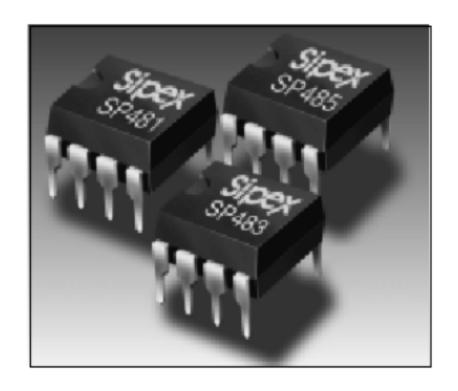


SP481/SP483/SP485

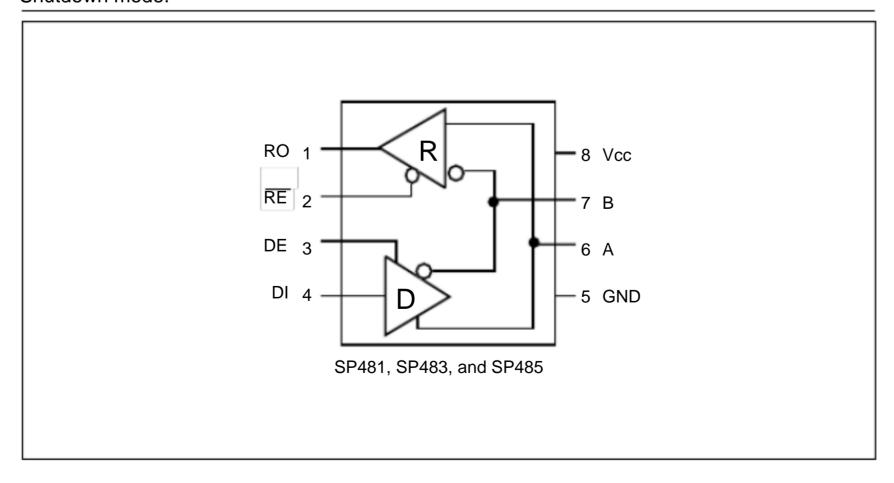
Low Power Half-Duplex RS-485 Transceivers

+5V Only
Low Power BiCMOS
Driver/Receiver Enable
Slew Rate Limited Driver for
Low EMI (SP483)
Low Power Shutdown Mode (SP481
and SP483)
RS-485 and RS-422 Drivers/Receivers



DESCRIPTION

The SP481, SP483, and the SP485 are a family of half-duplex transceivers that meet the requirements of RS-485 and RS-422. Their BiCMOS design allows low power operation without sacrificing performance. The SP481 and SP485 meet the requirements of RS-485 and RS-422 up to 5Mbps. Additionally, the SP481 is equipped with a low power Shutdown mode. The SP483 is internally slew rate limited to reduce EMI and can meet the requirements of RS-485 and RS-422 up to 250kbps. The SP483 is also equipped with a low power Shutdown mode.



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These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

V _{cc}	±12V
Input Voltages	
Logic	0.3V to (V _{cc} +0.5V)
Drivers.	0.3V to (V cc +0.5V)
Receive	rs ±15V
Output Voltages	
Logic	0.3V to (V _{cc} +0.5V)
Drivers.	±15V
Receive	rs0.3V to (V _{cc} +0.5V)
Storage Temperature	65?C to +150?C
	500mW

SPECIFICATIONS

 $T_{_{MIN}}$ to $T_{_{MAX}}$ and $V_{_{CC}}$ = 5V ±5% unless otherwise noted.

PARAMETERS	MIN.	TYP.	MAX.	UNITS	CONDITIONS
SP481/SP483/SP485 DRIVER					
DC Characteristics					
Differential Output Voltage	GND		V _{cc}	Volts	Unloaded; R = ; see figure 1
Differential Output Voltage	2		V _{cc}	Volts	with load; R = 50 ?; (RS422);
					see figure 1
Differential Output Voltage	1.5		V_{cc}	Volts	with load; R = 27?; (RS485); see figure 1
Change in Magnitude of Driver					
Differential Output Voltage for					
Complimentary States			0.2	Volts	R = 27 ? or R = 50 ?; see figure 1
Driver Common-Mode					
Output Voltage			3	Volts	R = 27 ? or R = 50 ?; see figure 1
Input High Voltage	2.0			Volts	Applies to DE, DI, RE
Input Low Voltage			0.8	Volts	Applies to DE, DI, RE
Input Current			±10	Aµ	Applies to DE, DI, RE
Driver Short-Circuit Current	25		250	_{m ^}	71/ 1/ 1401/
V _{OUT} = HIGH	35 35		250 250	mA	-7V V _O +12V
V _{OUT} = LOW	35		250	mA	-7V V _O +12V
SP481/SP485 DRIVER					
AC Characteristics					
Maximum Data Rate	5			Mbps	RE = 5V, DE = 5V
Driver Input to Output	20	30	60	ns	$t_{PLH}; R_{DIFF} = 54?, C_{L1} = C_{L2} = 100pF;$
					see figures 3 and 6
Driver Input to Output	20	30	60	ns	t_{PHL} ; $R_{DIFF} = 54$?, $C_{L1} = C_{L2} = 100pF$;
D. in case Olympia		_	40		see figures 3 and 6
Driver Skew		5	10	ns	see figures 3 and 6,
Driver Rise or Fall Time	3	15	40	no	t _{SKEW} = t _{DPLH} - t _{DPHL}
Driver Rise of Fall Time	3	15	40	ns	From 10% to 90%; R DIFF = 54?,
Driver Enable to Output High		40	70	ns	$C_{L1} = C_{L2} = 100 \text{pF}$; see figures 3 and 6 $C_{L} = 100 \text{pF}$; see figures 4 & 7; S ₂ closed
Driver Enable to Output Low		40	70	ns	$C_1 = 100$ pF; see figures 4 & 7; S_2 closed $C_1 = 100$ pF; see figures 4 & 7; S_1 closed
Driver Disable Time from Low		40	70	ns	$C_1 = 15pF$; see figures 2 & 9; S_1 closed
Driver Disable Time from High		40	70	ns	$C_1 = 15pF$; see figures 2 & 9; S_2 closed
					ot ropr, occurgated to a c, og stoccu
SP481/SP483/SP485 RECEIVE	R				
DC Characteristics					
Differential Input Threshold	-0.2		+0.2	Volts	-7V V _{CM} +12V
Input Hysteresis		10		mV	$V_{CM} = 0V$
Output Voltage High	3.5			Volts	$I_{O} = -4mA, V_{ID} = +200mV$
Output Voltage Low			0.4	Volts	$I_O = +4mA$, $V_{ID} = -200mV$
Three-State (High Impedance)					
Output Current	,_		<u></u> ±1	Aµ	$0.4V V_0 2.4V; RE = 5V$
Input Resistance	12	15		k?	-7V V _{CM} +12V
Input Current (A, B); V _{IN} = 12V			+1.0	mA	DE = 0V, V $_{CC}$ = 0V or 5.25V, V $_{IN}$ = 12V
Input Current (A, B); V IN = -7V	-		-0.8	mA	DE = 0V, V $_{CC}$ = 0V or 5.25V, V $_{IN}$ = -7V
Short-Circuit Current	7		95	mA	0V V _{CM} V _{CC}

元器件交易网 www.cecb2b.com SPECIFICATIONS (continued)

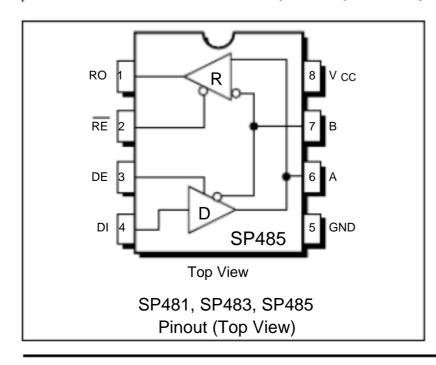
 T_{MIN} to T_{MAX} and $V_{CC} = 5V$ ±5% unless otherwise noted.

$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	AC Characteristics Maximum Data Rate Receiver Input to Output Receiver Input to Output Diff. Receiver Skew It Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
AC Characteristics Maximum Data Rate Receiver Input to Output 60 90 200 ns $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	AC Characteristics Maximum Data Rate Receiver Input to Output Receiver Input to Output Diff. Receiver Skew It PLH -t PHL Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Maximum Data Rate Receiver Input to Output Receiver Input to Output Diff. Receiver Skew It PLH-tPHL Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Maximum Data Rate Receiver Input to Output Receiver Input to Output Diff. Receiver Skew It PLH-tPHL Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
Receiver Input to Output 60 90 200 ns t_{pLH} ; $R_{\text{DIFF}} = 54?$, $C_{\text{L}_1} = C_{\text{L}_2} = 100\text{pF}$; Figures 3 & 8 the position of	Receiver Input to Output Receiver Input to Output Diff. Receiver Skew It PLH-tPHL Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
Receiver Input to Output Receiver Skew It PLH - t_{PLH} I 13	Receiver Input to Output Diff. Receiver Skew It PLH-tPHL Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
Receiver Input to Output $\begin{array}{c} 60 \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ $	Diff. Receiver Skew It PLH-tPHL Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
Receiver Input to Output Diff. Receiver Skew It PLH-tPHL I Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from High SP481 Receiver Input to Output High Shutdown to Output High Driver Enable from Shutdown Time to Shutdown Diff. Receiver Input to Output High Shutdown to Output High Shutdown Time to Shutdown Driver Enable from Shutdown	Diff. Receiver Skew It PLH-tPHL Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
Diff. Receiver Skew It PLH-tend It Receiver Skew It PLH-tend It PL	Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
Diff. Receiver Skew It PLH-tPHL I Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from High SP481 Shutdown Timing Time to Shutdown to Output High Driver Enable from Shutdown To Output High Time to	Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from High Sp481 Shutdown Timing Time to Shutdown to Output High Driver Enable from Shutdown To Shutdown Timing Time to Shutdown Timing Driver Enable from Shutdown To Shutdown Timing And Timing Time to Shutdown Timing Time Time Time Time Time Time Time Time	Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Output Low Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High $\begin{bmatrix} 20 & 50 & ns & C_{RL} = 15pF; Figures 2 \& 9; S_2 closed \\ 20 & 50 & ns & C_{RL} = 15pF; Figures 2 \& 9; S_1 closed \\ 20 & 50 & ns & C_{RL} = 15pF; Figures 2 \& 9; S_2 closed \\ \end{bmatrix}$ SP481 Shutdown Timing Time to Shutdown Driver Enable from Shutdown to Output High Driver Enable from Shutdown $\begin{bmatrix} 50 & 200 & 600 & ns & \overline{RE} = 5V, DE = 0V \\ 40 & 100 & ns & C_L = 100pF; See figures 4 \& 7; S_2 closed \\ \end{bmatrix}$	Receiver Enable to Output High Receiver Disable from Low Receiver Disable from High
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Output High Receiver Disable from Low Receiver Disable from High
Receiver Disable from Low Receiver Disable from High 20 50 ns C _{RL} = 15pF; Figures 2 & 9; S ₁ closed C _{RL} = 15pF; Figures 2 & 9; S ₂ closed SP481 Shutdown Timing Time to Shutdown Driver Enable from Shutdown to Output High Driver Enable from Shutdown To Output High Driver Enable from Shutdown The control of the	Receiver Disable from Low Receiver Disable from High
Receiver Disable from Low Receiver Disable from High $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Receiver Disable from High
Receiver Disable from High 20 50 ns $C_{RL} = 15pF$; Figures 2 & 9; S_2 closed SP481 Shutdown Timing Time to Shutdown 50 200 600 ns $\overline{RE} = 5V$, $DE = 0V$ Driver Enable from Shutdown to Output High 40 100 ns $C_L = 100pF$; See figures 4 & 7; S_2 closed	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	
Shutdown Timing Time to Shutdown Driver Enable from Shutdown to Output High Driver Enable from Shutdown	SP481
Shutdown Timing Time to Shutdown Driver Enable from Shutdown to Output High Driver Enable from Shutdown Time to Shutdown $C_L = 100pF$; See figures 4 & 7; S ₂ clos	C. 101
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Time to Shutdown Driver Enable from Shutdown to Output High Driver Enable from Shutdown Driver Enable from Shutdown $A = A = A = A = A = A = A = A = A = A $	Shutdown Timina
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to Output High Driver Enable from Shutdown 40 100 ns $C_L = 100pF$; See figures 4 & 7; S_2 clos	
Driver Enable from Shutdown	
10 0 alpat 2011 10 10 10 10 10 10 10	
Receiver Enable from	•
Shutdown to Output High 300 1000 ns C ₁ = 15pF; See figures 2 & 9; S ₂ close	
Receiver Enable from	
Shutdown to Output Low 300 1000 ns $C_1 = 15pF$; See figures 2 & 9; S_1 close	
POWER REQUIREMENTS	POWER REQUIREMENTS
	117
Supply Current SP481/485	
	No Load
$A \mu$ RE = 0V, DI = 0V or 5V; DE = 0V	CD402
	No Load
SP481/SP483 A μ RE=0V, DI = 0V or 5V; DE = 0V	SD481/SD482
Shutdown Mode $10 A\mu DE = 0V, \overline{RE} = V_{CC}$	
	Shalaowh Mode
ENVIRONMENTAL AND	ENVIDONMENTAL AND
ENVIRONMENTAL AND	_
Operating Temperature	
Commercial (_C_) 0 +70 C	` ,
Industrial (_E_) -40 +85 C	`
Storage Temperature -65 +150 C	Storage Lemperature
	Daalaaaa
	Package
NSOIC (_N)	Plastic DIP (_S)

元器件交易网 www.cecb2b.com SP483 AC SPECIFICATIONS

 T_{min} to T_{max} and V_{cc} = 5V $\pm 5\%$ unless otherwise noted.

PARAMETERS	MIN.	TYP.	MAX.	UNITS	CONDITIONS
SP483 DRIVER					
AC Characteristics	h				
Maximum Data Rate	250			kbps	
Driver Input to Output	250	800	2000	ns	t_{PLH} ; $R_{DIFF} = 54$?, $C_{L1} = C_{L2} = 100pF$;
Driver Skew	250	800	2000	ns	see figures 3 & 6 t_{PHL} ; $R_{DIFF} = 54$?, $C_{L1} = C_{L2} = 100pF$;
Dilver okew	230		2000	113	see figures 3 & 6
Driver Rise and Fall Time		100	800	ns	see figures 3 & 6,
	250		2000	ns	$t_{SKEW} = t_{DPLH} - t_{DPHL} $ From 10% to 90%; R DIFF = 54?,
	250		2000	113	$C_{11} = C_{12} = 100 \text{pF}$, see figures 3 & 6
Driver Enable to Output High	250		2000	ns	$C_{L} = 100 \text{pF}$; See figures 4 & 7; S_{2} closed
Driver Enable to Output Low	250		2000	ns	$C_L = 100pF$; See figures 4 & 7; S_1 closed
Driver Disable Time from Low	300		3000	ns	$C_L = 15pF$; See figures 4 & 7; S_1 closed
Driver Disable Time from High	300		3000	ns	$C_L = 15pF$; See figures 4 & 7; S_2 closed
SP483 RECEIVER					
AC Characteristics					
Maximum Data Rate	250			kbps	
Receiver Input to Output	250		2000	ns	t_{PLH} ; $R_{DIFF} = 54$?, $C_{L1} = C_{L2} = 100pF$;
Treesiver input to eutput	200		2000	"	Figures 3 & 8
Diff. Receiver Skew It _{PLH} -t _{PHL} I		100		ns	$R_{DIFF} = 54?$, $C_{L1} = C_{L2} = 100pF$;
Receiver Enable to					Figures 3 & 8
Output Low		20	50	l ns	C _{RL} = 15pF; Figures 2 & 9; S ₁ closed
Receiver Enable to		-			SRL = 10p1 , 1 1gui se = 51 e, e, e, olosed
Output High		20	50	ns	C _{RL} = 15pF; Figures 2 & 9; S ₂ closed
Receiver Disable from Low		20	50	ns	C _{RL} = 15pF; Figures 2 & 9; S ₁ closed
Receiver Disable from High		20	50	ns	C _{RL} = 15pF; Figures 2 & 9; S ₂ closed
SP483					
Shutdown Timing					
Time to Shutdown	50	200	600	ns	RE = 5V, DE = 0V
Driver Enable from Shutdown	"		""		
to Output High			2000	ns	$C_L = 100pF$; See figures 4 & 7; S_2 closed
Driver Enable from Shutdown to Output Low			2000	ns	C _L = 100pF; See figures 4 & 7; S ₁ closed
Receiver Enable from					
Shutdown to Output High			2500	ns	$C_L = 15pF$; See figures 4 & 7; S_2 closed
Receiver Enable from Shutdown to Output Low			2500	ns	$C_1 = 15pF$; See figures 4 & 7; S_1 closed
İ					



PIN FUNCTION

Pin#	Name	Description
1	RO	Receiver Output.
2	RE	Receiver Output Enable
		Active LOW.
3	DE	Driver Output Enable
		Active HIGH.
4	DI	Driver Input.
5	GND	Ground Connection.
6	Α	Driver Output/Receiver Input
		Non-inverting.
7	В	Driver Output/Receiver Input
		Inverting.
8	Vcc	Positive Supply 4.75V <vcc< 5.25v.<="" td=""></vcc<>

元器件交易网 www.cecb2b.com DESCRIPTION SP481, SP483, SP485

The SP481, SP483, and SP485 are half-duplex differential transceivers that meet the requirements of RS-485 and RS-422. Fabricated with a Sipex proprietary BiCMOS process, all three products require a fraction of the power of older bipolar designs.

The RS-485 standard is ideal for multi-drop applications and for long-distance interfaces. RS-485 allows up to 32 drivers and 32 receivers to be connected to a data bus, making it an ideal choice for multi-drop applications. Since the cabling can be as long as 4,000 feet, RS-485 transceivers are equipped with a wide (-7V to +12V) common mode range to accommodate ground potential differences. Because RS-485 is a differential interface, data is virtually immune to noise in the transmission line.

Drivers SP481, SP483, SP485

The driver outputs of the SP481, SP483, and SP485 are differential outputs meeting the RS-485 and RS-422 standards. The typical voltage output swing with no load will be 0 volts to +5 volts. With worst case loading of 54 across the differential outputs, the drivers can maintain greater than 1.5V voltage levels. The drivers of the SP481, SP483 and SP485 have an enable control line which is active HIGH. A logic HIGH on DE (pin 5) will enable the differential driver outputs. A logic LOW on DE (pin 5) will tri-state the driver outputs.

The transmitters of the SP481 and SP485 will operate up to at least 5Mbps. The SP483 has internally slew rate limited driver outputs to minimize EMI. The maximum data rate for the SP483 driver is 250kbps.

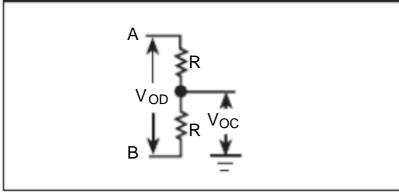
Receivers SP481, SP483, SP485

The SP481, SP483, and SP485 receivers have differential inputs with an input sensitivity as low as ±200mV. Input impedance of the receivers is typically 15k? (12k? minimum). A wide common mode range of -7V to +12V allows for large ground potential differences between systems. The receivers of the SP481, SP483 and SP485 have a tri-state enable control pin. A logic LOW on RE (pin 4) will enable the receiver, a logic HIGH on RE (pin 4) will disable the receiver.

The receiver for the SP481 and SP485 will operate up to at least 5Mbps. TSP483 receiver is rated for data rates up to 250kbps. The receiver for each of the three devices is equipped with the fail-safe feature. Fail-safe guarantees that the receiver output will be in a HIGH state when the input is left unconnected.

Shutdown Mode SP481/SP483

The SP481 and SP483 are equipped with a Shutdown mode. To enable the Shutdown state, both the driver and receiver must be disabled simultaneously. A logic LOW on DE (pin 5) and a logic HIGH on RE (pin 4) will put the SP481 or SP483 into Shutdown mode. In Shutdown, supply current will drop to typically 1 µA.



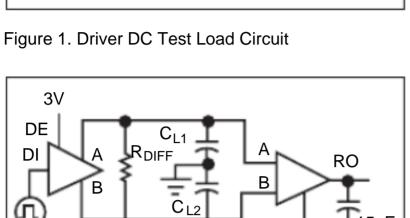


Figure 3. Driver/Receiver Timing Test Circuit

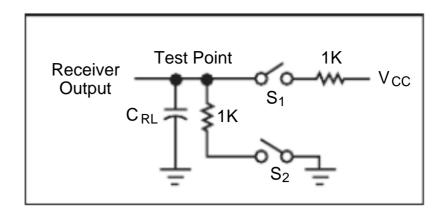


Figure 2. Receiver Timing Test Load Circuit

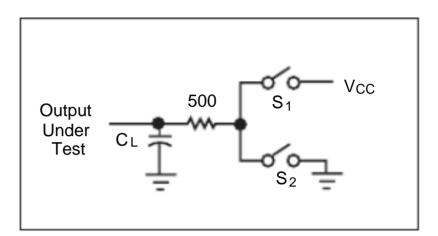


Figure 4. Driver Timing Test Load #2 Circuit

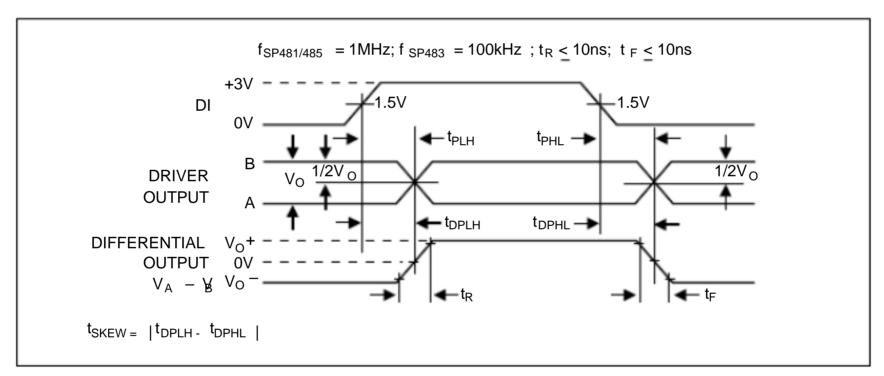


Figure 6. Driver Propagation Delays

INPUTS				OUTPUTS		
RE	DE	DI	LINE CONDITION	В	A	
Χ	1	1	No Fault	0	1	
Χ	1	0	No Fault	1	0	
Χ	0	Χ	X	Z	Z	
Х	1	Х	Fault	Z	Z	

Table 1. Transmit Function Truth Table

INPUTS			OUTPUTS	
RE	DE	A - B	R	
0	0	+0.2V	1	
0	0	-0.2V	0	
0	0	Inputs Open	1	
1	0	X	Z	

Table 2. Receive Function Truth Table

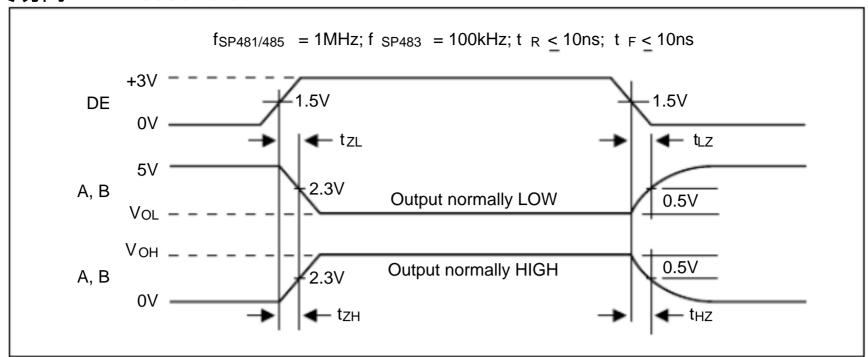


Figure 7. Driver Enable and Disable Times

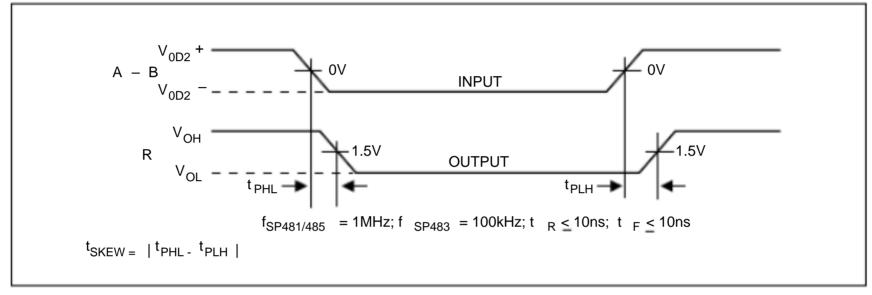


Figure 8. Receiver Propagation Delays

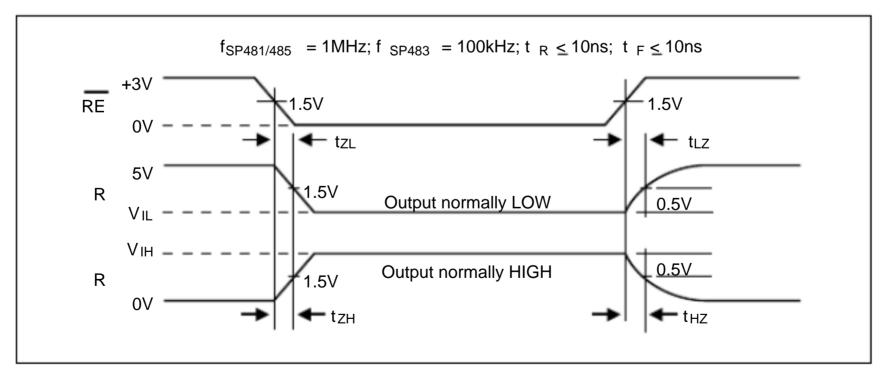
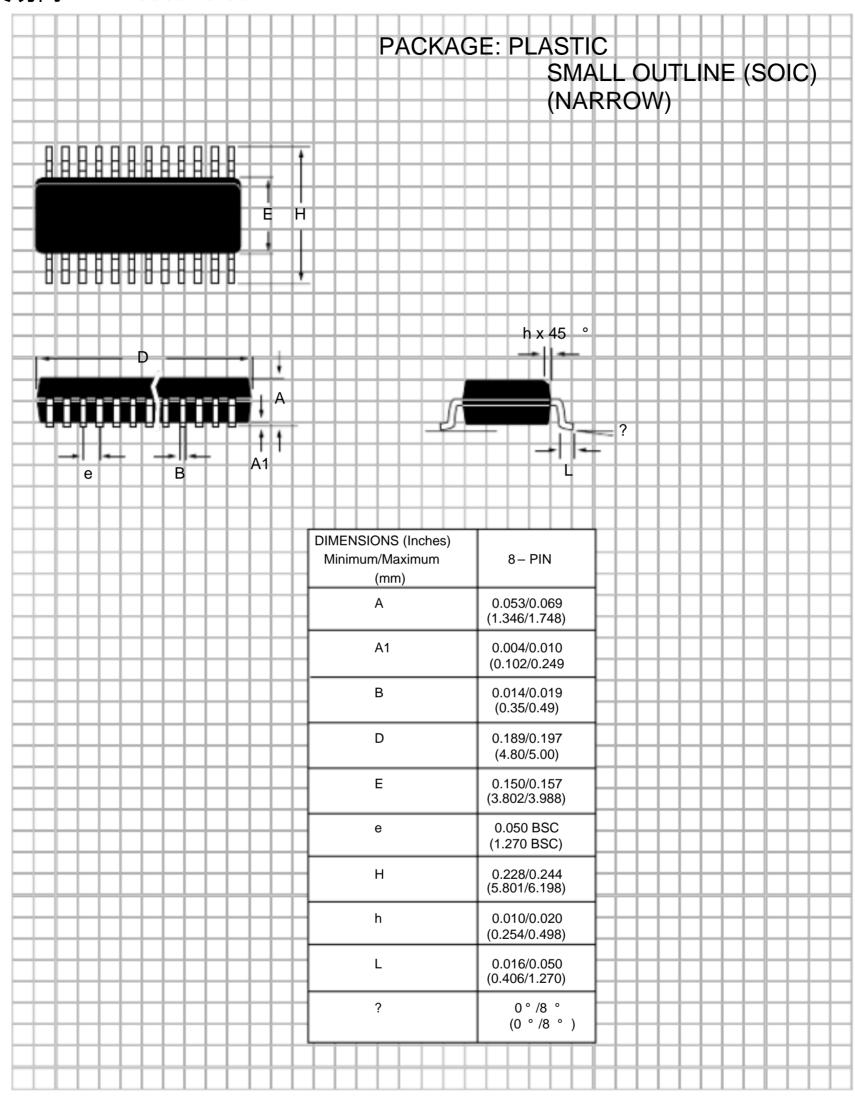
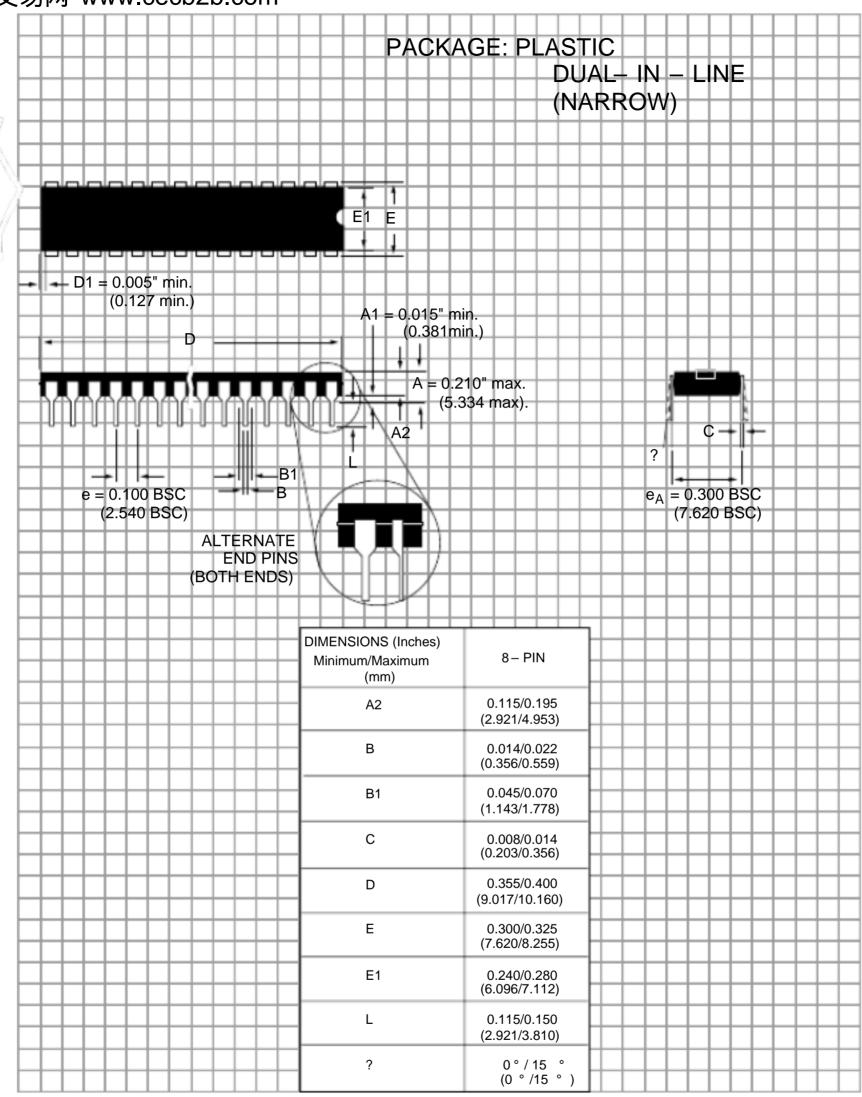


Figure 9. Receiver Enable and Disable Times





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ORDERING INFORMATION					
Model T SP481CN	Temperature Range 0?C to +70?C	Package 8-pin Narrow SOIC 8-pin Plastic DIP 8-pin Narrow SOIC			
SP481ES	-40?C to +85?C	8-pin Plastic DIP			
SP483CNSP483ENSP483ES	0?C to +70?C	8-pin Narrow SOIC 8-pin Plastic DIP 8-pin Narrow SOIC 8-pin Plastic DIP			
SP485CN	0?C to +70?C	8-pin Narrow SOIC 8-pin Plastic DIP 8-pin Narrow SOIC 8-pin Plastic DIP			

Please consult the factory for pricing and availability on a Tape-On-Reel option.



SIGNAL PROCESSING EXCELLENCE

Sipex Corporation

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