# Homework 1, MAT 258A

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## Problem 9 — Disk Packing into a Square Box

## (a) Non-Intersection Condition

We show that two circular disks of radii  $r_1$ ,  $r_2$  centered at  $x_1$ ,  $x_2 \in \mathbb{R}^2$  do not intersect if and only if

$$||x_1 - x_2||_2 \ge r_1 + r_2.$$

*Proof.* The Euclidean distance between centers must be at least the sum of the radii to avoid overlap. If the distance is less, their perimeters intersect.

## (b) Optimization Model Formulation

Let m sphere, each of fixed radius  $r_i$ , be placed in a box centered at the origin, with variable half-length R > 0. Let  $(x_i, y_i)$  be the center of disk i.

#### Variables:

- $(x_i, y_i, ...)$  for i = 1, ..., m
- R > 0: half-size of the enclosing box (to minimize)

#### Constraints:

Containment:  $-R + r_i \le x_i, y_i, ... \le R - r_i \quad \forall i$ 

Non-overlap:  $||x_i - x_j||_2^2 \ge (r_i + r_j)^2 \quad \forall i < j$ 

### Objective:

 $\min R$ 

This is a nonconvex quadratic optimization since some convex combinations of optimal solutions will result in overlapping disks.

## (c) Code Implementation and Results

We used gurobipy with the NonConvex flag to solve this model for  $\mathbb{R}^2$ , m=5 and m=6, with r=1. The optimal R values obtained are:

- m = 5:  $R^* = 2.414$
- m = 6:  $R^* = 2.664$

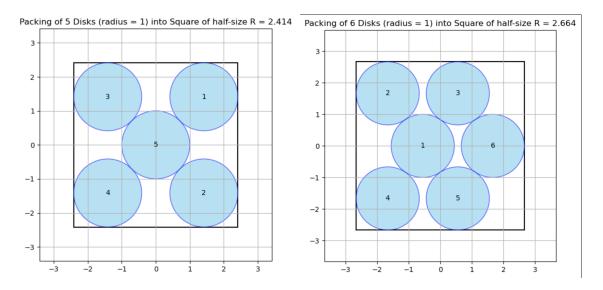


Figure 1: Optimal disk packings for m=5 (left) and m=6 (right) with r=1

### (d) Uniqueness Discussion

Due to the non-convex nature of the problem, multiple local minima may exist. The solution is not necessarily unique. Different initial guesses or solver tolerances may lead to different (but equally optimal) configurations.

Code, plots, and full writeup available at: https://github.com/smoralesduarte/mat258a