

1 2 기   정 규 세 셴

ToBig's   11기 임채빈

# Convolutional Neural Networks

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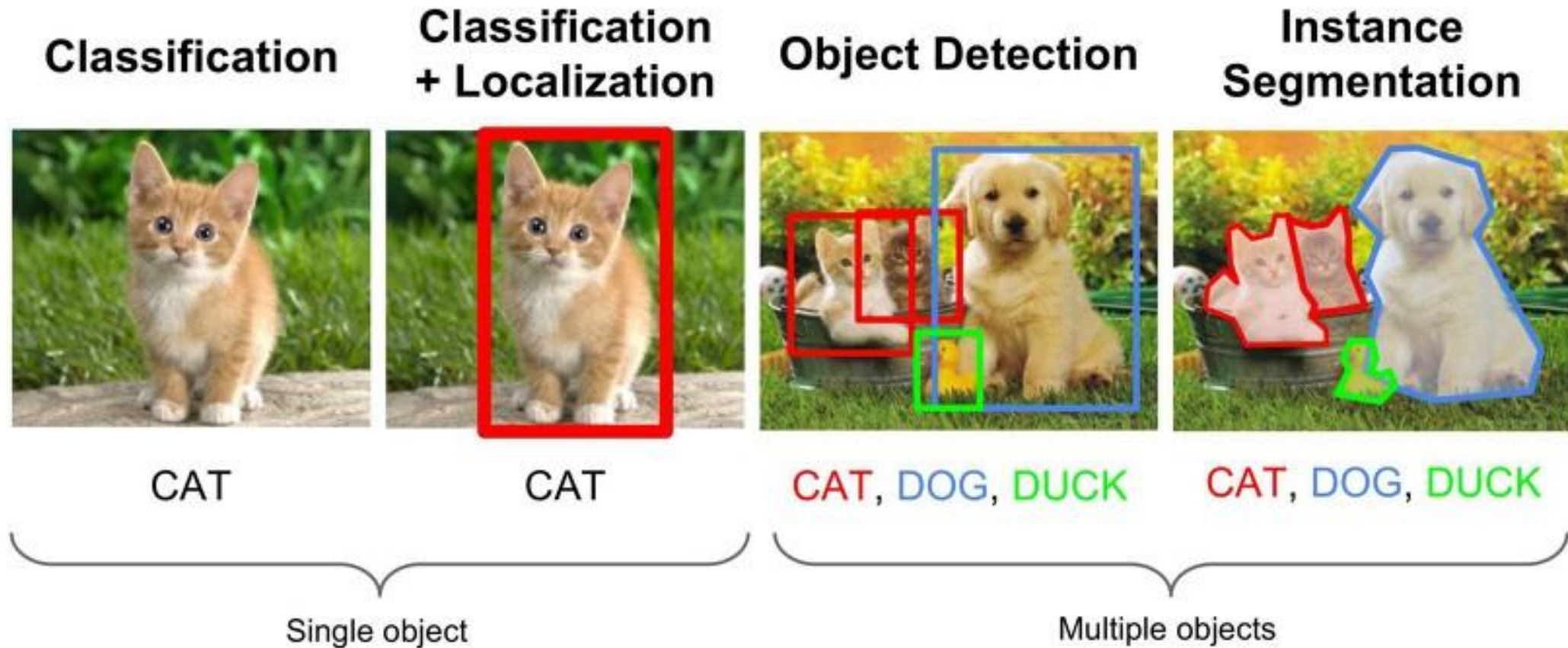
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Unit 05 | Summary

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## Unit 01 | intro : Applications of cnn

## ■ Applications of cnn



## Unit 01 | intro : Applications of cnn

- Image Caption Generation



↑ a living room with a couch and a television



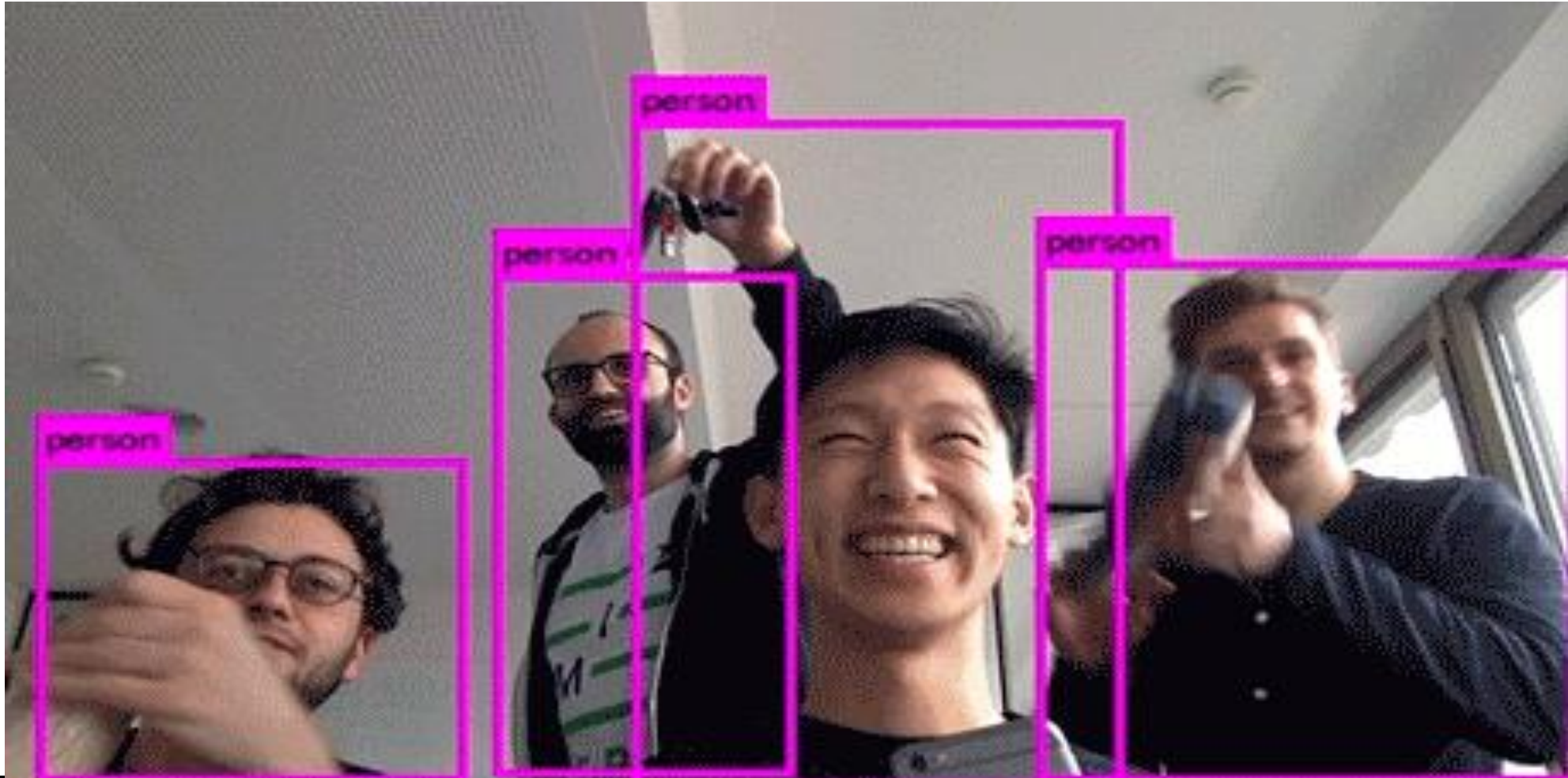
↑ a man riding a bike on a beach



a man is walking down the street with a suitcase ↗

## Unit 01 | intro : Applications of cnn

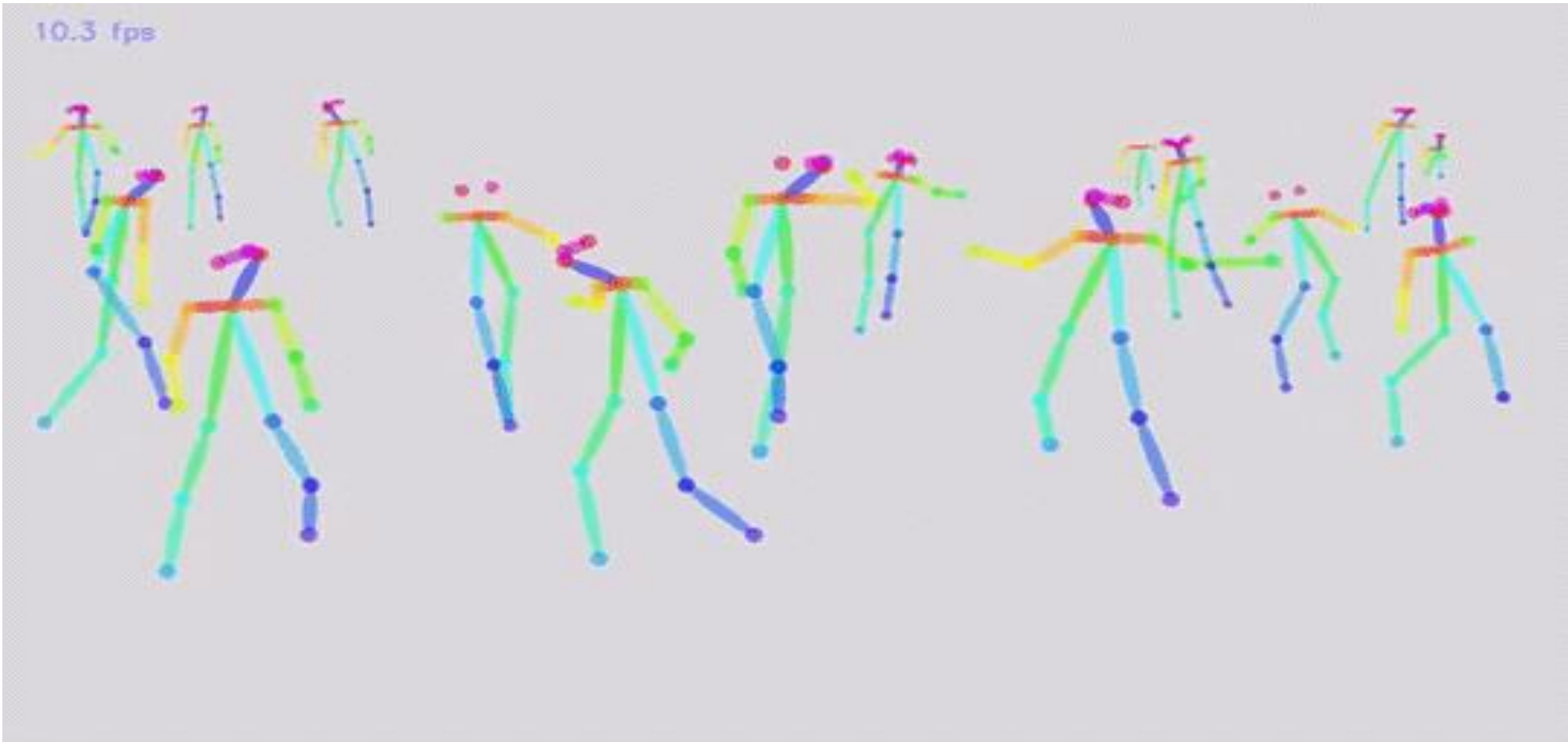
- Real Time Object Detection





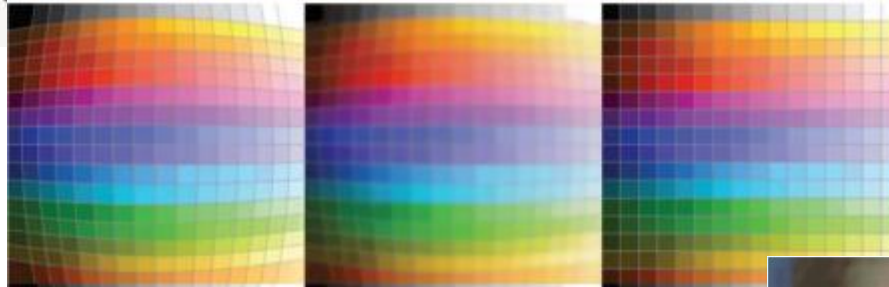
## Unit 01 | intro : Applications of cnn

- Real Time Pose Estimation

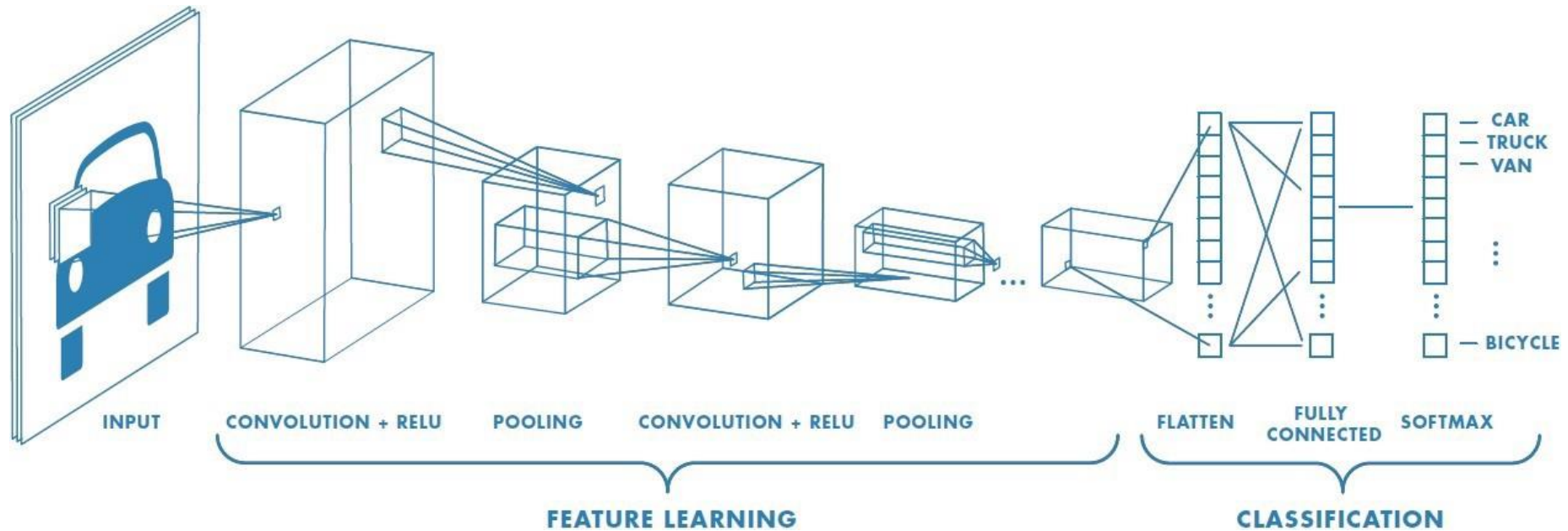


## Unit 01 | intro : Applications of cnn

- GAN



## Unit 02 | Layers in CNN



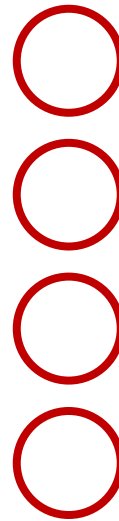
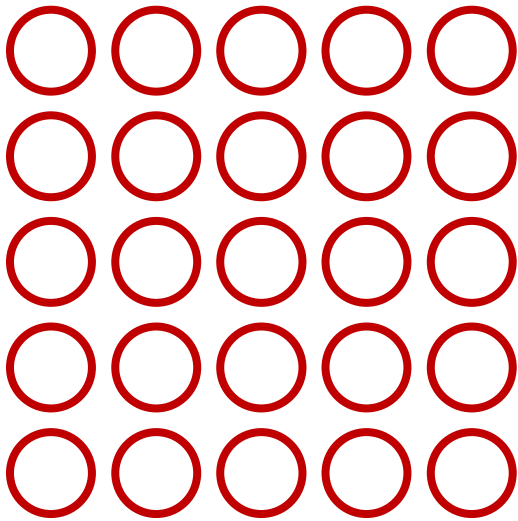
- **Convolution Layer** + **Subsampling Layer** + **Fully Connected Layer**
- Feature extraction : Convolution Layer + Pooling Layer
- Classification : Fully Connected Layer



## Unit 02 | Layers in CNN

## ■ Conventional Neural Network

3



## Unit 02 | Layers in CNN

## ■ Conventional Neural Network

3

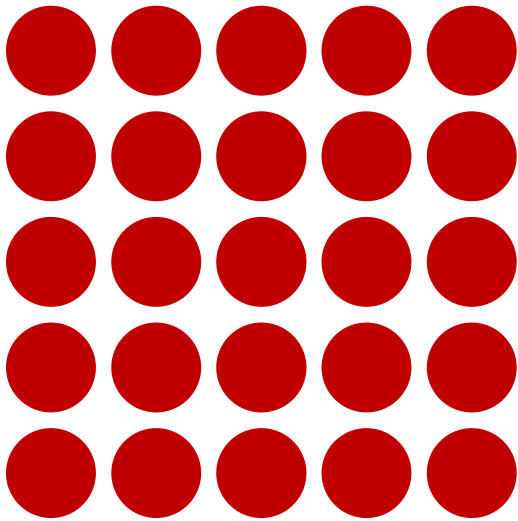
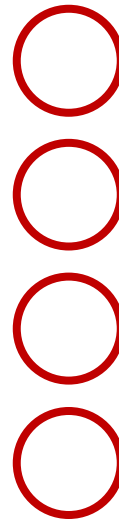


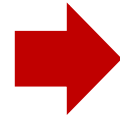
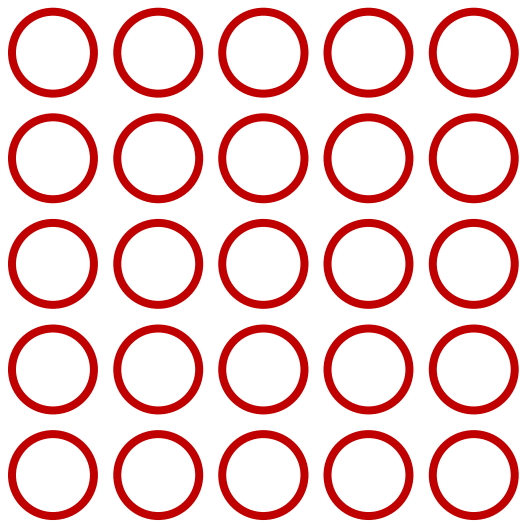
Image pixel (5x5)



## Unit 02 | Layers in CNN

## ■ Conventional Neural Network

3

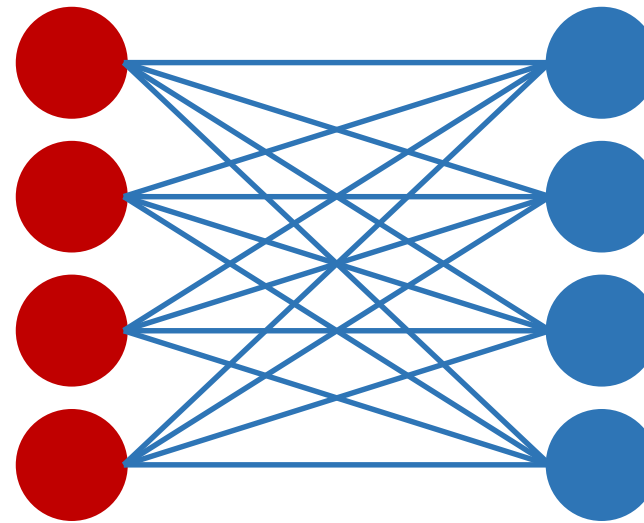
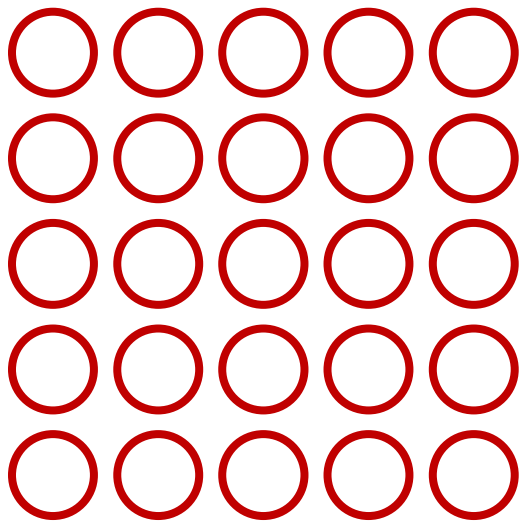


Flatten (1 x 25)

## Unit 02 | Layers in CNN

## ■ Conventional Neural Network

3



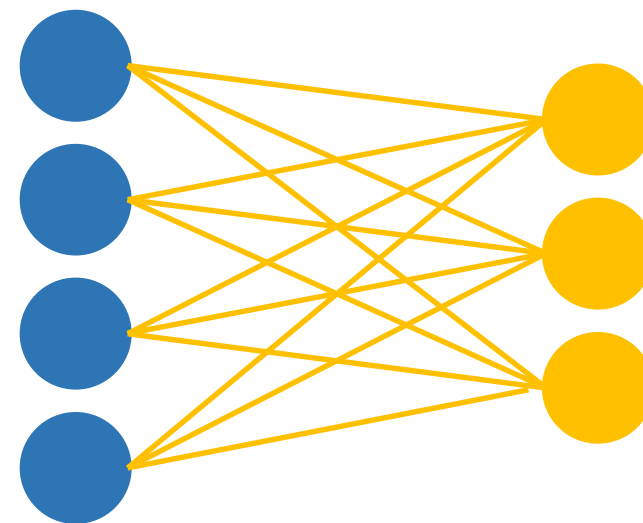
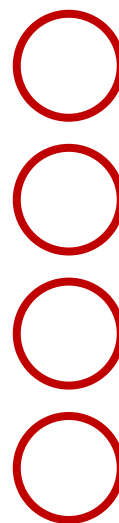
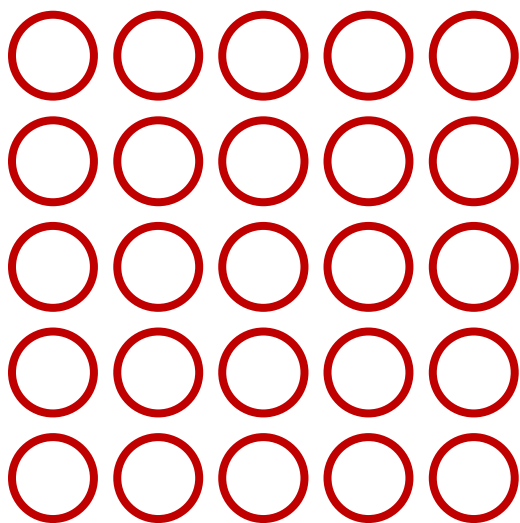
FC + Activation function



## Unit 02 | Layers in CNN

## ■ Conventional Neural Network

3



FC+ Classifier



## Unit 02 | Layers in CNN

## ■ Convolutional Neural Network

3

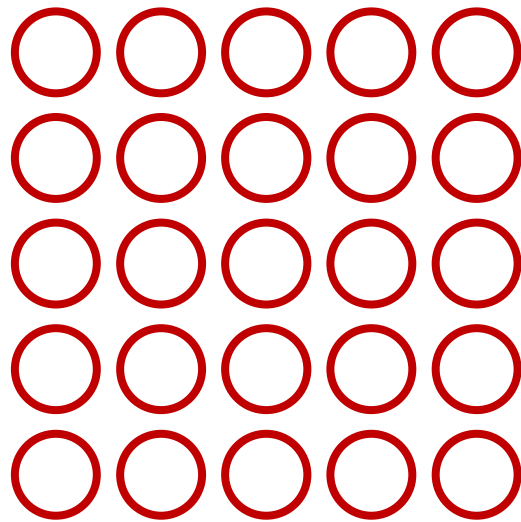
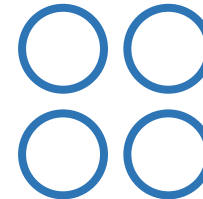
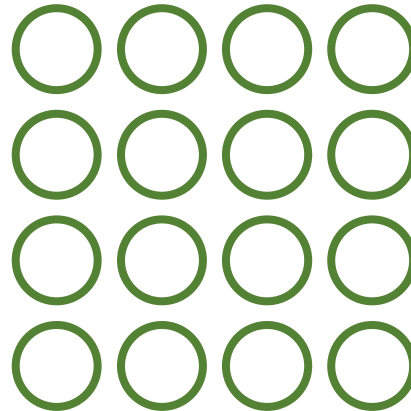


Image pixel (5x5)



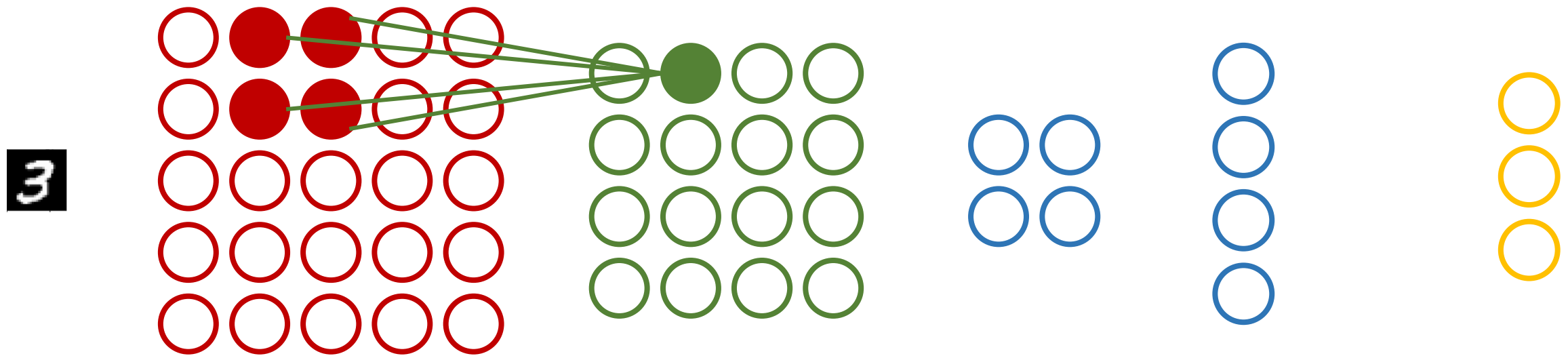
## Unit 02 | Layers in CNN

- Convolutional Neural Network
  - Receptive field : 출력 레이어의 뉴런 하나에 영향을 미치는 입력 뉴런들의 공간



## Unit 02 | Layers in CNN

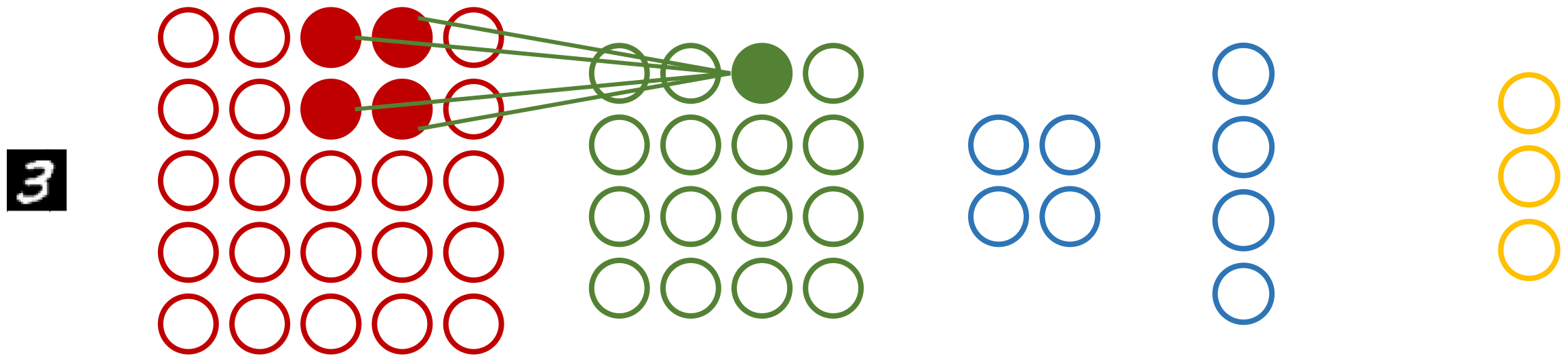
## ■ Convolutional Neural Network



Conv + Activation function

## Unit 02 | Layers in CNN

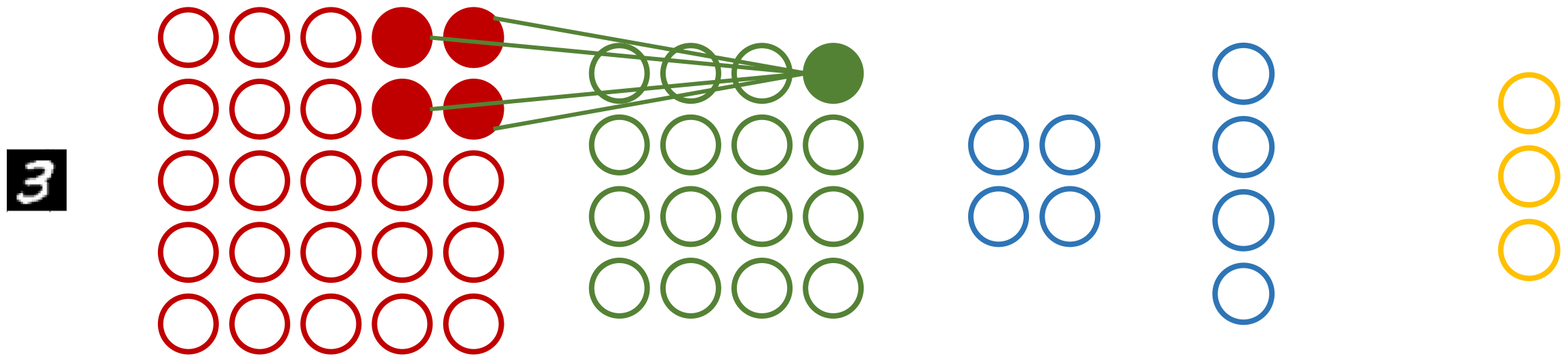
## ■ Convolutional Neural Network



Conv + Activation function

## Unit 02 | Layers in CNN

## ■ Convolutional Neural Network

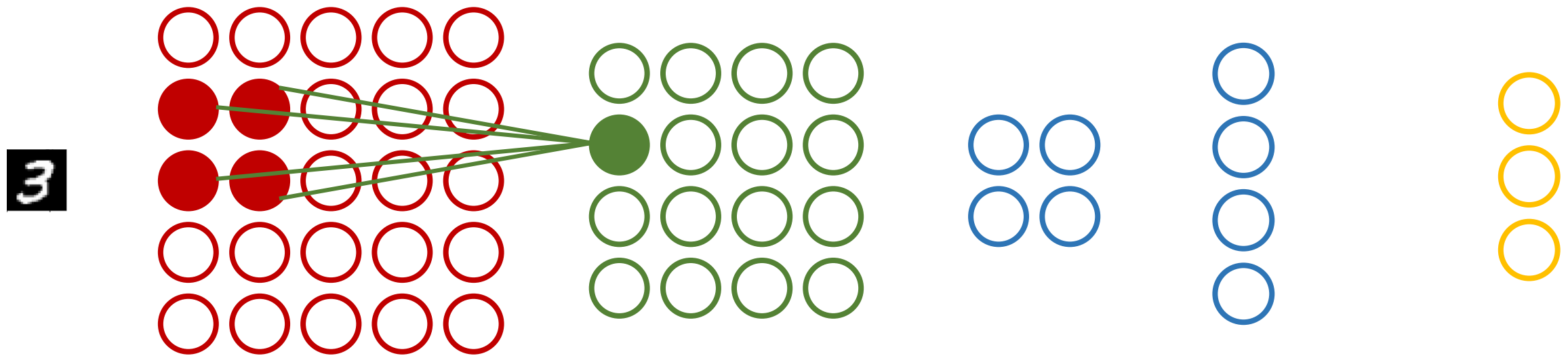


Conv + Activation function



## Unit 02 | Layers in CNN

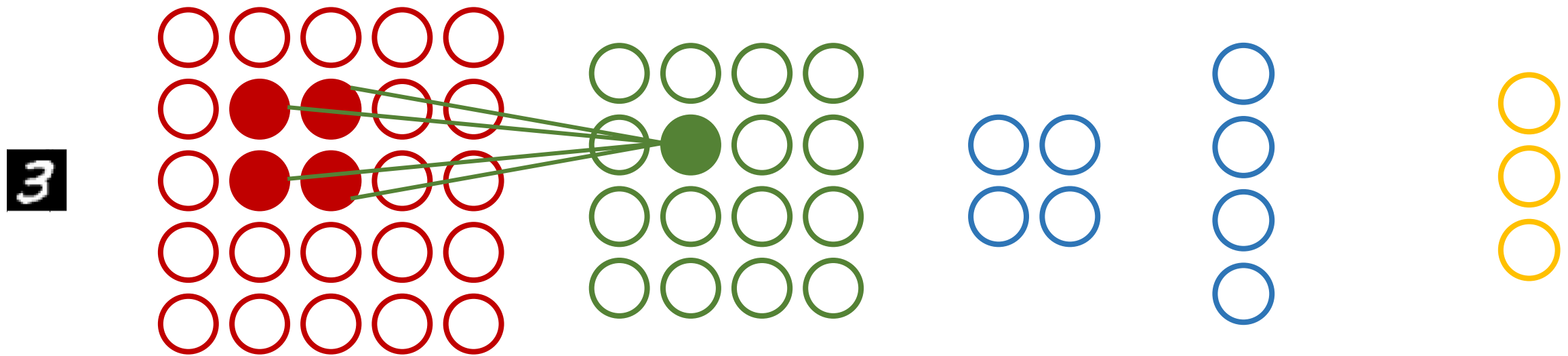
## ■ Convolutional Neural Network



Conv + Activation function

## Unit 02 | Layers in CNN

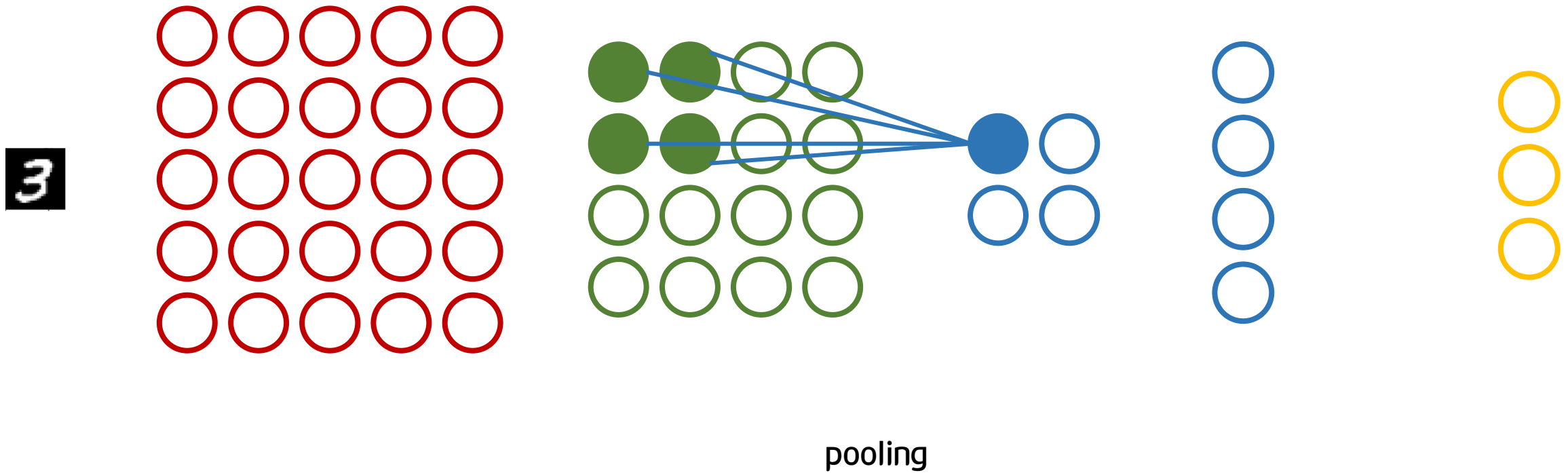
## ■ Convolutional Neural Network



Conv + Activation function

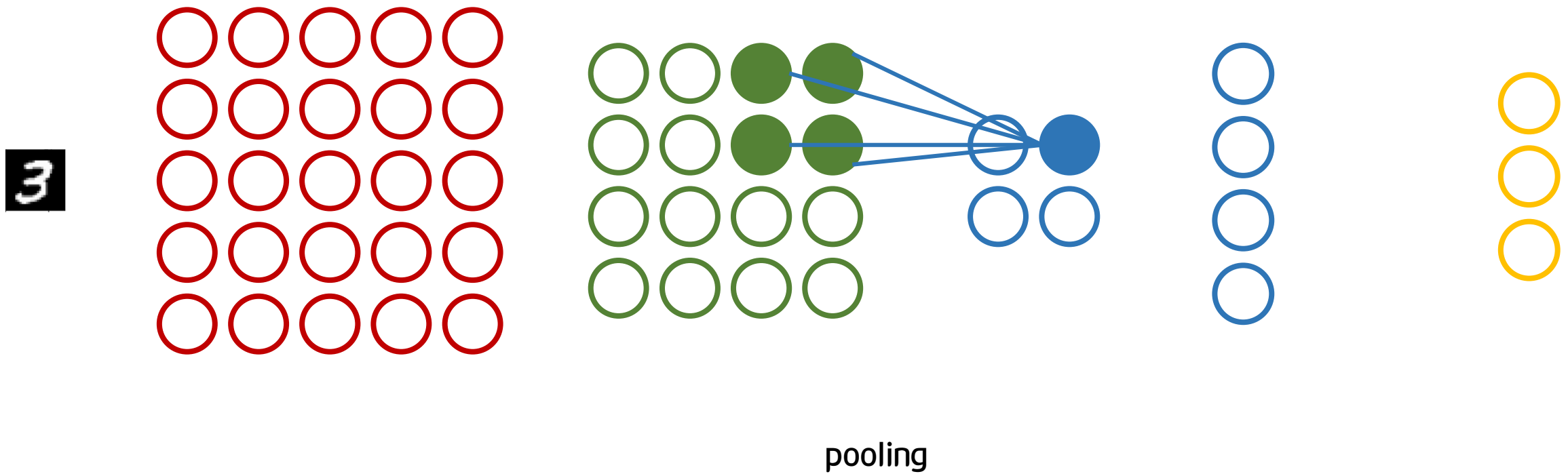
## Unit 02 | Layers in CNN

## ■ Convolutional Neural Network



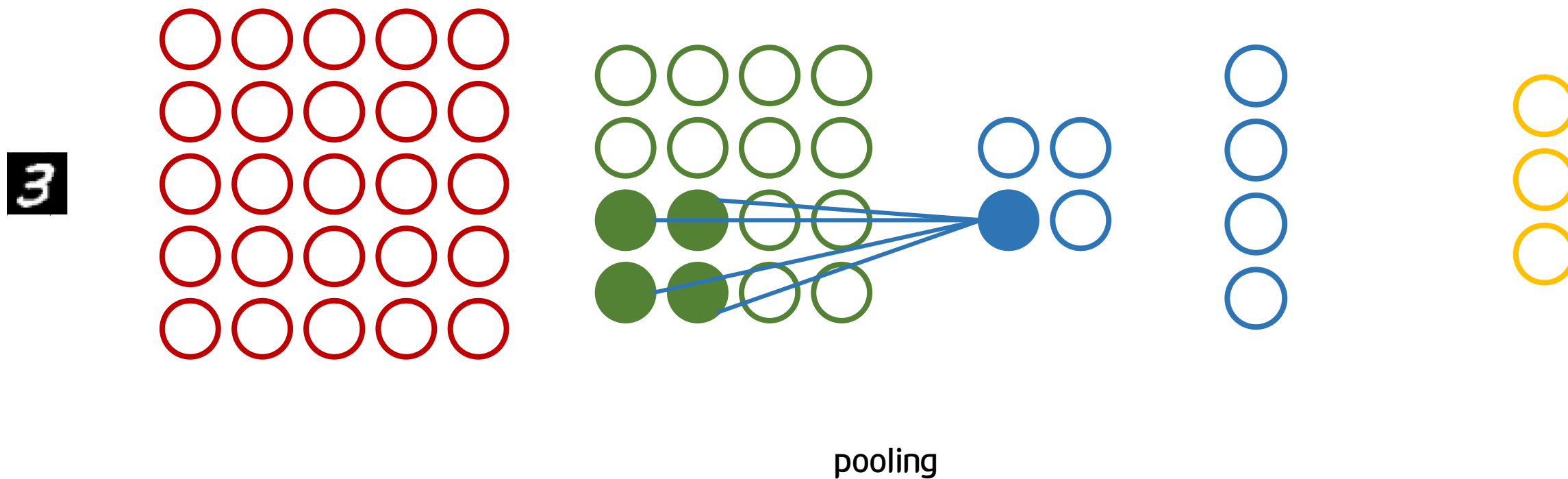
## Unit 02 | Layers in CNN

## ■ Convolutional Neural Network



## Unit 02 | Layers in CNN

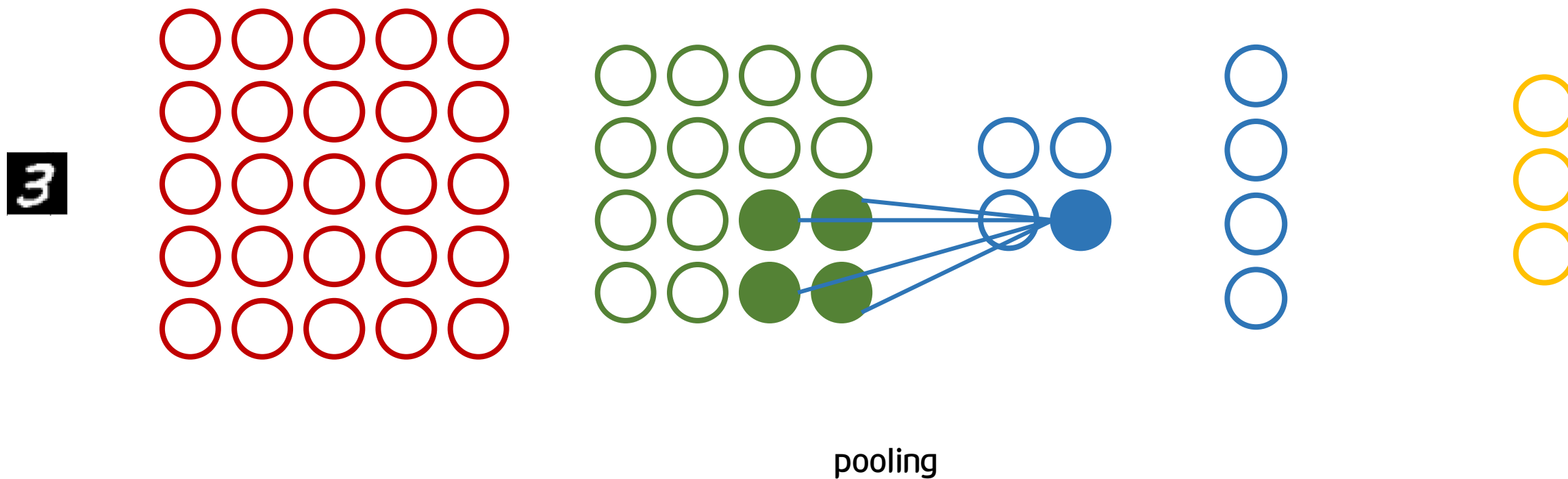
## ■ Convolutional Neural Network





## Unit 02 | Layers in CNN

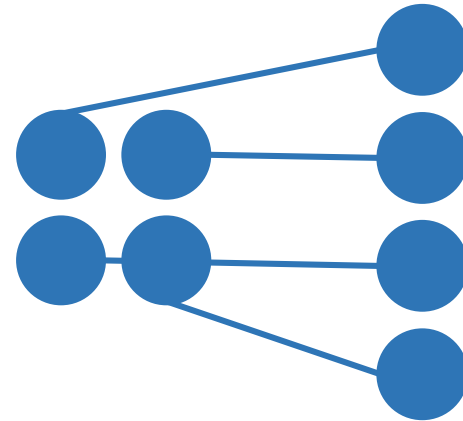
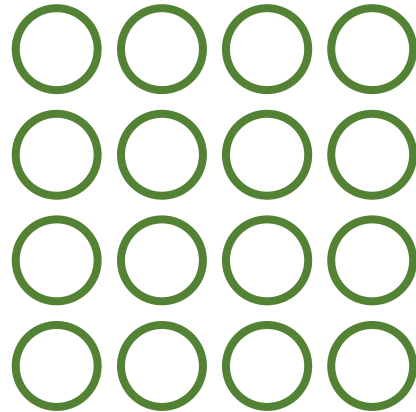
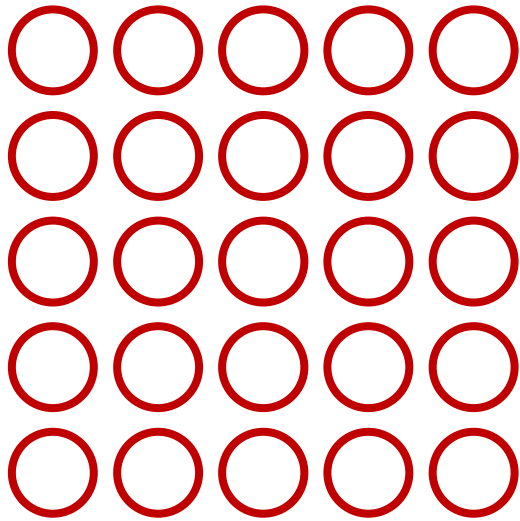
## ■ Convolutional Neural Network



## Unit 02 | Layers in CNN

## ■ Convolutional Neural Network

3



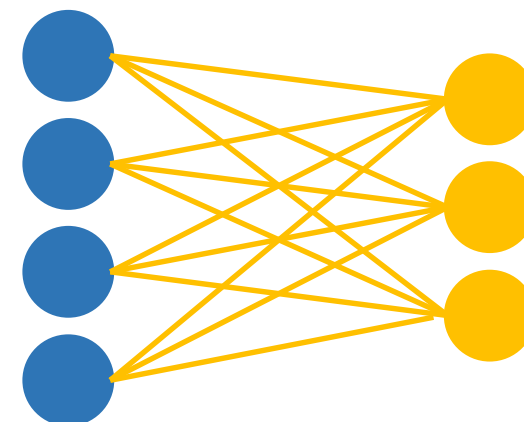
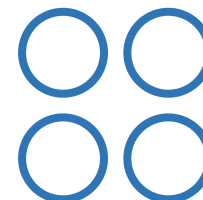
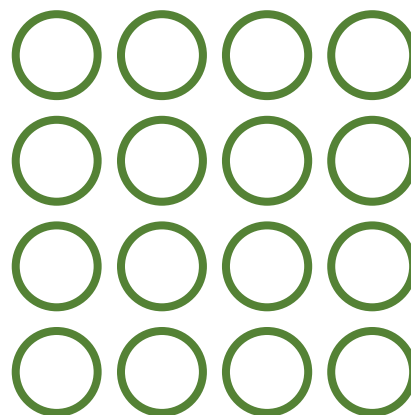
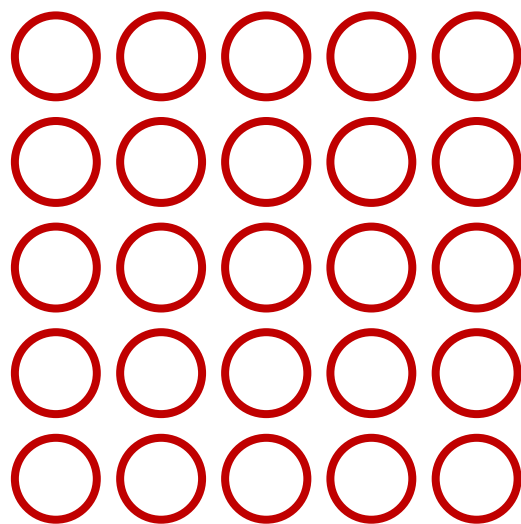
Flatten



## Unit 02 | Layers in CNN

## ■ Convolutional Neural Network

3

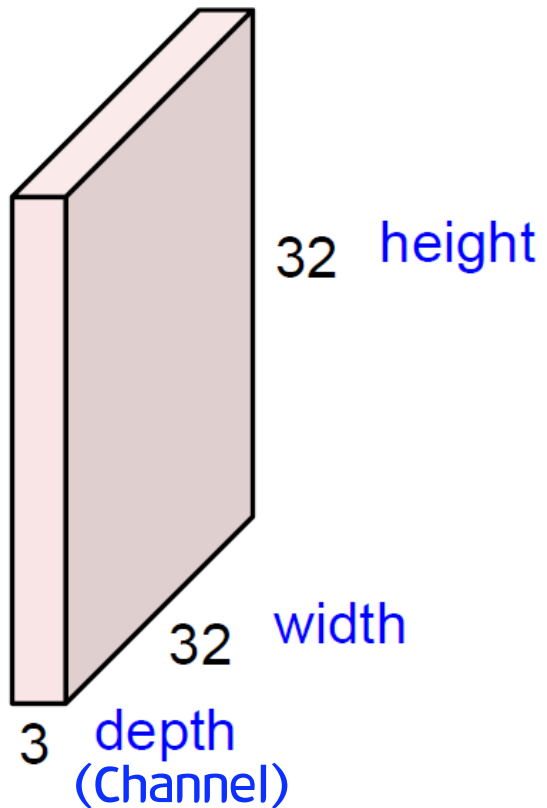


FC + Classifier

## Unit 03 | Convolution Layer

## ■ Convolution

32x32x3 image -> preserve spatial structure



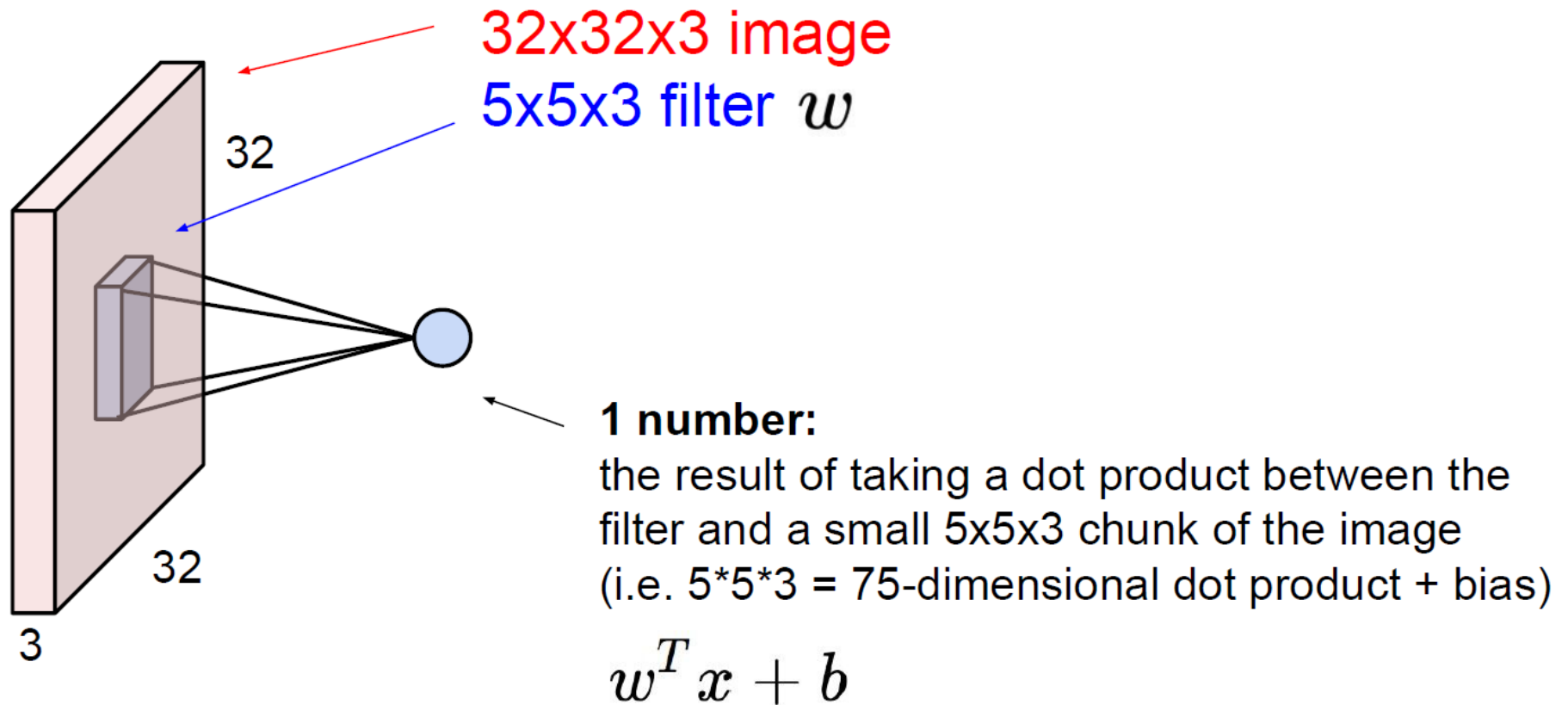
5x5x3 filter (Shared Weight)



- Image와 filter의 channel은 항상 같다.  
Ex) RGB = 3 channel, grayscale = 1channel

## Unit 03 | Convolution Layer

## ■ Convolution





## Unit 03 | Convolution Layer

## ■ Convolution

2	3	0	1	3	2	1	
0	1	0	2	0	1	0	3
1	0	2	2	2	2	1	0
3	2	2	1	1	1	0	3
2	0	2	2	0	0	2	0
0	0	0	0	0	0	2	2
1	2	0	0	2	2	2	0
	0	0	2	0	2	0	0

Image 7x7x3

1	0	1
1	0	0
0	0	0
0	1	0
0	0	0

filter 3x3x3

## Unit 03 | Convolution Layer

## ■ Convolution

2	3	0	1	3	2	1
0	2	2	2	2	1	0
1	2	1	1	1	0	0
3	2	2	0	0	2	3
2	0	0	0	0	2	0
0	0	0	2	2	2	2
1	3	2	3	2	1	0

Input Volumn ( 7x7 )

1	0	1
0	1	0
1	0	1

Filter ( 3 x 3 )


Convolved Feature Volumn ( 5 x 5 )

## Unit 03 | Convolution Layer

## ■ Convolution

2	3	0	1	3	2	1
0	2	2	2	2	1	0
1	2	1	1	1	0	0
3	2	2	0	0	2	3
2	0	0	0	0	2	0
0	0	0	2	2	2	2
1	3	2	3	2	1	0

Input Volumn ( 7x7 )

Dot Product

1	0	1
0	1	0
1	0	1

Filter ( 3 x 3 )



6				

Convolved Feature Volumn ( 5 x 5 )

## Unit 03 | Convolution Layer

## ■ Convolution

2	3	0	1	3	2	1
0	2	2	2	2	1	0
1	2	1	1	1	0	0
3	2	2	0	0	2	3
2	0	0	0	0	2	0
0	0	0	2	2	2	2
1	3	2	3	2	1	0

Input Volumn ( 7x7 )

Dot Product

1	0	1
0	1	0
1	0	1

Filter ( 3 x 3 )



6	9			

Convolved Feature Volumn ( 5 x 5 )

## Unit 03 | Convolution Layer

## ■ Convolution

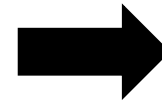
2	3	0	1	3	2	1
0	2	2	2	2	1	0
1	2	1	1	1	0	0
3	2	2	0	0	2	3
2	0	0	0	0	2	0
0	0	0	2	2	2	2
1	3	2	3	2	1	0

Input Volumn ( 7x7 )

Dot Product

1	0	1
0	1	0
1	0	1

Filter ( 3 x 3 )



6	9	7		

Convolved Feature Volumn ( 5 x 5 )

## Unit 03 | Convolution Layer

## ■ Convolution

2	3	0	1	3	2	1
0	2	2	2	2	1	0
1	2	1	1	1	0	0
3	2	2	0	0	2	3
2	0	0	0	0	2	0
0	0	0	2	2	2	2
1	3	2	3	2	1	0

Input Volumn ( 7x7 )

1	0	1
0	1	0
1	0	1

Filter ( 3 x 3 )



6	9	7	6	6
9	7	7	6	5
6	5	2	3	3
5	4	4	6	9
5	6	6	8	4

Convolved Feature Volumn ( 5 x 5 )

## Unit 03 | Convolution Layer

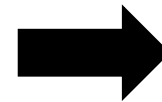
## ■ Convolution

0	2	0	0	0	0	1
1	2	2	2	2	1	0
0	2	1	1	1	0	0
3	2	2	0	0	2	2
2	0	3	0	0	2	0
1	0	0	2	2	2	2
0	1	0	1	0	0	0

Input Volumn ( 7x7 )

1	0	0
0	0	0
0	0	0

Filter ( 3 x 3 )



0	2	0	0	0
1	2	2	2	2
0	2	1	1	1
3	2	2	0	0
2	0	3	0	0

Convolved Feature Volumn ( 5 x 5 )

## Unit 03 | Convolution Layer

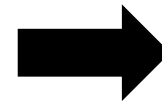
## ■ Convolution

1	0	2	0	1	0	3
0	2	2	2	2	1	0
2	2	1	1	1	0	3
0	2	2	0	0	2	0
0	0	0	0	0	2	2
2	0	0	2	2	2	0
0	0	2	0	2	0	0

Input Volumn ( 7x7 )

0	0	0
0	1	0
0	0	0

Filter ( 3 x 3 )



2	2	2	2	1
2	1	1	1	0
2	2	0	0	2
0	0	0	0	2
0	0	2	2	2

Convolved Feature Volumn ( 5 x 5 )



## Unit 03 | Convolution Layer

## ■ Convolution

6	9	7	6	6
9	7	7	6	5
6	5	2	3	3
5	4	4	6	9
5	6	6	8	4

+

0	2	0	0	0
1	2	2	2	2
0	2	1	1	1
3	2	2	0	0
2	0	3	0	0

+

2	2	2	2	1
2	1	1	1	0
2	2	0	0	2
0	0	0	0	2
0	0	2	2	2

=

New feature map

8	13	9	8	7
12	10	10	9	7
8	9	3	4	6
8	6	6	6	11
7	6	11	10	6

## Unit 03 | Convolution Layer

## ■ Convolution

2	3	0	1	3	2	1
0	1	0	2	0	1	0
1	0	2	2	2	2	1
3	2	2	1	1	1	0
2	0	2	2	0	0	2
0	0	0	0	0	0	2
1	2	0	0	2	2	2
0	0	0	2	0	2	0

Image 7x7x3

Dot Product

1	0	1
0	1	0
0	0	0
0	1	0
0	0	0

filter 3x3x3

=

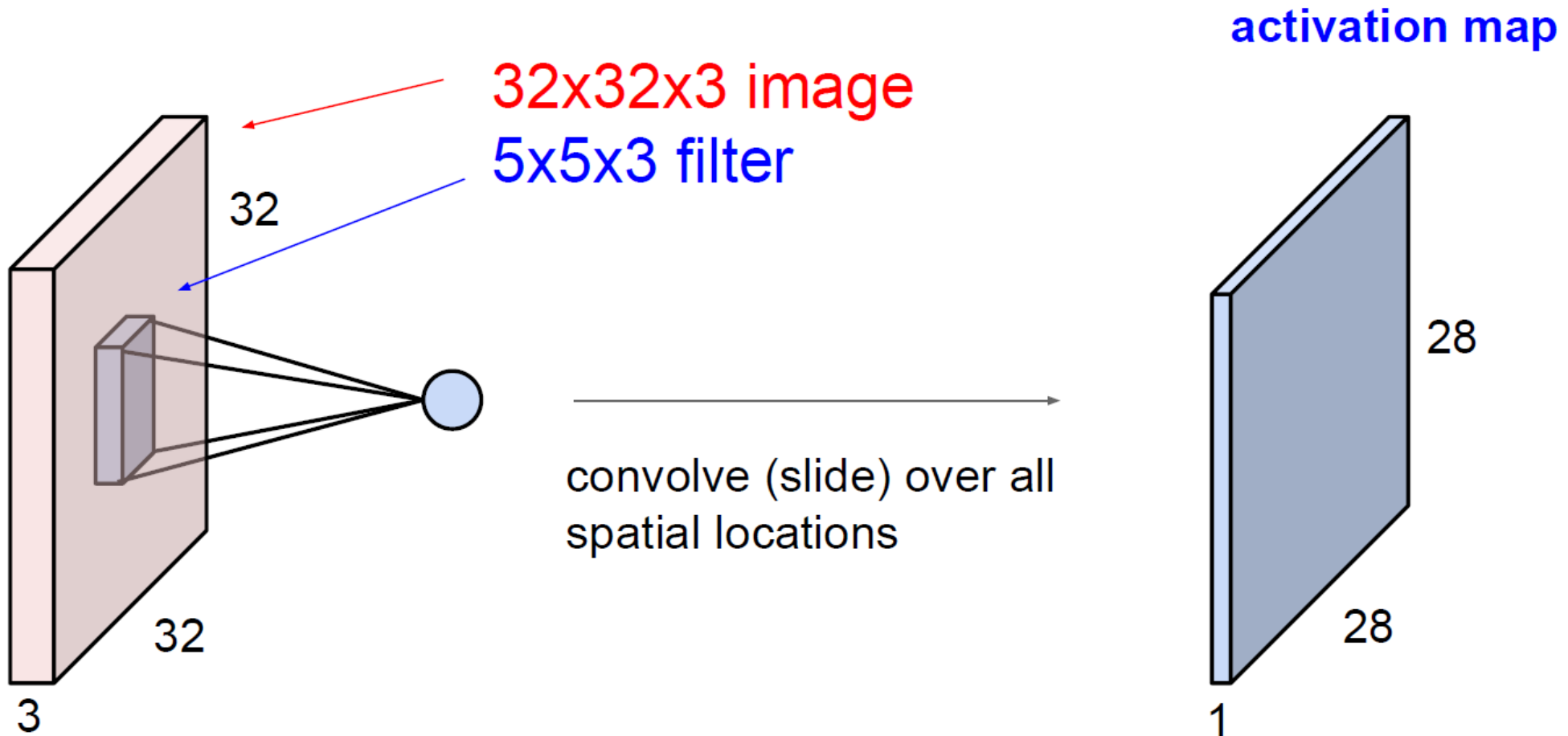
New feature map

8	13	9	8	7
12	10	10	9	7
8	9	3	4	6
8	6	6	6	11
7	6	11	10	6

Feature map 5x5x1

## Unit 03 | Convolution Layer

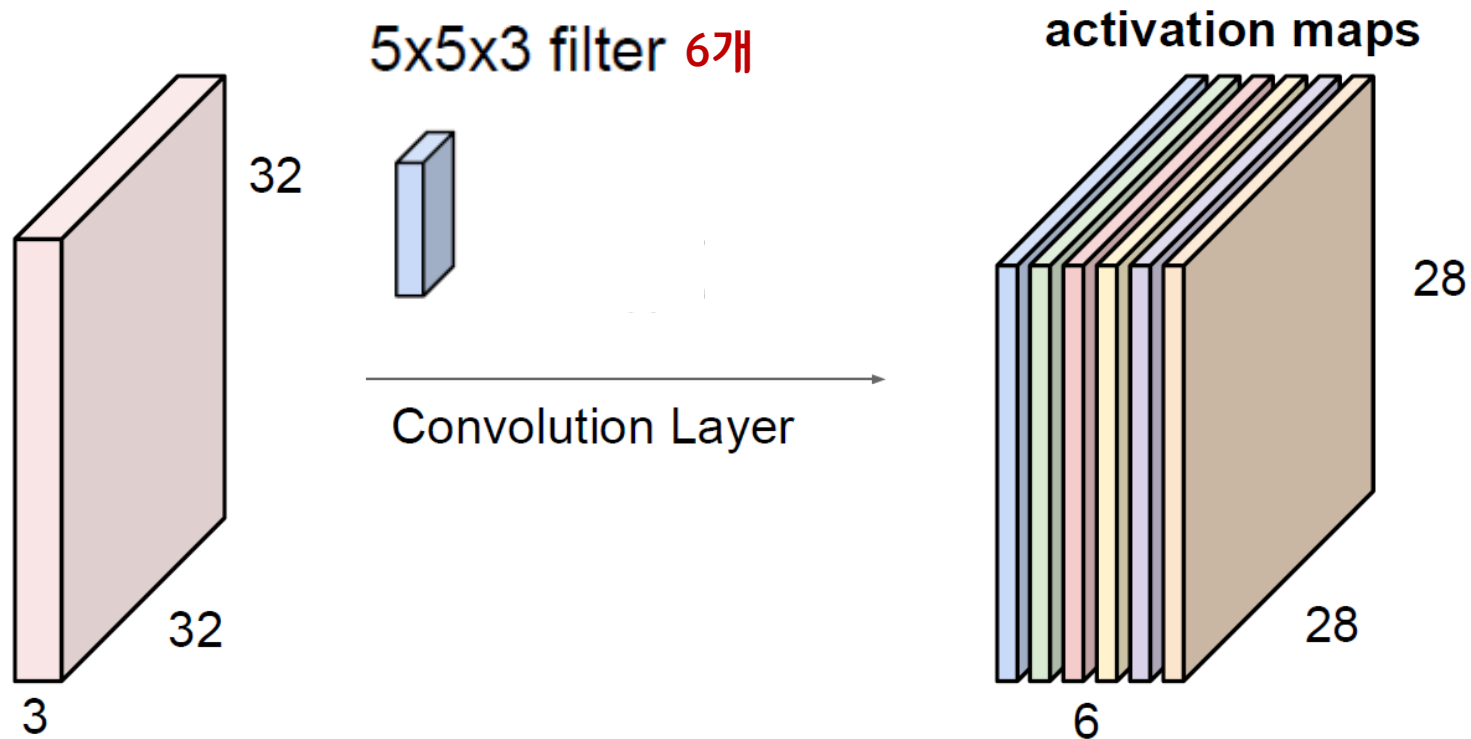
## ■ Convolution



## Unit 03 | Convolution Layer

## ■ Convolution

- Filter 수가 6개라면 6개의 새로운 feature map이 생성됨. (hyper parameter)
- 6개의 feature map을 stack up하여 28x28x6의 새로운 데이터 생성

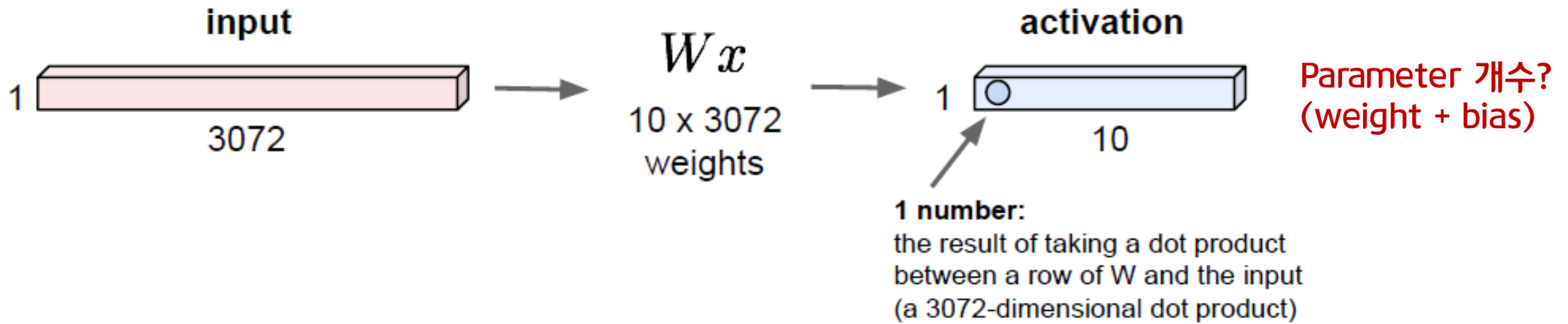


Parameter 개수?  
(weight + bias)

## Unit 03 | Convolution Layer

- Convolution
  - 각각의 pixel을 하나의 channel로 flatten 후  $1 \times 1 \times 3072$  filter 10개를 사용
  - FC?

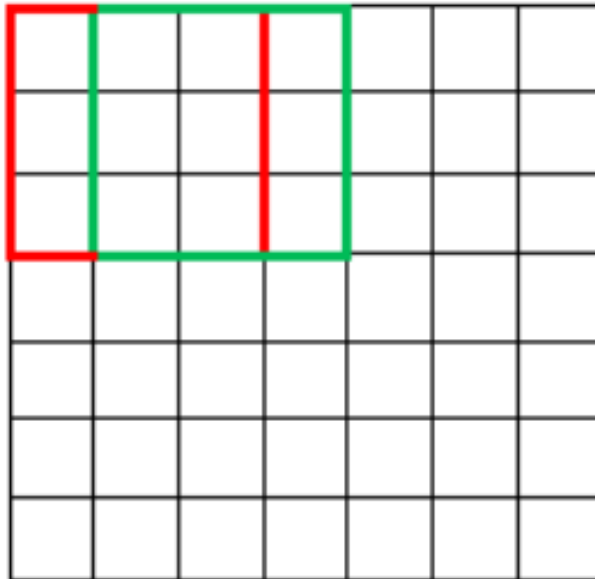
32x32x3 image -> stretch to 3072 x 1



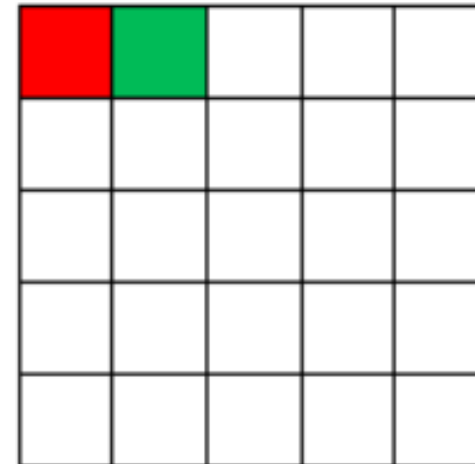
## Unit 03 | Convolution Layer

- Stride
  - Filter가 이동하는 거리

7 x 7 Input Volume



5 x 5 Output Volume

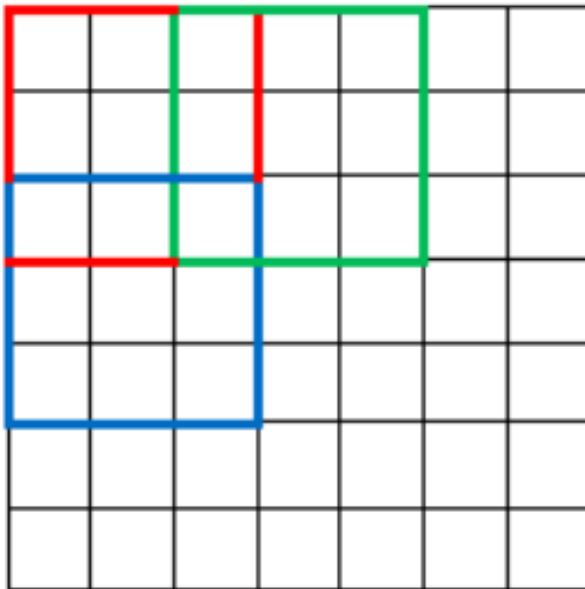


Stride = 1

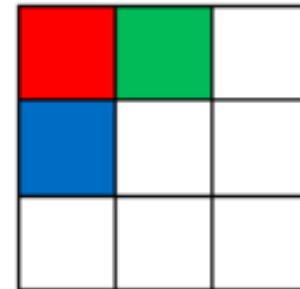
## Unit 03 | Convolution Layer

- Stride
  - Filter가 이동하는 거리

7 x 7 Input Volume



3 x 3 Output Volume

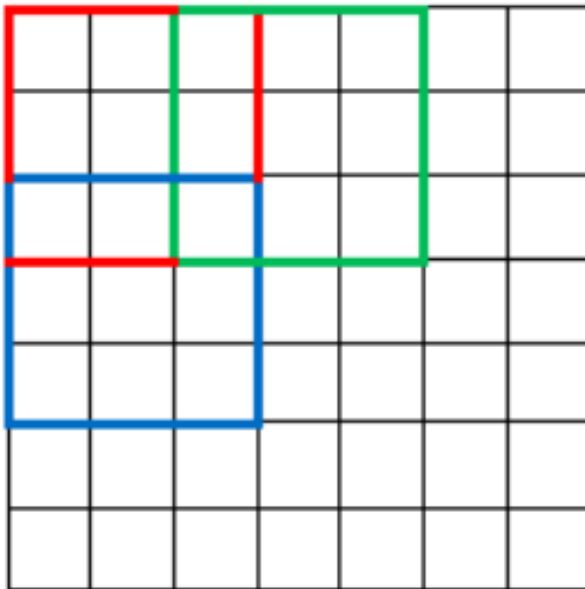


Stride = 2

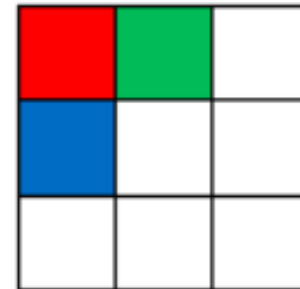
## Unit 03 | Convolution Layer

- Stride
  - Filter가 이동하는 거리

7 x 7 Input Volume



3 x 3 Output Volume

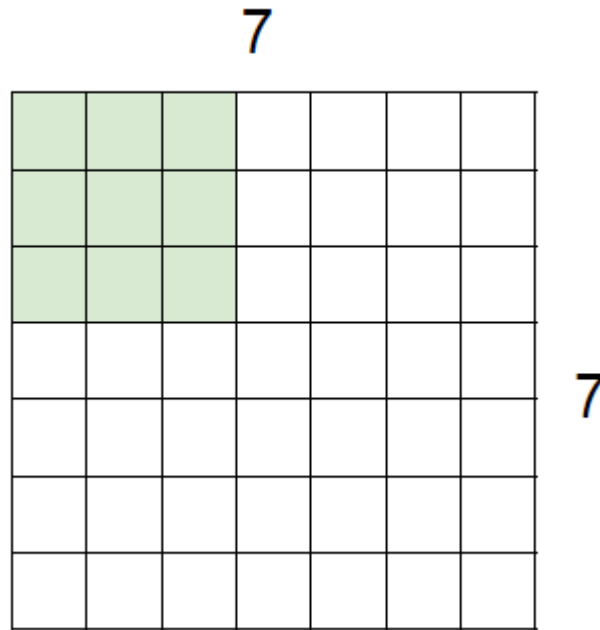


Stride = 2



## Unit 03 | Convolution Layer

- Stride
  - Filter가 이동하는 거리

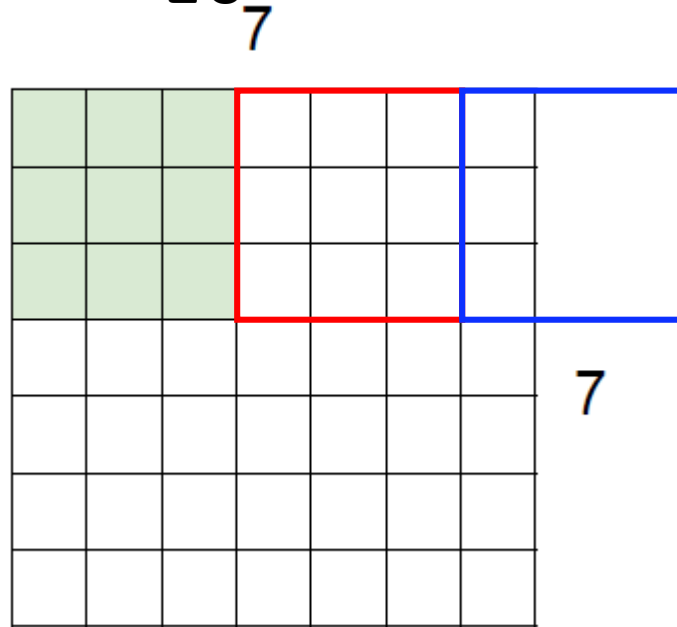


Stride = 3?

## Unit 03 | Convolution Layer

## ■ Stride

- Filter가 이동하는 거리
- Output의 volume이 integer가 되도록 stride 설정

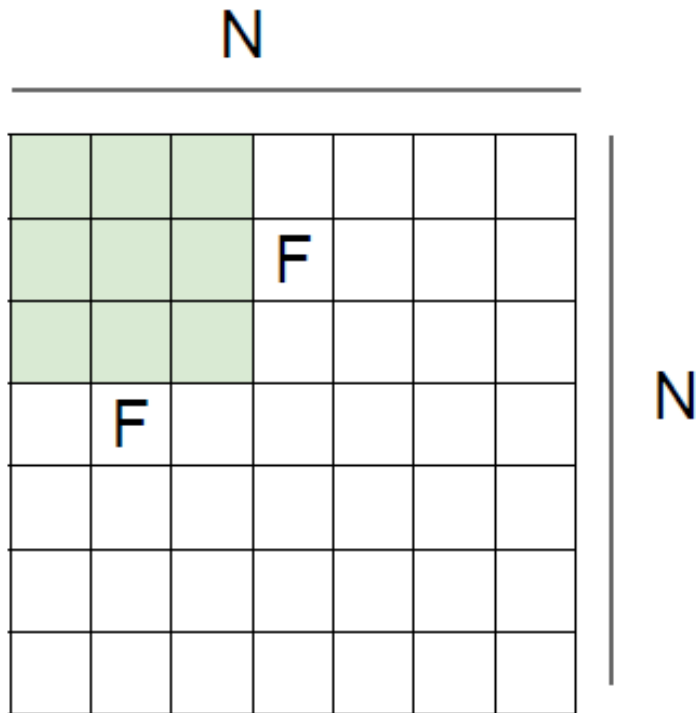


doesn't fit!

Stride = 3?

## Unit 03 | Convolution Layer

- Stride
  - Filter가 이동하는 거리
  - Output의 volume이 integer가 되도록 stride 설정



Output size:  
 $(N - F) / \text{stride} + 1$

e.g.  $N = 7, F = 3$ :

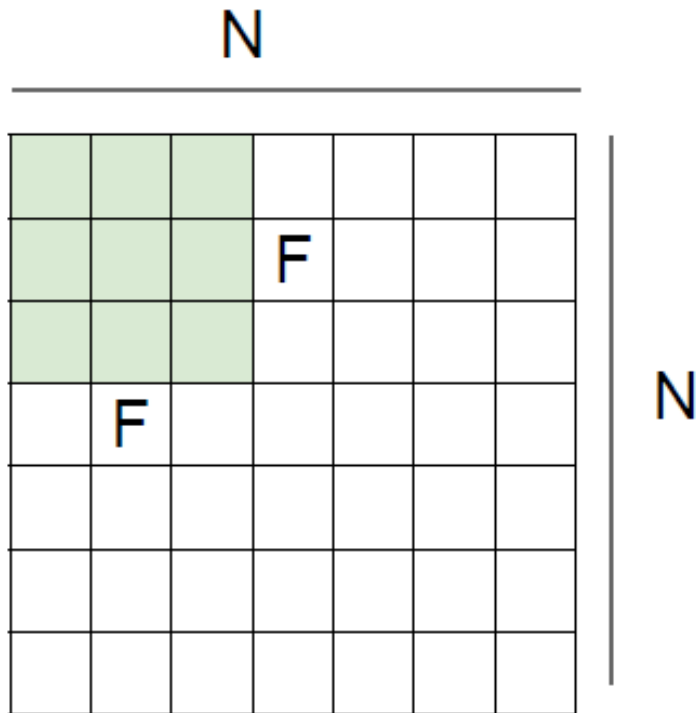
stride 1  $\Rightarrow (7 - 3) / 1 + 1 = 5$

stride 2  $\Rightarrow (7 - 3) / 2 + 1 = 3$

stride 3  $\Rightarrow (7 - 3) / 3 + 1 = 2.33$  **Fraction!**

## Unit 03 | Convolution Layer

- Stride
  - Filter가 이동하는 거리
  - Output의 volume이 integer가 되도록 stride 설정



Output size:  
 $(N - F) / \text{stride} + 1$

e.g.  $N = 7, F = 3$ :

stride 1  $\Rightarrow (7 - 3) / 1 + 1 = 5$

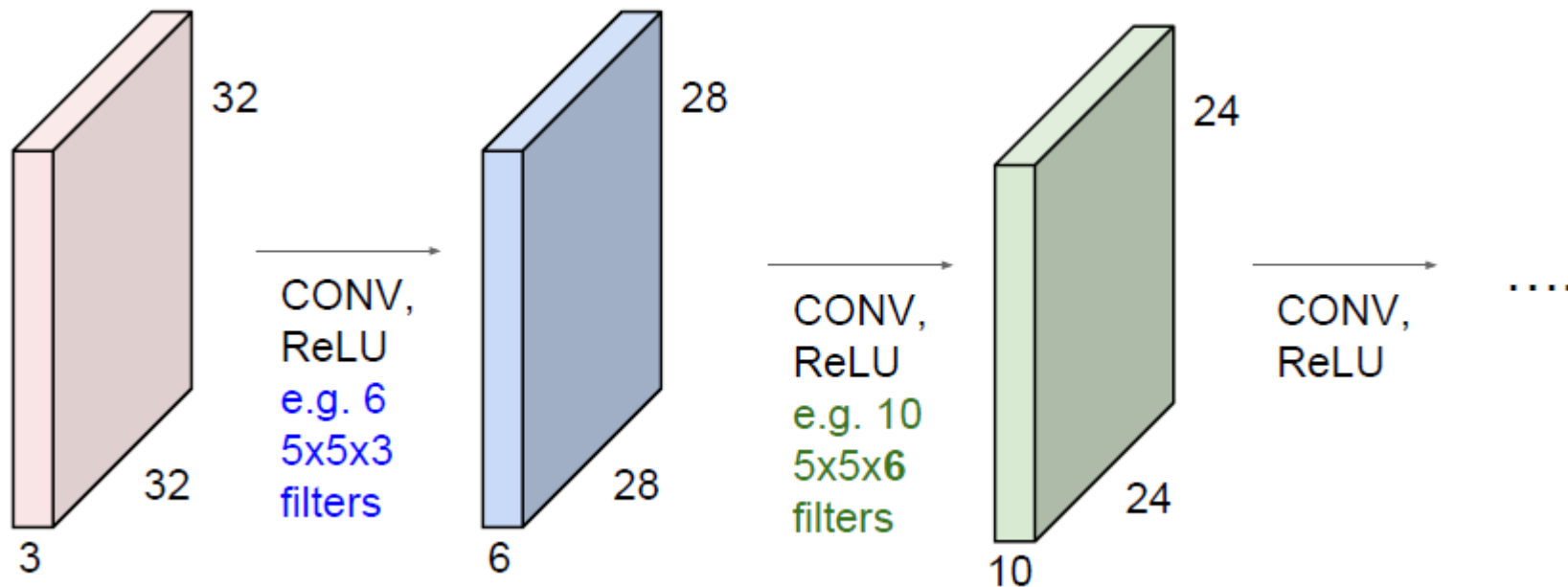
stride 2  $\Rightarrow (7 - 3) / 2 + 1 = 3$

stride 3  $\Rightarrow (7 - 3) / 3 + 1 = 2.33$  **Fraction!**

## Unit 03 | Convolution Layer

### ■ Padding

- Convolution layer 층이 깊어질 수록 data의 size가 줄어든다.
- Data size가 너무 빠르게 줄어들면 잘 작동하지 않음!



32 → 28 → 24 → 20 → 16 → ...

## Unit 03 | Convolution Layer

- Padding
  - 데이터 테두리에 zero-padding을 더해 크기 손실 방지

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

e.g. input 7x7

3x3 filter, applied with **stride 1**

**pad with 1 pixel** border => what is the output?

## Unit 03 | Convolution Layer

- Padding
  - 데이터 테두리에 zero-padding을 더해 크기 손실 방지

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

e.g. input 7x7

3x3 filter, applied with **stride 1**

**pad with 1 pixel** border => what is the output?

$$(N + P - F) / \text{stride} + 1$$

$$= (7 + 2 - 3) / 1 + 1$$

$$= 7$$

**Input size = Output size**

## Unit 03 | Convolution Layer

- Padding
  - 데이터 테두리에 zero-padding을 더해 크기 손실 방지

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

e.g. input 7x7

3x3 filter, applied with **stride 1**

**pad with 1 pixel** border => what is the output?

$$(N + P - F) / \text{stride} + 1$$

$$= (7 + 2 - 3) / 1 + 1 \quad \text{Input size} = \text{Output size}$$

$$= 7$$

e.g.  $F = 3 \Rightarrow$  zero pad with 1

$F = 5 \Rightarrow$  zero pad with 2

$F = 7 \Rightarrow$  zero pad with 3



## Unit 03 | Convolution Layer

- Padding
  - 데이터 테두리에 zero-padding을 더해 크기 손실 방지

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

e.g. input 7x7

3x3 filter, applied with **stride 1**

**pad with 1 pixel** border => what is the output?

$$(N + P - F) / \text{stride} + 1$$

$$= (7 + 2 - 3) / 1 + 1 \quad \text{Input size} = \text{Output size}$$

$$= 7$$

e.g.  $F = 3 \Rightarrow$  zero pad with 1

$F = 5 \Rightarrow$  zero pad with 2

$F = 7 \Rightarrow$  zero pad with 3

## Unit 03 | Convolution Layer

- Padding
  - 데이터 테두리에 zero-padding을 더해 크기 손실 방지

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

e.g. input 7x7

3x3 filter, applied with **stride 1**

**pad with 1 pixel** border => what is the output?

$$(N + P - F) / \text{stride} + 1$$

$$= (7 + 2 - 3) / 1 + 1 \quad \text{Input size} = \text{Output size}$$

$$= 7$$

e.g.  $F = 3 \Rightarrow$  zero pad with 1

$F = 5 \Rightarrow$  zero pad with 2

$F = 7 \Rightarrow$  zero pad with 3

## Unit 03 | Convolution Layer

- Example

Input volume:  $32 \times 32 \times 3$

10  $5 \times 5$  filters with stride 1, pad 2

1. Output volume size: ?

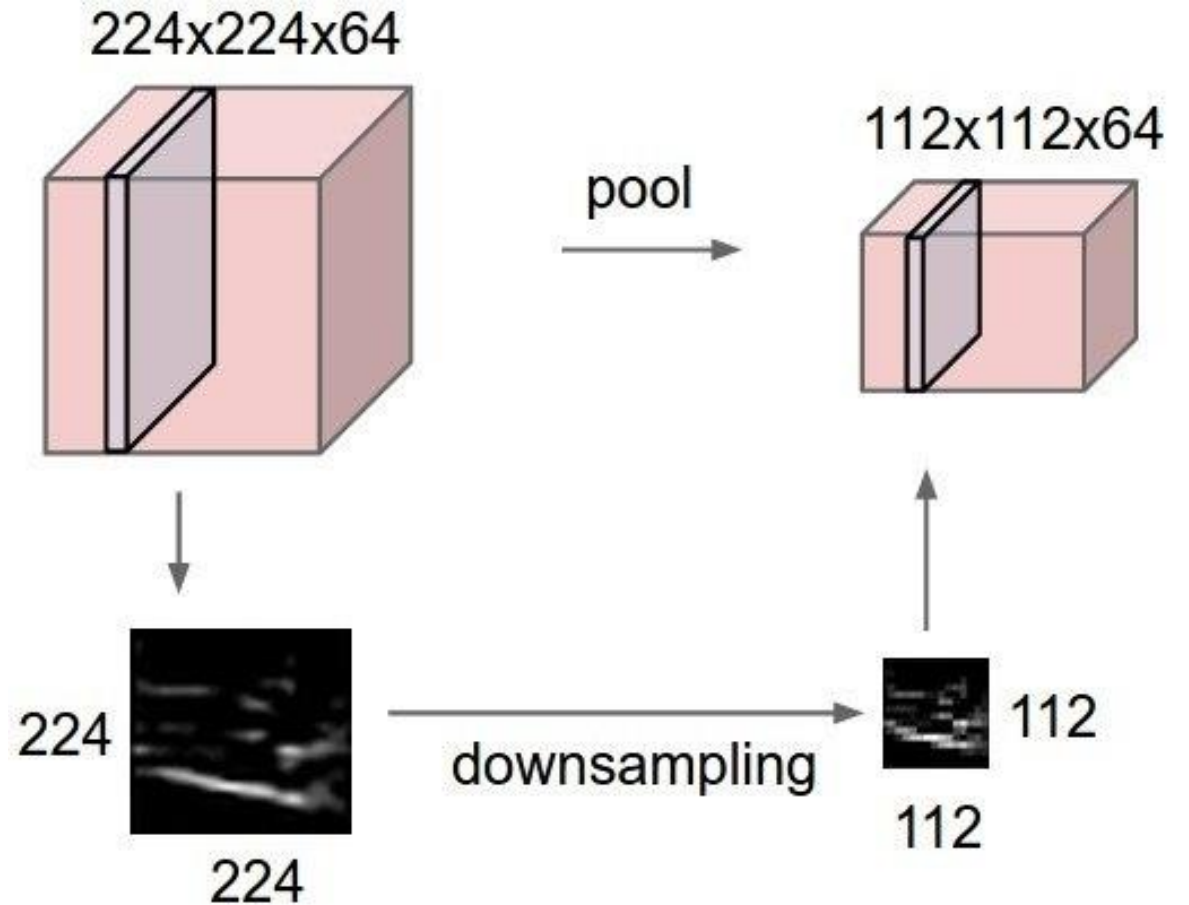
2. Number of parameters in this layer : ?

## Unit 04 | Sub-Sampling

## ■ Sub Sampling

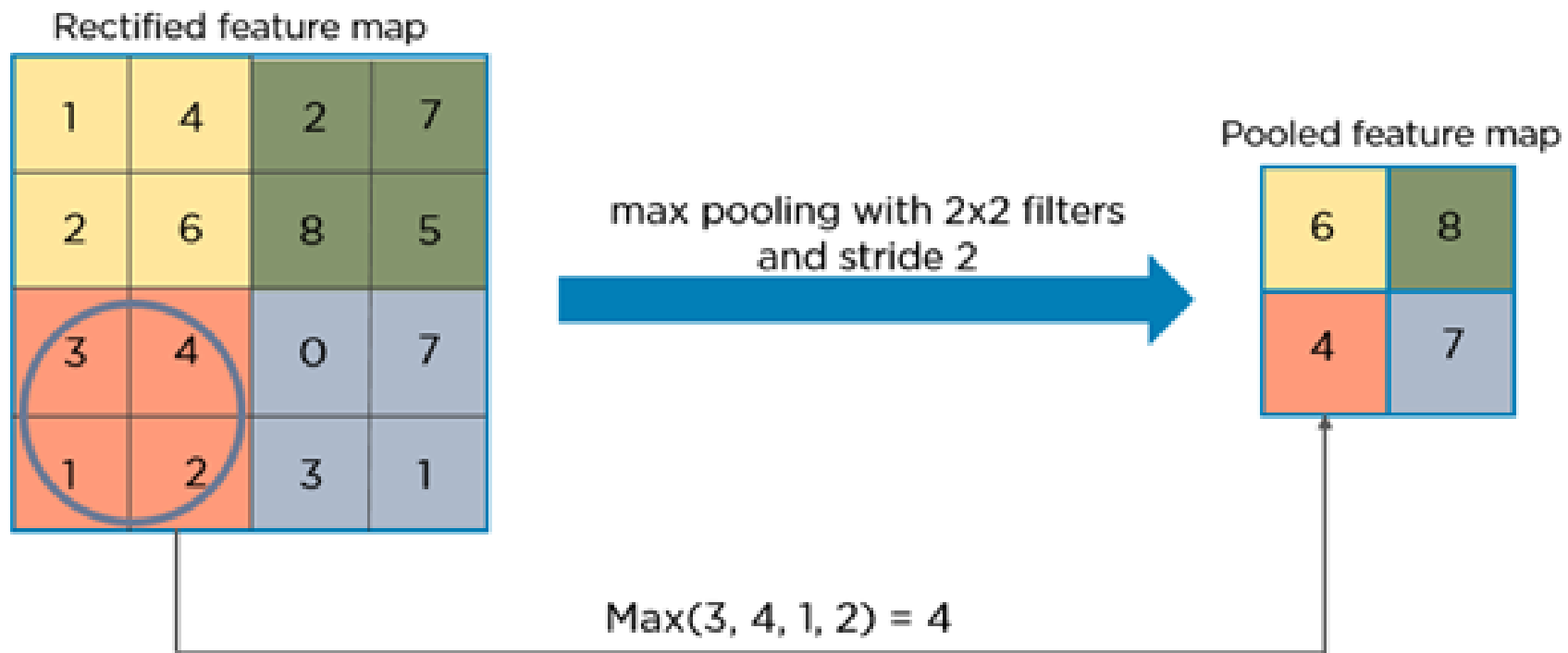
- 이미지의 특성은 유지
- 사이즈를 줄여 관리하기 쉽게 만듦
- 각 feature map마다 독립적으로 작용

**But** 기기의 성능 향상으로  
사이즈를 줄일 필요가 적어지면서  
성능을 위해 잘 사용하지 않는 추세



## Unit 04 | Sub-Sampling

- Sub Sampling
  - Max pooling
    - Filter size와 stride 존재



## Unit 04 | Sub-Sampling

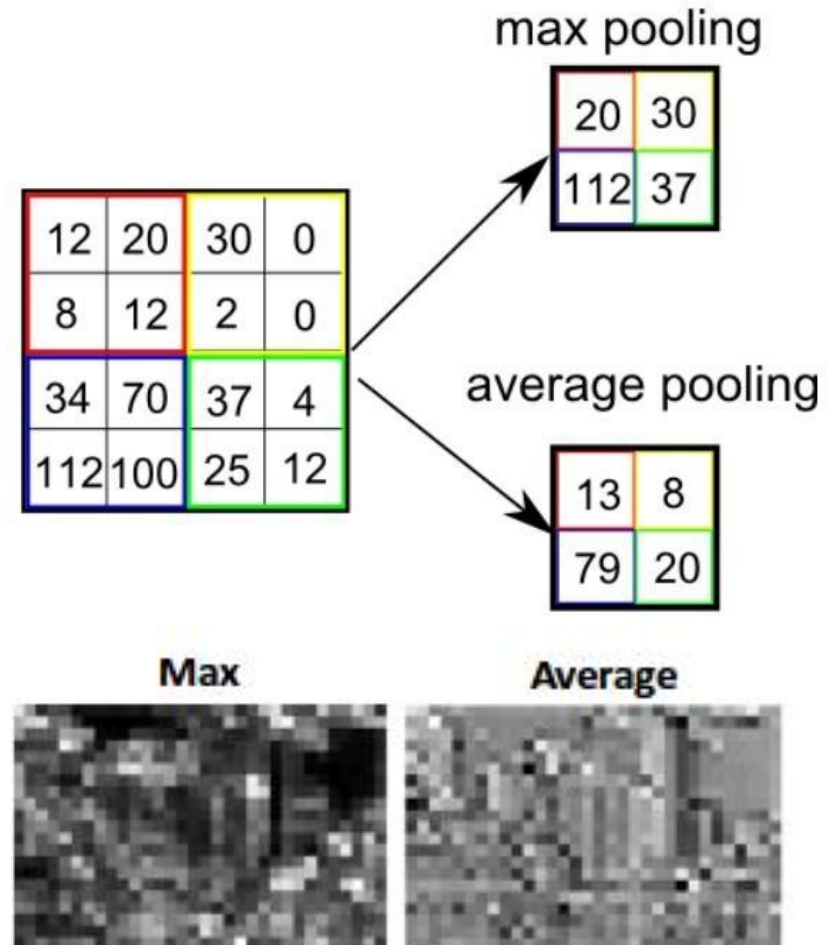
## ■ Max pooling vs Average pooling

## • Max pooling

해당 window의 max값을 추출

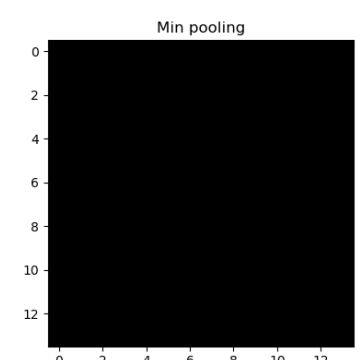
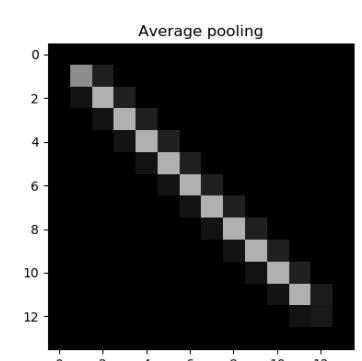
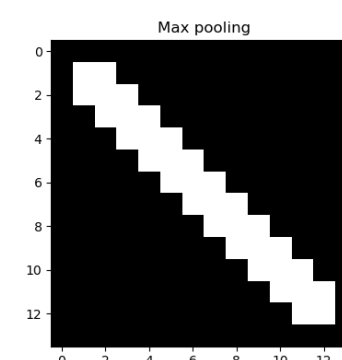
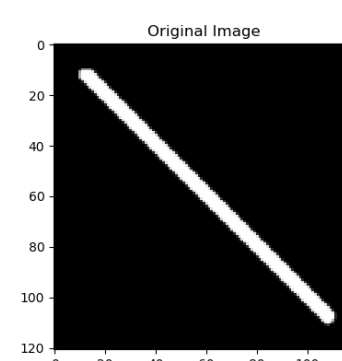
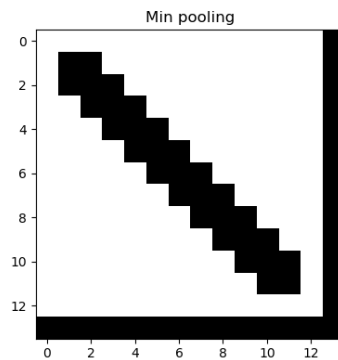
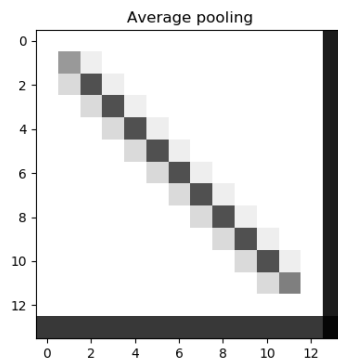
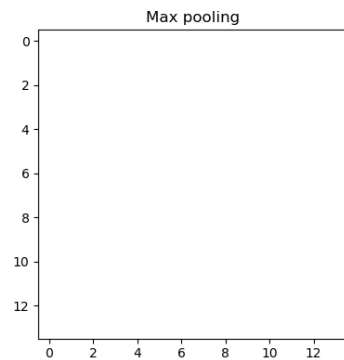
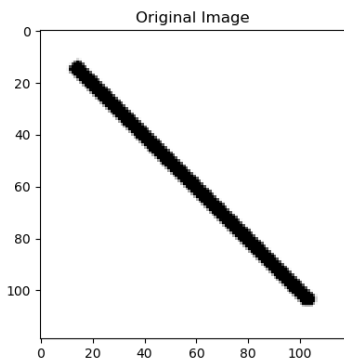
## • Average pooling

해당 window의 평균 값 추출 (smoothing 됨)



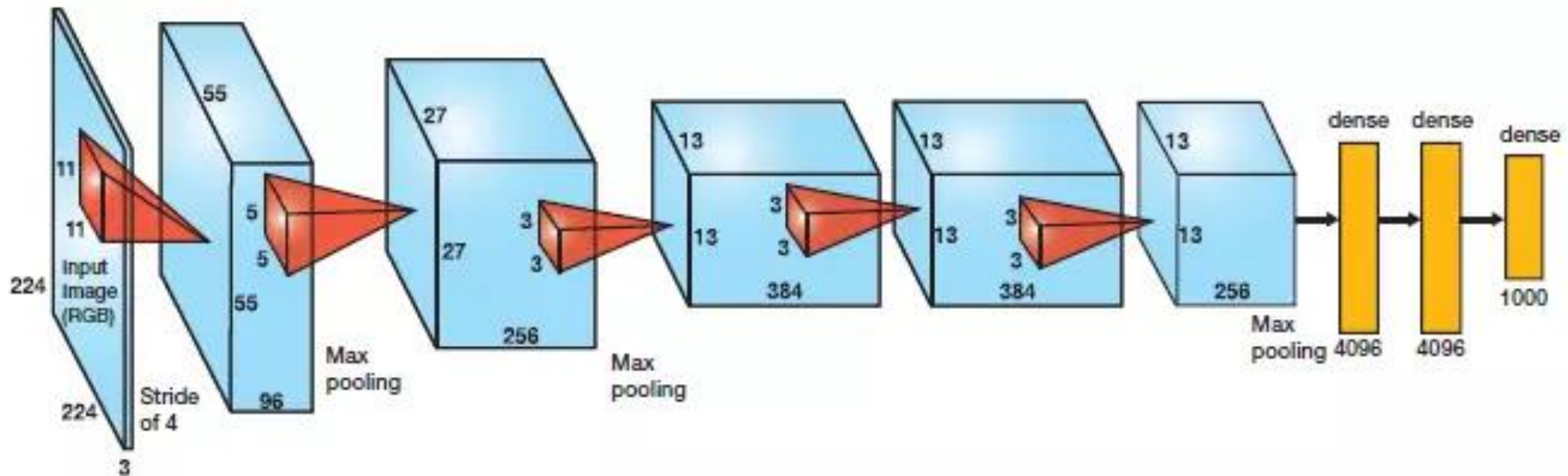
## Unit 04 | Sub-Sampling

- Max pooling vs Average pooling
  - Most important features를 뽑는다는 관점에서 일반적으로 Max pooling을 사용



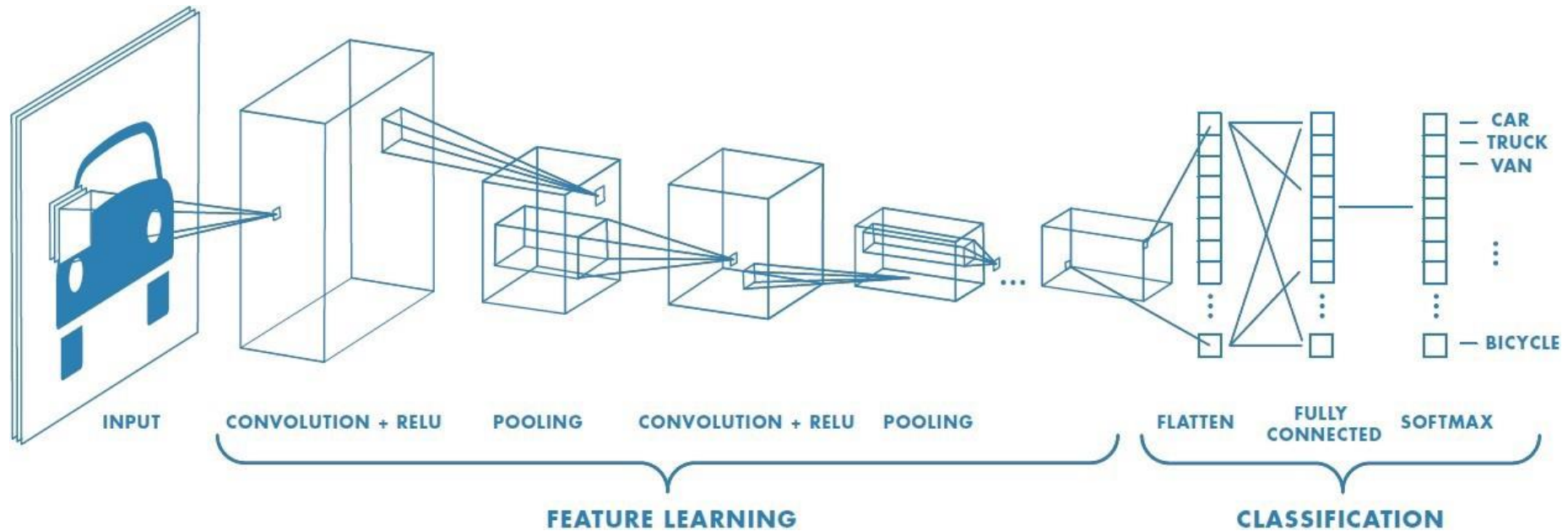
## Unit 04 | Sub-Sampling

- pretty much everything of 'CNN' (AlexNet)





## Unit 05 | Summary



- Convolution Layer + Subsampling Layer + Fully Connected Layer
- Feature extraction : Convolution Layer + Pooling Layer
- Classification : Fully Connected Layer

## Unit 02 | Layers in CNN

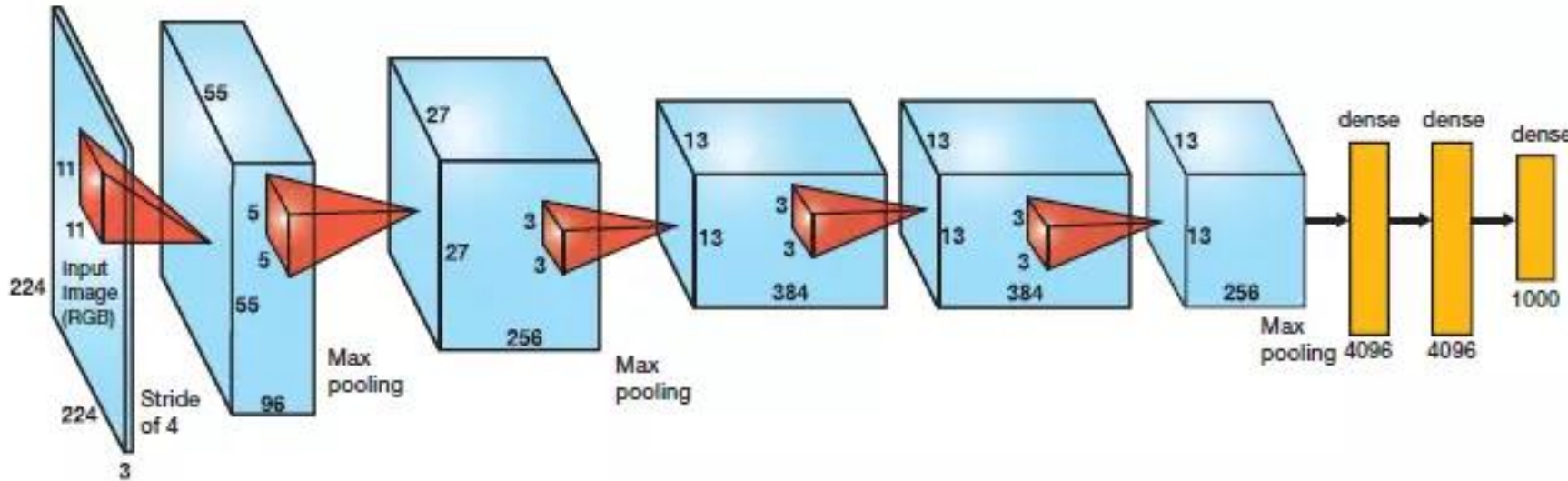
- Convolutional Neural Network
  - Local connectivity(receptive field)
    - 지역적으로 뉴런을 연결하여 다양한 local feature 추출 가능
  - Shared Weights and Biases (topology invariance)
    - Filter의 weight를 공유하여 parameter를 획기적으로 줄일 수 있다.
    - 찾고자 하는 특징이 이미지 어디에 위치해도 알 수 있다.
  - Compositionality
    - 저레벨 특징을 고레벨 특징으로 compose함
    - ex) 눈의 특징, 귀의 특징, 코의 특징 등등이 결합하여 사람의 얼굴의 특징으로 귀결

## Unit 05 | Summary

- 용어 정리
  - Convolution(합성곱)
  - 채널(Channel)
  - 필터(Filter) = 커널(Kernel)
  - 스트라이드(Stride)
  - 패딩(Padding), zero-Padding
  - 피쳐 맵(Feature Map) = 액티베이션 맵(Activation Map)
  - 풀링(Pooling) 레이어
  - receptive field(수용공간)

# Assignment

## AlexNet



과제 1. assignment\_1.ipynb 물음표 채우기

과제 2. AlexNet model 구현 (프레임워크 자유)

- 모델 구현 후 summary로 전체 모델 구조 보이고 주석을 통해 간단한 설명 (각 프레임워크 별 summary 방법 구글링)

Q & A

들어주셔서 감사합니다.

## Appendix

## • 참고자료

# 10기 박성진님 강의

[http://www.datamarket.kr/xe/index.php?mid=board\\_jPWY12&page=2&document\\_srl=52335](http://www.datamarket.kr/xe/index.php?mid=board_jPWY12&page=2&document_srl=52335)

# Stanford cs231n 강의

<http://cs231n.stanford.edu/syllabus.html>

# towards data science

<https://towardsdatascience.com/a-comprehensive-guide-to-convolutional-neural-networks-the-eli5-way-3bd2b1164a53>

# 케라스 창시자에게 배우는 딥러닝

<https://github.com/gilbutITbook/006975>