



• Reward is negative: The objective reduces to

$$\max\left(\frac{\pi_{\theta}(a^{(t)} \mid s^{(t)})}{\pi_{\theta_{\text{old}}}(a^{(t)} \mid s^{(t)})}, (1 - \epsilon)\right) R^{(t)}$$

Then, the objective decreases with $\pi_{\theta}(a^{(t)} \mid s^{(t)})$. Once $\pi_{\theta}(a^{(t)} \mid s^{(t)}) < (1 - \epsilon)\pi_{\theta_{\text{old}}}(a^{(t)} \mid s^{(t)})$, the max kicks in, with a ceiling of $(1 - \epsilon)R^{(t)}$.

Search as an optimization problem

• Reward is positive: The objective reduces to

$$\min\left(\frac{\pi_{\theta}(a^{(t)} \mid s^{(t)})}{\pi_{\theta_{\text{old}}}(a^{(t)} \mid s^{(t)})}, (1+\epsilon)\right) R^{(t)}$$

Then, the objective increases with $\pi_{\theta}(a^{(t)} \mid s^{(t)})$. Once $\pi_{\theta}(a^{(t)} \mid s^{(t)}) > (1 + \epsilon)\pi_{\theta_{\text{old}}}(a^{(t)} \mid s^{(t)})$, the min kicks in, with a ceiling of $(1 + \epsilon)R^{(t)}$.

 $g(\epsilon, R^{(t)}) = \begin{cases} (1 + \epsilon)R^{(t)} & R^{(t)} \ge 0\\ (1 - \epsilon)R^{(t)} & R^{(t)} < 0 \end{cases}$

[OpenAI SpinningUp, Proximal Policy Optimization]

PPO-Clip as a Regularizer

• Reward is negative: The objective reduces to

$$\max\left(\frac{\pi_{\theta}(a^{(t)} \mid s^{(t)})}{\pi_{\theta_{\text{old}}}(a^{(t)} \mid s^{(t)})}, (1 - \epsilon)\right) R^{(t)}$$

Then, the objective decreases with $\pi_{\theta}(a^{(t)} \mid s^{(t)})$. Once $\pi_{\theta}(a^{(t)} \mid s^{(t)}) < (1 - \epsilon)\pi_{\theta_{\text{old}}}(a^{(t)} \mid s^{(t)})$, the max kicks in, with a ceiling of $(1 - \epsilon)R^{(t)}$.

• Reward is positive: The objective reduces to

$$\min\left(\frac{\pi_{\theta}(a^{(t)} \mid s^{(t)})}{\pi_{\theta_{\text{old}}}(a^{(t)} \mid s^{(t)})}, (1+\epsilon)\right) R^{(t)}$$

Then, the objective increases with $\pi_{\theta}(a^{(t)} | s^{(t)})$. Once $\pi_{\theta}(a^{(t)} | s^{(t)}) > (1 + \epsilon)\pi_{\theta_{\text{old}}}(a^{(t)} | s^{(t)})$, the min kicks in, with a ceiling of $(1 + \epsilon)R^{(t)}$.