PAIRS-SHORTEST-PATHS

FASTER-ALL-PAIRS-SHORTEST-PATHS(W)

1. $n = W.\text{row}$
2. $L^{(1)} = W$
3. $m = 1$
4. while $m < n-1$
5. let $L^{(2^m)}$ be a new $n \times n$ matrix
6. $L^{(2^m)} = \text{Extend-Shortest-Path}(L^{(m)}, L^{(m)})$
7. $m = 2m$
8. return $L^{(m)}$

Some Algorithms

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The Floyd-Warshall algorithm

- A different dynamic programming formulation

- The structure of a shortest path:

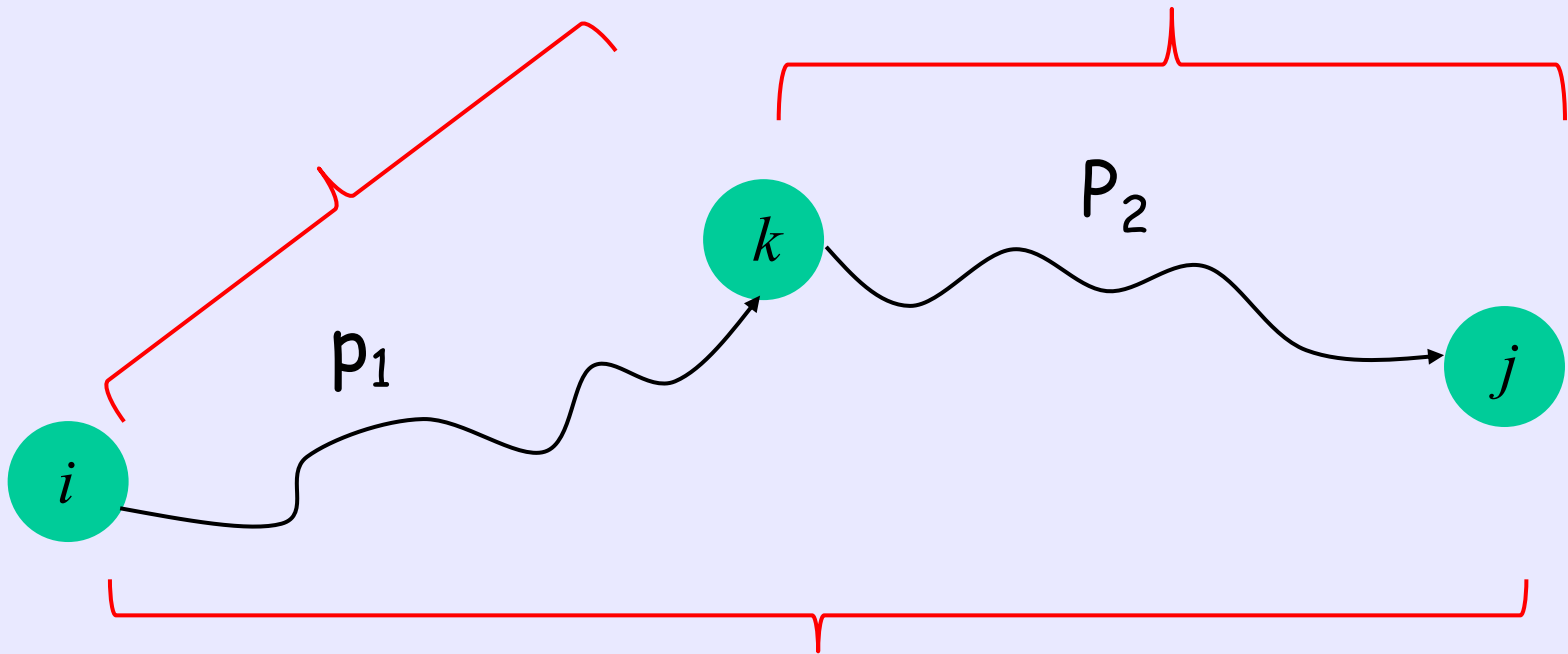
Let $V(G) = \{1, 2, \dots, n\}$. For any pair of vertices $i, j \in V$, consider all paths from i to j whose intermediate vertices are drawn from $\{1, 2, \dots, k\}$, and let p be a minimum weight path among them.

The structure of a shortest path

- If k is not in p , then all intermediate vertices are in $\{1, 2, \dots, k-1\}$.
- If k is an intermediate vertex of p , then p can be decomposed into $i \stackrel{p_1}{\sim} k \stackrel{p_2}{\sim} j$ where p_1 is a shortest path from i to k with all the intermediate vertices in $\{1, 2, \dots, k-1\}$ and p_2 is a shortest path from k to j with all the intermediate vertices in $\{1, 2, \dots, k-1\}$.

p_1 : all intermediate
vertices in $\{1, 2, 3, \dots, k-1\}$

p_2 : all intermediate
vertices in $\{1, 2, 3, \dots, k-1\}$



P : all intermediate vertices in $\{1, 2, 3, \dots, k\}$

A recursive solution to the all-pairs shortest path

- Let $d_{ij}^{(k)}$ = the weight of a shortest path from vertex i to vertex j with all intermediate vertices in the set $\{1, 2, \dots, k\}$.

$$\begin{aligned} d_{ij}^{(k)} &= w_{ij} && \text{if } k = 0 \\ &= \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}) && \text{if } k \geq 1 \end{aligned}$$

$D^{(n)} = (d_{ij}^{(n)})$ the final solution!

FLOYD-WARSHALL(W)

1. $n = W.rows$
2. $D^{(0)} = W$
3. for $k = 1$ to n
4. Let $D^{(k)} = (d_{ij}^{(k)})$ be a new $n \times n$ matrix
5. for $i = 1$ to n
6. for $j = 1$ to n
7. $d_{ij}^{(k)} = \min (d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)})$
8. return $D^{(n)}$

Complexity: $O(n^3)$

Example

$$D^{(0)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$D^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$d_{ij}^{(1)} = \min(d_{ij}^{(0)}, d_{ik}^{(0)} + d_{kj}^{(0)}) \quad k = 1$$

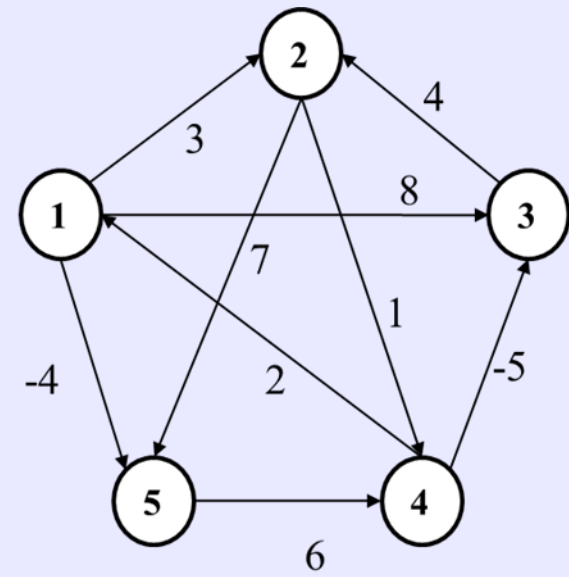
$$d_{41}^{(1)} = \min(d_{41}^{(0)}, d_{41}^{(0)} + d_{11}^{(0)}) = 2$$

$$d_{42}^{(1)} = \min(d_{42}^{(0)}, d_{41}^{(0)} + d_{12}^{(0)}) = 5$$

$$d_{43}^{(1)} = \min(d_{43}^{(0)}, d_{41}^{(0)} + d_{13}^{(0)}) = -5$$

$$d_{44}^{(1)} = \min(d_{44}^{(0)}, d_{41}^{(0)} + d_{14}^{(0)}) = 0$$

$$d_{45}^{(1)} = \min(d_{45}^{(0)}, d_{41}^{(0)} + d_{15}^{(0)}) = -2$$



$$D^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$k = 1$

$$D^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$k = 2$

$$d_{41}^{(2)} = \min (d_{41}^{(1)}, d_{42}^{(1)} + d_{21}^{(1)}) = 2$$

$$d_{42}^{(2)} = \min (d_{42}^{(1)}, d_{42}^{(1)} + d_{22}^{(1)}) = 5$$

$$d_{43}^{(2)} = \min (d_{43}^{(1)}, d_{42}^{(1)} + d_{23}^{(1)}) = -5$$

$$d_{44}^{(2)} = \min (d_{44}^{(1)}, d_{42}^{(1)} + d_{24}^{(1)}) = 0$$

$$d_{45}^{(2)} = \min (d_{45}^{(1)}, d_{42}^{(1)} + d_{25}^{(1)}) = -2$$

$$D^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$k = 2$

$$D^{(3)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$k = 3$

$$d_{41}^{(3)} = \min(d_{41}^{(2)}, d_{43}^{(2)} + d_{31}^{(2)}) = 2$$

$$d_{42}^{(3)} = \min(d_{42}^{(2)}, d_{43}^{(2)} + d_{32}^{(2)}) = -1$$

$$d_{43}^{(3)} = \min(d_{43}^{(2)}, d_{43}^{(2)} + d_{33}^{(2)}) = -5$$

$$d_{44}^{(3)} = \min(d_{44}^{(2)}, d_{43}^{(2)} + d_{34}^{(2)}) = 0$$

$$d_{45}^{(3)} = \min(d_{45}^{(2)}, d_{43}^{(2)} + d_{35}^{(2)}) = -2$$

Constructing a shortest path

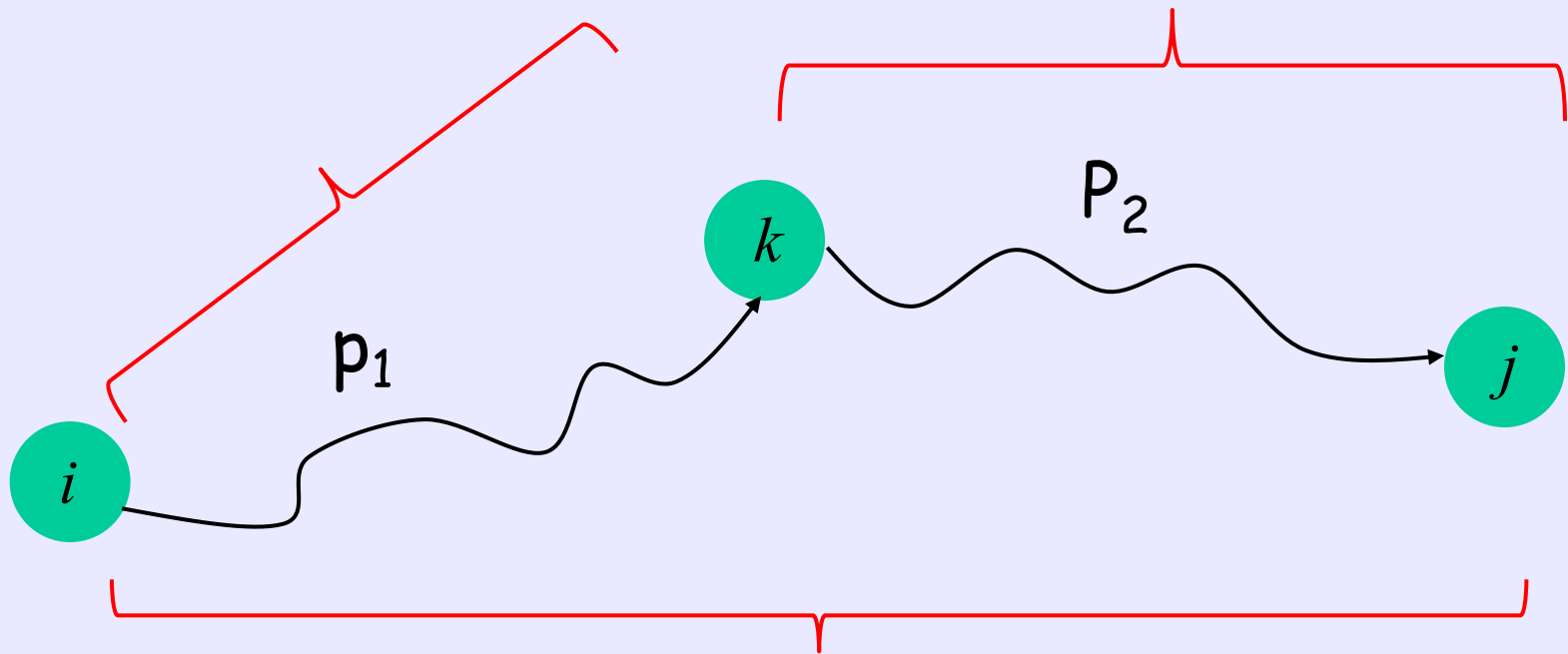
- $\pi^{(0)}, \pi^{(1)}, \dots, \pi^{(n)}$
- $\pi_{ij}^{(k)}$: is the **predecessor** of the vertex j on a shortest path from vertex i with all intermediate vertices in the set $\{1, 2, \dots, k\}$.

$$\begin{aligned}\pi_{ij}^{(0)} &= \text{NIL} \quad \text{if } i=j \text{ or } w_{ij} = \infty \\ &= i \quad \text{if } i \neq j \text{ and } w_{ij} < \infty\end{aligned}$$

$$\begin{aligned}\pi_{ij}^{(k)} &= \pi_{ij}^{(k-1)} \quad \text{if } d_{ij}^{(k-1)} \leq d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \\ &= \pi_{kj}^{(k-1)} \quad \text{if } d_{ij}^{(k-1)} > d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\end{aligned}$$

p_1 : all intermediate
vertices in $\{1, 2, 3, \dots, k-1\}$

p_2 : all intermediate
vertices in $\{1, 2, 3, \dots, k-1\}$



P : all intermediate vertices in $\{1, 2, 3, \dots, k\}$

Example

$$D^{(0)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$D^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$\Pi^{(0)} = \begin{pmatrix} N & 1 & 1 & N & 1 \\ N & N & N & 2 & 2 \\ N & 3 & N & N & N \\ 4 & N & 4 & N & N \\ N & N & N & 5 & N \end{pmatrix}$$

$$\Pi^{(1)} = \begin{pmatrix} N & 1 & 1 & N & 1 \\ N & N & N & 2 & 2 \\ N & 3 & N & N & N \\ 4 & 1 & 4 & N & 1 \\ N & N & N & 5 & N \end{pmatrix}$$

$K=1$

$$\begin{aligned} \pi_{ij}^{(1)} &= \pi_{ij}^{(0)} \quad \text{if } d_{ij}^{(0)} \leq d_{ik}^{(0)} + d_{kj}^{(0)} \\ &= \pi_{1j}^{(0)} \quad \text{if } d_{ij}^{(0)} > d_{i1}^{(0)} + d_{1j}^{(0)} \end{aligned}$$

Example

$$D^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$D^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$\Pi^{(1)} = \begin{pmatrix} N & 1 & 1 & N & 1 \\ N & N & N & 2 & 2 \\ N & 3 & N & N & N \\ 4 & 1 & 4 & N & 1 \\ N & N & N & 5 & N \end{pmatrix}$$

$K=1$

$$\Pi^{(2)} = \begin{pmatrix} N & 1 & 1 & 2 & 1 \\ N & N & N & 2 & 2 \\ N & 3 & N & 2 & 2 \\ 4 & 1 & 4 & N & 1 \\ N & N & N & 5 & N \end{pmatrix}$$

$K=2$

$$\begin{aligned} \pi_{ij}^{(2)} &= \pi_{ij}^{(1)} \quad \text{if } d_{ij}^{(1)} \leq d_{i2}^{(1)} + d_{2j}^{(1)} \\ &= \pi_{2j}^{(1)} \quad \text{if } d_{ij}^{(1)} > d_{i2}^{(1)} + d_{2j}^{(1)} \end{aligned}$$

$$D^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & \boxed{5} & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$D^{(3)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & \boxed{-1} & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$\Pi^{(2)} = \begin{pmatrix} N & 1 & 1 & 2 & 1 \\ N & N & N & 2 & 2 \\ N & \boxed{3} & N & 2 & 2 \\ 4 & 1 & 4 & N & 1 \\ N & N & N & 5 & N \end{pmatrix} \quad K = 2$$

$$\Pi^{(3)} = \begin{pmatrix} N & 1 & 1 & 2 & 1 \\ N & N & N & 2 & 2 \\ N & 3 & N & 2 & 2 \\ 4 & \boxed{3} & 4 & N & 1 \\ N & N & N & 5 & N \end{pmatrix} \quad K = 3$$

$$\begin{aligned} \pi_{ij}^{(k)} &= \pi_{ij}^{(k-1)} \quad \text{if } d_{ij}^{(k-1)} \leq d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \\ &= \pi_{kj}^{(k-1)} \quad \text{if } d_{ij}^{(k-1)} > d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \end{aligned}$$

$$D^{(4)} = \begin{pmatrix} 0 & 3 & -1 & 4 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

$$D^{(5)} = \begin{pmatrix} 0 & 1 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

$$\Pi^{(4)} = \begin{pmatrix} N & 1 & 4 & 2 & 1 \\ 4 & N & 4 & 2 & 1 \\ 4 & 3 & N & 2 & 1 \\ 4 & 3 & 4 & N & 1 \\ 4 & \boxed{3} & 4 & \boxed{5} & N \end{pmatrix} \quad K = 4$$

$$\Pi^{(5)} = \begin{pmatrix} N & \boxed{3} & 4 & \boxed{5} & 1 \\ 4 & N & 4 & 2 & 1 \\ 4 & 3 & N & 2 & 1 \\ 4 & 3 & 4 & N & 1 \\ 4 & 3 & 4 & 5 & N \end{pmatrix} \quad K = 5$$

For example:

The shortest path from 1 → 2 is: 1 → 5 → 4 → 3 → 2

The shortest path from 2 → 1 is: 2 → 4 → 1

The shortest path from 5 → 2 is: 5 → 4 → 3 → 2

Transitive-Closure of a Directed Graph

- Given a directed graph $G=(V, E)$ with $V=\{1, 2, \dots, n\}$
- We might wish to determine whether G contains a path from i to j for all vertex pairs $i, j \in V$.
- We define the transitive closure of G as the graph $G^* = (V, E^*)$, where $E^* = \{(i, j): \text{there is a path from vertex } i \text{ to vertex } j \text{ in } G\}$

Transitive closure of a directed graph

- Given a directed graph $G = (V, E)$ with $V = \{1, 2, \dots, n\}$
- The transitive closure of G is $G^* = (V, E^*)$ where $E^* = \{(i, j) \mid \text{there is a path from } i \text{ to } j \text{ in } G\}$.

Modify FLOYD-WARSHALL algorithm:

$$t_{ij}^{(0)} = \begin{cases} 0 & \text{if } i \neq j \text{ and } (i, j) \notin E \\ 1 & \text{if } i = j \text{ or } (i, j) \in E \end{cases}$$

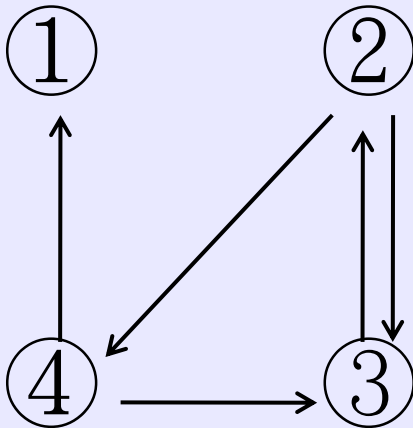
for $k \geq 1$

$$t_{ij}^{(k)} = t_{ij}^{(k-1)} \vee (t_{ik}^{(k-1)} \wedge t_{kj}^{(k-1)})$$

Example

$$T^{(0)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix}$$

$$T^{(1)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix} \quad K=1$$



$$T^{(2)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \end{pmatrix} \quad K=2$$

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$$T^{(4)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix} \quad K=4$$

$$t_{ij}^{(k)} = t_{ij}^{(k-1)} \vee (t_{ik}^{(k-1)} \wedge t_{kj}^{(k-1)})$$

TRANSITIVE-CLOSURE(G)

```
1   $n = |G.V|$ 
2  Let  $T^{(0)} = (t_{ij}^{(0)})$  be a new  $n \times n$  matrix
3  for  $i = 1$  to  $n$ 
4      for  $j = 1$  to  $n$ 
5          if  $i == j$  or  $(i, j) \in G.E$ 
6               $t_{ij}^{(0)} = 1$ 
7          else  $t_{ij}^{(0)} = 0$ 
8  for  $k = 1$  to  $n$ 
9      Let  $T^{(k)} = (t_{ij}^{(k)})$  be a new  $n \times n$  matrix
10     for  $i = 1$  to  $n$ 
11         for  $j = 1$  to  $n$ 
12              $t_{ij}^{(k)} = t_{ij}^{(k-1)} \vee (t_{ik}^{(k-1)} \wedge t_{kj}^{(k-1)})$ 
123 return  $T^{(n)}$ 
```

Time complexity: $O(n^3)$

Some Algorithms

- ✓ When no negative edges
 - Using Dijkstra's algorithm: $O(V^3)$
 - Using Binary heap implementation: $O(VE \lg V)$
 - Using Fibonacci heap: $O(VE + V^2 \log V)$
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 - Floyd-Warshall [1962]: $O(V^3)$ time
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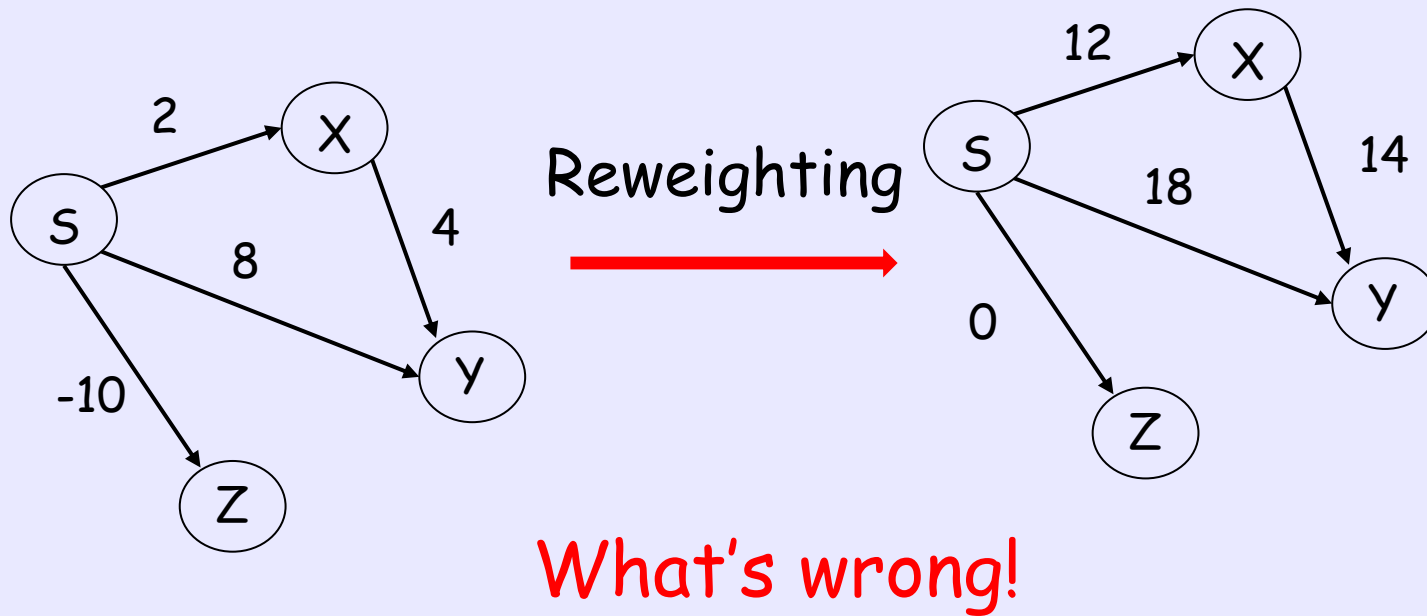
Johnson's algorithm for **sparse graphs**

- For sparse graphs, it is asymptotically faster than either repeated squaring of matrices or the Floyd-Warshall algorithm
- **Using reweighting technique**

Reweighting technique

- If G has negative-weighted edge, we compute a new set of nonnegative weight that allows us to use the same method. The new set of edge weight \hat{w} satisfies:
 1. For all pairs of vertices $u, v \in V$, a shortest path from u to v using weight function w is also a shortest path from u to v using the weight function \hat{w}
 2. $\forall (u,v) \in E(G), \hat{w}(u,v)$ is nonnegative

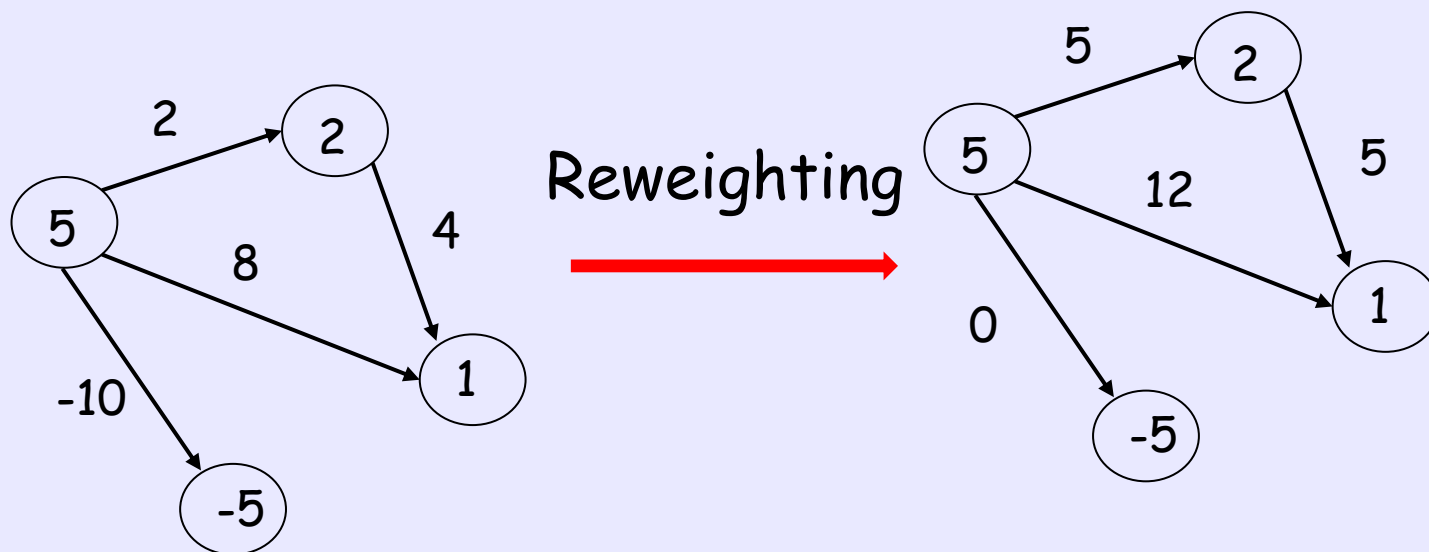
Reweighting Example



Lemma: (Reweighting doesn't change shortest paths)

- Given a weighted directed graph $G = (V, E)$ with weight function $w: E \rightarrow \mathbb{R}$, let $h: V \rightarrow \mathbb{R}$ be any function mapping vertices to real numbers. For each edge $(u, v) \in E$, $\hat{w}(u, v) = w(u, v) + h(u) - h(v)$

e.g.



Lemma: (Reweighting doesn't change shortest paths)

- Let $p = \langle v_0, v_1, \dots, v_k \rangle$
- Then $w(p) = \delta(v_0, v_k)$ if and only if $\hat{w}(p) = \hat{\delta}(v_0, v_k)$. Also, G has a negative-weight cycle using weight function w iff G has a negative weight cycle using weight function \hat{w} .
- Question: how to setting the value of $h(v_i)$ for all i ?

Proof

- First, we show that $\hat{w}(p) = w(p) + h(v_0) - h(v_k)$

$$\hat{w}(p) = \sum_{i=1}^k \hat{w}(v_{i-1}, v_i)$$

$$= \sum_{i=1}^k (w(v_{i-1}, v_i) + h(v_{i-1}) - h(v_i))$$

$$= \sum_{i=1}^k w(v_{i-1}, v_i) + h(v_0) - h(v_k)$$

$$= w(p) + h(v_0) - h(v_k)$$

Proof

- Because $h(v_0)$ and $h(v_k)$ do not depend on the path, if one path from v_0 to v_k is shorter than another using weight function w , then it is also shorter using \hat{w} . Thus,

$$\begin{aligned} w(p) = \delta(v_0, v_k) \text{ if and only if } \hat{w}(p) &= \bar{\delta}(v_0, v_k) \\ &= w(p) + h(v_0) - h(v_k) \end{aligned}$$

Proof

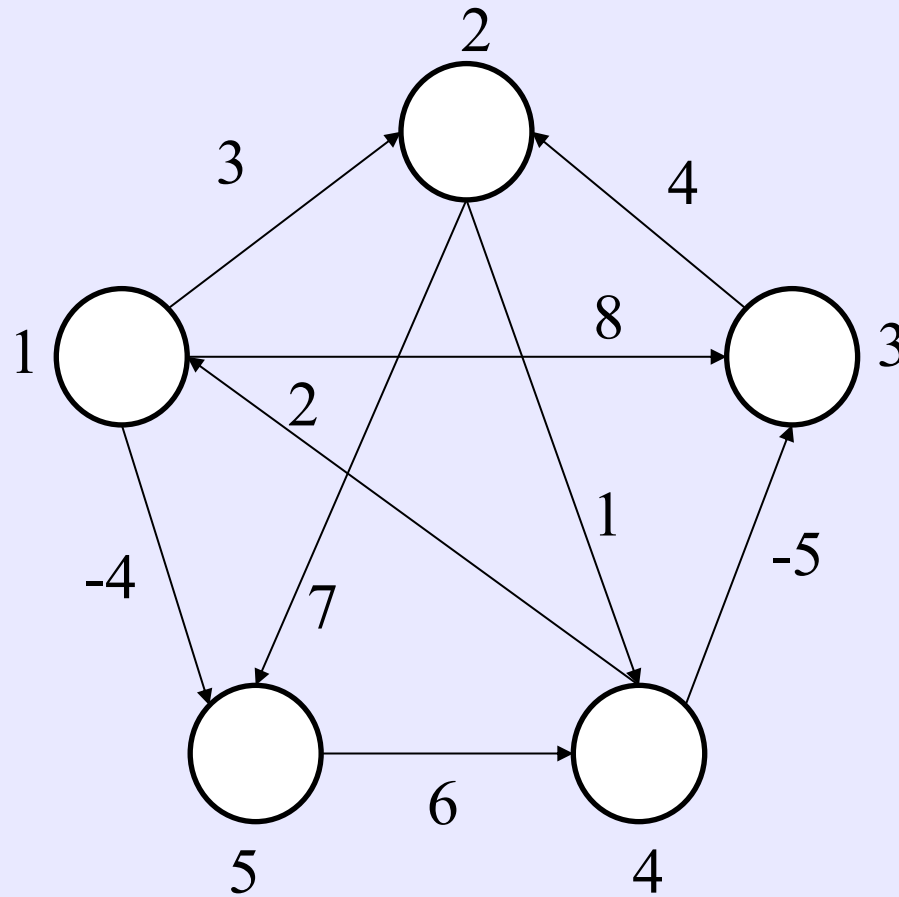
- G has a negative-weight cycle using w iff G has a negative-weight cycle using \hat{w} .
- Consider any cycle $C = \langle v_0, v_1, \dots, v_k \rangle$ with $v_0 = v_k$. Then $\hat{w}(C) = w(C) + h(v_0) - h(v_k) = w(C)$.

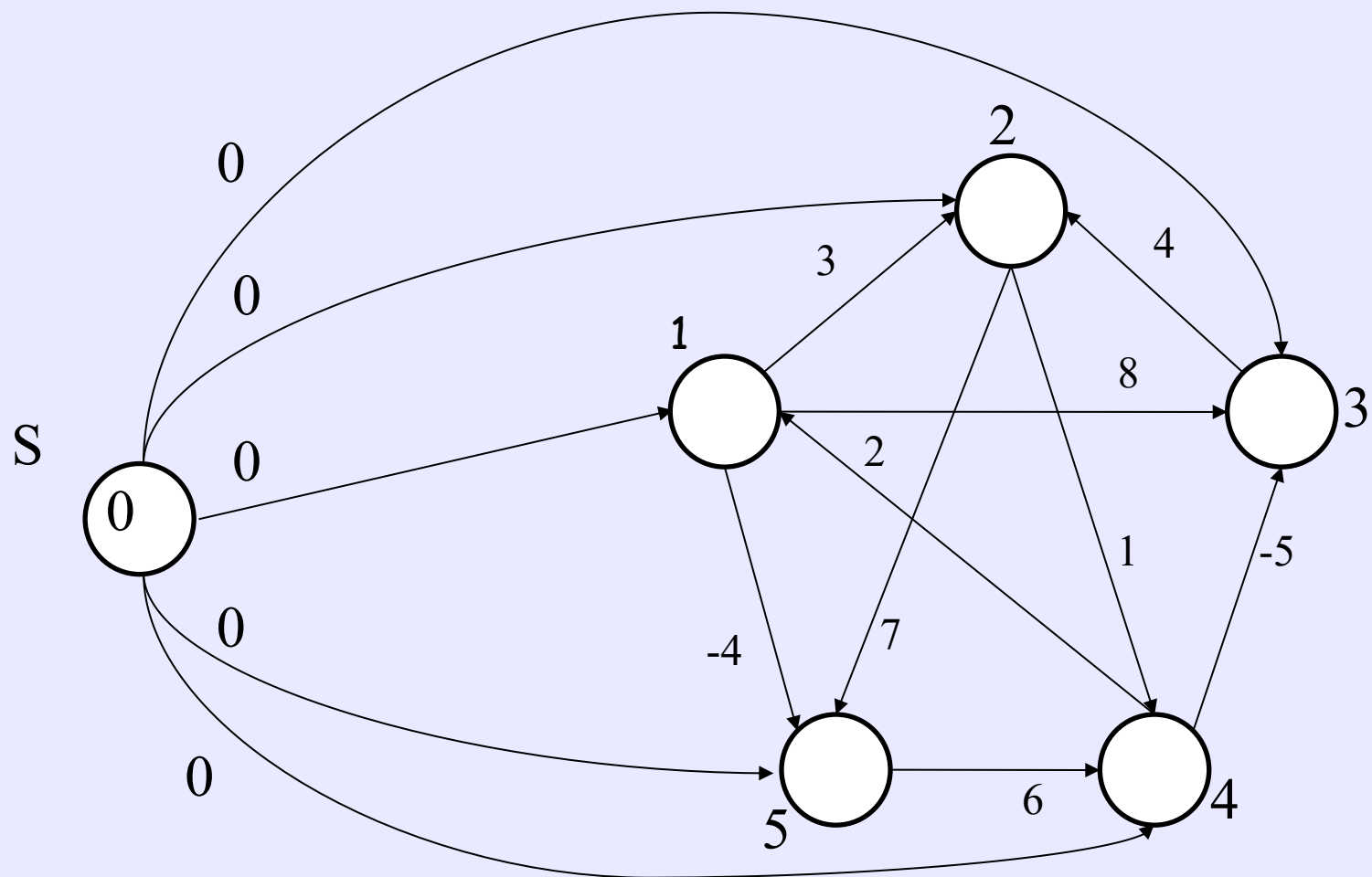
Question: how to setting the value of $h(v_i)$ for all i ?

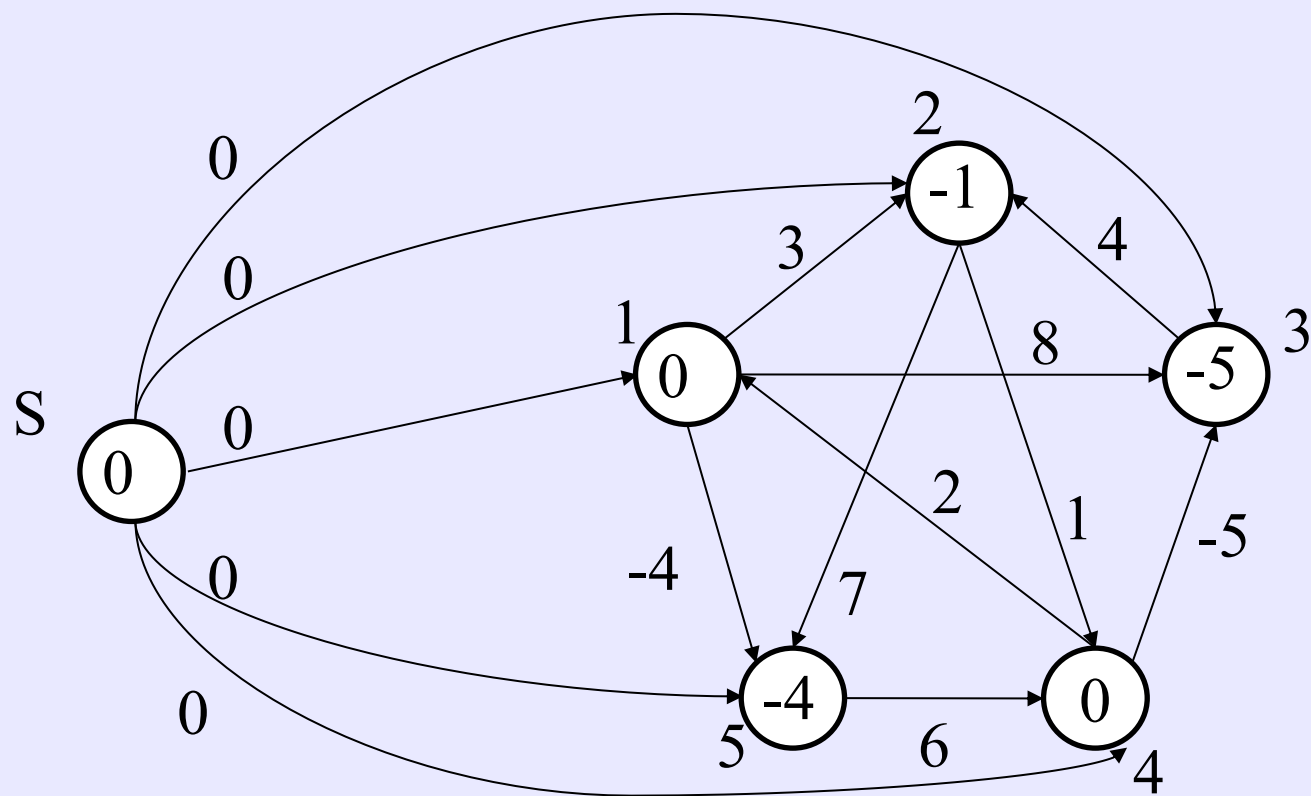
Producing nonnegative weight by reweighting

- Given a weighted directed graph $G = (V, E)$
- We make a new graph $G' = (V', E')$, $V' = V \cup \{s\}$, $E' = E \cup \{(s, v) : v \in V\}$ and $w(s, v) = 0$, for all v in V
- Let $h(v) = \delta(s, v)$ for all $v \in V$
- We have $h(v) \leq h(u) + w(u, v)$ if there is no negative weight cycle (why?)
- $\hat{w}(u, v) = w(u, v) + h(u) - h(v) \geq 0$

Example:

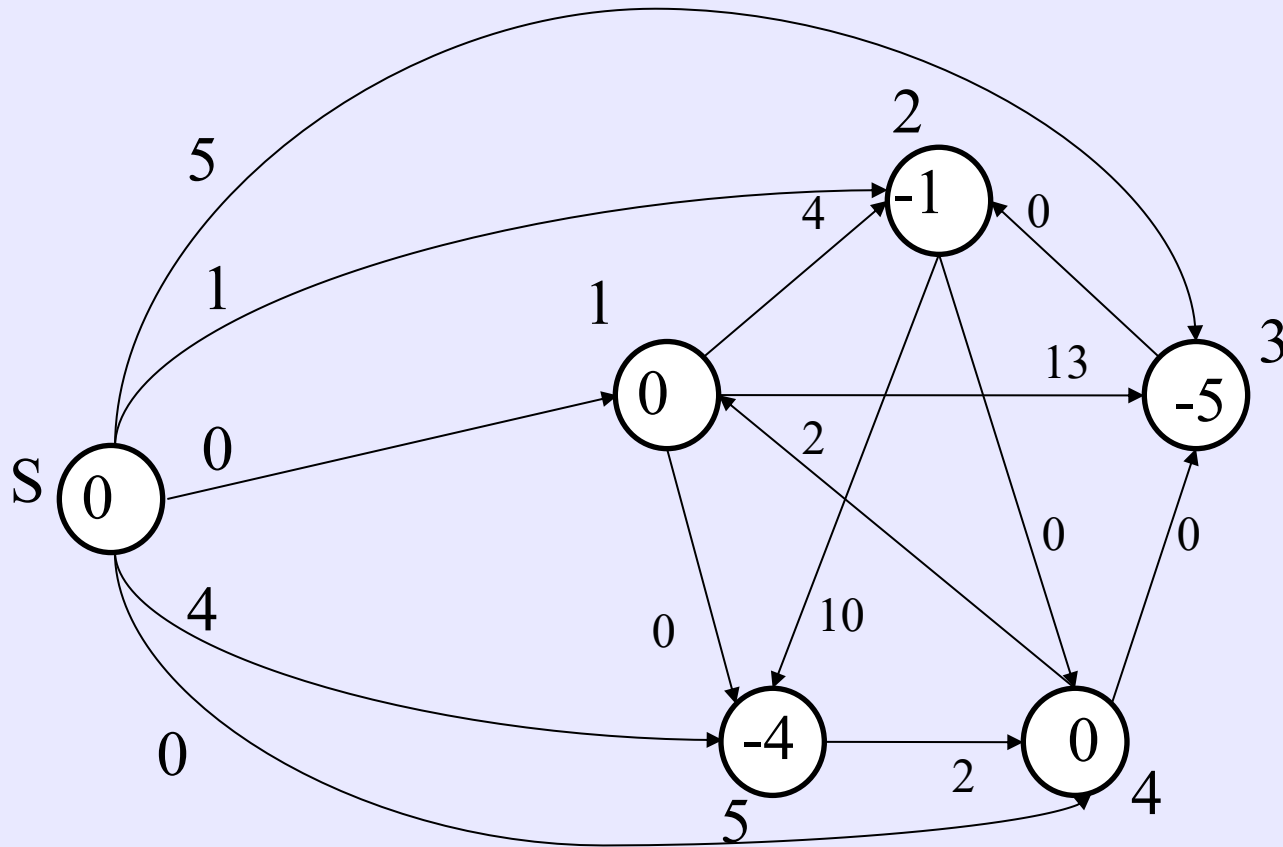






$$h(v) = \delta(s, v)$$

$$\hat{w}(u, v) = w(u, v) + h(u) - h(v) \geq 0$$



JOHNSON algorithm

- 1 Computing G' , where $G'.V = G.V \cup \{s\}$
and $G'.E = G.E \cup \{(s, v) : v \in G.V\}$ and $w(s, v) = 0$.
- 2 if **BELLMAN-FORD(G', w, s) = FALSE**
- 3 print "the input graph contains negative weight cycle"
- 4 else for each vertex $v \in G'.V$
- 5 set $h(v)$ to be the value of $\delta(s, v)$ computed by the BF algorithm
- 6 for each edge $(u, v) \in G'.E$, $\hat{w}(u, v) = w(u, v) + h(u) - h(v)$

JOHNSON algorithm

```
7  Let  $D = (d_{uv})$  be a new  $n \times n$  matrix
8  for each vertex  $u \in G.V$ 
    run DIJKSTRA ( $G, \hat{w}, u$ ) to compute  $\hat{\delta}(u, v)$ 
    for all  $v \in V[G]$ .
10 for each vertex  $v \in G.V$ 
11      $d_{uv} = \hat{\delta}(u, v) + h(v) - h(u)$ 
12 return  $D$ 
```

Complexity: Using Fibonacci heap $O(V^2 \lg V + VE)$

Using Binary heap implementation: $O(VE \lg V)$

Practice at home

- Exercises: 23.1-7, 23.1-9*, 23.1-10, 23.2-1*, 23.2-4, 23.2-6*, 23.2-8*, 23.3-1, 23.3-2*, 23.3-3, 23.3-5*, 23.3-6

Quiz

- For all-to-all shortest paths with no negative edges
 - The time complexity of using Dijkstra's algorithm with array is $O(?)$
 - The time complexity of using Binary heap implementation is $O(?)$
- When no negative **cycles**
 - The time complexity of Floyd-Warshall is $O(?)$