

KING'S COLLEGE LONDON

MASTER OF SCIENCE – INTELLIGENT SYSTEMS – 2018-19

COURSEWORK (MARKED)

7CCSMPRJ - INDIVIDUAL PROJECT

PREDICTING TRUTHFULNESS IN DATA SHARING (A MACHINE LEARNING PROJECT)

LANGUAGE: PYTHON

- a. Implemented end-to-end machine learning pipeline and applied **unweighted, imbalanced** and **cost-sensitive** learning to predict whether users were likely to be truthful or not about data.
- b. Re-defined the problem as an **unsupervised** learning to identify **customer segments** within shared data.
- c. Learned Bayesian networks from data to draw **meaningful inferences** from the survey responses.

7CCSMAIN - ARTIFICIAL INTELLIGENCE

CODING AND REPORT PREPARATION

LANGUAGE: PYTHON

- I. Implemented simplistic code to control Pacman in standardGrid and win games despite the **limitations of observability**.
 - a. Met the requirement to win games when there were no ghosts.
 - b. Met the requirement to win one game in five, on average, when there were ghosts.
 - c. Generalized to run in any other grid.
- II. Created an **MDP-solver** to control Pacman and win games.
 - a. Met the requirement to win at least four games out of ten in smallGrid. On average, the MDP Agent achieved 64% win-rate when experimented with 3 rounds of 50 runs each.
 - b. Met the requirement to win at least two games out of ten in mediumClassic. On average, the win-rate was 50.67% when experimented with 3 rounds of 50 runs each.
 - c. Generalized to run in any other grid.

7CCSMCVI - COMPUTER VISION

CODING AND REPORT PREPARATION

LANGUAGE: MATLAB

- I. MODELING LOW-LEVEL COMPUTER VISION
Performed convolution on images with:
 - a. Smoothing Masks: Box and Gaussian Masks.
 - b. Difference Masks: 1-D, 2-D and others.
 - c. Gaussian Derivative Masks, Laplacian of Gaussian (LoG) Mask and Difference of Gaussian (DoG) Masks for Edge Detection.
 - d. Gaussian Image Pyramid and Laplacian Image Pyramid for multi-scale representations.
 - e. Edge Detection algorithms.
- II. MODELING LOW-LEVEL BIOLOGICAL VISION
 - a. Identified redundancy in natural images.
 - b. Modelled Retinal Ganglion Cells using DoG Masks.
 - c. Modelled V1 Orientation Selective Cells using Gabor Masks.
- III. MODELING HIGH-LEVEL COMPUTER VISION
 - a. Designed and implemented Computer Vision system which could read in a LEGO image and count the number of Blue 2 by 4 bricks (object A) and Red 2 by 2 bricks (object B). The colored mask, morphological operations, blob detection (image segmentation) and bounding box were computed/ applied to the images in order to detect specific objects (bricks).

7CCSMML1 - MACHINE LEARNING

LANGUAGE: PYTHON

- I. Created **Naïve Bayes Classifier** that helped make Pacman Agent decisions on how to move in the classic game.
 - a. Applied **m-estimation** technique for samples having conditional probability value equal to zero.
 - b. Selected next action/ move based on **Epsilon-Greedy** algorithm against normalized cumulative probabilities for effective decision-making rather than using the move with maximum probability from NB classifier.
 - c. Met the requirement for code to run until the game was won or lost within time limit.
- II. Implemented **Q-Learning** and **Adaptive Dynamic Programming** (ADP) Reinforcement Learning algorithms helping Pacman agent choose how to move in the classic game.
 - a. Met the requirement to win at least eight games out of ten in smallGrid.

7CCSMPNN - PATTERN RECOGNITION

CODING AND REPORT PREPARATION

LANGUAGE: MATLAB

- I. BAYESIAN DECISION THEORY AND DISCRIMINANT FUNCTIONS
 - a. Performed **Parzen Density Estimation** and classified patterns/ samples using **Bayes Decision Rule**.
 - b. Implemented k-Nearest-Neighbor classifier.
 - c. Determined a linear discriminant function using **Sequential Widrow-Hoff Learning** Algorithm for classification.
- II. NEURAL NETWORKS AND FEATURE EXTRACTION
 - a. Learned the weights of a Linear Threshold Unit using **Sequential Delta Learning Algorithm** for classification.
 - b. Implemented **Karhunen-Loeve Transform** method to perform **Principal Component Analysis** (PCA) on the given dataset.
 - c. Performed classification using **Sparse Coding** method.
- III. SUPPORT VECTOR MACHINES (SVMs)
 - a. Designed and implemented **multi-class classifier** using self-generated linearly separable dataset. Identified support vectors of the linear SVMs by “inspection” and designed their hyperplanes by hand.
- IV. ENSEMBLE METHODS
 - a. Designed and implemented **Bagging** and **Boosting** classifiers from scratch and predicted the classification of test samples.

7CCSMAMS - AGENTS AND MULTI-AGENT SYSTEMS

CODING AND REPORT PREPARATION

ENVIRONMENT: NETLOGO

- I. FOREST FIRES AND REACTIVE AGENTS
- II. FOREST FIRES AND COOPERATIVE AGENTS

7CCSMART - ADVANCED RESEARCH TOPICS

LITERATURE REVIEW: LEARNING TO IMPROVE AI PLANNING (6000-8000 WORDS)