

Chapter 10. Vector Integral Calculus

1. Line Integral, Path Independence
2. Green's Theorem
3. Surface Integral
4. Triple Integrals, Divergence Theorem
5. Stoke's Theorem

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Line Integrals

- Definite integral

$$\vee \int_a^b f(x)dx$$

- Integral along a curve C

\vee Integration part, $C: \mathbf{r}(t) = (x(t), y(t), z(t))$, $a \leq t \leq b$

\dagger Smooth curve, closed path

- Line integral of $\mathbf{F}(\mathbf{r})$ over a curve C (integration path)

$$\vee \int_C \mathbf{F}(\mathbf{r}) \cdot d\mathbf{r} = \int_C \mathbf{F}(\mathbf{r}) \cdot \mathbf{r}'(t)dt \quad \leftarrow \mathbf{r}'(t) = \frac{d\mathbf{r}(t)}{dt} \text{ and } d\mathbf{r} = (dx, dy, dz)$$

$$\dagger \int_C \mathbf{F}(\mathbf{r}) \cdot d\mathbf{r} = \int_C (F_1 dx + F_2 dy + F_3 dz) = \int_a^b (F_1 x' + F_2 y' + F_3 z')dt$$

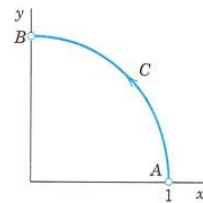
Line Integrals

- **Example 1.** $\mathbf{F}(\mathbf{r}) = (-y, -xy)$ with C ... circular arc

$$\vee \mathbf{r}(t) = (\cos t, \sin t), t \in \left[0, \frac{\pi}{2}\right] \Rightarrow x(t) = \cos t \text{ and } y(t) = \sin t$$

$$\vee \mathbf{F}(\mathbf{r}) = (\sin t, -\cos t \cdot \sin t)$$

$$\vee \int_C \mathbf{F}(\mathbf{r}) \cdot d\mathbf{r} = \int_{t=0}^{\pi/2} (\sin t, -\cos t \cdot \sin t) \cdot (-\sin t, \cos t) dt = \int_0^{\pi/2} \frac{1}{2}(1 - \cos 2t) dt$$



- **Example 2.** $\mathbf{F}(\mathbf{r}) = (z, x, y)$ with C ... circular helix

$$\vee \mathbf{r}(t) = (\cos t, \sin t, 3t), t \in [0, 2\pi] \Rightarrow x(t) = \cos t, y(t) = \sin t, z(t) = 3t$$

$$\vee \mathbf{F}(\mathbf{r}) = (3t, \cos t, \sin t)$$

$$\vee \mathbf{F}(\mathbf{r}) \cdot d\mathbf{r} = (3t, \cos t, \sin t) \cdot (-\sin t, \cos t, 3) = -3t \sin t + \cos^2 t + 3 \sin t$$

$$\vee \int_C \mathbf{F}(\mathbf{r}) \cdot d\mathbf{r} = \int_{t=0}^{2\pi} (-3t \sin t + \cos^2 t + 3 \sin t) dt$$

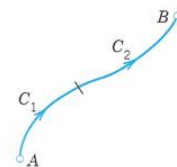
Line Integrals

- **Properties**

$$1. \int_C k\mathbf{F} \cdot d\mathbf{r} = k \int_C \mathbf{F} \cdot d\mathbf{r}$$

$$2. \int_C (\mathbf{F} + \mathbf{G}) \cdot d\mathbf{r} = \int_C \mathbf{F} \cdot d\mathbf{r} + \int_C \mathbf{G} \cdot d\mathbf{r}$$

$$3. \int_C \mathbf{F} \cdot d\mathbf{r} = \int_{C_1} \mathbf{F} \cdot d\mathbf{r} + \int_{C_2} \mathbf{F} \cdot d\mathbf{r}, \text{ where } \{C_1, C_2\} \text{ is a partition of } C.$$



- **Example** $\mathbf{F} = (0, xy, 0)$

$$\vee C_1: \mathbf{r}_1(t) = (t, t, 0), t \in [0, 1], \int_{C_1} \mathbf{F} \cdot d\mathbf{r} = \int_{t=0}^1 (0, t^2, 0) \cdot (1, 1, 0) dt = \frac{1}{3}$$

$$\vee C_2: \mathbf{r}_2(t) = (t, t^2, 0), t \in [0, 1], \int_{C_2} \mathbf{F} \cdot d\mathbf{r} = \int_{t=0}^1 (0, t^3, 0) \cdot (1, 2t, 0) dt = \frac{2}{5}$$

∨ Different path could result in different line integral.

More work in longer path.

Line Integrals: Motivation

- Work done by a force

- ∨ Work W done by a constant force \mathbf{F} in the direction along a line segment \mathbf{d}

- † $W = \mathbf{F} \cdot \mathbf{d}$

- ∨ Work W done by a time-varying force \mathbf{F} in the direction along a curve $C: \mathbf{r}(t)$

- † $W = \int_C \mathbf{F} \cdot d\mathbf{r}$

- Example 4. $\mathbf{F} = m\mathbf{a}$

- ∨ A time-varying force \mathbf{F} in the direction along a curve $C: \mathbf{r}(t)$

- † Velocity, $\mathbf{v}(t) = \frac{d\mathbf{r}}{dt}$

- † $W = \int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b m\mathbf{v}' \cdot \mathbf{v}(t) dt = \int_a^b \frac{m}{2} (\mathbf{v} \cdot \mathbf{v})' dt = \frac{m}{2} |\mathbf{v}|^2 \Big|_{t=a}^b$

Line Integral: Path Independence

- Theorem 1. Path independence (1)

A line integral with continuous F_1, F_2, F_3 in a domain D is path independent in D , if and only if $\mathbf{F} = (F_1, F_2, F_3) = \text{grad}(f)$ for some function $f \in D$.

- ∨ If $\mathbf{F} = (F_1, F_2, F_3) = \text{grad}(f)$, $F_1 = \frac{\partial f}{\partial x}$, $F_2 = \frac{\partial f}{\partial y}$, $F_3 = \frac{\partial f}{\partial z}$ and so

- † $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \left(\frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} \right) dt = \int_a^b \frac{df}{dt} dt = f(B) - f(A)$

- † Line integral is path independent, if and only if \mathbf{F} is a gradient of a potential in D .

Line Integral: Path Independence

- **Example 1.** $\int_C (2xdx + 2ydy + 4zdz)$: Path from $A: (0, 0, 0)$ to $B: (2, 2, 2)$
 - ✓ Check, $\mathbf{F} = (2x, 2y, 4z) = \text{grad}(f) \Rightarrow \frac{\partial f}{\partial x} = 2x, \frac{\partial f}{\partial y} = 2y, \text{ and } \frac{\partial f}{\partial z} = 4z \Rightarrow f = x^2 + y^2 + 2z^2 \Rightarrow \text{path independent}$
 - ✓ $\int_C (2xdx + 2ydy + 4zdz) = f(B) - f(A) = 16$
- **Example 2.** $\int_C (3x^2dx + 2yzdy + y^2dz)$: Path from $A: (0, 1, 2)$ to $B: (1, -1, 7)$
 - ✓ $\frac{\partial f}{\partial x} = 3x^2 \Rightarrow f = x^3 + g(y, z),$
 - ✓ $\frac{\partial f}{\partial y} = 2yz = g_y \Rightarrow g(y, z) = y^2z + h(z),$
 - ✓ $\frac{\partial f}{\partial z} = y^2 = y^2 + h_z \Rightarrow h(z) = c \text{ (const.): } f = x^3 + y^2z + c$
 - ✓ $\int_C (3x^2dx + 2yzdy + y^2dz) = f(B) - f(A) = 6$

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Line Integral: Path Independence

- **Theorem 2. Path independence (2)**

A line integral is path independent in a domain D , **if and only if** $\oint_C \mathbf{F} \cdot d\mathbf{r} = 0$, for all closed path C .

✓ Work along a closed path C is zero: **Conservative vector field**
- **Theorem 3. Path independence (3)**

A line integral is path independent in a domain D , **if and only if** the differential form $\mathbf{F} \cdot d\mathbf{r} = F_1dx + F_2dy + F_3dz$ has continuous coefficient functions F_1, F_2, F_3 and is **exact** in D .

✓ Differential form, $\mathbf{F} \cdot d\mathbf{r}$ is exact, if $\exists f \in D$, such that

$$df = \frac{\partial f}{\partial x}dx + \frac{\partial f}{\partial y}dy + \frac{\partial f}{\partial z}dz = \text{grad}(f) \cdot d\mathbf{r} \quad (\Leftrightarrow \mathbf{F} \cdot d\mathbf{r} = df)$$

✓ Differential form, $\mathbf{F} \cdot d\mathbf{r} = F_1dx + F_2dy + F_3dz$ is exact, if and only if $\exists f \in D$, such that $\mathbf{F} = \text{grad}(f)$.

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Exact & Path Independence

- **Theorem 3. Criterion** for exactness and path independence

Let F_1, F_2, F_3 in the line integral, $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C (F_1 dx + F_2 dy + F_3 dz)$ be continuous and have continuous first partial derivatives in a domain D .

- ① If the differential form $\mathbf{F} \cdot d\mathbf{r} = F_1 dx + F_2 dy + F_3 dz$ is exact in D (and thus path independent), then $\text{curl}(\mathbf{F}) = \mathbf{0}$;

$$\frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z}, \frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x}, \frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y}$$

- ② If $\text{curl}(\mathbf{F}) = \mathbf{0}$ in a simply connected domain D , then the differential form is exact in D .

† For the line integral in 2-D space, $\mathbf{F} = (F_1, F_2)$. \Rightarrow Exact, only if $\frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y}$.

Exact & Path Independence

- **Example 3.** $F = (2xyz^2, x^2z^2 + z \cos yz, 2x^2yz + y \cos yz)$

$$\checkmark (F_3)_y = 2x^2z + \cos yz - yz \sin yz = (F_2)_z, (F_1)_z = (F_3)_x, (F_2)_x = (F_1)_y \Rightarrow \text{exact}$$

$$\checkmark F_2 = \frac{\partial f}{\partial y} \Rightarrow f = \int F_2 dy = x^2yz^2 + \sin yz + g(x, y)$$

$$\checkmark f_x = 2xyz^2 + g_x = F_1 \Rightarrow g_x = 0 \text{ and } g = h(z)$$

$$\checkmark f_z = 2x^2yz + y \cos yz + h_z = F_3 \Rightarrow h_z = 0 \text{ and } h(z) = c$$

$$\checkmark f = x^2yz^2 + \sin yz$$

$$\checkmark \text{Line integral from A: (0, 0, 1) to B: } \left(1, \frac{\pi}{4}, 2\right), I = \int_C \mathbf{F} \cdot d\mathbf{r} = f(B) - f(A) = \pi + 1$$

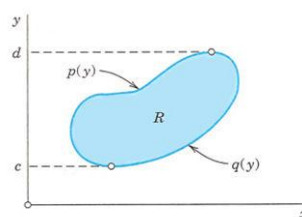
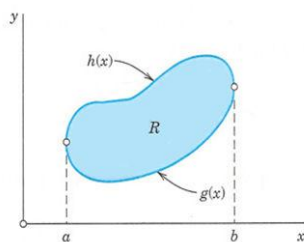
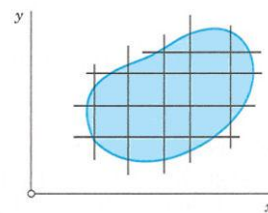
Double Integrals

- **Volume** of the region between the **surface** and **plane**.

$$\vee \iint_R f dx dy$$

$$\vee \iint_R f dx dy = \int_{x=a}^b \int_{g(x)}^{h(x)} f(x, y) dy dx$$

$$\vee \iint_R f dx dy = \int_{y=c}^d \int_{p(y)}^{q(y)} f(x, y) dx dy$$



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Double Integrals

- **Area**

$$\vee \text{Area of a region } R \text{ in } xy\text{-plane: } A = \iint_R dx dy$$

- **Volume**

$$\vee \text{Volume beneath the surface } z = f(x, y) > 0 \text{ and above } R \text{ in } xy\text{-plane:}$$

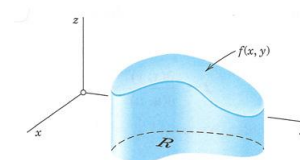
$$\vee V = \iint_R f(x, y) dx dy$$

- When $f(x, y)$ is the density of a distribution of mass in xy -plane,

$$\vee \text{Total mass in } R, M = \iint_R f(x, y) dx dy$$

$$\vee \text{Center of gravity, } \bar{x} = \frac{1}{M} \iint_R x f(x, y) dx dy, \bar{y} = \frac{1}{M} \iint_R y f(x, y) dx dy$$

$$\vee \text{Moment of inertia, } I_x = \iint_R y^2 f(x, y) dx dy, I_y = \iint_R x^2 f(x, y) dx dy$$



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Double Integrals

- **Jacobian:** Change of variables in double integrals

✓ From (x, y) to (u, v)

$$\checkmark \iint_R f(x, y) dx dy = \iint_{R^*} f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

$$\dagger \text{ Jacobian, } J = \frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \cdot \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \cdot \frac{\partial y}{\partial u}$$

✓ **Polar coordinate,** $x = r \cos \theta$, $y = r \sin \theta$; $r = \sqrt{x^2 + y^2}$, $\theta = \tan^{-1} \frac{y}{x}$

$$\dagger J = \left| \frac{\partial(x, y)}{\partial(r, \theta)} \right| = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r$$

$$\dagger \iint_R f(x, y) dx dy = \iint_{R^*} f(r \cos \theta, r \sin \theta) r dr d\theta$$

Double Integrals

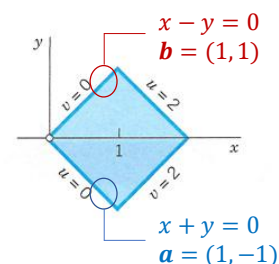
- **Example 1.** $\iint_R (x^2 + y^2) dx dy$, R ... square

✓ $x + y = u$, $x - y = v \Rightarrow R^* = \{(u, v): 0 \leq u \leq 2, 0 \leq v \leq 2\}$

✓ $x = \frac{1}{2}(u + v)$, $y = \frac{1}{2}(u - v) \Rightarrow x^2 + y^2 = \frac{1}{2}(u^2 + v^2)$

$$\checkmark J = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{vmatrix} = -\frac{1}{2}$$

$$\checkmark I = \iint_R (x^2 + y^2) dx dy = \int_{v=0}^2 \int_{u=2}^0 \frac{1}{2}(u^2 + v^2) \left(-\frac{1}{2}\right) du dv = \frac{8}{3}$$



$$\begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{aligned} \mathbf{a} &= (1, -1) \rightarrow T(\mathbf{a}) = (0, 2) \\ \mathbf{b} &= (1, 1) \rightarrow T(\mathbf{b}) = (2, 0) \\ \mathbf{c} &= (2, 0) \rightarrow T(\mathbf{c}) = (2, 2) \end{aligned}$$

$$I = \int_{x=0}^1 \int_{y=-x}^x (x^2 + y^2) dy dx + \int_{x=1}^2 \int_{y=x-2}^{-x+2} (x^2 + y^2) dy dx$$

Double Integrals

- **Example 2.** Density, $f(x, y) = 1$, R ... unit circle in 1st quadrant

$$\vee x = r \cos \theta, y = r \sin \theta; r = \sqrt{x^2 + y^2}, \theta = \tan^{-1} \frac{y}{x}, \text{ and } J = r$$

$$\vee \text{Mass, } M = \iint_R dx dy = \int_{\theta=0}^{\pi/2} \int_{r=0}^1 r dr d\theta = \frac{\pi}{4}$$

$$\vee \text{Center of gravity, } \bar{x} = \frac{1}{M} \iint_R x dx dy = \frac{4}{\pi} \int_{\theta=0}^{\pi/2} \int_{r=0}^1 (r \cos \theta) r dr d\theta = \frac{4}{3\pi}$$

$$\vee \text{Moment of inertia, } I_x = \iint_R y^2 dx dy = \int_{\theta=0}^{\pi/2} \int_{r=0}^1 (r \sin \theta)^2 r dr d\theta = \frac{\pi}{16}$$

Green's Theorem in the Plane

- **Theorem 1. Green's theorem**

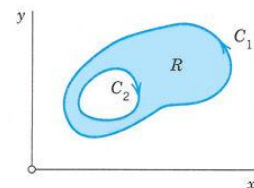
Let R be a closed bounded region in the xy -plane whose boundary C consists of finitely many smooth curves. Let $F_1(x, y)$ and $F_2(x, y)$ be functions that are continuous and have continuous partial derivatives $\partial F_1 / \partial y$ and $\partial F_2 / \partial x$ everywhere in some domain containing R . Then

$$\iint_R \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy = \oint_C (F_1 dx + F_2 dy)$$

Here we integrate along the entire boundary C of R in such a sense that R is on the left as we advance in the direction of integration.

$$\vee \text{ If } \mathbf{F} = (F_1, F_2, 0), \iint_R \text{curl}(\mathbf{F}) \cdot \mathbf{k} dx dy = \oint_C \mathbf{F} \cdot d\mathbf{r}$$

† Transform between double integral and line integral



Green's Theorem in the Plane

- Example 1. $F_1 = y^2 - 7y$, $F_2 = 2xy + 2x$, $C: x^2 + y^2 = 1$

$$\vee \iint_R \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy = \iint_R (2y + 2 - (2y - 7)) dx dy = \int_{\theta=0}^{2\pi} \int_{r=0}^1 9r dr d\theta = 9\pi$$

$$\dagger C: \mathbf{r}(t) = (\cos t, \sin t), \mathbf{dr} = (-\sin t, \cos t), 0 \leq t \leq 2\pi$$

$$\dagger \mathbf{F} = (\sin^2 t - 7 \sin t, 2 \cos t \cdot \sin t + 2 \cos t)$$

$$\vee \oint_C \mathbf{F} \cdot d\mathbf{r} = \int_{t=0}^{2\pi} (-\sin^3 t - 7 \sin^2 t + 2 \cos^2 t \cdot \sin t + 2 \cos^2 t) dt = 0 + 7\pi - 0 + 2\pi$$

- Example 2. Area of a plane region over the boundary C

$$\vee \text{Choose } F_1 = 0, F_2 = x:$$

$$\dagger A = \iint_R \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy = \iint_R dx dy = \oint_C (F_1 dx + F_2 dy) = \oint_C x dy$$

$$\vee \text{Choose } F_1 = -y, F_2 = 0:$$

$$\dagger A = \iint_R dx dy = -\oint_C y dy$$

Green's Theorem in the Plane

- Example 2. Area of a plane region over the boundary C

$$\vee A = \frac{1}{2} \oint_C (x dy - y dx) \leftarrow \text{Green's theorem with } F_1 = -y, F_2 = x$$

$$\vee \text{When } R \text{ is a region covered by an ellipse, } C: \frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

$$\dagger C: \mathbf{r}(t) = (a \cos t, b \sin t), t \in [0, 2\pi) \quad A = \frac{1}{2} \int_{t=0}^{2\pi} (a \cos t \cdot b \cos t + b \sin t \cdot a \cos t) dt = \pi ab$$

- Example 3. Area of a plane region (polar coordinates)

$$\vee x = r \cos \theta, y = r \sin \theta: dx = \cos \theta dr - r \sin \theta d\theta, dy = \sin \theta dr + r \cos \theta d\theta,$$

$$\dagger x dy - y dx = r \cos \theta (\sin \theta dr + r \cos \theta d\theta) - r \sin \theta (\cos \theta dr - r \sin \theta d\theta) = r^2 d\theta$$

$$\vee A = \frac{1}{2} \oint_C r^2 d\theta$$

$$\vee \text{Cardioid, } r = a(1 - \cos \theta), \theta \in [0, 2\pi)$$

$$\dagger A = \frac{a^2}{2} \int_{\theta=0}^{2\pi} (1 - \cos \theta) d\theta = \frac{3\pi}{2} a^2$$

Surfaces

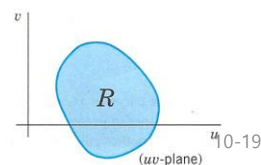
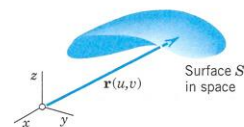
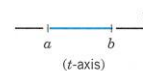
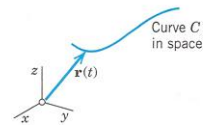
- Parametric representation of surfaces

✓ $z = f(x, y)$ or $g(x, y, z) = 0$

† e.g., hemisphere 반구, $z = \sqrt{a^2 - x^2 - y^2}$ ($z \geq 0$)

✓ $\mathbf{r}(u, v) = (x(u, v), y(u, v), z(u, v)) \leftarrow$ two parameters u and v

† Extension of a curve, $\mathbf{r}(t) = (x(t), y(t), z(t))$



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Surfaces: Parametric Representation

- Example 1. Circular cylinder

✓ $x^2 + y^2 = a^2, -1 \leq z \leq 1$

✓ $\mathbf{r}(u, v) = (a \cos u, a \sin u, v), u \in [0, 2\pi)$ and $v \in [-1, 1]$

† Fixed $u = u_0, \mathbf{r}(u_0, v) \dots$ vertical line, while fixed $v = v_0, \mathbf{r}(u, v_0) \dots$ circle

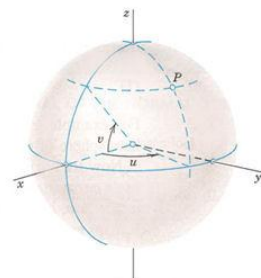
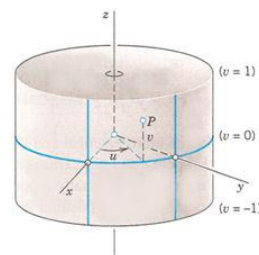
- Example 2. Sphere

✓ $x^2 + y^2 + z^2 = a^2, -1 \leq z \leq 1$

✓ $\mathbf{r}(u, v) = (a \cos v \cos u, a \cos v \sin u, a \sin v), u \in [0, 2\pi)$ and $v \in [-\pi, \pi)$

† Spherical coordinate system

✓ $\mathbf{r}(u, v) = (a \cos u \cos v, a \sin u \cos v, a \sin v), u \in [0, 2\pi), v \in [0, \pi)$



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Surfaces: Tangent Plane

- **Tangent plane:**

- ∨ A plane which is formed by tangent vectors of all the curves on a surface S through a point P in S .

- † **Normal vector** to the tangent plane

- † Given $S: \mathbf{r}(u, v)$, choose a **curve on S** by taking $u = u(t)$ and $v = v(t)$: $C: \tilde{\mathbf{r}}(t) = \mathbf{r}(u(t), v(t))$.

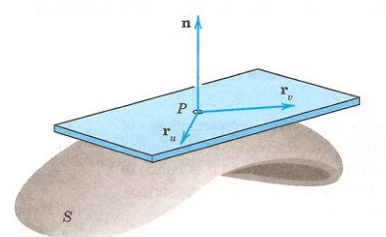
- † **Tangent vector** of C on S , $\tilde{\mathbf{r}}'(t) = \frac{\partial \mathbf{r}}{\partial u} \cdot \frac{du}{dt} + \frac{\partial \mathbf{r}}{\partial v} \cdot \frac{dv}{dt} = \mathbf{r}_u u' + \mathbf{r}_v v'$

- Linear combination of \mathbf{r}_u and \mathbf{r}_v .

- \mathbf{r}_u and \mathbf{r}_v span the tangent plane of S at P .

- † **Normal vector**, \mathbf{N} of S at P , $\mathbf{N} = \mathbf{r}_u \times \mathbf{r}_v \neq \mathbf{0}$

- **Unit normal vector**, $\mathbf{n} = \frac{\mathbf{N}}{|\mathbf{N}|}$



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Surfaces: Tangent Plane

- When $S: g(x, y, z) = 0$

- ∨ $\mathbf{n} = \frac{\text{grad}(g)}{|\text{grad}(g)|}$... gradient is a surface normal vector for a surface, $S: g(x, y, z) = 0$

- **Example 4. Sphere**

- ∨ $g(x, y, z) = x^2 + y^2 + z^2 - a^2 = 0$

- ∨ $\text{grad}(g) = (2x, 2y, 2z)$, $|\text{grad}(g)| = \sqrt{4x^2 + 4y^2 + 4z^2} = 2a$

- ∨ $\mathbf{n} = \left(\frac{x}{a}, \frac{y}{a}, \frac{z}{a} \right)$

공업수학2: 10. Vector Integral Calculus

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Surfaces: Tangent Plane

• Example 4. Sphere

$$\vee g(x, y, z) = x^2 + y^2 + z^2 - a^2 = 0$$

$$\vee \mathbf{r}(u, v) = (a \cos v \cdot \cos u, a \cos v \cdot \sin u, a \sin v)$$

$$\vee \mathbf{r}_u = (-a \cos v \cdot \sin u, a \cos v \cdot \cos u, 0), \mathbf{r}_v = (-a \sin v \cdot \cos u, -a \sin v \cdot \sin u, a \cos v)$$

$$\vee \text{Normal vector, } \mathbf{N} = \mathbf{r}_u \times \mathbf{r}_v = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -a \cos v \cdot \sin u & a \cos v \cdot \cos u & 0 \\ -a \sin v \cdot \cos u & -a \sin v \cdot \sin u & a \cos v \end{vmatrix}$$

$$\dagger \mathbf{N} = (a^2 \cos^2 v \cdot \cos u, a^2 \cos^2 v \cdot \sin u, a^2 \cos v \cdot \sin v \cdot \sin^2 u + a^2 \cos v \cdot \sin v \cdot \cos^2 u) = (a^2 \cos^2 v \cdot \cos u, a^2 \cos^2 v \cdot \sin u, a^2 \cos v \cdot \sin v)$$

$$\dagger |\mathbf{N}|^2 = a^4 \cos^2 v (\cos^2 v \cdot \cos^2 u + \cos^2 v \cdot \sin^2 u + \sin^2 v) = a^4 \cos^2 v$$

$$\vee \text{Unit normal vector, } \mathbf{n} = (\cos v \cdot \cos u, \cos v \cdot \sin u, \sin v) = \left(\frac{x}{a}, \frac{y}{a}, \frac{z}{a}\right)$$

Surface Integrals

• Surface

$$\vee S: \mathbf{r}(u, v) = (x(u, v), y(u, v), z(u, v)), \text{ where } (u, v) \in R$$

$$\vee \text{Unit normal vector, } \mathbf{n} = \frac{\mathbf{N}}{|\mathbf{N}|}, \text{ where } \mathbf{N} = \mathbf{r}_u \times \mathbf{r}_v$$

$$\bullet \text{Surface integral: } \iint_S \mathbf{F} \cdot \mathbf{n} dA = \iint_R \mathbf{F}(u, v) \cdot \mathbf{N}(u, v) du dv$$

$$\vee dA = |\mathbf{N}| du dv \text{ and } \mathbf{N}(u, v) = |\mathbf{N}| \mathbf{n}(u, v)$$

$$\vee \text{When } \mathbf{F} = (F_1, F_2, F_3), \mathbf{N} = (N_1, N_2, N_3), \text{ and } \mathbf{n} = (\cos \alpha, \cos \beta, \cos \gamma)$$

$$\vee \iint_S \mathbf{F} \cdot \mathbf{n} dA = \iint_S (F_1 \cos \alpha + F_2 \cos \beta + F_3 \cos \gamma) dA = \iint_R (F_1 N_1 + F_2 N_2 + F_3 N_3) du dv = \iint_S (F_1 dy dz + F_2 dz dx + F_3 dx dy)$$

$$\dagger \mathbf{n} \cdot \mathbf{i} = \cos \alpha, \mathbf{n} \cdot \mathbf{j} = \cos \beta, \mathbf{n} \cdot \mathbf{k} = \cos \gamma \Rightarrow \mathbf{n} = \cos \alpha \mathbf{i} + \cos \beta \mathbf{j} + \cos \gamma \mathbf{k}$$

$$\dagger \cos \alpha dA = dy dz, \cos \beta dA = dz dx, \cos \gamma dA = dx dy$$

Surface Integrals

• Example 1. Flux through a surface

$$\vee \mathbf{F} = \mathbf{v} = (3z^2, 6, 6xz), S: y = x^2, 0 \leq x \leq 2, 0 \leq z \leq 3$$

$$\vee \mathbf{r}(u, v) = (u, u^2, v), 0 \leq u \leq 2, 0 \leq v \leq 3$$

$$\dagger \mathbf{r}_u = (1, 2u, 0), \mathbf{r}_v = (0, 0, 1) \Rightarrow \mathbf{N} = \mathbf{r}_u \times \mathbf{r}_v = (2u, -1, 0)$$

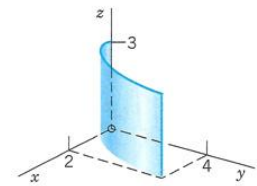
$$\vee \mathbf{F}(u, v) \cdot \mathbf{N} = (3v^2, 6, 6uv) \cdot (2u, -1, 0) = 6uv^2 - 6$$

$$\vee \iint_S \mathbf{F} \cdot \mathbf{n} dA = \iint_R \mathbf{F} \cdot \mathbf{N} du dv = \int_{v=0}^3 \int_{u=0}^2 (6uv^2 - 6) du dv = 72$$

$$\vee \iint_S (F_1 \cos \alpha + F_2 \cos \beta + F_3 \cos \gamma) dA = \int_{z=0}^3 \int_{y=0}^4 3z^2 dy dz - \int_{x=0}^2 \int_{z=0}^3 6 dz dx = 72$$

$$\dagger \mathbf{N} = (2x, -1, 0) \Rightarrow \cos \alpha > 0, \cos \beta < 0, \text{ and } \cos \gamma = 0$$

$$\dagger \cos \alpha dA = dydz, \cos \beta dA = dzdx, \cos \gamma dA = dxdy$$



Surface Integrals

• Example 2. Surface integral

$$\vee \mathbf{F} = (x^2, 0, 3y^2), S: x + y + z = 1, 0 \leq x, y, z \leq 1 \text{ (1st octant)}$$

$$\vee \text{ Choose } u = x \text{ and } v = y, S: \mathbf{r}(u, v) = (u, v, 1 - u - v),$$

$$\dagger R = \{(u, v); 0 \leq u \leq 1, 0 \leq v \leq 1, u + v \leq 1\} \dots \text{triangle in } xy\text{-plane (projection of surface } S \text{ onto } xy\text{-plane)}$$

$$\dagger \mathbf{r}_u = (1, 0, -1), \mathbf{r}_v = (0, 1, -1) \Rightarrow \mathbf{N} = \mathbf{r}_u \times \mathbf{r}_v = (1, 1, 1)$$

$$\vee \mathbf{F}(u, v) \cdot \mathbf{N} = u^2 + 3v^2$$

$$\vee \iint_S \mathbf{F} \cdot \mathbf{n} dA = \iint_R \mathbf{F} \cdot \mathbf{N} du dv = \int_{v=0}^1 \int_{u=0}^{1-v} (u^2 + 3v^2) du dv = \frac{1}{3}$$

$$\vee \iint_S (F_1 \cos \alpha + F_2 \cos \beta + F_3 \cos \gamma) dA = \int_{z=0}^1 \int_{y=0}^{1-z} (1 - y - z)^2 dy dz + \int_{y=0}^1 \int_{x=0}^{1-y} 3y^2 dx dy$$

$$\dagger \mathbf{N} = (1, 1, 1) \Rightarrow \cos \alpha > 0, \cos \beta > 0, \text{ and } \cos \gamma > 0$$

Surface Integrals: Second Type

- $\iint_S G(\mathbf{r})dA = \iint_R G(\mathbf{r}(u, v))|\mathbf{N}(u, v)|dudv$

∨ $dA = |\mathbf{N}|dudv = |\mathbf{r}_u \times \mathbf{r}_v|dudv$

∨ Surface area, $A(S) = \iint_S dA = \iint_R |\mathbf{r}_u \times \mathbf{r}_v|dudv$

- Example 4. Surface area of a sphere

∨ $\mathbf{r}(u, v) = (a \cos v \cdot \cos u, a \cos v \cdot \sin u, a \sin v)$

∨ Normal vector, $\mathbf{N} = \mathbf{r}_u \times \mathbf{r}_v = a^2 \cos v (\cos v \cdot \cos u, \cos v \cdot \sin u, \sin v)$

† $|\mathbf{N}| = a^2 |\cos v|$

∨ $A(S) = a^2 \int_{v=-\pi}^{\pi} \int_{u=0}^{2\pi} |\cos v| du dv = 2\pi a^2 \int_{v=-\pi}^{\pi} \cos v dv = 4\pi a^2$

Triple Integral

∨ An integral of a function $f(x, y, z)$ over a closed bounded region T .

- Theorem 1. Divergence theorem

Let T be a closed bounded region in the space whose boundary is a piecewise smooth orientable surface S . Let $\mathbf{F}(x, y, z)$ be a function that is continuous and has continuous partial derivatives in some domain containing T . Then

$$\iiint_T \operatorname{div}(\mathbf{F})dV = \iint_S \mathbf{F} \cdot \mathbf{n}dA$$

∨ If $\mathbf{F} = (F_1, F_2, F_3)$ and the outer unit normal vector $\mathbf{n} = (\cos \alpha, \cos \beta, \cos \gamma)$ of S ,

$$\iiint_T \operatorname{div}(\mathbf{F})dV = \iiint_T \left(\frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \right) dx dy dz = \dots$$

$$\dots = \iint_S (F_1 \cos \alpha + F_2 \cos \beta + F_3 \cos \gamma) dA = \iint_S (F_1 dy dz + F_2 dz dx + F_3 dx dy)$$

Divergence Theorem

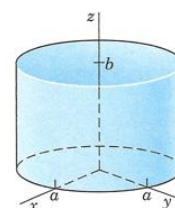
- It relates the flux of a vector field through a closed surface S to the divergence over the region T inside the surface S .
- The surface integral of a vector field over a closed surface S is equal to the volume integral of divergence over the region inside the surface.

• Example 1. $I = \iint_S (x^3 dydz + x^2 ydzdx + x^2 zdx dy)$

✓ $S: x^2 + y^2 = a^2, 0 \leq z \leq b$ (surface of a cylinder and two circular disks)

✓ $\text{div}(\mathbf{F}) = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} = 3x^2 + x^2 + x^2 = 5x^2$

✓ $I = \iiint_T 5x^2 dx dy dz = \int_{z=0}^b \int_{\theta=0}^{2\pi} \int_{r=0}^a 5(r \cos \theta)^2 dr d\theta dz = \frac{5\pi}{4} a^4 b$



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Divergence Theorem

• Example 1 (contd.). $I = \iint_S (x^3 dydz + x^2 ydzdx + x^2 zdx dy)$

✓ $S_1: x^2 + y^2 = a^2, 0 \leq z \leq b$ (surface of a cylinder)

† $x = a \cos u, y = a \sin u, z = v, C_1: \mathbf{r}_1(u, v) = (a \cos u, a \sin u, v)$

† $\mathbf{r}_{1u} = (-a \sin u, a \cos u, 0), \mathbf{r}_{1v} = (0, 0, 1) \Rightarrow \mathbf{N} = \mathbf{r}_{1u} \times \mathbf{r}_{1v} = (a \cos u, a \sin u, 0)$

† $\mathbf{F} \cdot \mathbf{N} = (x^3, x^2 y, x^2 z) \cdot (x, y, 0) = x^4 + x^2 y^2 = a^4 \cos^2 u$

† $I_1 = \iint_R \mathbf{F} \cdot \mathbf{N} du dv = \int_{v=0}^b \int_{u=0}^{2\pi} \frac{1}{2} a^4 (1 + \cos 2u) du dv = \pi a^4 b$

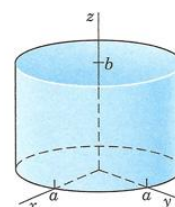
✓ $S_2: x^2 + y^2 = a^2, z = b$ (top disk)

† $\mathbf{n}_2 = \mathbf{k} \Rightarrow \cos \alpha = \mathbf{i} \cdot \mathbf{n}_1 = 0 = \cos \beta$ and $dA = \cos \gamma dx dy = dx dy$

† $I_2 = \iint_S F_3 dx dy = \iint_S x^2 z dx dy = \int_{\theta=0}^{2\pi} \int_{r=0}^a (r \cos \theta)^2 \cdot b \cdot r dr d\theta = \frac{\pi}{4} a^4 b$

✓ $S_3: x^2 + y^2 = a^2, z = 0$ (bottom disk), $\mathbf{n}_3 = -\mathbf{k}$ and $I_3 = 0$ (since $z = 0$)

✓ $I = I_1 + I_2 + I_3 = \pi a^4 b + \frac{\pi}{4} a^4 b + 0 = \frac{5\pi}{4} a^4 b$



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Divergence Theorem

- **Example 2.** $\mathbf{F} = (7x, 0, -z)$ and $S: x^2 + y^2 + z^2 = 4$ (sphere)

$$\vee I = \iiint_T \operatorname{div}(\mathbf{F}) dV = \iint_S \mathbf{F} \cdot \mathbf{n} dA$$

$$\dagger \operatorname{div}(\mathbf{F}) = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} = 7 - 1 = 6$$

$$\vee I = \iiint_T 6 dV = 6 \cdot \frac{4}{3} \pi (2^2) = 64\pi$$

$$\vee S: \mathbf{r}(u, v) = (a \cos v \cdot \cos u, a \cos v \cdot \sin u, a \sin v)$$

$$\dagger \mathbf{r}_u = (-a \cos v \cdot \sin u, a \cos v \cdot \cos u, 0), \mathbf{r}_v = (-a \sin v \cdot \cos u, -a \sin v \cdot \sin u, a \cos v)$$

$$\dagger \mathbf{N} = \mathbf{r}_u \times \mathbf{r}_v = 4 \cos v (\cos v \cdot \cos u, \cos v \cdot \sin u, \sin v)$$

$$\dagger \mathbf{F} \cdot \mathbf{N} = (14 \cos v \cdot \cos u, 0, -2 \sin v) \cdot \mathbf{N} = 56 \cos^3 v \cdot \cos^2 u - 8 \cos v \cdot \sin^2 v$$

$$\vee I = \iint_S \mathbf{F} \cdot \mathbf{n} dA = \iint_R \mathbf{F} \cdot \mathbf{N} du dv = \int_{v=-\pi}^{\pi} \int_{u=0}^{2\pi} (56 \cos^3 v \cdot \cos^2 u - 8 \cos v \cdot \sin^2 v) du dv$$

Stoke's Theorem

- **Theorem 1. Stoke's theorem**

Let S be a piecewise smooth orientable surface and let the boundary of S be a piecewise smooth simple closed curve C . Let $\mathbf{F}(x, y, z)$ be a function that is continuous and has continuous partial derivatives in some domain containing S . Then

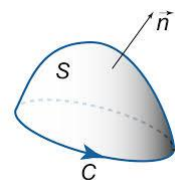
$$\iint_S \operatorname{curl}(\mathbf{F}) \cdot \mathbf{n} dA = \oint_C \mathbf{F} \cdot \mathbf{r}'(s) ds$$

Here \mathbf{n} is a unit normal vector of S and $\mathbf{r}'(s) = \frac{d\mathbf{r}}{ds}$ is the unit tangent vector and s the arc length of C .

$$\vee \text{ If } \mathbf{F} = (F_1, F_2, F_3), \mathbf{N} = (N_1, N_2, N_3), \mathbf{n} dA = \mathbf{N} du dv, \mathbf{r}' ds = (dx, dy, dz)$$

$$\iint_R \left(\left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) N_1 + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) N_2 + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) N_3 \right) du dv = \oint_C (F_1 dx + F_2 dy + F_3 dz)$$

$\dagger R$ is the region with boundary curve \bar{C} in the uv -plane corresponding to S represented by $\mathbf{r}(u, v)$.



Stoke's Theorem

- Example 1. $\mathbf{F} = (y, z, x)$, $S: z = 1 - (x^2 + y^2)$, $z \geq 0$... paraboloid

$$\vee C: \mathbf{r}(s) = (\cos s, \sin s, 0)$$

$$\dagger \mathbf{r}'(s) = (-\sin s, \cos s, 0), \mathbf{F}(\mathbf{r}(s)) = (\sin s, 0, \cos s)$$

$$\vee \oint_C \mathbf{F} \cdot \mathbf{r}'(s) ds = \int_{s=0}^{2\pi} (-\sin^2 s) ds = -\pi$$

$$\vee \text{curl}(\mathbf{F}) = \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} = \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z}, \frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x}, \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) = (-1, -1, -1)$$

$$\dagger \text{ Given } S: g(x, y, z) = x^2 + y^2 + z - 1 = 0, \mathbf{N} = \text{grad}(g) = (2x, 2y, 1)$$

$$\dagger \text{curl}(\mathbf{F}) \cdot \mathbf{N} = -2x - 2y - 1$$

$$\vee \iint_S \text{curl}(\mathbf{F}) \cdot \mathbf{n} dA = \iint_R \text{curl}(\mathbf{F}) \cdot \mathbf{N} dx dy = \iint_R (-2x - 2y - 1) dx dy \dots$$

$$\dagger \dots \int_{\theta=0}^{2\pi} \int_{r=0}^1 (-2r(\cos \theta + \sin \theta) - 1) r dr d\theta = -\pi$$

