

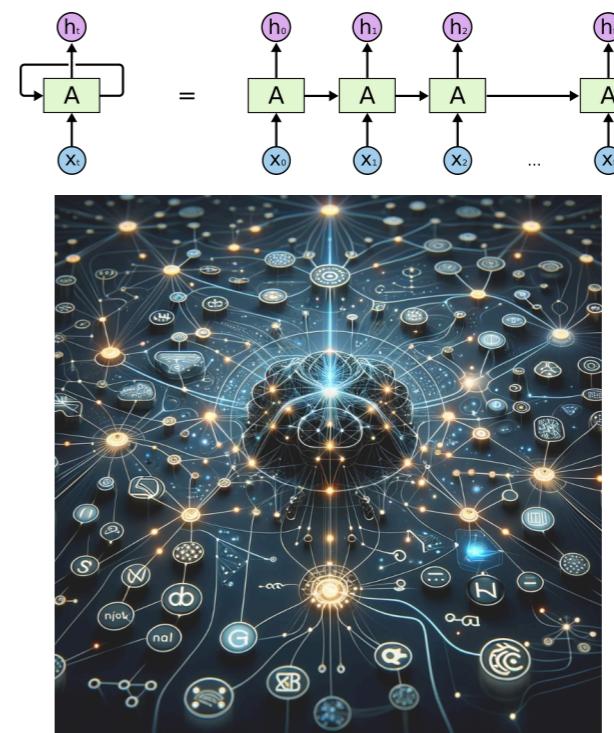
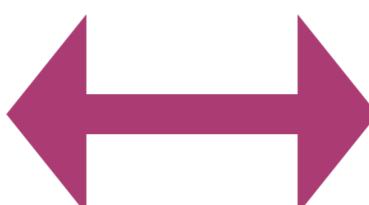
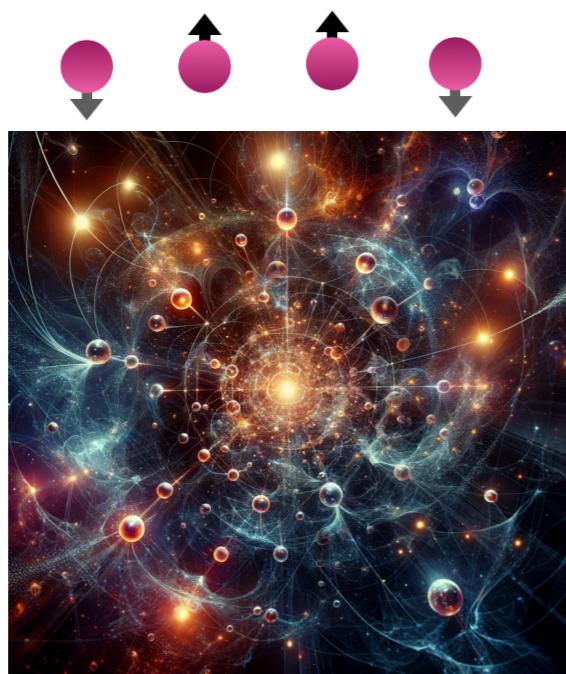
From explainable NLP to quantum dynamics prediction:

A two-way synergy between many-body quantum physics and temporal machine learning models

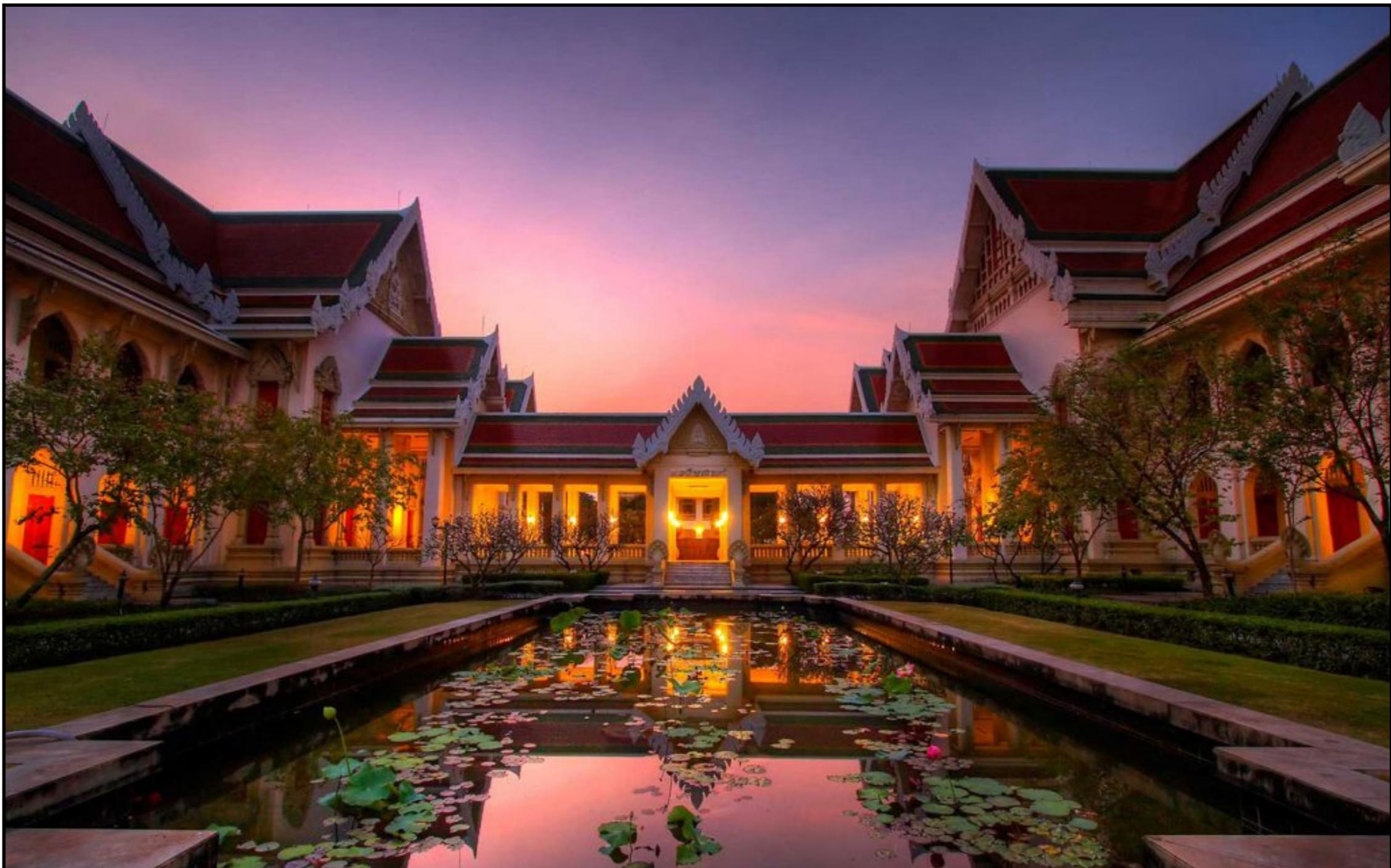
Thiparat Chotibut (Thip)

Chula Intelligent and Complex Systems Research Unit,
Chulalongkorn University, Bangkok, Thailand

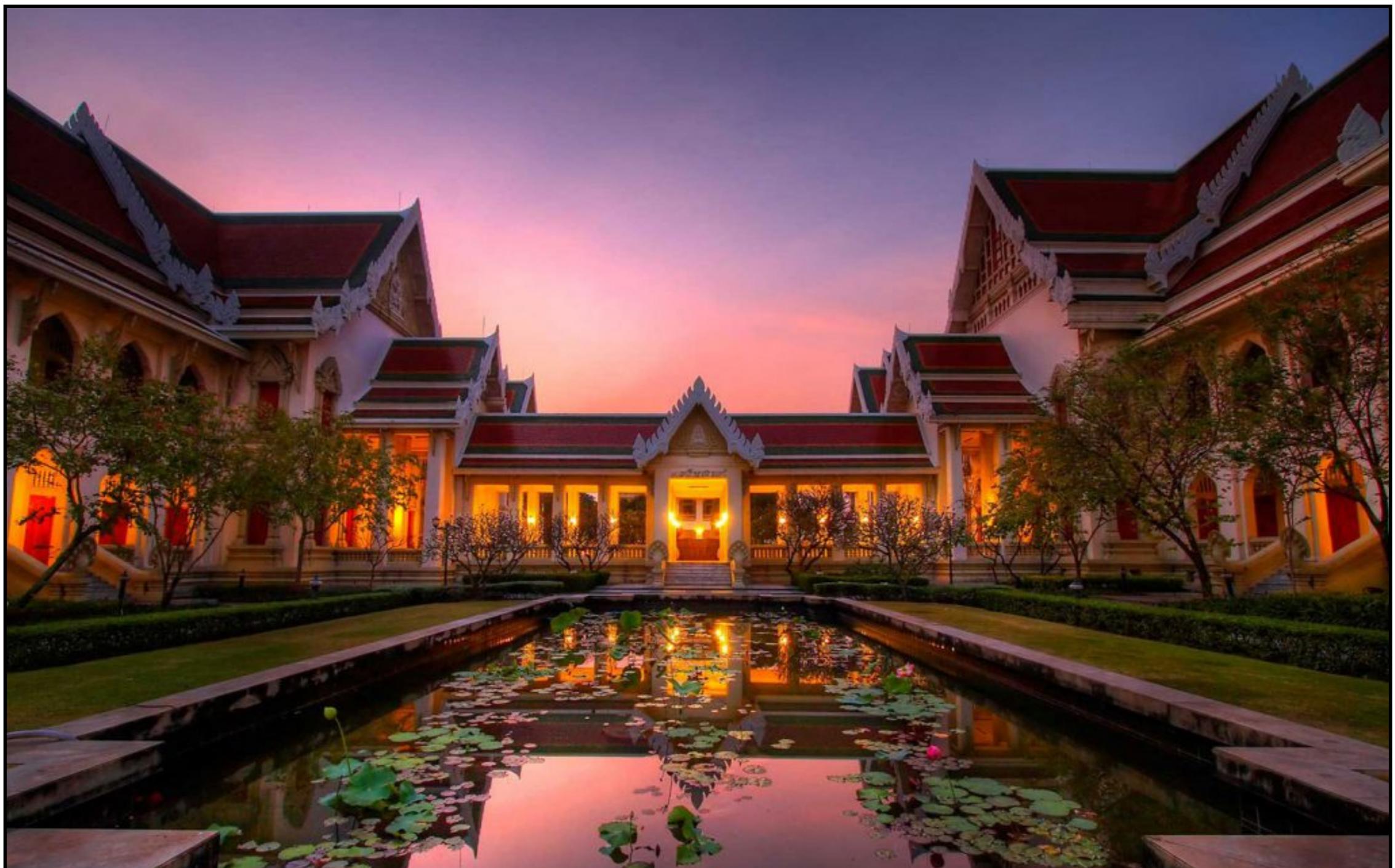
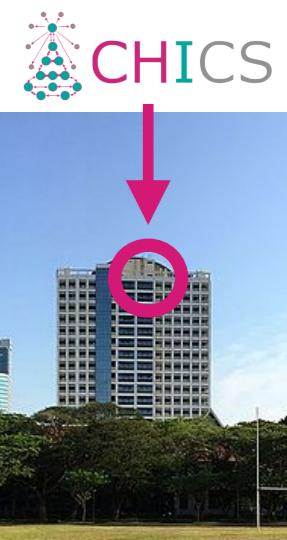
April 18, 2024
CS Katha Barta



Chulalongkorn University, Bangkok



Chulalongkorn University, Bangkok



Chula Intelligent & Complex Systems

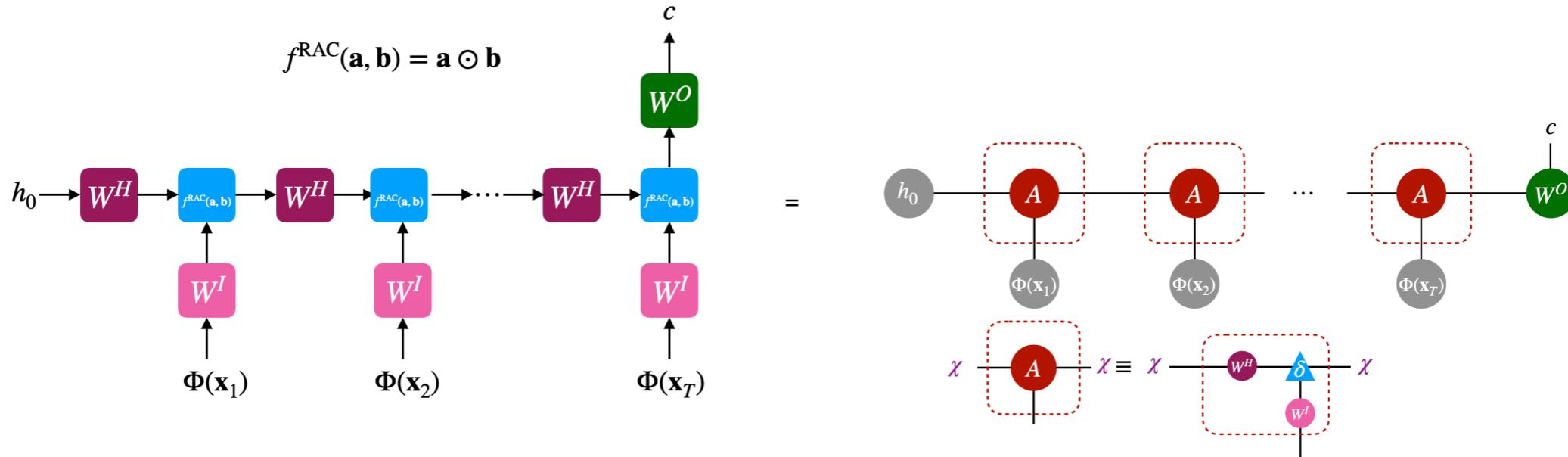
Welcome!

Our research lab investigates scientific frontiers at the intersection of complex systems and intelligent systems. See more details in [research & publications](#).



Outline

Part 1: Quantum Meets Language



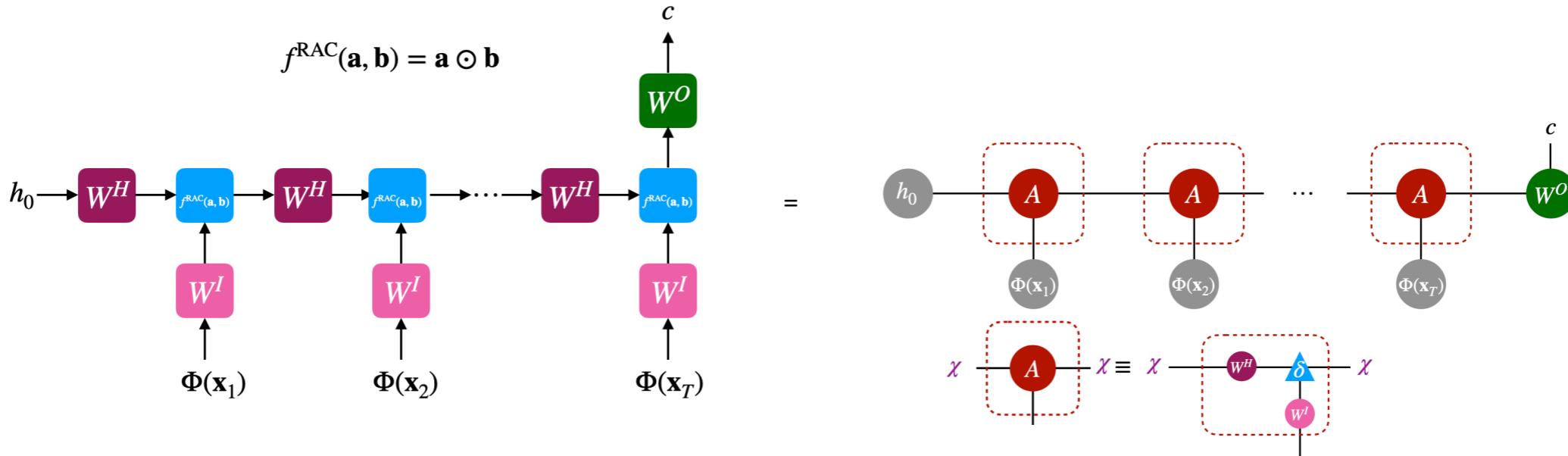
J. Tangpanitanon, ..., T. Chotibut



NJP 2022

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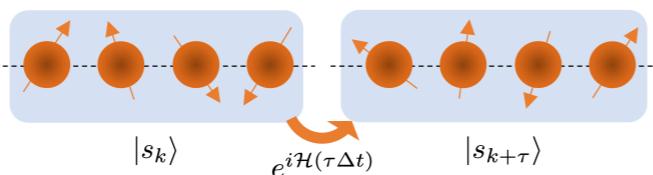
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NJP 2022

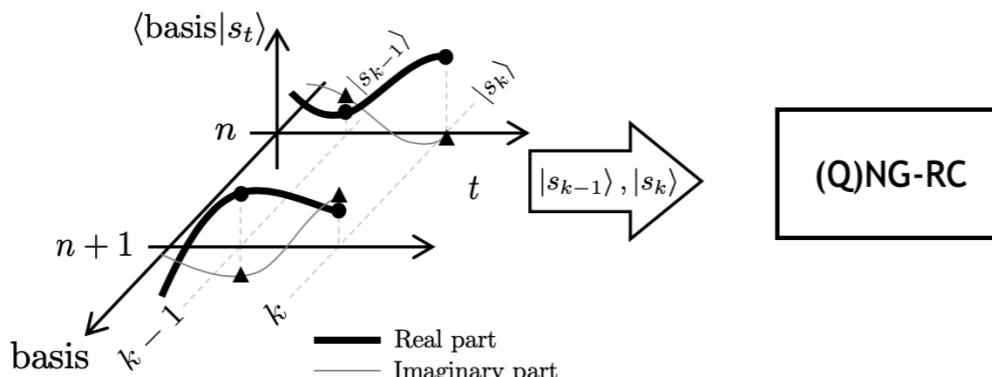
Part 2: Next Generation Reservoir Computing (NG-RC) for Many-body Quantum Dynamics Prediction

$$\mathcal{H} = -J \sum_{i=1}^4 Z_i Z_{i+1} + h \sum_{i=1}^4 X_i$$



$$|s_t\rangle = e^{iHt}|s_0\rangle$$

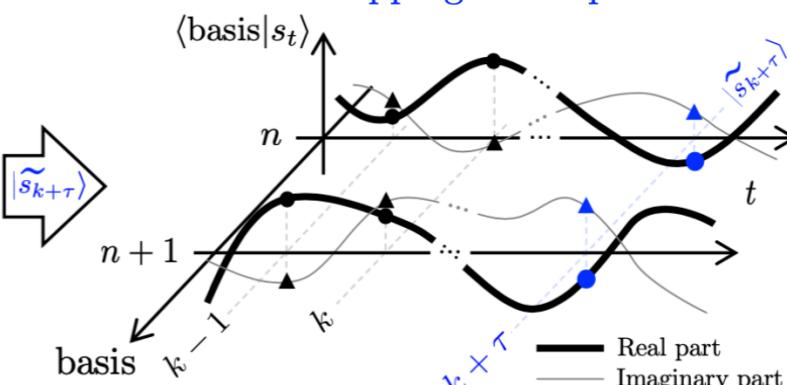
Quantum dynamics



Skipping-ahead prediction

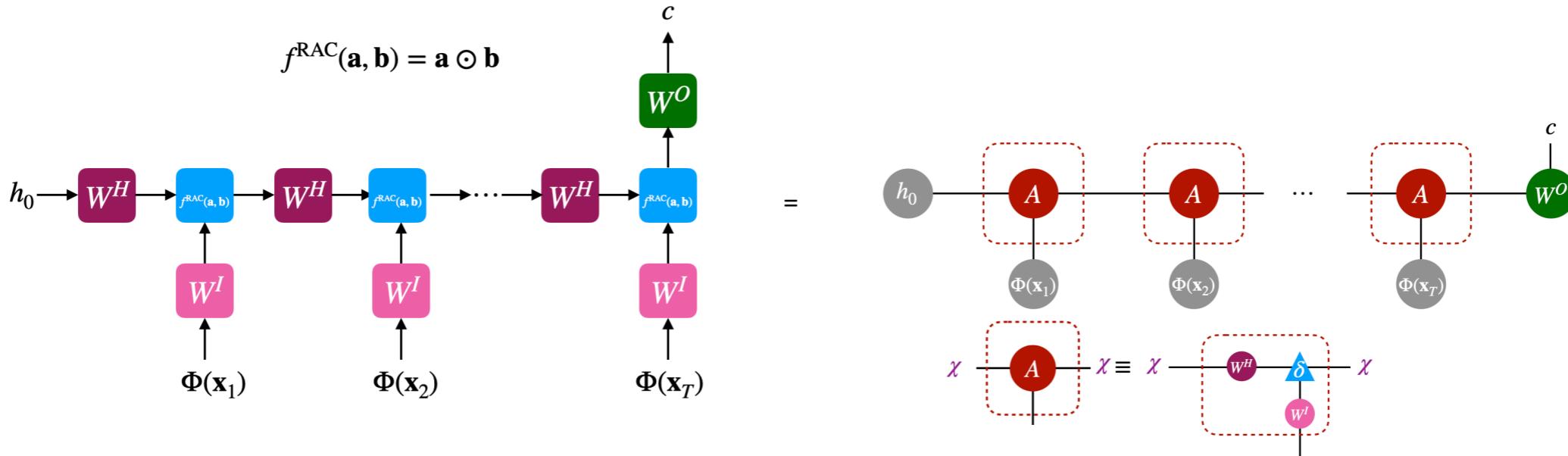
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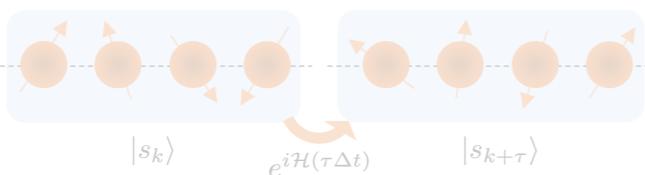
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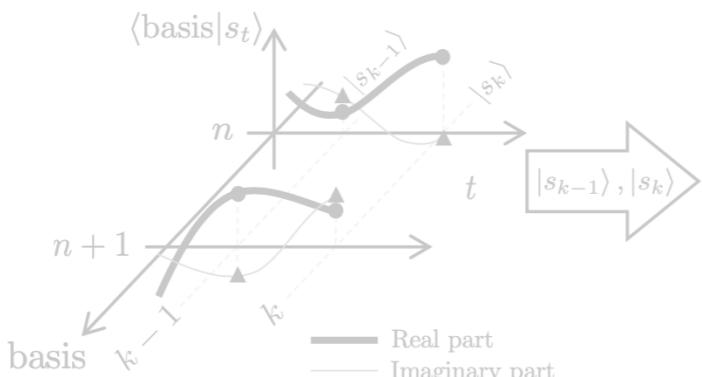
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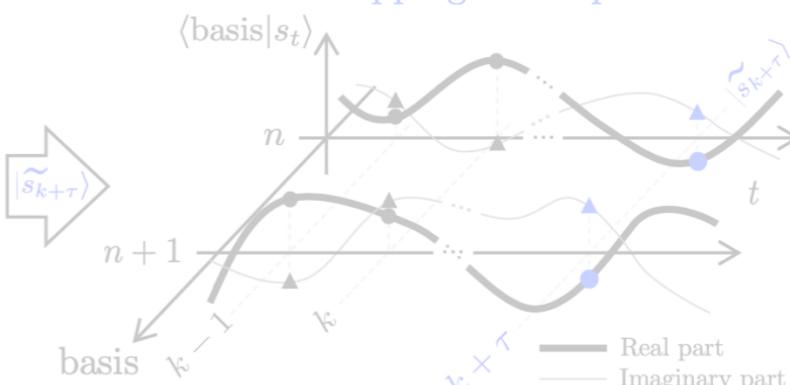


(Q)NG-RC

Skipping-ahead prediction

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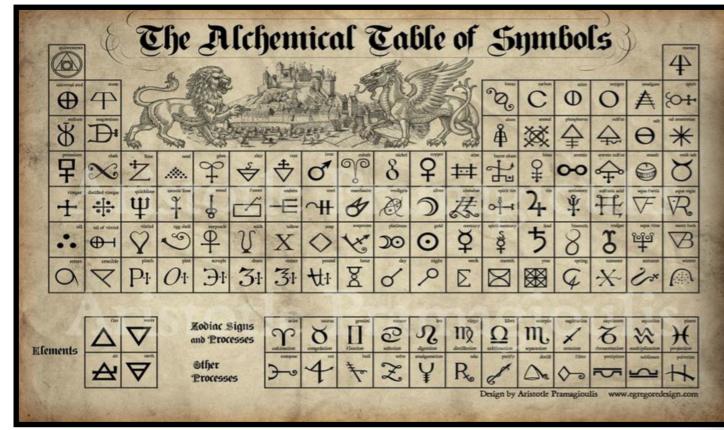
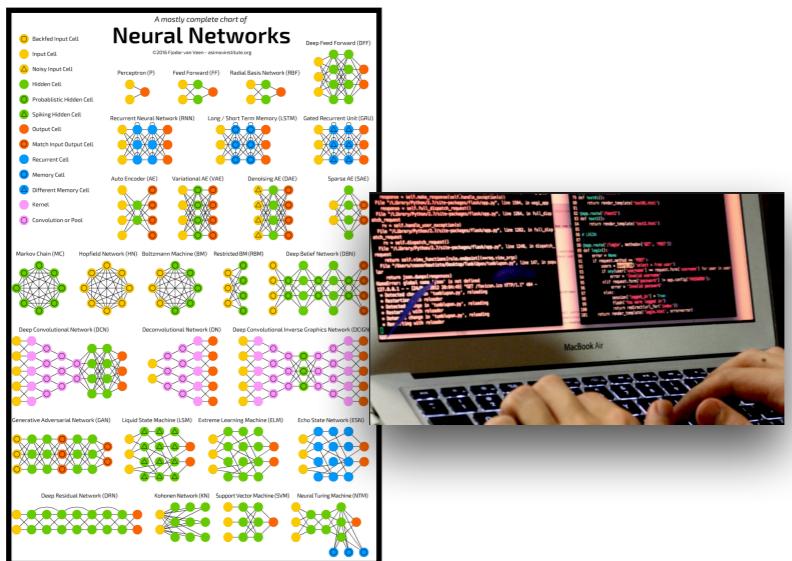
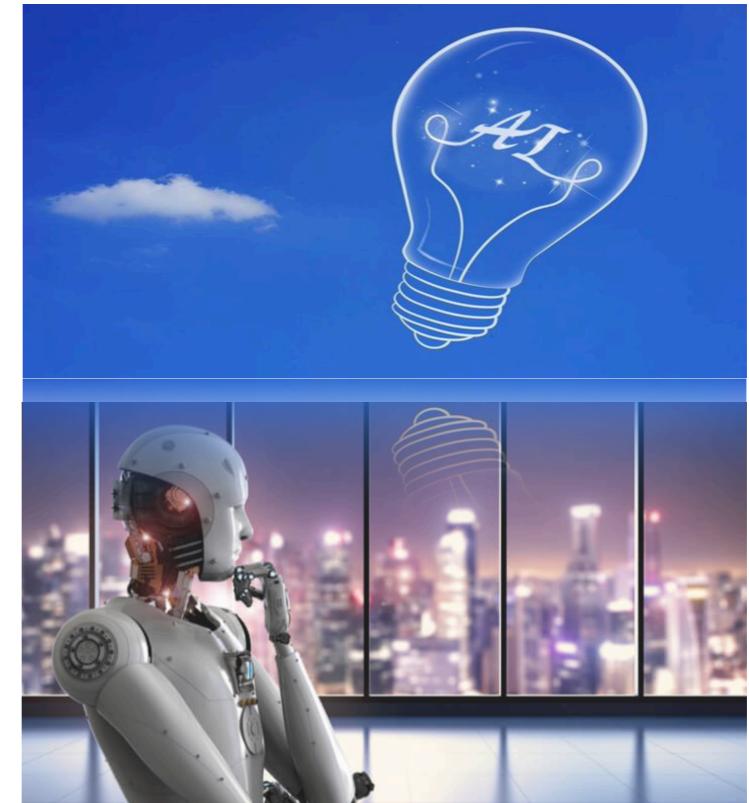
'AI IS THE NEW ELECTRICITY'



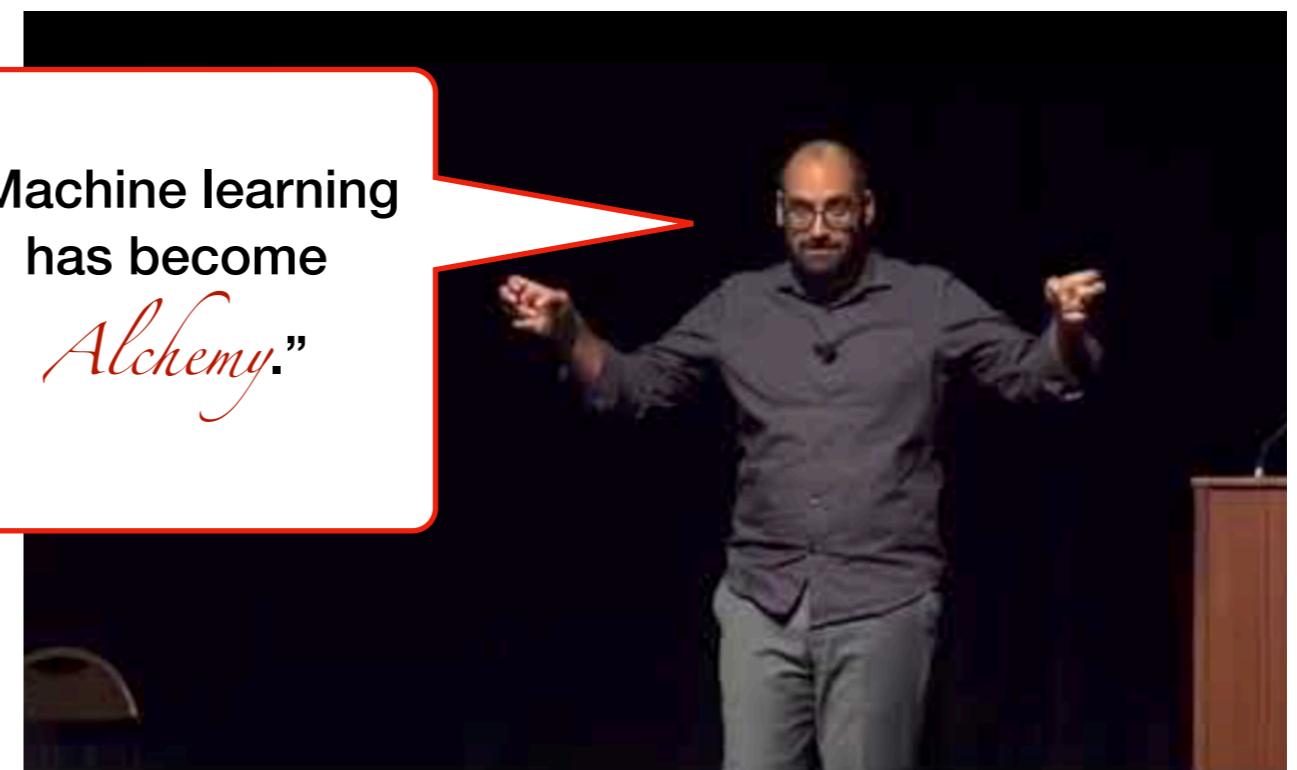
"Just as electricity transformed almost everything 100 years ago, today I actually have a hard time thinking of an industry that I don't think AI will transform in the next several years."

Andrew Ng

Former chief scientist at Baidu, Co-founder at Coursera



"Machine learning
has become
Alchemy."



Ali Rahimi (Google) at NIPS 2017

Statistical Sequence Modeling

Next word prediction



$$P(x_n | x_{n-1}, \dots, x_1)$$

Statistical Sequence Modeling

Next word prediction



$$P(x_n | x_{n-1}, \dots, x_1)$$

Sentiment Analysis

“This is a great movie!!” $\sigma = +1$
“This is a boring movie...” $\sigma = -1$

$$P(\sigma | x_n, \dots, x_1)$$

Statistical Sequence Modeling

Next word prediction



Sentiment Analysis

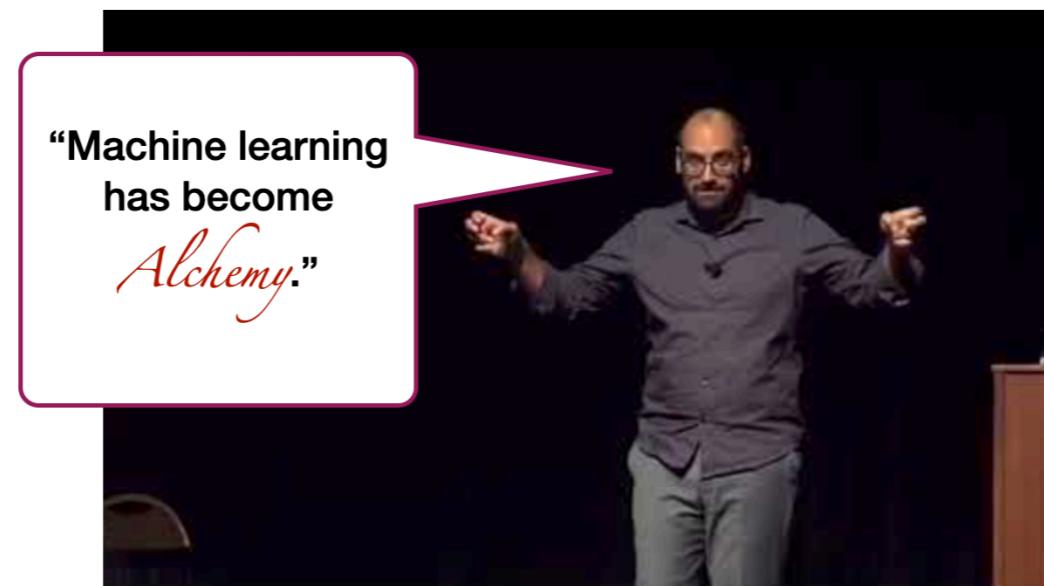
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In Deep Learning era, typically parametrised by Recurrent Neural Networks (RNNs).

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$$P(\sigma | x_n, \dots, x_1)$$

Lack explainability!



Ali Rahimi ([Google](#)) at *NIPS* 2017

Sequence Modeling and Many-body Quantum Physics

Statistical Sequence Modeling

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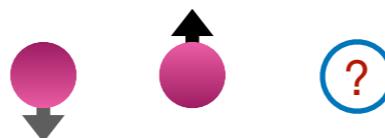
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Lack explainability!

Many-body Quantum Physics

1-D Spin Chain



MPS, DMRG

Sequence Modeling and Many-body Quantum Physics

Statistical Sequence Modeling

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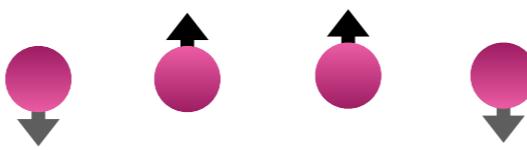
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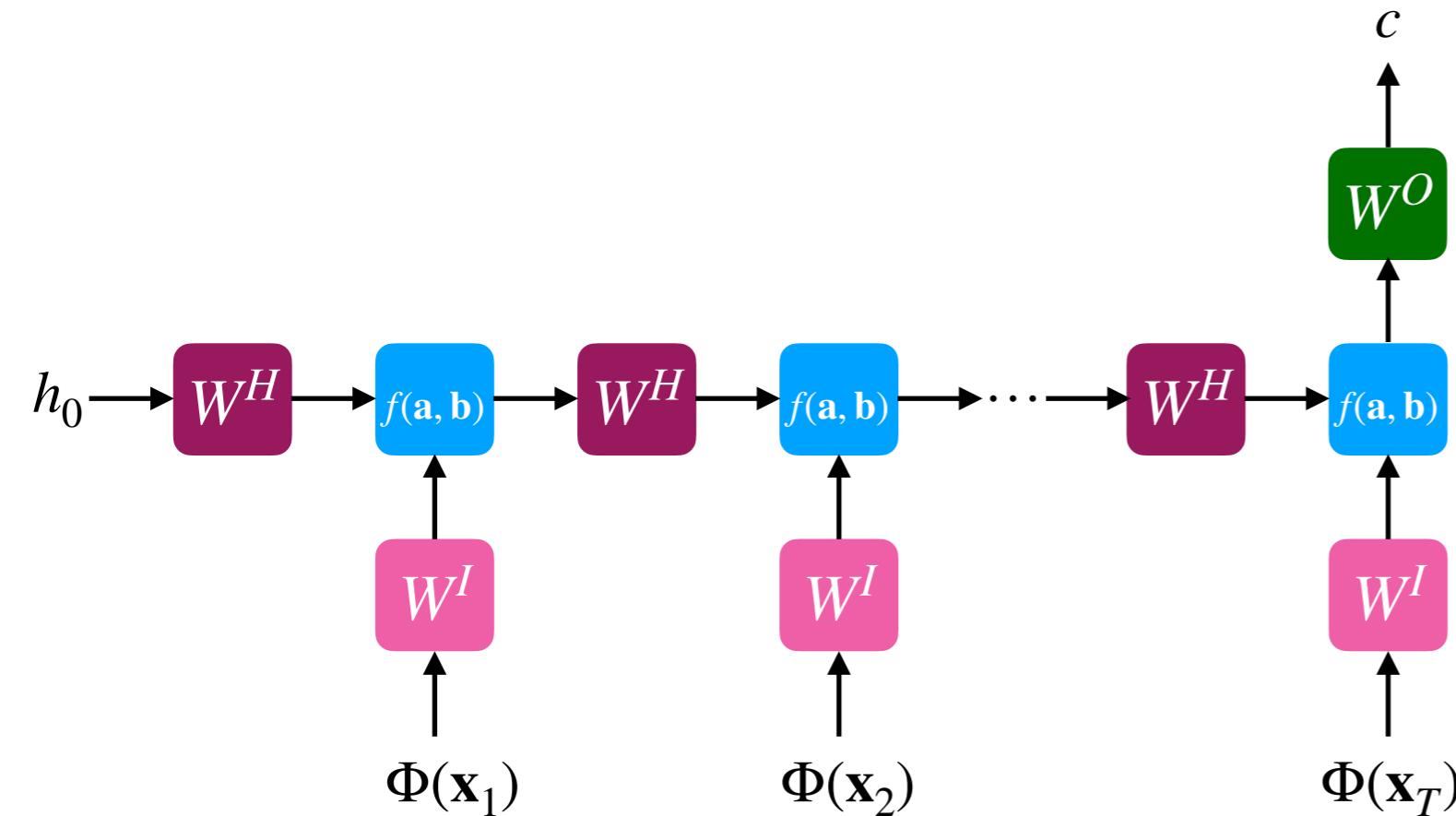
Classification of Phase of Matters



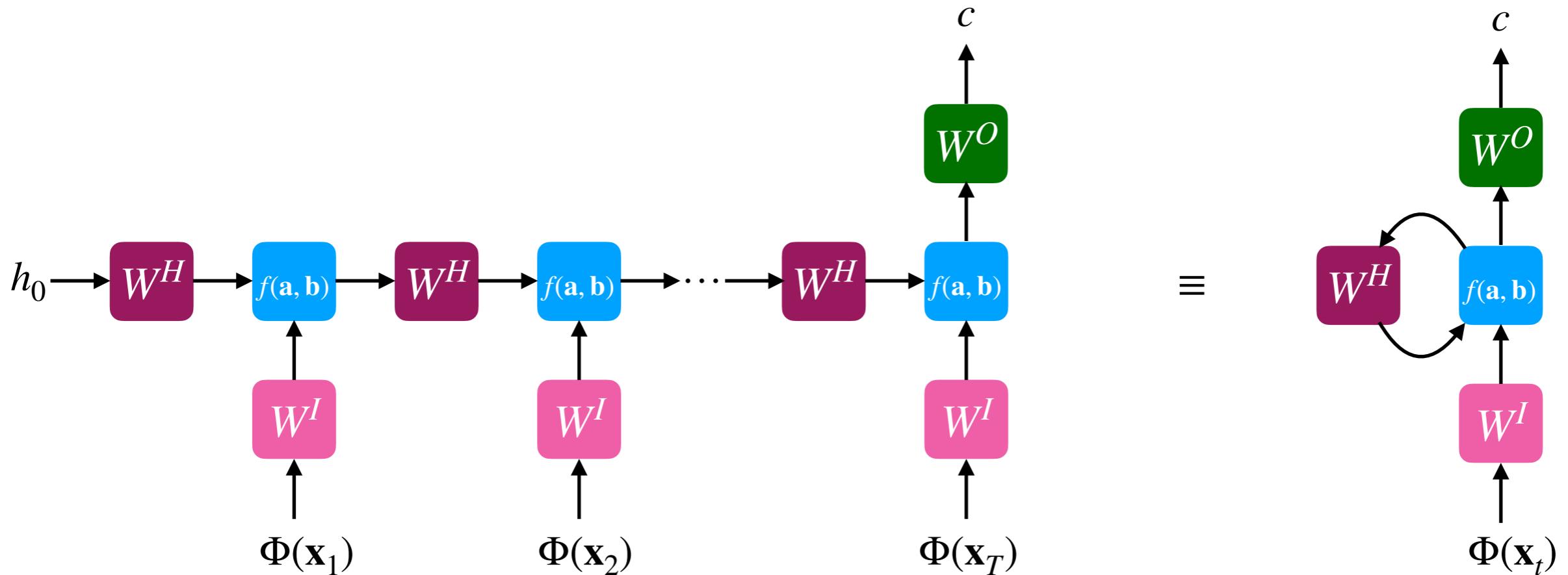
“Ferromagnets”

Relatively well developed

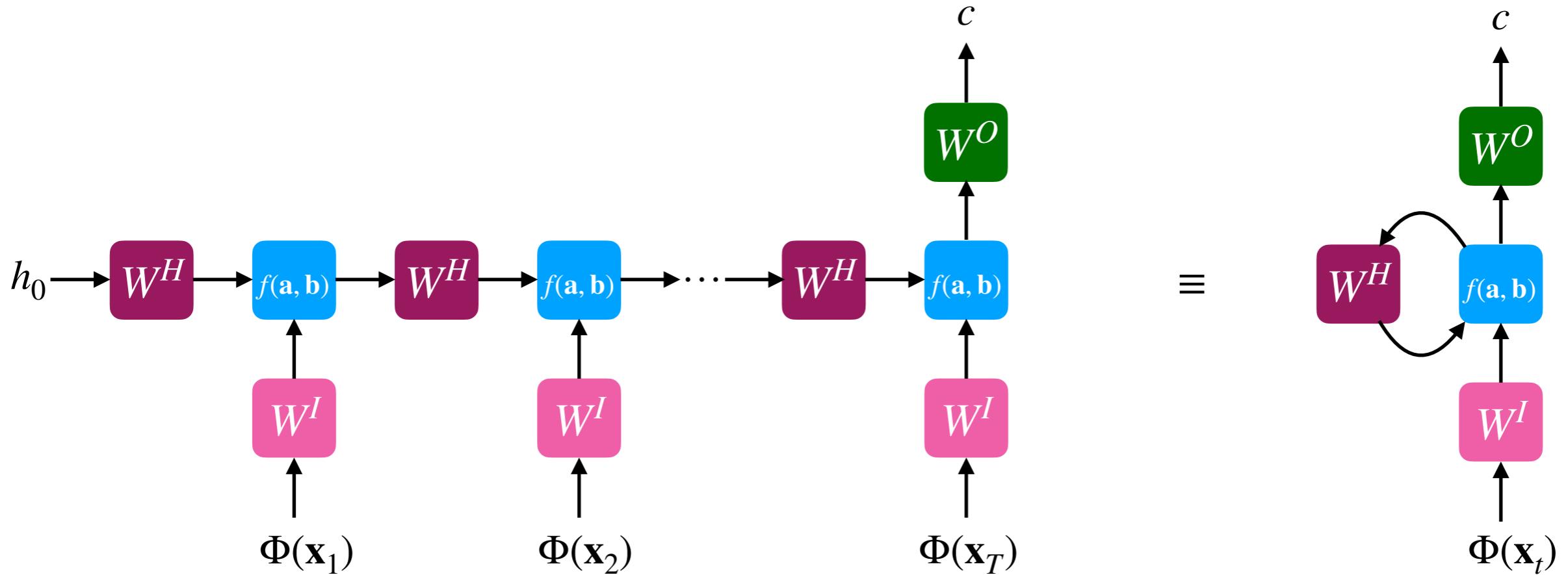
Shallow Recurrent Neural Networks (RNNs) Architecture for Sentiment Analysis



Shallow Recurrent Neural Networks (RNNs) Architecture for Sentiment Analysis



Shallow Recurrent Neural Networks (RNNs) Architecture for Sentiment Analysis



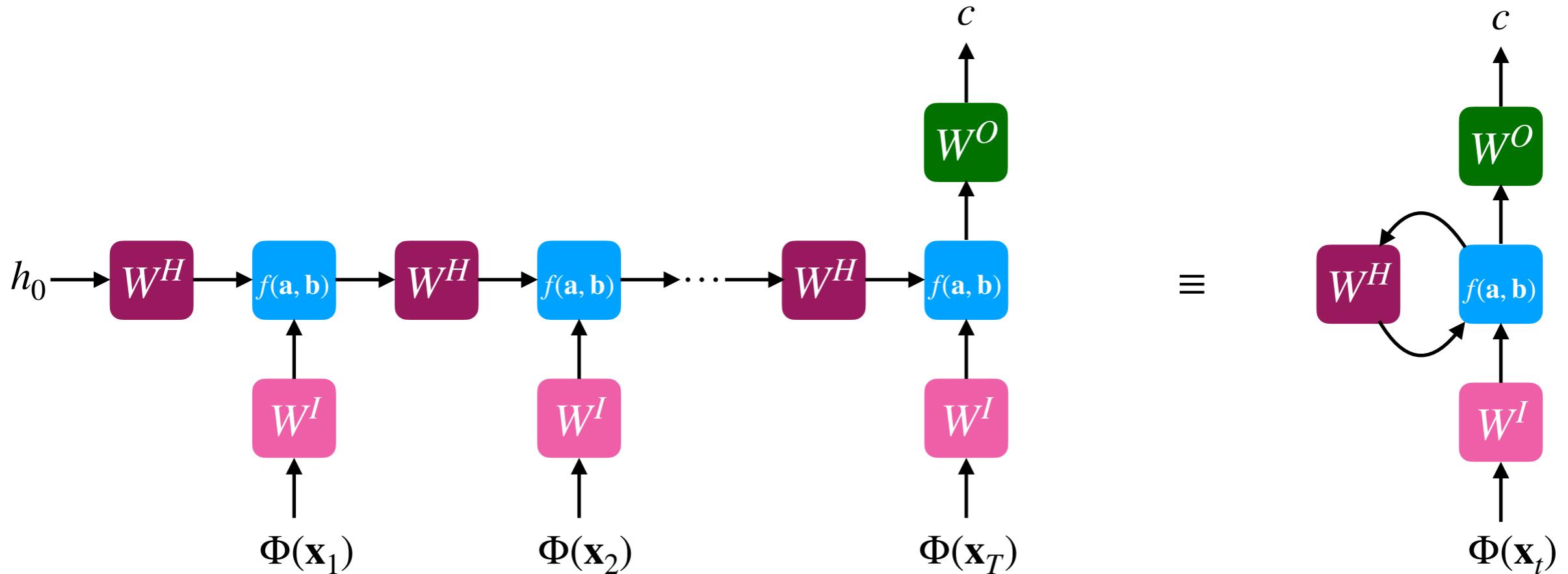
$$\mathbf{h}^t = f\left(W^H \mathbf{h}^{t-1}, W^I \Phi(\mathbf{x}_t)\right)$$

$$c = \sigma(W^O \mathbf{h}^T)$$

$$\approx P(c | x_T, \dots, x_1)$$

$f(\mathbf{a}, \mathbf{b})$ is typically a highly non-linear function, which makes the analysis of iterated non-linear map in RNNs difficult.

Shallow Recurrent Neural Networks (RNNs) Architecture for Sentiment Analysis



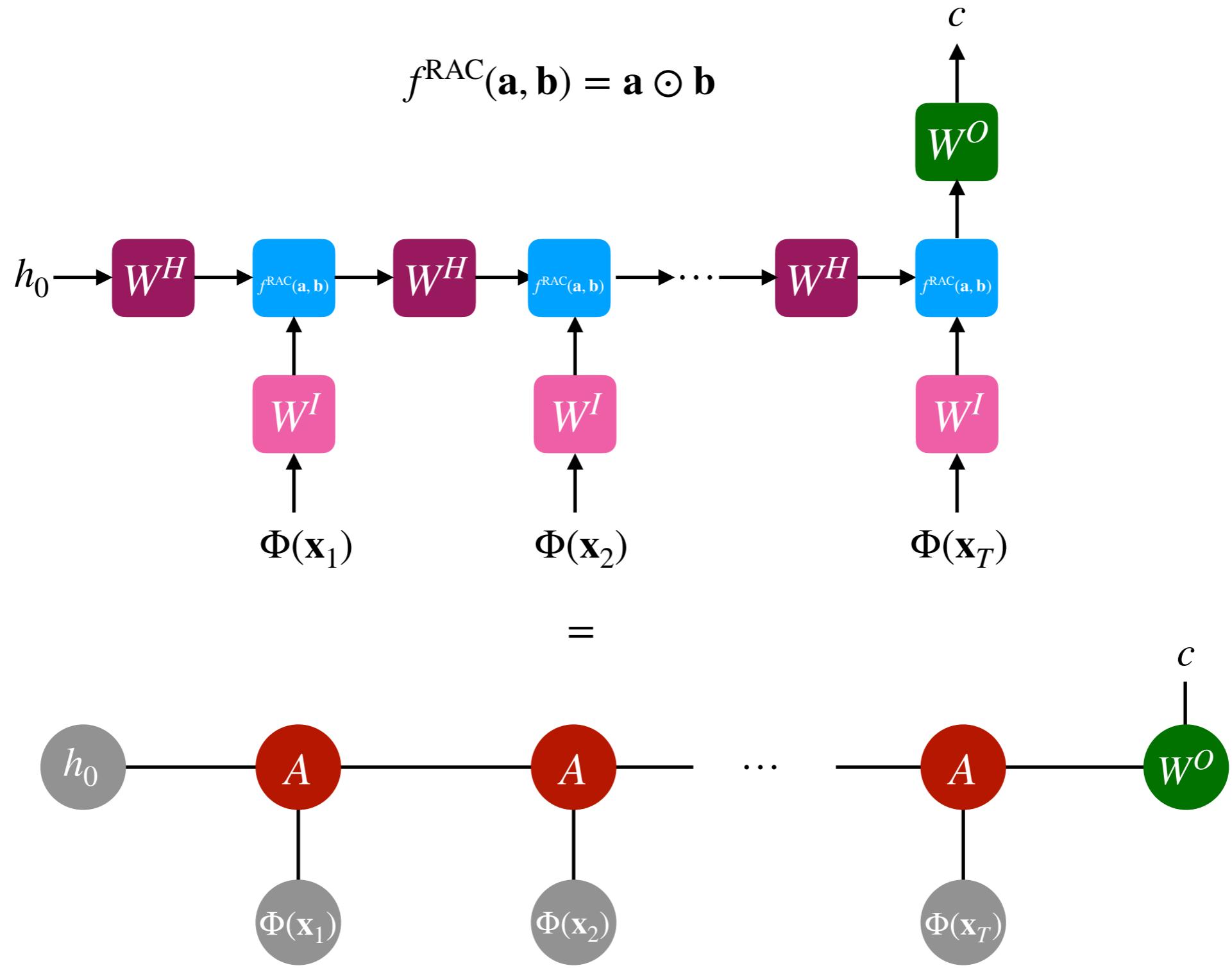
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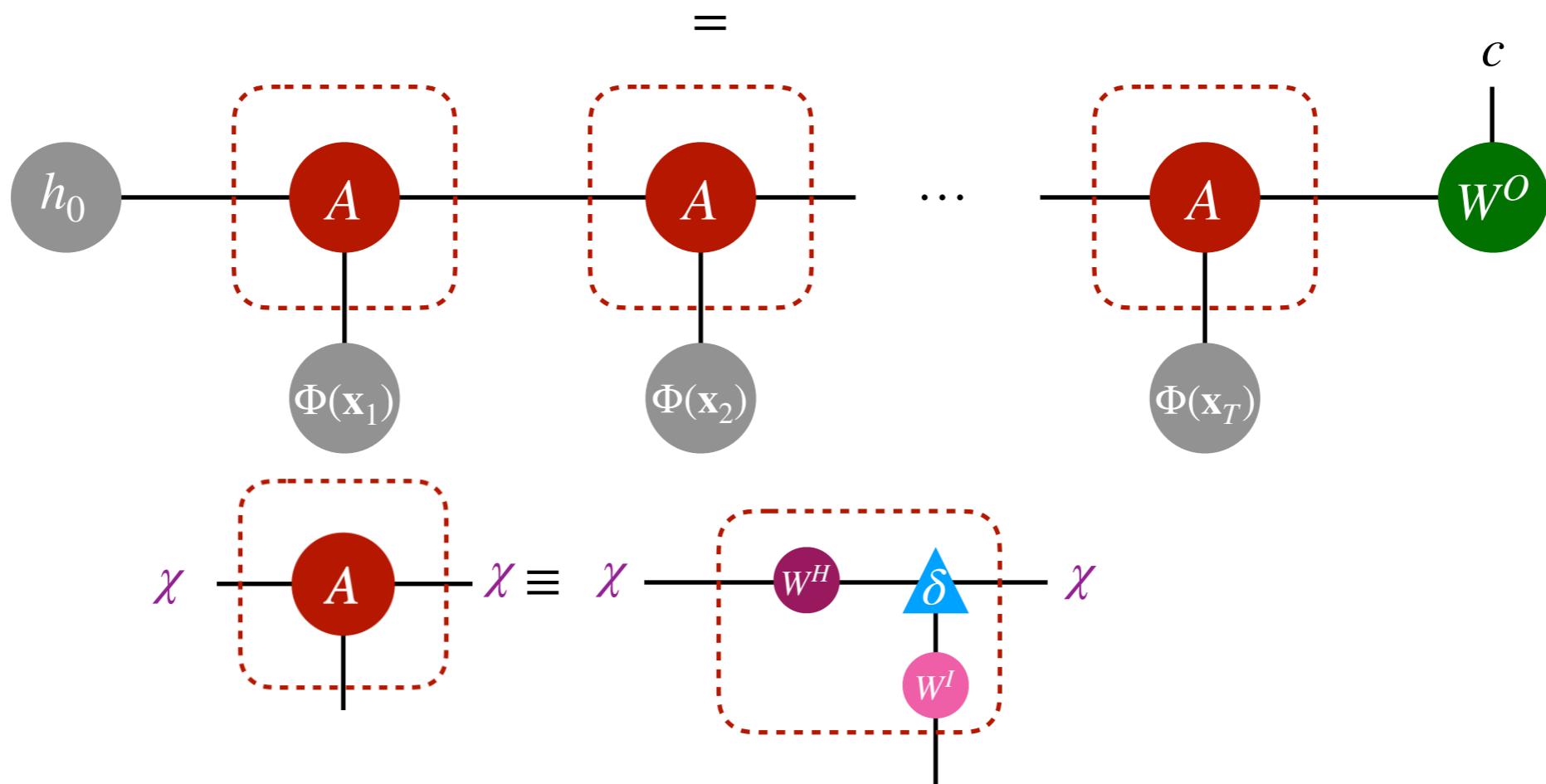
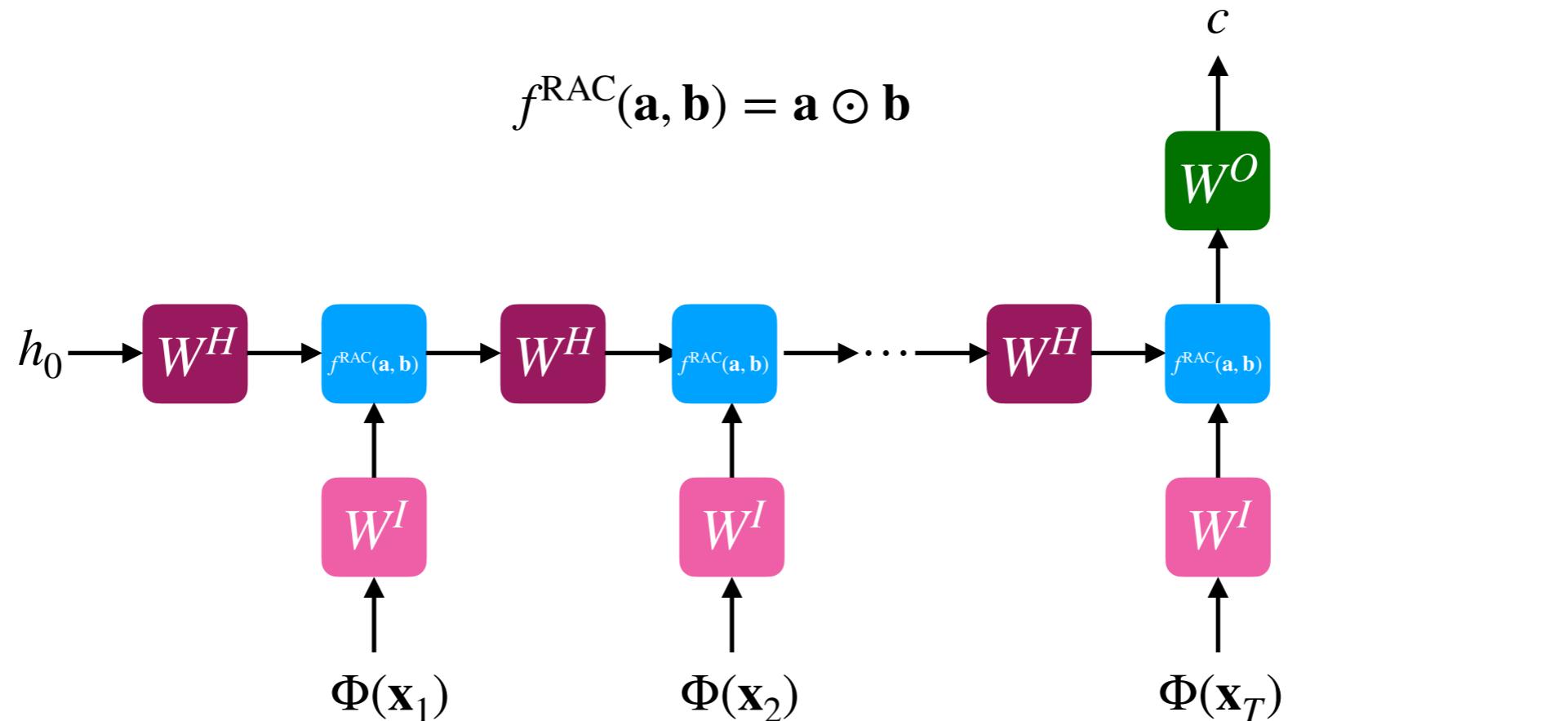
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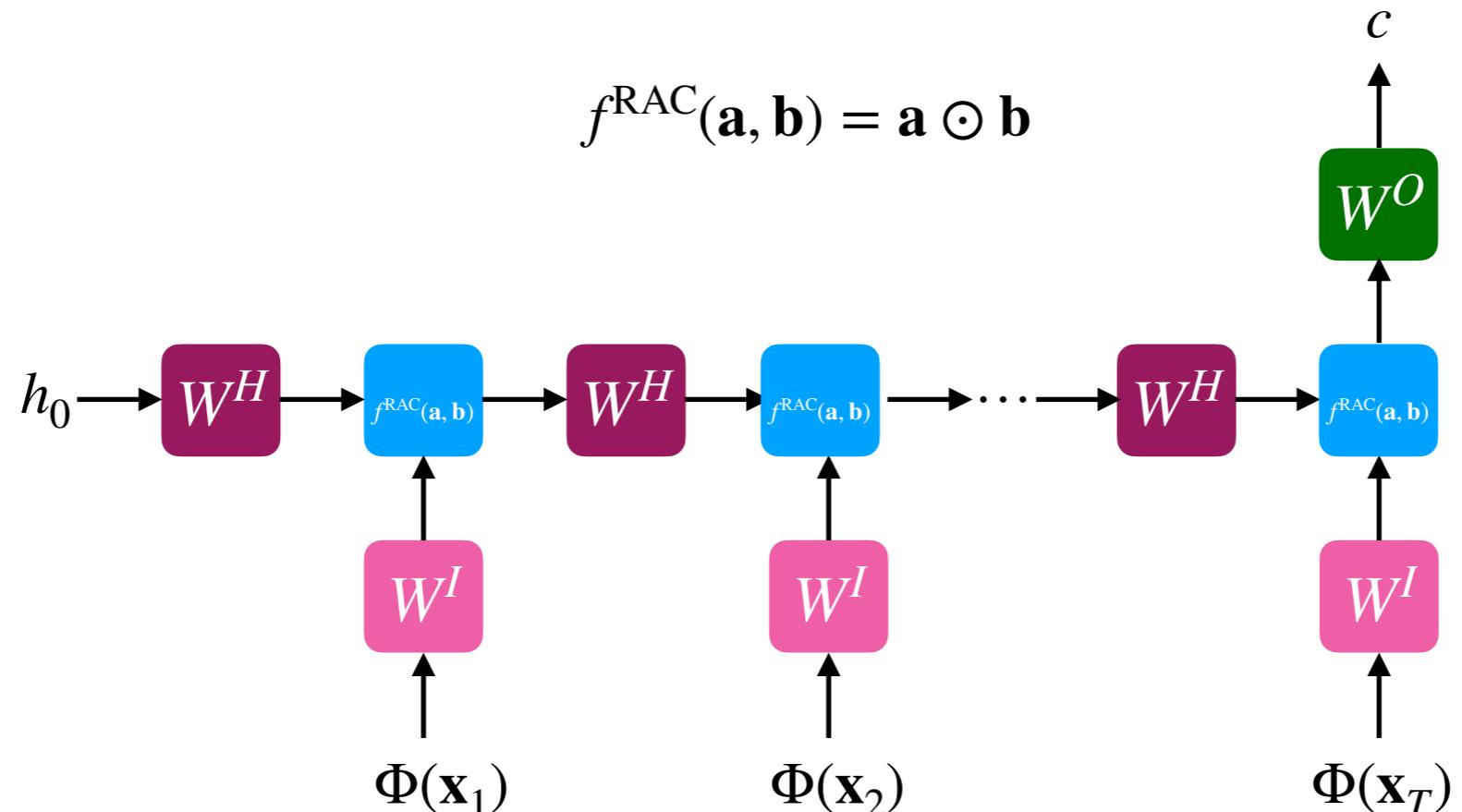
$f(\mathbf{a}, \mathbf{b})$ is typically a highly non-linear function, which makes the analysis of iterated non-linear map in RNNs difficult.

However, for a specific type of activation function called Recurrent Arithmetic Circuits (RACs), there's a mapping to a translational invariant Matrix Product State (MPS)

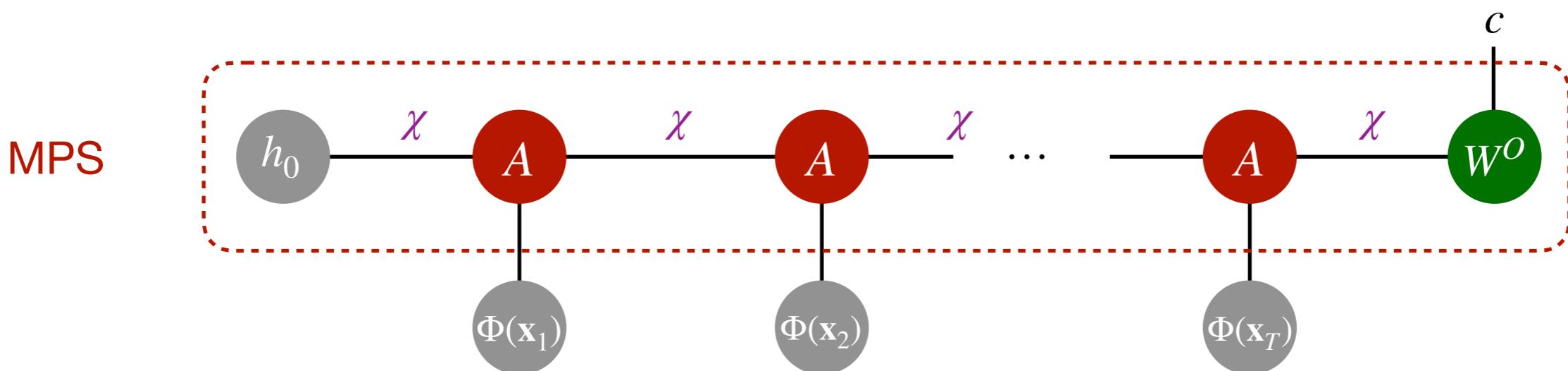
$$f(\mathbf{a}, \mathbf{b}) \equiv f^{\text{RAC}}(\mathbf{a}, \mathbf{b}) = \mathbf{a} \odot \mathbf{b}$$



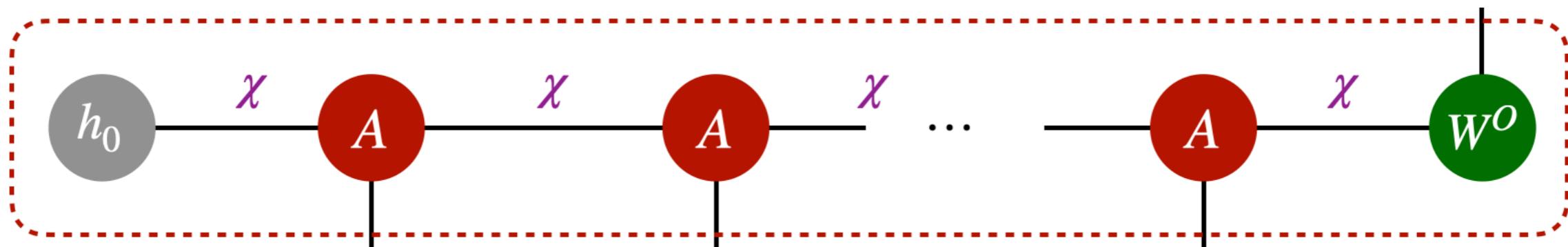




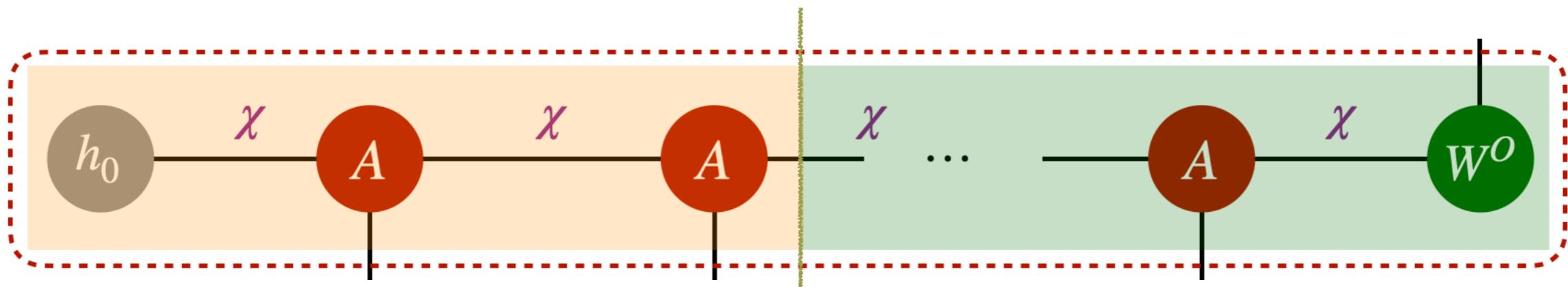
=



Entanglement Entropy as a Proxy of Information Propagation in RACs



Entanglement Entropy as a Proxy of Information Propagation in RACs

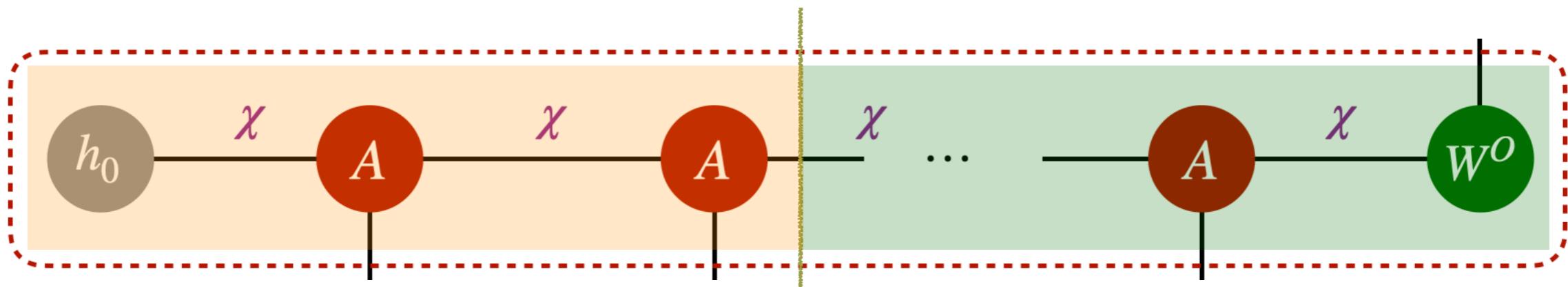


$$|\psi_{MPS}\rangle = \sum_{\alpha=1}^r \lambda_\alpha |\phi_\alpha^L\rangle \otimes |\phi_\alpha^R\rangle$$

Entanglement Entropy

$$S = - \sum_{\alpha=1}^r |\lambda_\alpha|^2 \ln |\lambda_\alpha|^2$$

Entanglement Entropy as a Proxy of Information Propagation in RACs



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Entanglement Entropy

$$S = - \sum_{\alpha=1}^r |\lambda_\alpha|^2 \ln |\lambda_\alpha|^2$$

If $r \ll \chi$, then $|\psi_{MPS}\rangle$ does not possess long-range correlation.

Thus S can be a good proxy to test whether the learned RACs has long-range information propagation.

Sentiment Analysis for IMDB dataset



The Martian

2015 · Science fiction film/Drama film · 2h 31m



[Play trailer on YouTube](#)



Like



Dislike

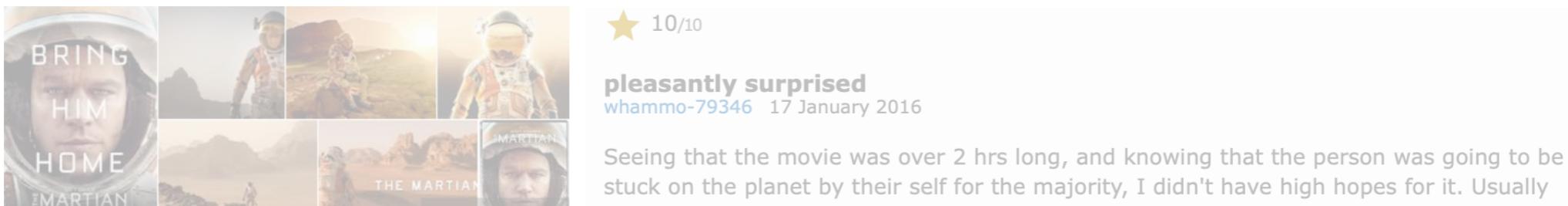
★ 10/10

pleasantly surprised

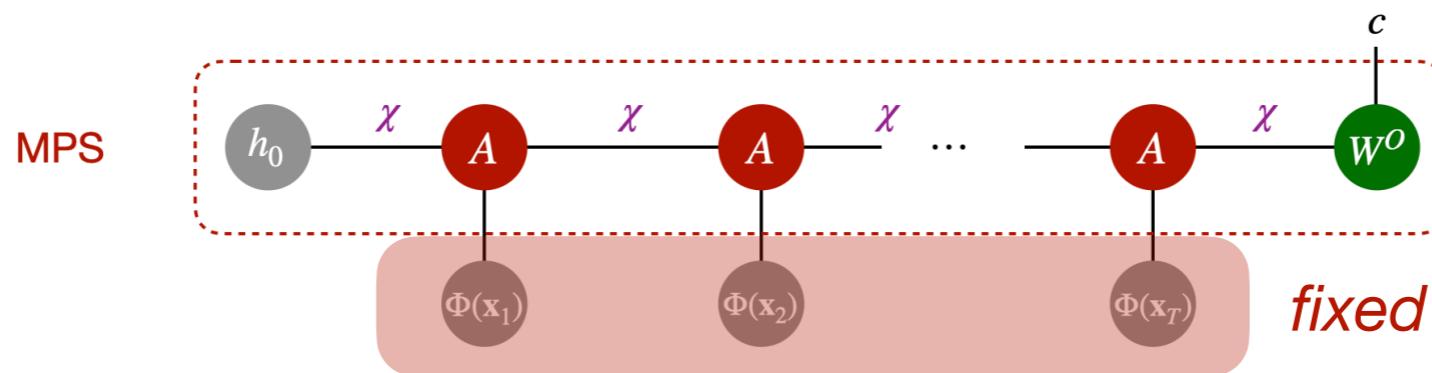
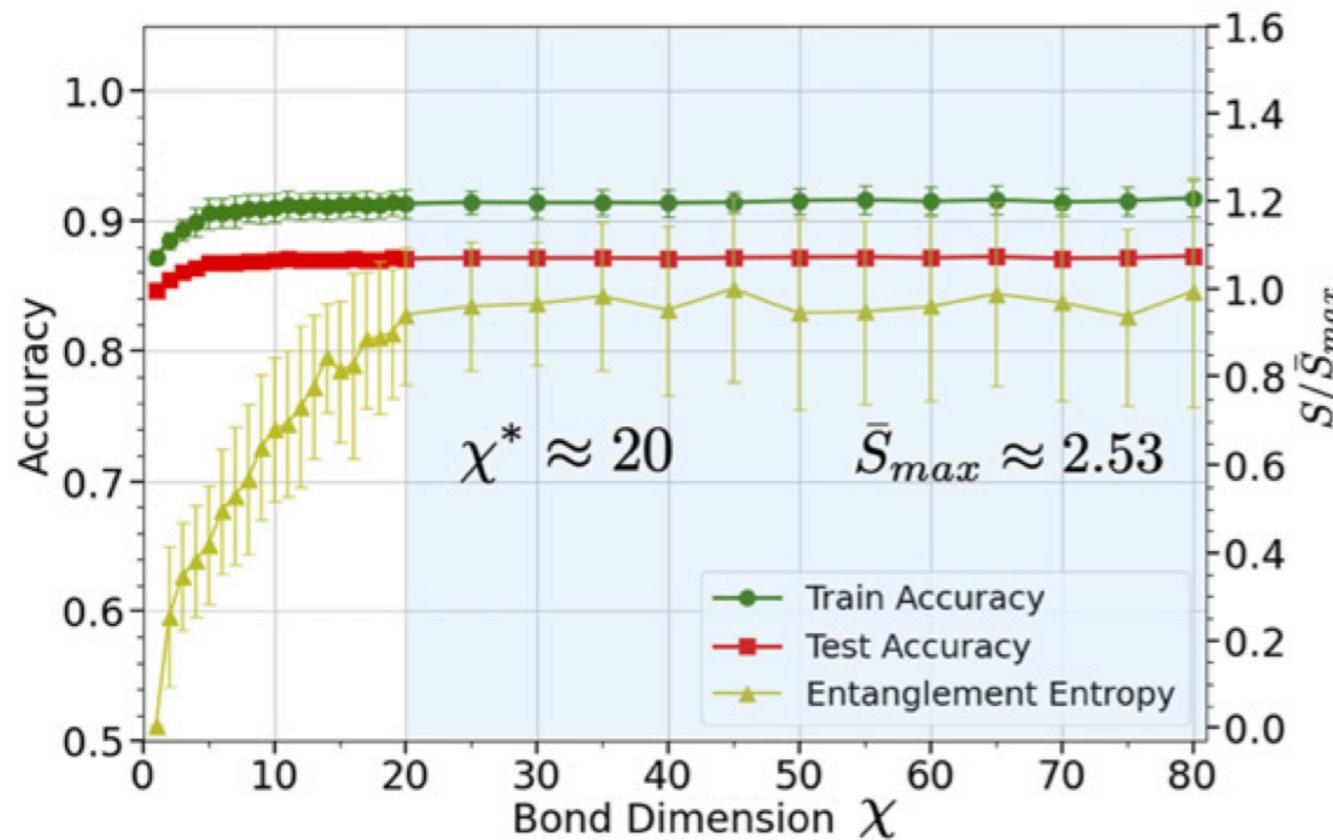
whammo-79346 17 January 2016

Seeing that the movie was over 2 hrs long, and knowing that the person was going to be stuck on the planet by their self for the majority, I didn't have high hopes for it. Usually these types of movies are boring. Not a lot of writers can pull this off. This movie was really good tho. A group of us watched it and really enjoyed. There were some things they failed to explain, that we collectively came up with our own answer for. Other than that, it was great. I never felt bored or left waiting for more. Overall, I feel it was very

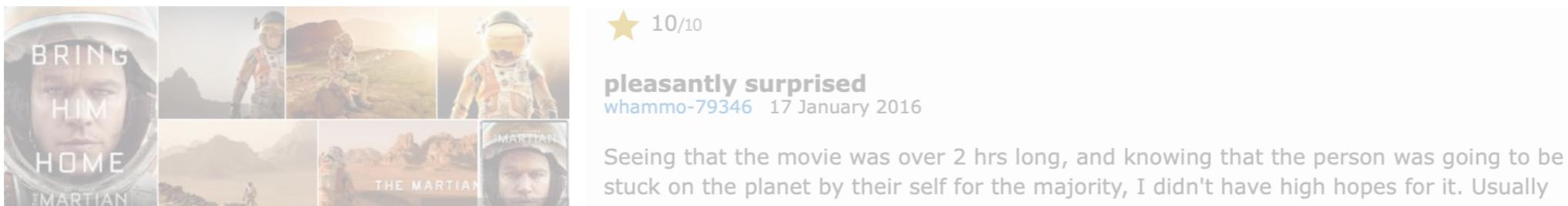
Sentiment Analysis for IMDB dataset: fixed word embedding



Fix the pre-trained $\Phi(w) \in \mathbb{R}^4$

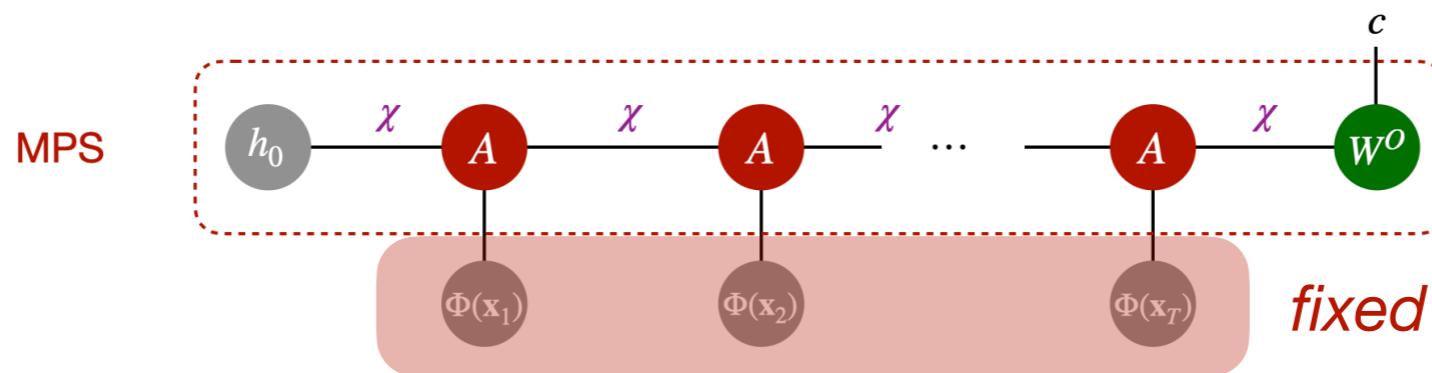
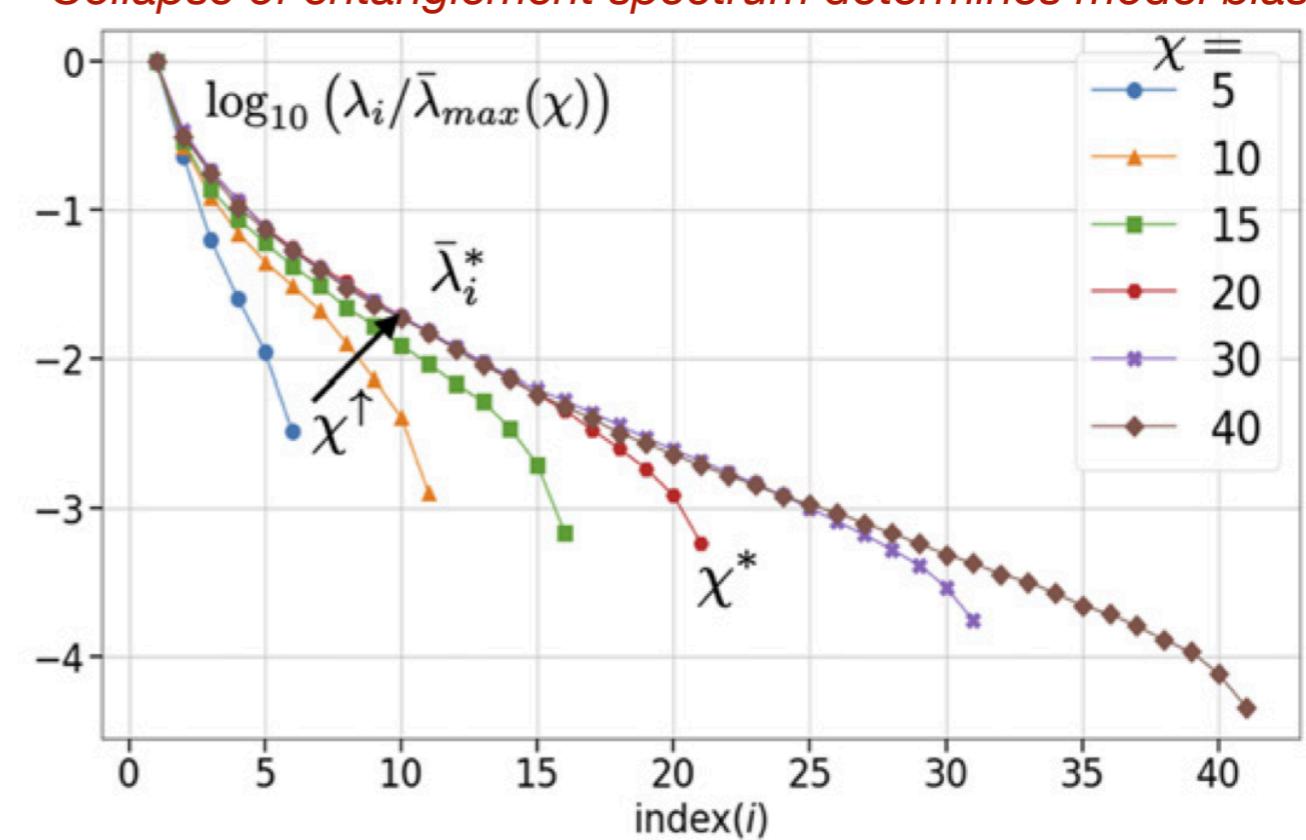
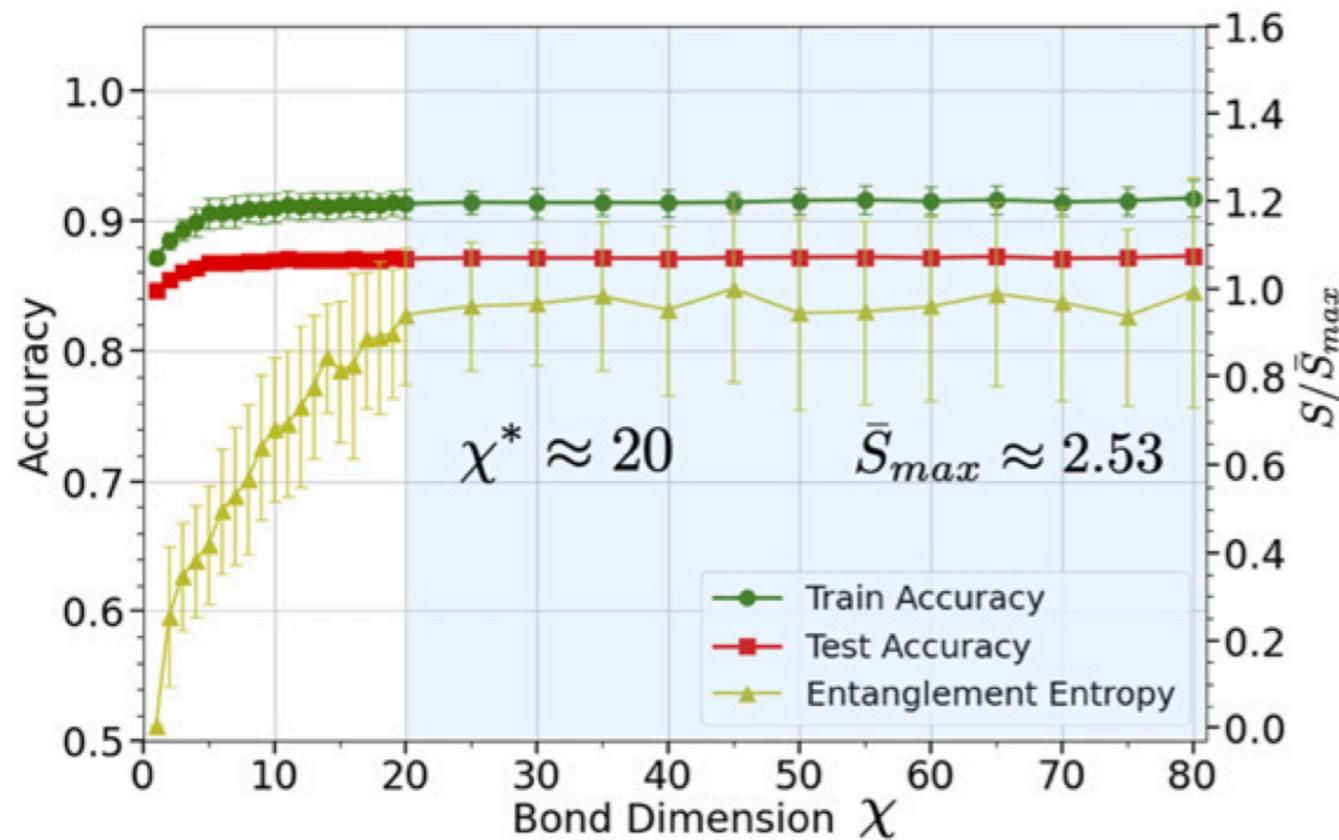


Sentiment Analysis for IMDB dataset: fixed word embedding

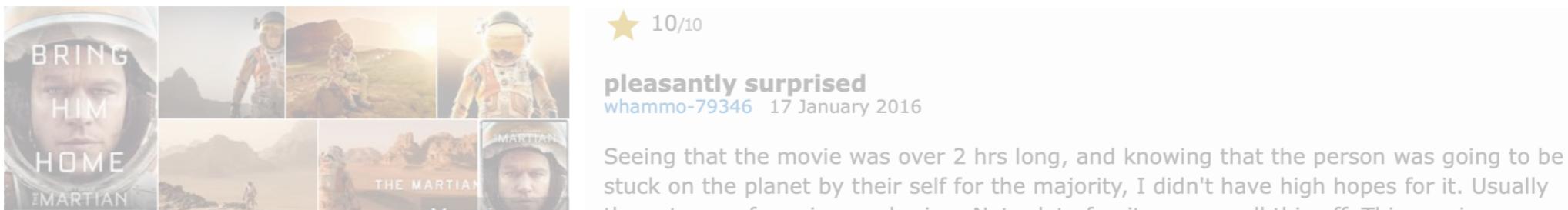


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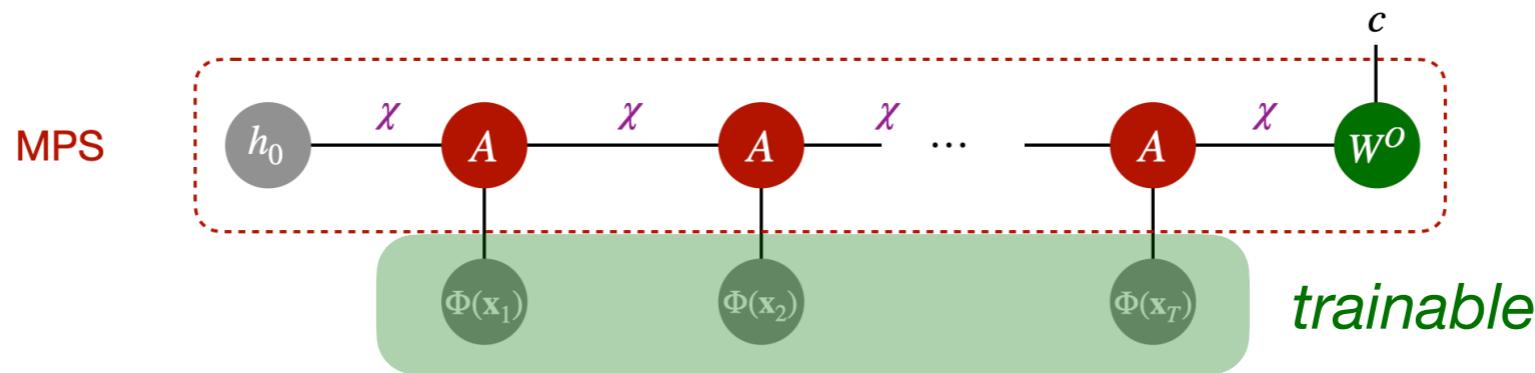
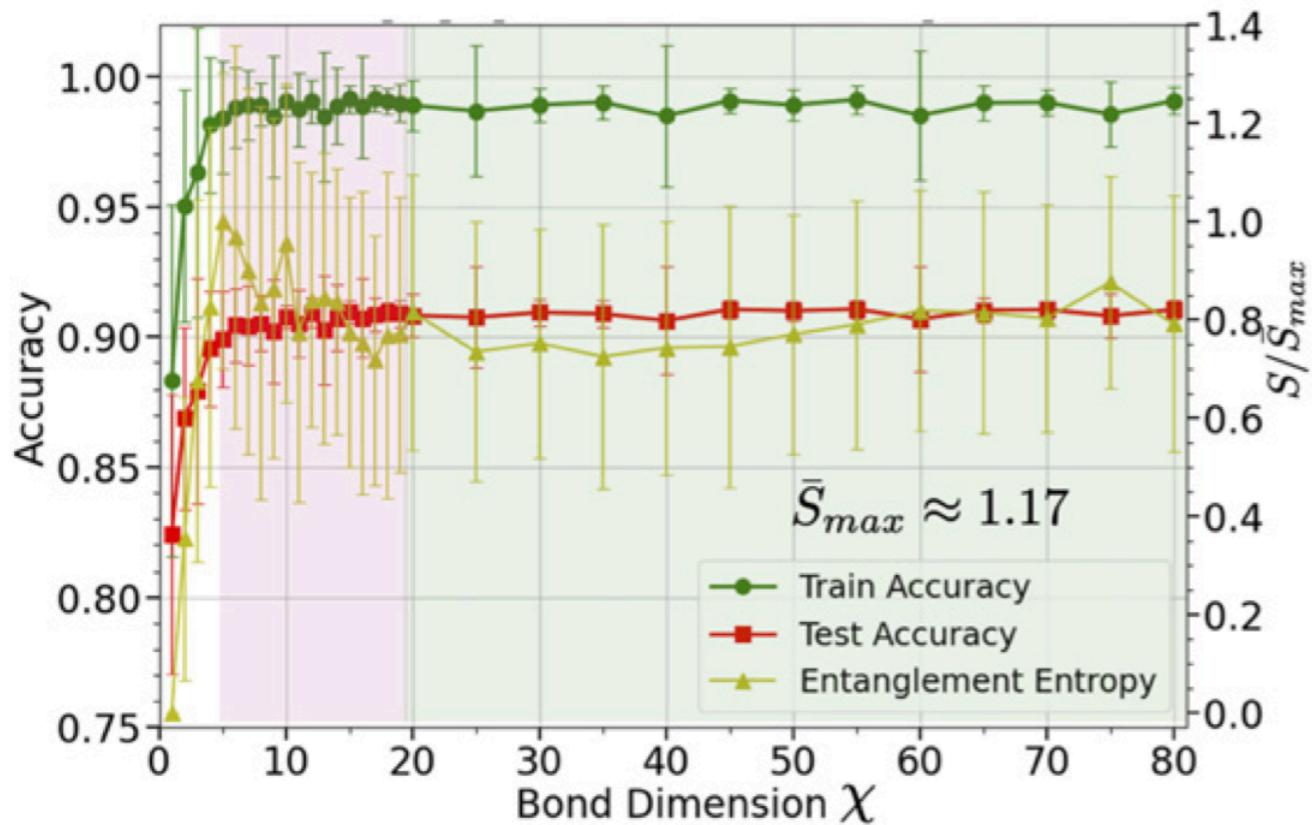
Collapse of entanglement spectrum determines model bias



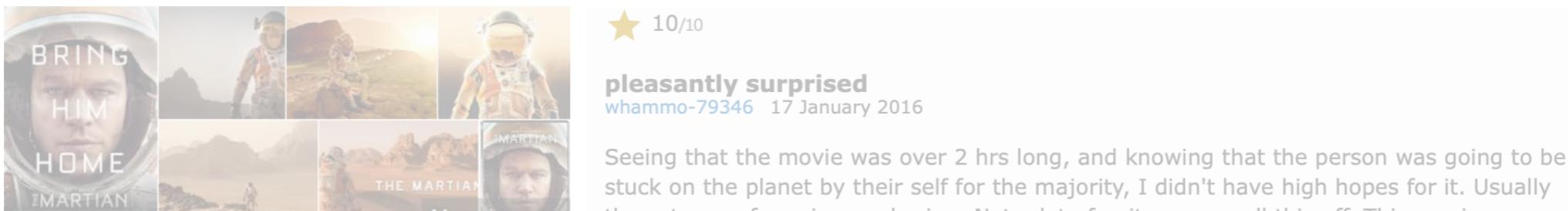
Sentiment Analysis for IMDB dataset: trainable word embedding



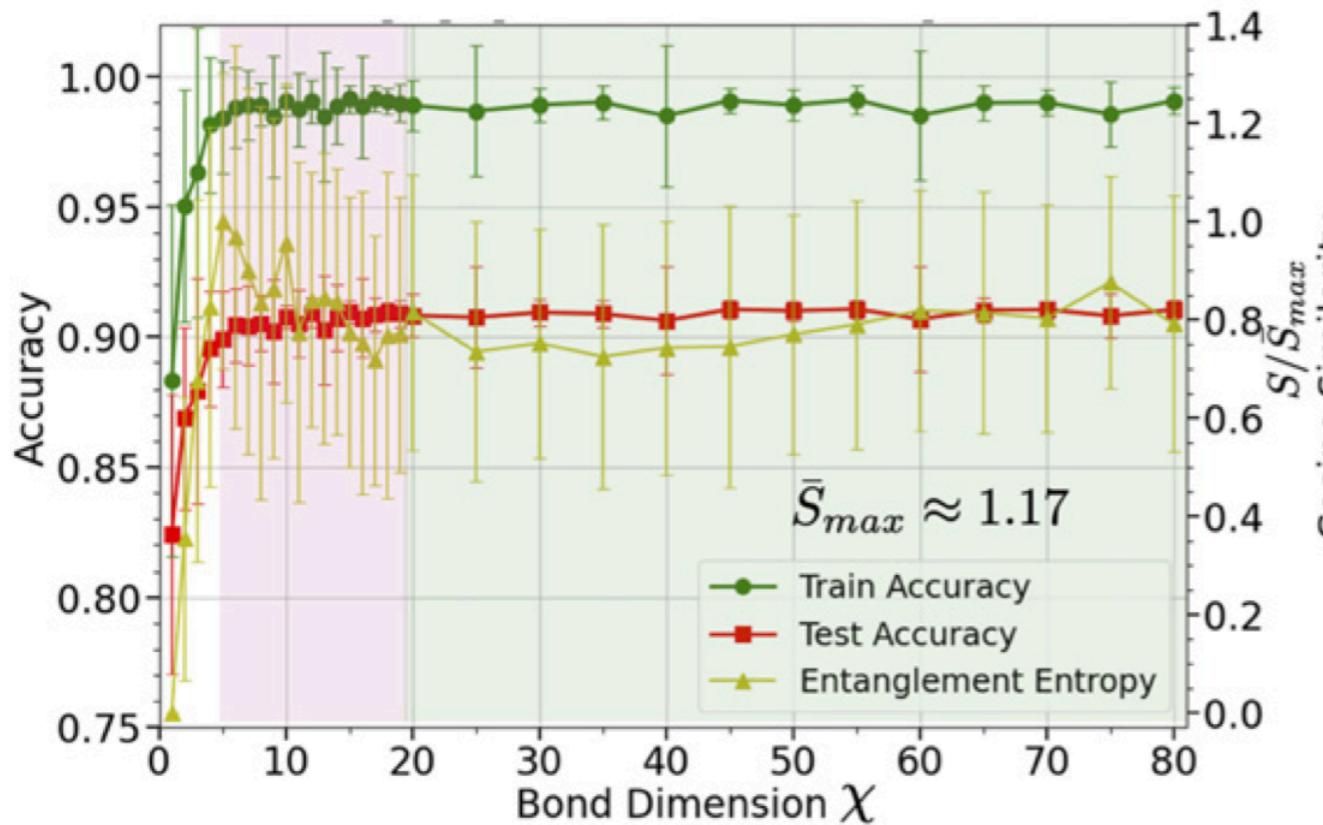
Train $\Phi(w) \in \mathbb{R}^4$ with RACs



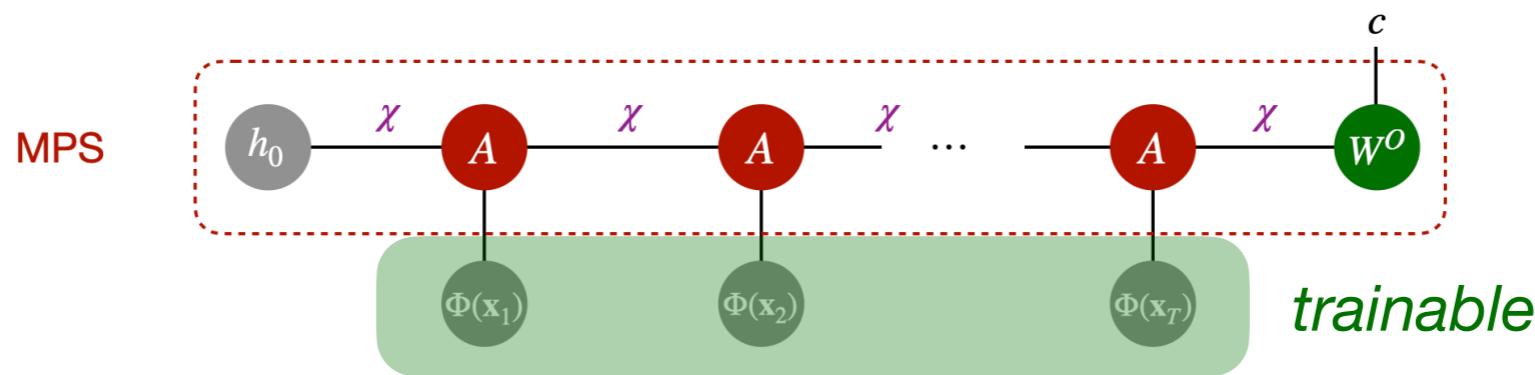
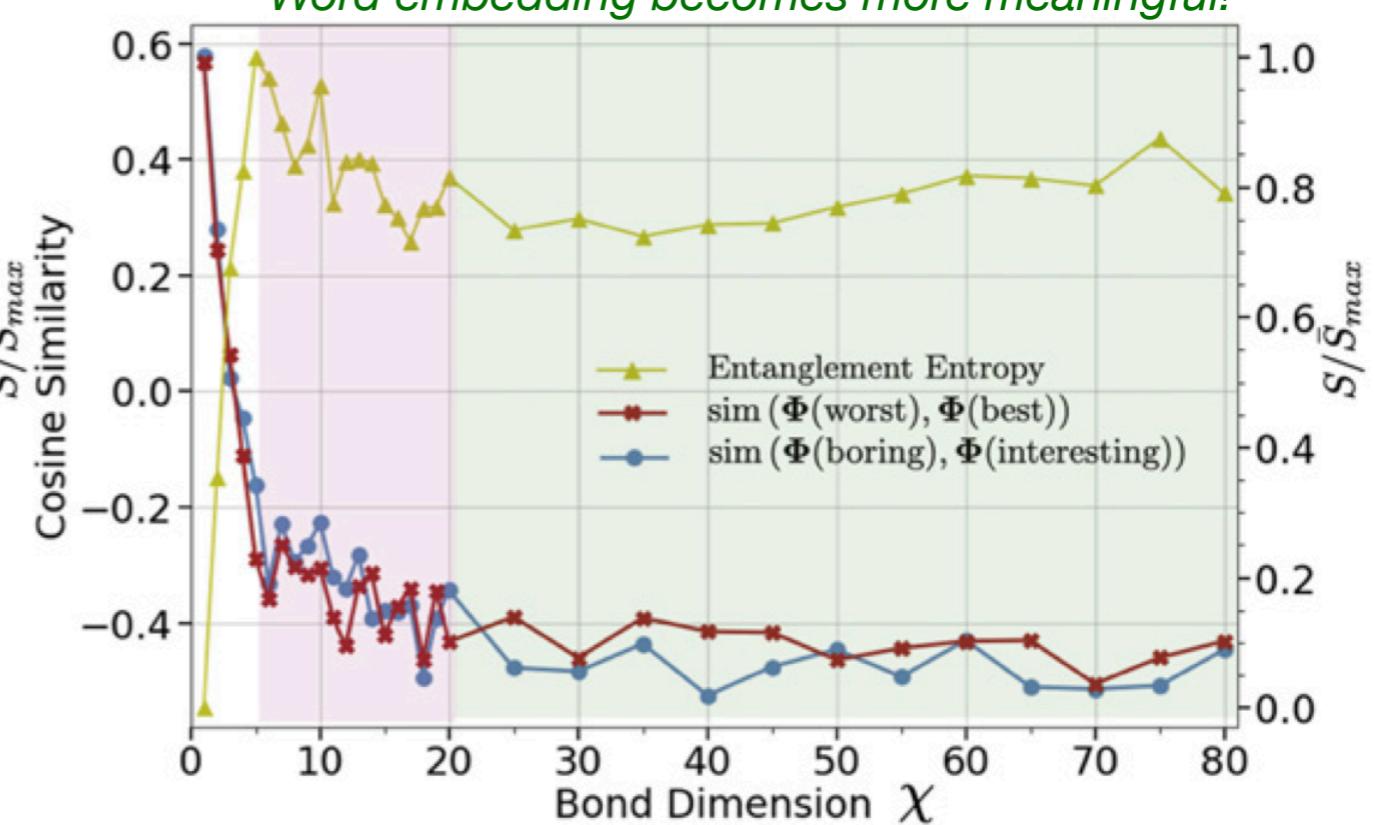
Sentiment Analysis for IMDB dataset: trainable word embedding



Train $\Phi(w) \in \mathbb{R}^4$ with RACs



Word embedding becomes more meaningful!



Summary

Mapping RACs to MPS allows one to exploit entanglement entropy as a measure of long-range correlation in natural language modeling.

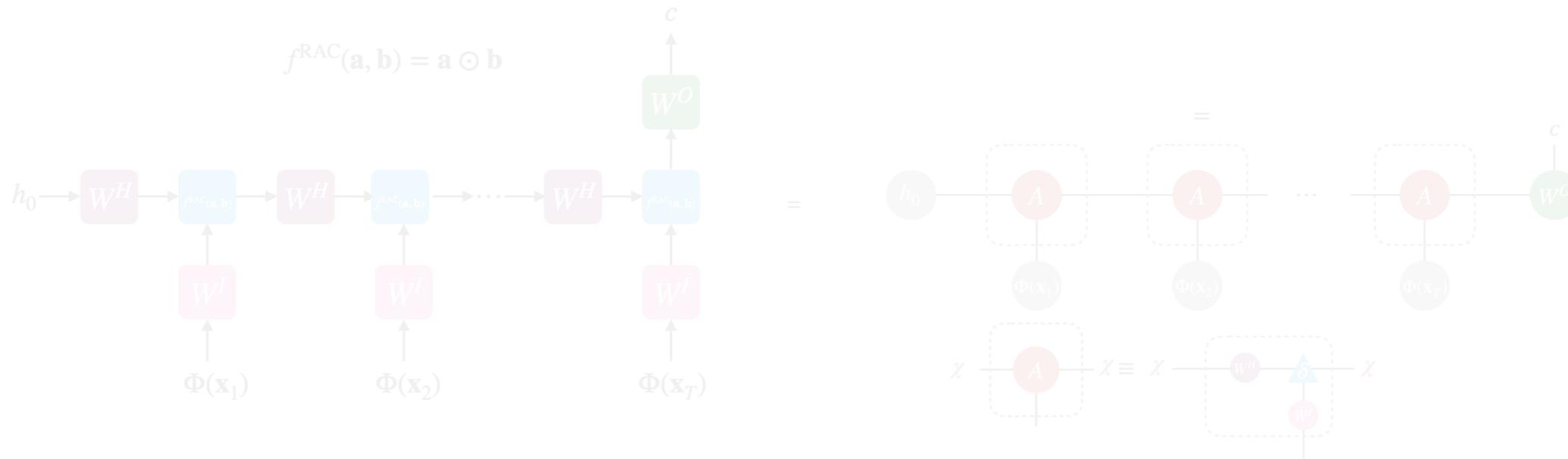
Machine learning model bias in sentiment analysis is closely related to the saturation of information propagation, arising from the collapse of MPS's entanglement spectrum.

Word embedding plays a very crucial role in expressing data. Although long-range information propagation is limited by the area law of MPS, the expressiveness of model is boosted by more meaningful word embeddings.



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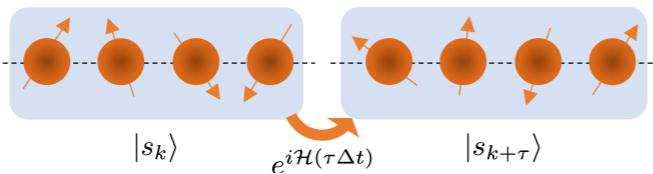
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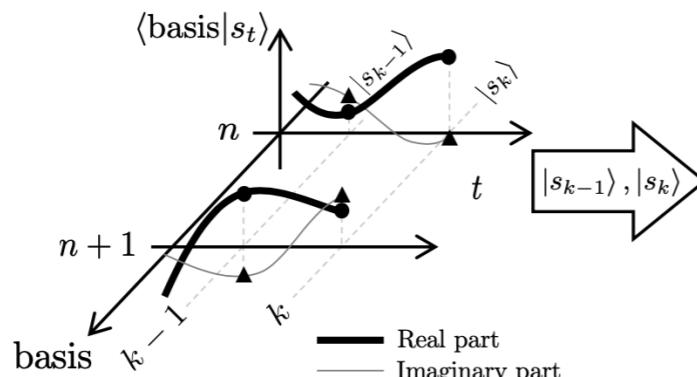
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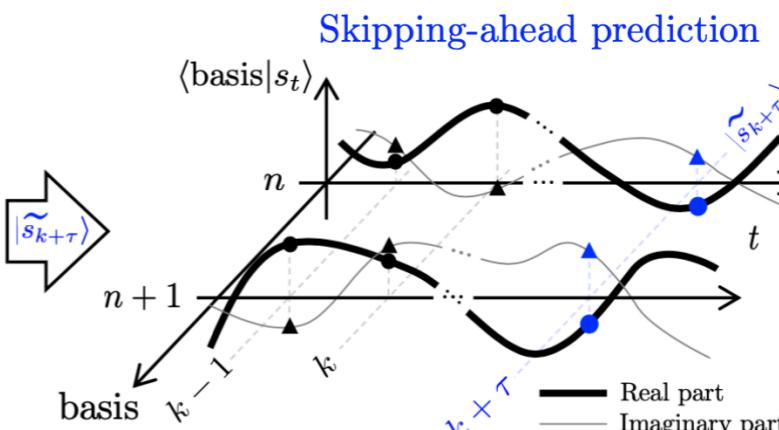
$$|s_t\rangle = e^{i\mathcal{H}t}|s_0\rangle$$

Quantum dynamics

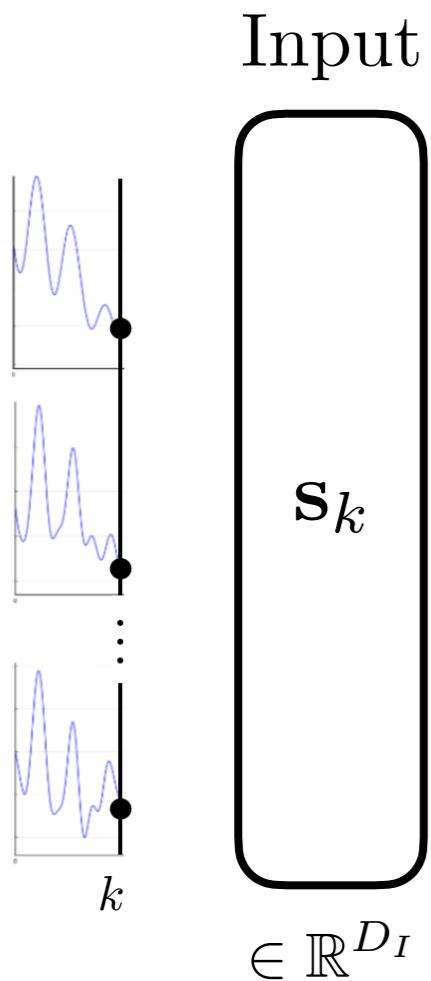


(Q)NG-RC

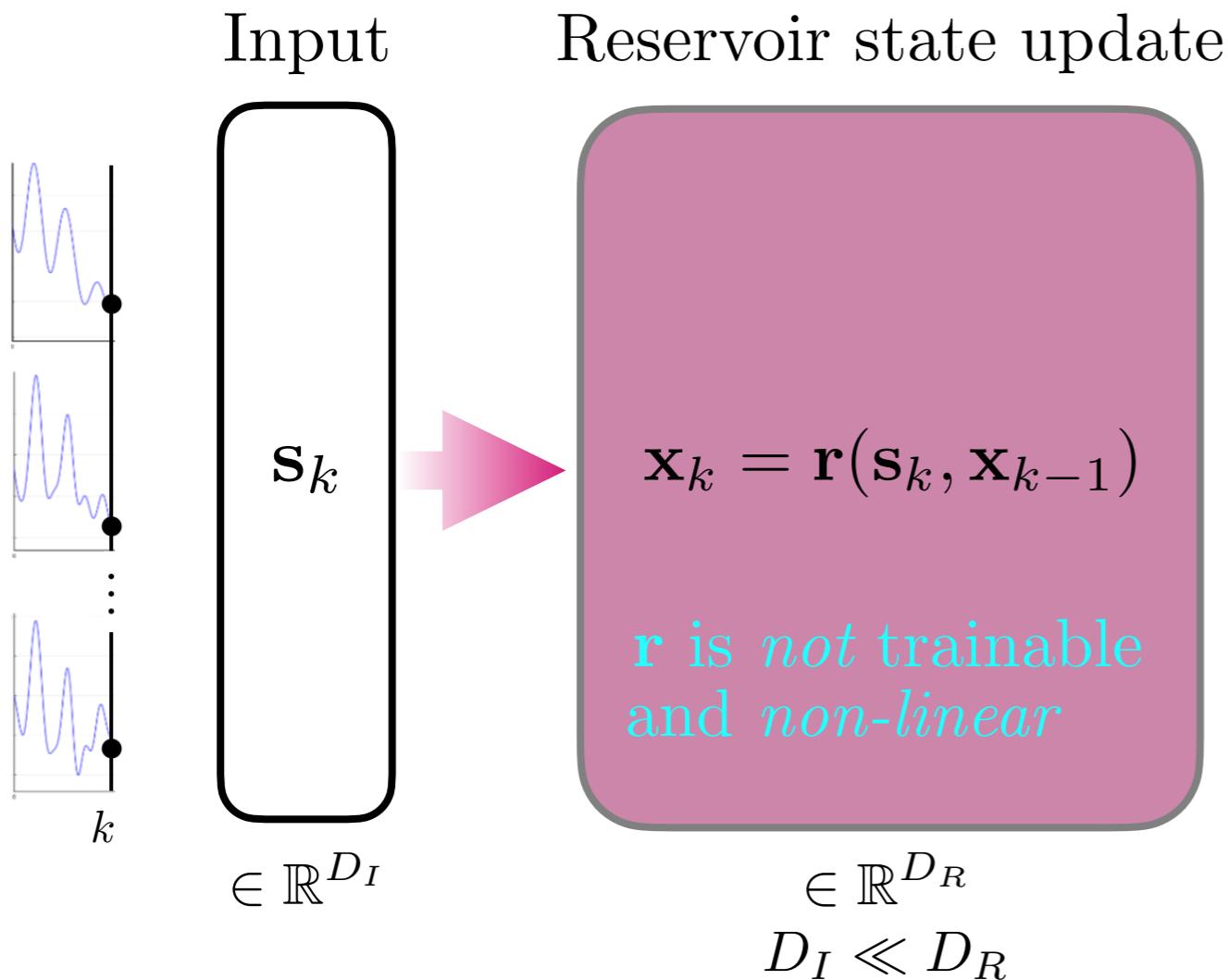
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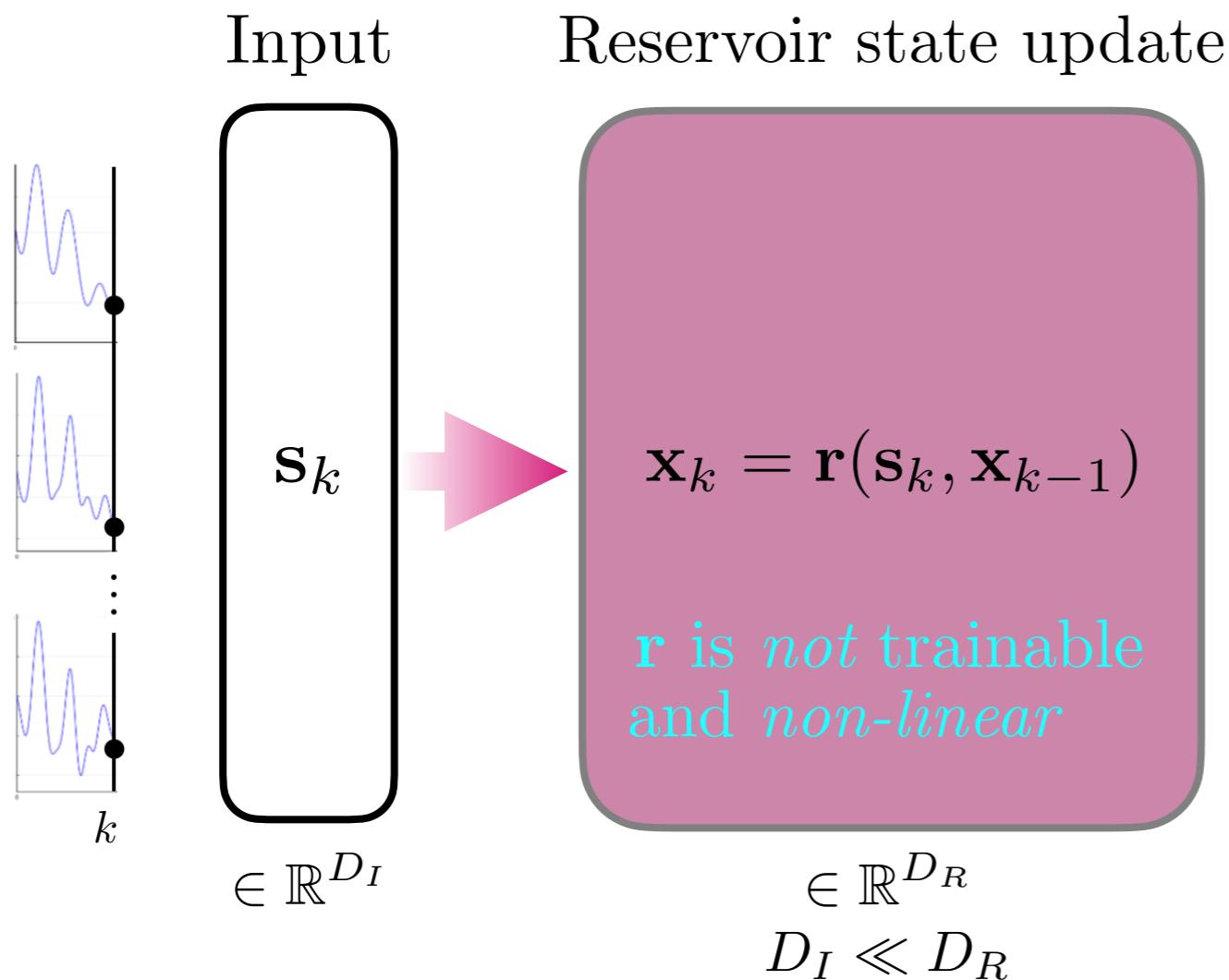
Reservoir Computing (RC) in a nutshell



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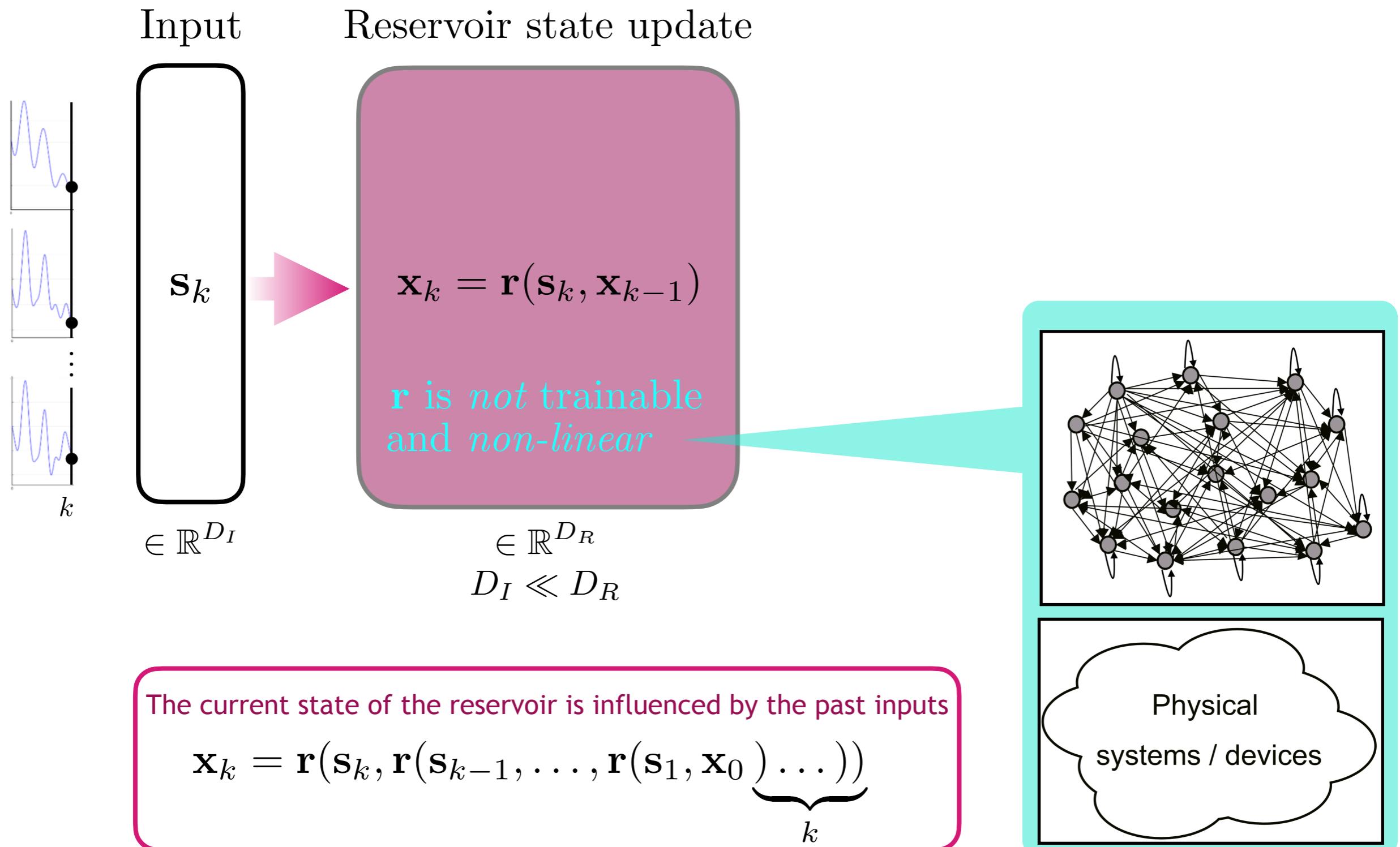
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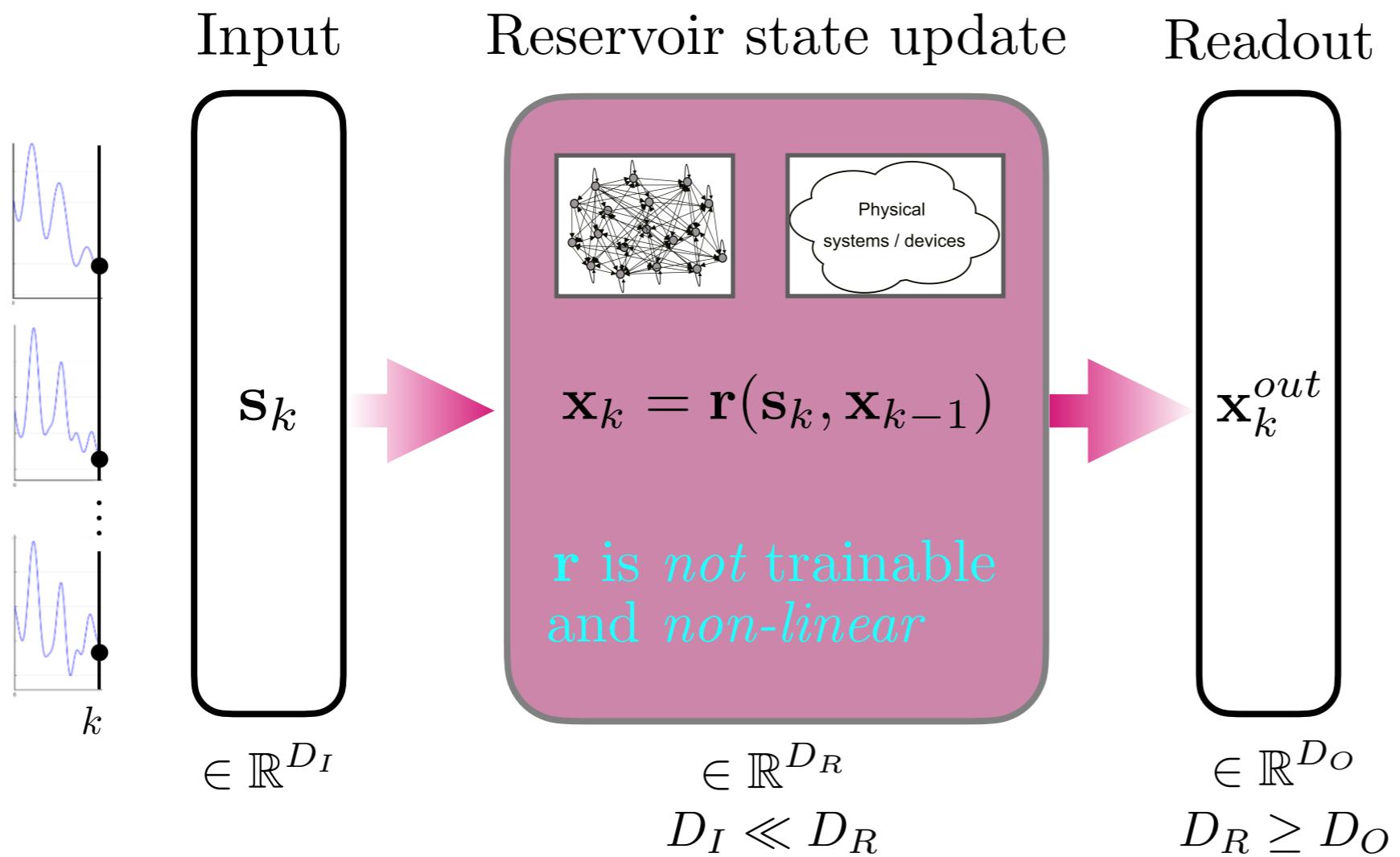
The current state of the reservoir is influenced by the past inputs

$$\mathbf{x}_k = \mathbf{r}(\mathbf{s}_k, \mathbf{r}(\mathbf{s}_{k-1}, \dots, \underbrace{\mathbf{r}(\mathbf{s}_1, \mathbf{x}_0)}_k \dots))$$

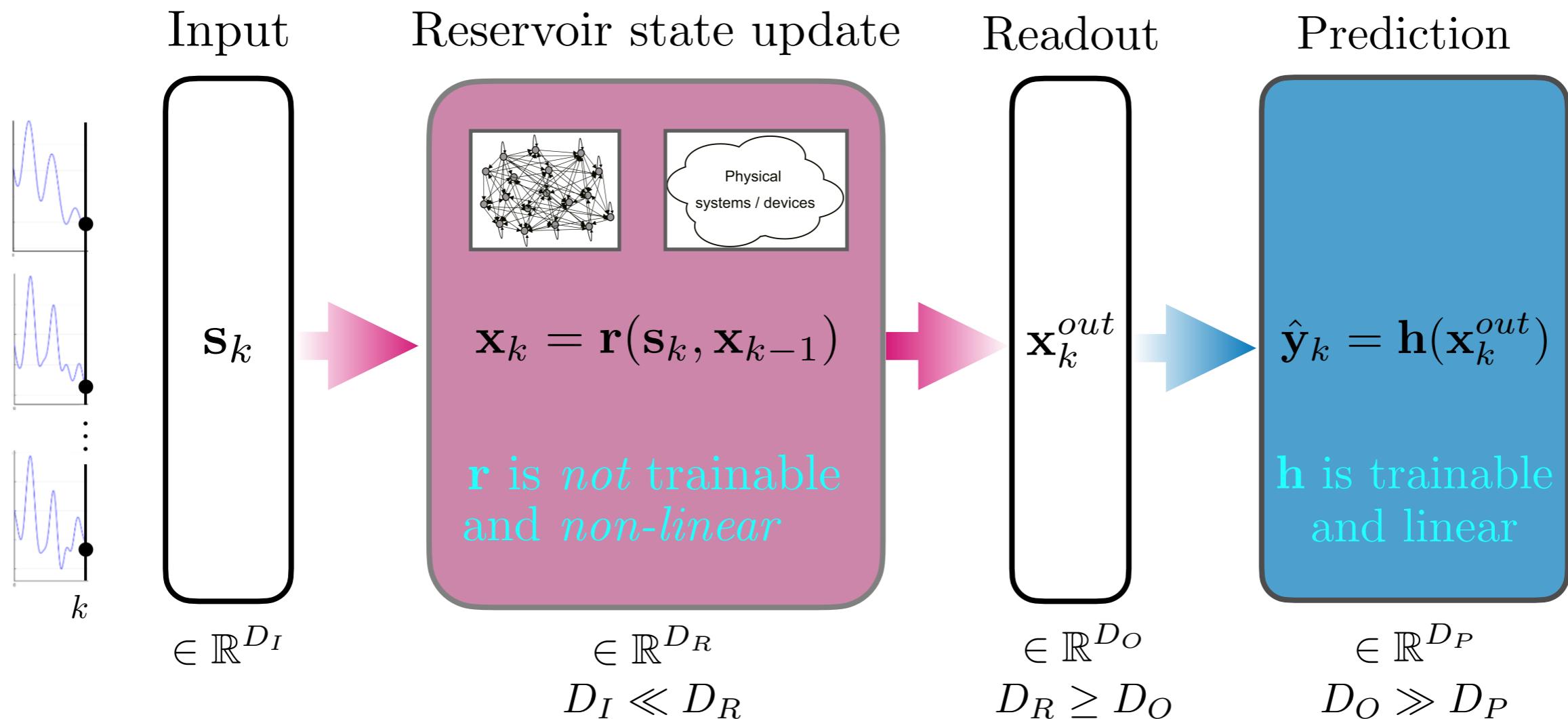
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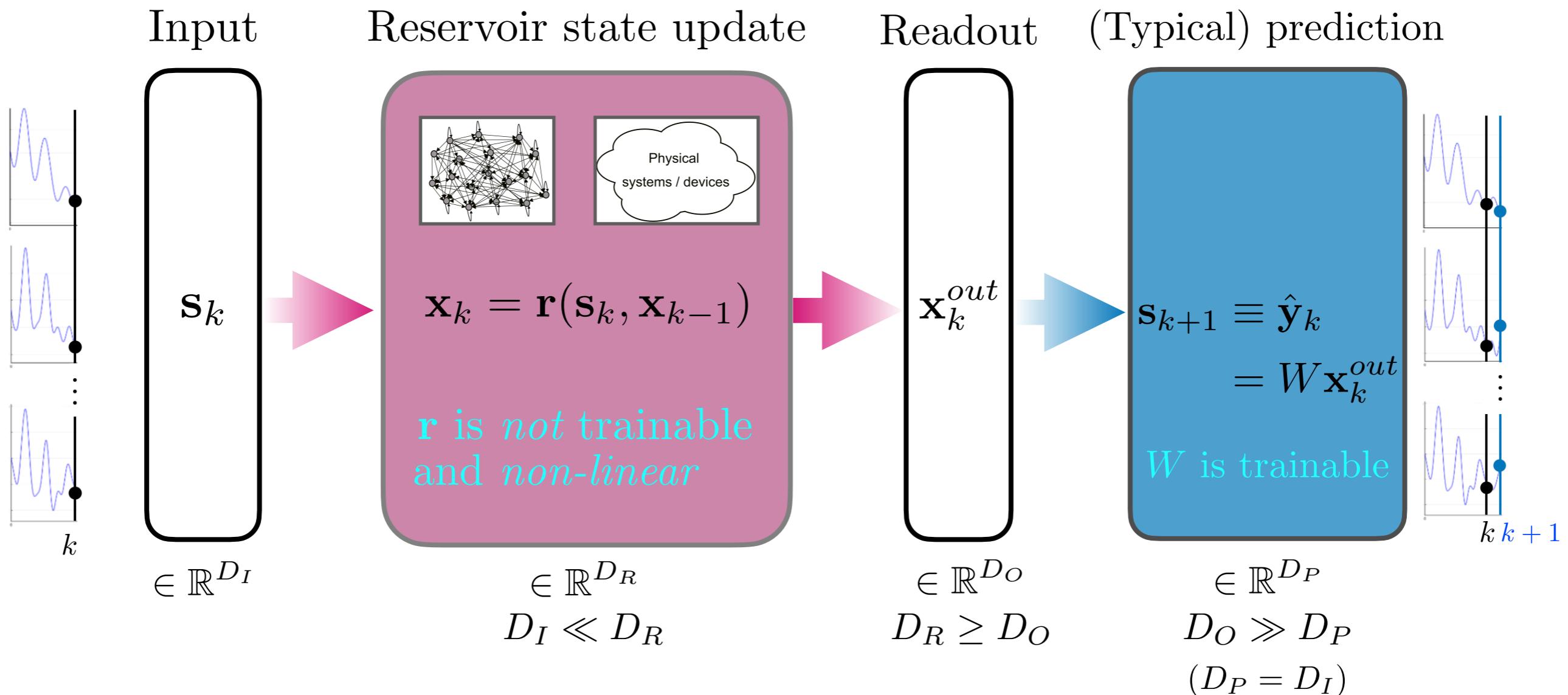
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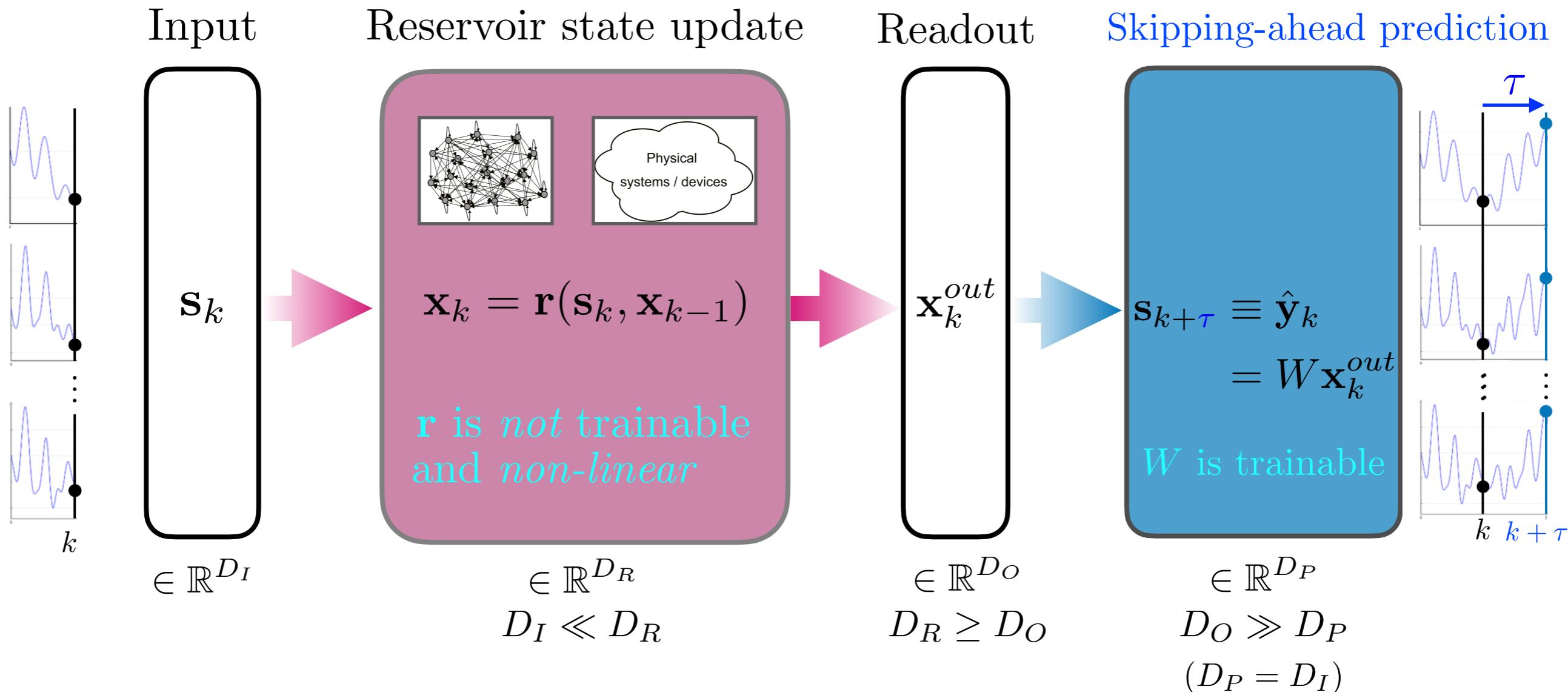
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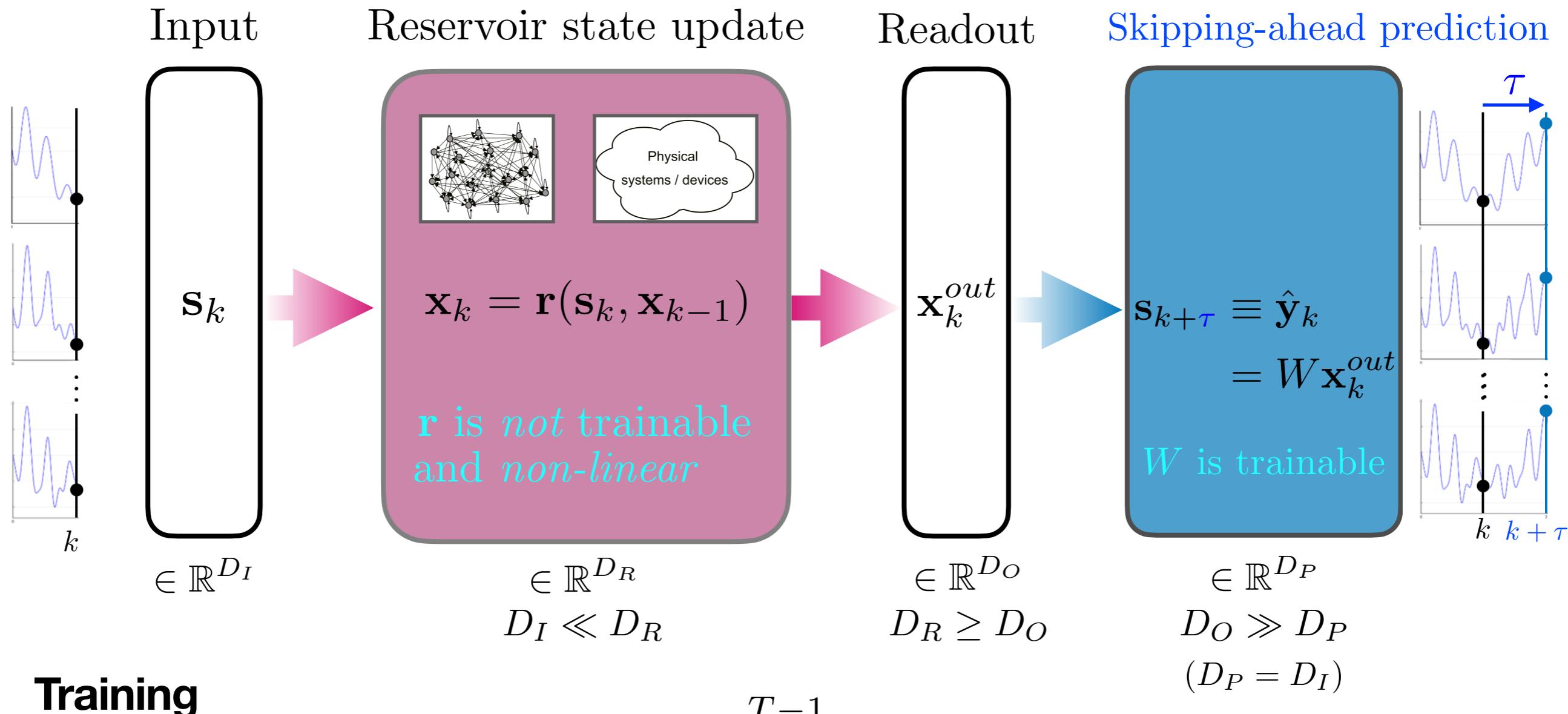
Reservoir Computing (RC) in a nutshell



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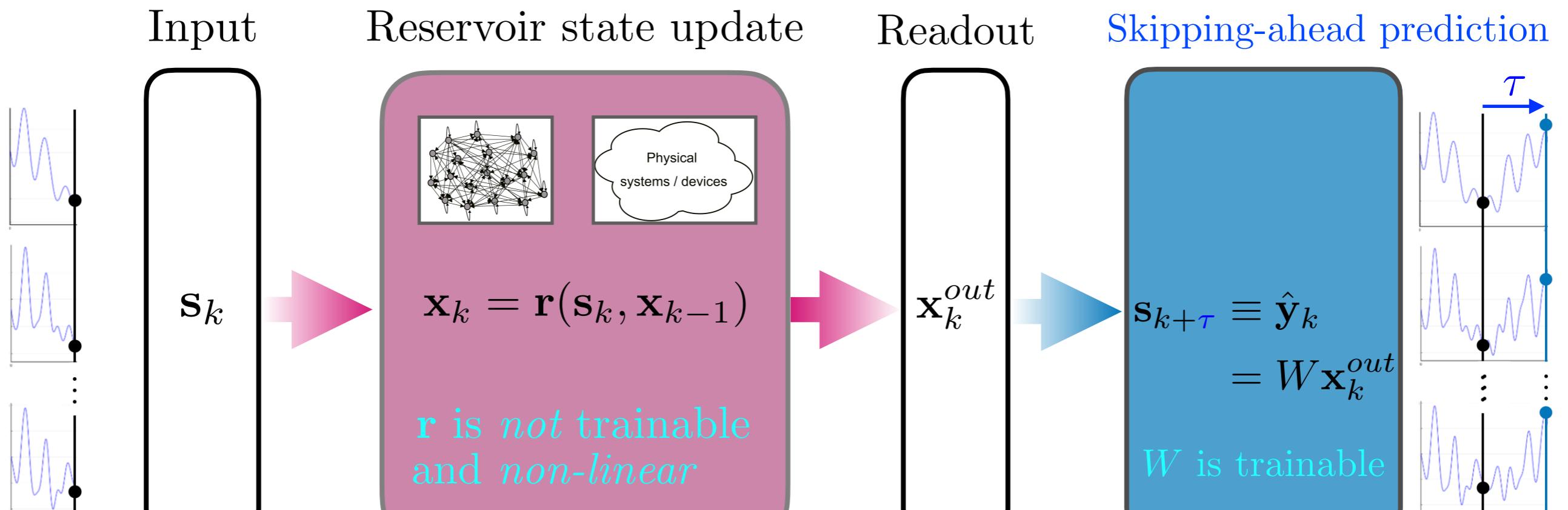
Reservoir Computing (RC) in a nutshell



\mathbf{W} is “trained” by minimizing

$$\frac{1}{T} \sum_{k=0}^{T-1} \|\hat{\mathbf{y}}_k - \mathbf{W} \mathbf{x}_k^{out}\|_2^2 + \lambda \|\mathbf{W}\|^2$$

Reservoir Computing (RC) in a nutshell



Training

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$$\frac{1}{T} \sum_{k=0}^{T-1} \|\hat{y}_k - W x_k^{out}\|_2^2 + \lambda \|W\|^2$$

$$W = Y X^\dagger (X X^\dagger + \lambda I)^{-1}$$

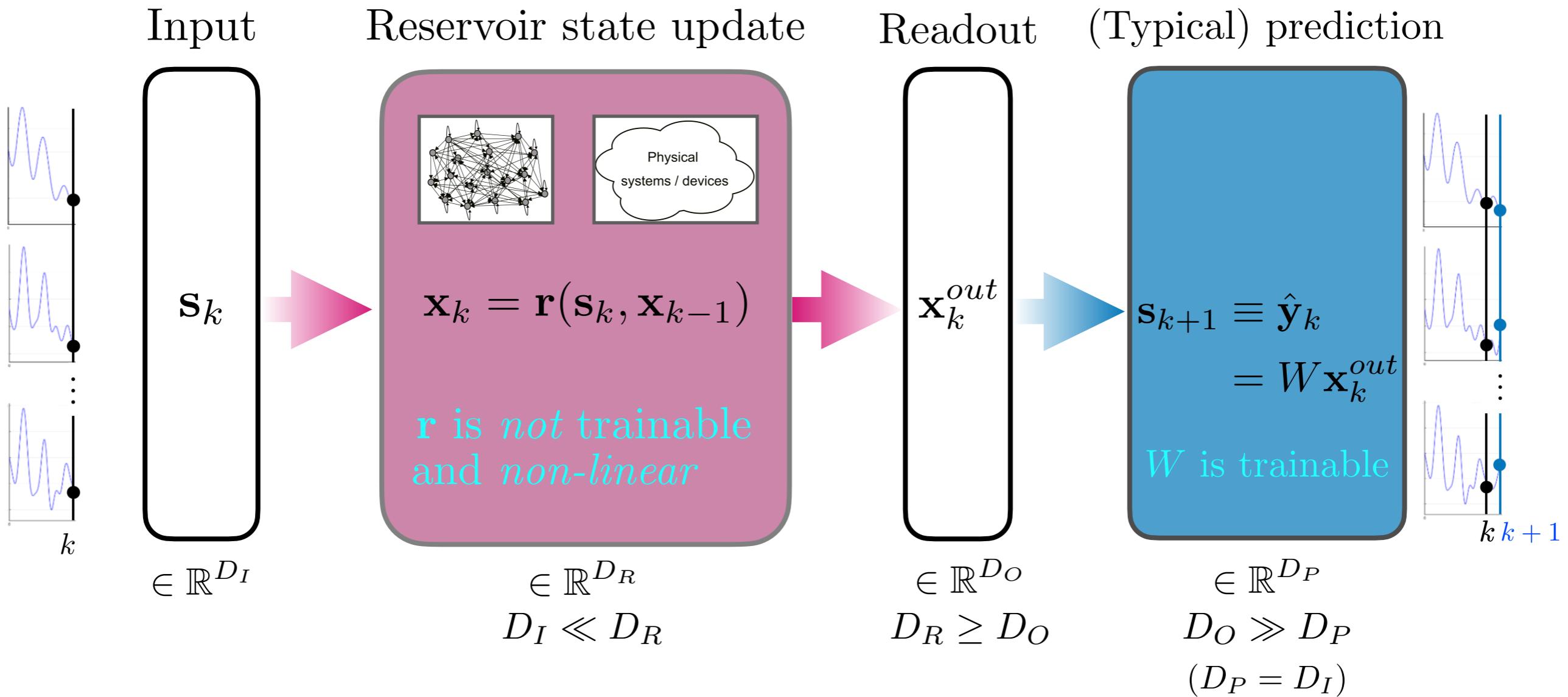
$$Y = (\hat{y}_0, \dots, \hat{y}_{T-1}) \in \mathbb{R}^{D_P \times T}$$

$$X = (x_0^{out}, \dots, x_{T-1}^{out}) \in \mathbb{R}^{D_O \times T}$$

target matrix

feature matrix

Reservoir Computing (RC) in a nutshell



Typical Prediction

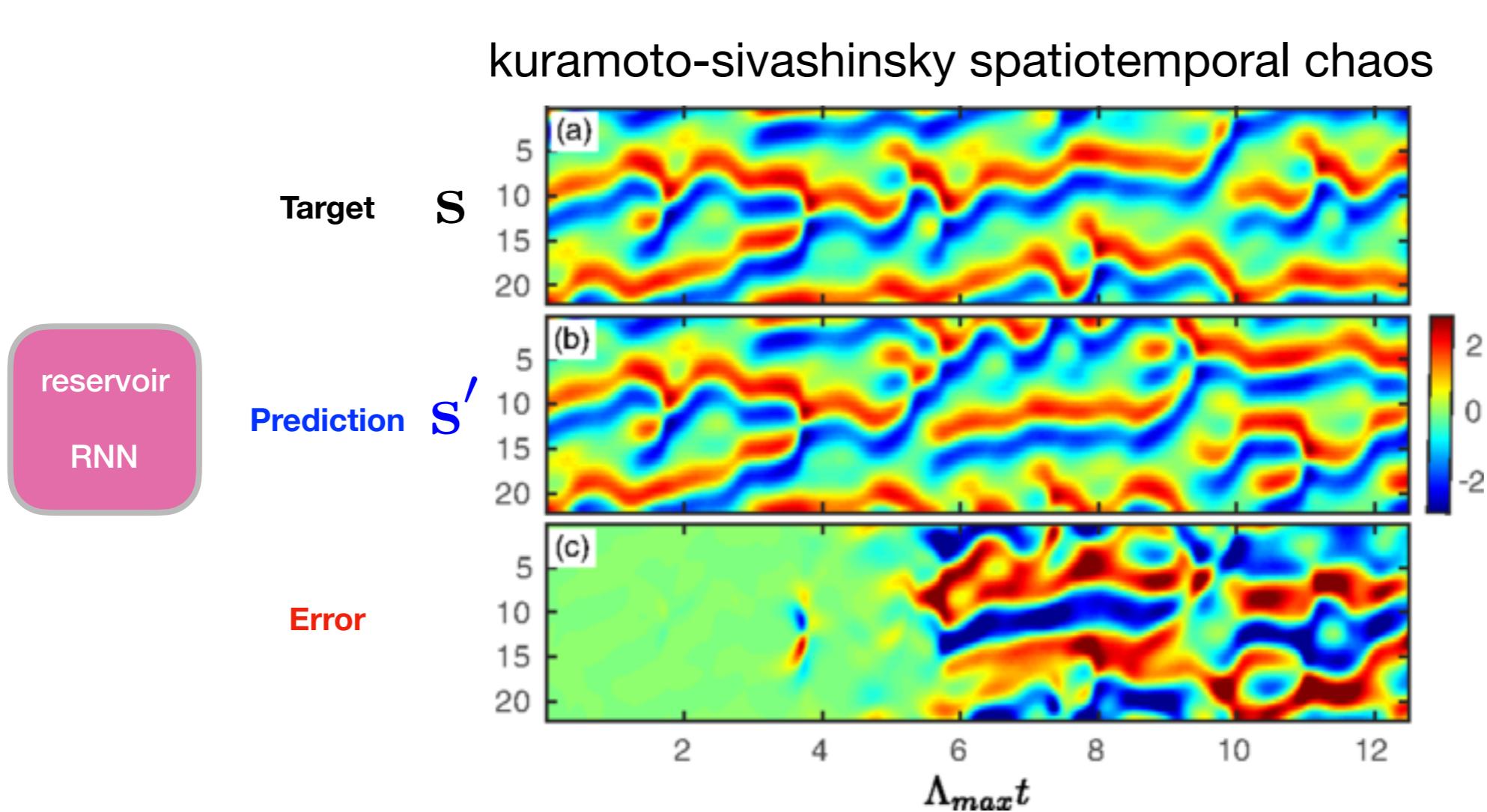
$$(x_k^{out} = x_k)$$

$$s'_{k+1} = W x_k = W r(s'_k, x_{k-1})$$

$$s'_{k+2} = W r(s'_{k+1}, x_k) = W r(W r(s'_k, x_{k-1}), x_k)$$

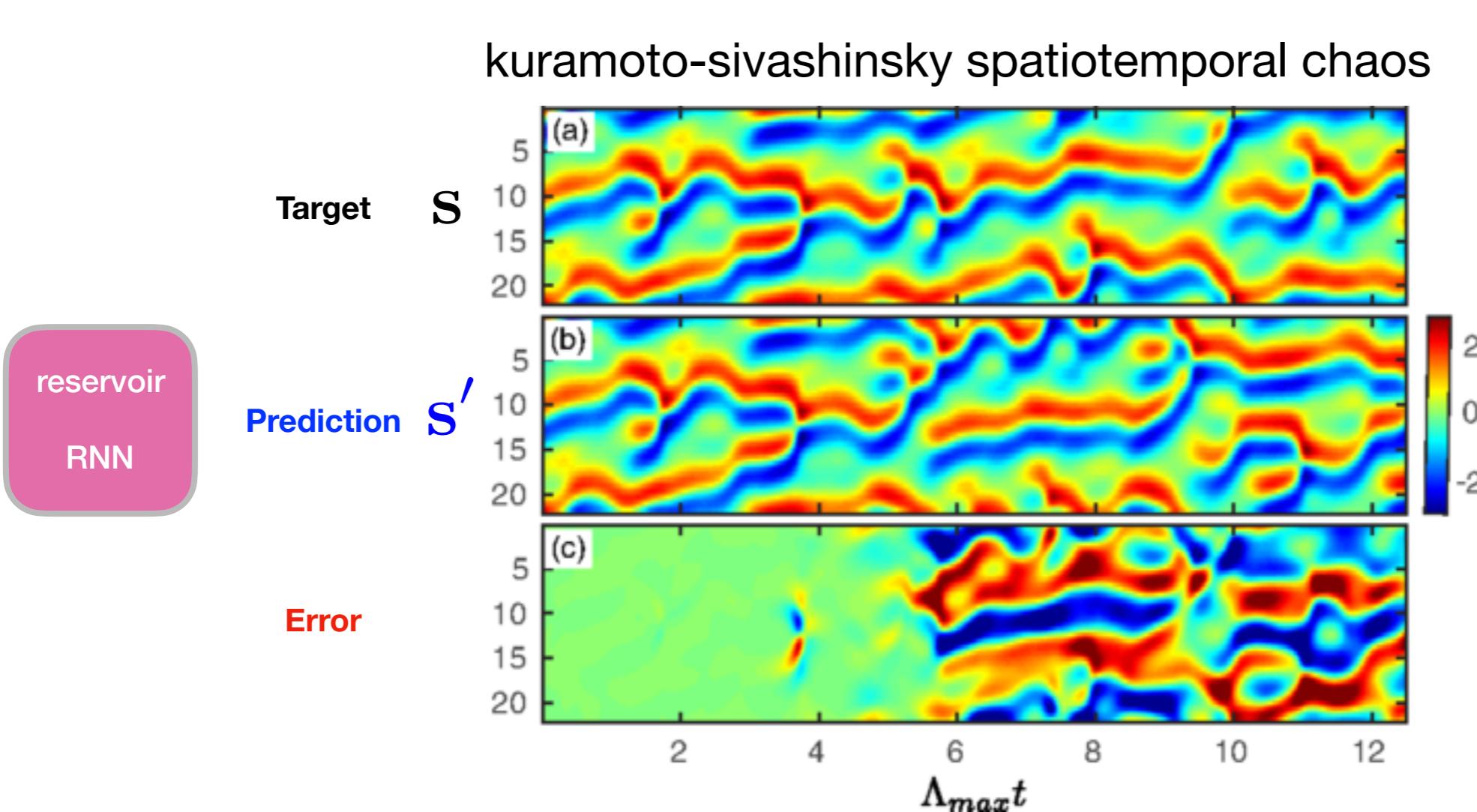
:

kuramoto-sivashinsky spatiotemporal chaos

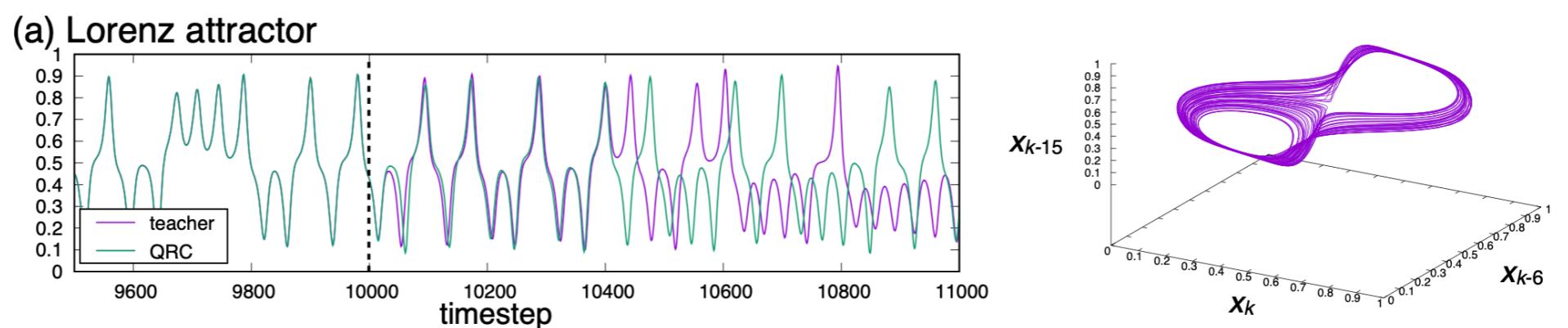


J. Pathak et. al. Model-Free Prediction of Large Spatiotemporally Chaotic Systems from Data: A Reservoir Computing Approach, *Phys. Rev. Lett.* **120**, 024102, 2018

kuramoto-sivashinsky spatiotemporal chaos

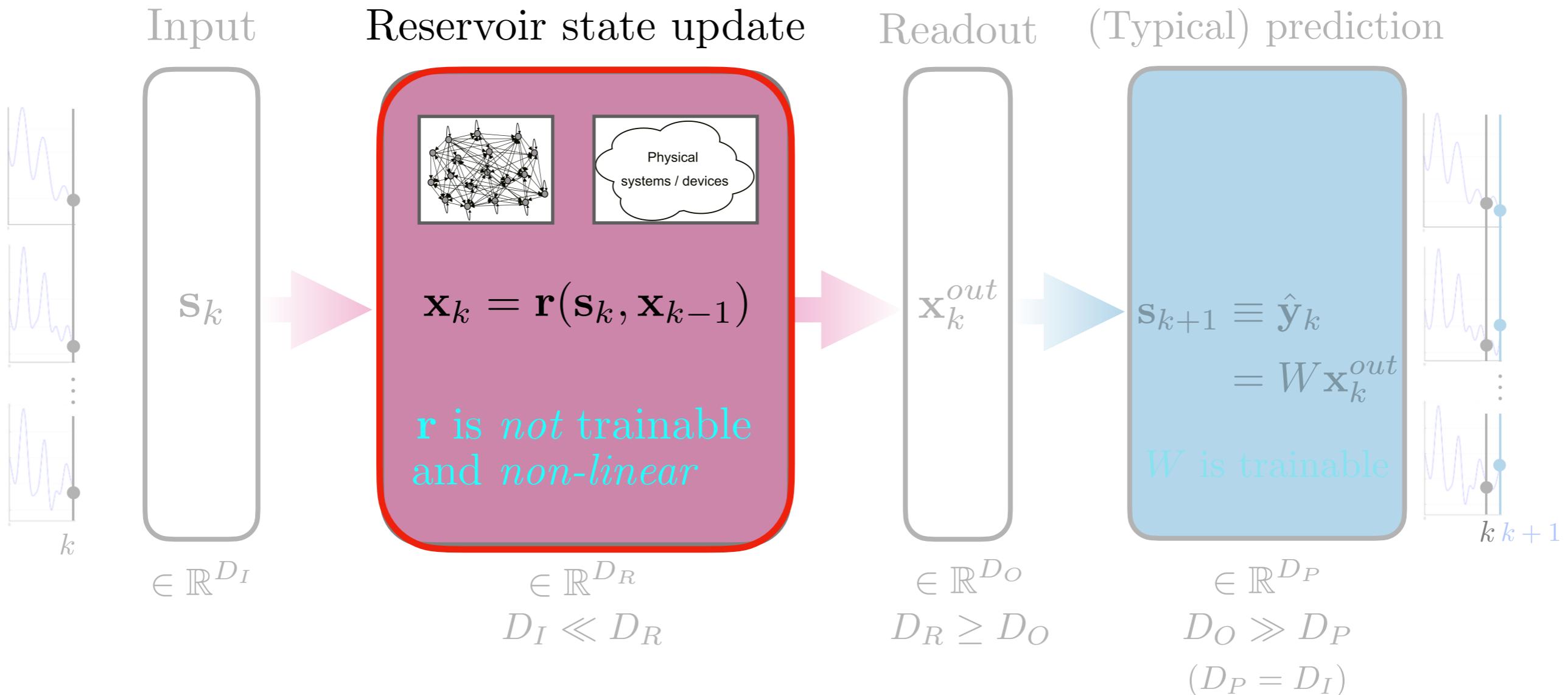


J. Pathak et. al. Model-Free Prediction of Large Spatiotemporally Chaotic Systems from Data: A Reservoir Computing Approach, *Phys. Rev. Lett.* **120**, 024102, 2018



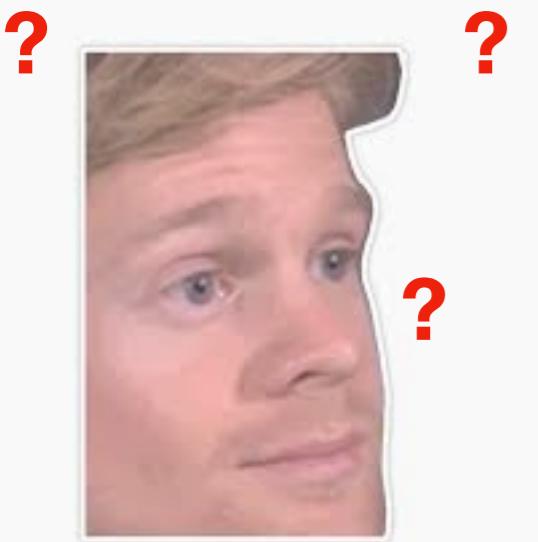
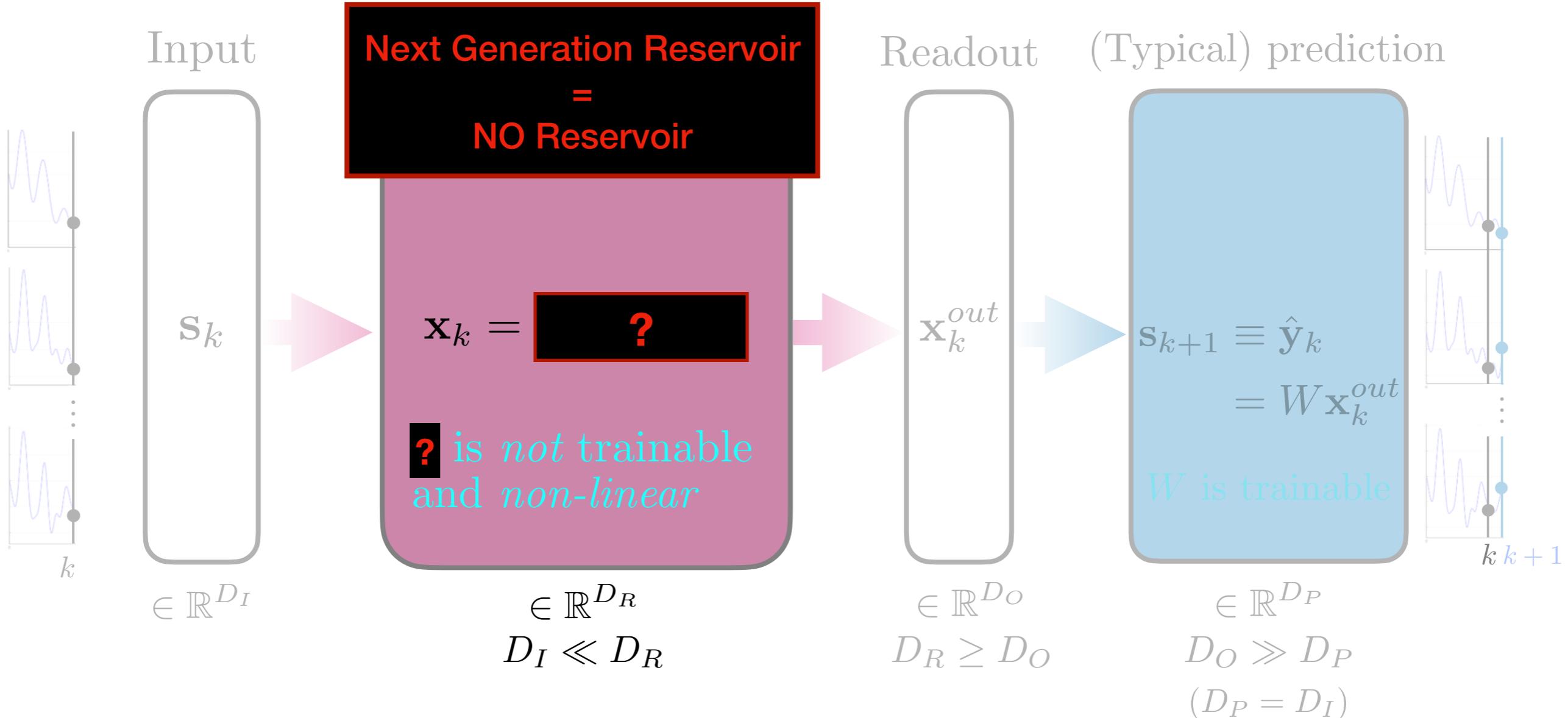
K. Fujii, K. Navajoma Quantum Reservoir Computing: A Reservoir Approach Toward Quantum Machine Learning Near-Term Devices, *Reservoir Computing* 423-450, 2021

Reservoir Computing (RC) in a nutshell

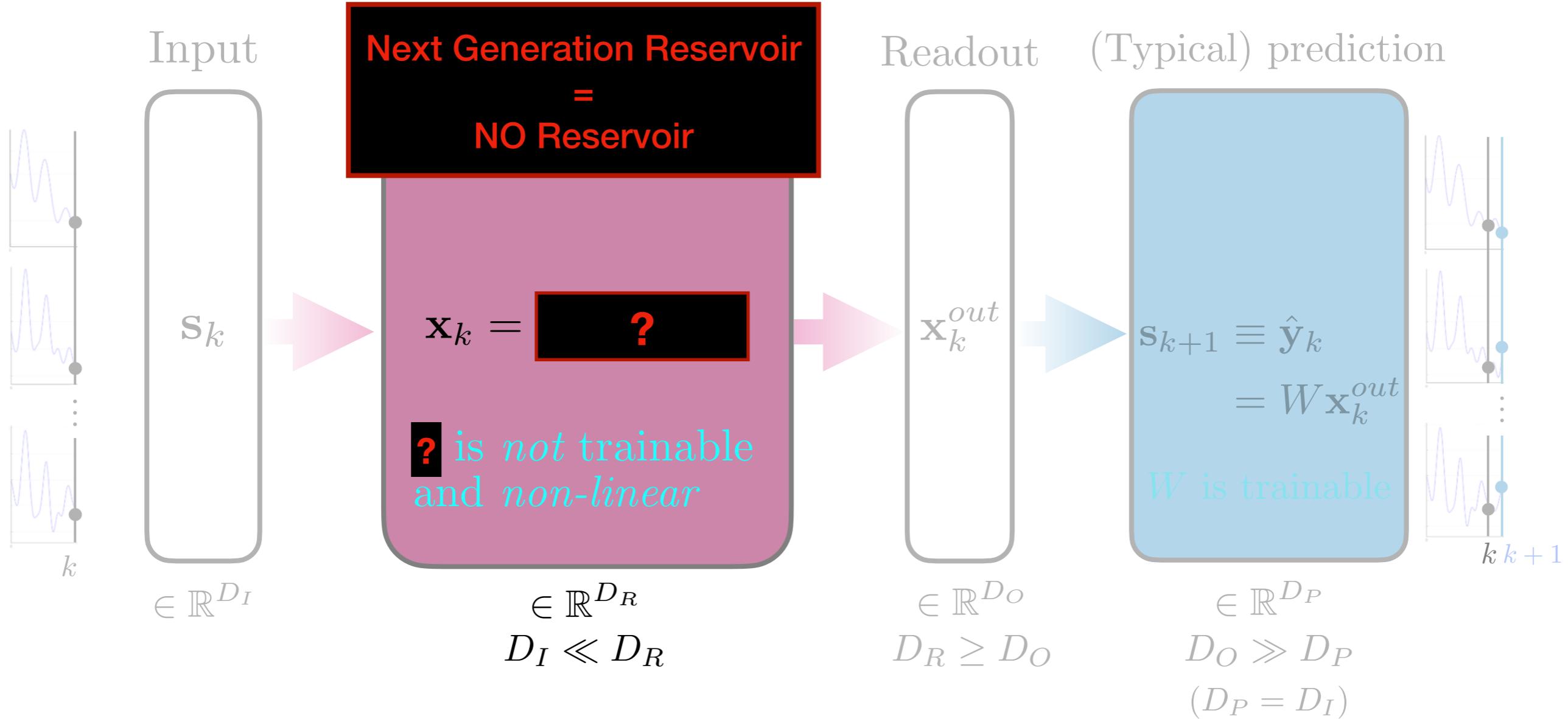


! No clear strategy on how to initialize different types of reservoir !

Next Generation Reservoir Computing (NG-RC) in a nutshell



Next Generation Reservoir Computing (NG-RC) in a nutshell



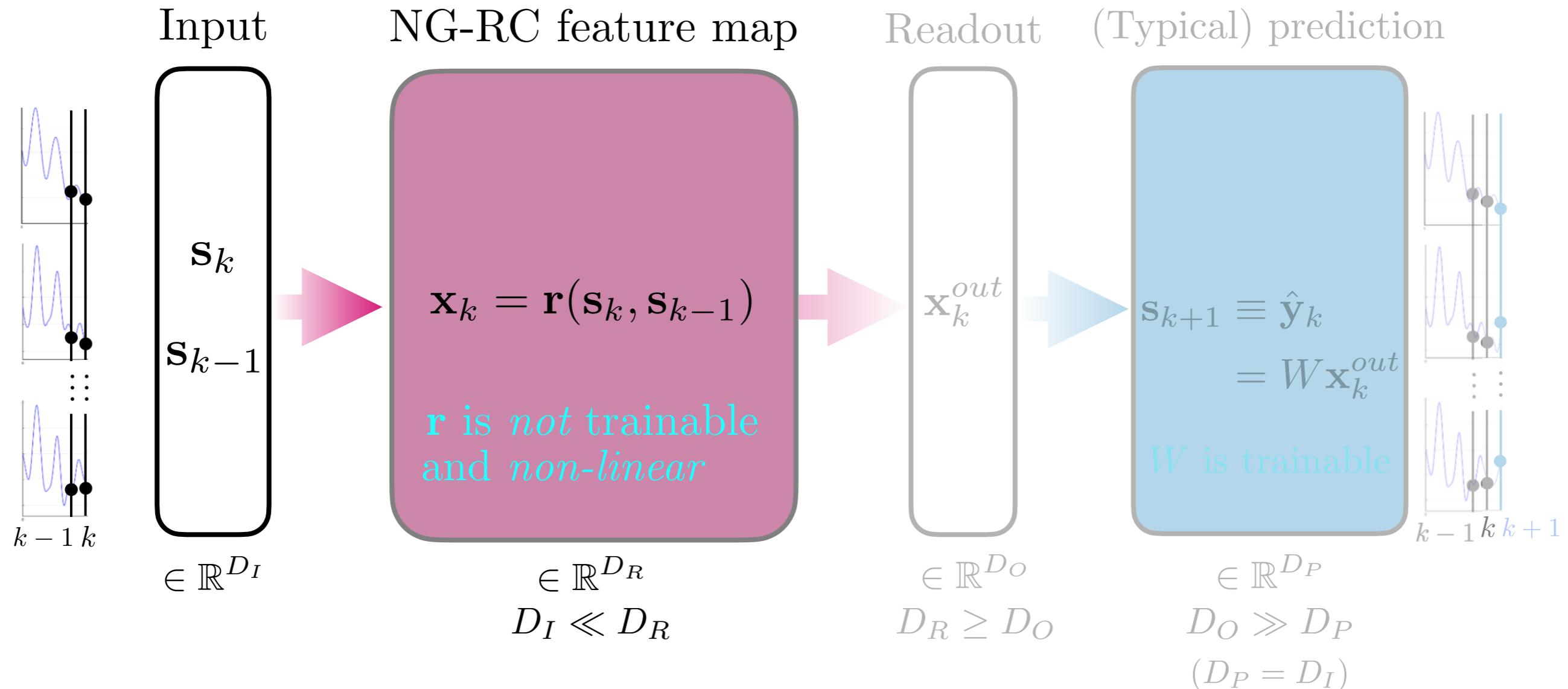
Non-linear feature map with “memory” of the past data

$$\mathbf{o}_k = \mathbf{s}_k \oplus \mathbf{s}_{k-\Delta} \oplus \mathbf{s}_{k-2\Delta} \oplus \dots \oplus \mathbf{s}_{k-(m-1)\Delta}$$

$$\mathbf{x}_k = \mathbf{o}_k \oplus (\mathbf{o}_k)^{\otimes p} \quad (\text{non-linear for } p > 1)$$

In some limit, equivalent to nonlinear vector autoregression (NVAR) with universal approximation property for dynamical systems

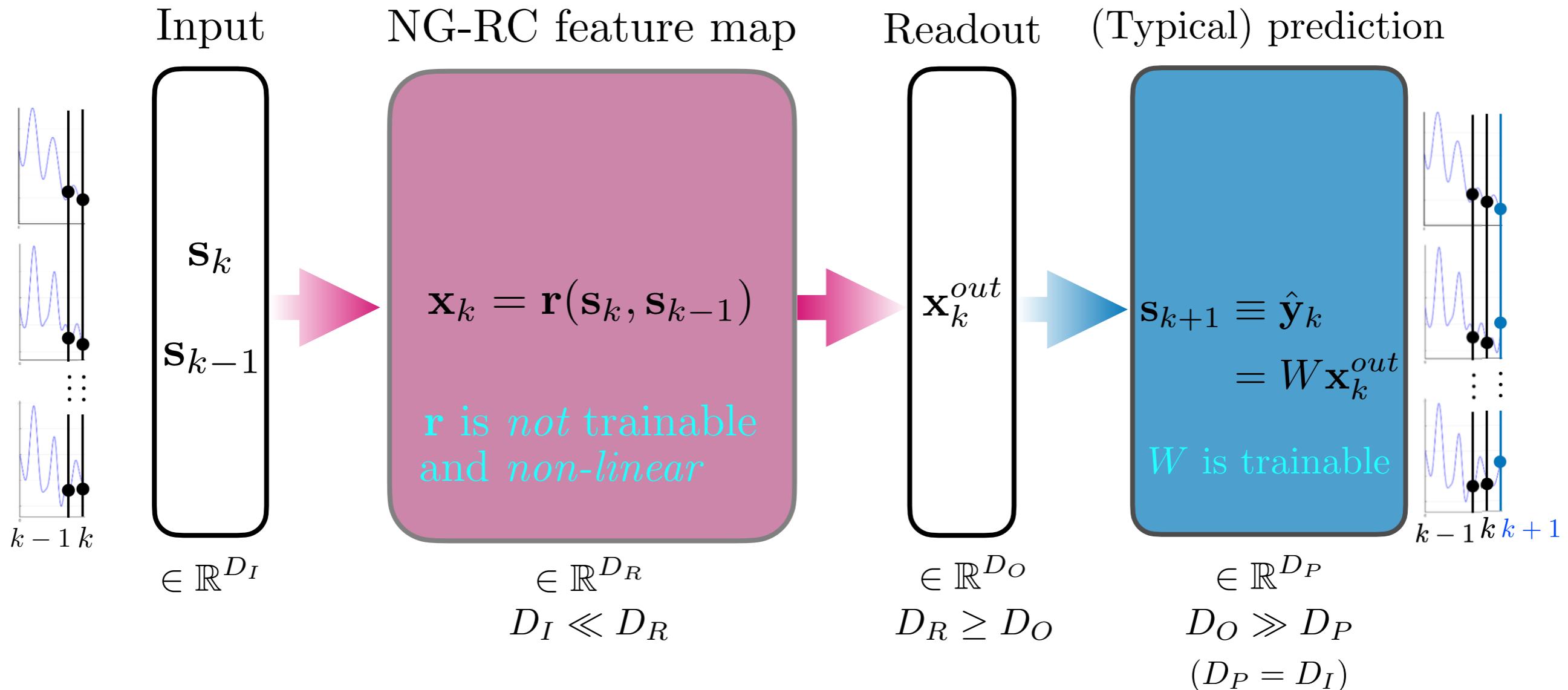
Next Generation Reservoir Computing (NG-RC) in a nutshell



For example $\Delta = 1, m = 2, p = 2$

$$\begin{aligned}\mathbf{x}_k &= \mathbf{s}_k \oplus \mathbf{s}_{k-1} \oplus [(\mathbf{s}_k \oplus \mathbf{s}_{k-1}) \otimes (\mathbf{s}_k \oplus \mathbf{s}_{k-1})] \\ &\equiv \mathbf{r}(\mathbf{s}_k, \mathbf{s}_{k-1})\end{aligned}$$

Next Generation Reservoir Computing (NG-RC) in a nutshell

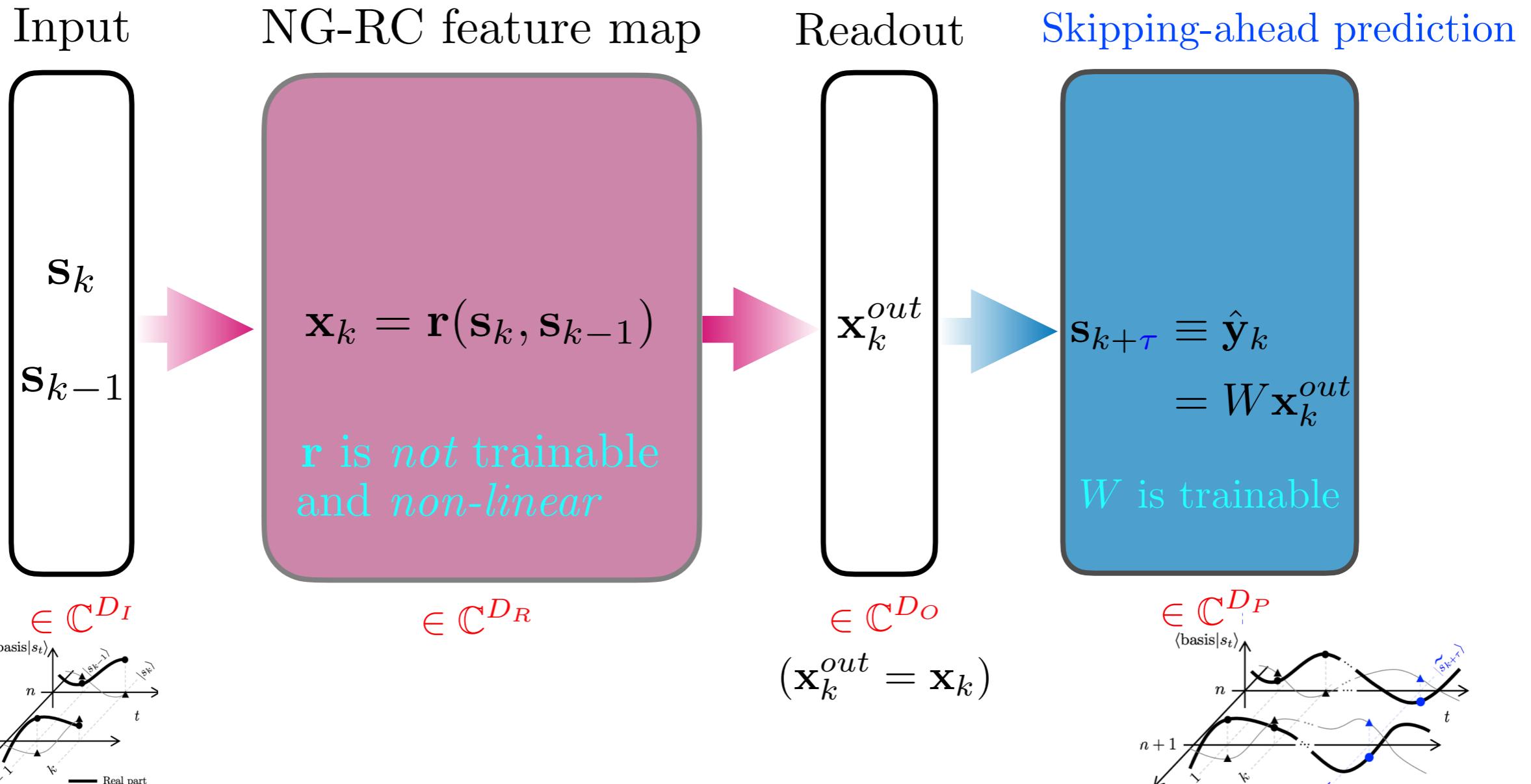


Training

$$\mathbf{W} = Y X^\dagger (X X^\dagger + \lambda I)^{-1}$$

Typical prediction $\mathbf{s}'_{k+1} = \mathbf{W}\mathbf{x}_k = \mathbf{W}\mathbf{r}(\mathbf{s}'_k, \mathbf{s}'_{k-1})$ $(\mathbf{x}_k^{\text{out}} = \mathbf{x}_k)$

NG-RC for forecasting quantum dynamics



Training

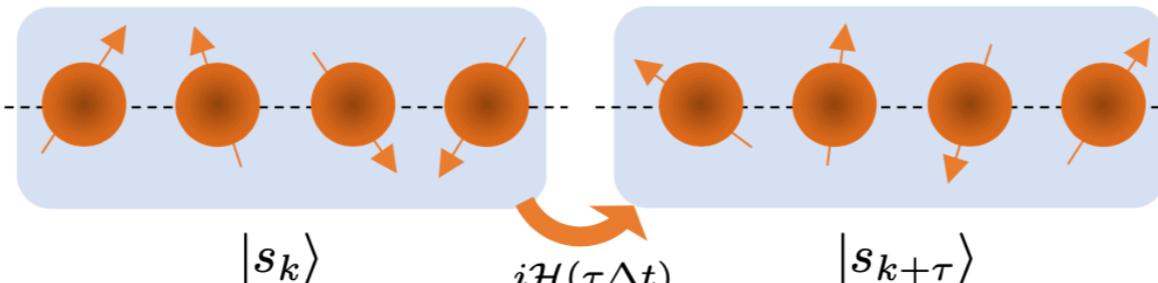
$$W = YX^\dagger(XX^\dagger + \lambda I)^{-1}$$

Skipping-ahead
prediction

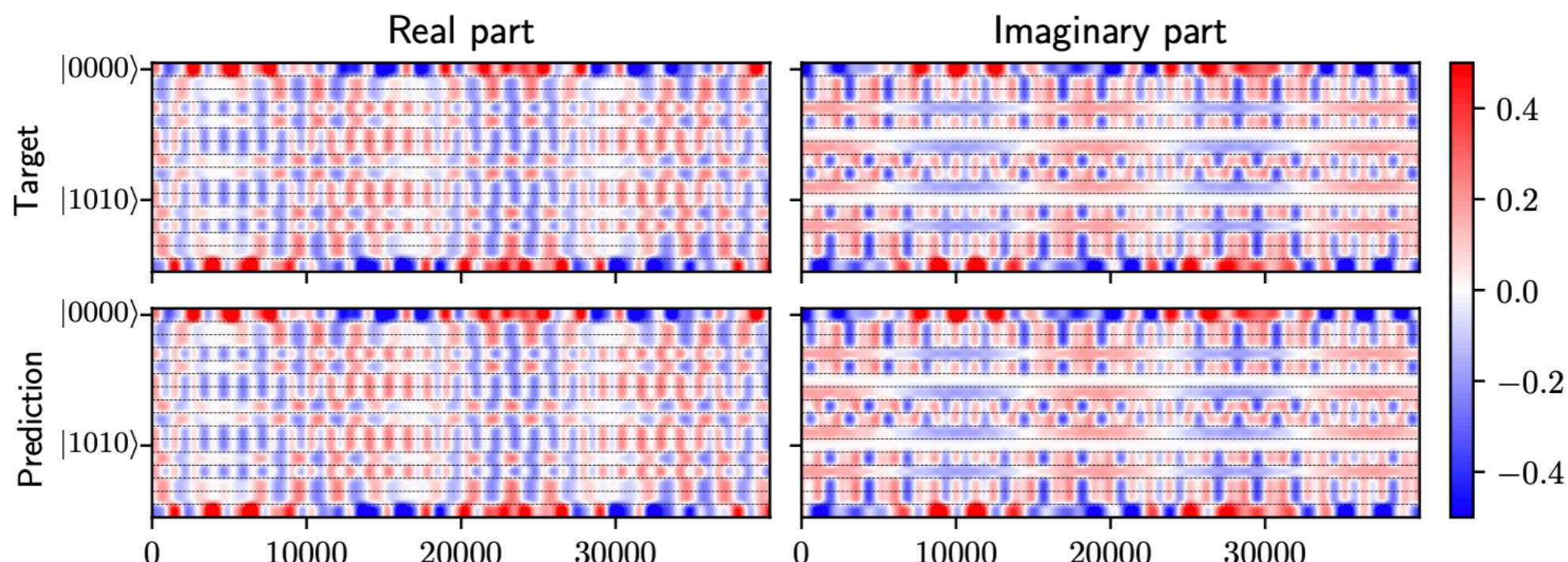
$$\mathbf{s}'_{k+\tau} = W\mathbf{x}_k = W\mathbf{r}(\mathbf{s}'_k, \mathbf{s}'_{k-1})$$

NG-RC for forecasting integrable quantum dynamics

$$\mathcal{H} = -J \sum_{i=1}^4 Z_i Z_{i+1} + h \sum_{i=1}^4 X_i$$

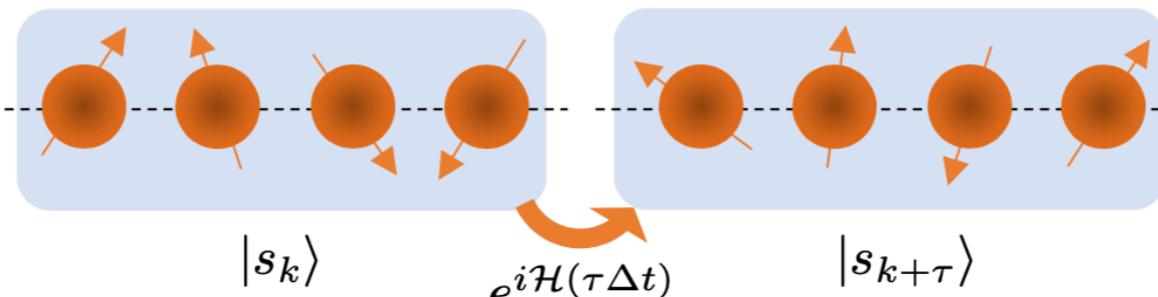


skipping-ahead with $\tau = 10^6$

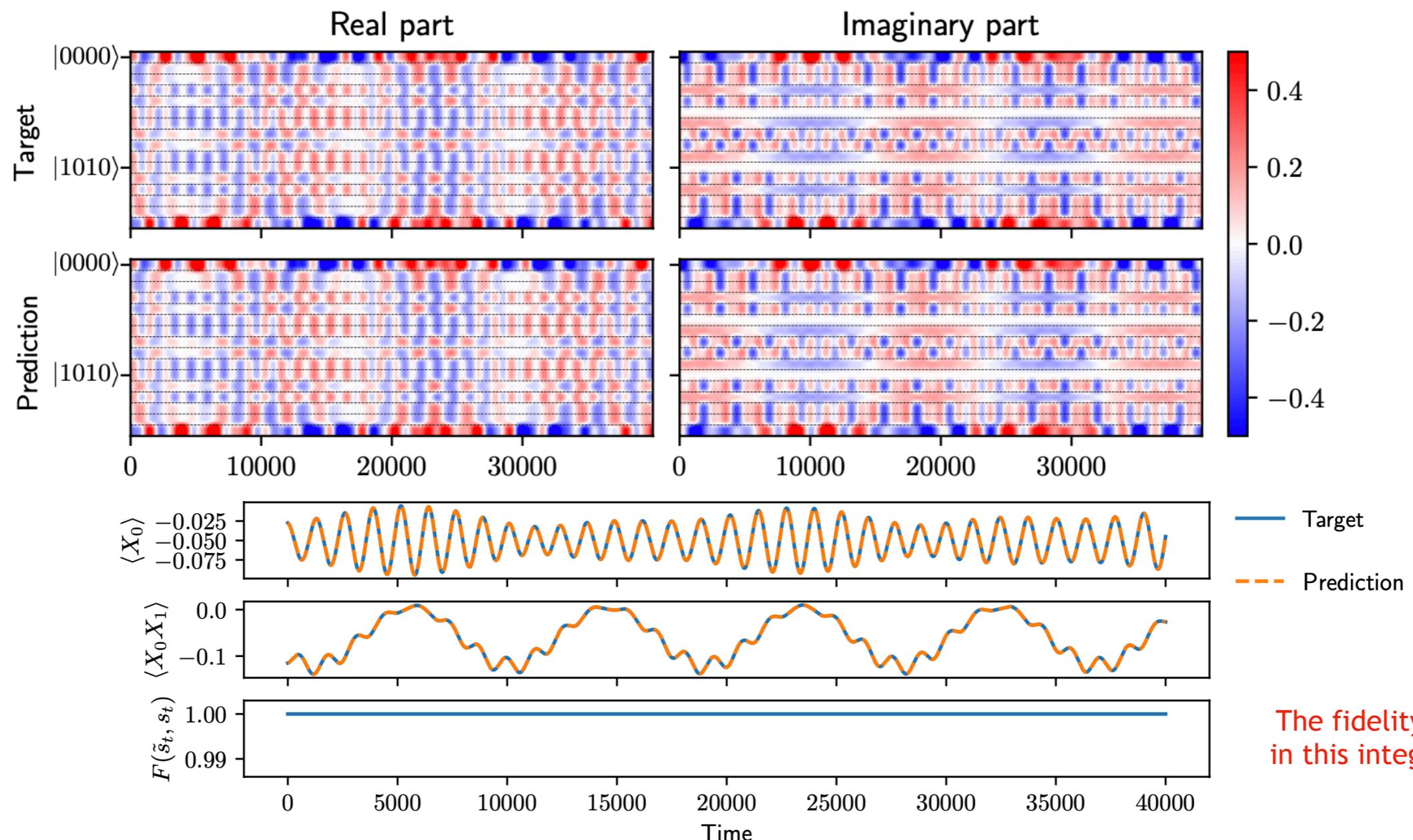


NG-RC for forecasting integrable quantum dynamics

$$\mathcal{H} = -J \sum_{i=1}^4 Z_i Z_{i+1} + h \sum_{i=1}^4 X_i$$



skipping-ahead with $\tau = 10^6$

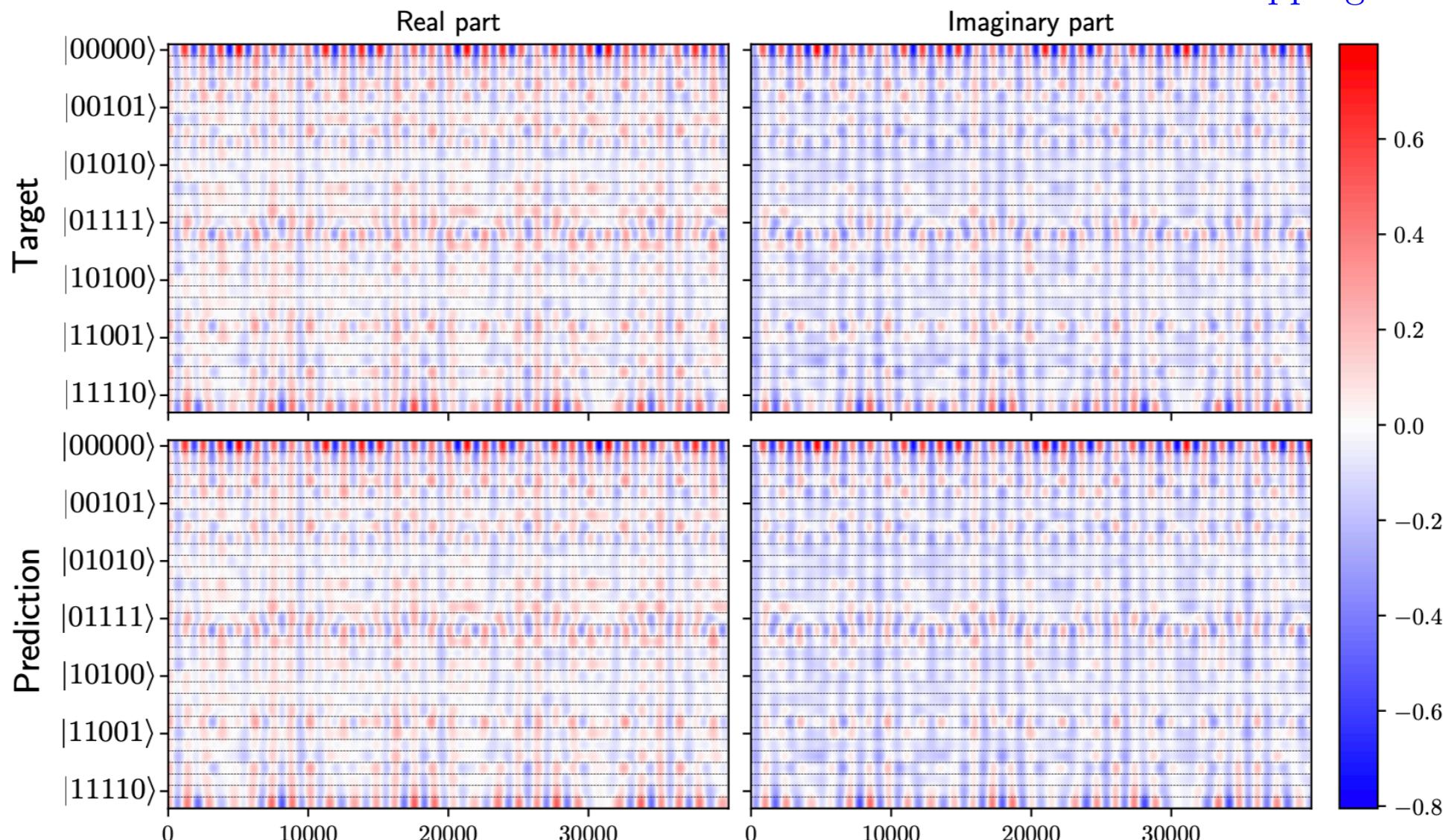


NG-RC for forecasting *chaotic* quantum dynamics

$$\mathcal{H}_{\text{tilted}} = J \sum_{i=1}^{d-1} Z_i Z_{i+1} + h \sum_{i=1}^d (X_i \sin \theta + Z_i \cos \theta)$$

$d = 5, \theta = 15\pi/32$

skipping-ahead with $\tau = 10^6$

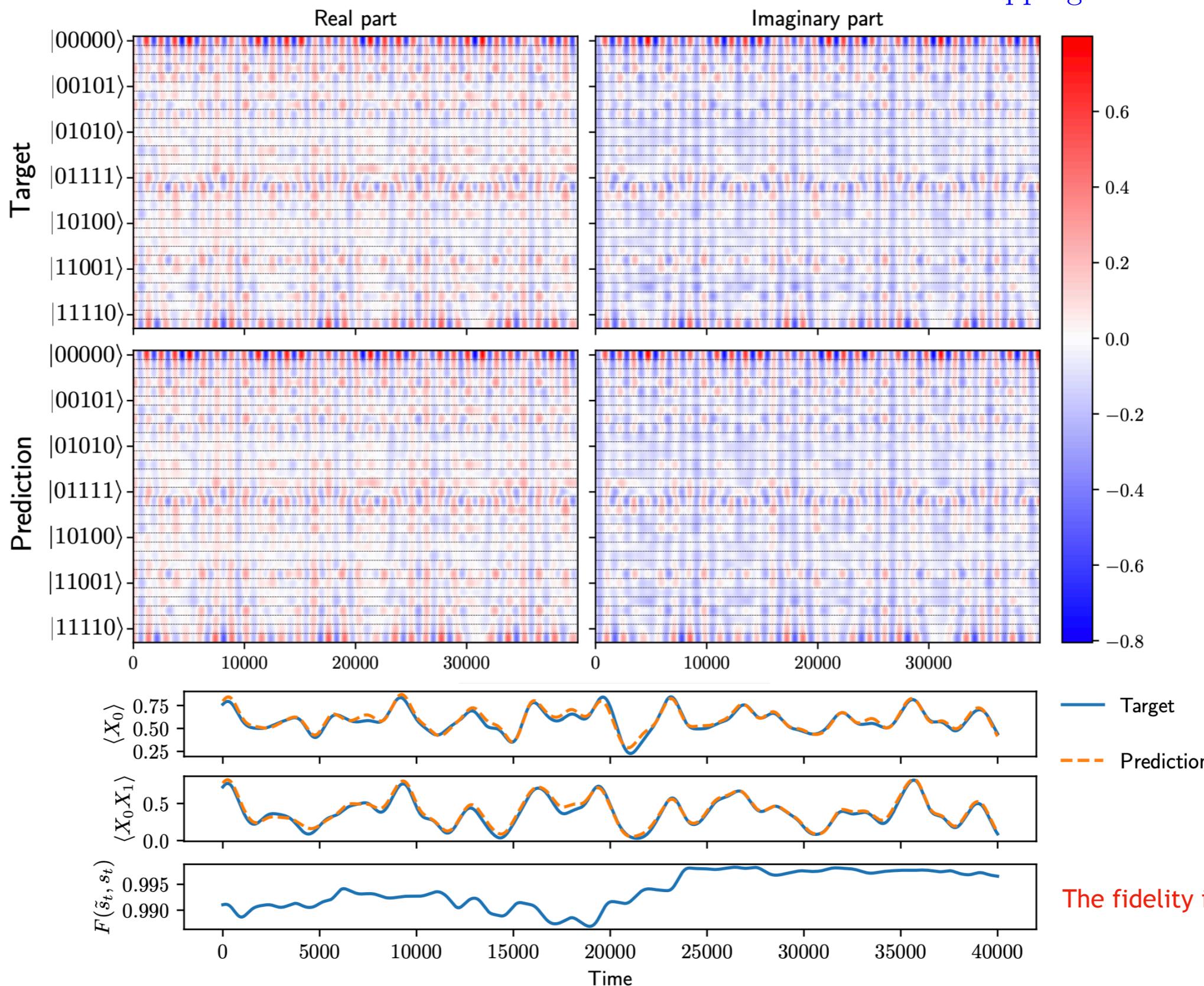


NG-RC for forecasting *chaotic* quantum dynamics

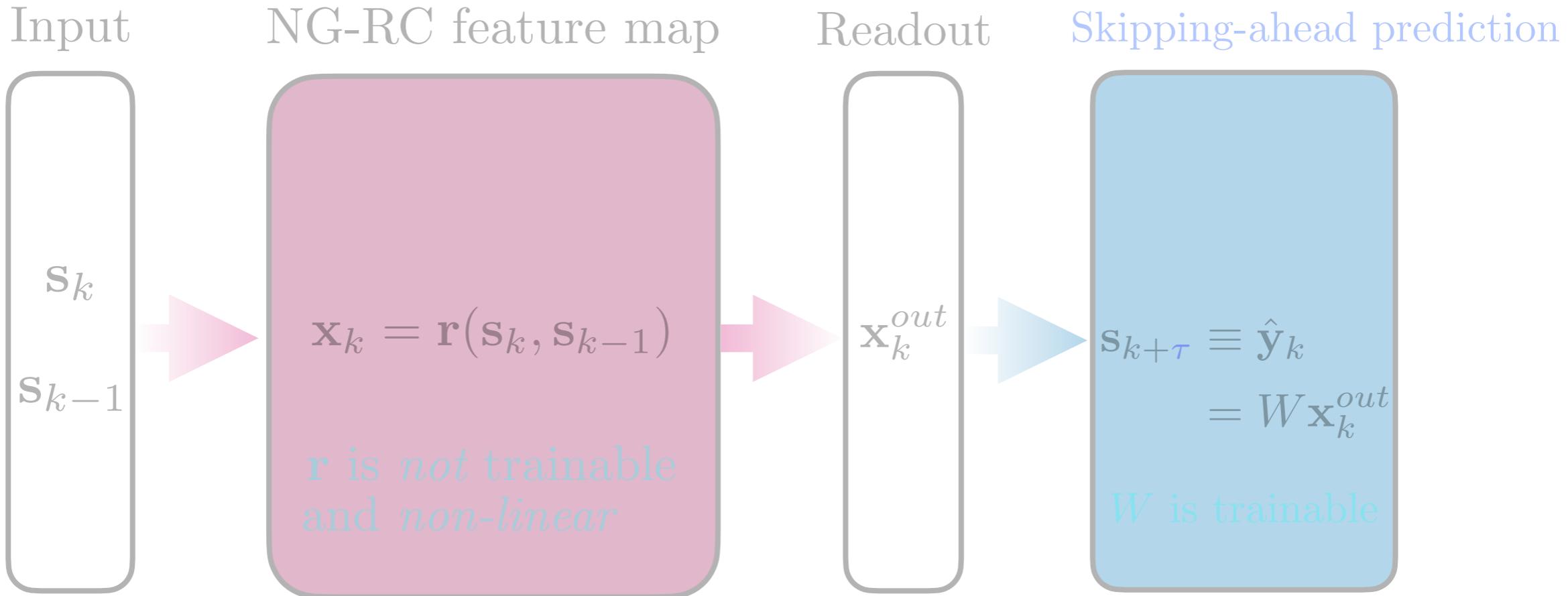
$$\mathcal{H}_{\text{tilted}} = J \sum_{i=1}^{d-1} Z_i Z_{i+1} + h \sum_{i=1}^d (X_i \sin \theta + Z_i \cos \theta)$$

$$d = 5, \theta = 15\pi/32$$

skipping-ahead with $\tau = 10^6$



Scalability issue of classical NG-RC for many-body systems



Training

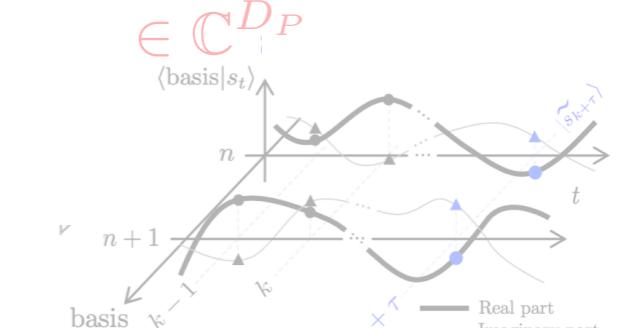
$\in \mathbb{C}^{D_I}$

Real part
Imaginary part

$$W = Y X^\dagger (X X^\dagger + \lambda I)^{-1}$$

Skipping-ahead prediction

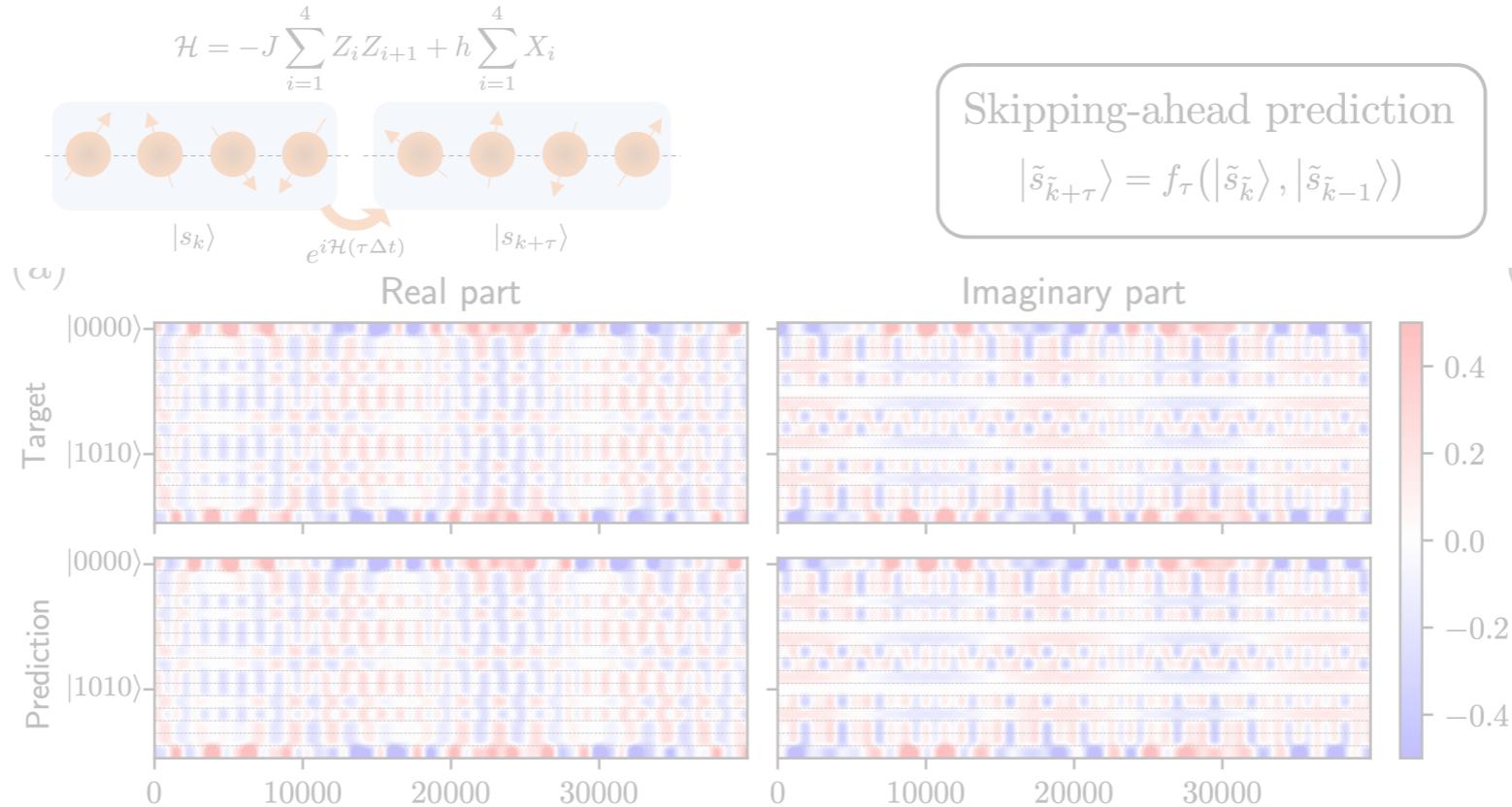
$$\mathbf{s}'_{k+\tau} = W \mathbf{x}_k = W \mathbf{r}(\mathbf{s}'_k, \mathbf{s}'_{k-1})$$



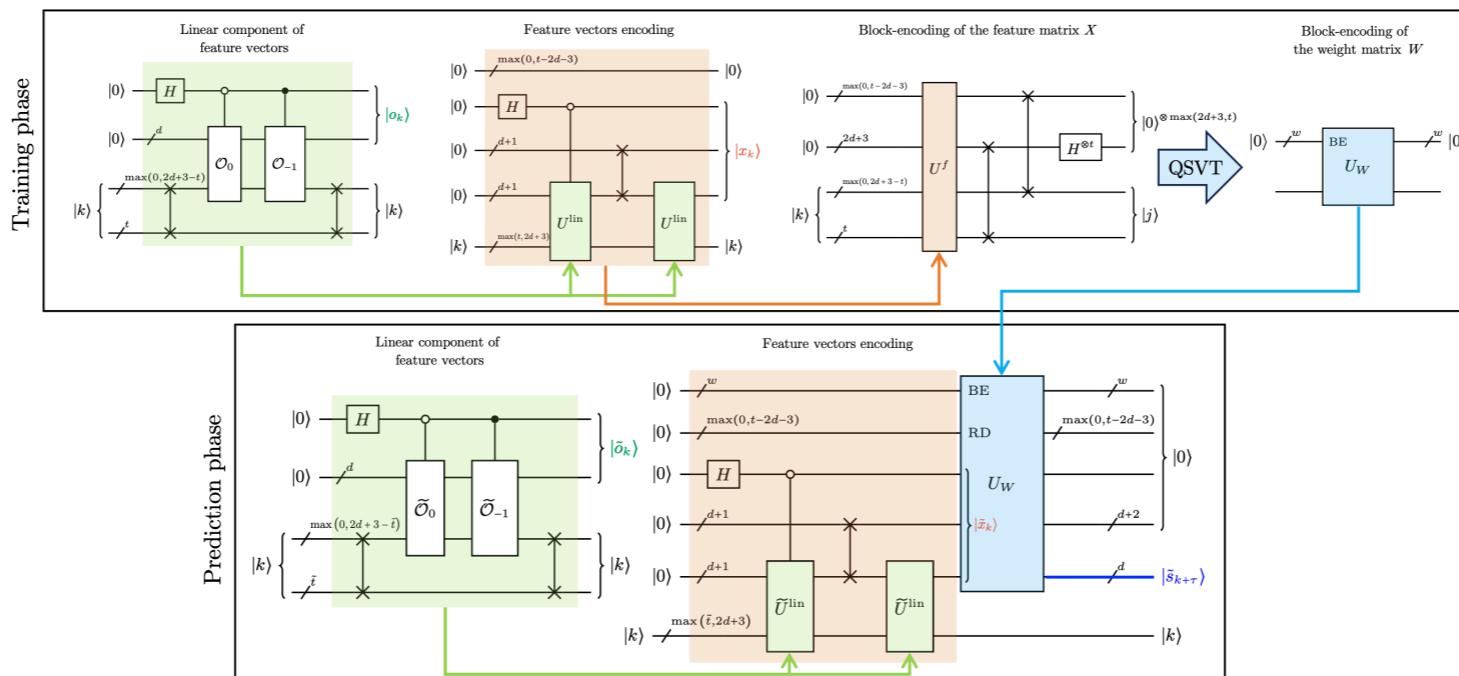
$O(2^{2d} T)$
Pseudoinverse Computation
 $d = \#$ of qubits

Outline

Part 1: NG-RC for Many-body Quantum Dynamics Prediction

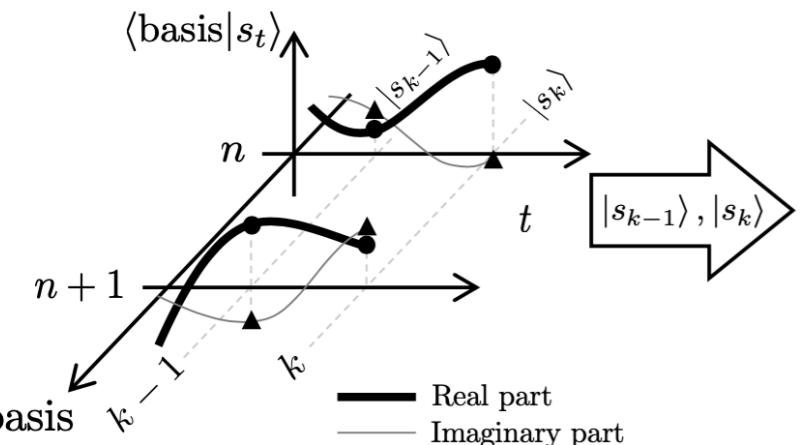


Part 2: Quantum Algorithm for NG-RC (QNG-RC)

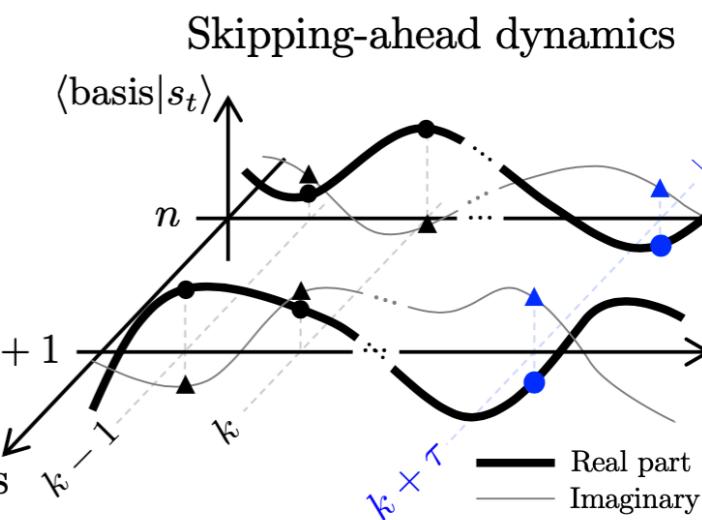


Quantum Algorithm for NG-RC (QNG-RC)

Quantum dynamics

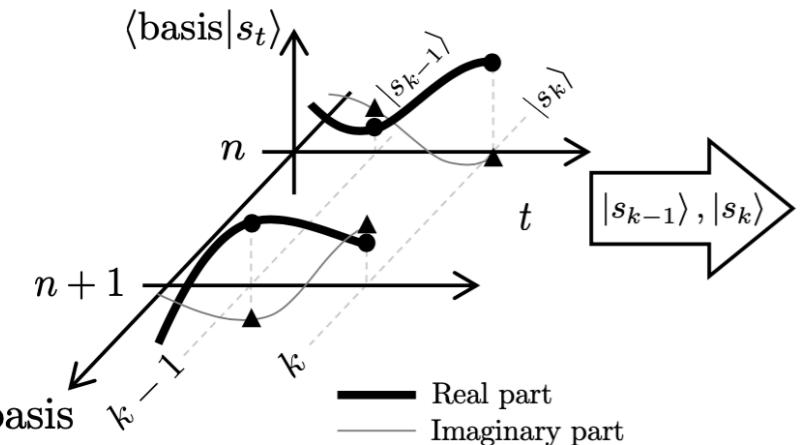


Regularized Linear Layer W



Quantum Algorithm for NG-RC (QNG-RC)

Quantum dynamics



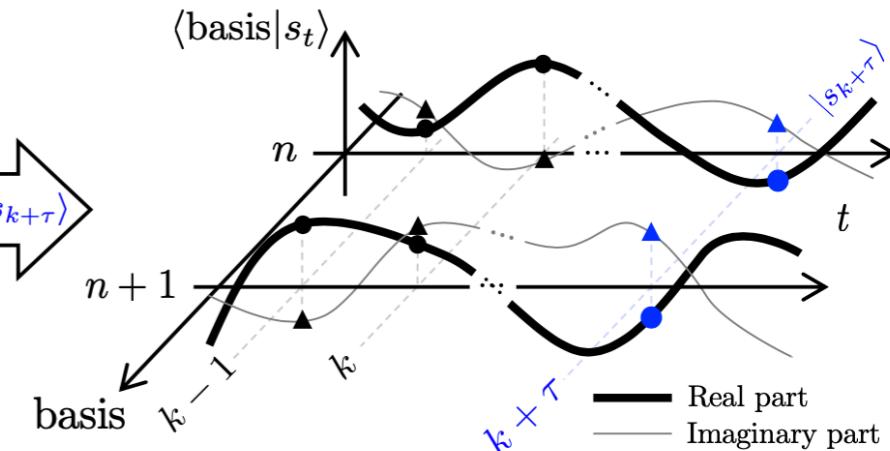
Feature encoder

$$(|s_{k-1}\rangle, |s_k\rangle) \rightarrow |o_k\rangle = |s_k\rangle \oplus |s_{k-1}\rangle$$

$$|o_k\rangle \rightarrow |x_k\rangle = (|o_k\rangle \otimes |o_k\rangle) \oplus |o_k\rangle$$



Skipping-ahead dynamics



Training

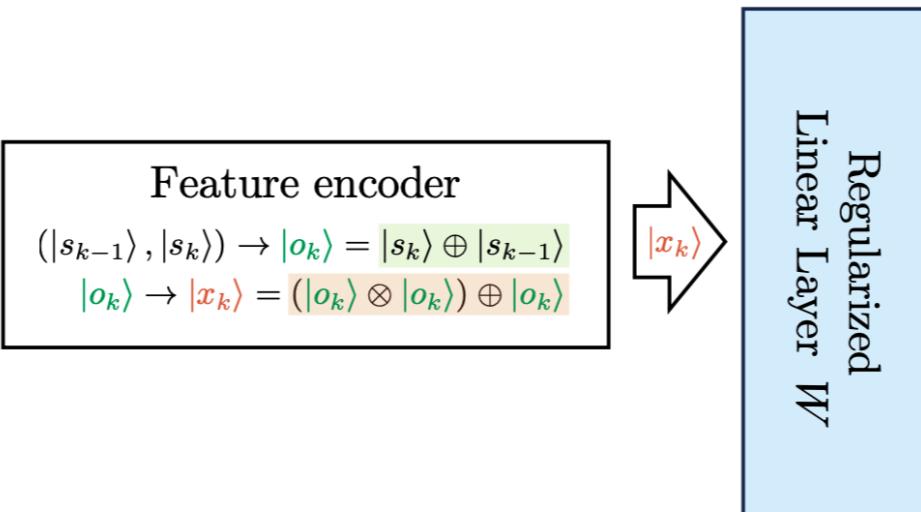
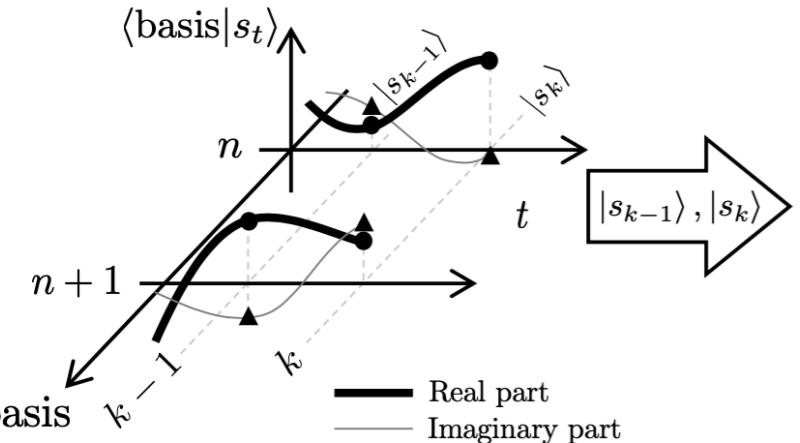
$$W = Y X^\dagger (X X^\dagger + \lambda I)^{-1}$$

Skipping-ahead prediction

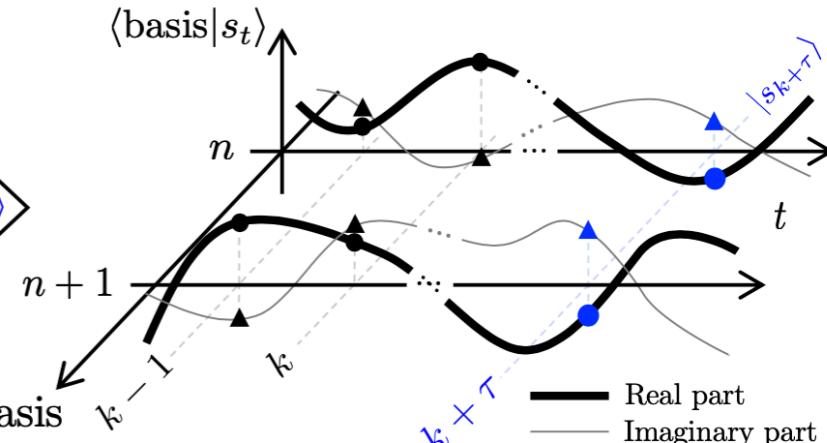
$$|s'_{k+\tau}\rangle = W|x_k\rangle = W\mathbf{r}(|s'_k\rangle, |s'_{k-1}\rangle)$$

Quantum Algorithm for NG-RC (QNG-RC)

Quantum dynamics

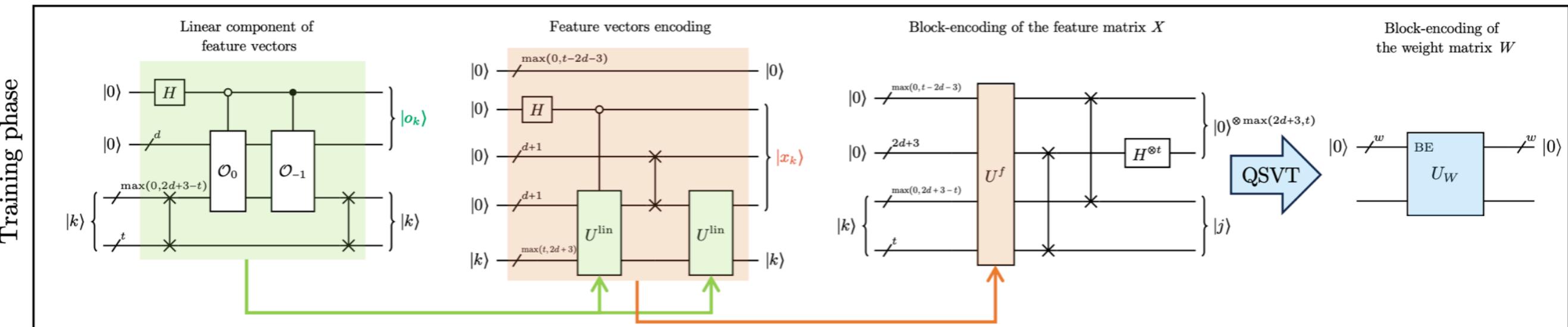


Skipping-ahead dynamics



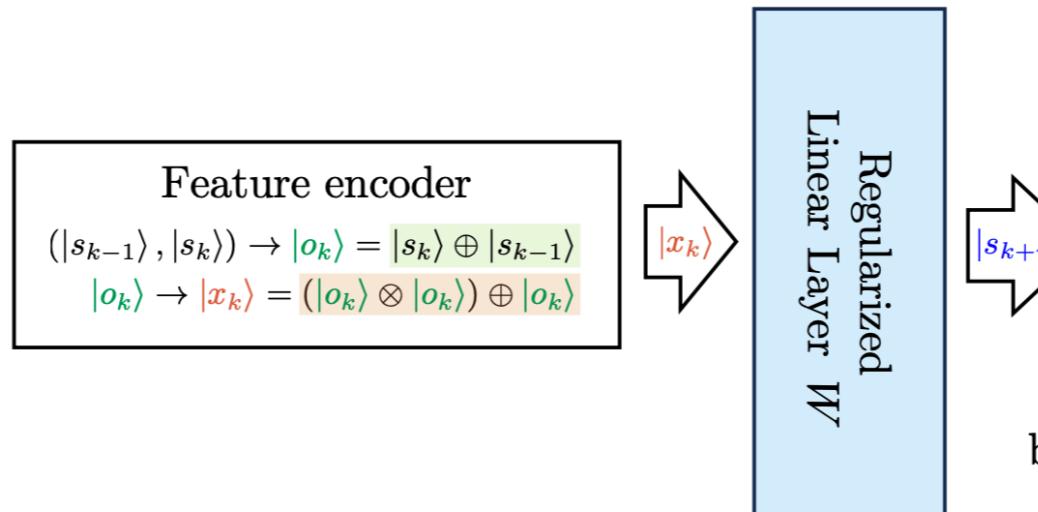
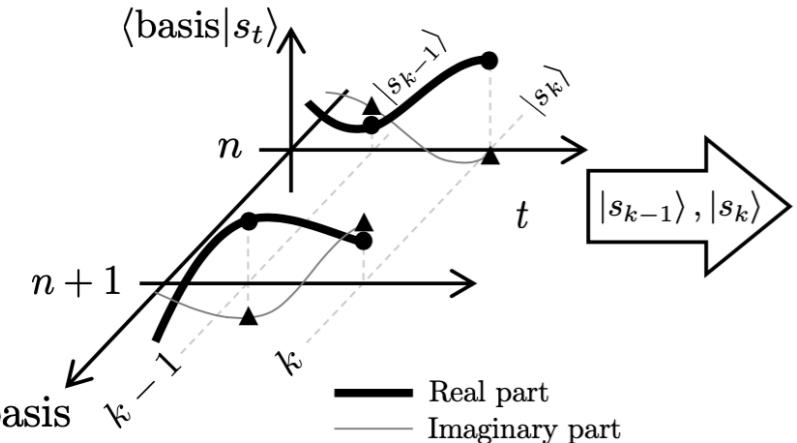
Training

$$W = Y X^\dagger (X X^\dagger + \lambda I)^{-1}$$

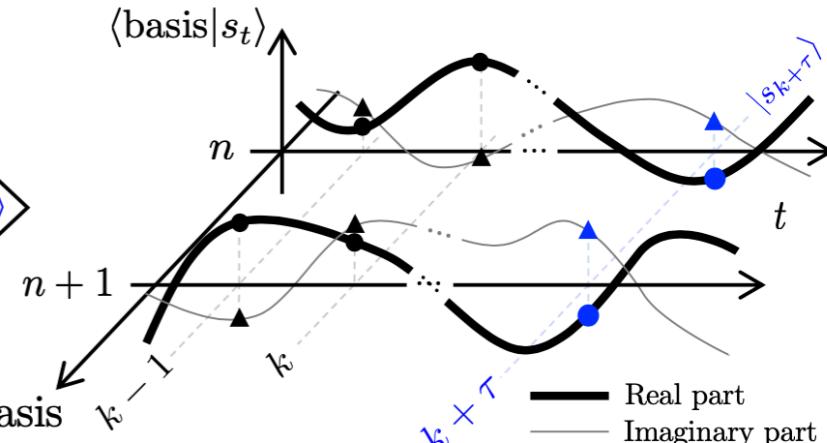


Quantum Algorithm for NG-RC (QNG-RC)

Quantum dynamics

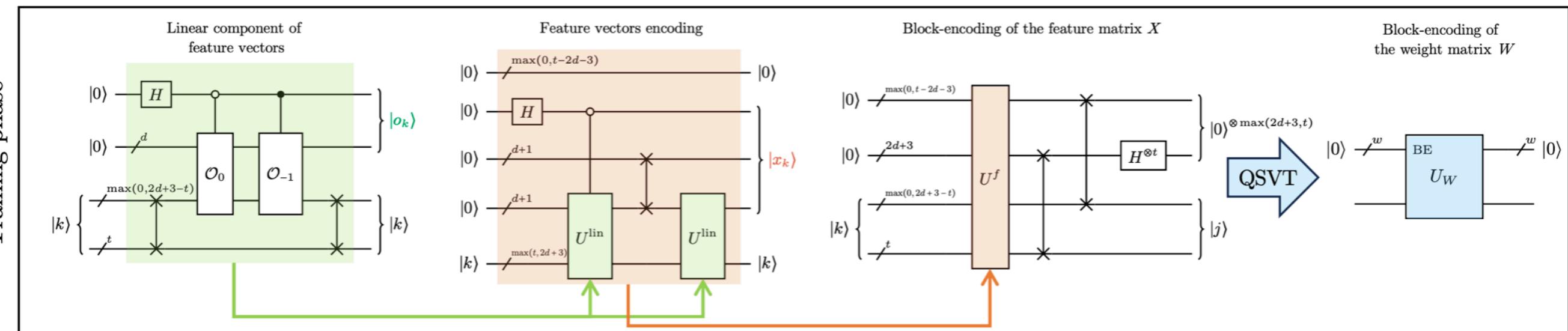


Skipping-ahead dynamics



Training

$$W = Y X^\dagger (X X^\dagger + \lambda I)^{-1}$$

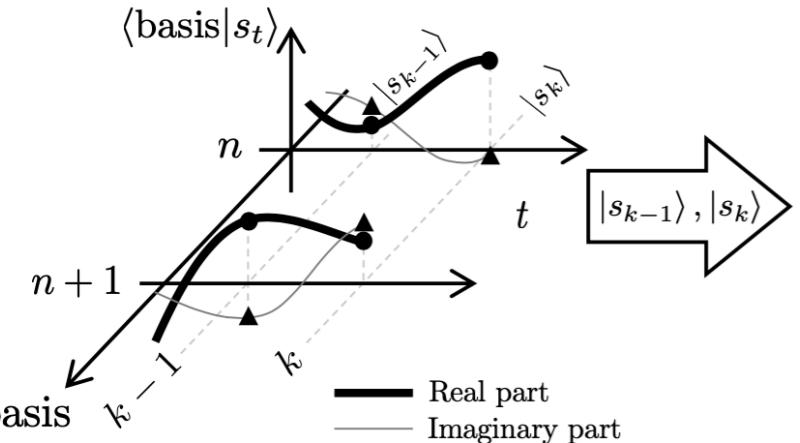


Theorem Given the block-encoded feature matrix X and target matrix Y , constructed in time T_O , and κ being a

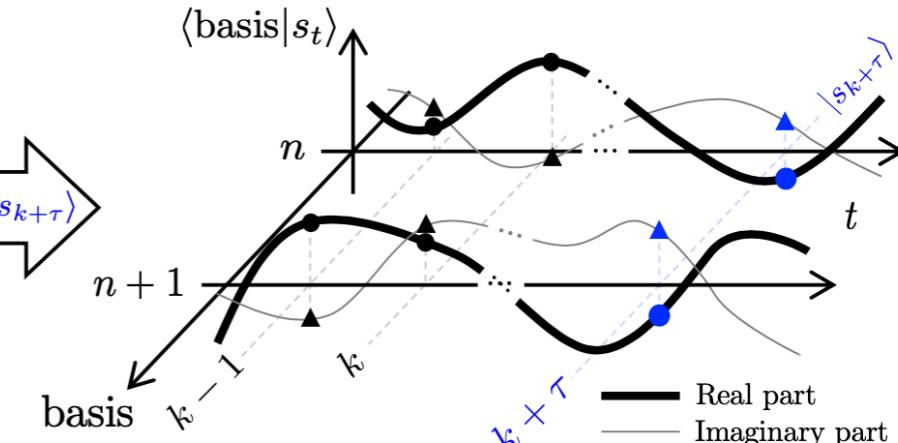
condition number of the Tikhonov-regularized feature matrix $\begin{pmatrix} X & \sqrt{\lambda}I \\ 0 & 0 \end{pmatrix}$, then the block-encoding of W , with error $\delta_W \in (0,1)$, can be constructed in time $T_W = O\left(\frac{d}{\delta_W} \kappa T \log\left(\frac{\kappa T}{\delta_W}\right) T_O\right)$ with $O(d)$ number of qubits.

Quantum Algorithm for NG-RC (QNG-RC)

Quantum dynamics

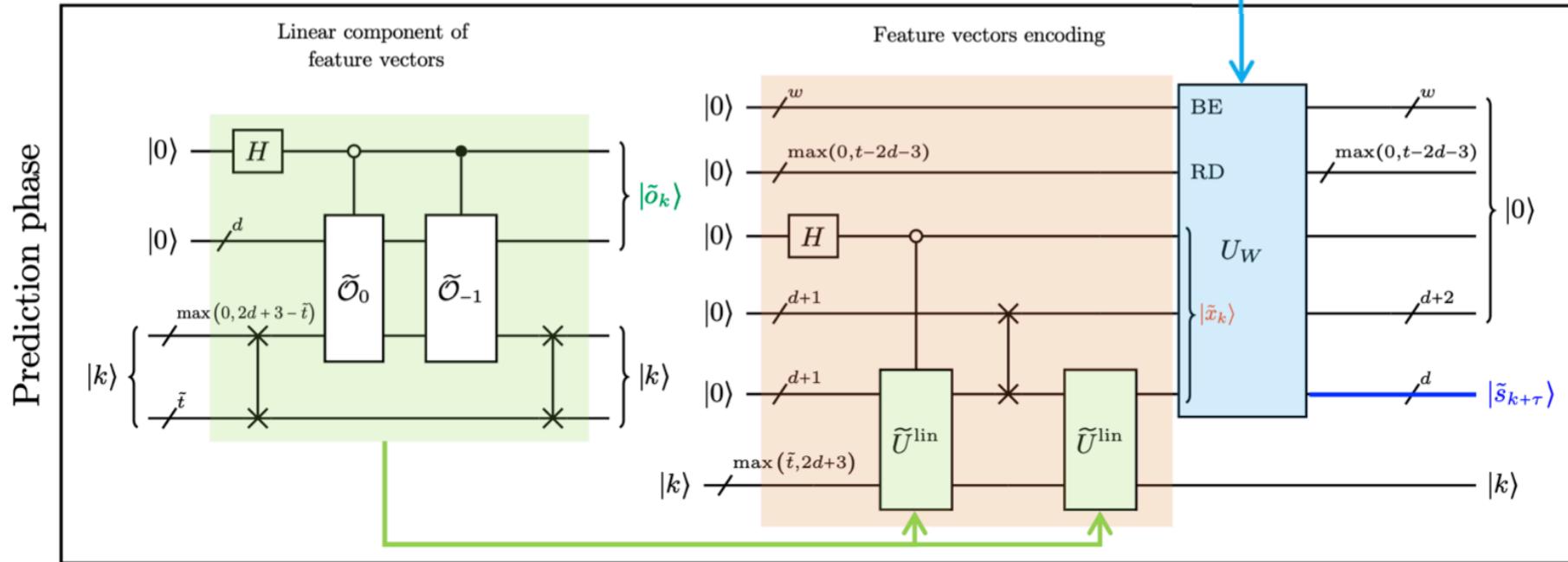
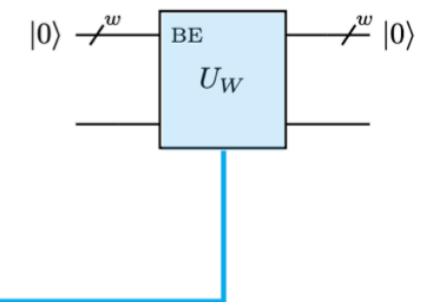


Skipping-ahead dynamics



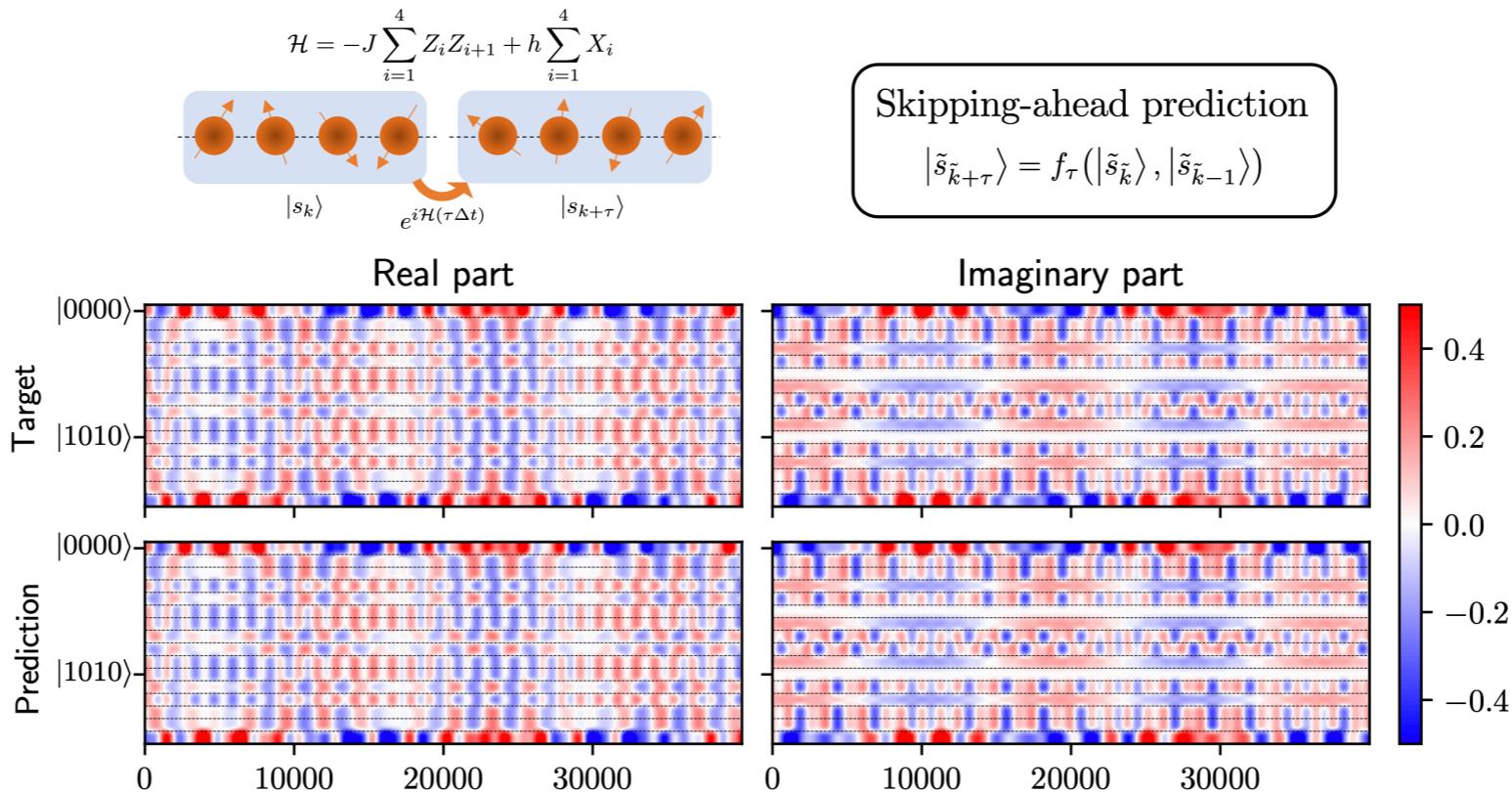
Skipping-ahead prediction

$$|s'_{k+\tau}\rangle = W|x_k\rangle = W\mathbf{r}(|s'_k\rangle, |s'_{k-1}\rangle)$$

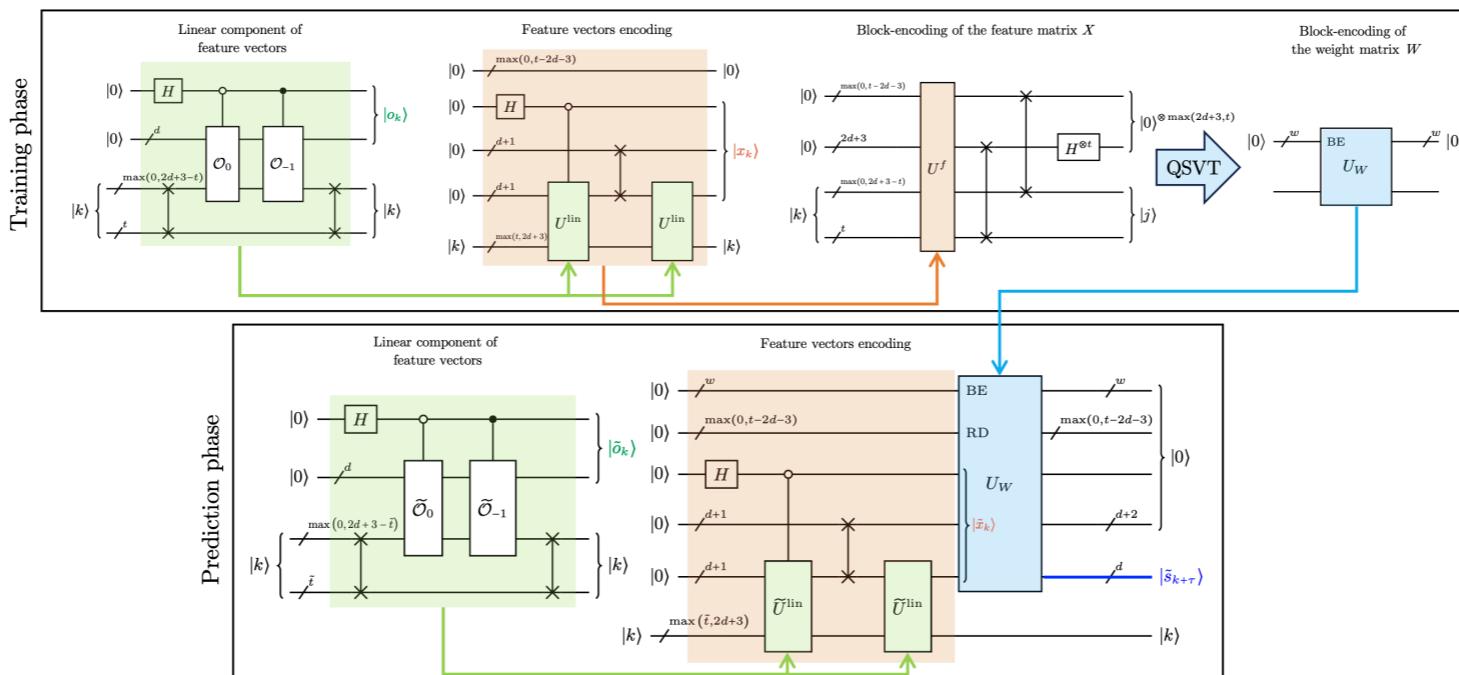


Summary

1. NG-RC can be applied to forecast *full* many-body dynamics far into the future, but with the time cost that scales as $O(2^{2d})$



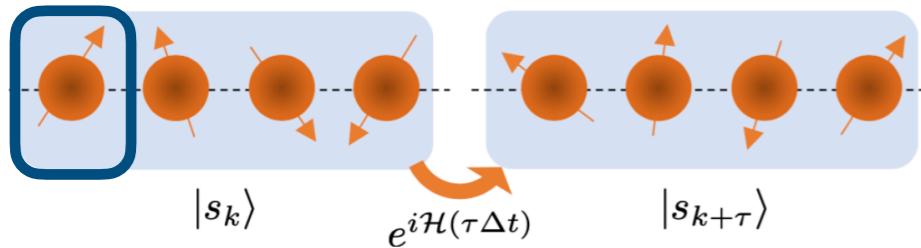
2. There is a quantum algorithm that performs skipping-ahead prediction coherently with the time cost and resource that scales as $O(d)$



Question Inspired by Experiments:

Can we measure one observable dynamics and reconstruct ALL the observables dynamics?

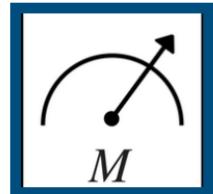
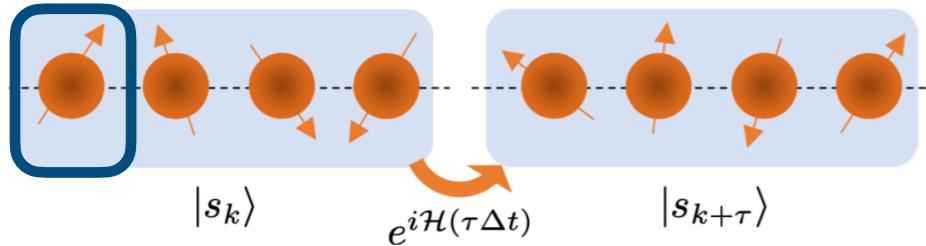
$$\mathcal{H} = -J \sum_{i=1}^4 Z_i Z_{i+1} + h \sum_{i=1}^4 X_i$$



Question Inspired by Experiments:

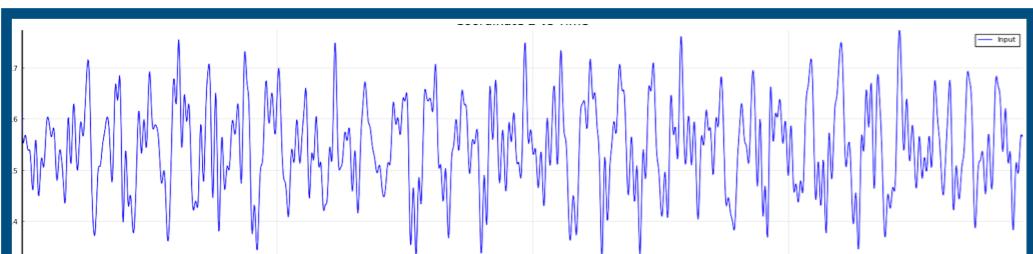
Can we measure one observable dynamics and reconstruct ALL the observables dynamics?

$$\mathcal{H} = -J \sum_{i=1}^4 Z_i Z_{i+1} + h \sum_{i=1}^4 X_i$$



Partial observation of the past

$\langle X_1 \rangle$

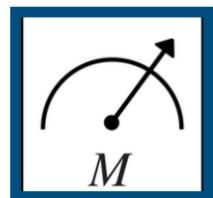
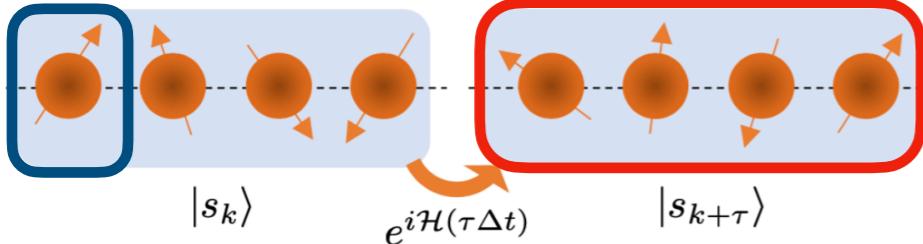


t

Question Inspired by Experiments:

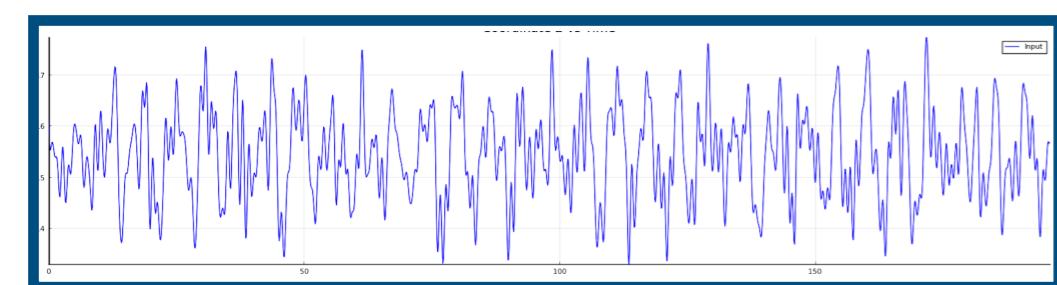
Can we measure one observable dynamics and reconstruct ALL the observables dynamics?

$$\mathcal{H} = -J \sum_{i=1}^4 Z_i Z_{i+1} + h \sum_{i=1}^4 X_i$$



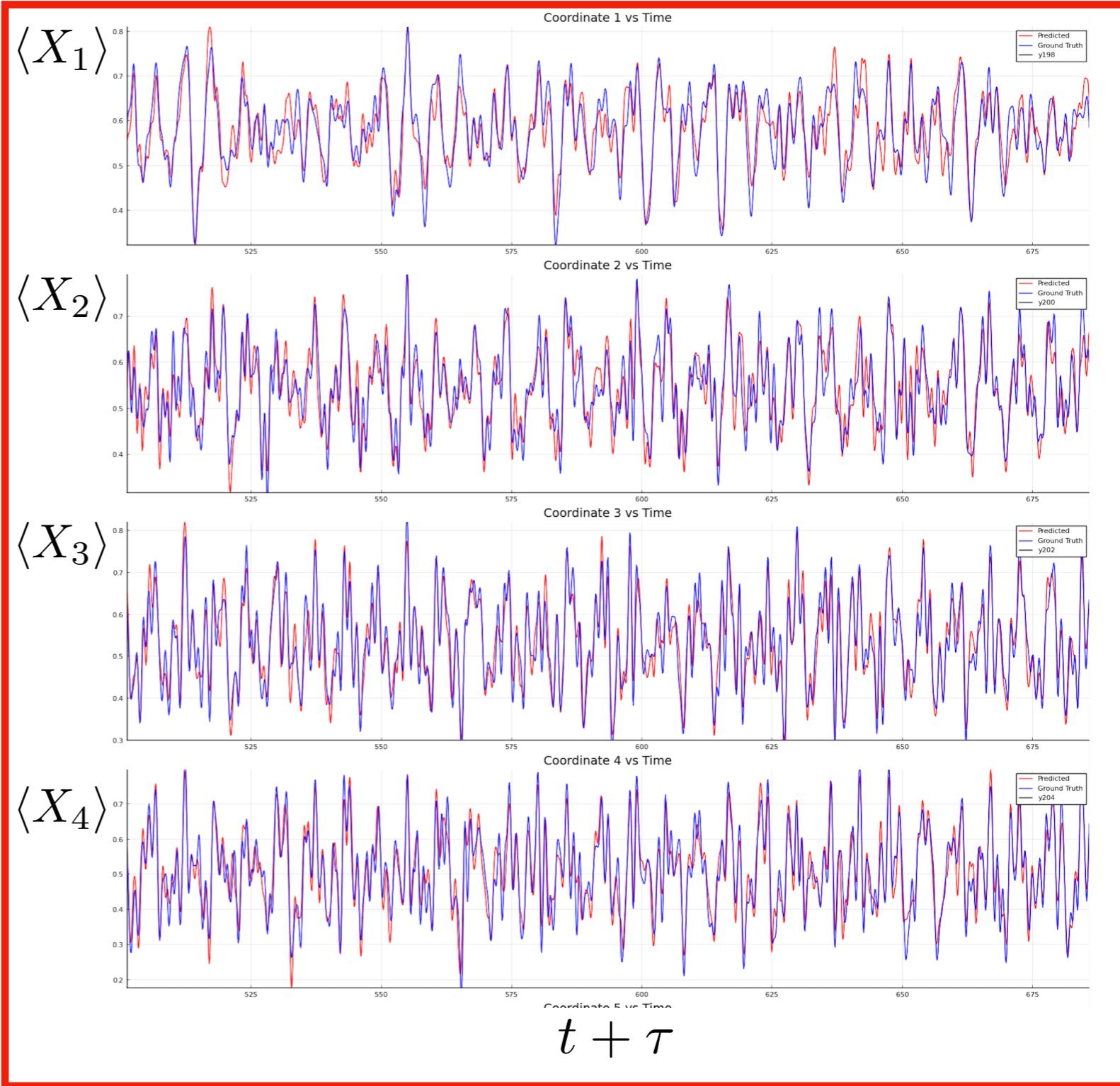
Partial observation of the past

$\langle X_1 \rangle$



t

Reconstruction of ALL observables into the far future ($\tau = 10^6$)



$t + \tau$

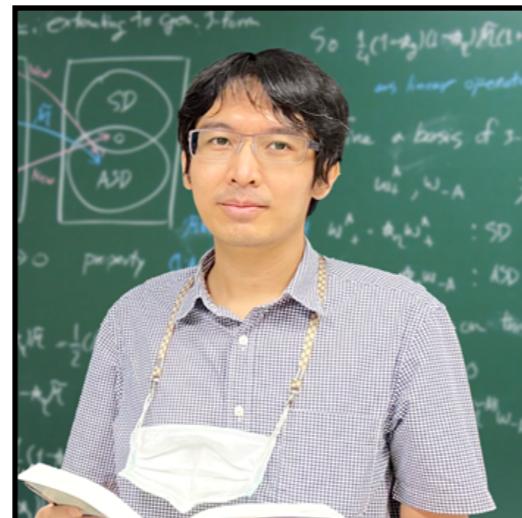
Acknowledgement

Apimuk Sornsaeng



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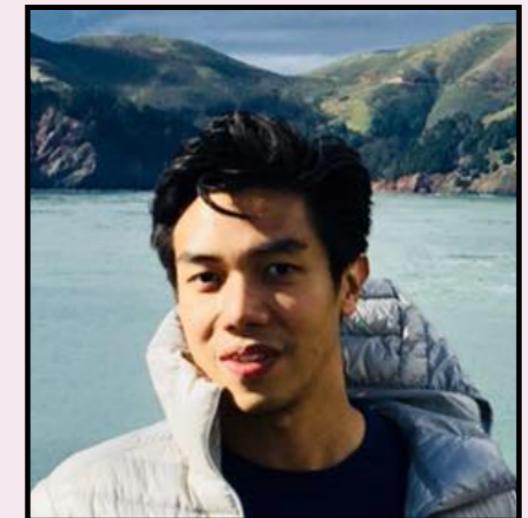
Ninnat Dangniam



Institute for Fundamental Study
Thailand

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Thailand

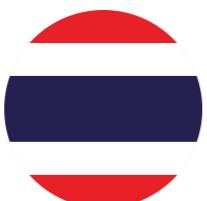


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Funding Acknowledgement



Lab website: www.chics.ai



Benefits of Matrix Product States: Exponential Data Compression

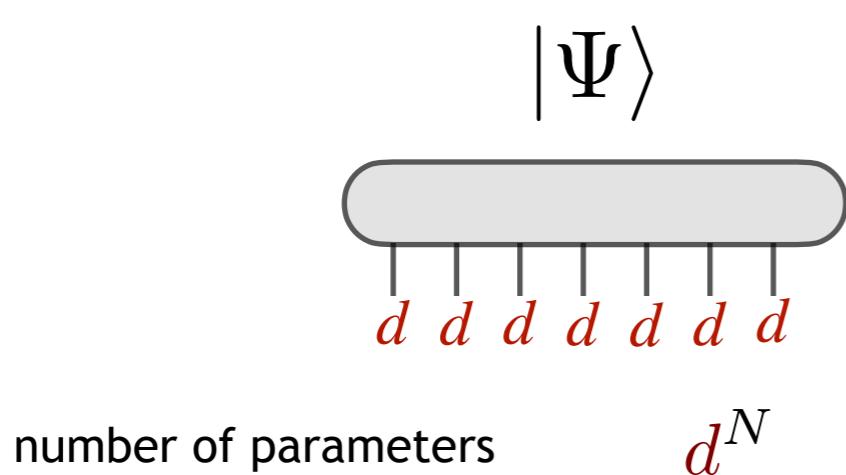
$$|\Psi\rangle = \sum_{d_1, d_2, \dots, d_N} c_{d_1, d_2, \dots, d_N} |d_1 \ d_2 \ \dots \ d_N\rangle$$

If the Hilbert space of each particle has dimension d , need to specify all d^N tensor coefficients.

However, for a gapped 1D systems, a useful ansatz is the [MPS](#)

$$|\tilde{\Psi}\rangle_{\text{MPS}} \approx \sum_{\{\alpha\}} A_{d_1}^{\alpha_1} \dots A_{d_i}^{\alpha_{i-1} \alpha_i} \dots A_{d_N}^{\alpha_{N-1}} |d_1\rangle |d_2\rangle \dots |d_N\rangle$$

α_i denotes the interaction with particle i with an effective dimension χ , called the *bond dimension*.



\approx

