

hw7

May 27, 2025

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[78]: import numpy as np
import matplotlib.pyplot as plt
import time

# 1) Data generation
m, n, s = 100, 500, 5
np.random.seed(0)
A = np.random.randn(m, n)
x_star = np.zeros(n)
p = np.random.permutation(n)
x_star[p[:s]] = np.random.randn(s)
b = A.dot(x_star)

# True objective at x*, used for f-diff
def objective(x, ):
    return np.linalg.norm(A.dot(x) - b)**2 + * np.linalg.norm(x, 1)

# Soft-thresholding operator
def soft_threshold(x, lam):
    return np.sign(x) * np.maximum(np.abs(x) - lam, 0.0)

def subgradient_optimal(A, b, , x0, eps, max_iter=1000000):
    x = x0.copy()
    f_star = objective(x_star, )
    errors, f_diffs = [], []
    t_start = time.time()

    for k in range(1, max_iter + 1):
        grad_g = 2 * A.T.dot(A.dot(x) - b)
        subgrad_h = * np.sign(x)
        gk = grad_g + subgrad_h

        g_norm_sq = np.linalg.norm(gk)**2
        if g_norm_sq == 0:
            break # Already optimal

    t = (objective(x, ) - f_star) / g_norm_sq
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        x -= t * gk

        err = np.linalg.norm(x - x_star) / np.linalg.norm(x_star)
        errors.append(err)
        f_diffs.append(objective(x, ) - f_star)
        if err < eps:
            break

    return x, errors, f_diffs, time.time() - t_start

def ista_lasso(A, b, , x0, eps, max_iter=1000000):
    x = x0.copy()
    f_star = objective(x_star, )
    L = 2 * np.linalg.norm(A, 2)**2
    t = 1.0 / L
    errors, f_diffs = [], []
    t_start = time.time()
    for k in range(1, max_iter+1):
        grad_g = 2 * A.T.dot(A.dot(x) - b)
        x = soft_threshold(x - t * grad_g, t * )

        err = np.linalg.norm(x - x_star) / np.linalg.norm(x_star)
        errors.append(err)
        f_diffs.append(objective(x, ) - f_star)
        if err < eps:
            break

    return x, errors, f_diffs, time.time() - t_start

# 3) Run experiments
= 0.0001
eps_list = [1e-2, 1e-4, 1e-6]

results = {}
for eps in eps_list:
    x0 = np.zeros(n)
    x_sub, err_sub, f_sub, t_sub = subgradient_optimal(A, b, 0.0001, x0, eps)
    x_ist, err_ist, f_ist, t_ist = ista_lasso(A, b, 0.005, x0, eps)
    results[eps] = {
        'time': {'sub': t_sub, 'ista': t_ist},
        'f_diff': {'sub': f_sub[-1], 'ista': f_ist[-1]},
        'iters': {'sub': len(err_sub), 'ista': len(err_ist)},
        'errors': {'sub': err_sub, 'ista': err_ist},
        'f_traj': {'sub': f_sub, 'ista': f_ist}
    }

# 4) Bar-charts at termination

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labels      = [f"{e:.0e}" for e in eps_list]
xpos        = np.arange(len(eps_list))
width       = 0.35

sub_times   = [results[e]['time']['sub']   for e in eps_list]
ista_times  = [results[e]['time']['ista']  for e in eps_list]
sub_fdiff   = [results[e]['f_diff']['sub']  for e in eps_list]
ista_fdiff  = [results[e]['f_diff']['ista'] for e in eps_list]
#    5) Convergence plots
for eps in eps_list:
    err_sub = results[eps]['errors']['sub']
    err_ist = results[eps]['errors']['ista']
    time_sub = np.cumsum([results[eps]['time']['sub'] / len(err_sub)] *
↳len(err_sub))
    time_ist = np.cumsum([results[eps]['time']['ista'] / len(err_ist)] *
↳len(err_ist))

    plt.figure(figsize=(6, 4))
    plt.semilogy(time_sub, err_sub, label='Subgradient')
    plt.semilogy(time_ist, err_ist, label='ISTA')
    plt.xlabel('Time (s)')
    plt.ylabel('Relative error  $\|x - x^*\| / \|x^*\|$  ')
    plt.title(f'Convergence ( = {eps:.0e} )')
    plt.legend()
    plt.grid(True, which='both', ls='--', lw=0.5)
    plt.tight_layout()
    plt.show()

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