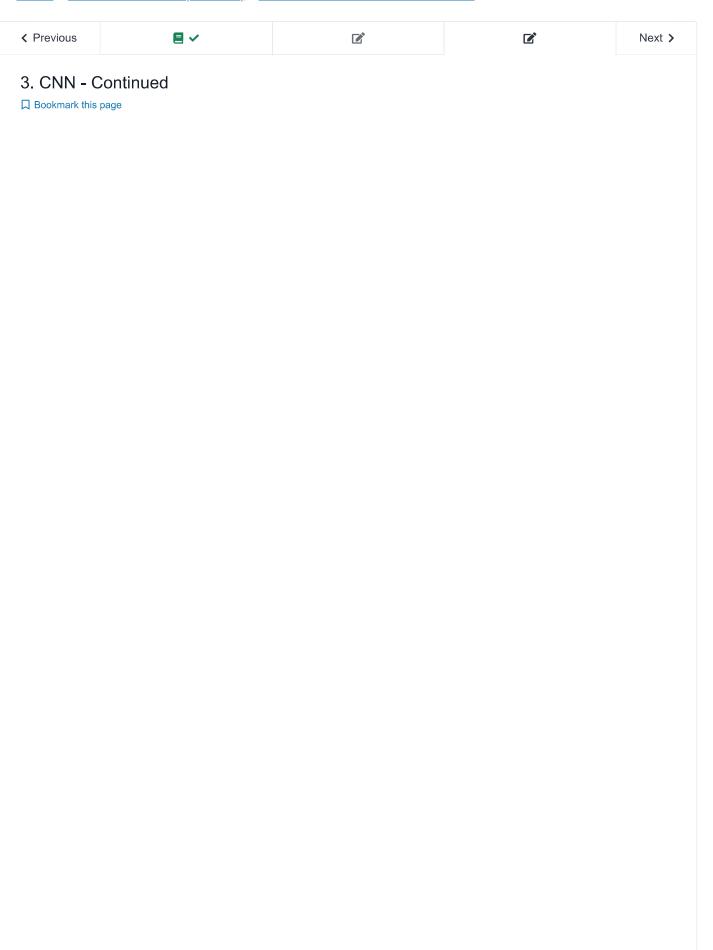
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☆ Course / Unit 3 Neural networks (2.5 weeks) / Lecture 12. Convolutional Neural Networks



Convolution Neural Networks (Continued)



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All right.

So let's look at how to then actually construct

a convolutional neural network.

I will take input image here.

And now, since each convolution corresponds

to some weight matrix here associated

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CNN - Numerical Example

1/1 point (graded)

In this problem, we are going to work out the outputs of a tiny toy example of CNN that is made up of just one conv layer consisting of just one filter F of shape 2×2 followed by a max-pooling layer of shape 2×2 . The input image is of shape 3×3

The output of the CNN is calculated as $\operatorname{Pool}\left(\operatorname{ReLU}\left(\operatorname{Conv}\left(I\right)\right)\right)$ where ReLU is the rectified linear activation function given by:

$$\operatorname{ReLU}(x) = \max(0, x)$$

Also assume that the stride for the convolution and pool layers is $\boldsymbol{1}$

For the following values of the image I and filter weights F enter below the value of the output of the CNN (hint - it will be a single integer):

$$I = egin{bmatrix} 1 & 0 & 2 \ 3 & 1 & 0 \ 0 & 0 & 4 \end{bmatrix}$$

$$F = egin{bmatrix} 1 & 0 \ 0 & 1 \end{bmatrix}$$

✓ Answer: 5

5

Solution:

First let's calculate the output of the convolutional layer

$$I = egin{bmatrix} 1 & 0 & 2 \ 3 & 1 & 0 \ 0 & 0 & 4 \end{bmatrix}$$

$$F = egin{bmatrix} 1 & 0 \ 0 & 1 \end{bmatrix}$$

$$\operatorname{Conv}\left(I
ight) = egin{bmatrix} 1 & 0 & 2 \ 3 & 1 & 0 \ 0 & 0 & 4 \end{bmatrix} . egin{bmatrix} 1 & 0 \ 0 & 1 \end{bmatrix}$$

$$\operatorname{Conv}\left(I
ight) = egin{bmatrix} 2 & 0 \ 3 & 5 \end{bmatrix}$$

$$\operatorname{ReLU}\left(\operatorname{Conv}\left(I\right)\right) = \operatorname{ReLU}\left(\begin{bmatrix}2 & 0 \\ 3 & 5\end{bmatrix}\right)$$

$$\operatorname{ReLU}\left(\operatorname{Conv}\left(I
ight)
ight) = egin{bmatrix} 2 & 0 \ 3 & 5 \end{bmatrix}$$

$$\operatorname{Pool}\left(\operatorname{ReLU}\left(\operatorname{Conv}\left(I\right)
ight)
ight)=\operatorname{Pool}\left(egin{bmatrix}2 & 0 \ 3 & 5\end{bmatrix}
ight)$$

$$\operatorname{Pool}\left(\operatorname{ReLU}\left(\operatorname{Conv}\left(I\right)\right)\right)=5$$

Submit

You have used 1 of 3 attempts

1 Answers are displayed within the problem

CNN Meaning

1/1 point (graded)

If you are trying to recognize a large number of features, you should have a small number of filters.

() true





Solution:

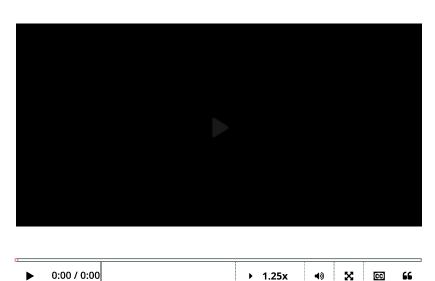
Each filter represents a distinct set of weights, which corresponds to searching for a particular feature in the image. If you have a large number of features, you want many filters.

Submit

You have used 2 of 2 attempts

1 Answers are displayed within the problem

Recitation: Convolution/Cross Correlation: Definition



1.25x

SPEAKER: Welcome to the recitation of convolutional neural network. In this video, we will talk about the mathematical operation that is used in the convolutional layer of CNN, which namely is convolution, or its equivalence,

Start of transcript. Skip to the end.

cross correlation.

called

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CC

X

Discrete 1D example



INSTRUCTOR: So what we just talked about

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is a continuous version of the convolution

and cross-correlation.

But as you know, most of our signals in the digital world

are actually discrete functions, for example an image or video.

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0:00 / 0:00

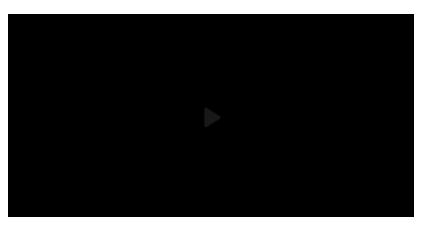
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CC

X

1.25x

Discrete 2D example



0:00 / 0:00 × 1.25x **∢**》 CC " PROFESSOR WANGZHI: Now let's take a look

at the two-dimensional case of crosscorrelation.

One example of the two-dimensional signal

would be an image which is just a 2D matrix of discrete numbers.

So in the 2D version of cross-

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