# Classification

CISC 7026: Introduction to Deep Learning

University of Macau

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I am still grading quiz 2, but I had a look at the responses to question 4

Some requests from students:

1. More coding, less theory

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There are conflicting student needs

- 1. Review
- 2. Torch optimization coding
- 3. Classification task
- 4. Probability review
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and gradients

$$\nabla_{\boldsymbol{x}} f \left( \begin{bmatrix} x_1 & x_2 & \dots & x_n \end{bmatrix}^\top \right) = \begin{bmatrix} \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \dots & \frac{\partial f}{\partial x_n} \end{bmatrix}^\top$$

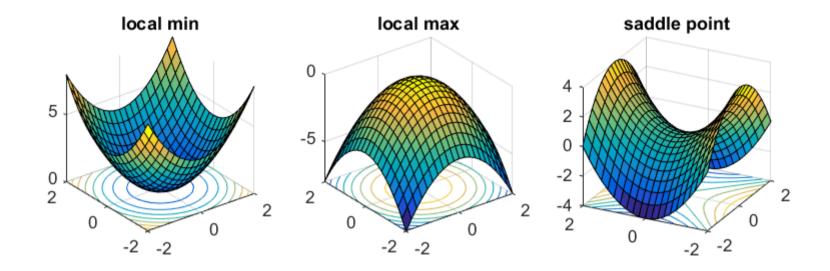
Gradients are important in deep learning for two reasons:

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**Reason 1**: f(x) has critical points at  $\nabla_x f(x) = 0$ 

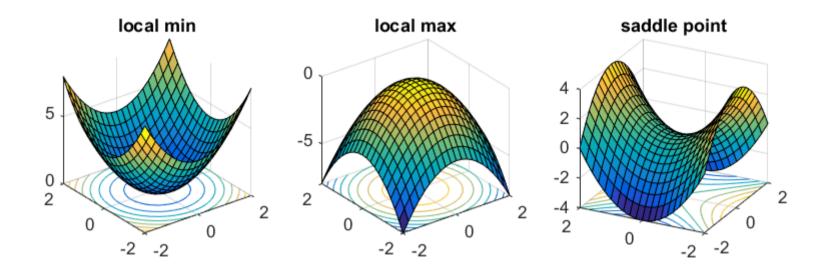
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With optimization, we attempt to find minima of loss functions

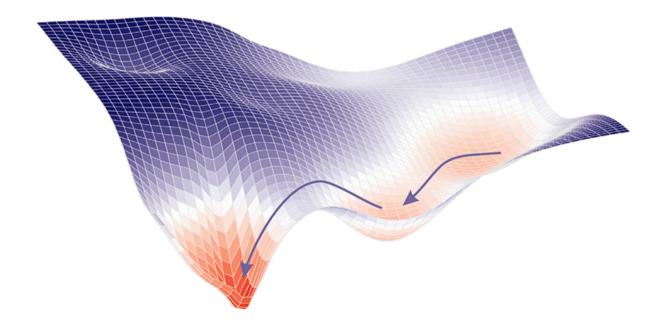
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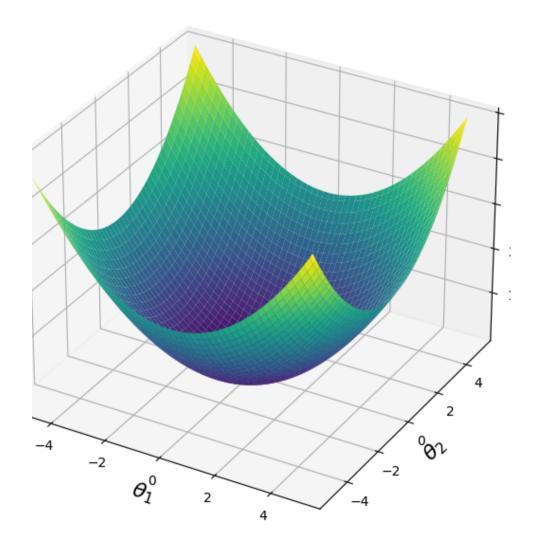
$$\mathcal{L}(oldsymbol{X},oldsymbol{Y},oldsymbol{ heta}) = \sum_{i=1}^n \left(fig(oldsymbol{x}_{[i]},oldsymbol{ heta}ig) - oldsymbol{y}_{[i]}
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$$\mathcal{L}(\boldsymbol{X},\boldsymbol{Y},\boldsymbol{\theta}) = (\boldsymbol{Y} - \boldsymbol{X}_D\boldsymbol{\theta})^\top (\boldsymbol{Y} - \boldsymbol{X}_D\boldsymbol{\theta})$$

$$egin{aligned} \mathcal{L}(m{X},m{Y},m{ heta}) &= \sum_{i=1}^n \left(fig(m{x}_{[i]},m{ heta}ig) - m{y}_{[i]}ig)^2 \ & \mathcal{L}(m{X},m{Y},m{ heta}) &= (m{Y} - m{X}_Dm{ heta})^ op (m{Y} - m{X}_Dm{ heta}) \ & \mathcal{L}(m{X},m{Y},m{ heta}) &= \underbrace{(m{Y} - m{X}_Dm{ heta})^ op}_{ ext{Linear function of }m{ heta}} \underbrace{(m{Y} - m{X}_Dm{ heta})}_{ ext{Linear function of }m{ heta}} \end{aligned}$$

A quadratic function has a single critical point, which must be a global minimum



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Which solves

$$rg\min_{oldsymbol{ heta}} \mathcal{L}(oldsymbol{X}, oldsymbol{Y}, oldsymbol{ heta})$$

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Loss function

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$$\mathcal{L}(x, y, \boldsymbol{\theta}) = (f(x, \boldsymbol{\theta}) - y)^2$$

 $f(x, \boldsymbol{\theta}) = \sigma(\theta_0 + \theta_1 x)$ 

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Neural network model

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There is no analytical solution for heta

Instead, we found the parameters of a neural network through gradient descent

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Gradient descent is an optimization method for differentiable functions

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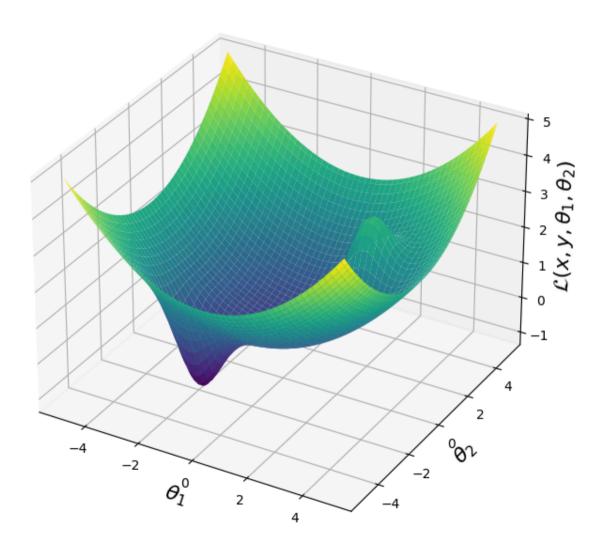
Gradient descent is an optimization method for differentiable functions

We went over both the intuition and mathematical definitions









The gradient descent algorithm:

```
1:function Gradient Descent(\boldsymbol{X}, \boldsymbol{Y}, \mathcal{L}, t, \alpha)
```

- 2: > Randomly initialize parameters
- 3:  $\theta \leftarrow \mathcal{N}(0,1)$
- 4: **for**  $i \in 1...t$  **do**
- 5: Compute the gradient of the loss
- 6:  $\boldsymbol{J} \leftarrow \nabla_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{X}, \boldsymbol{Y}, \boldsymbol{\theta})$
- 7: b Update the parameters using the negative gradient
- 8:  $\boldsymbol{\theta} \leftarrow \boldsymbol{\theta} \alpha \boldsymbol{J}$
- 9: return  $\theta$

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abla}_{oldsymbol{ heta}}f(oldsymbol{x},[oldsymbol{\phi}\ \psi\ ...\ oldsymbol{\xi}]^{ op}) = egin{bmatrix} 
abla_{oldsymbol{\phi}}f_1(oldsymbol{x},oldsymbol{arphi}) \ 
abla_{oldsymbol{\psi}}f_2(oldsymbol{z}_1,oldsymbol{\psi}) \ 
& arphi \ 
abla_{oldsymbol{\psi}}f_2(oldsym$$

$$\nabla_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{X}, \boldsymbol{Y}, \boldsymbol{\theta}) = \sum_{i=1}^{n} 2 \Big( f \Big( \boldsymbol{x}_{[i]}, \boldsymbol{\theta} \Big) - \boldsymbol{y}_{[i]} \Big) \nabla_{\boldsymbol{\theta}} f \Big( \boldsymbol{x}_{[i]}, \boldsymbol{\theta} \Big)$$

$$\begin{aligned} \nabla_{\boldsymbol{\theta}} f(\boldsymbol{x}, \boldsymbol{\theta}) &= \nabla_{\boldsymbol{\varphi}, \boldsymbol{\psi}, \dots, \boldsymbol{\xi}} f \big( \boldsymbol{x}, \left[ \boldsymbol{\varphi} \;\; \boldsymbol{\psi} \;\; \dots \; \boldsymbol{\xi} \right]^{\top} \big) = \begin{bmatrix} \nabla_{\boldsymbol{\varphi}} f_1(\boldsymbol{x}, \boldsymbol{\varphi}) \\ \nabla_{\boldsymbol{\psi}} f_2(\boldsymbol{z}_1, \boldsymbol{\psi}) \\ \vdots \\ \nabla_{\boldsymbol{\xi}} f_{\ell}(\boldsymbol{z}_{\ell-1}, \boldsymbol{\xi}) \end{bmatrix} \end{aligned}$$

$$\nabla_{\pmb{\xi}} f_{\ell}(\pmb{z}_{\ell-1}, \pmb{\xi}) = \left(\sigma(\pmb{\xi}^{\top} \overline{\pmb{z}}_{\ell-1}) \odot \left(1 - \sigma(\pmb{\xi}^{\top} \overline{\pmb{z}}_{\ell-1})\right)\right) \overline{\pmb{z}}_{\ell-1}^{\top}$$

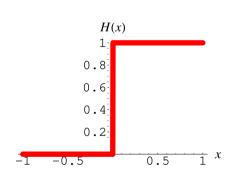
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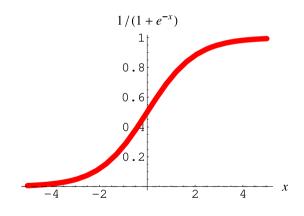
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$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

In jax, we compute the gradient using the jax.grad function

In jax, we compute the gradient using the jax.grad function import jax def L(theta, X, Y): # Create a new function that is the gradient of L # Then compute gradient of L for given inputs J = jax.grad(L)(X, Y, theta)# Update parameters alpha = 0.0001theta = theta - alpha \* J

In torch, we backpropagate through a graph of operations import torch optimizer = torch.optim.SGD(lr=0.0001) def L(model, X, Y): # Pytorch will record a graph of all operations # Everytime you do theta @ x, it stores inputs and outputs loss = L(X, Y, model) # compute loss # Traverse the graph backward and compute the gradient loss.backward() # Sets .grad attribute on each parameter optimizer.step() # Update the parameters using .grad optimizer.zero grad() # Set .grad to zero, DO NOT FORGET!!

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First, a video of one application of gradient descent

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Time for some interactive coding

https://colab.research.google.com/drive/1W8WVZ8n\_9yJCcOqkPVURp\_wJUx3EQc5w

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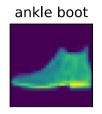
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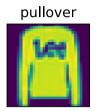
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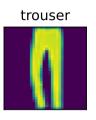
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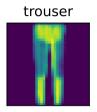
So far, we only looked at regression. Now, let us look at classification

 $X:\mathbb{Z}_{0,255}^{32 imes32}$ 

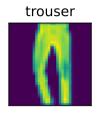


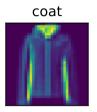


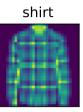






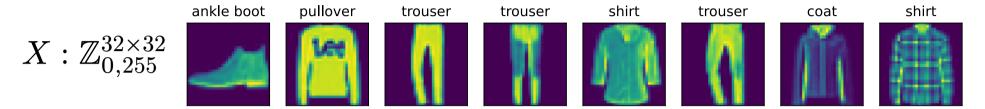






 $X: \mathbb{Z}_{0,255}^{32 imes 32}$  ankle boot pullover trouser trouser shirt trouser coat shirt  $X: \mathbb{Z}_{0,255}^{32 imes 32}$ 

Y: {T-shirt, Trouser, Pullover, Dress, Coat,Sandal, Shirt, Sneaker, Bag, Ankle boot}



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**Approach:** Learn  $\theta$  that produce **conditional probabilities** 

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### **Approach:** Learn $\theta$ that produce **conditional probabilities**

$$f(\boldsymbol{x}, \boldsymbol{\theta}) = P(\boldsymbol{y} \mid \boldsymbol{x}) = P\left(\begin{bmatrix} \text{T-Shirt} \\ \text{Trouser} \\ \vdots \end{bmatrix} \middle| \boldsymbol{x} \right) = \begin{bmatrix} 0.2 \\ 0.01 \\ \vdots \end{bmatrix}$$

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An experiment yields one of many possible outcomes

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An experiment yields one of many possible outcomes

Experiment

Outcome

In probability, we have **experiments** and **outcomes** 

An experiment yields one of many possible outcomes

Experiment

Outcome

Flip a coin

Heads

In probability, we have **experiments** and **outcomes** 

An experiment yields one of many possible outcomes

**Experiment** Outcome

Flip a coin Heads

Walk outside Rain

In probability, we have **experiments** and **outcomes** 

An experiment yields one of many possible outcomes

Experiment Outcome

Flip a coin Heads

Walk outside Rain

Grab clothing from closest Coat

In probability, we have **experiments** and **outcomes** 

An experiment yields one of many possible outcomes

Experiment Outcome

Flip a coin Heads

Walk outside Rain

Grab clothing from closest Coat

# The **sample space** S defines all possible outcomes for an experiment Experiment Sample Space S

Experiment

Sample Space S

$$S = \{\text{heads, tails}\}$$

Experiment

Sample Space S

Flip a coin

 $S = \{\text{heads, tails}\}$ 

Walk outside

 $S = \{\text{rain}, \text{sun}, \text{wind}, \text{cloud}\}$ 

Experiment

Sample Space S

Flip a coin

 $S = \{\text{heads, tails}\}$ 

Walk outside

 $S = \{\text{rain}, \text{sun}, \text{wind}, \text{cloud}\}$ 

Take clothing from closet

 $S = \{ \text{T-shirt}, \text{Trouser}, \text{Pullover}, \text{Dress}, \\ \text{Coat}, \text{Sandal}, \text{Shirt}, \text{Sneaker}, \text{Bag}, \\ \text{Ankle boot} \}$ 

Experiment

Sample Space

**Event** 

$$S = \{\text{heads, tails}\}$$

$$E = \{\text{heads}\}$$

Experiment

Sample Space

Event

Flip a coin

$$S = \{\text{heads, tails}\}$$

$$E = \{\text{heads}\}$$

Walk outside

$$S = \{\text{rain}, \text{sun}, \text{wind}, \text{cloud}\}\ E = \{\text{rain}, \text{wind}\}\$$

Experiment

Sample Space

Event

Flip a coin

$$S = \{\text{heads}, \text{tails}\}$$

$$E = \{\text{heads}\}$$

Walk outside

$$S = \{\text{rain}, \text{sun}, \text{wind}, \text{cloud}\}\ E = \{\text{rain}, \text{wind}\}\$$

{T-shirt, Trouser,

Take from closet

$$\frac{\text{Pullover, Dress,}}{\text{Coat, Sandal, Shirt,}}E = \{\text{Shirt, T-Shirt, Coat}\}$$

Sneaker, Bag, Ankle boot}

The probability must be between 0 (never occurs) and 1 (always occurs)

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$$0 \le P(A) \le 1; \quad \forall A \in S$$

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Experiment

Probabilities

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Experiment

Probabilities

$$P(\text{heads}) = 0.5$$

The probability must be between 0 (never occurs) and 1 (always occurs)

$$0 \le P(A) \le 1; \quad \forall A \in S$$

Experiment

Probabilities

Flip a coin

P(heads) = 0.5

Walk outside

P(rain) = 0.15

The probability must be between 0 (never occurs) and 1 (always occurs)

$$0 \le P(A) \le 1; \quad \forall A \in S$$

Experiment

Flip a coin

Walk outside

Take from closet

**Probabilities** 

$$P(\text{heads}) = 0.5$$

$$P(\text{rain}) = 0.15$$

$$P(Shirt) = 0.1$$

$$P: E \mapsto (0,1)$$

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The probabilities (distribution) must sum to one

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$$\sum_{x \in E} P(x) = 1$$

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Flip a coin

$$\{P(\text{heads}) = 0.5, P(\text{tails}) = 0.5\}$$

$$P: E \mapsto (0,1)$$

The probabilities (distribution) must sum to one

$$\sum_{x \in E} P(x) = 1$$

Flip a coin

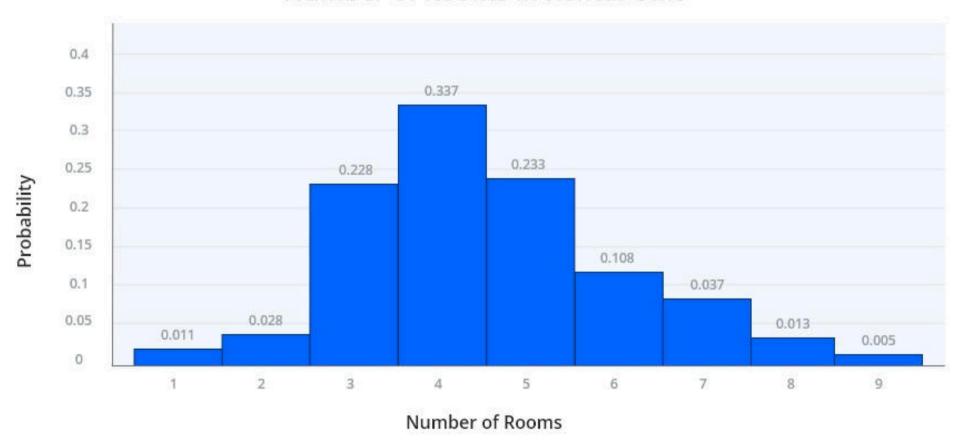
Take clothing from closet

$$\{P(\text{heads}) = 0.5, P(\text{tails}) = 0.5\}$$

$$\{P(\text{T-shirt}) = 0.1, P(\text{Trouser}) = 0.08,$$
 
$$P(\text{Pullover}) = 0.12, \ldots\}$$

The distribution is a function, so we can plot it

#### Number of Rooms in Rental Unit



Events can overlap with each other

## Events can overlap with each other

• Disjoint events

#### Events can overlap with each other

- Disjoint events
- Conditionally dependent events

With disjoint events,  $P(A \cap B) = 0$ 

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Flip a coin

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Flip a coin

$$P(\text{Heads}) = 0.5, P(\text{Tails}) = 0.5$$
  
 $P(\text{Heads} \cap \text{Tails}) = 0$ 

Be careful!

Walk outside

$$P(\text{Rain}) = 0.05, P(\text{Sun}) = 0.4$$
  
 $P(\text{Rain} \cap \text{Sun}) \neq 0$ 

$$P(\text{cloud}) = 0.2, P(\text{rain}) = 0.05$$

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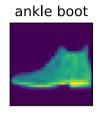
 $P(\text{Rain} \cap \text{Cloud}) = 0.2$ 

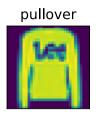
$$P(\text{Cloud}) = 0.4$$

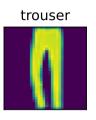
$$P(\text{Rain} \mid \text{Cloud}) = \frac{0.2}{0.4} = 0.5$$

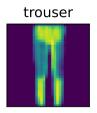
Walk outside

 $X:\mathbb{Z}_{0,255}^{32 imes32}$ 

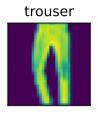


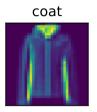


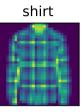






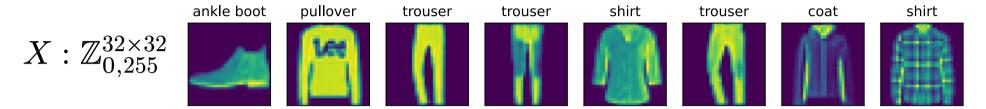






ankle boot pullover shirt shirt trouser trouser trouser coat  $X: \mathbb{Z}_{0.255}^{32 imes 32}$ 

 $Y: \{ \text{T-shirt, Trouser, Pullover, Dress, Coat, } \}$ Sandal, Shirt, Sneaker, Bag, Ankle boot}



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**Approach:** Learn  $\theta$  that produce **conditional probabilities** 

ankle boot pullover shirt coat shirt trouser trouser trouser  $X:\mathbb{Z}_{0.255}^{32 imes32}$ 

Y: {T-shirt, Trouser, Pullover, Dress, Coat, Sandal, Shirt, Sneaker, Bag, Ankle boot}

### **Approach:** Learn $\theta$ that produce **conditional probabilities**

$$f(\boldsymbol{x}, \boldsymbol{\theta}) = P(\boldsymbol{y} \mid \boldsymbol{x}) = P\left(\begin{bmatrix} \text{T-Shirt} \\ \text{Trouser} \\ \vdots \end{bmatrix} \middle| \boldsymbol{x} \right) = \begin{bmatrix} 0.2 \\ 0.01 \\ \vdots \end{bmatrix}$$

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- 1. Review
- 2. Torch optimization coding
- 3. Classification task
- 4. Probability review
- 5. Define model f
- 6. Define loss function  $\mathcal{L}$
- 7. Find  $\theta$  that minimize  $\mathcal{L}$
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**Question:** Can we use this model to predict probabilities?

Answer: No! Because probabilities must sum to one

How can we represent a distribution as a vector?

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$$oldsymbol{v} = \left\{ egin{bmatrix} v_1 \ dots \ v_{d_y} \end{bmatrix} igg| egin{array}{c} d_y \ \sum_{i=1}^{d_y} v_i = 1 \end{array} 
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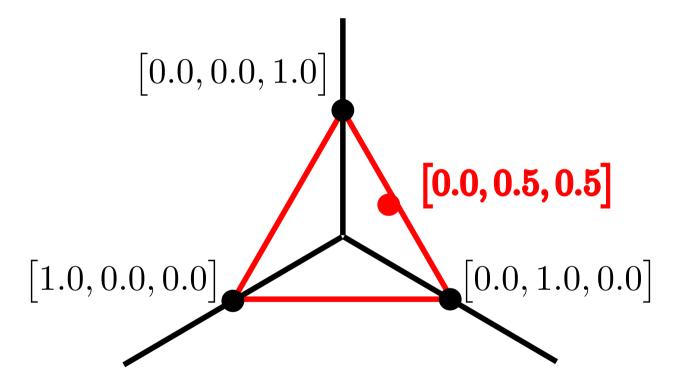
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$$\Delta^{d_y-1}$$

The simplex  $\Delta^k$  is an k-1-dimensional triangle in k-dimensional space

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It has only k-1 free variables, because  $x_k = 1 - \sum_{i=1}^{k-1} x_i$ 

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One example is dividing by the  $L_1$  norm:

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In deep learning we often use the **softmax** function. When combined with the classification loss the gradient is linear, making learning faster

The softmax function maps real numbers to the simplex (probabilities)

 $\operatorname{softmax}: \mathbb{R}^k \mapsto \Delta^{k-1}$ 

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$$\operatorname{softmax}: \mathbb{R}^k \mapsto \Delta^{k-1}$$

$$\operatorname{softmax}\left(\begin{bmatrix} x_1 \\ \vdots \\ x_k \end{bmatrix}\right) = \frac{e^{x}}{\sum_{i=1}^{k} e^{x_i}} = \begin{bmatrix} \frac{e^{x_1}}{e^{x_1} + e^{x_2} + \dots e^{x_k}} \\ \frac{e^{x_2}}{e^{x_1} + e^{x_2} + \dots e^{x_k}} \\ \vdots \\ \frac{e^{x_k}}{e^{x_1} + e^{x_2} + \dots e^{x_k}} \end{bmatrix}$$

If we attach it to our linear model, we can output probabilities!

$$f(\boldsymbol{x}, \boldsymbol{\theta}) = \operatorname{softmax}(\boldsymbol{\theta}^{\top} \boldsymbol{x})$$

And naturally, we can use the same method for a deep neural network

$$egin{aligned} f_1(oldsymbol{x},oldsymbol{arphi}) &= \sigma(oldsymbol{arphi}^ op oldsymbol{x}) \ &drawnothing f_\ell(oldsymbol{x},oldsymbol{\xi}) = \operatorname{softmax}(oldsymbol{\xi}^ op oldsymbol{x}) \end{aligned}$$

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Now, our neural network can output probabilities

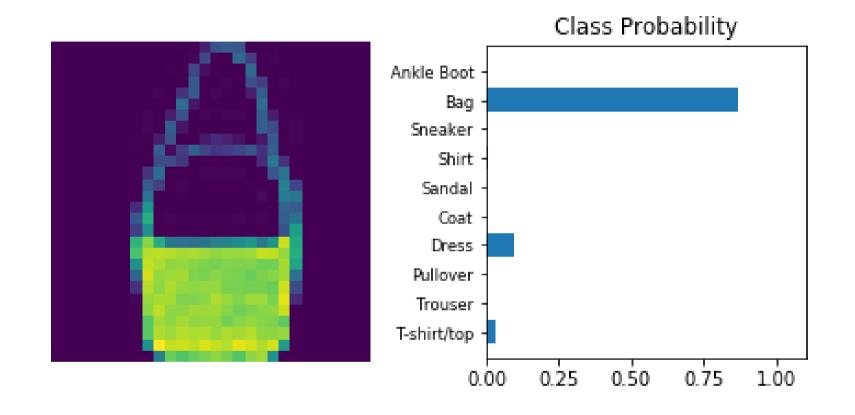
Question: Why do we output probabilities instead of a binary values

$$f(oldsymbol{x}, oldsymbol{ heta}) = egin{bmatrix} Pig( \mathrm{Shirt} \mid oldsymbol{eta} ig) \ Pig( \mathrm{Bag} \mid oldsymbol{eta} ig) \end{bmatrix}$$

$$f(\boldsymbol{x}, \boldsymbol{\theta}) = egin{bmatrix} 1 \\ 0 \end{bmatrix}$$

**Answer 1:** Outputting probabilities results in differentiable functions

Answer 2: We report uncertainty, which is useful in many applications



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What loss function should we use for classification?

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Let us derive it

We can model  $f(\boldsymbol{x}, \boldsymbol{\theta})$  and  $\boldsymbol{y}$  as probability distributions

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How do we measure the difference between probability distributions?

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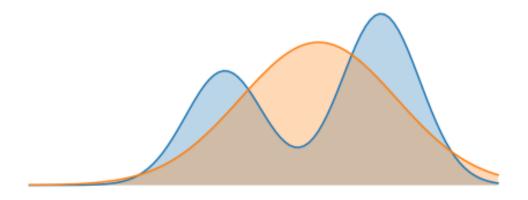
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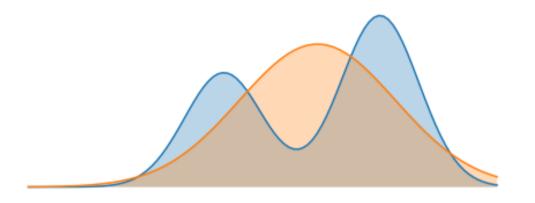
We use the Kullback-Leibler Divergence (KL)

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#### First, write down KL-divergence

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Plug in our two distributions P = f and Q = y

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Rewrite the logarithm using the sum rule of logarithms

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Split the sum into two parts

$$= \sum_{i=1}^{d_y} P(y_i \mid \boldsymbol{x}) \log P(y_i \mid \boldsymbol{x}) - \sum_{i=1}^{d_y} P(y_i \mid \boldsymbol{x}) \log f(\boldsymbol{x}, \boldsymbol{\theta})_i$$

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The first term is constant, and we will minimize the loss. So  $\arg\min_{\theta} \mathcal{L} + k = \arg\min_{\theta} \mathcal{L}$ . Therefore, we can ignore the first term.

$$= -\sum_{i=1}^{d_y} P(y_i \mid \boldsymbol{x}) \log f(\boldsymbol{x}, \boldsymbol{\theta})_i$$

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This is the loss for a classification task! We call this the **cross-entropy** loss function

$$\mathcal{L}(\boldsymbol{x}, \boldsymbol{y}, \boldsymbol{\theta}) = -\sum_{i=1}^{d_y} P(y_i \mid \boldsymbol{x}) \log f(\boldsymbol{x}, \boldsymbol{\theta})_i$$

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$$\nabla_{\boldsymbol{\theta}} \operatorname{softmax}(\boldsymbol{z}) = \operatorname{softmax}(\boldsymbol{z}) \odot (1 - \operatorname{softmax}(\boldsymbol{z}))$$

This is because softmax is a multi-class generalization of the sigmoid function

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The rest of this course will examine neural network architectures