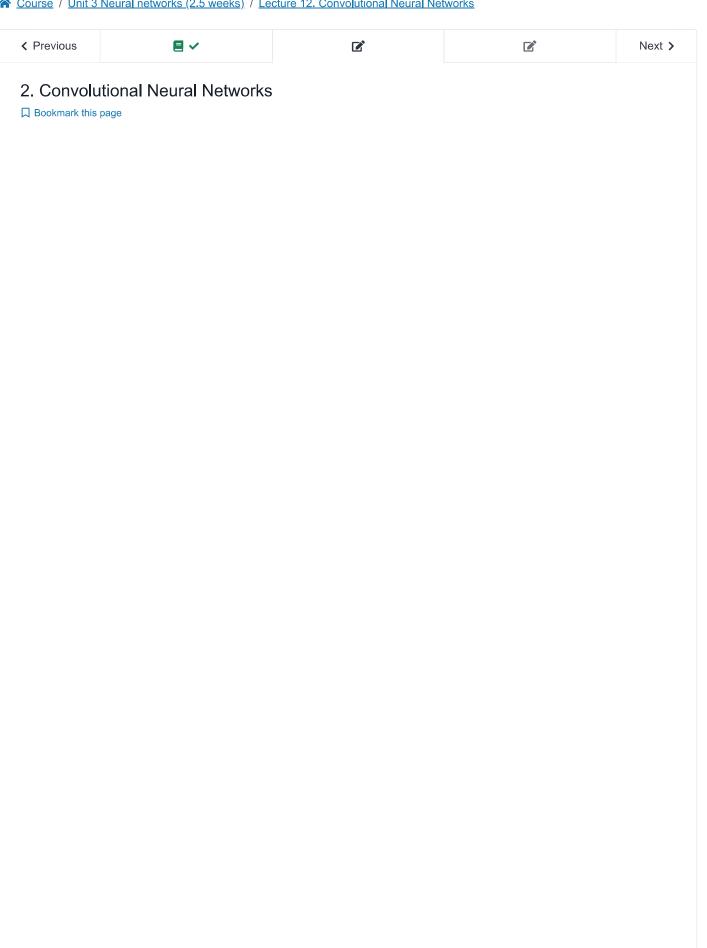


<u>Help</u> smitha_kannur -

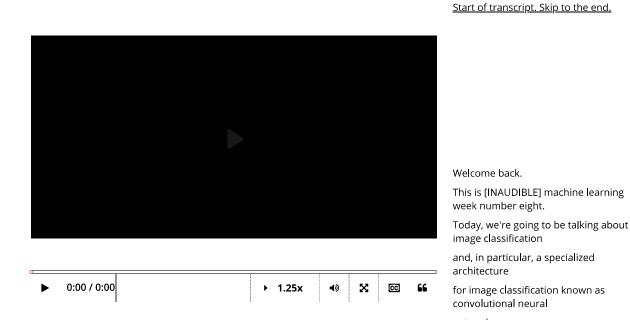
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☆ Course / Unit 3 Neural networks (2.5 weeks) / Lecture 12. Convolutional Neural Networks



Exercises due Nov 5, 2020 05:29 IST Completed

Introduction to Convolution Neural Networks



Video

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Transcripts

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Motivation for CNN

2/2 points (graded)

Let's suppose that we wish to classify images of 1000×1000 dimensions.

We wish to pass the above input through a feed-forward neural network with a single hidden layer made up of 1000×1000 hidden units each of which is fully connected to the full image.

If the number of connections that exist between the first hidden layer and the input image is given by x, then enter below the value of $log_{10}(x)$, i.e. the logarithm of x to the base 10:



Instead of a fully-connected layer, now suppose that we use a convolutional layer with 1 filter of shape 11 imes 11 instead. Enter below the number of parameters in the first layer (ignoring the bias terms):



Solution:

Each of the hidden unit is connected to all the pixels from the input image.

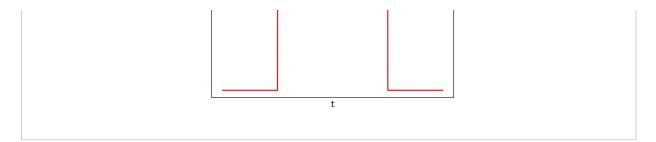
So, there are a total of $1000*1000=10^6$ connections between each of the hidden layers and the input. Since there are $1000*1000=10^6$ hidden units in the first hidden layer, the total number of connections x amounts to $x=10^6*10^6=10^{12}$

The first convolutional layer with a 11×11 filter will have 11 * 11 = 121 parameters that operate on the entire image.

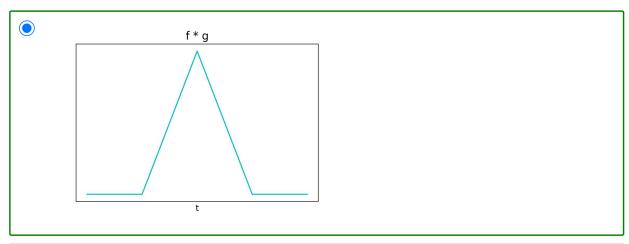
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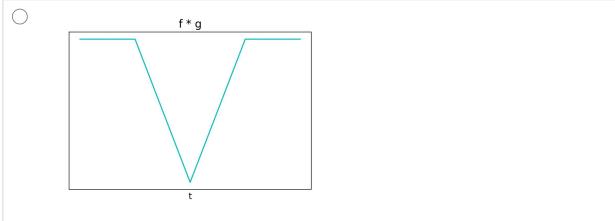
1 Answers	are displayed within the problem
Second Mo	otivation for CNN
	d) d-forward, non-convolutional neural network is learning how to classify images. Then, it can classify the relevant object is in a different part of the image.
<u></u> true	
false	
✓	
olution:	
arameters at	plains this with a mushroom example. If the mushroom is in a different place, the weight matrix that location need to learn to recognize the mushroom anew. With convolutional layers, we have envariance as the same filter is passed over the entire image. Therefore, it will detect the mushroom ocation
Submit	You have used 1 of 2 attempts
1 Answers	are displayed within the problem
2 points (grad	on: Continuous Case
n the lecture	we saw the example of using the convolution operation to create a feature map. Here we formally volution as an operation between 2 functions f and g :
	$\left(fst g ight)\left(t ight)\equiv\int_{-\infty}^{+\infty}f\left(au ight)g\left(t- au ight)d au$
	, $ au$ is the dummy variable for integration and t is the parameter. Intuitively, convolution 'blends' the and g by expressing the amount of overlap of one function as it is shifted over another function.
low, suppose	we are given two rectangular function f and g as shown in the figures below.
	f
	t

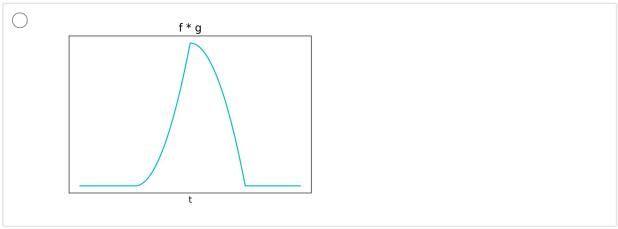
g

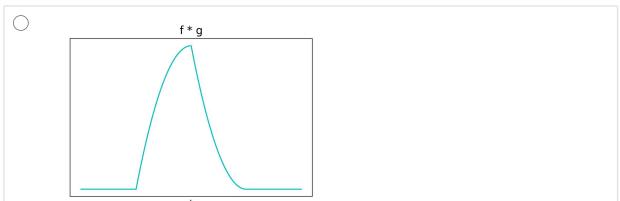


What is the shape of of f * g?





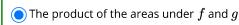




What is the area under the convolution: $\int_{-\infty}^{+\infty} \left(f * g
ight) dt$

 \bigcirc The area under f

 \bigcirc The area under g



 \bigcirc The sum of the areas under f and g



Solution:

We can flip g and shift it over f. f * g stays at 0 when there's no overlap. It increse linearly and reach the peak when f and g fully overlap with each other.

The area under the convolution:

$$\int_{-\infty}^{+\infty} (f * g) dt = \int_{-\infty}^{+\infty} \left[\int_{-\infty}^{+\infty} f(\tau) g(t - \tau) d\tau \right] dt$$
$$= \int_{-\infty}^{+\infty} f(\tau) \left[\int_{-\infty}^{+\infty} g(t - \tau) dt \right] d\tau$$
$$= \left[\int_{-\infty}^{+\infty} f(\tau) d\tau \right] \left[\int_{-\infty}^{+\infty} g(t) dt \right]$$

This is the product of the areas under f and g.

Submit

You have used 2 of 3 attempts

1 Answers are displayed within the problem

Convolution: 1D Discrete Case

2.0/2 points (graded)

Similarly, for discrete functions, we can define the convolution as:

$$(fst g)\left[n
ight] \equiv\sum_{m=-\infty}^{m=+\infty}f\left[m
ight] g\left[n-m
ight]$$

Here, we give an example of convolution on 1D discrete signal.

Let f[n]=[1,2,3], g[n]=[2,1] and suppose n starts from 0. We are computing h[n]=f[n]*g[n]. As f and g are finite signals, we just put 0 to where f and g are not defined. This is usually called zero padding. Now, let's compute h[n] step by step:

$$\begin{array}{ll} h\left[0\right] \ = \ f\left[0\right] \cdot g\left[0-0\right] + f\left[1\right] \cdot g\left[0-1\right] + \cdots = f\left[0\right] \cdot g\left[0\right] = 2 \\ h\left[1\right] \ = \ f\left[0\right] \cdot g\left[1-0\right] + f\left[1\right] \cdot g\left[1-1\right] + f\left[2\right] \cdot g\left[1-2\right] + \cdots = f\left[0\right] \cdot g\left[1\right] + f\left[1\right] \cdot g\left[0\right] = 5 \\ h\left[2\right] \ = \ f\left[0\right] \cdot g\left[2-0\right] + f\left[1\right] \cdot g\left[2-1\right] + f\left[2\right] \cdot g\left[2-2\right] + f\left[3\right] \cdot g\left[2-3\right] + \cdots = f\left[1\right] \cdot g\left[1\right] + f\left[2\right] \cdot g\left[0\right] = 8 \\ h\left[3\right] \ = \ f\left[0\right] \cdot g\left[3-0\right] + f\left[1\right] \cdot g\left[3-1\right] + f\left[2\right] \cdot g\left[3-2\right] + f\left[3\right] \cdot g\left[3-3\right] + f\left[4\right] \cdot g\left[3-4\right] + \cdots = f\left[2\right] \cdot g\left[1\right] \end{array}$$

The other parts of h are all 0.

Intuitively, we can get this result by first flipping g[n] and shift it over f[n] and compute the inner product at each step, as shown in the figures below:

In practice, it is common to call the flipped g' as filter or kernel, for the input signal or image f.

As we forced to pad zeros to where the input are not defined, the result on the edge of the input may not be accurate. To avoid this, we can just keep the convolution result where g' has operated exclusively on where the input f is actually defined. That is $h\left[n\right]=\left[5,8\right]$.

Now suppose the input f=[1,3,-1,1,-3], and the filter g'=[1,0,-1], what is the convolutional output of f*g without zero padding on f? Enter your answer as a list below (e.g. [0,0,0])

What is the convolutional output of f * g if we pad a 0 on both edges of f so that the output dimension is the same as the input? Enter your answer as a list below (e.g. [0,0,0,0,0])

Solution:

Without zero padding, we have

$$f * g(0) = 1 \times 1 + 3 \times 0 + (-1) \times (-1) = 2$$

 $f * g(1) = 3 \times 1 + (-1) \times 0 + 1 \times (-1) = 2$
 $f * g(2) = (-1) \times 1 + 1 \times 0 + (-3) \times (-1) = 2$

With zero padding, we add 0 to f such that f = [0, 1, 3, -1, 1, -3, 0],

$$\begin{array}{lll} f*g\left(0\right) &=& 0\times 1+1\times 0+3\times (-1)=-3\\ f*g\left(1\right) &=& 1\times 1+3\times 0+(-1)\times (-1)=2\\ f*g\left(2\right) &=& 3\times 1+(-1)\times 0+1\times (-1)=2\\ f*g\left(3\right) &=& (-1)\times 1+1\times 0+(-3)\times (-1)=2\\ f*g\left(4\right) &=& 1\times 1+(-3)\times 0+0\times (-1)=1 \end{array}$$

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You have used 1 of 5 attempts

1 Answers are displayed within the problem

Convolution: 2D Discrete Case

1/1 point (graded)

Now, let's apply the same idea on images, which are 2D discrete signals. Suppose we had an image f and a filter g' as shown below. Calculate the sum of the elements in the output matrix after passing the image through the convolutional filter, without zero padding.

$$f = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$g' = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}$$

15

✓ Answer: 15

Solution:

We align the filter with the top left corner of the image, and take the element wise multiplication of the filter and the 2 by 2 square in the top left corner. We then shift the filter along the top row, doing the same thing. We then apply the same procedure to the next row. If we went another row down, the bottom row of the filter would not have any numbers to be multiplied with. Thus, we stop.

The result of the convolution is

$$C = egin{bmatrix} 4 & 4 \ 4 & 3 \end{bmatrix}$$

. The sum is therefore 15

Submit

You have used 1 of 3 attempts

• Answers are displayed within the problem

Pooling Practice

1/1 point (graded)

A pooling layer's purpose is to pick up on a feature regardless of where it appears in the image.



false



Solution:

A pooling layer finds the maximum value over a given area. The max value can be seen as a "signal" representing whether or not the feature exists. For example, a high max value could indicate that the feature did appear in the image.

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You have used 1 of 2 attempts

1 Answers are displayed within the problem

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Convolution- wrong definition?? For a convolution as I've studied in discrete signal processing, the size of resulting convolution would be M+N-1 where M is the size	2	
? Where does the weights used to make feature maps come from So, from what I was able to grasp they come from training with relation to the smaller patches. But when and how this is made? Bec	2	
? Help to way my answer in 1D isn't valid Hi. I have written my answer as [1,2,3] and [1,2,3,1,2,3] but it comes back with the answer: "Expected answer to be a vector, but inpu	2	
where are you scooopydoo): where are you scooopydoo):	3	
[Staff] Grader does not mark the answer of the 1st question correctly if given in a ln() format If someone wanted to include the answer in ln() format, the grader currently does not mark it correctly. Maybe confirm that ln() sho	1	
A good video for convolution of discrete distribution in class 6.431x This is a video that introduces convolution formula of discrete distribution by Prof. John Tsitsiklis in class 6.431x https://youtu.be/zb	4	
Accepted Matrix Syntax Convolution: 1D Discrete Case I had enter formate1: [1,2,3] format2: ([1,2,3]) format3: (1,2,3) in all formats Invalid Input: Could not parse which one is correct	7	
? Convolution: 1D Discrete Case	3	
? staff. subtitles are not synchronised subtitles are not synchronised for the video	1	
Convolution: 1D Discrete Case: Answer checker is wrong I think Answer checker is not working properly. Correct Answers are: [1,3,-2][0,1,3,-2,-2]	3	
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