Linear Regression

CISC 7026: Introduction to Deep Learning

University of Macau

I need the class to ask questions when they do not understand

I need the class to ask questions when they do not understand

I need the class to answer my questions, so I know that you understand

I need the class to ask questions when they do not understand

I need the class to answer my questions, so I know that you understand

If you ask/answer questions I will give the class 100% participation grade

I need the class to ask questions when they do not understand

I need the class to answer my questions, so I know that you understand

If you ask/answer questions I will give the class 100% participation grade

Otherwise, I will have to grade students individually on participation

I need the class to ask questions when they do not understand

I need the class to answer my questions, so I know that you understand

If you ask/answer questions I will give the class 100% participation grade

Otherwise, I will have to grade students individually on participation

You will make name tags, and I will count each time you participate

1. Review

- 1. Review
- 2. Quiz

- 1. Review
- 2. Quiz
- 3. Linear Regression

- 1. Review
- 2. Quiz
- 3. Linear Regression

We often know **what** we want, but we do not know **how**

We often know **what** we want, but we do not know **how**

We have many pictures of either dogs or muffins $x \in X$

We often know **what** we want, but we do not know **how**

We have many pictures of either dogs or muffins $x \in X$

We want to know if the picture is $[dog \mid muffin] y \in Y$

We often know **what** we want, but we do not know **how**

We have many pictures of either dogs or muffins $x \in X$

We want to know if the picture is $[dog \mid muffin] y \in Y$

We learn a function or mapping from X to Y

Why do we call it machine **learning**?

Why do we call it machine **learning**?

We learn the function f from the **data** $x \in X, y \in Y$

Why do we call it machine **learning**?

We learn the function f from the **data** $x \in X, y \in Y$

More specifically, we learn function **parameters** Θ

Why do we call it machine **learning**?

We learn the function f from the **data** $x \in X, y \in Y$

More specifically, we learn function **parameters** Θ

$$f: X \times \Theta \mapsto Y$$

Why do we call it machine **learning**?

We learn the function f from the **data** $x \in X, y \in Y$

More specifically, we learn function **parameters** Θ

$$f: X \times \Theta \mapsto Y$$

$$f\left(你好吗, \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \end{bmatrix}\right) = \text{You good?}$$

Why do we call it machine **learning**?

We learn the function f from the **data** $x \in X, y \in Y$

More specifically, we learn function **parameters** Θ

$$f: X \times \Theta \mapsto Y$$

$$f\left(你好吗, \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \end{bmatrix}\right) = \text{You good?}$$

x =你好吗,X =Chinese sentences

Why do we call it machine **learning**?

We learn the function f from the **data** $x \in X, y \in Y$

More specifically, we learn function **parameters** Θ

$$f: X \times \Theta \mapsto Y$$

$$f\left(你好吗, \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \end{bmatrix} \right) = \text{You good?}$$

x =你好吗,X =Chinese sentences

y =You good?, Y =English sentences

Create vectors, matrices, or tensors in jax

```
import jax.numpy as jnp
a = jnp.array(1) # Scalar
b = jnp.array([1, 2]) # Vector
C = jnp.array([[1,2], [3,4]]) # 2x2 Matrix
D = jnp.ones((3,3,3)) # 3x3x3 Tensor
```

You can determine the dimensions of a variable using shape

```
b.shape # Prints (2,)
C.shape # Prints (2,2)
D.shape # prints (3,3,3)
```

Create vectors, matrices, or tensors in pytorch

```
import torch
a = torch.tensor(1) # Scalar
b = torch.tensor([1, 2]) # Vector
C = torch.tensor([[1,2], [3,4]]) # 2x2 Matrix
D = torch.ones((3,3,3)) # 3x3x3 Tensor
```

You can determine the dimensions of a variable using shape

```
b.shape # Prints (2,)
C.shape # Prints (2,2)
D.shape # prints (3,3,3)
```

```
import jax.numpy as jnp
s = 5 * jnp.array([1, 2])
print(s) # jnp.array(5, 10)
x = jnp.array([1, 2]) + jnp.array([3, 4])
print(x) # jnp.array([4, 6])
y = jnp.array([1, 2]) * jnp.array([3, 4]) # Careful!
print(y) # jnp.array([3, 8])
z = jnp.array([[1], [2]]) @ jnp.array([[3, 4]])
print(z) # A^t B (dot product), jnp.array([[11]])
```

pytorch is very similar to jax import torch s = 5 * torch.tensor([1, 2])print(s) # torch.tensor(5, 10) x = torch.tensor([1, 2]) + torch.tensor([3, 4])print(x) # torch.tensor([4, 6]) y = torch.tensor([1, 2]) * torch.tensor([3, 4]) # Careful! print(y) # torch.tensor([3, 8]) z = torch.tensor([[1], [2]]) @ torch.tensor([[3, 4]])print(z) # A^t B (dot product), torch.tensor([[11]])

You can also call various methods on arrays/tensors

```
import jax.numpy as jnp

x = jnp.array([[1, 2], [3, 4]]).sum(axis=0)
print(x) # Sum across leading axis, array([4, 6])
y = jnp.array([[1, 2], [3, 4]]).mean()
print(y) # Mean across all axes, array(2.5)
z = jnp.array([[1, 2], [3, 4]]).reshape((4,))
print(z) # jnp.array([1, 2, 3, 4])
```

Same thing for pytorch

import torch

```
x = torch.tensor([[1, 2], [3, 4]]).sum(axis=0)
print(x) # Sum across leading axis, array([4, 6])
y = torch.tensor([[1, 2], [3, 4]]).mean()
print(y) # Mean across all axes, array(2.5)
z = torch.tensor([[1, 2], [3, 4]]).reshape((4,))
print(z) # torch.tensor([1, 2, 3, 4])
```

- 1. Review
- 2. Quiz
- 3. Linear Regression

- 1. Review
- 2. Quiz
- 3. Linear Regression



Time for a quiz!

Time for a quiz!

All laptops and phones away

Time for a quiz!

All laptops and phones away

Everyone take out paper and pen, write your name and student ID

Time for a quiz!

All laptops and phones away

Everyone take out paper and pen, write your name and student ID

I will explain the questions, then you have **15 minutes** to answer the questions

Time for a quiz!

All laptops and phones away

Everyone take out paper and pen, write your name and student ID

I will explain the questions, then you have **15 minutes** to answer the questions

You are not expected to answer all questions correctly, do not stress!

Time for a quiz!

All laptops and phones away

Everyone take out paper and pen, write your name and student ID

I will explain the questions, then you have **15 minutes** to answer the questions

You are not expected to answer all questions correctly, do not stress!

Q1: What is the function signature for machine learning?

Q2: What does the following code print?

```
jnp.array([1, 2]) * jnp.array([2, 1]) + jnp.array([5, 6])
```

Q3: What does the following code print?

```
jnp.array([[1, 2], [3, 4]]).sum(axis=1)
```

Q4: What does the following code print?

torch.arange(4)

Q1: What is the function signature for machine learning?

Q1: What is the function signature for machine learning?

A1: $f: X \times \Theta \mapsto Y$ $f: X, \Theta \mapsto Y$ also ok.

Q1: What is the function signature for machine learning?

A1:
$$f: X \times \Theta \mapsto Y$$
 $f: X, \Theta \mapsto Y$ also ok.

Q2: What does the following code print?

```
jnp.array([1, 2]) * jnp.array([2, 1]) + jnp.array([5, 6])
```

Q1: What is the function signature for machine learning?

A1:
$$f: X \times \Theta \mapsto Y$$
 $f: X, \Theta \mapsto Y$ also ok.

Q2: What does the following code print?

```
jnp.array([1, 2]) * jnp.array([2, 1]) + jnp.array([5, 6])
[1 * 2 + 5, 2 * 1 + 6]
```

Q1: What is the function signature for machine learning?

A1:
$$f: X \times \Theta \mapsto Y$$
 $f: X, \Theta \mapsto Y$ also ok.

Q2: What does the following code print?

```
jnp.array([1, 2]) * jnp.array([2, 1]) + jnp.array([5, 6])
[1 * 2 + 5, 2 * 1 + 6]
```

A2: Array([7, 8], dtype=int32), [7, 8] also ok

Q3: What does the following code print?

```
jnp.array([[1, 2], [3, 4]]).sum(axis=1)
```

Q3: What does the following code print?

```
jnp.array([[1, 2], [3, 4]]).sum(axis=1)
[1 + 2, 3 + 4]
```

Q3: What does the following code print?

```
jnp.array([[1, 2], [3, 4]]).sum(axis=1)
[1 + 2, 3 + 4]
```

A3: Array([3, 7], dtype=int32), [3, 7] also ok

Q3: What does the following code print? jnp.array([[1, 2], [3, 4]]).sum(axis=1)[1 + 2, 3 + 4]**A3:** Array([3, 7], dtype=int32), [3, 7] also ok **Q4:** What does the following code print? jnp.arange(4)

```
Q3: What does the following code print?
jnp.array([[1, 2], [3, 4]]).sum(axis=1)
[1 + 2, 3 + 4]
A3: Array([3, 7], dtype=int32), [3, 7] also ok
Q4: What does the following code print?
jnp.arange(4)
A4: Array([0, 1, 2, 3], dtype=int32), [0, 1, 2, 3] also ok
```

Agenda

- 1. Review
- 2. Quiz
- 3. Linear Regression

Agenda

- 1. Review
- 2. Quiz
- 3. Linear Regression

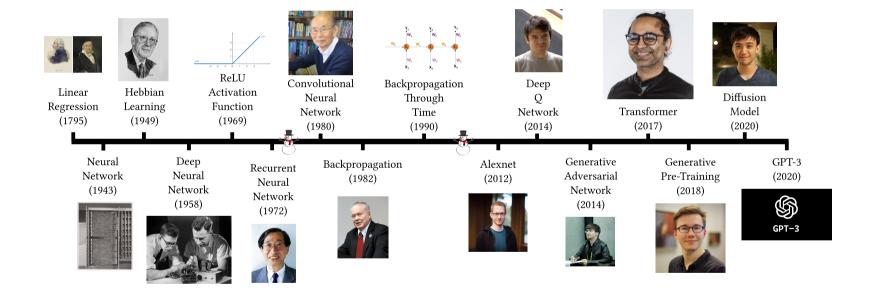
Today, we will learn about linear regression

Today, we will learn about linear regression

Probably the oldest method for machine learning (Gauss and Legendre)

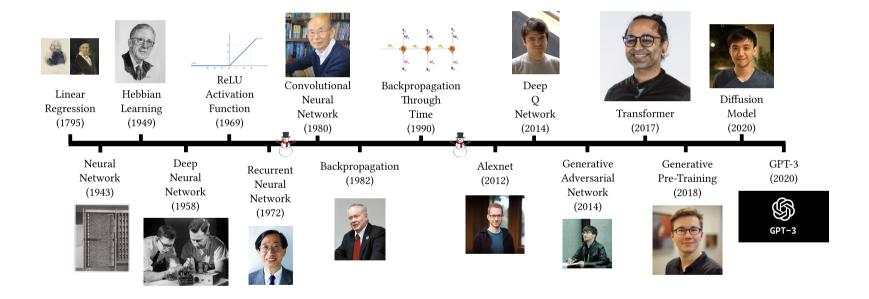
Today, we will learn about linear regression

Probably the oldest method for machine learning (Gauss and Legendre)



Today, we will learn about linear regression

Probably the oldest method for machine learning (Gauss and Legendre)



Neural networks share many similarities with linear regression

Many problems in ML can be reduced to **regression** or **classification**

Many problems in ML can be reduced to **regression** or **classification**

Regression asks how many

Many problems in ML can be reduced to **regression** or **classification**

Regression asks how many

• Given my parents height, How tall will I be?

Many problems in ML can be reduced to **regression** or **classification**

Regression asks how many

- Given my parents height, How tall will I be?
- Given the rain today, how much rain will there be tomorrow?

Many problems in ML can be reduced to **regression** or **classification**

Regression asks how many

- Given my parents height, How tall will I be?
- Given the rain today, how much rain will there be tomorrow?
- Given a camera image, how far away is this object?

Many problems in ML can be reduced to **regression** or **classification**

Regression asks how many

- Given my parents height, How tall will I be?
- Given the rain today, how much rain will there be tomorrow?
- Given a camera image, how far away is this object?

Classification asks which one

Many problems in ML can be reduced to **regression** or **classification**

Regression asks how many

- Given my parents height, How tall will I be?
- Given the rain today, how much rain will there be tomorrow?
- Given a camera image, how far away is this object?

Classification asks which one

• Is this image of a dog or muffin?

Many problems in ML can be reduced to **regression** or **classification**

Regression asks how many

- Given my parents height, How tall will I be?
- Given the rain today, how much rain will there be tomorrow?
- Given a camera image, how far away is this object?

Classification asks which one

- Is this image of a dog or muffin?
- Given the rain today, will it rain tomorrow? Yes or no?

Many problems in ML can be reduced to **regression** or **classification**

Regression asks how many

- Given my parents height, How tall will I be?
- Given the rain today, how much rain will there be tomorrow?
- Given a camera image, how far away is this object?

Classification asks which one

- Is this image of a dog or muffin?
- Given the rain today, will it rain tomorrow? Yes or no?
- Given a camera image, what color is this object? Yellow, blue, red, ...?

Many problems in ML can be reduced to **regression** or **classification**

Regression asks how many

- Given my parents height, How tall will I be?
- Given the rain today, how much rain will there be tomorrow?
- Given a camera image, how far away is this object?

Classification asks which one

- Is this image of a dog or muffin?
- Given the rain today, will it rain tomorrow? Yes or no?
- Given a camera image, what color is this object? Yellow, blue, red, ...?

Let us start with regression

Today, we will come up with a regression problem and then solve it!

1. Define an example problem

- 1. Define an example problem
- 2. Define our linear model f

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Example Problem

The World Health Organization (WHO) has collected data on life expectancy

Example Problem

The World Health Organization (WHO) has collected data on life expectancy



Available for free at https://www.who.int/data/gho/data/themes/mortality-and-global-health-estimates/ghe-life-expectancy-and-healthy-life-expectancy

Example Problem

The WHO collected data from roughly 3,000 people from 193 countries

The WHO collected data from roughly 3,000 people from 193 countries

The WHO collected data from roughly 3,000 people from 193 countries

For each person, they recorded:

• Home country

The WHO collected data from roughly 3,000 people from 193 countries

- Home country
- Alcohol consumption

The WHO collected data from roughly 3,000 people from 193 countries

- Home country
- Alcohol consumption
- Education

The WHO collected data from roughly 3,000 people from 193 countries

- Home country
- Alcohol consumption
- Education
- Gross domestic product (GDP) of the country

The WHO collected data from roughly 3,000 people from 193 countries

- Home country
- Alcohol consumption
- Education
- Gross domestic product (GDP) of the country
- Immunizations for Measles and Hepatitis B

The WHO collected data from roughly 3,000 people from 193 countries

- Home country
- Alcohol consumption
- Education
- Gross domestic product (GDP) of the country
- Immunizations for Measles and Hepatitis B
- How long this person lived

The WHO collected data from roughly 3,000 people from 193 countries

For each person, they recorded:

- Home country
- Alcohol consumption
- Education
- Gross domestic product (GDP) of the country
- Immunizations for Measles and Hepatitis B
- How long this person lived

We can use this data to make future predictions

Since everyone here is very educated, we will focus on how education affects life expectancy

Since everyone here is very educated, we will focus on how education affects life expectancy

There are studies showing a causal effect of education on health

Since everyone here is very educated, we will focus on how education affects life expectancy

There are studies showing a causal effect of education on health

• The causal effects of education on health outcomes in the UK Biobank. Davies et al. Nature Human Behaviour.

Since everyone here is very educated, we will focus on how education affects life expectancy

There are studies showing a causal effect of education on health

- The causal effects of education on health outcomes in the UK Biobank. Davies et al. Nature Human Behaviour.
- By staying in school, you are likely to live longer

Task: Given your education, predict your life expectancy

Task: Given your education, predict your life expectancy

 $X \in \mathbb{R}_+$: Years in school

Task: Given your education, predict your life expectancy

 $X \in \mathbb{R}_+$: Years in school

 $Y \in \mathbb{R}_+$: Age of death

Task: Given your education, predict your life expectancy

 $X \in \mathbb{R}_+$: Years in school

 $Y \in \mathbb{R}_+$: Age of death

Each $x \in X$ and $y \in Y$ represent a single person

Task: Given your education, predict your life expectancy

 $X \in \mathbb{R}_+$: Years in school

 $Y \in \mathbb{R}_+$: Age of death

Each $x \in X$ and $y \in Y$ represent a single person

Approach: Learn the parameters θ such that

$$f(x,\theta) = y; \quad x \in X, y \in Y$$

Task: Given your education, predict your life expectancy

 $X \in \mathbb{R}_+$: Years in school

 $Y \in \mathbb{R}_+$: Age of death

Each $x \in X$ and $y \in Y$ represent a single person

Approach: Learn the parameters θ such that

$$f(x,\theta) = y; \quad x \in X, y \in Y$$

Goal: Given someone's education, predict how long they will live

Linear Regression

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Linear Regression

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Soon, f will be a deep neural network

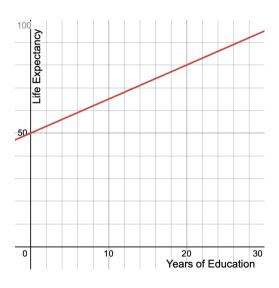
Soon, f will be a deep neural network

For now, it is easier if we make f a **linear function**

Soon, f will be a deep neural network

For now, it is easier if we make f a **linear function**

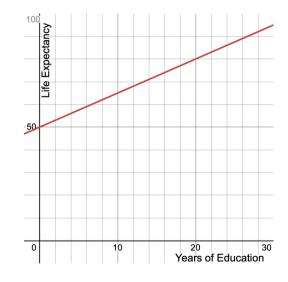
$$f(x, \boldsymbol{\theta}) = f\left(x, \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}\right) = \theta_1 x + \theta_0$$



Soon, f will be a deep neural network

For now, it is easier if we make f a **linear function**

$$f(x, \boldsymbol{\theta}) = f\left(x, \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}\right) = \theta_1 x + \theta_0$$



Now, we need to find the parameters $m{ heta} = egin{bmatrix} heta_1 \\ heta_0 \end{bmatrix}$ that makes $f(x, m{ heta}) = y$

Linear Regression

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Linear Regression

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Now, we need to find the parameters $\pmb{\theta} = \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}$ that make $f(x,\pmb{\theta}) = y$

Now, we need to find the parameters $\pmb{\theta} = \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}$ that make $f(x,\pmb{\theta}) = y$

How do we find θ ? (Hint: We want $f(x, \theta) = y$)

Now, we need to find the parameters $\pmb{\theta} = \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}$ that make $f(x,\pmb{\theta}) = y$

How do we find θ ? (Hint: We want $f(x, \theta) = y$)

We will minimize the **loss** (error) between $f(x, \theta)$ and y, for all

$$x \in X, y \in Y$$

We compute the loss using the **loss function**

We compute the loss using the **loss function**

$$\mathcal{L}: X^n \times Y^n \times \Theta \mapsto \mathbb{R}$$

We compute the loss using the loss function

$$\mathcal{L}: X^n \times Y^n \times \Theta \mapsto \mathbb{R}$$

The loss function tells us how close $f(x, \theta)$ is to y

We compute the loss using the **loss function**

$$\mathcal{L}: X^n \times Y^n \times \Theta \mapsto \mathbb{R}$$

The loss function tells us how close $f(x, \theta)$ is to y

By **minimizing** the loss function, we make $f(x, \theta) = y$

We compute the loss using the **loss function**

$$\mathcal{L}: X^n \times Y^n \times \Theta \mapsto \mathbb{R}$$

The loss function tells us how close $f(x, \theta)$ is to y

By **minimizing** the loss function, we make $f(x, \theta) = y$

There are many possible loss functions, but for regression we often use the **square error**

We compute the loss using the **loss function**

$$\mathcal{L}: X^n \times Y^n \times \Theta \mapsto \mathbb{R}$$

The loss function tells us how close $f(x, \theta)$ is to y

By **minimizing** the loss function, we make $f(x, \theta) = y$

There are many possible loss functions, but for regression we often use the **square error**

$$\operatorname{error}(y, \hat{y}) = (y - \hat{y})^2$$

Let's derive the error function

Let's derive the error function

$$f(x, \boldsymbol{\theta}) = y$$

f(x) should predict y

Let's derive the error function

$$f(x, \boldsymbol{\theta}) = y$$

$$f(x, \boldsymbol{\theta}) - y = 0$$

f(x) should predict y

Move y to LHS

Let's derive the error function

$$f(x, \boldsymbol{\theta}) = y$$

$$f(x, \boldsymbol{\theta}) - y = 0$$

$$\left(f(x,\boldsymbol{\theta}) - y\right)^2 = 0$$

f(x) should predict y

Move y to LHS

Square for minimization

Let's derive the error function

$$f(x, \boldsymbol{\theta}) = y$$

$$f(x, \boldsymbol{\theta}) - y = 0$$

$$\left(f(x,\boldsymbol{\theta}) - y\right)^2 = 0$$

$$\operatorname{error}(f(x, \boldsymbol{\theta}), y) = (f(x, \boldsymbol{\theta}) - y)^2$$

f(x) should predict y

Move y to LHS

Square for minimization

We can write the loss function for a single datapoint x_i, y_i as

$$\mathcal{L}(x_i, y_i, \boldsymbol{\theta}) = \operatorname{error}(f(x_i, \boldsymbol{\theta}), y_i) = \left(f(x_i, \boldsymbol{\theta}) - y_i\right)^2$$

We can write the loss function for a single datapoint x_i, y_i as

$$\mathcal{L}(x_i, y_i, \boldsymbol{\theta}) = \operatorname{error}(f(x_i, \boldsymbol{\theta}), y_i) = \left(f(x_i, \boldsymbol{\theta}) - y_i\right)^2$$

Question: Will this \mathcal{L} give us a good prediction for all possible x?

We can write the loss function for a single datapoint x_i, y_i as

$$\mathcal{L}(x_i, y_i, \boldsymbol{\theta}) = \operatorname{error}(f(x_i, \boldsymbol{\theta}), y_i) = \left(f(x_i, \boldsymbol{\theta}) - y_i\right)^2$$

Question: Will this \mathcal{L} give us a good prediction for all possible x?

Answer: No! We only consider a single datapoint x_i, y_i . We want to learn θ for the entire dataset, for all $x \in X, y \in Y$

For a single x_i, y_i :

$$\mathcal{L}(x_i, y_i, \boldsymbol{\theta}) = \operatorname{error}(f(x_i, \boldsymbol{\theta}), y_i) = \left(f(x_i, \boldsymbol{\theta}) - y_i\right)^2$$

For a single x_i, y_i :

$$\mathcal{L}(x_i, y_i, \boldsymbol{\theta}) = \operatorname{error}(f(x_i, \boldsymbol{\theta}), y_i) = \left(f(x_i, \boldsymbol{\theta}) - y_i\right)^2$$

For the entire dataset:

$$oldsymbol{x} \equiv \begin{bmatrix} x_1 & x_2 & ... & x_n \end{bmatrix}^ op, oldsymbol{y} \equiv \begin{bmatrix} y_1 & y_2 & ... & y_n \end{bmatrix}^ op$$

For a single x_i, y_i :

$$\mathcal{L}(\boldsymbol{x}_i, \boldsymbol{y}_i, \boldsymbol{\theta}) = \text{error}(f(\boldsymbol{x}_i, \boldsymbol{\theta}), \boldsymbol{y}_i) = \left(f(\boldsymbol{x}_i, \boldsymbol{\theta}) - \boldsymbol{y}_i\right)^2$$

For the entire dataset:

$$oldsymbol{x} \equiv \begin{bmatrix} x_1 & x_2 & ... & x_n \end{bmatrix}^ op, oldsymbol{y} \equiv \begin{bmatrix} y_1 & y_2 & ... & y_n \end{bmatrix}^ op$$

$$\mathcal{L}(\boldsymbol{x},\boldsymbol{y},\boldsymbol{\theta}) = \sum_{i=1}^n \operatorname{error}(f(x_i,\boldsymbol{\theta}),y_i) = \sum_{i=1}^n \left(f(x_i,\boldsymbol{\theta}) - y_i\right)^2$$

For a single x_i, y_i :

$$\mathcal{L}(x_i, y_i, \boldsymbol{\theta}) = \operatorname{error}(f(x_i, \boldsymbol{\theta}), y_i) = \left(f(x_i, \boldsymbol{\theta}) - y_i\right)^2$$

For the entire dataset:

$$\boldsymbol{x} = \begin{bmatrix} x_1 & x_2 & \dots & x_n \end{bmatrix}^{\top}, \boldsymbol{y} = \begin{bmatrix} y_1 & y_2 & \dots & y_n \end{bmatrix}^{\top}$$

$$\mathcal{L}(\boldsymbol{x},\boldsymbol{y},\boldsymbol{\theta}) = \sum_{i=1}^n \operatorname{error}(f(x_i,\boldsymbol{\theta}),y_i) = \sum_{i=1}^n \left(f(x_i,\boldsymbol{\theta}) - y_i\right)^2$$

When $\mathcal{L}(\boldsymbol{x},\boldsymbol{y},\boldsymbol{\theta})$ is small, then $f(x,\boldsymbol{\theta})\approx y$ for the whole dataset!

Linear Regression

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Linear Regression

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Here is our loss function:

$$\mathcal{L}(\boldsymbol{x},\boldsymbol{y},\boldsymbol{\theta}) = \sum_{i=1}^{n} \operatorname{error}(f(x_i,\boldsymbol{\theta}),y_i) = \sum_{i=1}^{n} \left(f(x_i,\boldsymbol{\theta}) - y_i\right)^2$$

Here is our loss function:

$$\mathcal{L}(\boldsymbol{x},\boldsymbol{y},\boldsymbol{\theta}) = \sum_{i=1}^n \operatorname{error}(f(x_i,\boldsymbol{\theta}),y_i) = \sum_{i=1}^n \left(f(x_i,\boldsymbol{\theta}) - y_i\right)^2$$

When $\mathcal{L}(x, y, \theta)$ is small, then $f(x, \theta) \approx y$ for the whole dataset!

Here is our loss function:

$$\mathcal{L}(\boldsymbol{x},\boldsymbol{y},\boldsymbol{\theta}) = \sum_{i=1}^n \operatorname{error}(f(x_i,\boldsymbol{\theta}),y_i) = \sum_{i=1}^n \left(f(x_i,\boldsymbol{\theta}) - y_i\right)^2$$

When $\mathcal{L}(\boldsymbol{x},\boldsymbol{y},\boldsymbol{\theta})$ is small, then $f(x,\boldsymbol{\theta})\approx y$ for the whole dataset!

We want to find parameters θ that make the loss small

Here is our loss function:

$$\mathcal{L}(\boldsymbol{x},\boldsymbol{y},\boldsymbol{\theta}) = \sum_{i=1}^n \operatorname{error}(f(x_i,\boldsymbol{\theta}),y_i) = \sum_{i=1}^n \left(f(x_i,\boldsymbol{\theta}) - y_i\right)^2$$

When $\mathcal{L}(\boldsymbol{x},\boldsymbol{y},\boldsymbol{\theta})$ is small, then $f(x,\boldsymbol{\theta})\approx y$ for the whole dataset!

We want to find parameters θ that make the loss small

Let us state this more formally

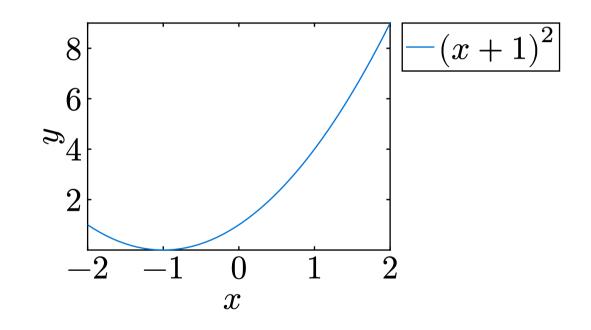
Our objective is to **minimize** the loss, using arg min

Our objective is to **minimize** the loss, using arg min arg $\min_x f(x)$ means find the x that makes f(x) smallest

Our objective is to **minimize** the loss, using arg min arg $\min_x f(x)$ means find the x that makes f(x) smallest

Question:

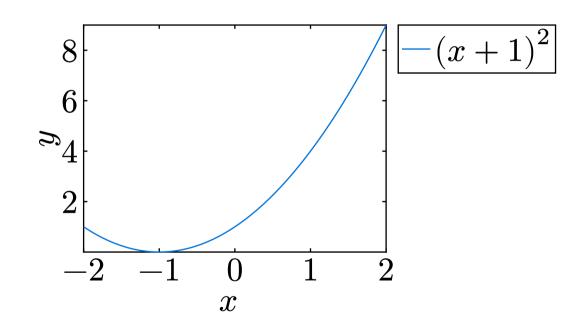
What is $\underset{x}{\operatorname{arg min}} (x+1)^2$



Our objective is to **minimize** the loss, using arg min arg $\min_x f(x)$ means find the x that makes f(x) smallest

Question:

What is $\underset{x}{\operatorname{arg min}} (x+1)^2$



Answer: arg min_x $(x+1)^2 = -1$, where f(x) = 0

Formally, our objective is to find the arg min of the loss

$$\begin{split} \arg\min_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{x}, \boldsymbol{y}, \boldsymbol{\theta}) &= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \operatorname{error}(f(x_i, \boldsymbol{\theta}), y_i) \\ &= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left(f(x_i, \boldsymbol{\theta}) - y_i \right)^2 \end{split}$$

$$\begin{split} \arg\min_{\pmb{\theta}} \mathcal{L}(\pmb{x}, \pmb{y}, \pmb{\theta}) &= \arg\min_{\pmb{\theta}} \sum_{i=1}^n \operatorname{error}(f(x_i, \pmb{\theta}), y_i) \\ &= \arg\min_{\pmb{\theta}} \sum_{i=1}^n \left(f(x_i, \pmb{\theta}) - y_i\right)^2 \end{split}$$

$$\begin{split} \arg\min_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{x}, \boldsymbol{y}, \boldsymbol{\theta}) &= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^n \operatorname{error}(f(\boldsymbol{x}_i, \boldsymbol{\theta}), y_i) \\ &= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^n \left(f(\boldsymbol{x}_i, \boldsymbol{\theta}) - y_i\right)^2 \end{split}$$

Question: How do we evaluate this expression to find θ ?

$$\begin{split} \arg\min_{\pmb{\theta}} \mathcal{L}(\pmb{x}, \pmb{y}, \pmb{\theta}) &= \arg\min_{\pmb{\theta}} \sum_{i=1}^n \operatorname{error}(f(x_i, \pmb{\theta}), y_i) \\ &= \arg\min_{\pmb{\theta}} \sum_{i=1}^n \left(f(x_i, \pmb{\theta}) - y_i\right)^2 \end{split}$$

Question: How do we evaluate this expression to find θ ?

Answer: Deriving the solution for this objective requires taking partial derivatives of matrices

$$\begin{split} \arg\min_{\pmb{\theta}} \mathcal{L}(\pmb{x}, \pmb{y}, \pmb{\theta}) &= \arg\min_{\pmb{\theta}} \sum_{i=1}^n \operatorname{error}(f(x_i, \pmb{\theta}), y_i) \\ &= \arg\min_{\pmb{\theta}} \sum_{i=1}^n \left(f(x_i, \pmb{\theta}) - y_i\right)^2 \end{split}$$

Question: How do we evaluate this expression to find θ ?

Answer: Deriving the solution for this objective requires taking partial derivatives of matrices

We will derive the solution later. For now, trust me!

$$\begin{split} \arg\min_{\pmb{\theta}} \mathcal{L}(\pmb{x}, \pmb{y}, \pmb{\theta}) &= \arg\min_{\pmb{\theta}} \sum_{i=1}^n \operatorname{error}(f(x_i, \pmb{\theta}), y_i) \\ &= \arg\min_{\pmb{\theta}} \sum_{i=1}^n \left(f(x_i, \pmb{\theta}) - y_i\right)^2 \end{split}$$

Question: How do we evaluate this expression to find θ ?

Answer: Deriving the solution for this objective requires taking partial derivatives of matrices

We will derive the solution later. For now, trust me!

We will go over the steps to find heta

First, we will construct a $\operatorname{\mathbf{design}}$ $\operatorname{\mathbf{matrix}}$ \boldsymbol{X}_D containing input data x

First, we will construct a $\operatorname{\mathbf{design}}$ $\operatorname{\mathbf{matrix}}$ \boldsymbol{X}_D containing input data x

$$m{X}_D = [m{x} \ \ m{1}] = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix}$$

We add the column of ones so that we can multiply X_D with θ to get a linear function $\theta_1 x + \theta_0$ evaluated at each data point

$$egin{aligned} oldsymbol{X}_D oldsymbol{ heta} &= egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix} egin{bmatrix} heta_1 \ heta_0 \ heta_0 \end{bmatrix} = egin{bmatrix} heta_1 x_1 + heta_0 \ heta_1 x_2 + heta_0 \ dots \ heta_1 x_n + heta_0 \end{bmatrix} \ & heta_1 x_2 + heta_0 \ heta_2 \ heta_1 x_2 + heta_0 \ heta_1 x_2 + heta_0 \ heta_2 \ heta_1 x_2 + heta_0 \ heta_2 \ heta_1 x_2 + heta_0 \ heta_2 \ heta$$

We can also evaluate our model for new datapoints

We add the column of ones so that we can multiply X_D with θ to get a linear function $\theta_1 x + \theta_0$ evaluated at each data point

$$m{X}_Dm{ heta} = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix} egin{bmatrix} heta_1 \ heta_0 \ heta_1 \ heta_0 \ heta_1 \ heta_2 + heta_0 \ dots \ heta_1 x_2 + heta_0 \ heta_1 \ heta_1 x_1 + heta_0 \ heta_2 \ heta_1 \ heta_2 \ heta_1 \ heta_2 \ heta_2 \ heta_1 \ heta_2 \ he$$

We can also evaluate our model for new datapoints

$$\boldsymbol{X}_D \boldsymbol{\theta} = \begin{bmatrix} x_{\text{Steven}} & 1 \end{bmatrix} \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix} = \underbrace{[\theta_1 x_{\text{Steven}} + \theta_0]}_{\text{Predicted } y}$$

With our design matrix X_D and desired output y,

$$oldsymbol{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix}, oldsymbol{y} = egin{bmatrix} y_1 \ y_2 \ dots \ y_n \end{bmatrix}$$

With our design matrix X_D and desired output y,

$$oldsymbol{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix}, oldsymbol{y} = egin{bmatrix} y_1 \ y_2 \ dots \ y_n \end{bmatrix}$$

and our parameters θ ,

$$oldsymbol{ heta} = egin{bmatrix} heta_1 \ heta_0 \end{bmatrix},$$

With our design matrix X_D and desired output y,

$$oldsymbol{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix}, oldsymbol{y} = egin{bmatrix} y_1 \ y_2 \ dots \ y_n \end{bmatrix}$$

and our parameters θ ,

$$oldsymbol{ heta} = egin{bmatrix} heta_1 \ heta_0 \end{bmatrix},$$

$$oldsymbol{ heta} = ig(oldsymbol{X}_D^ op oldsymbol{X}_D^ op ig)^{-1} oldsymbol{X}_D^ op oldsymbol{y}$$

(Magic!) We can find the parameters that minimize \mathcal{L}

To summarize:

To summarize:

The θ given by

$$oldsymbol{ heta} = ig(oldsymbol{X}_D^ op oldsymbol{X}_D^ op ig)^{-1} oldsymbol{X}_D^ op oldsymbol{y}$$

Optimization

To summarize:

The heta given by

$$oldsymbol{ heta} = ig(oldsymbol{X}_D^ op oldsymbol{X}_D^ op ig)^{-1} oldsymbol{X}_D^ op oldsymbol{y}$$

Provide the solution to

$$\begin{split} \arg\min_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{x}, \boldsymbol{y}, \boldsymbol{\theta}) &= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \operatorname{error}(f(x_i, \boldsymbol{\theta}), y_i) \\ &= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left(f(x_i, \boldsymbol{\theta}) - y_i \right)^2 \end{split}$$

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Back to the example...

Back to the example...

Task: Given your education, predict your life expectancy

Back to the example...

Task: Given your education, predict your life expectancy

 $X \in \mathbb{R}_+$: Years in school

Back to the example...

Task: Given your education, predict your life expectancy

 $X \in \mathbb{R}_+$: Years in school

 $Y \in \mathbb{R}_+$: Age of death

Back to the example...

Task: Given your education, predict your life expectancy

 $X \in \mathbb{R}_+$: Years in school

 $Y \in \mathbb{R}_+$: Age of death

Approach: Learn the parameters θ such that

$$f(x,\theta) = y; \quad x \in X, y \in Y$$

Back to the example...

Task: Given your education, predict your life expectancy

 $X \in \mathbb{R}_+$: Years in school

 $Y \in \mathbb{R}_+$: Age of death

Approach: Learn the parameters θ such that

$$f(x,\theta) = y; \quad x \in X, y \in Y$$

Goal: Given someone's education, predict how long they will live

Back to the example...

Task: Given your education, predict your life expectancy

 $X \in \mathbb{R}_+$: Years in school

 $Y \in \mathbb{R}_+$: Age of death

Approach: Learn the parameters θ such that

$$f(x,\theta) = y; \quad x \in X, y \in Y$$

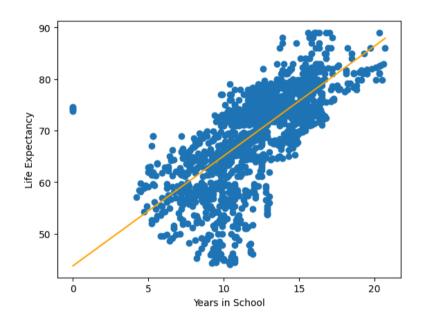
Goal: Given someone's education, predict how long they will live

You will be doing this in your first assignment!

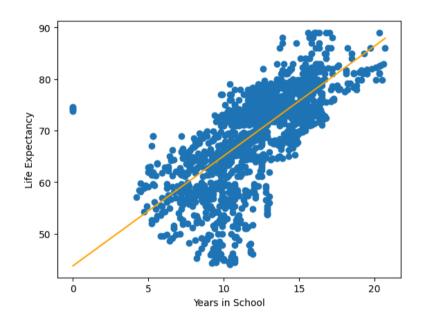
Plot the datapoints $(x_1, y_1), (x_2, y_2), \dots$

Plot the datapoints $(x_1, y_1), (x_2, y_2), \dots$

Plot the datapoints $(x_1, y_1), (x_2, y_2), \dots$



Plot the datapoints $(x_1, y_1), (x_2, y_2), \dots$



- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Relax

Task: Given your education, predict your life expectancy

Task: Given your education, predict your life expectancy

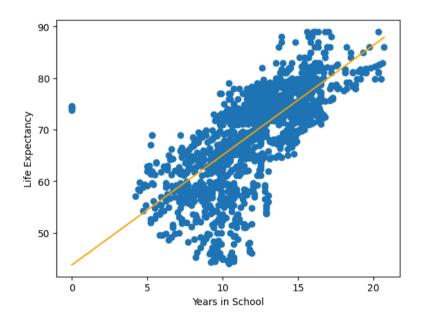
Plot the datapoints $(x_1, y_1), (x_2, y_2), \dots$

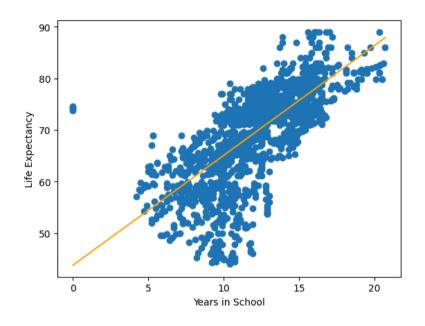
Task: Given your education, predict your life expectancy

Plot the datapoints $(x_1, y_1), (x_2, y_2), \dots$

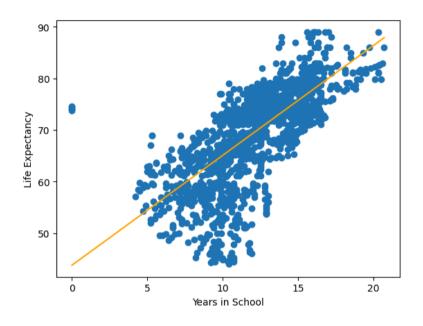
Task: Given your education, predict your life expectancy

Plot the datapoints $(x_1, y_1), (x_2, y_2), \dots$





We figured out linear regression!



We figured out linear regression!

But can we do better?

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

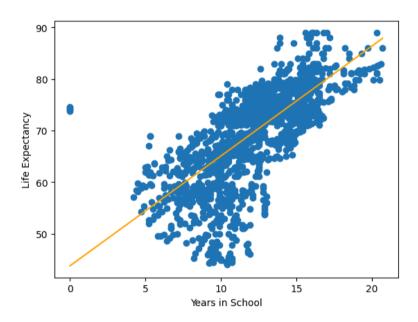
Question:

Question:

Does the data look linear?

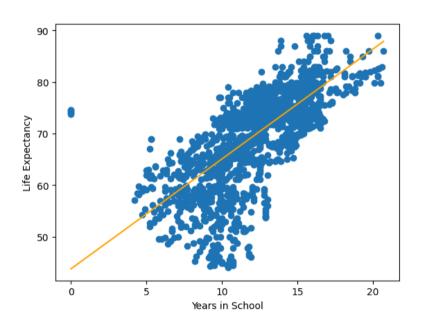
Question:

Does the data look linear?



Question:

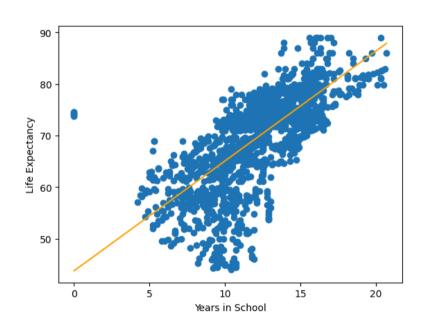
Does the data look linear?



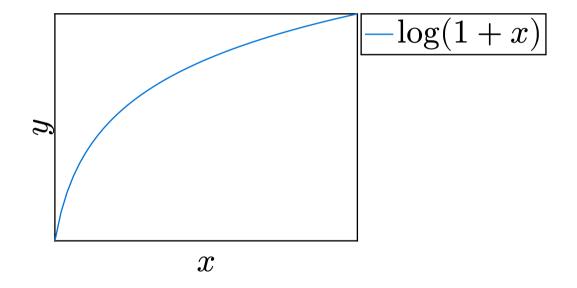
Or maybe more logarithmic?

Question:

Does the data look linear?

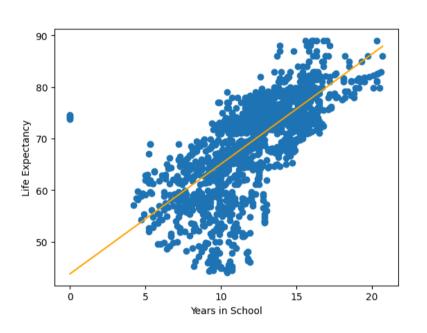


Or maybe more logarithmic?

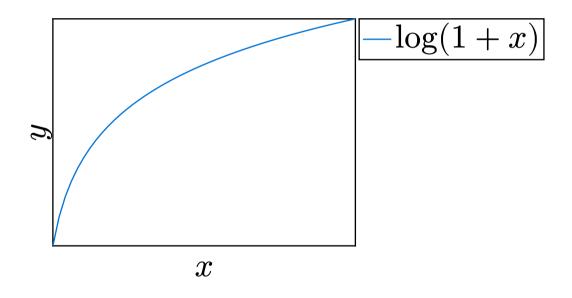


Question:

Does the data look linear?



Or maybe more logarithmic?



However, linear regression must be linear!

Question: What does it mean when we say linear regression is linear?

Question: What does it mean when we say linear regression is linear?

Answer: The function $f(x, \theta)$ is a linear function of x

Question: What does it mean when we say linear regression is linear?

Answer: The function $f(x, \theta)$ is a linear function of x

Trick: Change of variables to make f nonlinear: $x_{\text{new}} = \log(1 + x_{\text{data}})$

Question: What does it mean when we say linear regression is linear?

Answer: The function $f(x, \theta)$ is a linear function of x

Trick: Change of variables to make f nonlinear: $x_{\text{new}} = \log(1 + x_{\text{data}})$

$$m{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix} \Rightarrow m{X}_D = egin{bmatrix} \log(1+x_1) & 1 \ \log(1+x_2) & 1 \ dots & dots \ \log(1+x_n) & 1 \end{bmatrix}$$

Now, f is a linear function of log(1+x) – a nonlinear function of x!

New design matrix...

$$\boldsymbol{X}_D = \begin{bmatrix} \log(1+x_1) & 1 \\ \log(1+x_2) & 1 \\ \vdots & \vdots \\ \log(1+x_n) & 1 \end{bmatrix}$$

New function...

$$f\left(x, \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}\right) = \theta_1 \log(1+x) + \theta_0$$

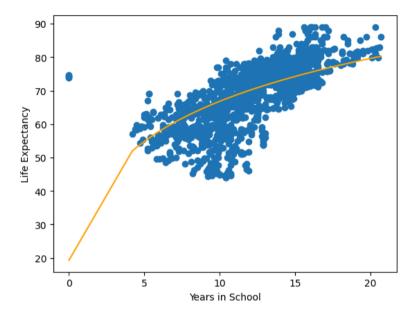
New design matrix...

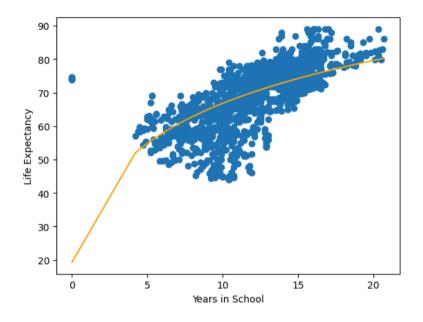
$$\boldsymbol{X}_{D} = \begin{bmatrix} \log(1 + x_{1}) & 1 \\ \log(1 + x_{2}) & 1 \\ \vdots & \vdots \\ \log(1 + x_{n}) & 1 \end{bmatrix}$$

New function...

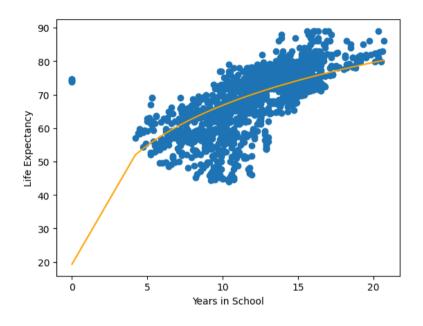
Same solution...

$$f\!\left(x, \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}\right) = \theta_1 \log(1+x) + \theta_0 \qquad \qquad \boldsymbol{\theta} = \left(\boldsymbol{X}_D^\top \boldsymbol{X}_D\right)^{-1} \boldsymbol{X}_D^\top \boldsymbol{y}$$





Better, but still not perfect



Better, but still not perfect

Can we do even better?

What about polynomials?

What about polynomials?

$$f(x) = ax^{m} + bx^{m-1} + \dots + cx + d$$

What about polynomials?

$$f(x) = ax^m + bx^{m-1} + \dots + cx + d$$

Polynomials can approximate **any** function (universal function approximator)

What about polynomials?

$$f(x) = ax^m + bx^{m-1} + \dots + cx + d$$

Polynomials can approximate **any** function (universal function approximator)

Can we extend linear regression to polynomials?

Expand x to a multi-dimensional input space...

Expand x to a multi-dimensional input space...

$$m{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix} \Rightarrow m{X}_D = egin{bmatrix} x_1^m & x_1^{m-1} & \dots & x_1 & 1 \ x_2^m & x_2^{m-1} & \dots & x_2 & 1 \ dots & dots & \ddots & \ x_n^m & x_n^{m-1} & \dots & x_n & 1 \end{bmatrix}$$

Expand x to a multi-dimensional input space...

$$m{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix} \Rightarrow m{X}_D = egin{bmatrix} x_1^m & x_1^{m-1} & \dots & x_1 & 1 \ x_2^m & x_2^{m-1} & \dots & x_2 & 1 \ dots & dots & \ddots & \ x_n^m & x_n^{m-1} & \dots & x_n & 1 \end{bmatrix}$$

Remember, n datapoints and m+1 polynomial terms

Expand x to a multi-dimensional input space...

$$m{X}_D = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_n & 1 \end{bmatrix} \Rightarrow m{X}_D = egin{bmatrix} x_1^m & x_1^{m-1} & \dots & x_1 & 1 \ x_2^m & x_2^{m-1} & \dots & x_2 & 1 \ dots & dots & \ddots & \ x_n^m & x_n^{m-1} & \dots & x_n & 1 \end{bmatrix}$$

Remember, n datapoints and m+1 polynomial terms

And add some new parameters...

$$oldsymbol{ heta} = \left[eta_1 \;\; heta_0
ight]^{ op} \Rightarrow oldsymbol{ heta} = \left[eta_m \;\; heta_{m-1} \;\; ... \;\; eta_1 \;\; eta_0
ight]^{ op}$$

$$\boldsymbol{X}_{D}\boldsymbol{\theta} = \underbrace{\begin{bmatrix} x_{1}^{m} & x_{1}^{m-1} & \dots & x_{1} & 1 \\ x_{2}^{m} & x_{2}^{m-1} & \dots & x_{2} & 1 \\ \vdots & \vdots & \ddots & & \vdots \\ x_{n}^{m} & x_{n}^{m-1} & \dots & x_{n} & 1 \end{bmatrix}}_{n \times (m+1)} \underbrace{\begin{bmatrix} \theta_{m} \\ \theta_{m-1} \\ \vdots \\ \theta_{0} \end{bmatrix}}_{(m+1) \times 1} = \underbrace{\begin{bmatrix} \theta_{m} x_{1}^{m} + \theta_{m-1} x_{1}^{m-1} + \dots + \theta_{0} \\ \theta_{m} x_{2} + \theta_{m-1} x_{2}^{m-1} + \dots + \theta_{0} \\ \vdots \\ \theta_{n} x_{n}^{m} + \theta_{m-1} x_{n}^{m-1} + \dots + \theta_{0} \end{bmatrix}}_{\text{Y prediction, } n \times 1}$$

$$\boldsymbol{X}_{D}\boldsymbol{\theta} = \underbrace{\begin{bmatrix} x_{1}^{m} & x_{1}^{m-1} & \dots & x_{1} & 1 \\ x_{2}^{m} & x_{2}^{m-1} & \dots & x_{2} & 1 \\ \vdots & \vdots & \ddots & & \vdots \\ x_{n}^{m} & x_{n}^{m-1} & \dots & x_{n} & 1 \end{bmatrix}}_{n \times (m+1)} \underbrace{\begin{bmatrix} \theta_{m} \\ \theta_{m-1} \\ \vdots \\ \theta_{0} \end{bmatrix}}_{(m+1) \times 1} = \underbrace{\begin{bmatrix} \theta_{m} x_{1}^{m} + \theta_{m-1} x_{1}^{m-1} + \dots + \theta_{0} \\ \theta_{m} x_{2} + \theta_{m-1} x_{2}^{m-1} + \dots + \theta_{0} \\ \vdots \\ \theta_{n} x_{n}^{m} + \theta_{m-1} x_{n}^{m-1} + \dots + \theta_{0} \end{bmatrix}}_{\text{Y prediction, } n \times 1}$$

New function...
$$f(x, \boldsymbol{\theta}) = \theta_m x^m + \theta_{m-1} x^{m-1}, ..., \theta_1 + x^1 + \theta_0$$

$$\boldsymbol{X}_{D}\boldsymbol{\theta} = \underbrace{\begin{bmatrix} x_{1}^{m} & x_{1}^{m-1} & \dots & x_{1} & 1 \\ x_{2}^{m} & x_{2}^{m-1} & \dots & x_{2} & 1 \\ \vdots & \vdots & \ddots & & \vdots \\ x_{n}^{m} & x_{n}^{m-1} & \dots & x_{n} & 1 \end{bmatrix}}_{n \times (m+1)} \underbrace{\begin{bmatrix} \theta_{m} \\ \theta_{m-1} \\ \vdots \\ \theta_{0} \end{bmatrix}}_{(m+1) \times 1} = \underbrace{\begin{bmatrix} \theta_{m} x_{1}^{m} + \theta_{m-1} x_{1}^{m-1} + \dots + \theta_{0} \\ \theta_{m} x_{2} + \theta_{m-1} x_{2}^{m-1} + \dots + \theta_{0} \\ \vdots \\ \theta_{n} x_{n}^{m} + \theta_{m-1} x_{n}^{m-1} + \dots + \theta_{0} \end{bmatrix}}_{\text{Y prediction, } n \times 1}$$

New function...
$$f(x, \theta) = \theta_m x^m + \theta_{m-1} x^{m-1}, ..., \theta_1 + x^1 + \theta_0$$

Same solution...
$$\boldsymbol{\theta} = \left(\boldsymbol{X}_D^{\top} \boldsymbol{X}_D \right)^{-1} \boldsymbol{X}_D^{\top} \boldsymbol{y}$$

$$f(x, \theta) = \theta_m x^m + \theta_{m-1} x^{m-1}, ..., \theta_1 + x^1 + \theta_0$$

$$f(x, \theta) = \theta_m x^m + \theta_{m-1} x^{m-1}, ..., \theta_1 + x^1 + \theta_0$$

Summary: By changing the input space, we can fit a polynomial to the data using a linear fit!

Linear Regression

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Linear Regression

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

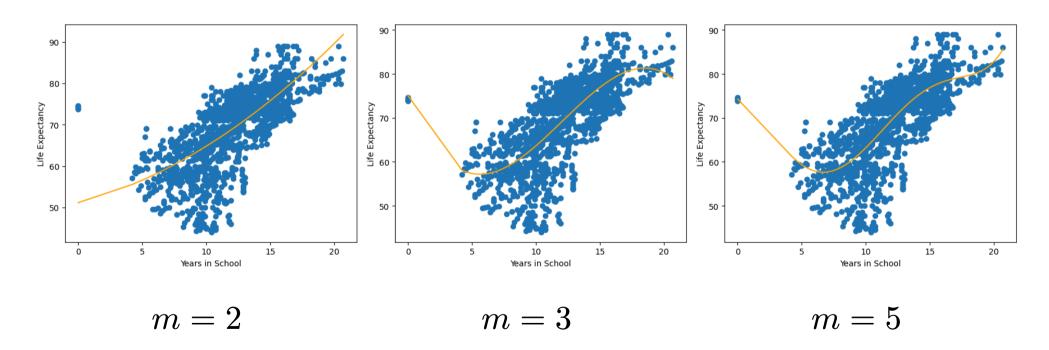
$$f(x, \theta) = \theta_n x^m + \theta_{m-1} x^{m-1}, ..., \theta_1 + x^1 + \theta_0$$

$$f(x, \theta) = \theta_n x^m + \theta_{m-1} x^{m-1}, ..., \theta_1 + x^1 + \theta_0$$

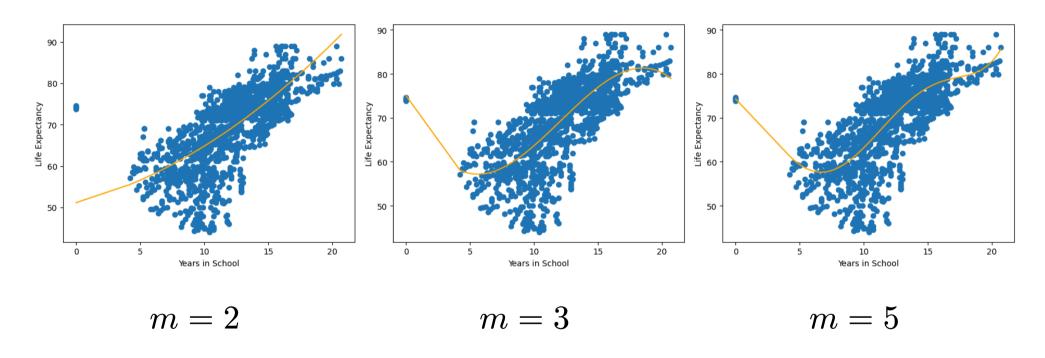
How do we choose m (polynomial order) that provides the best fit?

$$f(x, \theta) = \theta_n x^m + \theta_{m-1} x^{m-1}, ..., \theta_1 + x^1 + \theta_0$$

How do we choose m (polynomial order) that provides the best fit?

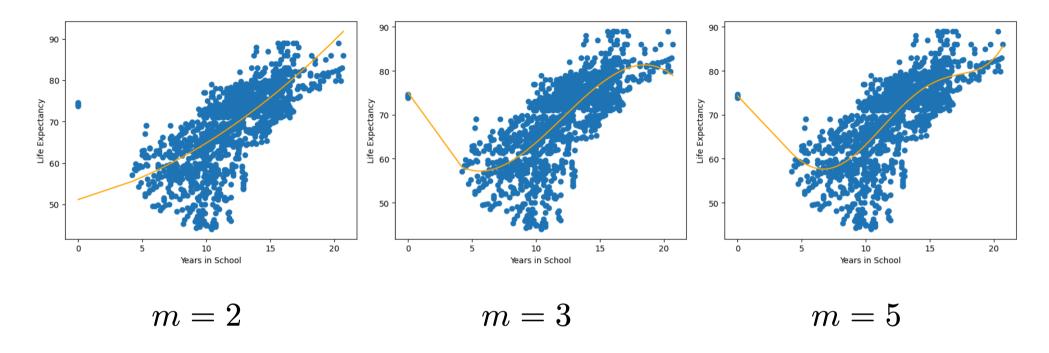


How do we choose n (polynomial order) that provides the best fit?

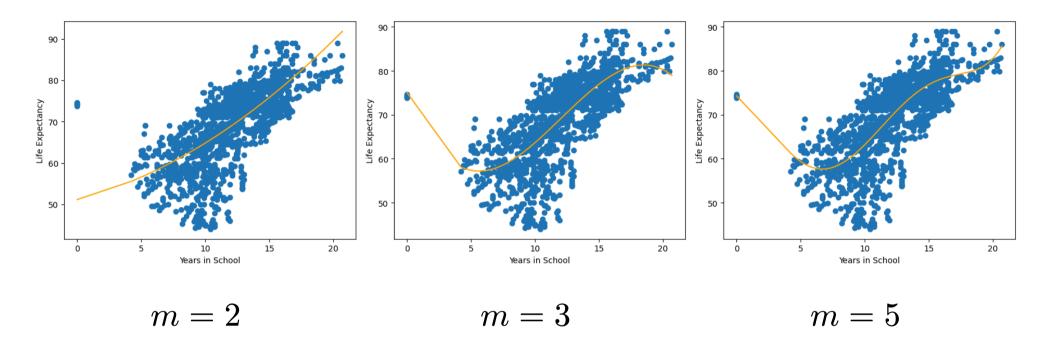


Pick the m with the smallest loss

$$\operatorname*{arg\ min}_{\boldsymbol{\theta},m} \mathcal{L}(\boldsymbol{x},\boldsymbol{y},(\boldsymbol{\theta},m))$$

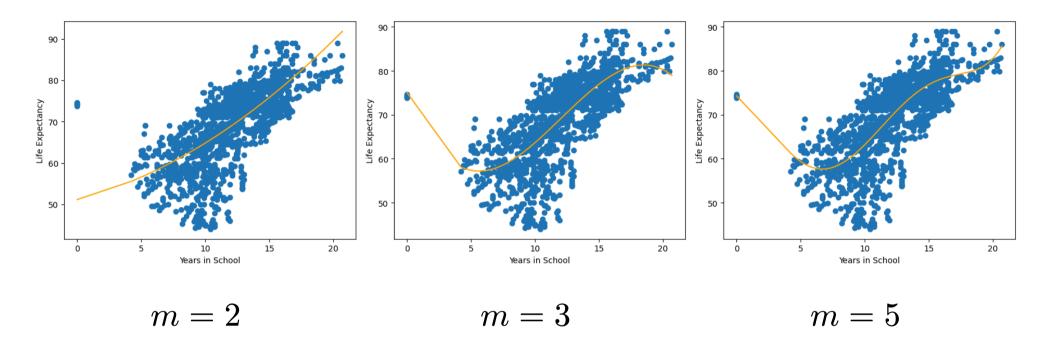


Question: Which m do you think has the smallest loss?

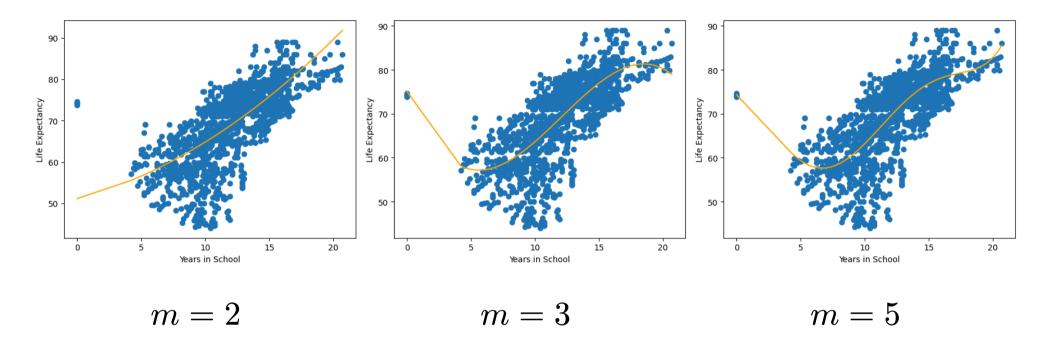


Question: Which m do you think has the smallest loss?

Answer: m=5, but intuitively, m=5 does not seem very good...

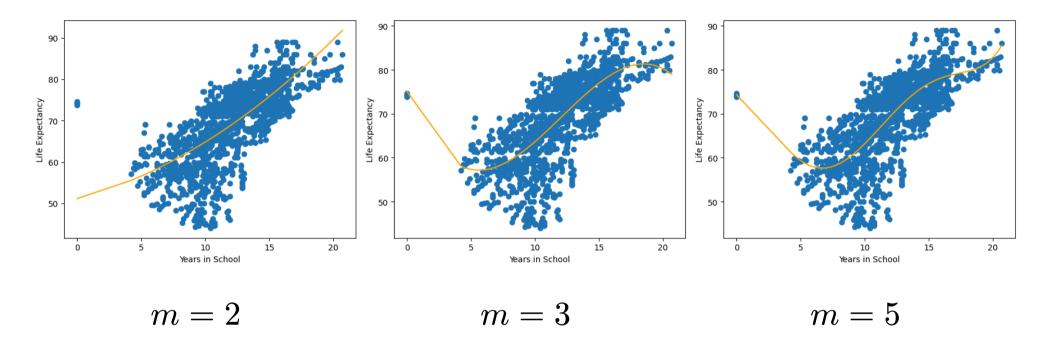


More specifically, m=5 will not generalize to new data



More specifically, m=5 will not generalize to new data

We will only use our model for new data (we already have the y for a known x)!



More specifically, m=5 will not generalize to new data

We will only use our model for new data (we already have the y for a known x)!

When our model has a small loss but does not generalize to new data, we call it **overfitting**

When our model has a small loss but does not generalize to new data, we call it **overfitting**

The model has fit too closely to the sampled data points, rather than the trend

When our model has a small loss but does not generalize to new data, we call it **overfitting**

The model has fit too closely to the sampled data points, rather than the trend

Models that overfit are not useful for making predictions

When our model has a small loss but does not generalize to new data, we call it **overfitting**

The model has fit too closely to the sampled data points, rather than the trend

Models that overfit are not useful for making predictions

Back to the question...

When our model has a small loss but does not generalize to new data, we call it **overfitting**

The model has fit too closely to the sampled data points, rather than the trend

Models that overfit are not useful for making predictions

Back to the question...

Question: How do we choose m such that our polynomial model works for unseen/new data?

When our model has a small loss but does not generalize to new data, we call it **overfitting**

The model has fit too closely to the sampled data points, rather than the trend

Models that overfit are not useful for making predictions

Back to the question...

Question: How do we choose m such that our polynomial model works for unseen/new data?

Answer: Compute the loss on unseen data!

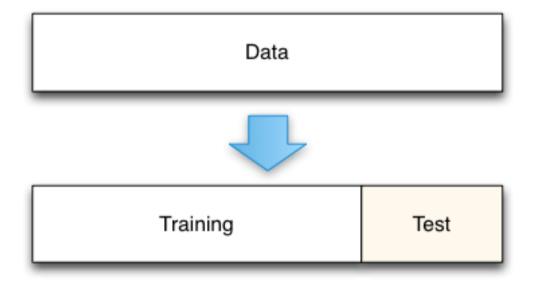
To compute the loss on unseen data, we will need unseen data

To compute the loss on unseen data, we will need unseen data

Let us create some unseen data!

To compute the loss on unseen data, we will need unseen data

Let us create some unseen data!



Question: How do we choose the training and testing datasets?

Question: How do we choose the training and testing datasets?

Option 1:
$$m{x}_{ ext{train}} = egin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} m{y}_{ ext{train}} = egin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}; \quad m{x}_{ ext{test}} = egin{bmatrix} x_4 \\ x_5 \end{bmatrix} m{y}_{ ext{test}} = egin{bmatrix} y_4 \\ y_5 \end{bmatrix}$$

Question: How do we choose the training and testing datasets?

Option 1:
$$m{x}_{ ext{train}} = egin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} m{y}_{ ext{train}} = egin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}; \quad m{x}_{ ext{test}} = egin{bmatrix} x_4 \\ x_5 \end{bmatrix} m{y}_{ ext{test}} = egin{bmatrix} y_4 \\ y_5 \end{bmatrix}$$

Option 2:
$$m{x}_{\mathrm{train}} = egin{bmatrix} x_4 \\ x_1 \\ x_3 \end{bmatrix} m{y}_{\mathrm{train}} = egin{bmatrix} y_4 \\ y_1 \\ y_3 \end{bmatrix}; \quad m{x}_{\mathrm{test}} = egin{bmatrix} x_2 \\ x_5 \end{bmatrix} m{y}_{\mathrm{test}} = egin{bmatrix} y_2 \\ y_5 \end{bmatrix}$$

Question: How do we choose the training and testing datasets?

Option 1:
$$m{x}_{ ext{train}} = egin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} m{y}_{ ext{train}} = egin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}; \quad m{x}_{ ext{test}} = egin{bmatrix} x_4 \\ x_5 \end{bmatrix} m{y}_{ ext{test}} = egin{bmatrix} y_4 \\ y_5 \end{bmatrix}$$

Option 2:
$$\boldsymbol{x}_{\text{train}} = \begin{bmatrix} x_4 \\ x_1 \\ x_3 \end{bmatrix} \boldsymbol{y}_{\text{train}} = \begin{bmatrix} y_4 \\ y_1 \\ y_3 \end{bmatrix}$$
; $\boldsymbol{x}_{\text{test}} = \begin{bmatrix} x_2 \\ x_5 \end{bmatrix} \boldsymbol{y}_{\text{test}} = \begin{bmatrix} y_2 \\ y_5 \end{bmatrix}$

Answer: Always shuffle the data

Question: How do we choose the training and testing datasets?

Option 1:
$$m{x}_{ ext{train}} = egin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} m{y}_{ ext{train}} = egin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}; \quad m{x}_{ ext{test}} = egin{bmatrix} x_4 \\ x_5 \end{bmatrix} m{y}_{ ext{test}} = egin{bmatrix} y_4 \\ y_5 \end{bmatrix}$$

Option 2:
$$m{x}_{ ext{train}} = egin{bmatrix} x_4 \\ x_1 \\ x_3 \end{bmatrix} m{y}_{ ext{train}} = egin{bmatrix} y_4 \\ y_1 \\ y_3 \end{bmatrix}; \quad m{x}_{ ext{test}} = egin{bmatrix} x_2 \\ x_5 \end{bmatrix} m{y}_{ ext{test}} = egin{bmatrix} y_2 \\ y_5 \end{bmatrix}$$

Answer: Always shuffle the data

Note: The model must never see the testing dataset during training. This is very important!

We can now measure how the model generalizes to new data

We can now measure how the model generalizes to new data



Learn parameters from the train dataset, evaluate on the test dataset

We can now measure how the model generalizes to new data



Learn parameters from the train dataset, evaluate on the test dataset

$$\mathcal{L}(oldsymbol{X}_{ ext{train}}, oldsymbol{y}_{ ext{train}}, oldsymbol{ heta})$$

$$\mathcal{L}(oldsymbol{X}_{ ext{test}}, oldsymbol{y}_{ ext{test}}, oldsymbol{ heta})$$

We use separate training and testing datasets on **all** machine learning models, not just linear regression

We use separate training and testing datasets on **all** machine learning models, not just linear regression

Linear Regression

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Linear Regression

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Q: When should we use test and train splits?

Q: When should we use test and train splits?

Q: Are neural networks more powerful than linear regression?

Q: When should we use test and train splits?

Q: Are neural networks more powerful than linear regression?

Q: Why would we want to use linear regression instead of neural networks?

Q: When should we use test and train splits?

Q: Are neural networks more powerful than linear regression?

Q: Why would we want to use linear regression instead of neural networks?

Q: What are interesting problems that we can apply linear regression to?

Q: When should we use test and train splits?

Q: Are neural networks more powerful than linear regression?

Q: Why would we want to use linear regression instead of neural networks?

Q: What are interesting problems that we can apply linear regression to?

Q: We use a squared error loss. What effect does this have on outliers?

Q: When should we use test and train splits?

Q: Are neural networks more powerful than linear regression?

Q: Why would we want to use linear regression instead of neural networks?

Q: What are interesting problems that we can apply linear regression to?

Q: We use a squared error loss. What effect does this have on outliers?

Linear Regression

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Linear Regression

- 1. Define an example problem
- 2. Define our linear model f
- 3. Define a loss function \mathcal{L}
- 4. Use \mathcal{L} to learn the parameters θ of f
- 5. Solve the example problem
- 6. Expand to nonlinear models
- 7. Discuss overfitting
- 8. Interactive discussion
- 9. Homework summary

Tips for assignment 1

```
Tips for assignment 1

def f(theta, design):
    # Linear function
    return design @ theta
```

```
Tips for assignment 1

def f(theta, design):
    # Linear function
    return design @ theta
```

Not all matrices can be inverted! Ensure the matrices are square and the condition number is low

```
A.shape
cond = jax.numpy.linalg.cond(A)
```

```
Tips for assignment 1

def f(theta, design):
    # Linear function
    return design @ theta
```

Not all matrices can be inverted! Ensure the matrices are square and the condition number is low

```
A.shape
cond = jax.numpy.linalg.cond(A)
```

Everything you need is in the lecture notes

https://colab.research.google.com/drive/1I6YgapkfaU71RdOotaTPLYdX9 WflV1me