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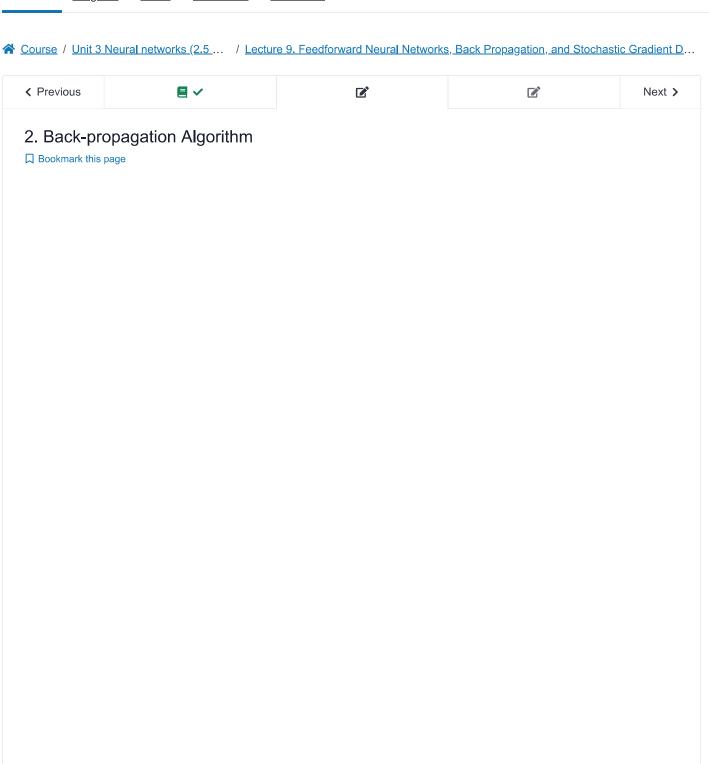
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<u>Progress</u>

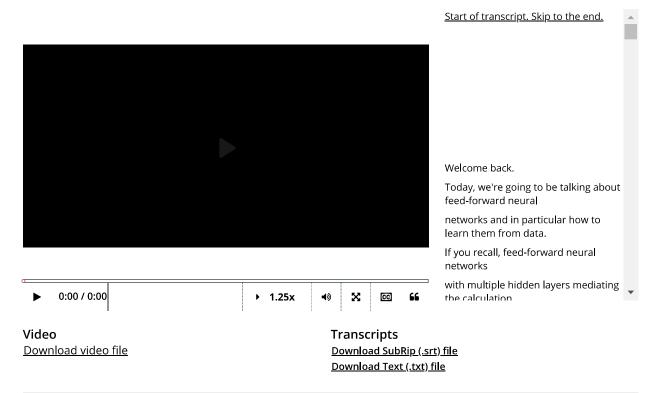
<u>Dates</u>

Discussion

Resources



Back-propagation Algorithm



Once we set up the architecture of our (feedforward) neural network, our goal will be to find weight parameters that minimize our loss function. We will use the **stochastic gradient descent algorithm** (which you learned in <u>Lecture 4</u> and revisited in <u>lecture 5</u>) to carry out the optimization.

This involves computing the gradient of the loss function with respect to the weight parameters.

Since the loss function is a long chain of compositions of activation functions with the weight parameters entering at different stages, we will break down the computation of the gradient into different pieces via the chain rule; this way of computing the gradient is called the back-propagation algorithm.

In the following problems, we will explore the main step in the stochastic gradient descent algorithm for training the following simple neural network from the video:

$$x \bigcirc \xrightarrow{w_1} \xrightarrow{z_1} \xrightarrow{f_1} \xrightarrow{w_2} \xrightarrow{z_2} \xrightarrow{f_2} \xrightarrow{w_L} \xrightarrow{z_L} \xrightarrow{f_L} \xrightarrow{f_L}$$

This simple neural network is made up of L hidden layers, but each layer consists of only one unit, and each unit has activation function f.

As usual, x is the input, z_i is the weighted combination of the inputs to the i^{th} hidden layer. In this one-dimensional case, weighted combination reduces to products:

$$egin{array}{lcl} z_1 &=& xw_1 \ && & \ ext{for}\ i=2\dots L: & z_i &=& f_{i-1}w_i & ext{where}\ f_{i-1} &=& f\left(z_{i-1}
ight). \end{array}$$

We will use the following loss function:

$$\mathcal{L}\left(y,f_{L}
ight)=\left(y-f_{L}
ight)^{2}$$

where y is the true value, and f_L is the output of the neural network.

Gradient Descent Update

1/1 point (graded)

Let η be the learning rate for the stochastic gradient descent algorithm.

Recall that our goal is to tune the parameters of the neural network so as to minimize the loss function. Which of the following is the appropriate update rule for the parameter w_1 in the stochastic gradient descent algorithm?

$$extstyle egin{aligned} igwedge w_1 \leftarrow w_1 - \eta \cdot
abla_{w_1} \mathcal{L}\left(y, f_L
ight) \end{aligned}$$

$$oxed{w}_1 \leftarrow w_1 + \eta \cdot
abla_{w_1} \mathcal{L}\left(y, f_L
ight)$$

$$igcap w_1 \leftarrow \eta \cdot
abla_{w_1} \mathcal{L}\left(y, f_L
ight)$$

$$igcap w_1 \leftarrow -\eta \cdot
abla_{w_1} \mathcal{L}\left(y, f_L
ight)$$



Solution:

The value of a function is non-decreasing in the direction of its gradient from any given point in its domain. Since our goal is to tune the parameters of the neural network so as to minimize the loss, we update the weights in the direction opposite to that of the gradient from any point.

The learning rate η controls the magnitude of the update made during gradient descent.

The final update for any parameter θ with gradient $\nabla_{\theta} \mathcal{L}$ would be given as follows:

$$\theta \leftarrow \theta - \eta \cdot \nabla_{\theta} \mathcal{L}$$
.

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You have used 1 of 2 attempts

1 Answers are displayed within the problem

Recursive Expression - Part I

1/1 point (graded)

$$x \bigcirc \xrightarrow{w_1} \xrightarrow{z_1} \xrightarrow{f_1} \xrightarrow{w_2} \xrightarrow{z_2} \xrightarrow{f_2} \xrightarrow{w_L} \xrightarrow{z_L} \xrightarrow{f_L} \xrightarrow{f_L}$$

As above, let $\mathcal{L}\left(y,f_{L}
ight)$ denote the loss function as a function of the predictions f_{L} and the true label y. Recall

$$z_1 \; = \; x w_1 \ ext{for} \; i = 2 \ldots L : \quad z_i \; = \; f_{i-1} w_i \quad ext{where} \; f_{i-1} \; = \; f\left(z_{i-1}
ight).$$

Let
$$\delta_i = rac{\partial \mathcal{L}}{\partial z_i}.$$

The first step to updating any weight w is to calculate $\dfrac{\partial \mathcal{L}}{\partial w}$

Which of the following option(s) is/are correct expression(s) for $\frac{\partial \mathcal{L}}{\partial w_1}$?

(Choose all that apply.)

$$\frac{\partial \mathcal{L}}{\partial w_1} = \frac{\partial z_1}{\partial w_1} \cdot \frac{\partial \mathcal{L}}{\partial z_1}$$

$$rac{\partial \mathcal{L}}{\partial w_1} = x \cdot \delta_1$$

$$\prod rac{\partial \mathcal{L}}{\partial w_1} = x + \delta_1$$



Solution:

From the chain rule we have:

$$rac{\partial \mathcal{L}}{\partial w_1} = rac{\partial z_1}{\partial w_1} rac{\partial \mathcal{L}}{\partial z_1}.$$

Since $z_1=w_1x, ext{ we get}$

$$rac{\partial z_1}{\partial w_1} \; = \; rac{\partial \left(w_1 \, . \, x
ight)}{\partial w_1} \; = \; x.$$

Therefore, equivalently,

$$rac{\partial \mathcal{L}}{\partial w_1} = x \delta_1.$$

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• Answers are displayed within the problem

Recursive Expression - Part II

1/1 point (graded)

As above, let $\mathcal{L}\left(y,f_L
ight)$ denote the loss function as a function of the predictions f_L and the true label y. Let $\delta_i=rac{\partial \mathcal{L}}{\partial z_i}.$

In this problem, we derive a recurrence relation between δ_i and δ_{i+1}

Assume that f is the hyperbolic tangent function:

$$f(x) = \tanh(x)$$

$$f'(x) = (1 - \tanh^{2}(x)).$$

Which of the following option is the correct expression for δ_1 in terms of δ_2 ?

$$igotimes \delta_1 = (1-f_1^2) \cdot w_2 \cdot \delta_2$$

$$igcirc$$
 $\delta_1 = (1-f_1^2) \cdot w_1 \cdot \delta_2$

$$igcircle \delta_1 = (1-f_2^2)\cdot w_2\cdot \delta_2$$
 $igcircle \delta_2 = (1-f_1^2)\cdot w_2\cdot \delta_1$

$$igcirc$$
 $\delta_2 = (1-f_1^2) \cdot w_2 \cdot \delta_1$



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Final Expression of the Gradient

1/1 point (graded)

As above, let $\mathcal{L}\left(y,f_{L}
ight)$ denote the loss function as a function of the predictions f_{L} and the true label y. Let $\delta_i = \frac{\partial \mathcal{L}}{\partial z_i}.$

In this problem, we unroll the recurrence expression for $\frac{\partial \mathcal{L}}{\partial w_1}$. We will use the loss function

$$\mathcal{L}\left(y,f_{L}
ight)=\left(y-f_{L}
ight)^{2}.$$

Compute $\frac{\partial \mathcal{L}}{\partial w_1}$ and select the correct option from below.

$$igcircled{\partial \mathcal{L}}{\partial w_1} = x \, (1 - f_2^2) \cdots (1 - f_L^2) \, w_2 w_3 \cdots w_L . \left(2 \, (f_L - y)
ight)$$

$$igcirc$$
 $rac{\partial \mathcal{L}}{\partial w_1} = x \left(1 - f_1^2
ight) \left(1 - f_2^2
ight) \cdots \left(1 - f_L^2
ight) w_1 w_2 w_3 \cdots w_L \left(2 \left(f_L - y
ight)
ight)$

$$igotimes rac{\partial \mathcal{L}}{\partial w_1} = x \left(1 - f_1^2
ight) \left(1 - f_2^2
ight) \cdots \left(1 - f_L^2
ight) w_2 w_3 \cdots w_L \left(2 \left(f_L - y
ight)
ight)$$

$$igcirc$$
 $rac{\partial \mathcal{L}}{\partial w_1} = x w_2 w_3 \cdots w_L \left(2 \left(f_L - y
ight)
ight)$



Solution:

From the previous problem, we know the following:

$$egin{array}{ll} rac{\partial \mathcal{L}}{\partial w_1} &=& x \cdot \delta_1 \ \delta_1 &=& (1 - f_1^2) \cdot w_2 \cdot \delta_2. \end{array}$$

Similarly, $\delta_2, \delta_3 \dots \delta_L$ can be given as follows:

$$egin{array}{ll} \delta_2 &= (1-f_2^2) \cdot w_3 \cdot \delta_3 \ \delta_3 &= (1-f_3^2) \cdot w_4 \cdot \delta_4 \ &dots \ \delta_{L-1} &= (1-f_{L-1}^2) \cdot w_L \cdot \delta_L \ \delta_L &= rac{\partial \mathcal{L}}{\partial z_L} \ \delta_L &= rac{\partial \mathcal{L}}{\partial f_L} \cdot rac{\partial f_L}{\partial z_L} \ \delta_L &= rac{\partial (f_L-y)^2}{\partial f_L} rac{\partial f_L}{\partial z_L} \ \delta_L &= 2 \left(f_L-y
ight) rac{\partial f_L}{\partial z_L} \end{array}$$

$$egin{aligned} oz_L \ \delta_L \ &= 2 \left(f_L - y
ight) \left(1 - f_L^2
ight). \end{aligned}$$

Plugging the above equations into the expression for $\frac{\partial \mathcal{L}}{\partial w_1}$ we get:

$$\begin{split} \frac{\partial \mathcal{L}}{\partial w_1} &= x \cdot \delta_1 \\ \frac{\partial \mathcal{L}}{\partial w_1} &= x \cdot (1 - f_1^2) \cdot w_2 \cdot \delta_2 \\ \frac{\partial \mathcal{L}}{\partial w_1} &= x \cdot (1 - f_1^2) \cdot w_2 \cdot (1 - f_2^2) \cdot w_3 \cdot \delta_3 \\ &\vdots \\ \frac{\partial \mathcal{L}}{\partial w_1} &= x \left(1 - f_1^2\right) \left(1 - f_2^2\right) \cdots \left(1 - f_L^2\right) w_2 w_3 \cdots w_L \left(2 \left(f_L - y\right)\right). \end{split}$$

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1 Answers are displayed within the problem

Discussion Topic: Unit 3 Neural networks (2.5 weeks):Lecture 9. Feedforward Neural Networks, Back

Propagation, and Stochastic Gradient Descent (SGD) / 2. Back-propagation Algorithm

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• Video on Backpropagation by Statquest As always, a simpler view on the subject by StatQuest: https://www.youtube.com/watch?v=IN2XmBhILt4&t=143s	3
✓ I looked at the answer for " Final Expression of the Gradient ": the case of my "orphaned" negative ▲ Community TA	e sign. 9
? partial derivative with respect to a function Can anybody give an explanation on what does it even mean to take partial derivative with respect to a function like	e f1? Thanks.
Interpretation of the solutions to the problems So I did the calculus, the algebra, the recursion, I got them right, but what do these solution mean? Is there some we have the solution mean?	arbal interpretation t
Handwritten lecture notes Check out my notes for this lecture: https://drive.google.com/drive/folders/172YN9JMYWjb-6k6Sd3USa4TInUKSRC	8 Wr?usp=sharing
Notation for "Recursive Expression - Part II"	5
Chain Rule - Chain rule and tree diagrams of multivariable functions Found a video about chain rule. https://www.youtube.com/watch?v=kCr13iTRN7E and https://www.youtube.com/	vatch?v=NO3AqAaAE6o
Thank you for the notes after video segments whoever wrote them did me a huge favor	1
Technically, aren't there L-1 hidden layers?	2
Just a refresher of chain rule if needed (link) Hope it helps. https://www.youtube.com/watch?v=wl1myxrtQHQ Community_TA	2
? [STAFF] Recursive Expression - Part II I might be mistaken, but can the staff check the grader for this question? I'm not sure why it's incorrect since I used	3 I that basis to get the
? Links to Lecture 4 and Lecture 5 are broken The links on this page are to an old version of the course could they be updated?	4

Previous

Next >

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