

WIRELESS ATTACKS ON AIRCRAFTS



Presentation Agenda

1. Introduction
2. Signal Spoofing Attacks
3. Attacks Evaluation & Results
4. Conclusion

■ Author's Agenda

The authors wrote that "resilience of the aircraft landing systems to adversarial wireless attacks have not yet been studied in the open literature, despite their criticality and the increasing availability of low-cost software-defined radio (SDR) platforms."

So, the authors did— ***explore and show the vulnerability of aircraft instrument landing systems to wireless attacks.***

■ Key Technologies

ILS, Localizer, Glideslope, GPS, SDR, ILS spoofing, Overshadow attack, Single-tone attack, Air traffic controller

INTRODUCTION

Research Problems
ILS Subsystems, Signal generation
Landing course correction

Aircraft Wireless technologies

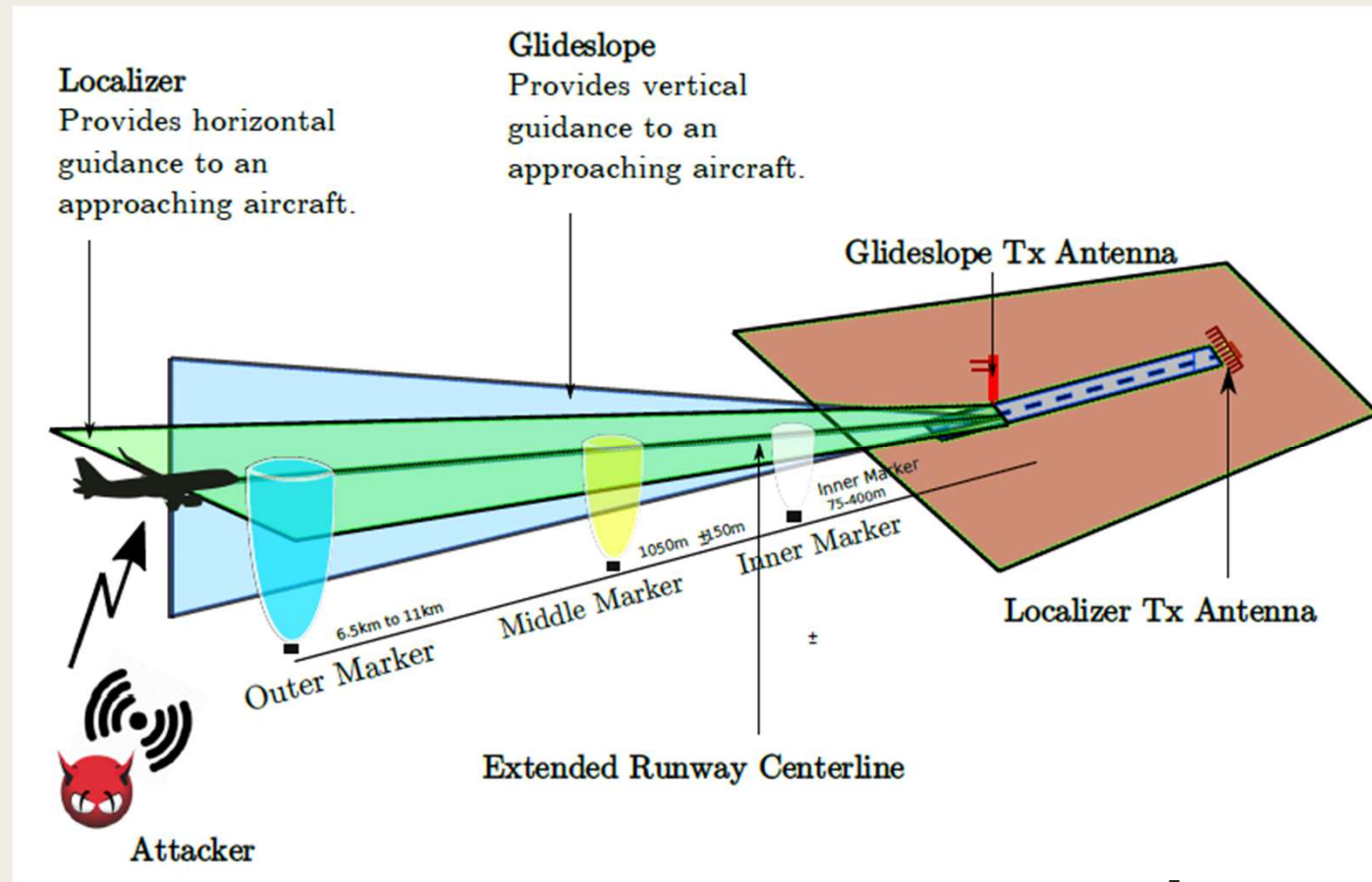
- ADS-B, TCAS, ACARS, GPS, ILS
 - *Localization, collision avoidance, addressing & reporting, Landing guidance*
- 59% of fatal accidents during landing (Boeing)

Research Problem

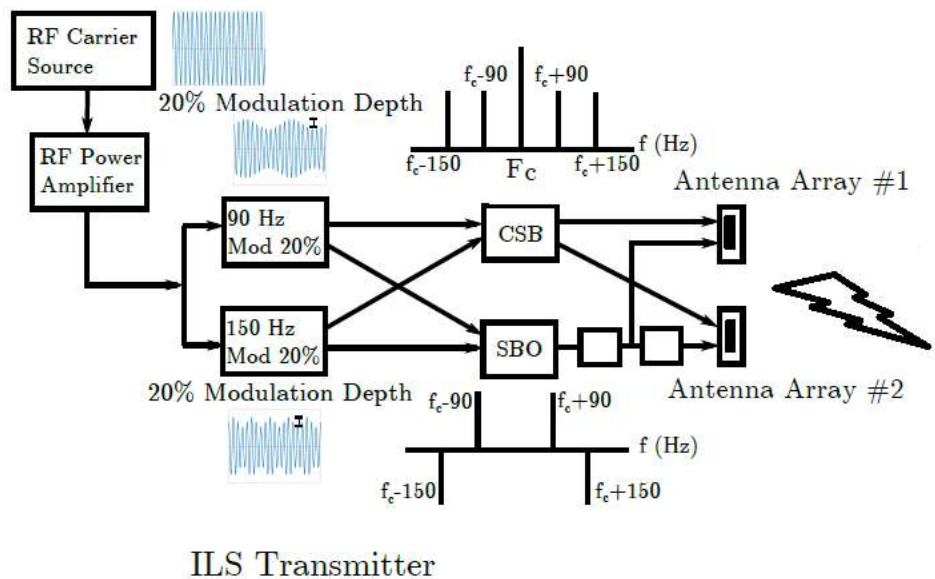
- How vulnerable are the landing technologies (ILS systems) to the wireless attacks?
- How feasible is to spoof the ILS radio signals using the SDR?
- How the potential attacks can be demonstrated and how they can be evaluated?

ILS Sub-systems

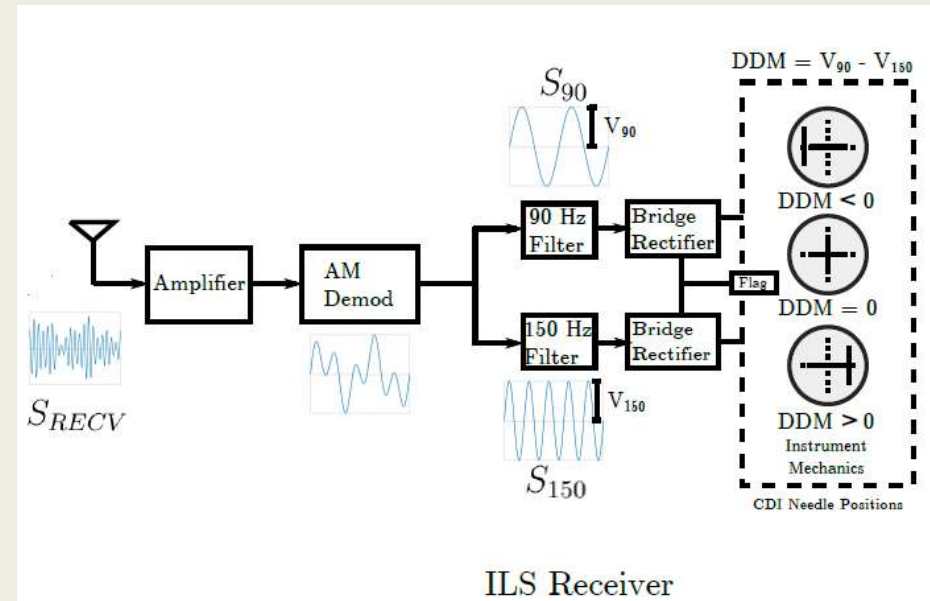
- Real-time guidance
- Localizer - Vertical
- Glideslope - Horizontal
- Beacons
- No encryption or auth
- 300 ILS related accidents
- 600\$ SDR attack method



ILS Signal Generation



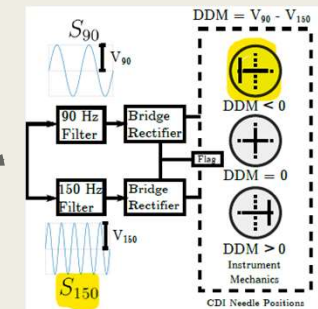
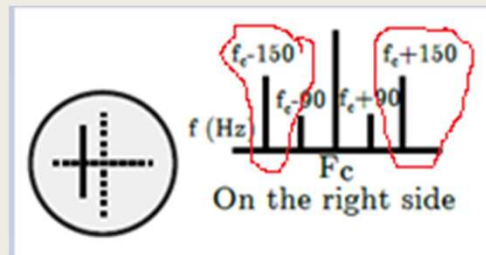
- **5 MESSAGES:** Center, Left, Right, Above, Below
- 150 Hz and 90 Hz signals
- Amplitude Modulation of 150 Hz & 90 Hz
- Generating the DDM



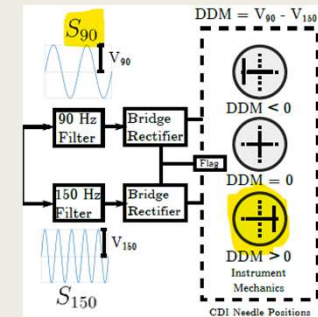
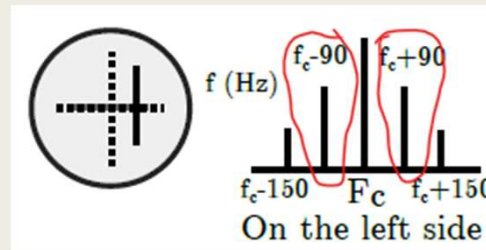
- DDM – Difference in Depth of Modulation
- Scenario's:
 - $DDM = 0$, Flight is on Runway (Center)
 - $DDM < 0$, Flight is on RIGHT of center (OR) above the glide path
 - $DDM > 0$, Flight is on LEFT of center (OR) below the glide path

How ILS guides course correction

- Flight is on RIGHT of Runway
150 Hz signal is made dominant;
it indicates the pilot to steer left

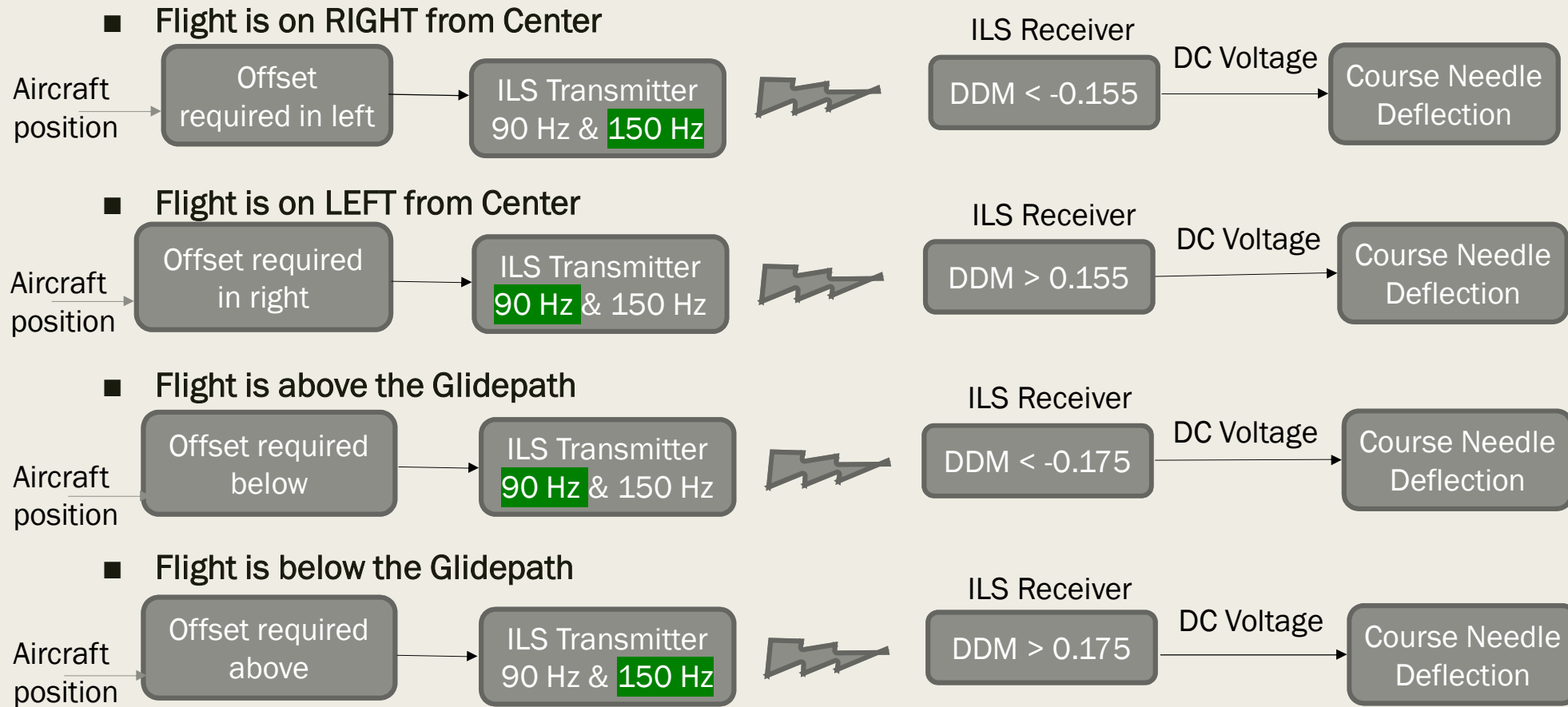


- Flight is on LEFT of Runway
90 Hz signal is made dominant;
it indicates the pilot to steer right.



- Flight is above the Glidepath
90 Hz signal is made dominant; it indicates the pilot to steer below.
- Flight is below the Glidepath
150 Hz signal is made dominant; it indicates the pilot to steer above.

How course correction maneuvers work



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SIGNAL SPOOFING ATTACKS

Attack Situation
Overshadow attack
Single-tone attack

Attack Situation

Aircraft in landing phase



- Pilot receives the landing clearance
- Pilot tunes to localizer/Glideslope freq
- Pilot verifies the runway identifier
- Chooses manual or auto-land feature

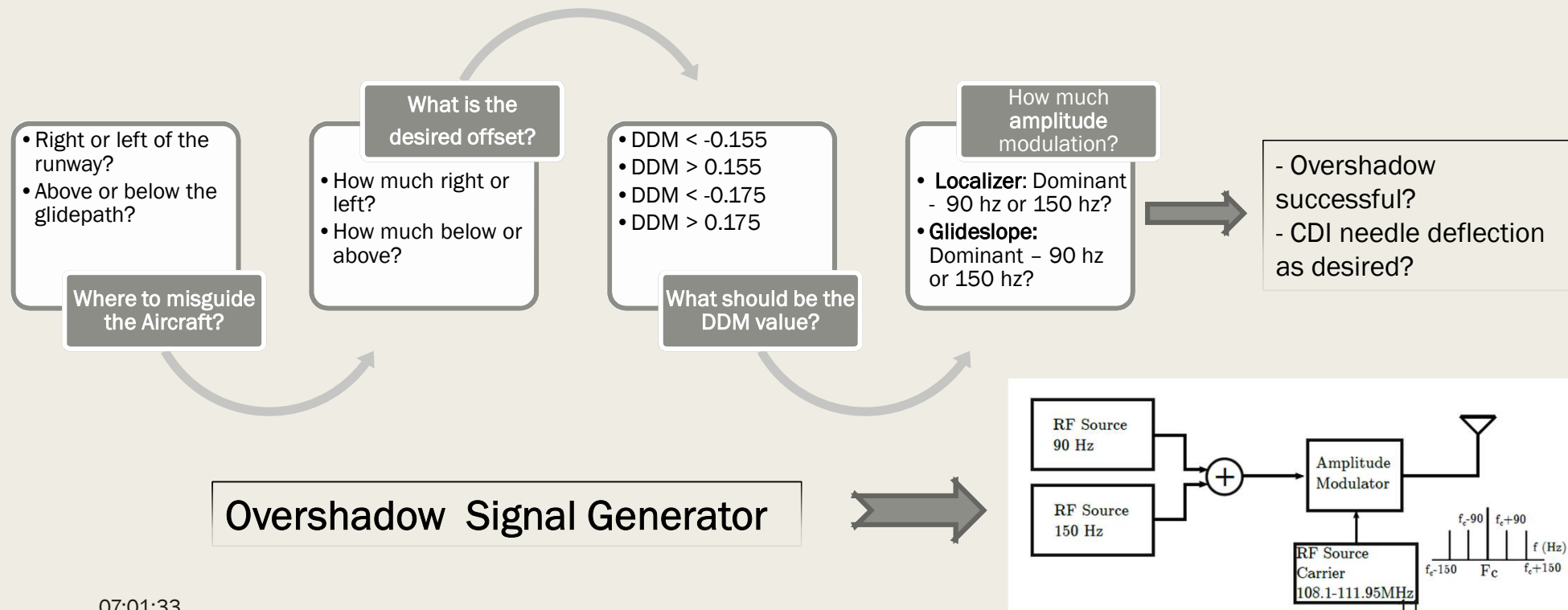
Attacker waiting to launch attack



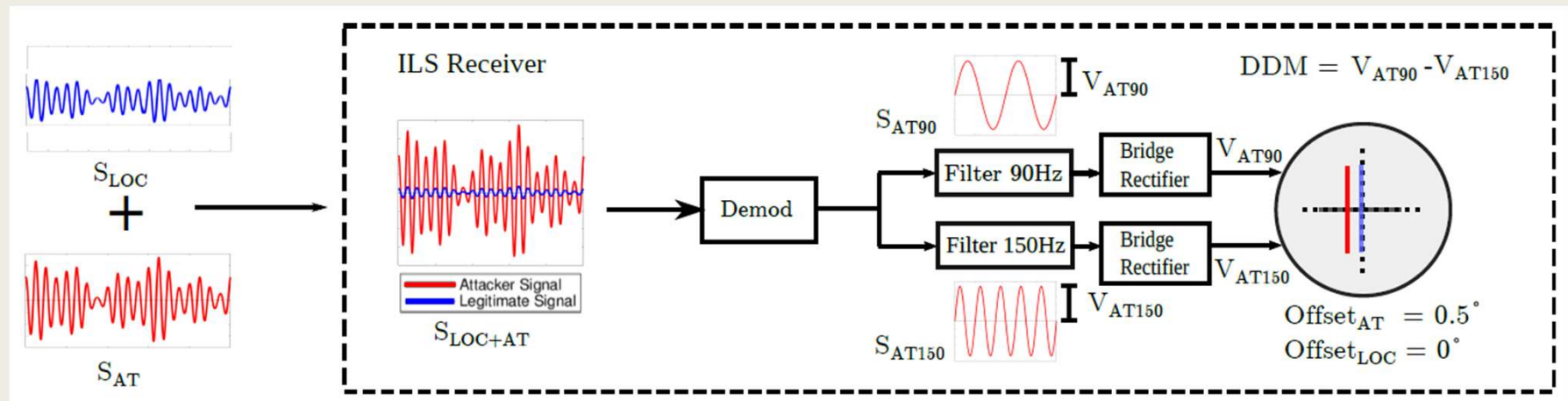
- Assumptions on attacker
 - *Expert in ILS signalling*
 - *Expert in using SDR*
 - *Location: Onboard or on ground*

How Overshadow attack works

- Overshadow the legitimate ILS signal by overpowering the ILS Tx signal.
- How does the attacker think?



Misguiding to Steer left

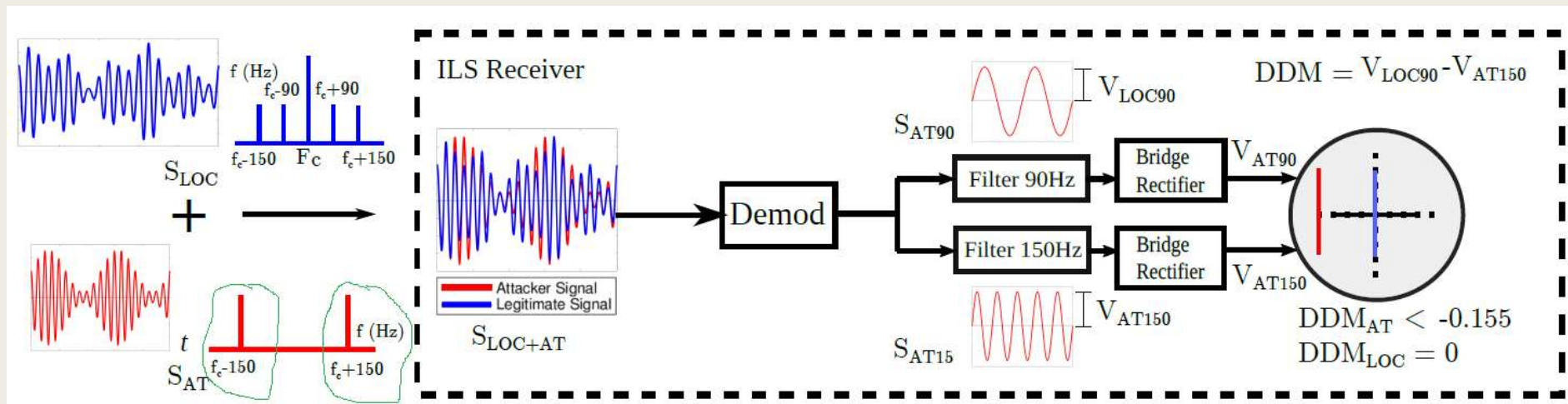


- Overshadow 'Precrafted' signal is sent as -> "Flight is on RIGHT from Center"

The attacker makes $Offset = 0.5^\circ$ and 150 Hz signal as dominant; it indicates the pilot to steer left.



How Single-tone attack is different?



- Single-tone 'Precrafted' signal is sent as -> "Flight is on RIGHT of Runway"

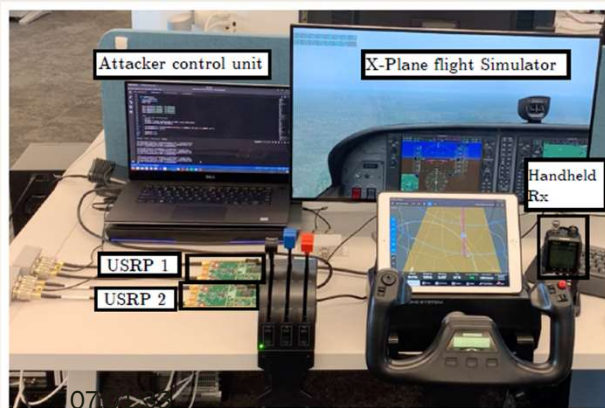
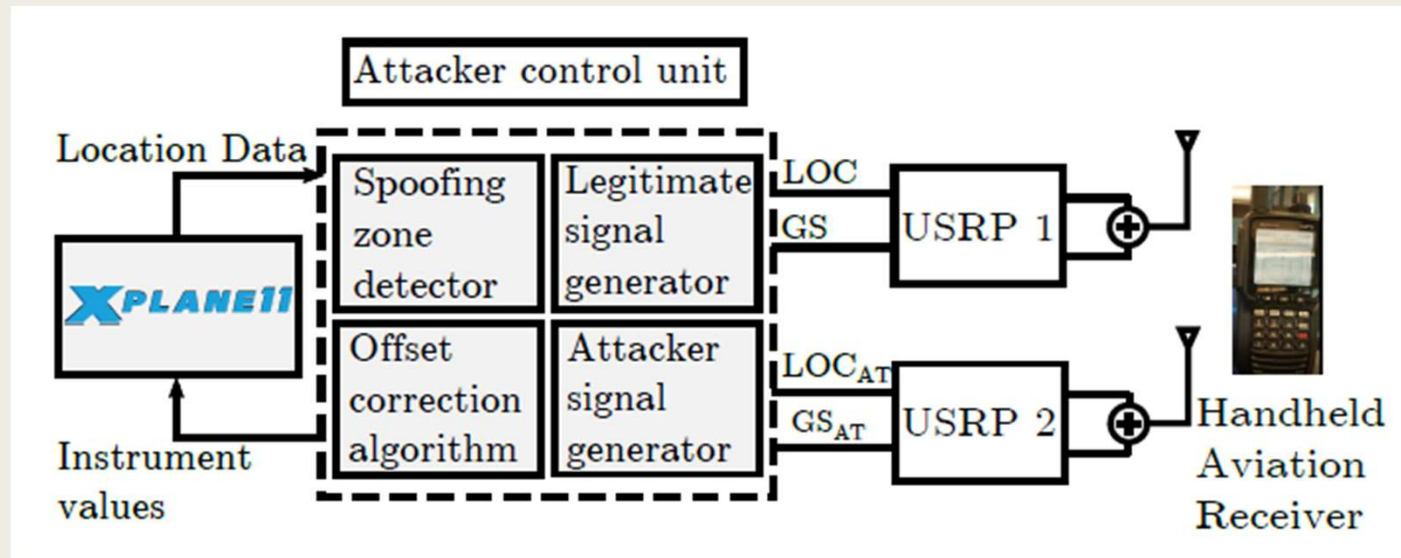
The attacker makes transmits ONLY the dominant 150 Hz signal;

It indicates the pilot to steer left.

ATTACKS EVALUATION & RESULTS

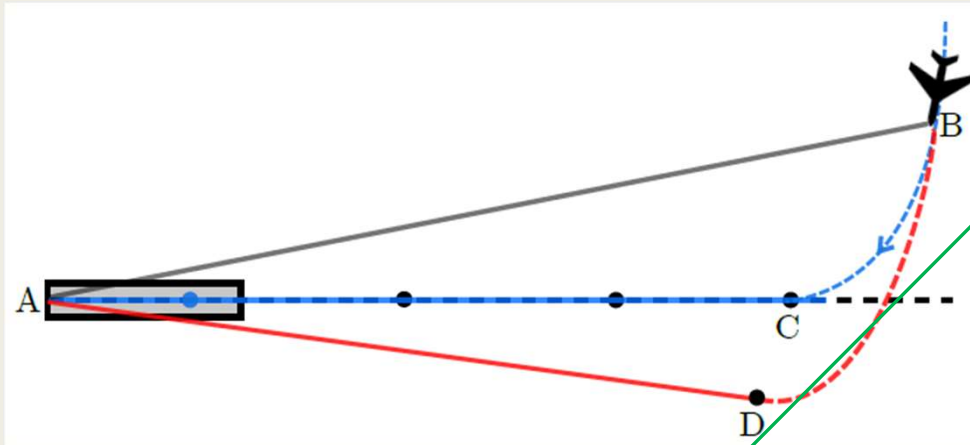
Experiment Setup
Results

Attack Experiment Setup



- Spoofing zone detection
 - Final approach patterns, even-odd algorithm
- Offset correction Algorithm
 - Aircraft location data (from ADS-B), real-time offsets

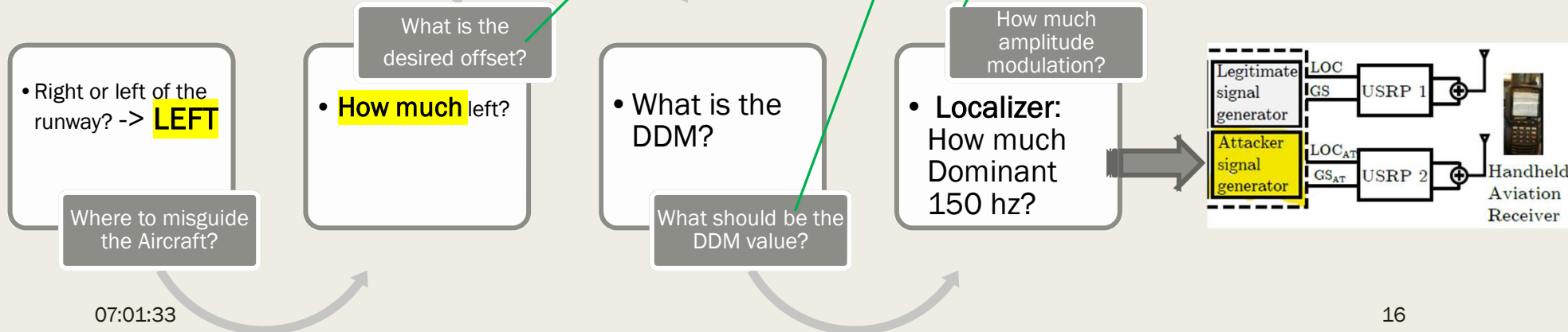
Attack Signal Generation



Algorithm 1 Offset correction algorithm.

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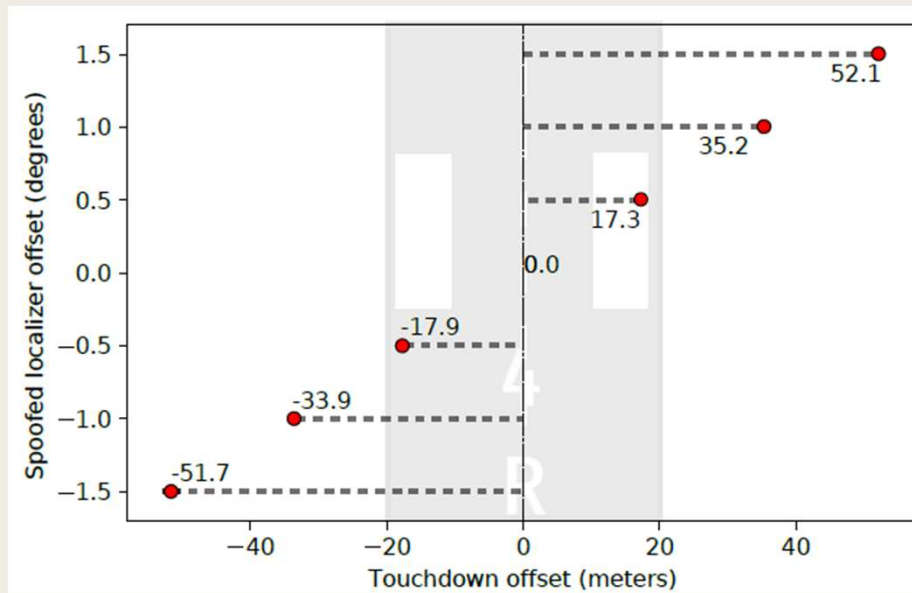
1: procedure GETANGLEDIFFERENCE
2:    $\angle DAC \leftarrow \text{TargetedLocalizerOffset}$ 
3:    $\angle BAC \leftarrow \text{GetAngle}(\text{location})$ 
4:    $\text{difference} \leftarrow \angle DAC - \angle BAC$ 
5:   return difference
6: procedure CALCULATEDDM
7:    $\text{difference} \leftarrow \text{GetAngleDifference}$ 
8:    $\text{ddm} \leftarrow (0.155 * \text{difference}) / 2.5$ 
9:    $\text{AT90} \leftarrow 0.2 + (\text{ddm}) / 2$ 
10:   $\text{AT150} \leftarrow 0.2 - (\text{ddm}) / 2$ 
11:  ChangeAmplitude(AT90, AT150)
  
```



Evaluation Results

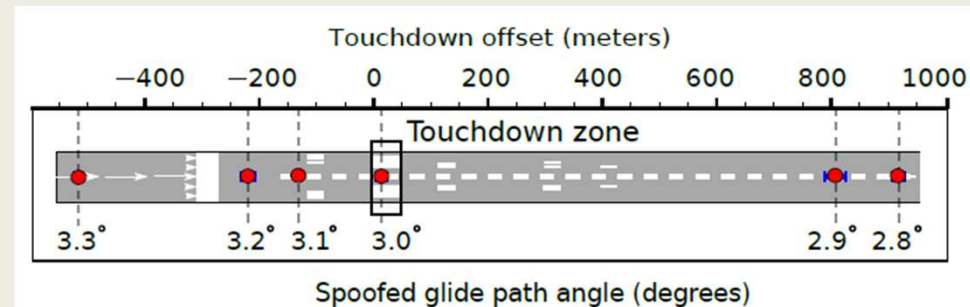
Horizontal Spoofing

- Localizer Offsets



Vertical Spoofing

- Glideslope Offsets



Horizontal Spoofing (Localizer) Offsets

- -0.5, -1.0, -1.5 (LEFT)
- 0.5, 1.0, 1.5 (RIGHT)

Vertical Spoofing (Glideslope) Offsets

- 2.8° to 3.3°

CONCLUSION

Security solutions
Further research

CONCLUSION

- ILS is vulnerable; GPS failsafe solutions do fail.
- ADS-B and other supporting technologies are also vulnerable
- Cryptographic solutions are not sufficient to prevent the localization attacks
- Widespread availability of powerful & low cost SDR platforms has increased the threats

FURTHER RESEARCH

- Wide-area secure localization system & secure proximity verification techniques
- GPS spoofing mitigation solutions & new systems for 'receiver' end
- GNSS based security
 - Septentrio AIM+ (*Advanced Interference Mitigation*)
 - *Commercial Authentication Service (CAS)*
 - *Chimera authentication system*

THANK YOU