Regression

CISC 7026: Introduction to Deep Learning

University of Macau

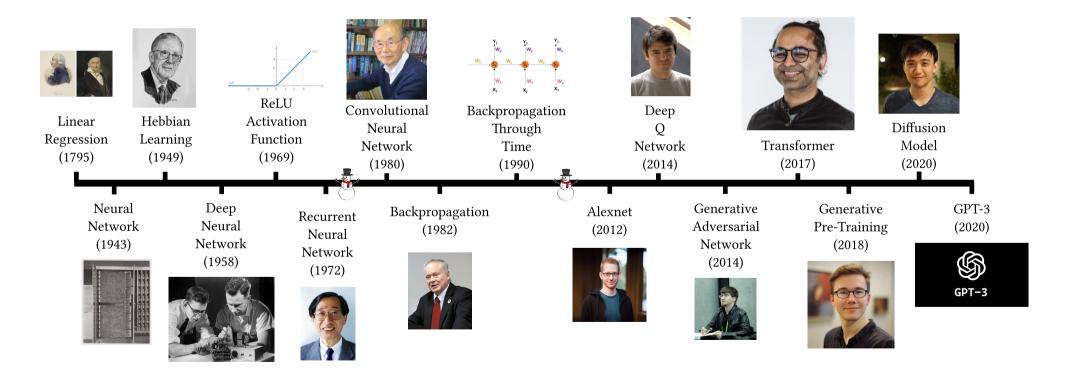
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Lecture 1: Introduction

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Let us start with regression

Today, we will come up with a regression problem and then solve it!

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Available for free at https://www.who.int/data/gho/data/themes/mortality-and-global-health-estimates/ghe-life-expectancy-and-healthy-life-expectancy

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Lecture 1: Introduction

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For each person, they recorded:

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We can use this data to make future predictions

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- The causal effects of education on health outcomes in the UK Biobank. Davies et al. Nature Human Behaviour.
- By staying in school, you are likely to live longer

Task: Given your education, predict your life expectancy

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$$f(x,\theta) = y; \quad x \in X, y \in Y$$

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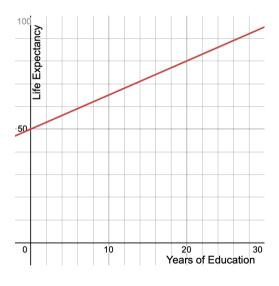
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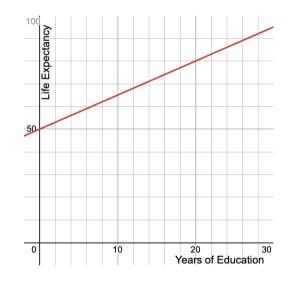
$$f(x, \boldsymbol{\theta}) = f\left(x, \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}\right) = \theta_1 x + \theta_0$$



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Now, we need to find the parameters $m{ heta} = egin{bmatrix} heta_1 \\ heta_0 \end{bmatrix}$ that makes $f(x, m{ heta}) = y$

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Now, we need to find the parameters $\pmb{\theta} = \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}$ that make $f(x,\pmb{\theta}) = y$

Question: How do we find θ ? (Hint: We want $f(x, \theta) = y$)

Answer: We will minimize the **loss** (error) between $f(x, \theta)$ and y, for all

$$x \in X, y \in Y$$

We compute the loss using the **loss function** $\mathcal{L}: X \times Y \times \Theta \mapsto \mathbb{R}$

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$$\operatorname{error}(y, \hat{y}) = (y - \hat{y})^2$$

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$$\operatorname{error}(f(x, \boldsymbol{\theta}), y) = (f(x, \boldsymbol{\theta}) - y)^2$$

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Square for minimization

We can write the loss function for a single datapoint x_i, y_i as

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Answer: We only consider a single datapoint! We want to learn θ for the entire dataset

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For the entire dataset:

$$oldsymbol{x} = \begin{bmatrix} x_1 & x_2 & ... & x_n \end{bmatrix}^ op, oldsymbol{y} = \begin{bmatrix} y_1 & y_2 & ... & y_n \end{bmatrix}^ op$$

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Minimizing this loss function will give us the optimal parameters!

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Answer: For now, magic! We need more knowledge before we can derive this.

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$$oldsymbol{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix}$$

We add the column of ones so that we can multiply X_D^{\top} with θ to get a linear function $\theta_1 x + \theta_0$ evaluated at each data point

$$m{X}_Dm{ heta} = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix} egin{bmatrix} heta_1 \ heta_0 \ heta_1 \end{bmatrix} = egin{bmatrix} heta_1x_1 + heta_0 \ heta_1x_2 + heta_0 \ dots \ heta_1x_n + heta_0 \end{bmatrix}$$

With our design matrix X_D and desired output y,

$$oldsymbol{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix}, oldsymbol{y} = egin{bmatrix} y_1 \ y_2 \ dots \ y_n \end{bmatrix}$$

and our parameters θ ,

$$oldsymbol{ heta} = egin{bmatrix} heta_1 \ heta_0 \end{bmatrix},$$

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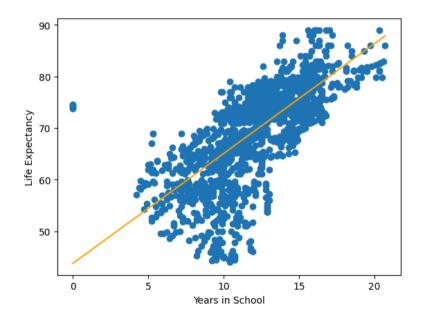
You will be doing this in your first assignment!

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Tips for assignment 1

```
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def f(theta, design):
    # Linear function
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Not all matrices can be inverted! Ensure the matrices are square and the condition number is low

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Everything you need is in the lecture notes

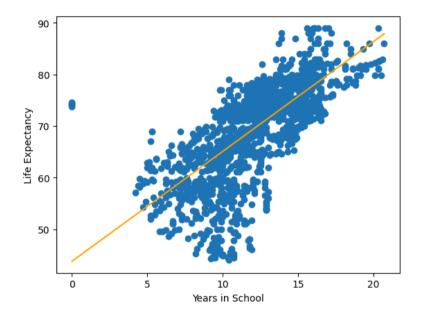
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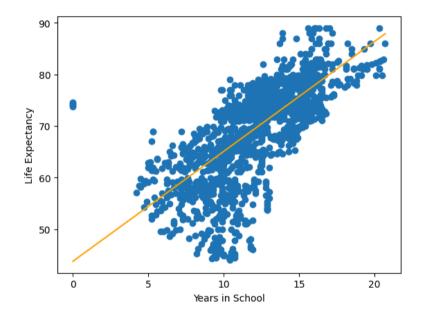
Relax

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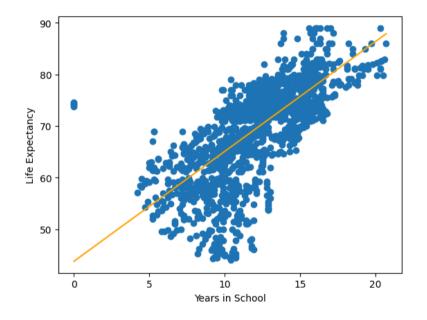


Task: Given your education, predict your life expectancy



We figured out linear regression!

Task: Given your education, predict your life expectancy



We figured out linear regression!

But can we do better?

1. Beyond linear functions

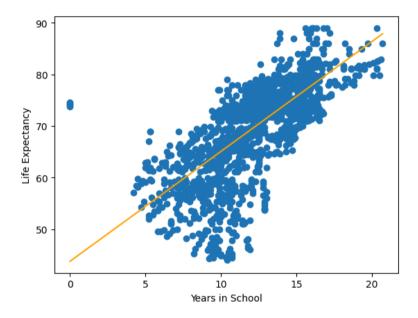
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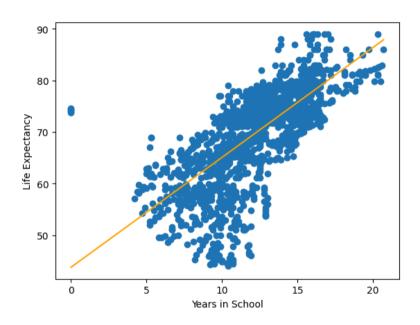
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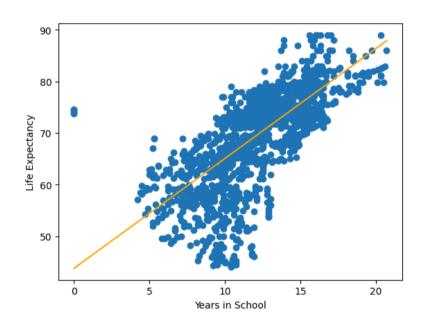
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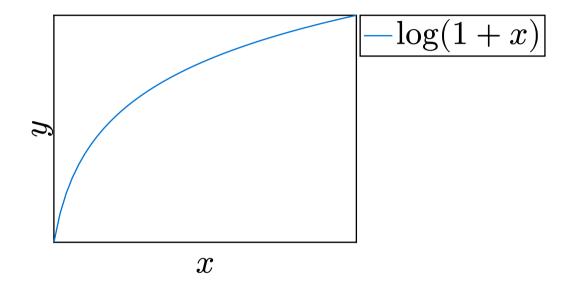




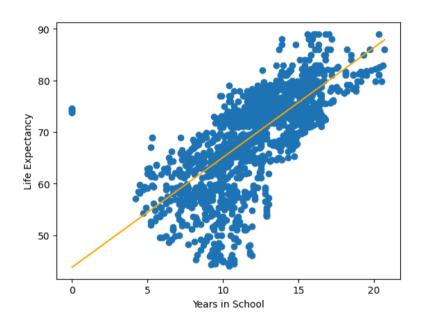
Or maybe more logarithmic?



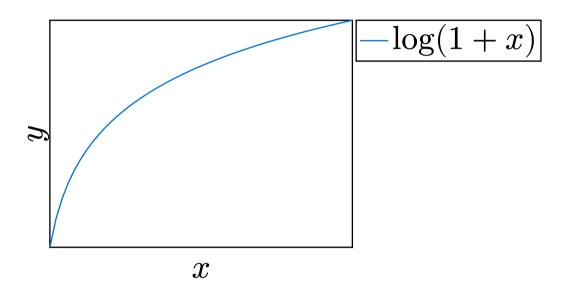
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Does the data look linear?

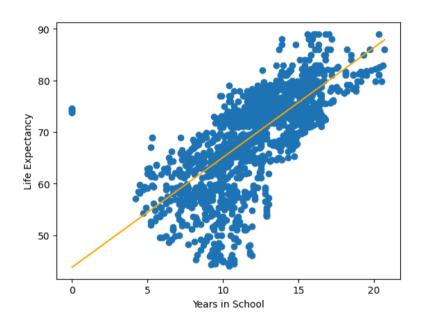


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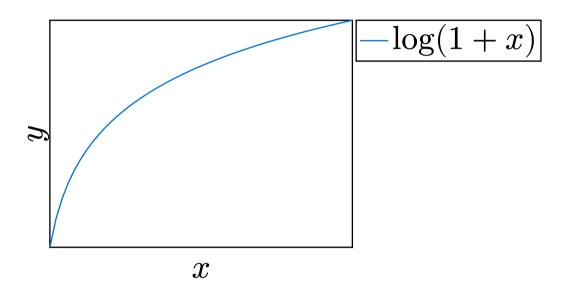


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Now, f is a linear function of $\log(x)$ – a nonlinear function of x!

New design matrix...

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New function...

$$f\bigg(x, \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix} \bigg) = \theta_1 \log(1+x) + \theta_0$$

New design matrix...

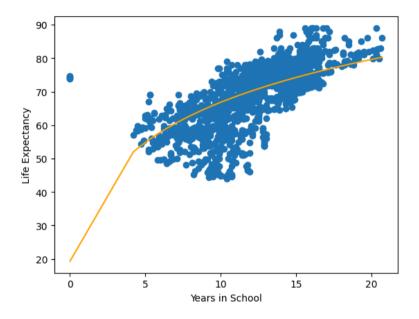
$$m{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix} \Rightarrow m{X}_D = egin{bmatrix} \log(1+x_1) & 1 \ \log(1+x_2) & 1 \ dots & dots \ \log(1+x_n) & 1 \end{bmatrix}$$

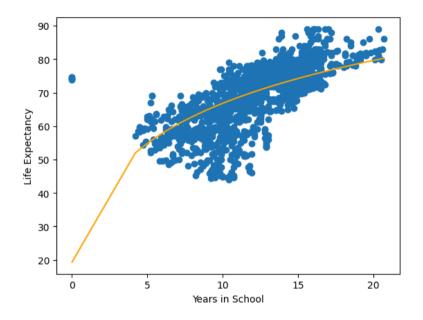
New function...

$$f\!\left(x, \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}\right) = \theta_1 \log(1+x) + \theta_0 \qquad \qquad \boldsymbol{\theta} = \left(\boldsymbol{X}_D^\top \boldsymbol{X}_D\right)^{-1} \boldsymbol{X}_D^\top \boldsymbol{y}$$

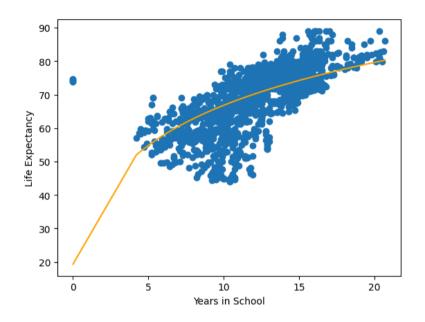
Same solution...

$$oldsymbol{ heta} = \left(oldsymbol{X}_D^ op oldsymbol{X}_D^ op oldsymbol{X}_D^ op oldsymbol{y}^{-1} oldsymbol{X}_D^ op oldsymbol{y}$$





Better, but still not perfect



Better, but still not perfect Can we do even better?

$$f(x) = ax^n + bx^{n-1} + \dots + cx + d$$

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Polynomials can approximate **any** function (universal function approximator)

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Can we extend linear regression to polynomials?

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Expand to multi-dimensional input space...

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$$m{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix} \Rightarrow m{X}_D = egin{bmatrix} x_1^n & x_1^{n-1} & \dots & x_1 & 1 \ x_2^n & x_2^{n-1} & \dots & x_2 & 1 \ dots & dots & \ddots & \ x_n & x_n^{n-1} & \dots & x_n & 1 \end{bmatrix}$$

And add some new parameters...

$$oldsymbol{ heta} = \left[eta_n \;\; heta_{n-1} \;\; ... \;\; oldsymbol{ heta}_1 \;\; oldsymbol{ heta}_0
ight]^{ op}$$

$$\boldsymbol{X}_{D}\boldsymbol{\theta} = \begin{bmatrix} x_{1}^{n} & x_{1}^{n-1} & \dots & x_{1} & 1 \\ x_{2}^{n} & x_{2}^{n-1} & \dots & x_{2} & 1 \\ \vdots & \vdots & \ddots & & \vdots \\ x_{n} & x_{n}^{n-1} & \dots & x_{n} & 1 \end{bmatrix} \begin{bmatrix} \theta_{n} \\ \theta_{n-1} \\ \vdots \\ \theta_{0} \end{bmatrix} = \begin{bmatrix} \theta_{n}x_{1}^{n} + \theta_{n-1}x_{1}^{n-1} + \dots + \theta_{0} \\ \theta_{n}x_{2} + \theta_{n-1}x_{2}^{n-1} + \dots + \theta_{0} \\ \vdots \\ \theta_{n}x_{n}^{n} + \theta_{n-1}x_{n}^{n-1} + \dots + \theta_{0} \end{bmatrix}$$

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New function...

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$$f(x, \theta) = \theta_n x^n + \theta_{n-1} x^{n-1}, ..., \theta_1 + x^1 + \theta_0$$

Same solution...

$$oldsymbol{ heta} = ig(oldsymbol{X}_D^ op oldsymbol{X}_D^ opig)^{-1} oldsymbol{X}_D^ op oldsymbol{y}$$

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Summary: By changing the input space, we can fit a polynomial to the data using a linear fit!

- 1. Beyond linear functions
- 2. Overfitting
- 3. Outliers
- 4. Regularization

Lecture 1: Introduction

- 1. Beyond linear functions
- 2. Overfitting
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Lecture 1: Introduction

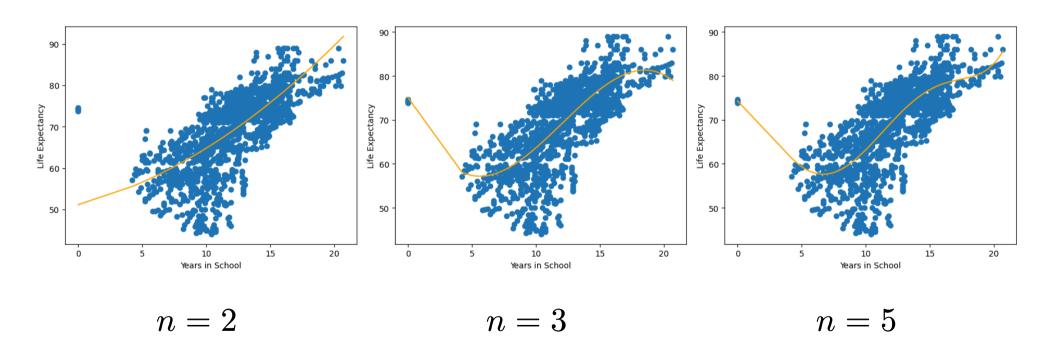
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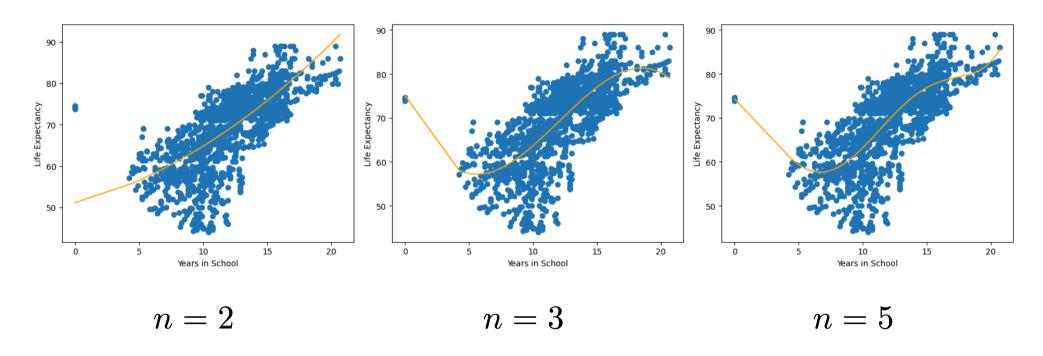
How do we choose n (polynomial order) that provides the best fit?

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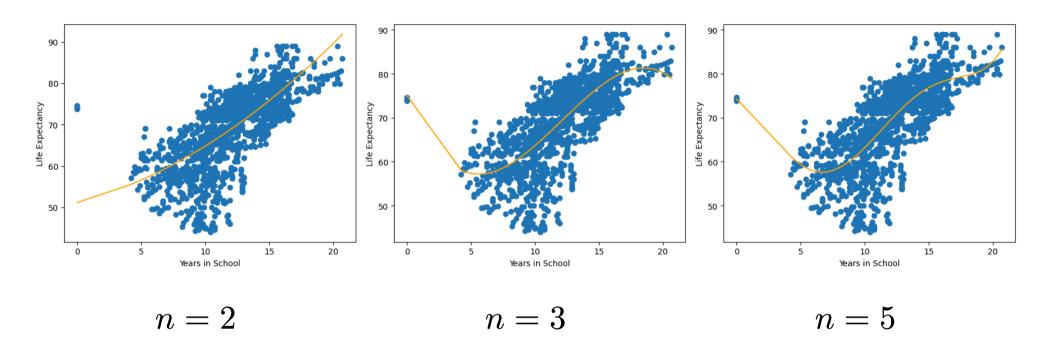


How do we choose n (polynomial order) that provides the best fit?

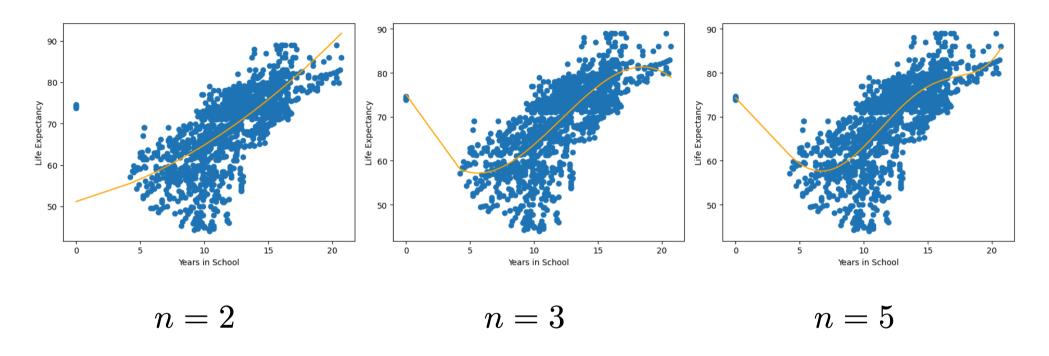


Pick the *n* with the smallest loss

$$\operatorname*{arg\ min}_{\boldsymbol{\theta},n} \mathcal{L}(\boldsymbol{x},\boldsymbol{y},(\boldsymbol{\theta},n))$$



Question: Which n do you think has the smallest loss?



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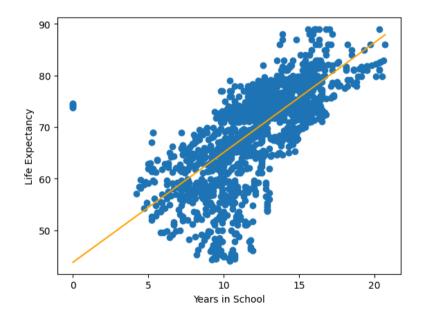
Answer: n = 5 – but intuitively, n = 5 does not seem very good...

Back to the example...

Task: Given your education, predict your life expectancy

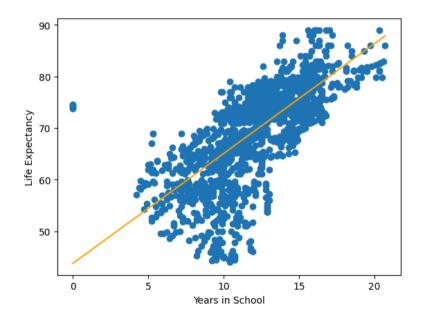
Back to the example...

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Back to the example...

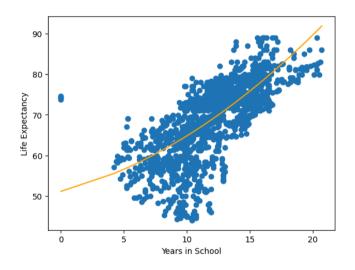
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Could we do better than a linear function f?

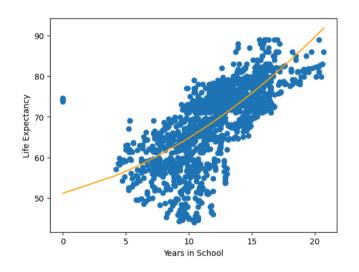
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What if we used a polynomial instead?

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$$f(x, \theta) = \theta_n x^n + \theta_{n-1} x^{n-1}, ..., \theta_1 + x^1 + \theta_0$$

But we said we were using a linear model, how can we come up with a nonlinear polynomial?

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$$f(x, \boldsymbol{\theta}) = f\left(x, \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \\ \vdots \\ \theta_n \end{bmatrix}\right) = \theta_n x^n + \theta_{n-1} x^{n-1}, ..., \theta_1 + x^1 + \theta_0$$

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$$f(x,\boldsymbol{\theta}) = \begin{bmatrix} \theta_n & \theta_{n-1} & \dots & \theta_1 & b \end{bmatrix} \begin{bmatrix} x^n \\ x^{n-1} \\ \vdots \\ x^1 \\ 1 \end{bmatrix}$$

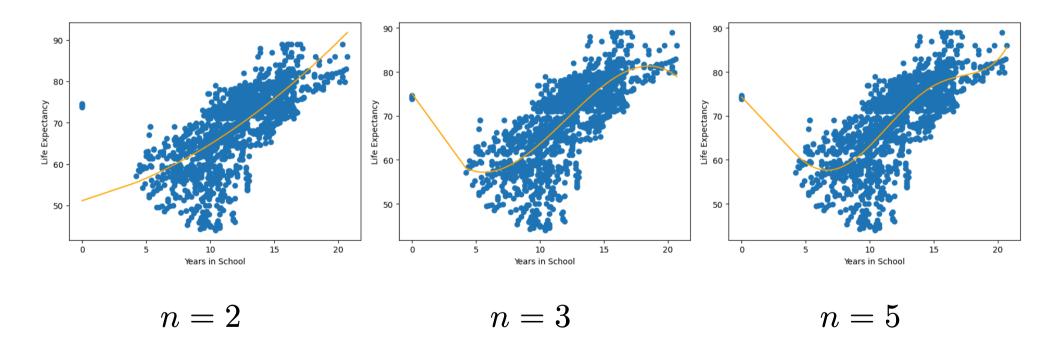
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How do we choose n? Let us try different n

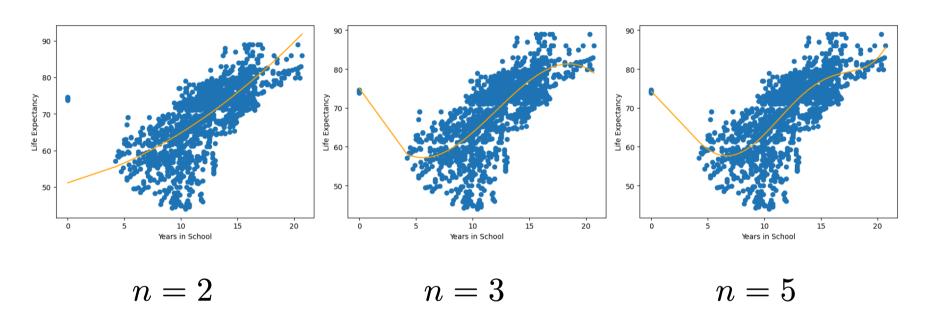
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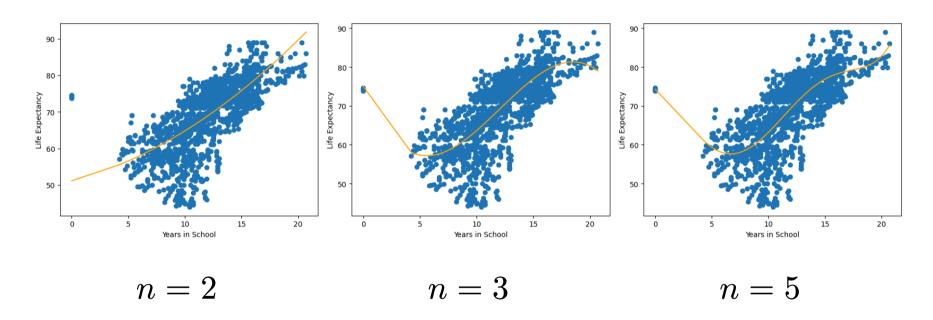
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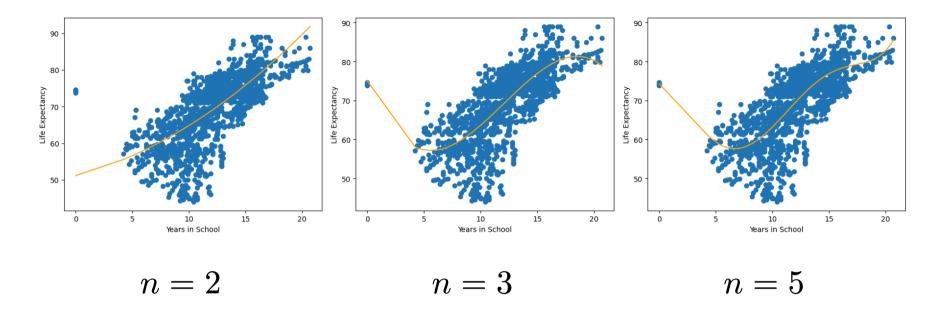
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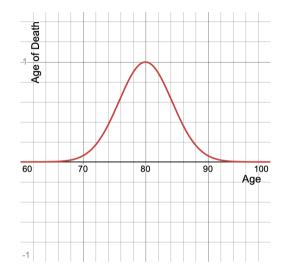
Answer: n = 2 feels right, but why?



Data can be noisy and we want to fit the trend, not the noise

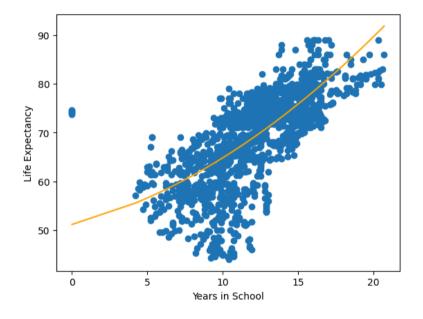
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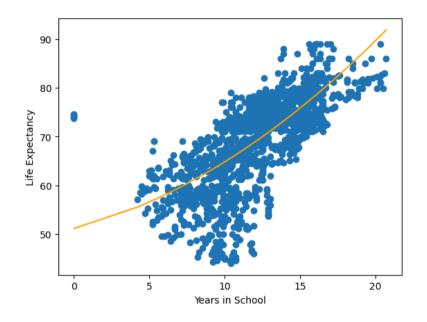


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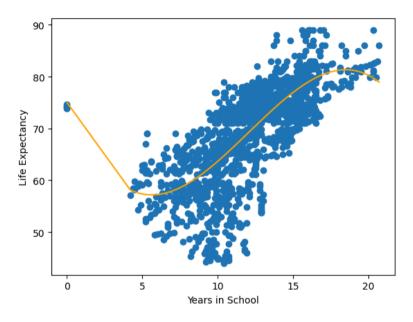
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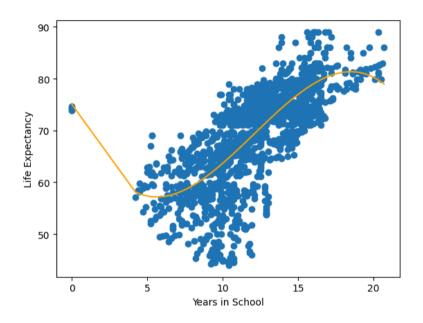


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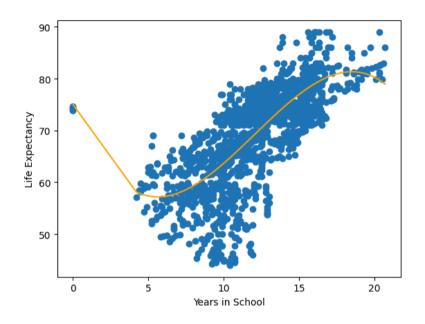


Going to school for 20 years will not save you from a hungry bear





When we fit to noise instead of the trend, we call it **overfitting**



When we fit to noise instead of the trend, we call it **overfitting**Overfitting is bad because new predictions will be inaccurate

How can we measure overfitting?

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Learn our parameters from one subset of data: training dataset

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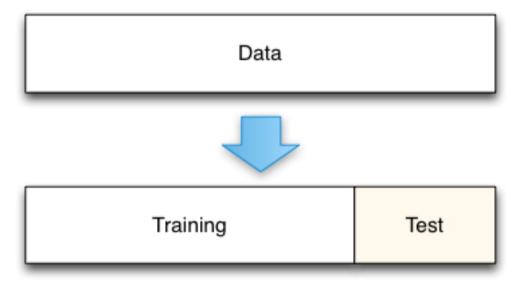
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Test our model on a different subset of data: **testing dataset**

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$$egin{aligned} \mathcal{D}_{ ext{train}} &= egin{bmatrix} x_1 & y_1 \ x_2 & y_2 \ x_3 & y_3 \end{bmatrix} \ \mathcal{D}_{ ext{test}} &= egin{bmatrix} x_4 & y_4 \ x_5 & y_5 \end{bmatrix} \end{aligned}$$

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Answer: Always shuffle the data

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Answer: Always shuffle the data

Note: The model must never see the testing dataset during training. This is very important!

Today we:

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- Discussed overfitting and test/train splits