# Regression

CISC 7026: Introduction to Deep Learning

University of Macau

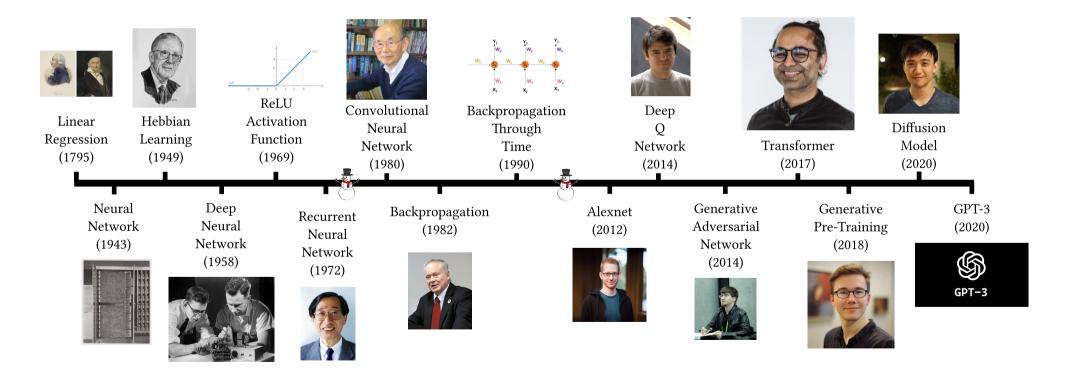
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Let us start with regression

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 $Available\ for\ free\ at\ https://www.who.int/data/gho/data/themes/mortality-and-global-health-estimates/ghe-life-expectancy-and-healthy-life-expectancy$ 

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We can use this data to make future predictions

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- The causal effects of education on health outcomes in the UK Biobank. Davies et al Nature Human Behaviour
- By staying in school, you are likely to live longer

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**Goal:** Given someone's education, predict how long they will live

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Lecture 1: Introduction

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Soon, f will be a deep neural network

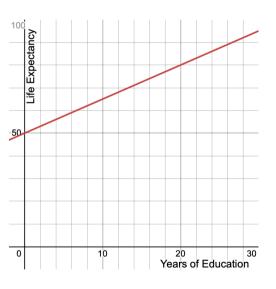
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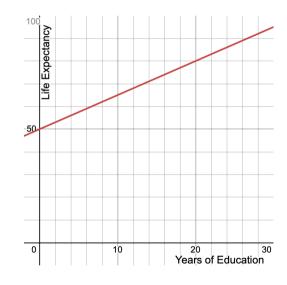
$$f(x, \boldsymbol{\theta}) = f\left(x, \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}\right) = \theta_1 x + \theta_0$$



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Now, we need to find the parameters  $m{ heta} = egin{bmatrix} heta_1 \\ heta_0 \end{bmatrix}$  that makes  $f(x, m{ heta}) = y$ 

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**Question:** How do we find  $\theta$ ? (Hint: We want  $f(x, \theta) = y$ )

**Answer:** We will minimize the **loss** (error) between  $f(x, \theta)$  and y, for all

$$x \in X, y \in Y$$

We compute the loss using the **loss function**  $\mathcal{L}: X \times Y \times \Theta \mapsto \mathbb{R}$ 

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$$\operatorname{error}(y, \hat{y}) = (y - \hat{y})^2$$

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Lecture 1: Introduction

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$$\operatorname{error}(f(x, \boldsymbol{\theta}), y) = (f(x, \boldsymbol{\theta}) - y)^2$$

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Square for minimization

We can write the loss function for a single datapoint  $x_i, y_i$  as

$$\mathcal{L}(x_i, y_i, \boldsymbol{\theta}) = \text{error}(f(x_i, \boldsymbol{\theta}), y_i) = \left(f(x_i, \boldsymbol{\theta}) - y_i\right)^2$$

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**Answer:** We only consider a single datapoint! We want to learn  $\boldsymbol{\theta}$  for the entire dataset

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For the entire dataset:

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Minimizing this loss function will give us the optimal parameters!

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**Answer:** For now, magic! We need more knowledge before we can derive this.

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$$m{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix}$$

We add the column of ones so that we can multiply  $X_D^ op$  with heta to get a linear function  $\theta_1 x + \theta_0$  evaluated at each data point

$$m{X}_Dm{ heta} = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix} egin{bmatrix} heta_1 \ heta_0 \ heta_1 \end{bmatrix} = egin{bmatrix} heta_1x_1 + heta_0 \ heta_1x_2 + heta_0 \ dots \ heta_1x_n + heta_0 \end{bmatrix}$$

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and our parameters  $\theta$ ,

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We can find the parameters that minimize  $\mathcal{L}$ 

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You will be doing this in your first assignment!

Tips for assignment 1

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def f(theta, design):
  # Linear function
  return design @ theta
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Not all matrices can be inverted! Ensure the matrices are square and the condition number is low

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A.shape
cond = jax.numpy.linalg.cond(A)
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Everything you need is in the lecture notes

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# Relax

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Plot the datapoints  $(x_1, y_1), (x_2, y_2), \dots$ 

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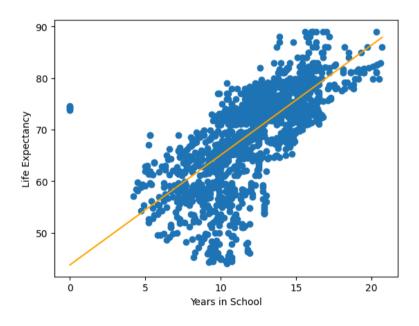
Plot the datapoints  $(x_1, y_1), (x_2, y_2), \dots$ 

Plot the curve  $f(x, \theta) = \theta_1 x + \theta_0$ ;  $x \in [0, 25]$ 

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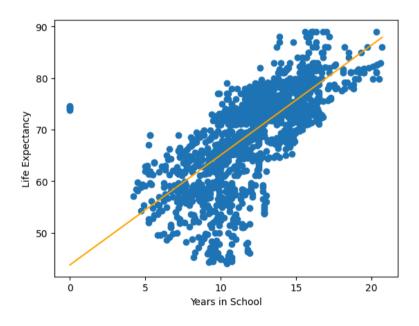
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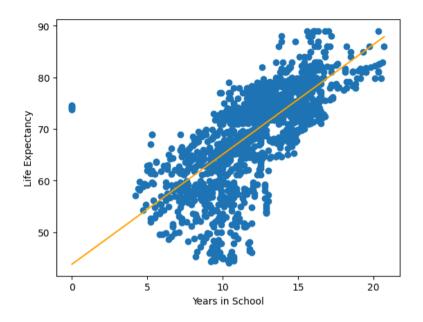


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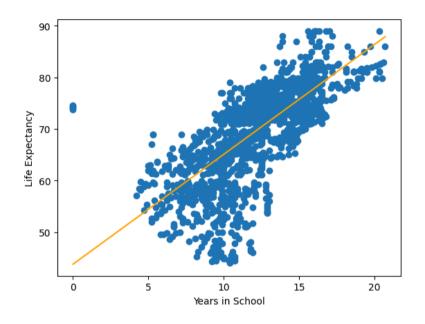
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We figured out linear regression!



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But can we do better?

1. Beyond linear functions

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- 2. Overfitting

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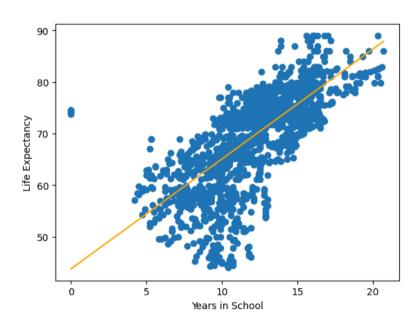
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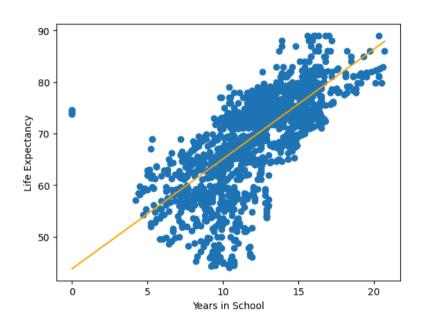
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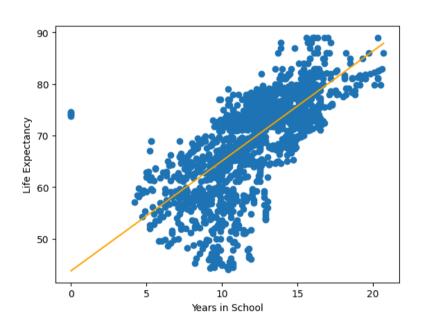
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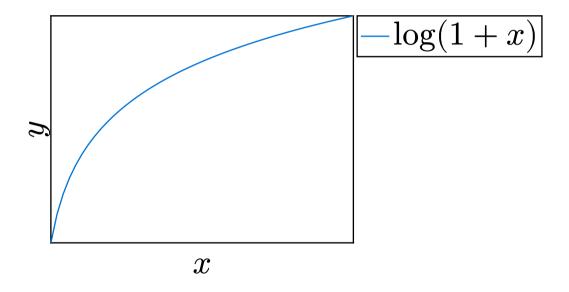
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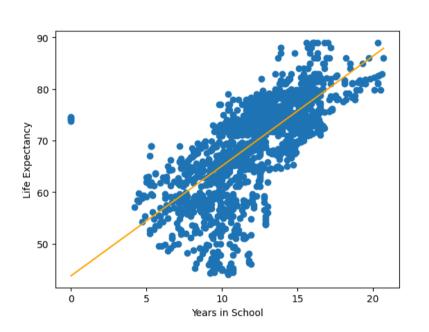


# Or maybe more logarithmic?

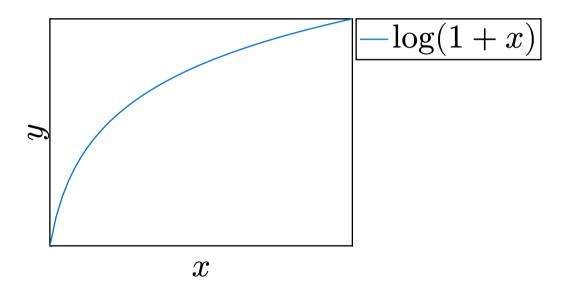


### **Question:**

Does the data look linear?



Or maybe more logarithmic?



However, linear regression must be linear!

**Answer:** The function  $f(x, \theta)$  is a linear function of x

Lecture 1: Introduction

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**Trick:** Change of variables to make f nonlinear:  $x_{\text{new}} = \log(1 + x_{\text{data}})$ 

Lecture 1: Introduction

**Answer:** The function  $f(x,\theta)$  is a linear function of x

**Trick:** Change of variables to make f nonlinear:  $x_{\text{new}} = \log(1 + x_{\text{data}})$ 

$$egin{aligned} oldsymbol{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix} \Rightarrow oldsymbol{X}_D = egin{bmatrix} \log(1+x_1) & 1 \ \log(1+x_2) & 1 \ dots & dots \ \log(1+x_n) & 1 \end{bmatrix} \end{aligned}$$

Now, f is a linear function of log(1+x) – a nonlinear function of x!

New design matrix...

$$\boldsymbol{X}_{D} = \begin{bmatrix} \log(1 + x_{1}) & 1 \\ \log(1 + x_{2}) & 1 \\ \vdots & \vdots \\ \log(1 + x_{n}) & 1 \end{bmatrix}$$

New function...

$$f\left(x, \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}\right) = \theta_1 \log(1+x) + \theta_0$$

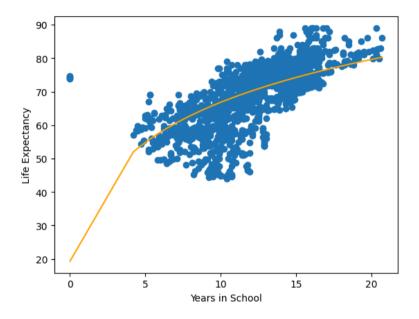
New design matrix...

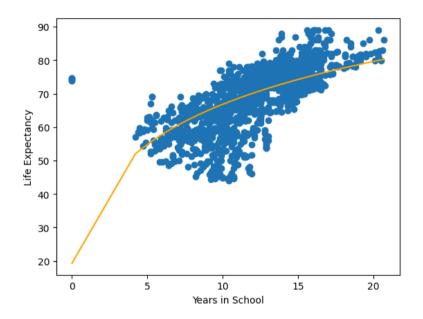
$$\boldsymbol{X}_D = \begin{bmatrix} \log(1+x_1) & 1 \\ \log(1+x_2) & 1 \\ \vdots & \vdots \\ \log(1+x_n) & 1 \end{bmatrix}$$

New function...

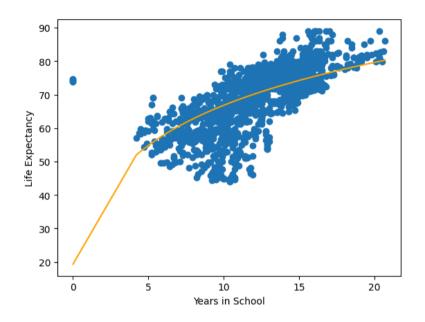
Same solution...

$$f\!\left(x, \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}\right) = \theta_1 \log(1+x) + \theta_0 \qquad \qquad \boldsymbol{\theta} = \left(\boldsymbol{X}_D^\top \boldsymbol{X}_D\right)^{-1} \boldsymbol{X}_D^\top \boldsymbol{y}$$





Better, but still not perfect



Better, but still not perfect Can we do even better?

$$f(x) = ax^n + bx^{n-1} + \dots + cx + d$$

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Polynomials can approximate **any** function (universal function approximator)

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Can we extend linear regression to polynomials?

Expand x to a multi-dimensional input space...

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$$m{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix} \Rightarrow m{X}_D = egin{bmatrix} x_1^n & x_1^{n-1} & \dots & x_1 & 1 \ x_2^n & x_2^{n-1} & \dots & x_2 & 1 \ dots & dots & \ddots & \ x_n & x_n^{n-1} & \dots & x_n & 1 \end{bmatrix}$$

And add some new parameters...

$$\boldsymbol{\theta} = \begin{bmatrix} \theta_1 & \theta_0 \end{bmatrix}^\top \Rightarrow \boldsymbol{\theta} = \begin{bmatrix} \theta_n & \theta_{n-1} & \dots & \theta_1 & \theta_0 \end{bmatrix}^\top$$

$$\boldsymbol{X}_{D}\boldsymbol{\theta} = \begin{bmatrix} x_{1}^{n} & x_{1}^{n-1} & \dots & x_{1} & 1 \\ x_{2}^{n} & x_{2}^{n-1} & \dots & x_{2} & 1 \\ \vdots & \vdots & \ddots & & \vdots \\ x_{n} & x_{n}^{n-1} & \dots & x_{n} & 1 \end{bmatrix} \begin{bmatrix} \theta_{n} \\ \theta_{n-1} \\ \vdots \\ \theta_{0} \end{bmatrix} = \begin{bmatrix} \theta_{n}x_{1}^{n} + \theta_{n-1}x_{1}^{n-1} + \dots + \theta_{0} \\ \theta_{n}x_{2} + \theta_{n-1}x_{2}^{n-1} + \dots + \theta_{0} \\ \vdots \\ \theta_{n}x_{n}^{n} + \theta_{n-1}x_{n}^{n-1} + \dots + \theta_{0} \end{bmatrix}$$

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New function...

$$f(x, \theta) = \theta_n x^n + \theta_{n-1} x^{n-1}, ..., \theta_1 + x^1 + \theta_0$$

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New function...

$$f(x, \theta) = \theta_n x^n + \theta_{n-1} x^{n-1}, ..., \theta_1 + x^1 + \theta_0$$

Same solution...

$$oldsymbol{ heta} = ig(oldsymbol{X}_D^ op oldsymbol{X}_D^ opig)^{-1} oldsymbol{X}_D^ op oldsymbol{y}$$

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**Summary:** By changing the input space, we can fit a polynomial to the data using a linear fit!

- 1. Beyond linear functions
- 2. Overfitting
- 3. Outliers
- 4. Regularization

Lecture 1: Introduction

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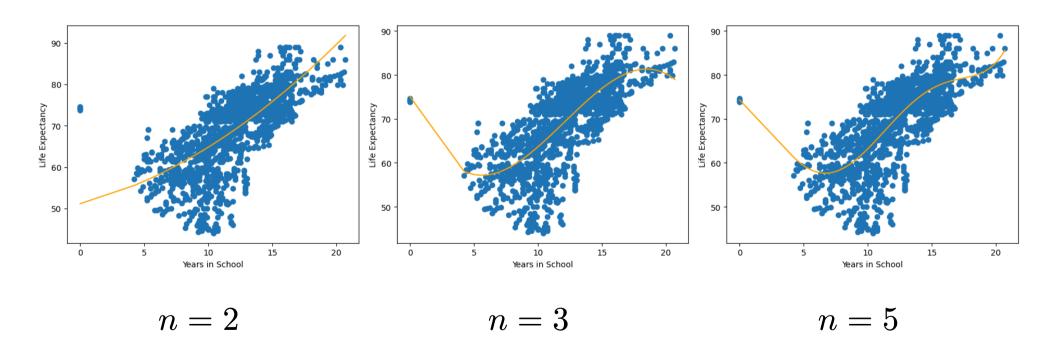
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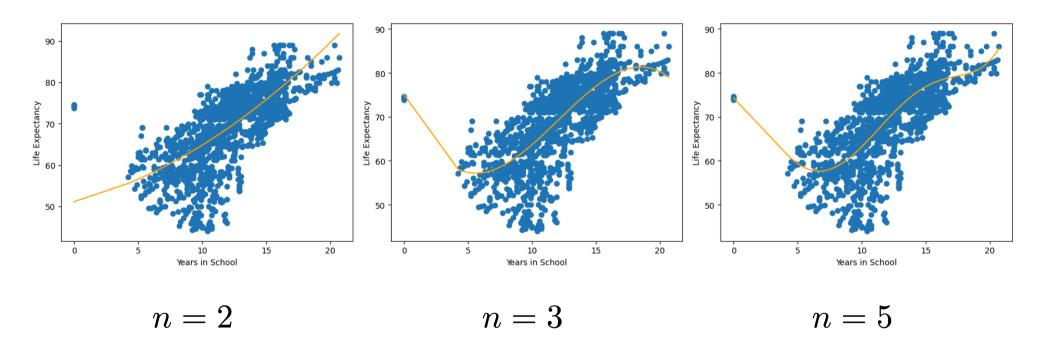
How do we choose n (polynomial order) that provides the best fit?

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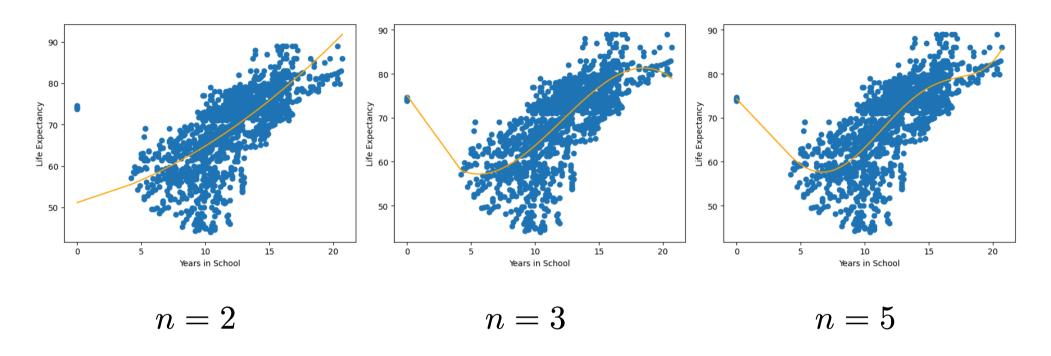


# How do we choose n (polynomial order) that provides the best fit?

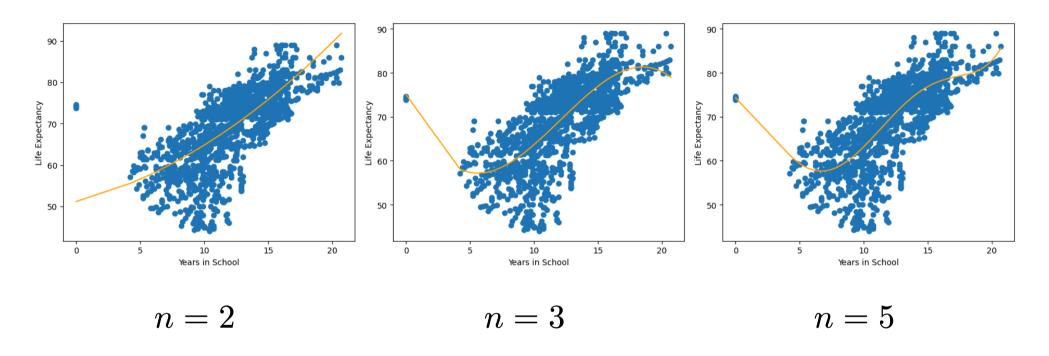


Pick the n with the smallest loss

$$\operatorname*{arg\ min}_{\boldsymbol{\theta},n} \mathcal{L}(\boldsymbol{x},\boldsymbol{y},(\boldsymbol{\theta},n))$$

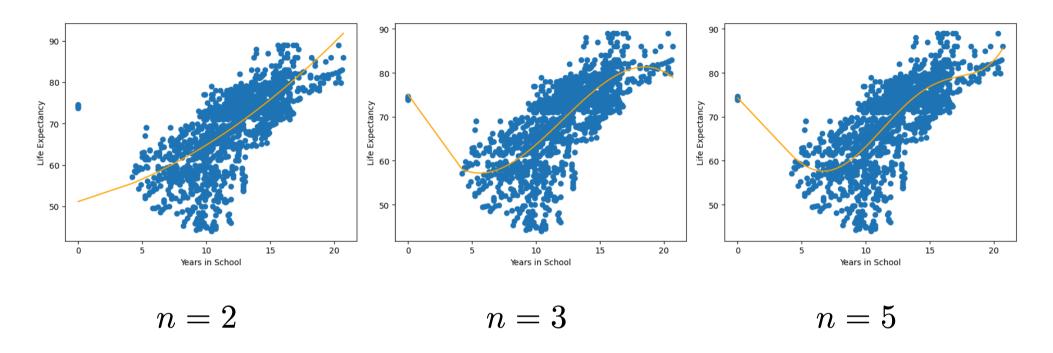


**Question:** Which n do you think has the smallest loss?

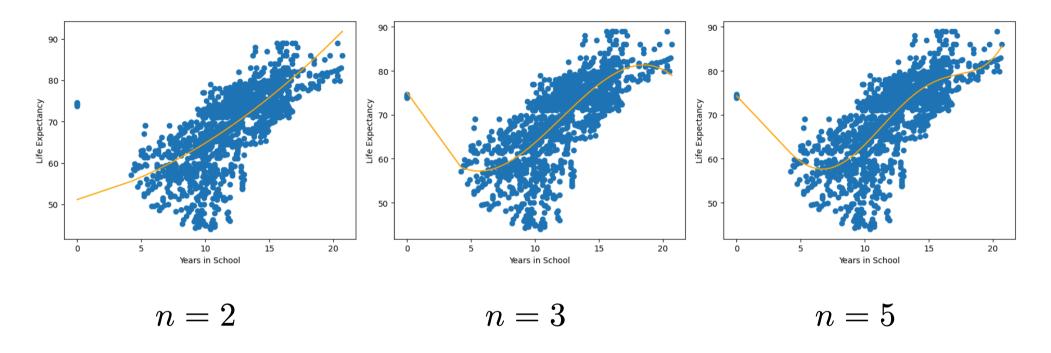


**Question:** Which n do you think has the smallest loss?

**Answer:** n = 5, but intuitively, n = 5 does not seem very good...

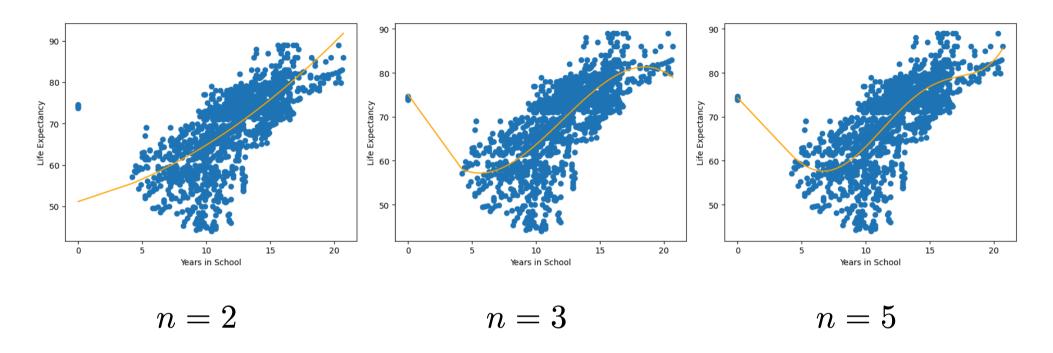


More specifically, n=5 will not generalize to new data



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We will only use our model for new data (we already have the y for a known x)!



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Lecture 1: Introduction

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Models that overfit are not useful for making predictions

Back to the question...

**Question:** How do we choose n such that our polynomial model works for unseen/new data?

**Answer:** Compute the loss on unseen data!

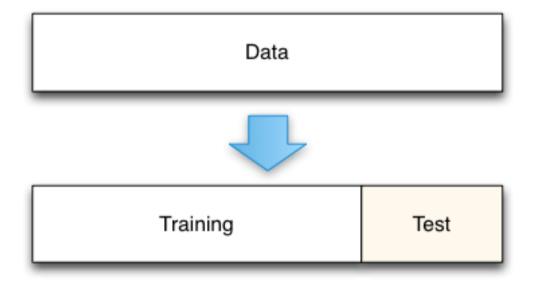
To compute the loss on unseen data, we will need unseen data

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Let us create some unseen data!

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Let us create some unseen data!



**Question:** How do we choose the training and testing datasets?

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Option 1: 
$$\boldsymbol{x}_{\text{train}} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \boldsymbol{y}_{\text{train}} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}; \quad \boldsymbol{x}_{\text{test}} = \begin{bmatrix} x_4 \\ x_5 \end{bmatrix}; \boldsymbol{y}_{\text{test}} = \begin{bmatrix} y_4 \\ y_5 \end{bmatrix}$$

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Option 2: 
$$m{x}_{\text{train}} = egin{bmatrix} x_4 \\ x_1 \\ x_3 \end{bmatrix} m{y}_{\text{train}} = egin{bmatrix} y_4 \\ y_1 \\ y_3 \end{bmatrix}; \quad m{x}_{\text{test}} = m{\begin{bmatrix}} x_2 \\ x_5 \end{bmatrix}; m{y}_{\text{test}} = m{\begin{bmatrix}} y_2 \\ y_5 \end{bmatrix}$$

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**Answer:** Always shuffle the data

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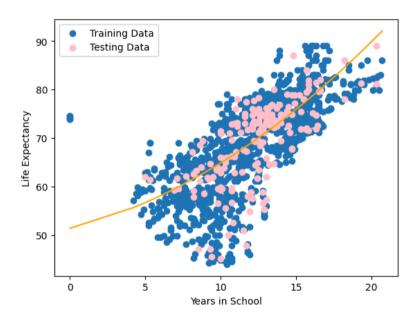
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**Answer:** Always shuffle the data

**Note:** The model must never see the testing dataset during training. This is very important!

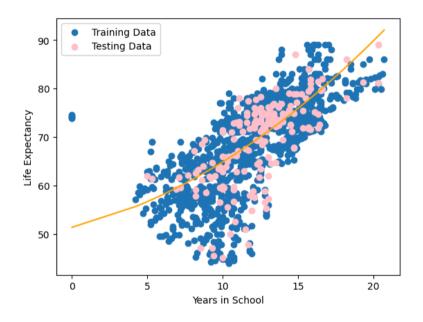
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Learn parameters from the train dataset, evaluate on the test dataset

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$$\mathcal{L}(oldsymbol{X}_{ ext{train}}, oldsymbol{y}_{ ext{train}}, oldsymbol{ heta})$$

$$\mathcal{L}(oldsymbol{X}_{ ext{test}}, oldsymbol{y}_{ ext{test}}, oldsymbol{ heta})$$

We use separate training and testing datasets on **all** machine learning models, not just linear regression

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