

Gradient Descent



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So so far, we have seen how to qualitatively understand the type of solutions that we get when we vary the regularization parameter

and optimize with respect to theta and theta naught.

Now, we are going to talk about, actually, algorithms

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Gradient Descent: Geometrically Revisited

2/2 points (graded)

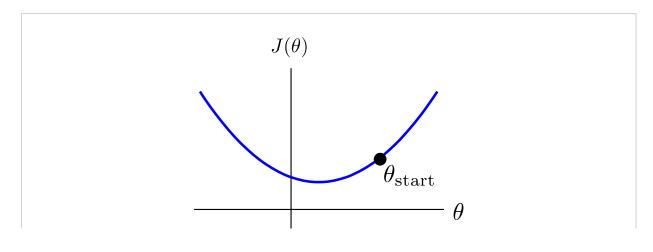
Assume $heta \in \mathbb{R}$. Our goal is to find heta that minimizes

$$J\left(heta, heta_0
ight) = rac{1}{n} \sum_{i=1}^n \operatorname{Loss}_h\left(y^{(i)}\left(heta \cdot x^{(i)} + heta_0
ight)
ight) + rac{\lambda}{2} \mid\mid heta \mid\mid^2$$

through gradient descent. In other words, we will

- 1. Start heta at an arbitrary location: $heta \leftarrow heta_{start}$
- ^{2.} Update heta repeatedly with $heta \leftarrow heta \eta rac{\partial J(heta, heta_0)}{\partial heta}$ until heta does not change significantly

In the 2 dimensional space below, we start our gradient descent at θ_{start} . What is the direction θ moves to in its first update?



away from the origin		
towards the origin		
upwards		
downwards		
•		
nat happens if we increase the stepsize η ?		
the magnitude of change in each update get	s larger	
the magnitude of change in each update get	s smaller	
/		
Submit You have used 2 of 3 attempts		
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