

Gaussian mixture

assume to be
≈ Gaussian

by Thm 1²

**predictive semantic
posterior**

physical likelihood

Key idea: Construct a conditional probability distribution to estimate physical properties based on semantic segmentation, as in [Ewan, P., et al. (2022)]*, [Nguyen, T., et al. (2021)]

Updatemeasurmentswithsemantics

$$p(\psi \mid \mathcal{Z}, \alpha) = \sum_{i=1}^k p(z=i \mid \mathcal{Z}, \alpha) \cdot p(\psi \mid z=i)$$

$$= \sum_{i=1}^k \frac{\alpha_i}{\sum_{j=1}^k \alpha_j} \cdot \mathcal{N}(\mu_i, \sigma_i^2)$$

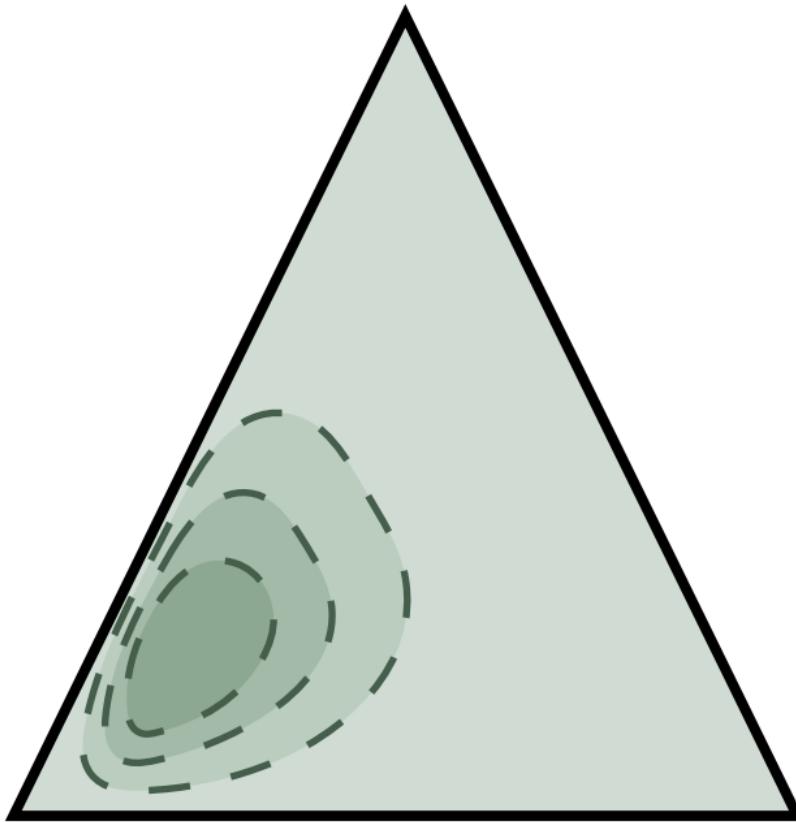
Physical estimation given semantic data

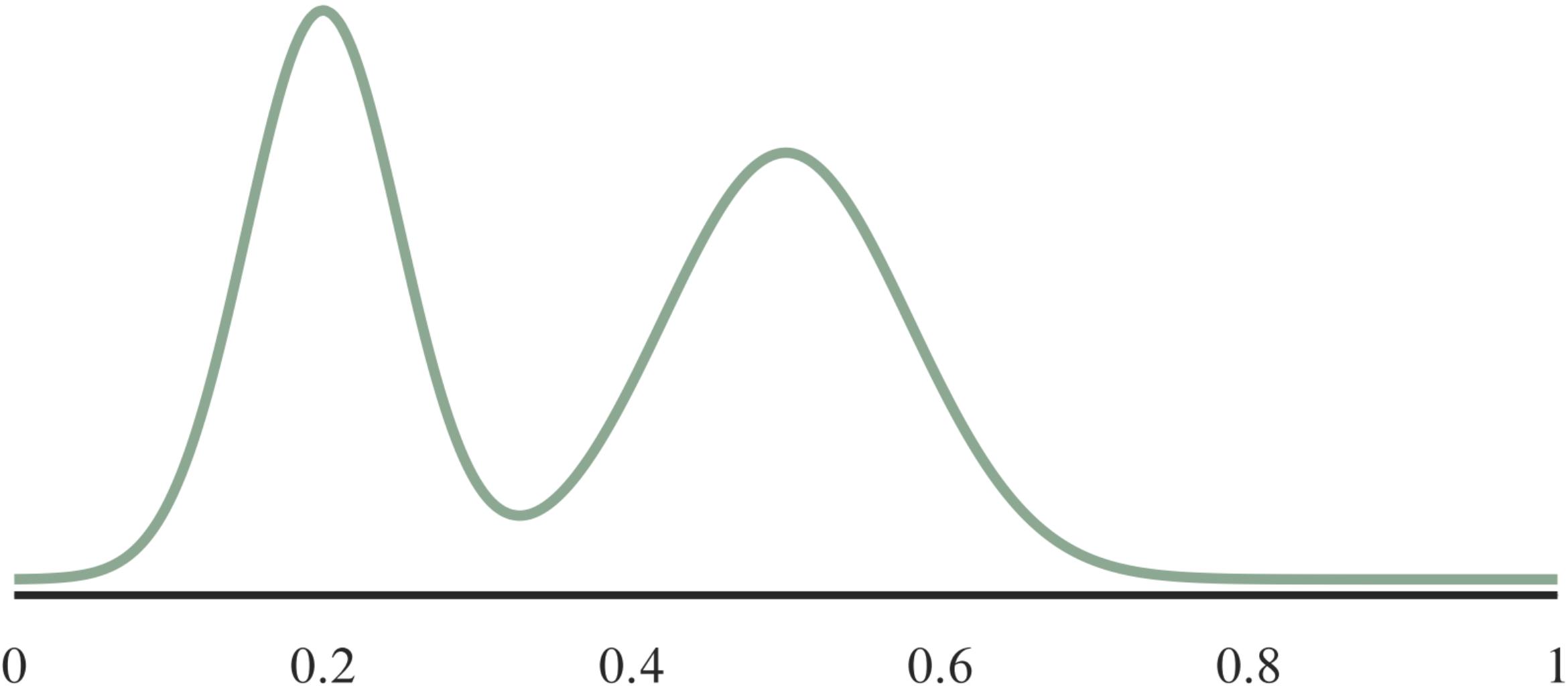
Z

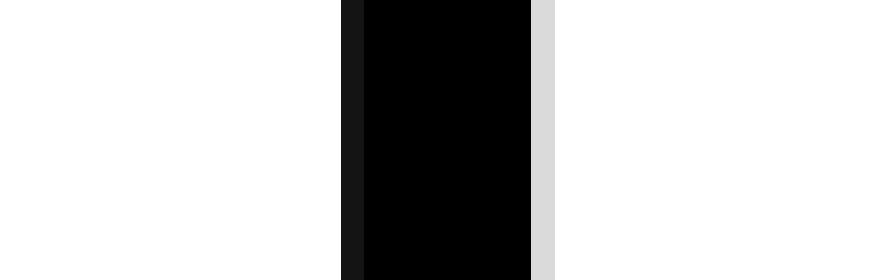
Snow

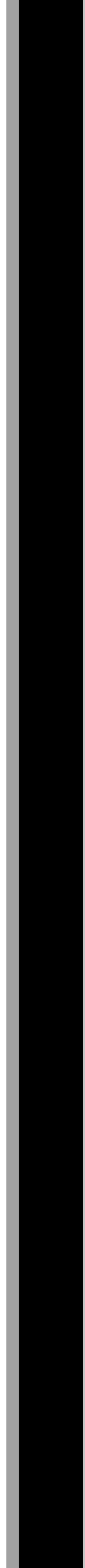
Ice

Dirt









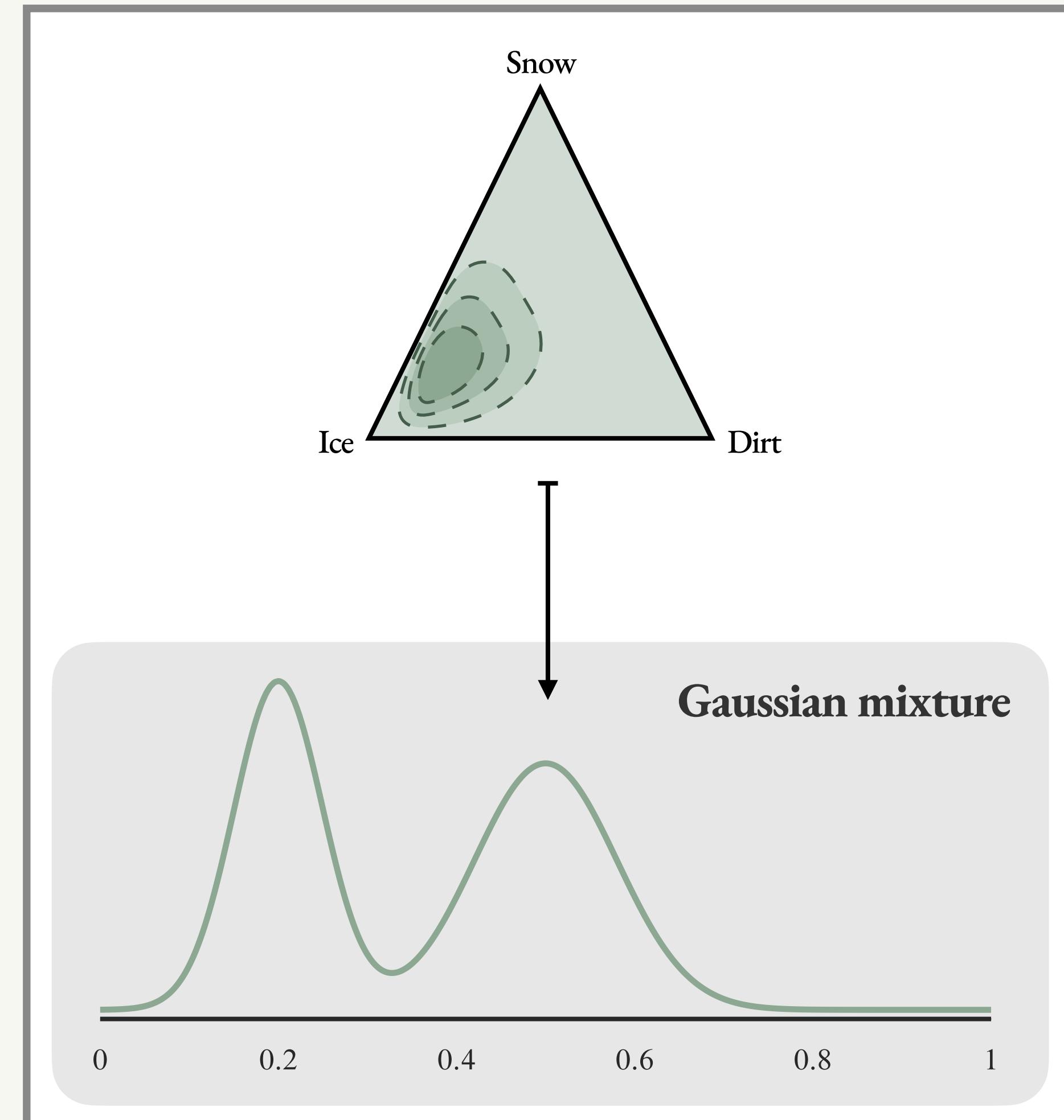
*parameters of the
Dirichlet prior*

[Tu, S. Inference] Multinomial and Dirichlet-Categorical models for Bayesian inference

Update measurements with semantics

Key idea: Construct a conditional probability distribution to estimate physical properties based on semantic segmentation, as in [Ewan, P., et al. (2022)]*, [Nguyen, T., et al. (2021)]

$$\begin{aligned}
 p(\psi \mid Z, \alpha) &= \sum_{i=1}^k p(z = i \mid Z, \alpha) \cdot p(\psi \mid z = i) \\
 &\quad \text{parameters of the Dirichlet prior} \\
 &\quad \text{predictive semantic posterior} \\
 &\quad \text{physical likelihood} \\
 \text{Physical estimation given semantic data } Z &= \sum_{i=1}^k \frac{\alpha_i}{\sum_{j=1}^k \alpha_j} \cdot \mathcal{N}(\mu_i, \sigma_i^2) \\
 &\quad \text{assume to be } \approx \text{Gaussian} \\
 &\quad \text{by Thm 12}
 \end{aligned}$$



Physical conjugate(?) prior